hu= lt ci=cext lt or u= yoe

The concept of statostily and convergence can be of linear equalion $u' = \lambda u$ corresponding to non-line as equation u'= f(xy). This linear from u'=> v is called test function.

Canosales (V) (linears u= +u, u(to) = 10

= exact solution is ult = 4 ext

ultjn) = Moextjn ultj) = Moextj

ultjn) = ex(tjn-tj) = exh

or ultjan) = eth ultj) - 3

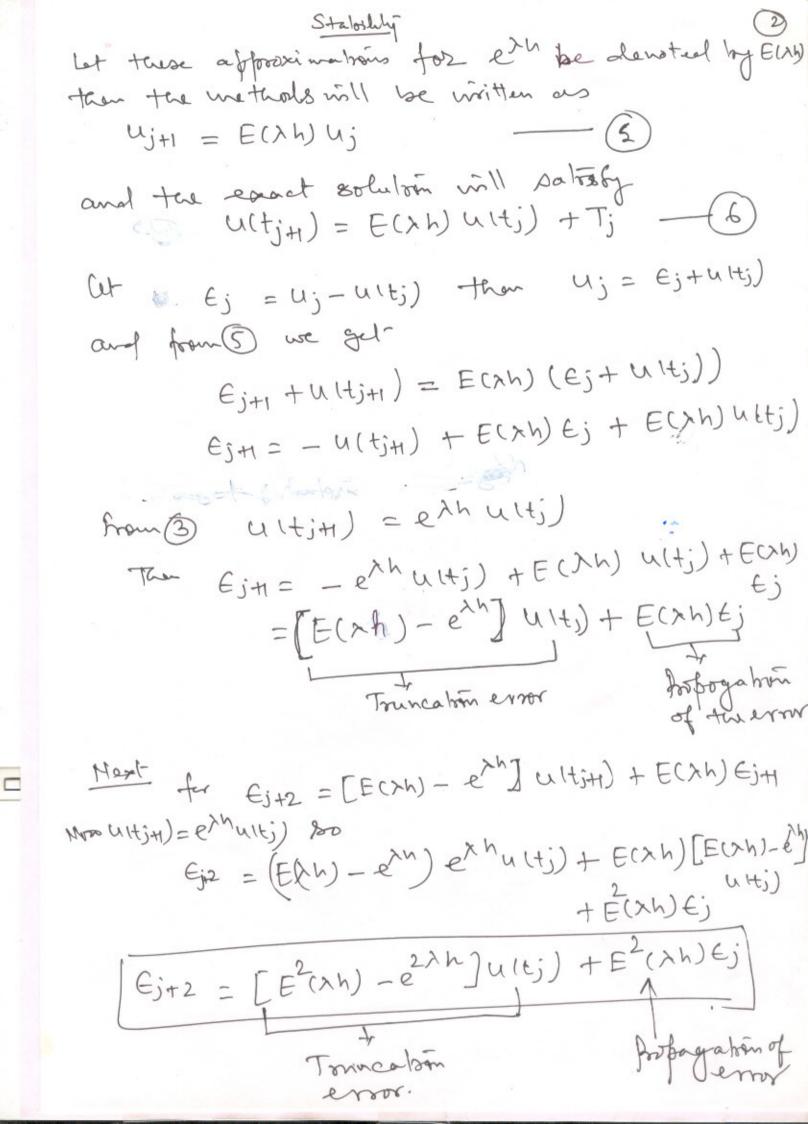
A numerical method can be obtained by writing an approximation to ext say

i) exh & 1+2h

(ii) $e^{\lambda h} \sim (+\lambda h + \frac{\lambda^2 h^2}{2} + \frac{3 h^2}{6})$ (iii) $e^{\lambda h} \sim (+\lambda h + \frac{\lambda^2 h^2}{2} + \frac{3 h^2}{6})$ (iv) $e^{\lambda h} \sim (+\lambda h + \frac{\lambda^2 h^2}{2} + \frac{\lambda^3 h^2}{6})$ (iv) $e^{\lambda h} \sim (+\lambda h + \frac{\lambda^2 h^2}{2} + \frac{\lambda^3 h^2}{6})$

(11)

Consider too problem u1= > u le, f(x,u) = > u Enter mothol = 4;+ h > 4; = (1+>h) 4; Ujti= Ujthf Taylor's second order watered u=f=xu u= du= 24 4j+1 = 4j+ huj + 1 4; = u; +kx xu; + e x2u; = [1+)h+ (h)2) 4; u"= 2u = 1.2u = 13 u Similarly for ligher order wothols. So a numerical method can be obtained by writing an apportionation to eth day ii) ether 1+2h cules mother.
iii) ether 1+2h Taylors second order wother



for furt term on r.h.s. UItj+) = ethultj) ultitz) = eth ultit) = ehulti) and numerical sof. Uj+1 = E (2h) Uj $u_{j+2} = E(xh) u_{3H} = E^2(xh) u_{3}$ Thus Tonnalin error = [E2(xh) - e2xh) u(ti) Now at j+k step. $E_{j+k} = (E^k(\lambda h) - e^{k\lambda h}) u(t_j) + E^k(\lambda h) E_j$ Trancaboneron Jestada pon of Defi A method is stable if cumulative effect of all errors, including round off errors is bounded, in dependent of week divisions. J [E(xh)] <1 = then method is Absolutely Stuble If Called absolutely Atuble. Relatively 87-161e of E(xh) < et = then the wethod is called relatively stuble.

Statoshly and hence to helakvely stuble calways) for Apsolute Atuloiluly (E(XH) / K) W -1<1+xh <1 11+2h1 <1 a -2 L > h L 0 Thus for $\lambda h \in (-2,0)$ the wethold is absolutely stuble and this interval is called interval of statorhity. (ii) E() = 1+2h + 2h (11) E(xh) = (+xh + \frac{1}{2})
Agrain for >>0 E(xh) < eth thews
for >>0 the method is relatively thatle for Alosolute stability 1 E(xh) (< 1 いり 15(1+2り) ナリント 1+24+ 22 1 (2h2+2xh+2) = 支[(1+入り2+1] -1 < =[1+2h)2+1] < 1 $-2<(1+\lambda h)^2+1<2$ The left hand toode in equality is always satisfied for 2-4.5.

(1+xh)2+1 < 2 ar (1+1/2)2 < 1 -1 < (th h) < 1 -24 hh <0 so interval of statisting is (-2,0). = - : 979 $\frac{1}{2}$ $\frac{1}$ So the (-2-5,0). (IV) Similarly for E(Xh) = 1+Xh+ x2+ x3x3+ x4x4 E(Xh) = 1+Xh+ x2+ x3x3+ x4x4 $\frac{2h}{E(2h)}$ | 0 -1 -2 -2.2 -2.6 -3.0 $\frac{2h}{E(2h)}$ | 0.3750 0.333 0.4212 .7547 1.375 (V) $E(x) = \frac{1+xy_2}{1-xy_2}$ We want |E(x)| < 1 or $|\frac{1+xy_2}{1-xy_2}| < 1$ or 11+2/2/2/1-242/ -8 for XLD in equality D is always Salvehiool, so interval of abosolute statoility (-00,0). Such method are called. unconditionally stuble.

6

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Stability
Euler Method
 Apply Euler weterd for y'=\lambda y'
       Jn+1 = Jn+ AhJn
        Jn41 = (1+ xh) In
        E(x) = 1+xh
     2nd Ords R-12 method
     Jn+1 = Jn+ 1 (K1+3k2)
        K1= hf(2n, 7n)
        K2 = hf (m+ 3/2h, yn+ 2/3 k1)
   Apply R-4 method for y'= 2y
      K2=W(yn+2/3 K1)
           ニトン(カナなかみずり)
            =[hx + 2/3 (hx)2 ] yn
     Jnn = Jn+ [4 h) + 3 (hx) - 3 (hx) - ]
```

= [1+ h入+ 22] ブル

E(xh) = 1+ hx + h2x2

Statishly .

The order R-1 method $Y_{n+1} = Y_{n} + \frac{1}{6} \left[K_1 + 2 K_2 + 2 K_3 + K_4 \right]$ $K_1 = k_1 \left(2 k_1 + 2 k_2 \right) \quad \text{and} \quad \frac{1}{2} k_1$ $K_2 = k_1 \left(2 k_1 + k_2 \right) \quad \text{and} \quad \frac{1}{2} k_2$ $K_3 = k_1 \left(2 k_1 + k_2 \right) \quad \text{and} \quad \frac{1}{2} k_2$ $K_4 = k_1 \left(2 k_1 + k_2 \right) \quad \text{and} \quad k_3$ $K_4 = k_1 \left(2 k_1 + k_2 \right) \quad \text{and} \quad k_4 = k_4$ $K_1 = k_1 \quad \text{and} \quad k_5 \quad \text{and} \quad k_6 \quad \text{and} \quad k_7 \quad \text{and} \quad k_8 \quad \text{and} \quad k_8 \quad \text{and} \quad k_9 \quad \text{and} \quad$

 $k_{2} = h\lambda \left[y_{n} + \frac{1}{2} h\lambda y_{n} \right]$ $= \left[h\lambda + \frac{1}{2} (h\lambda)^{2} \right] y_{n}$

 $K_3 = h\lambda (y_n + \frac{1}{2} K_2)$ = $h\lambda [y_n + \frac{1}{2} (h\lambda + \frac{1}{2} (h\lambda)^2) y_n]$ = $h\lambda + \frac{1}{2} (h\lambda)^2 + \frac{1}{4} (h\lambda)^3] y_n$

 $K_{4} = h\lambda (y_{n} + K_{3})$ $= h\lambda [y_{n} + (h\lambda) + \frac{1}{2}(h\lambda)^{2} + \frac{1}{4}(h\lambda)^{3})y_{3}$ $= [h\lambda + (h\lambda)^{2} + \frac{1}{2}(h\lambda)^{3} + \frac{1}{4}(h\lambda)^{4}]y_{n}$ $= [h\lambda + (h\lambda)^{2} + \frac{1}{2}(h\lambda)^{3} + \frac{1}{4}(h\lambda)^{4}]y_{n}$