Q3_ass7

November 22, 2021

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[4]: %run lib.ipynb
[5]: def shooting_method(d2ydx2, dydx, x0, y0, xf, yf, z_guess1, z_guess2, h,__
      \rightarrowtol=1e-6):
                                                                                        #x0:_
      \rightarrowLower boundary value of x, y0 = y(x0)
                                                                                        \#xf:
      \rightarrowUpper boundary value of x, yf = y(xf)
                                                                                        #z =
      \rightarrow dy/dx
         x, y, z = runge_kutta(d2ydx2, dydx, x0, y0, z_guess1, xf, h)
         yn = y[-1]
         if abs(yn - yf) > tol:
              if yn < yf:</pre>
                  z_1 = z_guess1
                  y1 = yn
                  x, y, z = runge_kutta(d2ydx2, dydx, x0, y0, z_guess2, xf, h)
                  yn = y[-1]
                  if yn > yf:
                      z_h = z_guess2
                      yh = yn
                      # calculate zeta using Lagrange interpolation
                      zeta = lagrange_interpolation(z_h, z_l, yh, yl, yf)
                      # using this zeta to solve using RK4
                      x, y, z = runge_kutta(d2ydx2, dydx, x0, y0, zeta, xf, h)
                      return x, y, z
                  else:
                      print("Bracketing failed. Change your set of guesses.")
              elif yn > yf:
```

```
z_h = z_guess1
yh = yn

x, y, z = runge_kutta(d2ydx2, dydx, x0, y0, z_guess2, xf, h)
yn = y[-1]

if yn < yf:
    z_l = z_guess2
    yl = yn

# calculate zeta using Lagrange interpolation
    zeta = lagrange_interpolation(z_h, z_l, yh, yl, yf)

x, y, z = runge_kutta(d2ydx2, dydx, x0, y0, zeta, xf, h)
    return x, y, z

else:
    print("Bracketing failed. Change your set of guesses.")

else:
    return x, y, z # bang-on solution with z_guess1</pre>
```

```
[6]: #Q3
# solv Schordinger Equation

def ad2ydt2(t, y, z): #ground state
    return -(math.pi**2)*y/4

def bd2ydt2(t, y, z):#ecxcited state
    return -(math.pi**2)*y

def dydt(t, y, z):
    return z

# Define boundary values

t_i = 0

t_f = 2

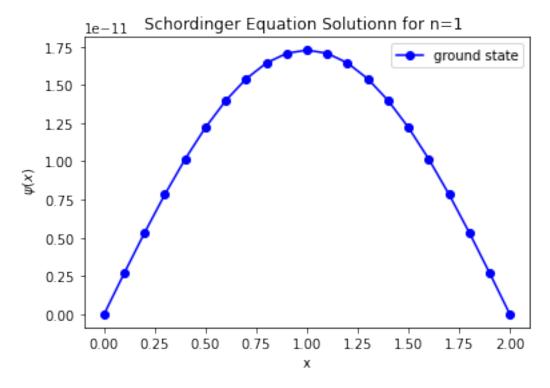
y_i = 0

y_f = 0

t, y, z = shooting_method(ad2ydt2, dydt, t_i, y_i, t_f, y_f, -2, 10, h=0.1)
```

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plt.plot(t,y,'b-o',label='ground state')
plt.xlabel('x')
plt.ylabel(' $\psi (x)$')
plt.title('Schordinger Equation Solutionn for n=1 ')
plt.legend()
plt.show()

t, y, z = shooting_method(bd2ydt2, dydt, t_i, y_i, t_f, y_f, -2, 10, h=0.1)
plt.plot(t,y,'r-o',label='excited state')
plt.xlabel('x')
plt.ylabel(' $\psi (x)$')
plt.title('Schordinger Equation Solution for n=2 ')
plt.legend()
```



[6]: <matplotlib.legend.Legend at 0x7ff4e2e3ed30>

