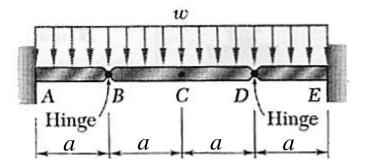
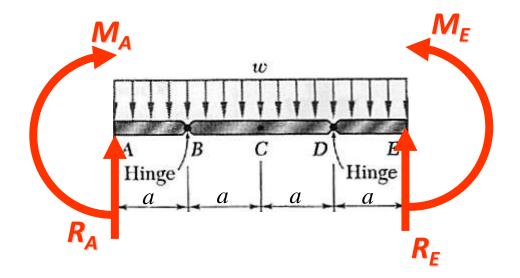
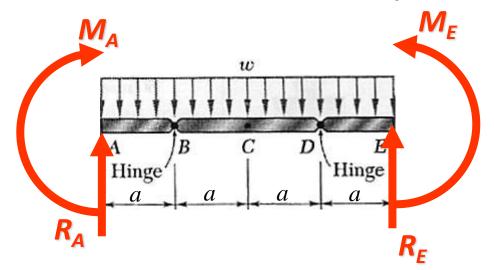
A beam BCD is joined to two cantilever beams AB and DE by hinges as shown. Derive expressions for the net deflection at C



 Draw the Free Body Diagram of the entire structure. There are 4 unknown reactions and 2 equations of equilibrium.



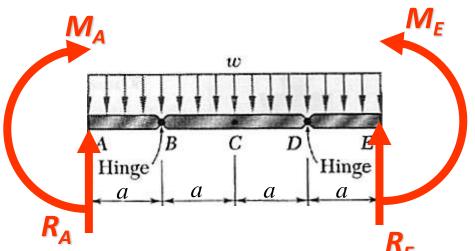
 If we take symmetry of the problem into consideration the number of unknown reactions becomes 2 and useful equations become 1 (only vertical force balance) .So the structure as a whole is statically indeterminate



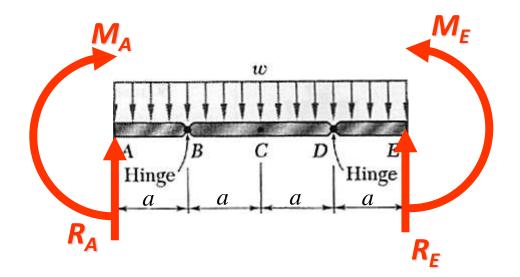
 Either way these are the information we can get at best

$$R_A + R_E = w \times 4a = 4aw$$

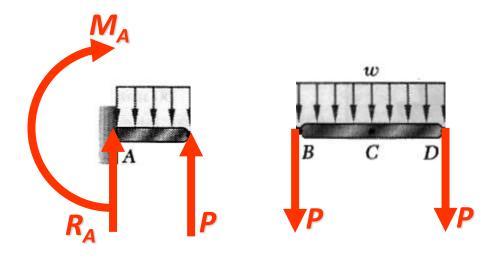
 $\sum M_A = 0 \Rightarrow -M_A + M_E + 4aR_E = 0$
From symmetry $R_A = R_E = 2aw$
 $M_A = M_E$



 Let us look at the individual beams. We need to consider only AB and BCD because of symmetry of the problem.



Let us look at FBDs of the individual beams.
 We need to consider only AB and BCD because of symmetry of the problem.

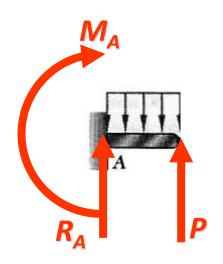


- Beam AB
- 3 unknowns, M_A , R_A Moment and force reaction at fixed end and P reaction at hinge
- 2 equations of equilibrium

$$\sum F_{y} = 0 \Longrightarrow R_{A} + P = \int_{0}^{a} w dx = wa$$

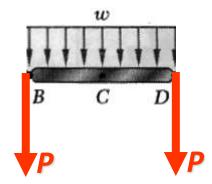
$$\sum M_A = 0$$

$$\Rightarrow Pa = M_A + \int_0^a xw dx = M_A + \frac{wa^2}{2}$$



- Beam BCD
- No new unknown. P has already been counted
- 1 new equation of equilibrium
- Moment balance is not useful, because we have already set the hinge reactions as equal from symmetry consideration

$$\sum F_{y} = 0 \Rightarrow 2P = -\int_{0}^{2a} w dx = -2wa$$

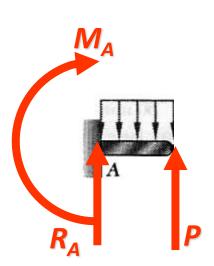


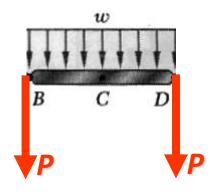
- Total unknowns are 3. M_A, R_A and P
- Total equations of equilibrium are 3
- So the structure is actually statically determinate once we break it down into components

$$R_A + P = wa$$

$$Pa = M_A + \frac{wa^2}{2}$$

$$2P = -2wa$$





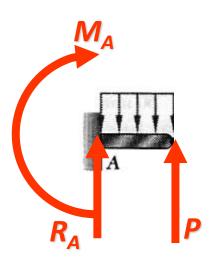
Solving we get

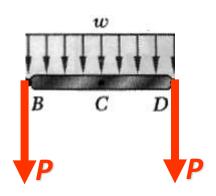
$$P = -wa$$

$$R_A = 2wa$$

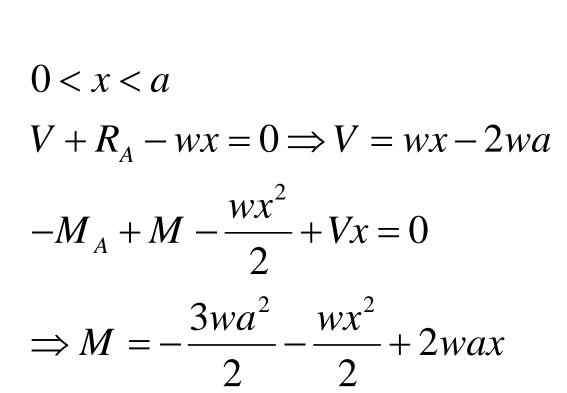
$$M_A = -\frac{3wa^2}{2}$$

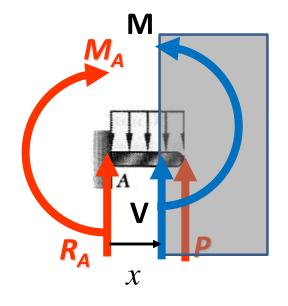
 We can now solve for the deflections of the beams AB and BCD individually





- Beam AB
- Equilibrium equations at section



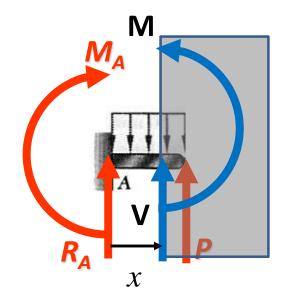


- Beam AB
- Deflection curve

$$EIv'' = -\frac{3wa^2}{2} - \frac{wx^2}{2} + 2wax$$

$$\Rightarrow EIv' = -\frac{3wa^2}{2}x - \frac{wx^3}{6} + wax^2 + C_1$$

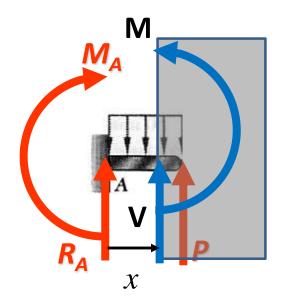
$$\Rightarrow EIv = -\frac{3wa^2x^2}{4} - \frac{wx^4}{24} + \frac{wax^3}{3} + C_1x + C_2$$



- Beam AB
- Apply boundary conditions

$$EIv'(0) = 0 \Rightarrow C_1 = 0$$

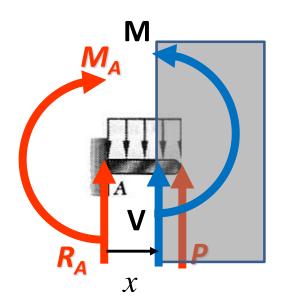
$$EIv(0) = 0 \Rightarrow C_2 = 0$$



- Beam AB
- Solution for slope and deflection

$$EIv' = -\frac{3wa^2x}{2} - \frac{wx^3}{6} + wax^2$$

$$EIv = -\frac{3wa^2x^2}{4} - \frac{wx^4}{24} + wa\frac{x^3}{3}$$



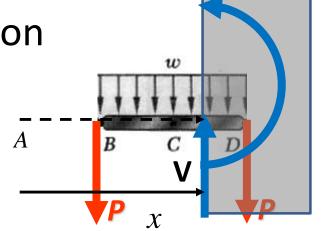
- Beam BCD.
- We still consider the origin to be at A
- Equilibrium equations at section

$$V - P - w(x - a) = 0$$

$$\Rightarrow V = w(x-2a)$$

$$M - \frac{w(x-a)^2}{2} + V(x-a) = 0$$

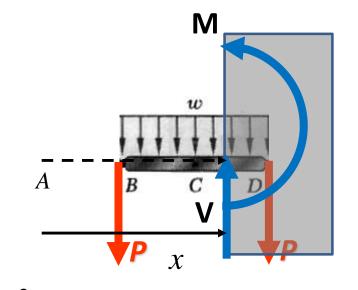
$$\Rightarrow M = -\frac{w(x-a)^2}{2} + wa(x-a) = \frac{w(x-a)(3a-x)}{2}$$



M

- Beam BCD.
- Deflection curve

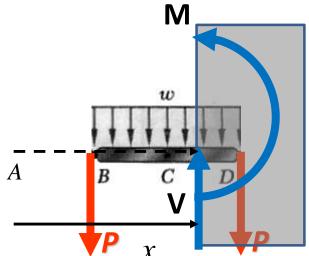
$$EIv'' = -\frac{w(x-a)^2}{2} + wa(x-a)$$



$$\Rightarrow EIv' = -\frac{w(x-a)^3}{6} + \frac{wa(x-a)^2}{2} + C_3$$

$$\Rightarrow EIv = -\frac{w(x-a)^4}{24} + \frac{wa(x-a)^3}{6} + C_3(x-a) + C_4$$

- · Beam BCD.
- Apply boundary conditions
- At hinge deflections must be the same
- Slopes need not be equal
- Because of symmetry
 deflection must be maximum
 and hence slope minimum at C



$$EIv(a-) = EIv(a+), EIv'(2a) = 0$$

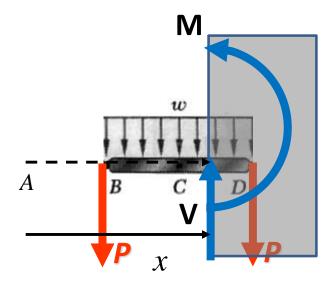
- Beam BCD.
- Apply deflection boundary condition at B

$$a < x < 3a$$

$$EIv(a-) = EIv(a+)$$

$$\Rightarrow -\frac{3wa^2a^2}{4} - \frac{wa^4}{24} + \frac{waa^3}{3} = C_4$$

$$11wa^4$$

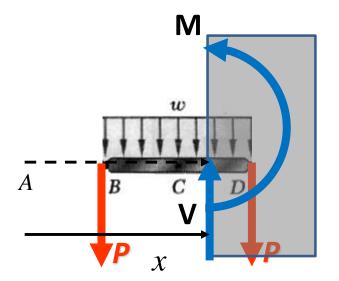


- Beam BCD.
- Apply slope boundary condition at C

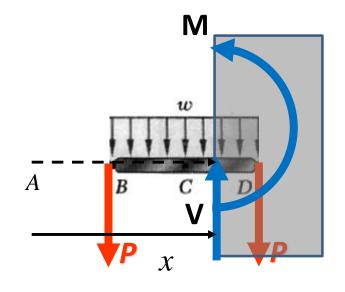
$$EIv'(2a) = 0$$

$$\Rightarrow -\frac{w(2a-a)^3}{6} + \frac{wa(2a-a)^2}{2} + C_3 = 0$$

$$\Rightarrow -\frac{wa^3}{6} + \frac{waa^2}{2} + C_3 = 0 \Rightarrow C_3 = -\frac{wa^3}{3}$$



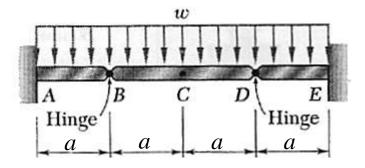
- Beam BCD.
- Solution for slope and deflection



$$EIv' = -\frac{w(x-a)^3}{6} + \frac{wa(x-a)^2}{2} - \frac{wa^3}{3}$$

$$EIv = -\frac{w(x-a)^4}{24} + \frac{wa(x-a)^3}{6} - \frac{wa^3}{3}(x-a) - \frac{11wa^4}{24}$$

Deflection at C

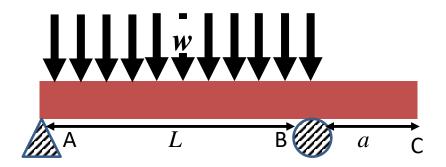


$$EIv(2a) = -\frac{w(a)^4}{24} + \frac{wa(a)^3}{6} - \frac{wa^3}{3}(a) - \frac{11wa^4}{24}$$

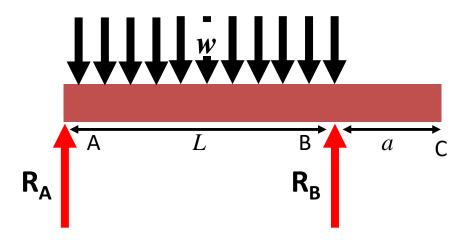
$$\Rightarrow EIv(2a) = -\frac{2wa^4}{3}$$

$$\Rightarrow EIv(2a) = -\frac{2wa^4}{3}$$

A problem with a twist. When drawing BMD only we ignore the overhang if any



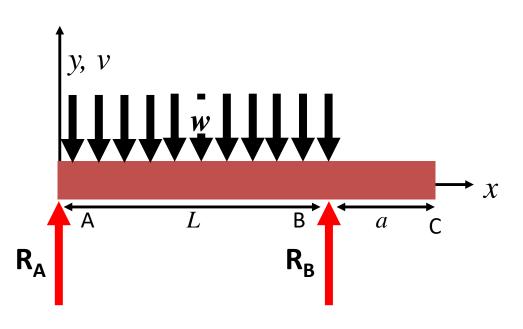
- Draw the FBD
- At both A and B, since pin (or roller) permits rotation but no (vertical) translation there will be only a force as reaction at A and B.



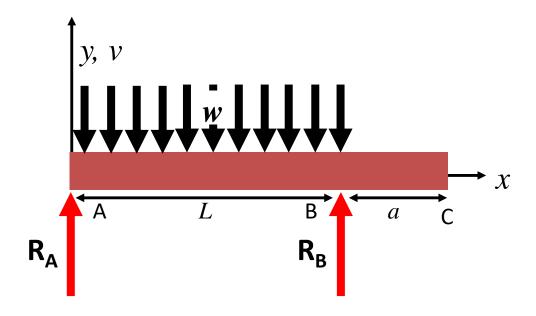
 Write the equilibrium equations. Here moments are being taken about A.

$$R_A + R_B = \int_0^L w dx = wL, R_B = \int_0^L x(w dx) = \frac{wL^2}{2}$$

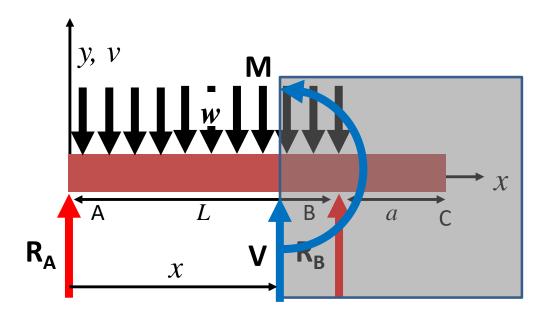
$$\therefore R_A = R_B = \frac{wL}{2}$$



- Set up a coordinate system
- We choose A to be the origin, x as positive from A to B and y,v as positive upwards
- There will be two domains AB and BC



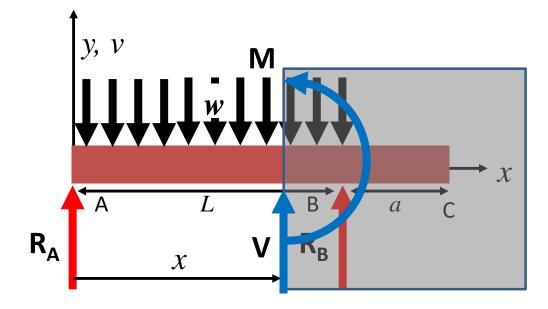
• Domain AB. Section is taken at distance x from A. For this section, while integrating for forces and moments, since the integral will be from 0 to x. Since the limit involves x we will be using a different variable ξ under the integral sign



Solve equilibrium equations

$$V + R_A - \int_0^x w d\xi = 0 \Rightarrow V(x) = w\left(x - \frac{L}{2}\right)$$

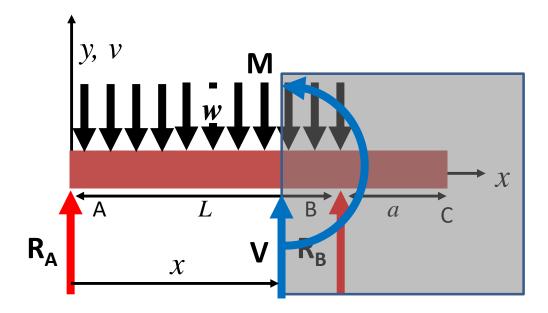
$$M + Vx - \int_0^x \xi(wd\xi) = 0 \Rightarrow M(x) = \frac{wx}{2}(L - x)$$



Solve the flexure equation

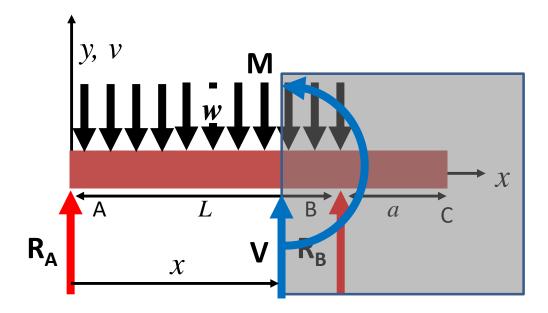
$$EIv'' = \frac{wx}{2}(L-x) \Rightarrow EIv' = \frac{wLx^2}{4} - \frac{wx^3}{6} + C_1$$

$$\Rightarrow EIv = \frac{wLx^3}{12} - \frac{wx^4}{24} + C_1x + C_2$$



The boundary conditions are deflection at A and B are zero

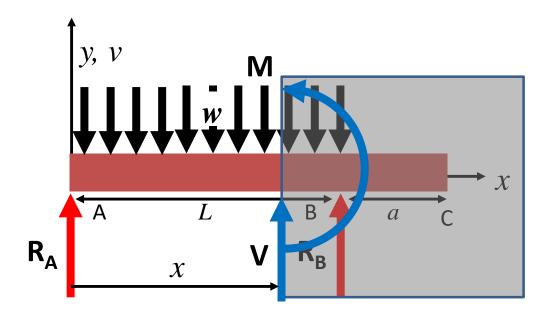
$$v(0) = 0, v(L) = 0$$



Applying boundary conditions (BCs) we get

$$v(0) = 0 \Rightarrow C_2 = 0$$

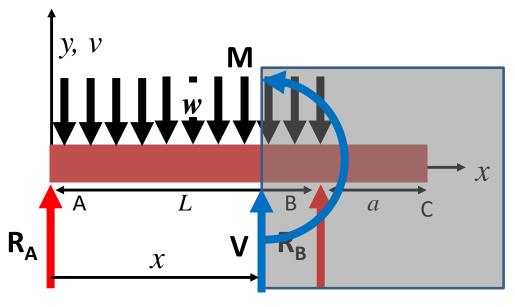
$$v(L) = 0 \Rightarrow \frac{wL^4}{12} - \frac{wL^4}{24} + C_1L = 0 \Rightarrow C_1 = -\frac{wL^3}{24}$$



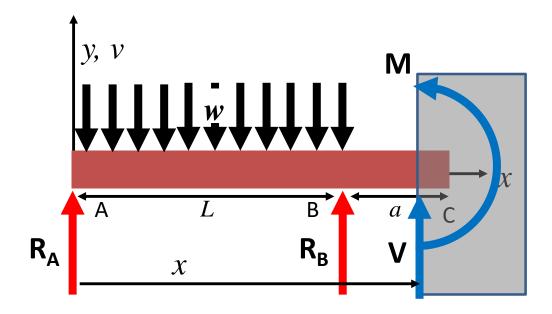
Thus the equation of the deflection curve (in AB) and its gradient are

$$v(x) = -\frac{wx^4}{24EI} + \frac{wLx^3}{12EI} - \frac{wL^3x}{24EI}$$

$$v'(x) = -\frac{wx^3}{6EI} + \frac{wLx^2}{4EI} - \frac{wL^3}{24EI}$$



- Domain BC
- Take a section and draw the FBD
- The reaction R_B now appears.



- Solve equilibrium equations
- The limits of integration will now be upto L

$$V + R_A + R_B - \int_0^L w d\xi = 0 \Rightarrow V(x) = 0$$

$$M + Vx + R_B L - \int_0^L \xi(w d\xi) = 0 \Rightarrow M(x) = 0$$

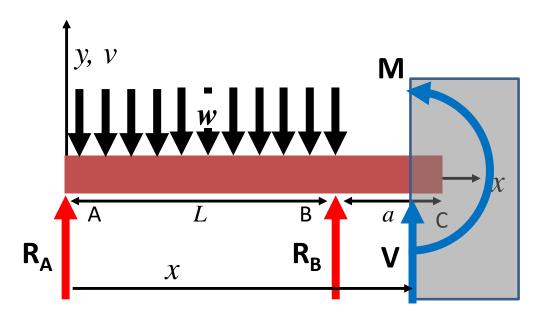
$$\downarrow^{y, v}$$

$$\downarrow^{x}$$

Solve the flexure equation

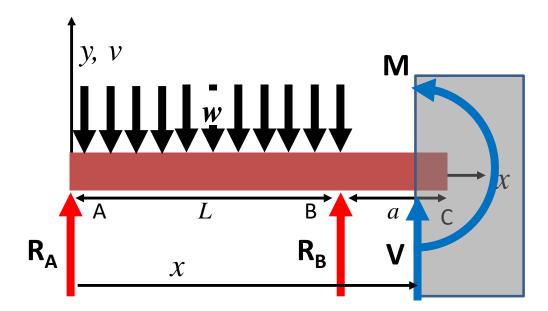
$$EIv''(x) = 0 \Rightarrow v'(x) = D_1 \Rightarrow v(x) = D_1x + D_2$$

- But this is the equation of a straight line!
- It makes sense, because there is nothing here to cause any new deformation. It simply follows the slope at B.



 Apply boundary conditions. The slope and deflection must match at B for both domains

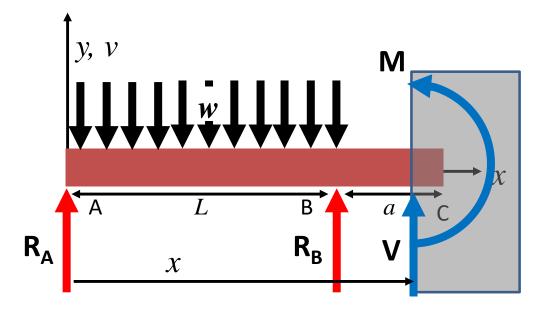
$$v'(L-) = v'(L+), v(L-) = v(L+) = 0$$



Solution for constants

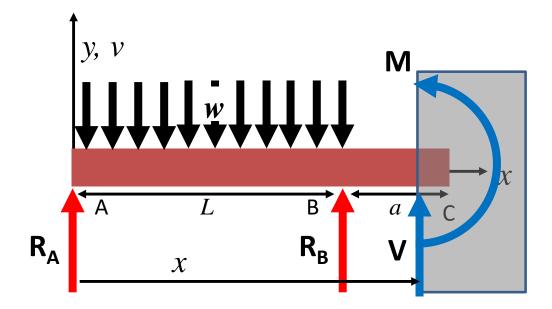
$$D_{1} = -\frac{wL^{3}}{6EI} + \frac{wx^{3}}{4EI} - \frac{wL^{3}}{24EI} = \frac{wL^{3}}{24EI}$$

$$D_1L + D_2 = 0 \Rightarrow D_2 = -\frac{wL^4}{24EI}$$



Solution for deflection curve

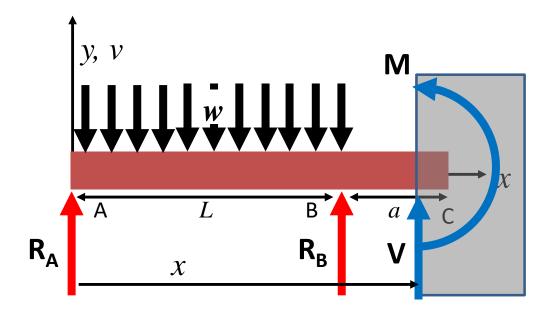
$$v'(x) = \frac{wL^3}{24EI}, v(x) = \frac{wL^3}{24EI}x - \frac{wL^4}{24EI}$$



Useful information

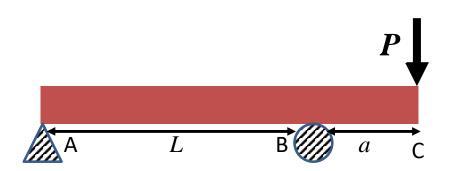
$$v'(L+a) = \frac{wL^3}{24EI}, v(L+a) = \frac{wL^3a}{24EI}$$

• If the overhang a>L then the maximum deflection will be at the free end, but upwards.

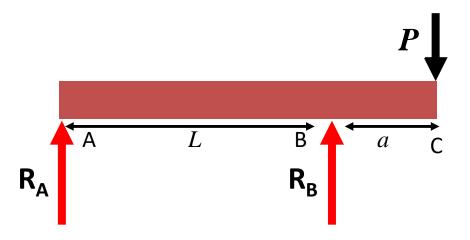


Simply supported beam with point load at overhang tip

 Here the point load is at the tip of the free end



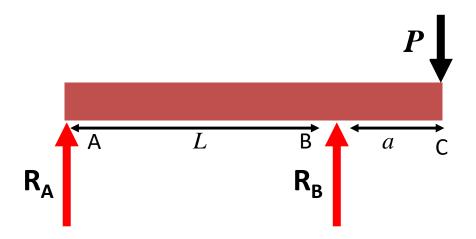
- Draw the FBD
- At both A and B, since pin (or roller) permits rotation but no (vertical) translation there will be only a force as reaction at A and B.



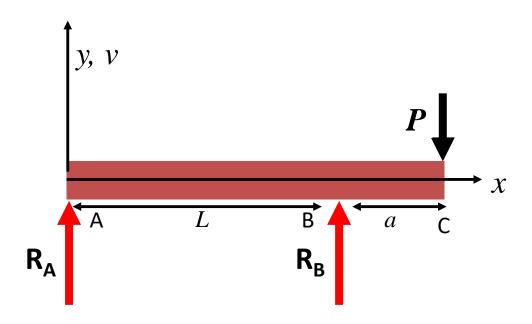
 Write the equilibrium equations. Here moments are being taken about A.

$$R_A + R_B = P, R_B L = P(a + L)$$

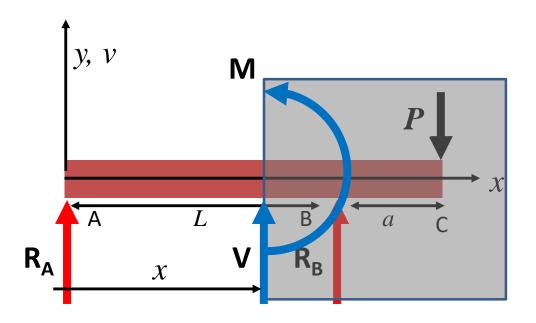
$$\therefore R_A = -P\frac{a}{L}, R_B = P\left(1 + \frac{a}{L}\right)$$



- Set up a coordinate system
- We choose A to be the origin, x as positive from A to B and y,v as positive upwards
- There will be two domains AB and BC



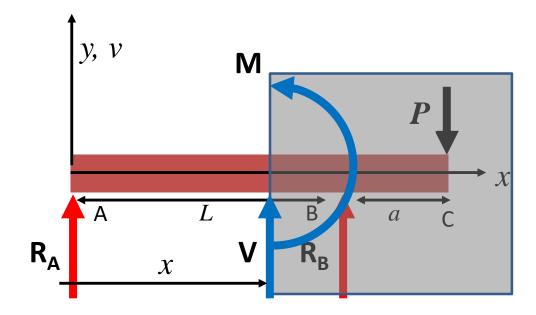
Domain AB. Section is taken at distance x from A.



Solve equilibrium equations

$$V + R_A = 0 \Rightarrow V(x) = -R_A = P\frac{a}{L}$$

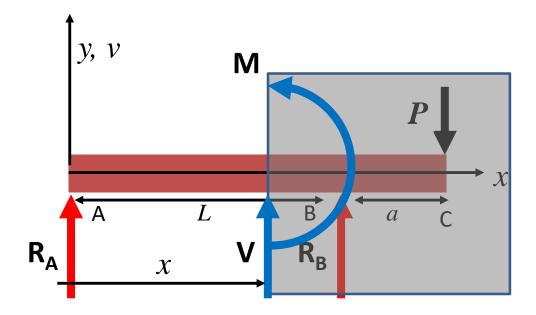
$$M + Vx = 0 \Rightarrow M(x) = -Vx = -P\frac{a}{L}x$$



Solve the flexure equation

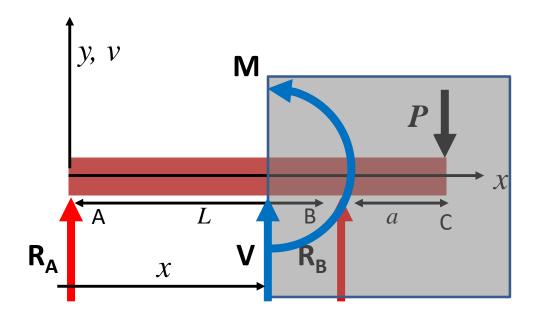
$$EIv'' = -\frac{Pax}{L} \Rightarrow EIv' = -\frac{Pax^2}{2L} + C_1$$

$$\Rightarrow EIv = -\frac{Pax^3}{6L} + C_1x + C_2$$



The boundary conditions are deflection at A and B are zero

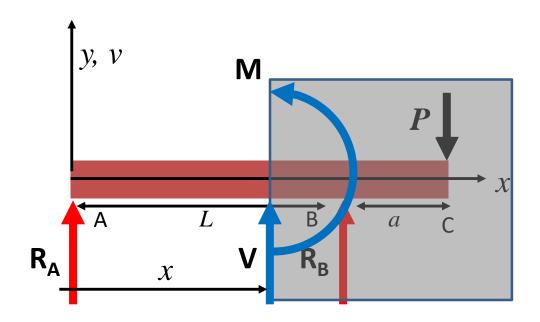
$$v(0) = 0, v(L) = 0$$



Applying boundary conditions (BCs) we get

$$v(0) = 0 \Rightarrow C_2 = 0$$

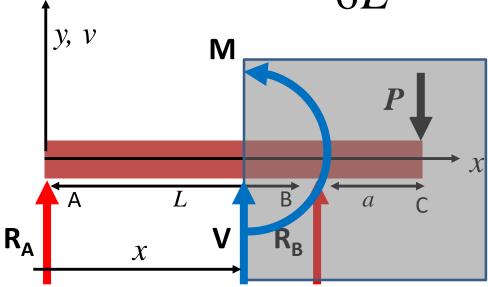
$$v(L) = 0 \Rightarrow -\frac{PaL^2}{6} + C_1L = 0 \Rightarrow C_1 = \frac{PaL}{6}$$



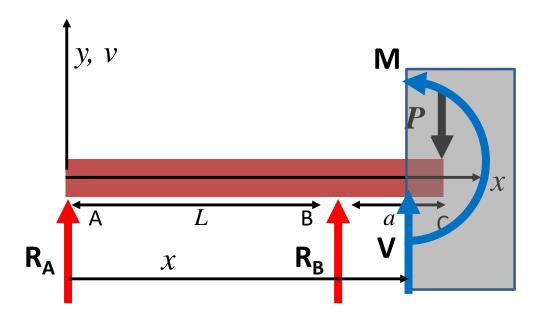
Thus the equation of the deflection curve (in AB) and its gradient are

$$EIv' = \frac{Pa}{2L} \left(\frac{L^2}{3} - x^2 \right)$$

$$\Rightarrow EIv = \frac{Pax}{6L} \left(L^2 - x^2 \right)$$

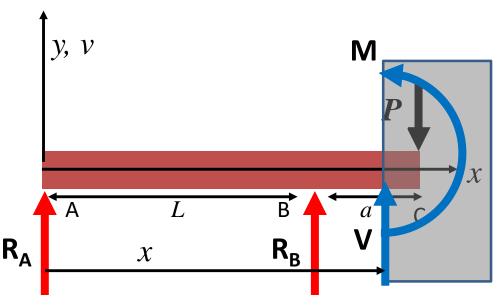


- Domain BC
- Take a section and draw the FBD
- The reaction R_B now appears.



Solve equilibrium equations

Solve the flexure equation



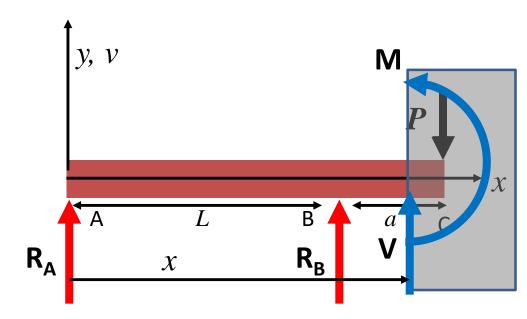
$$EIv''(x) = P(x-L-a)$$

$$\Rightarrow EIv'(x) = P\left\{\frac{x^2}{2} - (L+a)x\right\} + D_1$$

$$\Rightarrow EIv(x) = P\left\{\frac{x^3}{6} - (L+a)\frac{x^2}{2}\right\} + D_1x + D_2$$

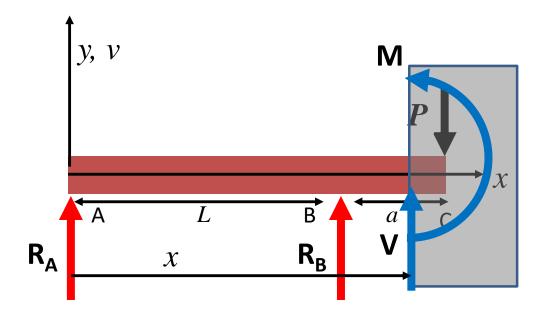
 Apply boundary conditions. The slope and deflection must match at B for both domains

$$v'(L-) = v'(L+), v(L-) = v(L+) = 0$$



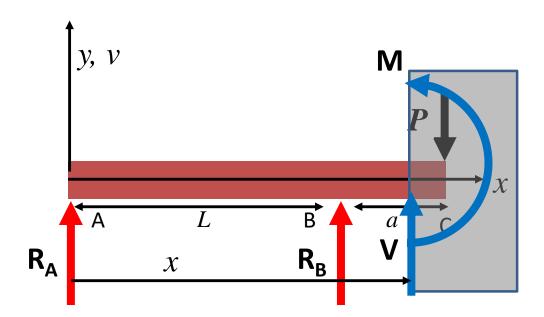
Solution for constants

$$D_1 = PL\left(\frac{4a+3L}{6}\right), D_2 = -PL^2\left(\frac{L+a}{6}\right)$$

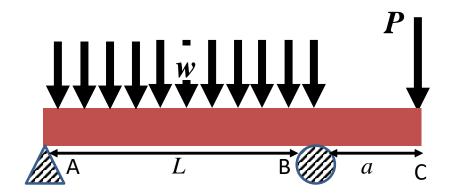


Solution for deflection curve

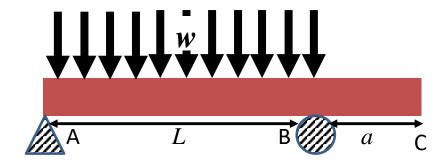
$$v'(x) = \frac{P}{EI} \left\{ \frac{x^2}{2} - (L+a)x \right\} + \frac{PL}{EI} \left(\frac{4a+3L}{6} \right)$$
$$v(x) = \frac{P}{EI} \left\{ \frac{x^3}{6} - (L+a)\frac{x^2}{2} \right\} + \frac{PL}{EI} \left(\frac{4a+3L}{6} \right) x - \frac{PL^2}{EI} \left(\frac{L+a}{6} \right)$$

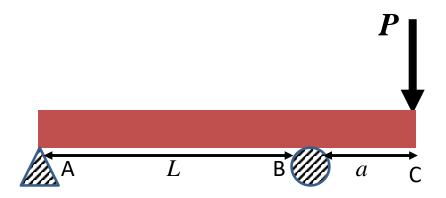


 What is the load P required to ensure that there is no deflection at C?

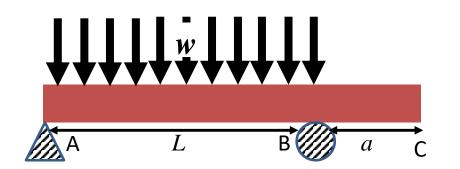


Split the problem into two parts





 Solve each problem individually for deflection in segment BC



$$v(x) = \frac{wL^3(x-L)}{24EI}$$

$$P$$
A L
B a
C

$$P \qquad v(x) = \frac{P}{EI} \left\{ \frac{x^3}{6} - (L+a)\frac{x^2}{2} \right\}$$

$$+ \frac{PL}{EI} \left(\frac{4a+3L}{6} \right) x - \frac{PL^2}{EI} \left(\frac{L+a}{6} \right)$$

$$+\frac{PL}{EI}\left(\frac{4a+3L}{6}\right)x-\frac{PL^2}{EI}\left(\frac{L+a}{6}\right)$$

 Add the solutions to find the deflection in segment BC. This is the method of superposition

$$v(x) = \frac{wL^{3}(x-L)}{24EI} + \frac{P}{EI} \left\{ \frac{x^{3}}{6} - (L+a)\frac{x^{2}}{2} \right\} + \frac{PL}{EI} \left(\frac{4a+3L}{6} \right) x - \frac{PL^{2}}{EI} \left(\frac{L+a}{6} \right)$$

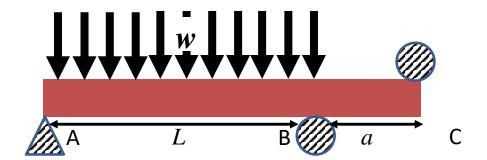
 Put x=a+L to get the deflection at C and set the answer to zero to get P

$$v(L+a) = \frac{wL^3a}{24EI} - \frac{P(L+a)a^2}{3EI}$$

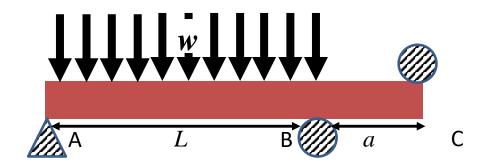
$$v(L+a) = 0 \Rightarrow \frac{wL^3a}{24EI} - \frac{P(L+a)a^2}{3EI} = 0$$

$$\Rightarrow P = \frac{wL^3}{8(L+a)a}$$

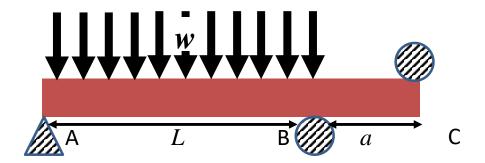
 Now consider this problem. Find the reactions at the supports for the beam loaded as shown.



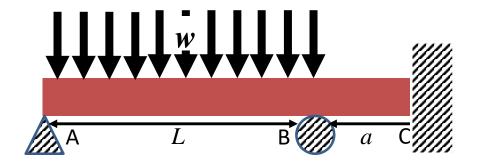
- This is A STATICALLY INDETREMINATE problem.
- We have 3 unknown reactions and only 2 static equilibrium equations.



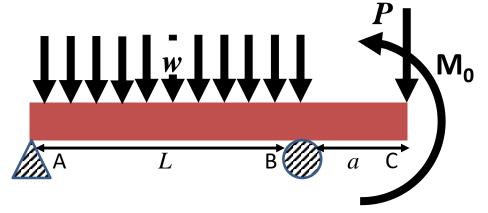
 And we have already solved the statically determinate version of this problem. The roller support at C will simply provide a reaction to maintain the zero deflection constraint.



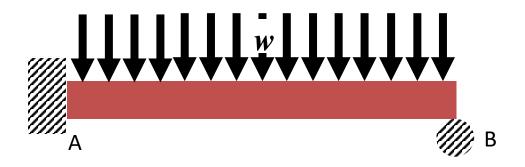
 What about the case when there is a fixed support at C?



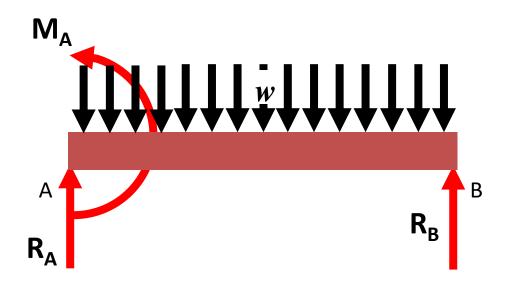
- The equivalent statically determinate problem is as follows –
- What combination of force at C and external moment will ensure zero deflection and slope at C?



Cantilever with roller support



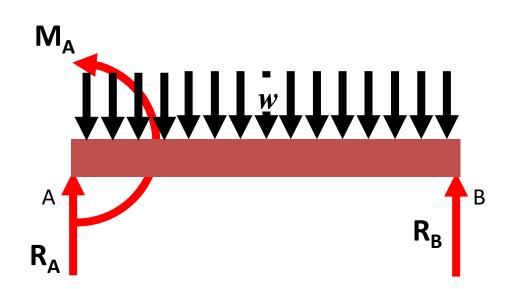
Draw the FBD



- Equilibrium equations
- Force equilibrium in the vertical direction

$$R_A + R_B = \int_0^L w dx$$

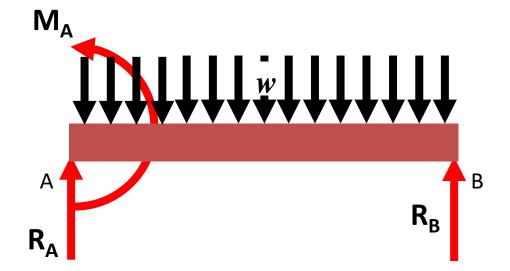
$$\Rightarrow R_A + R_B = wL$$



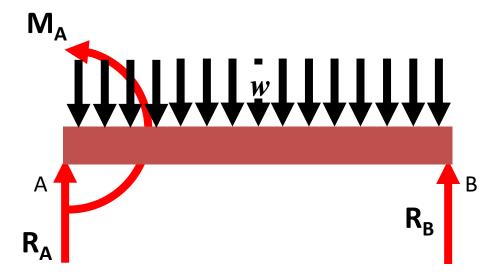
- Equilibrium equations
- Moment equilibrium about A

$$M_A + R_B L = \int_0^L x (w dx)$$

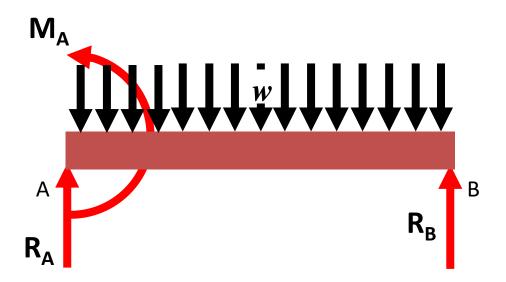
$$\Rightarrow M_A + R_B L = \frac{wL^2}{2}$$



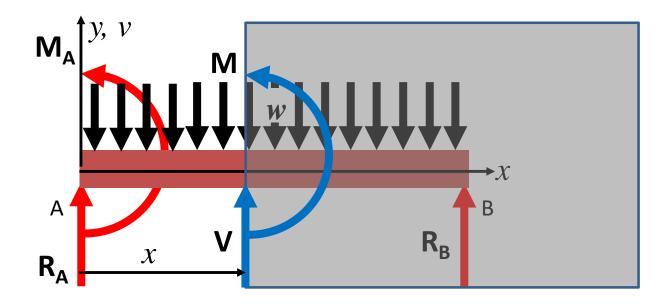
- We have 2 equations and 3 unknowns
- We have 1 extra unknowns



- Hence we will need one constraint.
- We will recast the problem considering the force at B as a unknown force that will cause zero deflection at B



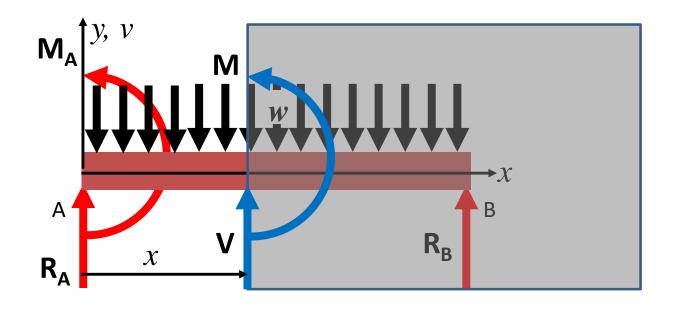
- Next we take a section between A and B.
- The internal moment and force show up at the section.



We consider the equilibrium of the section

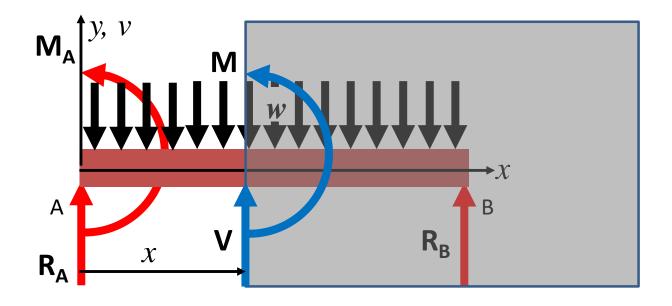
$$V + R_A - \int_0^x w d\xi = 0 \Rightarrow V(x) = wx - R_A$$

$$M_A + M + Vx - \int_0^x \xi(wd\xi) = 0 \Rightarrow M(x) = R_A x - w\frac{x^2}{2} - M_A$$



We consider the flexure equation next

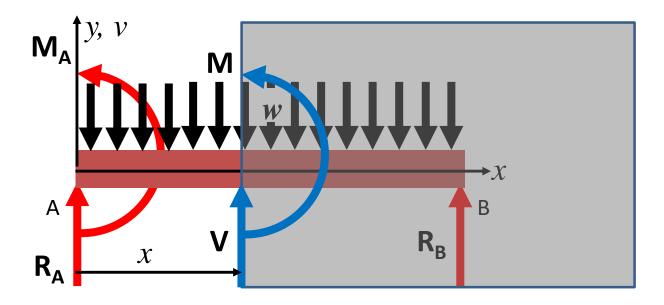
$$EIv'' = M(x) = R_A x - w \frac{x^2}{2} - M_A$$



Solving we get

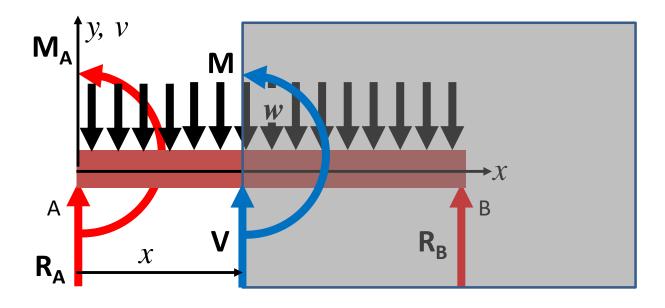
$$EIv' = R_A \frac{x^2}{2} - w \frac{x^3}{6} - M_A x + C_1$$

$$EIv = R_A \frac{x^3}{6} - w \frac{x^4}{24} - M_A \frac{x^2}{2} + C_1 x + C_2$$



The boundary conditions are

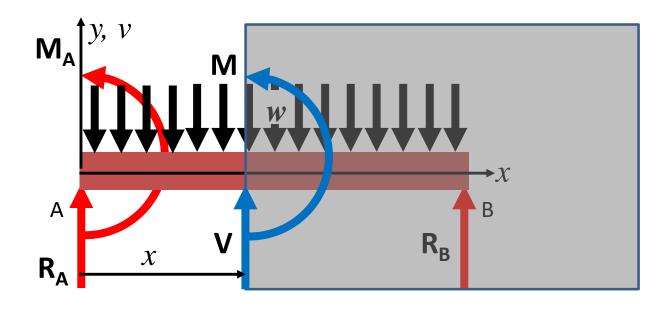
$$v'(0) = 0, v(0) = 0$$
$$v(L) = 0$$



Using BCs we get

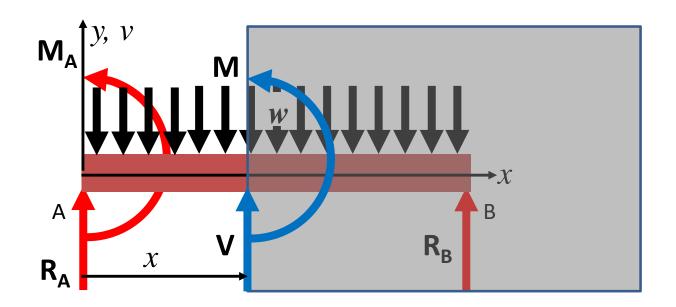
$$v'(0) = 0 \Rightarrow C_1 = 0, v(0) = 0 \Rightarrow C_2 = 0$$

$$v(L) = 0 \Rightarrow R_A \frac{L^3}{6} - w \frac{L^4}{24} - M_A \frac{L^2}{2} = 0$$



Solving we get

$$M_A = R_A \frac{L}{3} - \frac{wL^2}{12}$$



Using equations of equilibrium we can now get

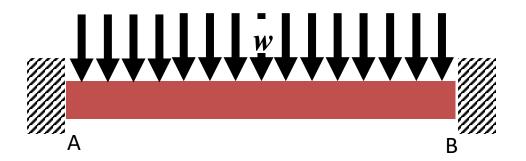
$$R_A + R_B = wL \Rightarrow R_B = wL - R_A$$

$$M_A + R_B L = \frac{wL^2}{2}$$

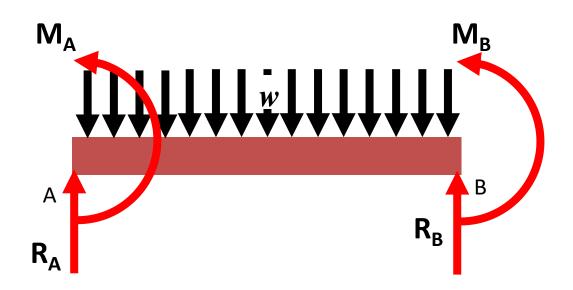
$$\Rightarrow \left(R_A \frac{L}{3} - \frac{wL^2}{12}\right) + \left(wL - R_A\right)L = \frac{wL^2}{2}$$

$$\Rightarrow R_A = \frac{15wL}{24}, R_B = \frac{9wL}{24}, M_A = \frac{wL^2}{8}$$

Double cantilever



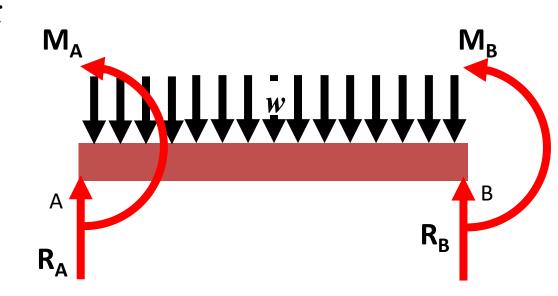
Draw the FBD



- Equilibrium equations
- Force equilibrium in the vertical direction

$$R_A + R_B = \int_0^L w dx$$

$$\Rightarrow R_A + R_B = wL$$



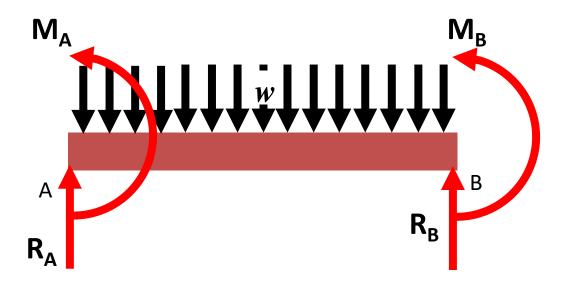
- Equilibrium equations
- Moment equilibrium about A

$$M_A + R_B L + M_B = \int_0^L x(wdx)$$

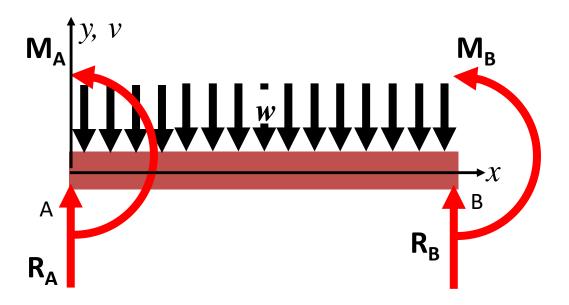
- We have 2 equations and 4 unknowns
- Even if we use the symmetry of the problem, we will be left with 2 unknowns

$$R_A = R_B = \frac{wL}{2}, M_A = -M_B$$
 M_A
 M_B
 M_B
 R_B

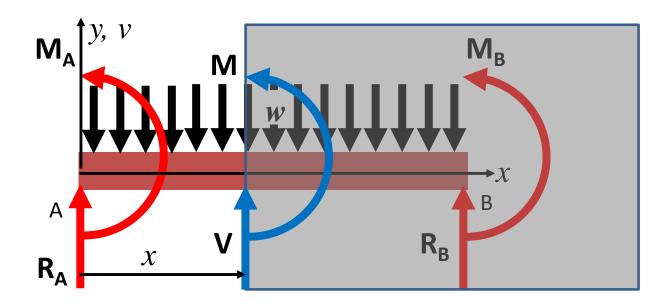
- Hence we will need two constraints
- We will recast the problem considering the moment and force at B as unknowns that will cause zero deflection and zero slope at B



- We will solve this problem without using symmetry however
- We set up a coordinate system as shown



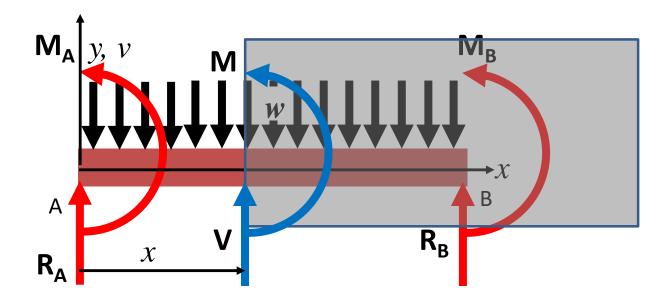
- Next we take a section between A and B.
- The internal moment and force show up at the section.



We consider the equilibrium of the section

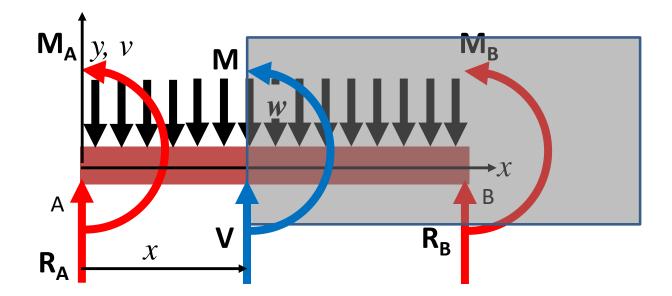
$$V + R_A - \int_0^x wd\xi = 0 \Rightarrow V(x) = wx - R_A$$

$$M_A + M + Vx - \int_0^x \xi(wd\xi) = 0 \Rightarrow M(x) = R_A x - w\frac{x^2}{2} - M_A$$



We consider the flexure equation next

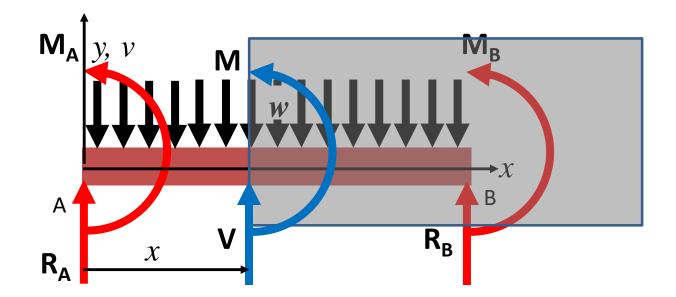
$$EIv'' = M(x) = R_A x - w \frac{x^2}{2} - M_A$$



Solving we get

$$EIv' = R_A \frac{x^2}{2} - w \frac{x^3}{6} - M_A x + C_1$$

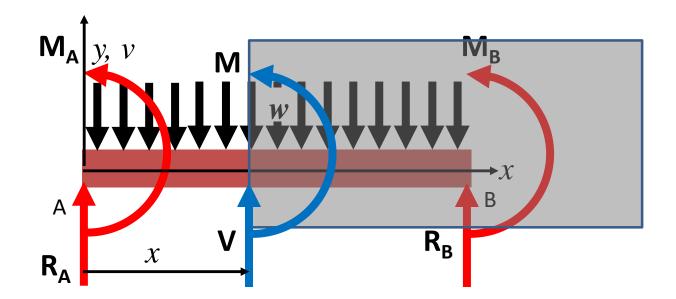
$$EIv = R_A \frac{x^3}{6} - w \frac{x^4}{24} - M_A \frac{x^2}{2} + C_1 x + C_2$$



The boundary conditions are

$$v'(0) = 0, v'(L) = 0$$

 $v(0) = 0, v(L) = 0$

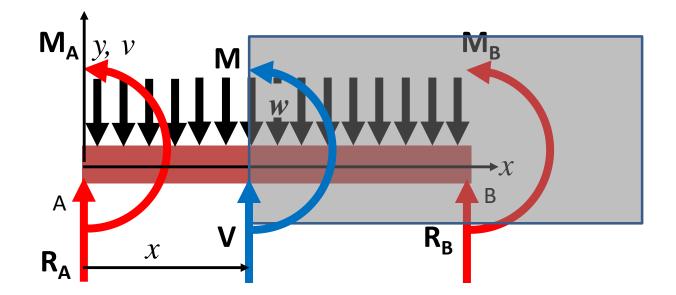


Using BCs we get

$$v'(0) = 0 \Rightarrow C_1 = 0, v(0) = 0 \Rightarrow C_2 = 0$$

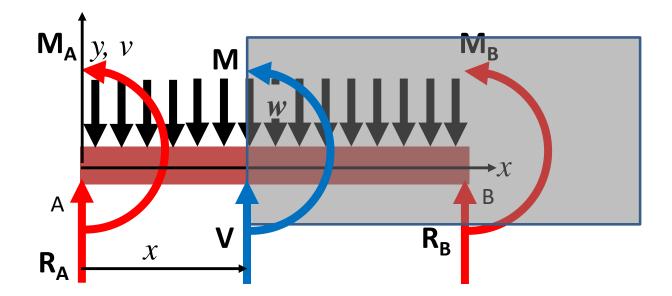
$$v'(L) = 0 \Rightarrow 3R_A L - wL^2 - 6M_A = 0$$

$$v(L) = 0 \Rightarrow 4R_A L - wL^2 - 12M_A = 0$$



Solving we get

$$R_A = \frac{wL}{2}$$
$$M_A = \frac{wL^2}{12}$$



Using equations of equilibrium we can now get

$$R_A + R_B = wL \Longrightarrow R_A = R_B = \frac{wL}{2}$$

$$M_A + M_B + R_B L = \frac{wL^2}{2} \Rightarrow M_A = -M_B = \frac{wL^2}{12}$$

