

CS663: Fundamentals of Digital Image Processing

Homework II

Yash Salunkhe, Scaria Kochidanadu, Rishabh Shetty

Question 7)

Answer:

Rotate (x, y) by θ to get (u, v) :

$$\begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

We get:

$$\begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} x \cos \theta + y \sin \theta \\ x \sin \theta + y \cos \theta \end{bmatrix}$$

We can define a new function $\tilde{f} : \mathbb{R}^2 \rightarrow \mathbb{R}$ that

$$\tilde{f}(u, v) = f(x(u, v), y(u, v))$$

If Laplace's Operator is rotationally invariant, then

$$\nabla^2 \tilde{f}(u, v) = \nabla^2 f(x, y)$$

This can be proved by the following:

$$\begin{aligned} \nabla^2 \tilde{f}(u, v) &= \tilde{f}_{uu} + \tilde{f}_{vv} \\ &= \frac{\partial}{\partial u} \left(f_x \frac{\partial x}{\partial u} + f_y \frac{\partial y}{\partial u} \right) + \frac{\partial}{\partial v} \left(f_x \frac{\partial x}{\partial v} + f_y \frac{\partial y}{\partial v} \right) \\ &\quad + f_{xx} \left(\frac{\partial x}{\partial u} \right)^2 + f_{yy} \left(\frac{\partial y}{\partial u} \right)^2 + f_{xy} \frac{\partial y}{\partial u} \frac{\partial x}{\partial u} \\ &\quad + f_x \frac{\partial^2 x}{\partial u^2} + f_y \frac{\partial^2 y}{\partial u^2} \\ &\quad + f_{xx} \left(\frac{\partial x}{\partial v} \right)^2 + f_{yy} \left(\frac{\partial y}{\partial v} \right)^2 + f_{xy} \frac{\partial y}{\partial v} \frac{\partial x}{\partial v} \\ &\quad + f_x \frac{\partial^2 x}{\partial v^2} + f_y \frac{\partial^2 y}{\partial v^2} \\ &= \tilde{f}_{uu} + \tilde{f}_{vv} + f_{xx} \cos^2 \theta - 2 \sin \theta \cos \theta f_{xy} + \sin^2 \theta f_{yy} \\ &\quad + f_{xx} \sin^2 \theta + 2 \sin \theta \cos \theta f_{xy} + \cos^2 \theta f_{yy} \\ &= f_{xx} \sin^2 \theta + 2 \sin \theta \cos \theta f_{xy} + \cos^2 \theta f_{yy} + \tilde{f}_{uu} + \tilde{f}_{vv} \\ &= \nabla^2 f(x, y) \end{aligned}$$