my_assignment3

September 4, 2021

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[2]: %run MyLibrary.ipynb
[3]: # Function to swap row1 and row2
     def swap_rows(Ab,row1,row2):
         temp = Ab[row1]
         Ab[row1] = Ab[row2]
         Ab[row2] = temp
         return Ab
     # Function for partial pivoting
     def partial_pivot(Ab,m,nrows):
         pivot = Ab[m][m]
                          # declare the pivot
         if (Ab[m][m] != 0):
                          # return if partial pivot is not required
             return Ab
         else:
             for r in range(m+1,nrows):
                 # check for non-zero pivot and swap rows with it
                 if Ab[r][m] != 0:
                     pivot = Ab[r][m]
                     Ab=swap_rows(Ab,m,r)
                     return Ab
                 else:
                     r+=1
         if (pivot==0):
                          # if there is no unique solution
             return None
     # Gauss Jordan Elimiination method
     def gauss_jordan(Ab,nrows,ncols):
         det=1
         r=0
         # does partial pivoting
        Ab = partial_pivot(Ab,r,nrows)
```

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for r in range(0,nrows):
             # if there is no solution
             if Ab==None:
                 return Ab
             else:
                 # Changes the diagonal elements to unity
                 fact=Ab[r][r]
                 det=det*fact # calculates the determinant
                 for c in range(r,ncols):
                     Ab[r][c]*=1/fact
                 # makes all elements other than diagonal elements to zero
                 for r1 in range(0,nrows):
                     # does not change if it is already done
                     if (r1==r or Ab[r1][r]==0):
                         r1+=1
                     else:
                         factor = Ab[r1][r]
                         for c in range(r,ncols):
                             Ab[r1][c] = factor * Ab[r][c]
         return Ab, det
     # Function to extract inverse from augmented matrix
     def get_inv(A,n):
        r=len(A)
         c=len(A[0])
         M=[[0 for j in range(n)] for i in range(n)]
         for i in range(r):
             for j in range(n,c):
                 M[i][j-n]=A[i][j]
         return M
     # Function to round off all elements of a matrix
     def round_matrix(M,r):
         for i in range(len(M)):
             for j in range(len(M[0])):
                 M[i][j]=round(M[i][j],r)
         return M
[4]: A = [[1,1,1,1,1,13],[2,3,0,-1,-1],[-3,4,1,2,10],[1,2,-1,1,1]]
     print("The augmented matrix is: ")
```

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M=round_matrix(A,2)
         print("Solutions are : ")
         for i in range(4):
            print(M[i][4])
     else:
         print("No unique solution exists.")
    The augmented matrix is:
    1
         1
              1
                   1
                        13
    2
         3
              0
                   -1
                        -1
    -3
         4
                   2
             1
                        10
         2
             -1
                 1
                        1
    Solutions are :
    2.0
    -0.0
    6.0
    5.0
[5]: B = [[0,2,-3,-1],[1,0,1,0],[1,-1,0,3]]
     print("The augmented matrix is: ")
     print_matrix(B,3,4)
     GJ, d=gauss_jordan(B,3,4)
     if GJ!=None:
        print("Solutions are : ")
         for i in range(3):
            print(B[i][3])
     else:
        print("No unique solution exists.")
    The augmented matrix is:
              -3
                   -1
         0
           1
                   0
    1
        -1
            0
                 3
    Solutions are :
    1.0
    -2.0
```

-1.0

```
[6]: C2 = [[0,2,1],[4,0,1],[-1,2,0]]
                                         # matrix
     C = [[0,2,1, 1,0,0], [4,0,1, 0,1,0], [-1,2,0, 0,0,1]] # augmented matrix
     print("The augmented matrix is: ")
     print_matrix(C,3,6)
     GJ, d=gauss_jordan(C,3,6)
     if GJ!=None:
         # Finding the inverse and printing in rounded form
         # Multiply the matrices to verify if it is identity and then rounding at the \Box
      \rightarrowend
         M=get_inv(C,3)
         MM,k,l=matrix_multiply(M,3,3,C2,3,3)
         M=round_matrix(M,2)
         print("The inverse matrix is: ")
         print_matrix(M,3,3)
         print("Verification: ")
         MM=round_matrix(MM,2)
         print_matrix(MM,3,3)
     else:
         print("No unique solution exists.")
```

The augmented matrix is:

 $4 \qquad 0 \qquad 1 \qquad 0 \qquad 1 \qquad 0$

-1 2 0 0 0 1

The inverse matrix is:

-0.33 0.33 0.33

-0.17 0.17 0.67

1.33 -0.33 -1.33

Verification:

1.0 0.0 0.0

0.0 1.0 0.0

0.0 0.0 1.0

The augmented matrix is:

```
0
             0 1
   1
      4
          4
-1
   0
      1
         0
            0
                0
                   1
                      0
2
   0
      4
          1
             0
                0
                    0
                      1
```

Determinant of the matrix = 65.0