

Mains Test Series - 2018

Test-5 Answer Key (Paper-I)

1(c) Find the values of  $a$  and  $b$  in order that  $\lim_{x \rightarrow 0} \frac{x(1+a\cos x) - b\sin x}{x^3}$  may be equal to 1.

Sol<sup>n</sup>:  $\lim_{x \rightarrow 0} \frac{x(1+a\cos x) - b\sin x}{x^3}$

It is a  $\frac{0}{0}$  form and so by L'Hospital's rule.

$$= \lim_{x \rightarrow 0} \frac{(1+a\cos x) - ax\sin x - b\cos x}{3x^2} \quad \text{--- (1)}$$

the denominator of (1)  $\rightarrow 0$  as  $x \rightarrow 0$  but

(1)  $\rightarrow$  a finite limit 1.

$\therefore$  The numerator  $(1+a\cos x - ax\sin x - b\cos x)$  must  $\rightarrow 0$  as  $x \rightarrow 0$

$$\therefore 1+a-b=0 \quad \text{--- (2)}$$

Also if the relation (2) holds, then

$$\lim_{x \rightarrow 0} \frac{1+(a-b)\cos x - ax\sin x}{3x^2}$$

$$= \lim_{x \rightarrow 0} \frac{-(a-b)\sin x - a\sin x - ax\cos x}{6x} \quad \left(\frac{0}{0} \text{ form}\right)$$

$$= \lim_{x \rightarrow 0} \frac{-(a-b)\cos x - 2a\cos x + ax\sin x}{6}$$

$$= \frac{-a+b-2a}{6} = \frac{-3a+b}{6} = 1 \text{ (given)}$$

$$\Rightarrow -3a+b=6 \quad \text{--- (3)}$$

solving (2) & (3), we get

$$\boxed{a = -\frac{5}{2}, b = -\frac{3}{2}}$$

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1(d) Find the volume of the region lying below the paraboloid with equation  $z = 4 - x^2 - y^2$  and above the  $xy$ -plane.

Sol<sup>n</sup>: Since the paraboloid intersects the  $xy$ -plane when

$$4 - x^2 - y^2 = 0,$$

i.e., when  $x^2 + y^2 = 4$

$V$  is the volume of the region bounded by  $f(x, y) = 4 - x^2 - y^2$  and below by the region  $D = \{(x, y) : x^2 + y^2 \leq 4\}$

If we describe  $D$  as  $D = \{x, y) : -2 \leq x \leq 2, -\sqrt{4-x^2} \leq y \leq \sqrt{4-x^2}\}$ , then we may compute

$$\begin{aligned} V &= \iint_D (4 - x^2 - y^2) dx dy \\ &= \int_{-2}^2 \int_{-\sqrt{4-x^2}}^{\sqrt{4-x^2}} (4 - x^2 - y^2) dy dx = \int_{-2}^2 \left( 4y - x^2 y - \frac{y^3}{3} \right) \Big|_{-\sqrt{4-x^2}}^{\sqrt{4-x^2}} dx \\ &= \int_{-2}^2 \left( 8\sqrt{4-x^2} - 2x^2\sqrt{4-x^2} - \frac{2}{3}(4-x^2)^{3/2} \right) dx \\ &= 2 \int_{-2}^2 \left( (4-x^2)\sqrt{4-x^2} - \frac{1}{3}(4-x^2)^{3/2} \right) dx \\ &= \frac{4}{3} \int_{-2}^2 (4-x^2)^{3/2} dx \end{aligned}$$

Using the substitution  $x = 2 \sin \theta$ , we have  $dx = 2 \cos \theta d\theta$ , and so

$$\begin{aligned} V &= \frac{4}{3} \int_{-2}^2 (4-x^2)^{3/2} dx \\ &= \frac{4}{3} \int_{-\pi/2}^{\pi/2} (4-4\sin^2 \theta)^{3/2} 2 \cos \theta d\theta = \frac{64}{3} \int_{-\pi/2}^{\pi/2} \cos^4 \theta d\theta \\ &= \frac{64}{3} \int_{-\pi/2}^{\pi/2} \left( \frac{1+\cos 2\theta}{2} \right)^2 d\theta = \frac{16}{3} \int_{-\pi/2}^{\pi/2} (1+2\cos 2\theta + \cos^2 2\theta) d\theta \\ &= \frac{16}{3} \left[ \theta \right]_{-\pi/2}^{\pi/2} + \left[ \sin 2\theta \right]_{-\pi/2}^{\pi/2} + \int_{-\pi/2}^{\pi/2} \frac{1+\cos 4\theta}{2} d\theta \\ &= \frac{16}{3} \left( \pi + \left[ \frac{\theta}{2} \right]_{-\pi/2}^{\pi/2} + \frac{1}{8} (\sin 4\theta) \Big|_{-\pi/2}^{\pi/2} \right) \\ &= \frac{16}{3} \left( \pi + \frac{\pi}{2} \right) = 8\pi \end{aligned}$$



10 Find the volume of a tetrahedron in terms of the lengths of the three edges which meet in a point and of the angles which these edges make with each other in pairs.

Sol'n: Let  $OABC$  be a tetrahedron.

Let  $OA=a, OB=b, OC=c$ .

Let  $\angle BOC=\lambda, \angle COA=\mu, \angle AOB=\nu$

we take 'O' as origin and any system of three mutually Har lines through O as coordinate axes.

Let the direction cosines of the

lines  $OA, OB, OC$  be  $l_1, m_1, n_1; l_2, m_2, n_2; l_3, m_3, n_3$

Thus, the coordinates of  $A, B, C$  are

$(l_1a, m_1a, n_1a); (l_2b, m_2b, n_2b); (l_3c, m_3c, n_3c)$

$\therefore$  the volume of the tetrahedron  $OABC$

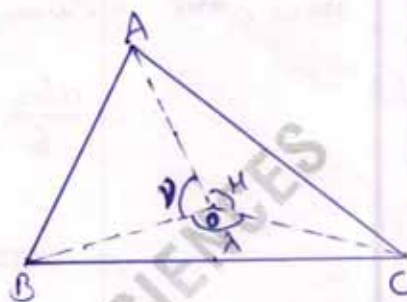
$$= \frac{1}{6} \begin{vmatrix} 0 & 0 & 0 & 1 \\ l_1a & m_1a & n_1a & 1 \\ l_2b & m_2b & n_2b & 1 \\ l_3c & m_3c & n_3c & 1 \end{vmatrix} = \frac{1}{6} \begin{vmatrix} l_1a & m_1a & n_1a \\ l_2b & m_2b & n_2b \\ l_3c & m_3c & n_3c \end{vmatrix}$$

$$= \frac{abc}{6} \begin{vmatrix} l_1 & m_1 & n_1 \\ l_2 & m_2 & n_2 \\ l_3 & m_3 & n_3 \end{vmatrix}$$

Now

$$\begin{vmatrix} l_1 & m_1 & n_1 \\ l_2 & m_2 & n_2 \\ l_3 & m_3 & n_3 \end{vmatrix}^2 = \begin{vmatrix} l_1 & m_1 & n_1 \\ l_2 & m_2 & n_2 \\ l_3 & m_3 & n_3 \end{vmatrix} \times \begin{vmatrix} l_1 & m_1 & n_1 \\ l_2 & m_2 & n_2 \\ l_3 & m_3 & n_3 \end{vmatrix}$$

$$= \begin{vmatrix} \sum l_i^2 & \sum l_1l_2 & \sum l_1l_3 \\ \sum l_1l_2 & \sum l_2^2 & \sum l_2l_3 \\ \sum l_3l_1 & \sum l_3l_2 & \sum l_3^2 \end{vmatrix}$$



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$$= \begin{vmatrix} 1 & \cos \nu & \cos \mu \\ \cos \nu & 1 & \cos \lambda \\ \cos \mu & \cos \lambda & 1 \end{vmatrix}$$

Thus, the volume of the tetrahedron OABC

$$= \frac{abc}{6} \begin{vmatrix} 1 & \cos \nu & \cos \mu \\ \cos \nu & 1 & \cos \lambda \\ \cos \mu & \cos \lambda & 1 \end{vmatrix}^{\frac{1}{2}}$$

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2(a) Investigate for what values of  $\lambda, \mu$  the simultaneous equations  $x+y+z=6$ ,  $x+2y+3z=10$ ,  $x+2y+\lambda z=\mu$  have (i) no solution, (ii) a unique solution (iii) an infinite number of solutions.

Sol<sup>n</sup>: The matrix form of the given system of equations is

$$AX = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 2 & \lambda \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 6 \\ 10 \\ \mu \end{bmatrix} = B$$

the augmented matrix

$$[A \ B] = \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 6 \\ 1 & 2 & 3 & 10 \\ 1 & 2 & \lambda & \mu \end{array} \right]$$

$$\sim \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 6 \\ 0 & 1 & 2 & 4 \\ 0 & 1 & \lambda-1 & \mu-6 \end{array} \right] \begin{array}{l} R_2 \rightarrow R_2 - R_1 \\ R_3 \rightarrow R_3 - R_1 \end{array}$$

$$\sim \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 6 \\ 0 & 1 & 2 & 4 \\ 0 & 0 & \lambda-3 & \mu-10 \end{array} \right] R_3 \rightarrow R_3 - R_2$$

\* If  $\lambda=3$  &  $\mu \neq 10$  then  $\rho(A|B)=3$  &  $\rho(A)=2$

$$\therefore \rho(A|B) \neq \rho(A)$$

$\therefore$  the given equations have no solutions.

$\rightarrow$  If  $\lambda \neq 3$  and  $\mu = \text{any value}$  then  $\rho(A|B) = \rho(A) = 3 =$  the number of unknown variables.

$\therefore$  The equations are consistent and have unique solution.

$\rightarrow$  If  $\lambda=3$  and  $\mu=10$  then  $\rho(A|B) = \rho(A) = 2 <$  the number of unknown variables.

$\therefore$  the given equations are consistent and have infinite solutions.

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2(b) → If  $\alpha$  is a characteristic root of a non-singular matrix  $A$ , then prove that  $\frac{|A|}{\alpha}$  is a characteristic root of  $\text{Adj } A$ .

Sol'n: Since  $\alpha$  is a characteristic root of a non-singular matrix, therefore  $\alpha \neq 0$ . Also  $\alpha$  is a characteristic root of  $A$  implies that there exists a non-zero vector  $x$  such that

$$\begin{aligned} Ax &= \alpha x \\ \Rightarrow (\text{Adj } A)(Ax) &= (\text{Adj } A)(\alpha x) \\ \Rightarrow [(\text{Adj } A)A]x &= \alpha (\text{Adj } A)x \\ \Rightarrow |A|Ix &= \alpha (\text{Adj } A)x \quad [\because (\text{Adj } A) = |A|I] \\ \Rightarrow |A|x &= \alpha (\text{Adj } A)x \quad [\because Ix = x] \\ \Rightarrow \frac{|A|}{\alpha}x &= (\text{Adj } A)x \quad [\because \alpha \neq 0] \\ \Rightarrow (\text{Adj } A)x &= \frac{|A|}{\alpha}x. \end{aligned}$$

Since  $x$  is a non-zero vector, therefore from the relation (1) it is obvious that  $\frac{|A|}{\alpha}$  is a characteristic root of the matrix  $\text{Adj } A$ .

2(c) → show that the function  $f$ , where

$$f(x, y) = \begin{cases} \frac{x^3 - y^3}{x^2 + y^2}, & (x, y) \neq (0, 0) \\ 0, & (x, y) = (0, 0) \end{cases}$$

is continuous possesses partial derivations but is not differentiable at the origin.

Sol'n: put  $x = r \cos \theta$ ,  $y = r \sin \theta$

$$\begin{aligned} \therefore \left| \frac{x^3 - y^3}{x^2 + y^2} \right| &= |r(\cos^3 \theta - \sin^3 \theta)| \leq 2|r| = 2\sqrt{x^2 + y^2} < \varepsilon, \\ x^2 &< \frac{\varepsilon^2}{8}, \quad y^2 < \frac{\varepsilon^2}{8} \end{aligned}$$



(or), if  $|x| < \frac{\epsilon}{2\sqrt{2}}, |y| < \frac{\epsilon}{2\sqrt{2}}$

$\therefore \left| \frac{x^3 - y^3}{x^2 + y^2} - 0 \right| < \epsilon$ , when  $|x| < \frac{\epsilon}{2\sqrt{2}}, |y| < \frac{\epsilon}{2\sqrt{2}}$

$\Rightarrow \lim_{(x,y) \rightarrow (0,0)} \frac{x^3 - y^3}{x^2 + y^2} = 0$

$\Rightarrow \lim_{(x,y) \rightarrow (0,0)} f(x,y) = f(0,0)$

Hence the function is continuous at  $(0,0)$

Again  $f_x(0,0) = \lim_{h \rightarrow 0} \frac{f(h,0) - f(0,0)}{h} = \lim_{h \rightarrow 0} \frac{h-0}{h} = 1$

$f_y(0,0) = \lim_{k \rightarrow 0} \frac{f(0,k) - f(0,0)}{k} = \lim_{k \rightarrow 0} \frac{-k}{k} = -1$

Thus, the function possesses partial derivatives at  $(0,0)$ .

If the function is differentiable at  $(0,0)$ , then by definition

$df = f(h,k) - f(0,0) = Ah + Bk + h\phi + k\psi$  — (1)

where  $A$  and  $B$  are constants ( $A = f_x(0,0) = 1, B = f_y(0,0) = -1$ )

and  $\phi, \psi$  tend to zero as  $(h,k) \rightarrow (0,0)$

Putting  $h = \rho \cos \theta, k = \rho \sin \theta$ , and dividing by  $\rho$ , we get

$\cos^3 \theta - \sin^3 \theta = \cos \theta - \sin \theta + \phi \cos \theta + \psi \sin \theta$  — (2)

For arbitrary  $\theta = \tan^{-1}(h/k)$ ,  $\rho \rightarrow 0$  implies that  $(h,k) \rightarrow (0,0)$ .

Thus we get the limit,

$\cos^3 \theta - \sin^3 \theta = \cos \theta - \sin \theta$

which is plainly impossible for arbitrary  $\theta$ .

Thus, the function is not differentiable at the origin.

2(d) show that the projections of the generators of a hyperboloid on any principal plane are tangents to the section of the hyperboloid by the principle plane.

Sol<sup>n</sup>: Let the equation of the hyperboloid be

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1 \quad \text{--- (1)}$$

Consider a generator

$$\frac{x - a \cos \theta}{a \sin \theta} = \frac{y - b \sin \theta}{-b \cos \theta} = \frac{z}{c} \quad \text{--- (2)}$$

Now consider the coordinate plane  $z=0$ . The section of the hyperboloid (1) by this plane  $z=0$  is given by

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1, \quad z=0 \quad \text{--- (3)}$$

The projection of the generator (2) on the plane  $z=0$  is given by

$$\frac{x - a \cos \theta}{a \sin \theta} = \frac{y - b \sin \theta}{-b \cos \theta}, \quad z=0$$

which is a plane through the generator  $\perp$ lar to the plane  $z=0$

on simplifying it reduces to  $\frac{x}{a \sin \theta} - \frac{\cos \theta}{\sin \theta} = \frac{y}{-b \cos \theta} + \frac{\sin \theta}{\cos \theta}, \quad z=0$

$$\text{i.e. } \frac{x}{a \sin \theta} + \frac{y}{b \cos \theta} = \frac{\cos \theta}{\sin \theta} + \frac{\sin \theta}{\cos \theta} = \frac{1}{\sin \theta \cos \theta}, \quad z=0.$$

$$\text{i.e. } \frac{x}{a} \cos \theta + \frac{y}{b} \sin \theta = 1, \quad z=0$$

which is evidently a tangent to the section (3) of the hyperboloid (1) by the plane  $z=0$  at the point  $(a \cos \theta, b \sin \theta, 0)$ .

Again consider the coordinate plane  $x=0$ . The section of the hyperboloid (1) by this plane  $x=0$  is given by

$$\frac{y^2}{b^2} - \frac{z^2}{c^2} = 1, \quad x=0 \quad \text{--- (4)}$$



The projection of the generator ② on the plane  $x=0$  is given by  $\frac{y-b\sin\theta}{-b\cos\theta} = \frac{z}{c}$ ,  $x=0$  which is a plane

through the generator  $\perp$  to the plane  $x=0$ .

on simplifying it reduces to  $\frac{y}{-b\cos\theta} + \frac{\sin\theta}{\cos\theta} = \frac{z}{c}$ ,  $x=0$

$$\Rightarrow \frac{y}{b} + \frac{z\cos\theta}{c} = \sin\theta, x=0 \text{ (or)}$$

$$\Rightarrow \frac{y}{b} \operatorname{cosec}\theta + \frac{z}{c} \cot\theta = 1, x=0$$

which is evidently a tangent to the section ④ of the hyperboloid ① by the plane  $x=0$  at the point  $(0, b\operatorname{cosec}\theta, -c\cot\theta)$ .

Similarly we can prove the result by considering the plane  $y=0$ .

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3(b) The temperature at a point  $(x, y)$  on a metal is  $T(x, y) = 4x^2 - 4xy + y^2$ . An ant on the plate walks around the circle of radius 5 centred at the origin. What are the highest and lowest temperatures encountered by the ant?

Given that the temperature at a point  $(x, y)$  on a metal is  $T(x, y) = 4x^2 - 4xy + y^2$  and given the circle of radius 5 with centre  $(0, 0)$ , i.e.  $x^2 + y^2 = 25$ .

We have to find the highest and lowest temperatures encountered by the ant of the function  $T(x, y) = 4x^2 - 4xy + y^2$  — (1) subject to the constraint  $x^2 + y^2 = 25$  — (2)

Consider the function

$$F = 4x^2 - 4xy + y^2 + \lambda(x^2 + y^2 - 25)$$

$$dF = (8x - 4y + 2\lambda x) dx + (-4x + 2y + 2y\lambda) dy$$

For stationary values  $F_x = F_y = 0$

$$\Rightarrow 8x - 4y + 2\lambda x = 0 \Rightarrow (4 + \lambda)x - 2y = 0 \quad \text{--- (3)}$$

$$\text{and } -4x + 2y + 2y\lambda = 0 \Rightarrow -2x + (1 + \lambda)y = 0 \quad \text{--- (4)}$$

Eliminating  $x$  and  $y$  from (3) and (4),

$$\text{we get } \begin{vmatrix} 4 + \lambda & -2 \\ -2 & 1 + \lambda \end{vmatrix} = 0$$

$$\Rightarrow (4 + \lambda)(1 + \lambda) - 4 = 0$$

$$\Rightarrow \lambda^2 + 5\lambda = 0$$

$$\Rightarrow \lambda(\lambda + 5) = 0 \Rightarrow \lambda = 0, -5$$

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Putting  $\lambda = 0$  in (3), gives

$$4x - 2y = 0 \Rightarrow y = 2x \text{ --- (5)}$$

from (2) and (5), we get

$$x^2 + (4x)^2 = 25 \Rightarrow 5x^2 = 25$$

$$\Rightarrow x = \pm\sqrt{5} \text{ and } y = \pm 2\sqrt{5}$$

Putting  $\lambda = -5$  in (3), gives,

$$-x - 2y = 0 \Rightarrow x = -2y \text{ --- (6)}$$

∴ from (2) and (6), we get

$$4y^2 + y^2 = 25 \Rightarrow y = \pm\sqrt{5}$$

$$\text{and } x = \mp 2\sqrt{5}$$

∴ the points are  $(\sqrt{5}, 2\sqrt{5})$ ,  $(-\sqrt{5}, -2\sqrt{5})$

and  $(2\sqrt{5}, +\sqrt{5})$ ,  $(2\sqrt{5}, -\sqrt{5})$

At  $(2\sqrt{5}, -\sqrt{5})$ ,

$$T(x, y) = 80 - 4(10) + 5 = 125$$

$$\text{At } (-2\sqrt{5}, \sqrt{5}) = 80 + 40 + 5 = 125$$

$$\text{At } (\sqrt{5}, 2\sqrt{5}) = 20 - 40 + 20 = 0$$

$$\text{At } (-\sqrt{5}, -2\sqrt{5}) = 20 + 40 + 20 = 0$$

∴ Maximum  $T = 125$  at  $\pm(2\sqrt{5}, -\sqrt{5})$

and minimum  $T = 0$  at  $\pm(\sqrt{5}, 2\sqrt{5})$

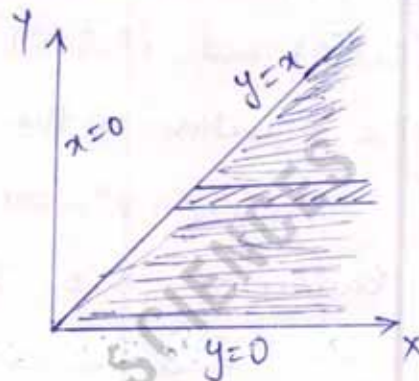
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3(b)(ii) Evaluate the integral  $\int_0^\infty \int_0^x x e^{-x^2/y} dx dy$  by changing the order of integration.

Soln: The limits of integration are given by the straight lines  $y=x$ ,  $y=0$ ,  $x=0$  and  $x=\infty$

i.e. the region of integration is bounded by  $y=0$ ,  $y=x$  and infinite boundary.



Hence taking the strips parallel to  $x$ -axis, the limits for  $y$  are from  $0$  to  $\infty$ .

from  $x=y$  to  $x=\infty$ .

Hence changing the order of integration

we have

$$\int_0^\infty \int_0^x x e^{-x^2/y} dx dy = \int_{y=0}^\infty \int_{x=y}^\infty x e^{-x^2/y} dx dy$$

$$= - \int_{y=0}^\infty \int_{-y}^0 \frac{y}{2} e^t dt dy$$

$$= - \int_0^\infty \frac{y}{2} (e^t)_{-y}^{-\infty} dy$$

$$= \int_0^\infty \frac{y}{2} e^{-y} dy$$

$$= \frac{1}{2} [-y e^{-y} + e^{-y}]_0^\infty$$

$$= \frac{1}{2} [-y e^{-y} - e^{-y}]_0^\infty$$

$$= \frac{1}{2} [0 - (0-1)]$$

$$= \frac{1}{2}$$

$$\left[ \begin{array}{l} \text{Let } \frac{x^2}{y} = t \\ -\frac{2x}{y} dx = dt \\ \Rightarrow x dx = -\frac{y}{2} dt \\ \text{Limits} \\ \text{when } x=y \\ -\frac{y^2}{y} = t \Rightarrow t = -y \\ \text{when } x=\infty \\ t=\infty \end{array} \right.$$

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3(C)

→ A sphere of constant radius  $2k$  passes through the origin and meets the axes in  $A, B, C$ . Find the locus of the centroid of the tetrahedron  $OABC$ .

Sol'n: Let coordinates of the points  $A, B, C$  be  $(a, 0, 0)$ ,  $(0, b, 0)$  and  $(0, 0, c)$  respectively.

The equation of the sphere  $OABC$  is

$$x^2 + y^2 + z^2 - ax - by - cz = 0.$$

Radius of this sphere is given equal to  $2k$ .

$$\therefore a^2 + b^2 + c^2 = 4(2k)^2 = 16k^2 \quad \text{--- (1)}$$

Let  $(x, y, z)$  be the coordinates of the centroid of the tetrahedron  $OABC$ : then

$$x = a/4, \quad y = b/4, \quad z = c/4$$

$$\Rightarrow a = 4x, \quad b = 4y, \quad c = 4z$$

Eliminating  $a, b, c$  from (1), the required locus is

$$\underline{\underline{x^2 + y^2 + z^2 = k^2}}$$



4(b) (i) If  $u = \cos^{-1} \frac{x+y}{\sqrt{x}+\sqrt{y}}$ , show that  $x \frac{du}{dx} + y \frac{du}{dy} + \frac{1}{2} \cot u = 0$ .

(ii) show that  $\int_0^\pi \log(1+\cos x) dx = -\pi \log 2$ .

Sol<sup>n</sup>: (ii) Let  $I = \int_0^\pi \log(1+\cos x) dx$  ——— (1)

$$\text{then } I = \int_0^\pi \log[1+\cos(\pi-x)] dx$$

$$\Rightarrow I = \int_0^\pi \log(1-\cos x) dx \text{ ——— (2)}$$

$\therefore$  Adding (1) and (2), we get

$$2I = \int_0^\pi [\log(1+\cos x) + \log(1-\cos x)] dx$$

$$= \int_0^\pi \log(1-\cos^2 x) dx$$

$$= \int_0^\pi \log \sin^2 x dx$$

$$= 2 \int_0^\pi \log \sin x dx = 4 \int_0^{\pi/2} \log \sin x dx$$

$$= -4 \cdot \frac{\pi}{2} \log 2$$

$$I = -\pi \log 2$$

(i) Let  $z = \cos u = \frac{x+y}{\sqrt{x}+\sqrt{y}} = \frac{x \left(1+\frac{y}{x}\right)}{\sqrt{x} \left(1+\sqrt{y/x}\right)} = x^{1/2} \left(\frac{1+y/x}{1+\sqrt{y/x}}\right)$

$z$  is a homogeneous function of  $x$  and  $y$

of degree  $\frac{1}{2}$ .

$$x \frac{\partial z}{\partial x} + y \frac{\partial z}{\partial y} = \frac{1}{2} z \text{ ——— (2)}$$

from (1),  $\frac{\partial z}{\partial x} = -\sin u \frac{\partial u}{\partial x}$

and  $\frac{\partial z}{\partial y} = -\sin u \frac{\partial u}{\partial y}$

from (2)

$$-x \sin u \frac{\partial u}{\partial x} - y \sin u \frac{\partial u}{\partial y} = \frac{1}{2} \cos u$$

$$x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} = -\frac{1}{2} \cot u$$

$$\Rightarrow x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} + \frac{1}{2} \cot u = 0$$

$$\frac{1}{x} \frac{\partial u}{\partial x} + \frac{1}{y} \frac{\partial u}{\partial y} + \frac{1}{2} \cot u = 0$$

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4(c) Lines are drawn through the origin with direction cosines proportional to  $(1, 2, 2)$ ,  $(2, 3, 6)$ ,  $(3, 4, 12)$ . Show that the axis of the right circular cone through them has direction cosines  $-\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}$  and that the semi-vertical angle of the cone is  $\cos^{-1}(\frac{1}{\sqrt{3}})$ .

Sol'n: The vertex of the cone is  $O(0, 0, 0)$  and so let the equation of its axis be

$$\frac{x}{l} = \frac{y}{m} = \frac{z}{n}, \text{ where } l, m, n \text{ are direction cosines.} \quad \text{--- ①}$$

Let  $\theta$  be the semi-vertical angle of the cone. Then the given lines with direction ratios  $(1, 2, 2)$ ,  $(2, 3, 6)$ ,  $(3, 4, 12)$  (or) direction cosines  $(\frac{1}{3}, \frac{2}{3}, \frac{2}{3})$ ,  $(\frac{2}{7}, \frac{3}{7}, \frac{6}{7})$ ,  $(\frac{3}{13}, \frac{4}{13}, \frac{12}{13})$  make angle  $\theta$  with ①

$$\begin{aligned} \therefore \text{ we have } \cos \theta &= l(\frac{1}{3}) + m(\frac{2}{3}) + n(\frac{2}{3}) \\ &= l(\frac{2}{7}) + m(\frac{3}{7}) + n(\frac{6}{7}) \\ &= l(\frac{3}{13}) + m(\frac{4}{13}) + n(\frac{12}{13}) \end{aligned}$$

from these we have

$$(\frac{1}{3})l + (\frac{2}{3})m + (\frac{2}{3})n = (\frac{2}{7})l + (\frac{3}{7})m + (\frac{6}{7})n \quad \text{--- ②}$$

$$\text{and } (\frac{1}{3})l + (\frac{2}{3})m + (\frac{2}{3})n = (\frac{3}{13})l + (\frac{4}{13})m + (\frac{12}{13})n$$

(or)  $\dots$

$$(\frac{1}{21})l + (\frac{5}{21})m - (\frac{4}{21})n = 0$$

$$\text{and } (\frac{4}{39})l + (\frac{14}{39})m - (\frac{10}{39})n = 0$$

$$\Rightarrow 2l + 5m - 4n = 0 \quad \text{and} \quad 2l + 7m - 5n = 0$$

Solving these simultaneously we get

$$\frac{l}{-25+28} = \frac{m}{-8+5} = \frac{n}{7-10}$$

$$\Rightarrow \frac{l}{-1} = \frac{m}{1} = \frac{n}{1}$$

$\therefore$  Direction cosines of axis of the cone, from (1), are proportional to  $-1, 1, 1$  (or) the direction cosines are

$$\frac{-1 \cdot 1 \cdot 1}{\sqrt{(-1)^2 + 1^2 + 1^2}} \Rightarrow \frac{-1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}} \quad \text{Hence proved.}$$

Also from (2) we have

$$\cos \theta = \frac{-1}{\sqrt{3}} \left( \frac{1}{3} \right) + \frac{1}{\sqrt{3}} \left( \frac{2}{3} \right) + \frac{1}{\sqrt{3}} \left( \frac{2}{3} \right)$$

$$\cos \theta = \frac{1}{3\sqrt{3}} (-1 + 2 + 2) = \frac{1}{\sqrt{3}}$$

$$\theta = \cos^{-1} \left( \frac{1}{\sqrt{3}} \right) \quad \text{Hence proved.}$$



5(a) → Find the orthogonal trajectories of  $r = a(1 + \cos \theta)$ .

Sol<sup>n</sup>: Given family is  $r = a(1 + \cos \theta)$ , where  $a$  is parameter. ①

Taking logarithm of both sides,

$$\log r = \log a + \log(1 + \cos \theta) \quad \text{--- ②}$$

Differentiating ② w.r.t  $\theta$

$$\left(\frac{1}{r}\right) \left(\frac{dr}{d\theta}\right) = -(\sin \theta)/(1 + \cos \theta) \quad \text{--- ③}$$

which is differential equation of the family of curves ①.

Replacing  $dr/d\theta$  by  $-r^2 \left(\frac{d\theta}{dr}\right)$  in ③, the differential equation of the required trajectories is

$$\frac{1}{r} \left(-r^2 \frac{d\theta}{dr}\right) = -\frac{\sin \theta}{1 + \cos \theta}$$

$$\Rightarrow \frac{n dr}{r} = \frac{1 + \cos \theta}{\sin \theta} d\theta$$

$$\Rightarrow \frac{n dr}{r} = \frac{2 \cos^2(\theta/2) d\theta}{2 \sin(\theta/2) \cos(\theta/2)}$$

$$\Rightarrow n \frac{dr}{r} = \cos(\theta/2) d\theta$$

Integrating  $n \log r = \frac{2}{n} \times \log \sin(\theta/2) + \left(\frac{1}{n}\right) \log c$ ,  $c$  being parameter

$$\Rightarrow n^2 \log r = \log \sin^2(\theta/2) + \log c$$

$$\Rightarrow r^{n^2} = c \sin^2(\theta/2)$$

$$\Rightarrow r^{n^2} = \left(\frac{c}{2}\right) (1 - \cos \theta)$$

$$\Rightarrow r^{n^2} = b(1 - \cos \theta), \quad \text{taking } b = \frac{c}{2}.$$

which is the equation of required orthogonal trajectories with  $b$  as parameter.

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**MATHEMATICS** by K. Venkanna

5(b). Use the variation of parameters method to show that the solution of equation  $\frac{d^2 y}{dx^2} + k^2 y = \phi(x)$  satisfying the initial conditions  $y(0) = 0, y'(0) = 0$  is  $y(x) = \frac{1}{k} \int_0^x \phi(t) \sin k(x-t) dt$ .

Sol<sup>n</sup>: Given  $y'' + k^2 y = \phi(x)$ , i.e.,  $(D^2 + k^2)y = \phi(x)$ ,  $D \equiv d/dx$  — ①.

Comparing ① with  $y'' + Py' + Qy = R$  here  $R = \phi(x)$  — ②

Consider  $(D^2 + k^2)y = 0$  whose auxiliary equation is

$$D^2 + k^2 = 0 \text{ so that } D = \pm ik$$

$\therefore$  C.F of ① =  $C_1 \cos kx + C_2 \sin kx$ ,  $C_1$  &  $C_2$  being arbitrary constants. — ③

Let  $u = \cos kx$  and  $v = \sin kx$  — ④

Here  $W = \text{Wronskian of } u \text{ and } v = \begin{vmatrix} u & v \\ u_1 & v_1 \end{vmatrix}$

$$= \begin{vmatrix} \cos kx & \sin kx \\ -k \sin kx & k \cos kx \end{vmatrix} = k \neq 0. \text{ — ⑤}$$

$\therefore$  P.I of ① =  $uf(x) + vg(x)$ , where — ⑥

$$\therefore f(x) = - \int \frac{vR}{W} dx = - \int_0^x \frac{\sin kx \phi(x)}{k} dx = - \frac{1}{k} \int_0^x \phi(t) \sin kt dt \text{ — ⑦}$$

$$\text{and } g(x) = \int \frac{uR}{W} dx = \int_0^x \frac{\cos kx \phi(x)}{k} dx = \frac{1}{k} \int_0^x \phi(t) \cos kt dt \text{ — ⑧}$$

using ⑥, ⑦ and ⑧ we have

$$\begin{aligned} \text{P.I of ①} &= -\frac{1}{k} \cos kx \int_0^x \phi(t) \sin kt dt + \frac{1}{k} \sin kx \int_0^x \phi(t) \cos kt dt \\ &= \frac{1}{k} \int_0^x \phi(t) (\sin kx \cos kt - \cos kx \sin kt) dt \\ &= \frac{1}{k} \int_0^x \phi(t) \sin(kx - kt) dt \end{aligned}$$

Hence the general solution of ① is  $y = \text{C.F} + \text{P.I}$

$$\text{i.e. } y = C_1 \cos kx + C_2 \sin kx + \frac{1}{k} \int_0^x \phi(t) \sin k(x-t) dt \text{ — ⑨}$$



Putting  $x=0$  in (9) and using the given condition  $y(0)=0$ , we get  $c_1=0$

$$\therefore (9) \Rightarrow y = c_2 \sin kx + \frac{1}{k} \int_0^x \phi(t) \sin k(x-t) dt$$

Differentiating both sides of (10) w.r.t  $x$  and using Leibnitz's rule of differentiation under integral sign, we have

$$y'(x) = c_2 k \cos kx + \frac{1}{k} \left[ \int_0^x \frac{\partial}{\partial x} \{ \phi(t) \sin k(x-t) \} dt + \phi(x) \sin k(x-x) \frac{dx}{dx} - \phi(0) \sin kx \frac{d0}{dx} \right]$$

$$\Rightarrow y'(x) = c_2 k \cos kx + \int_0^x \phi(t) \cos k(x-t) dt \quad \text{--- (11)}$$

Putting  $x=0$  in (11) and using the boundary condition  $y'(0)=0$ , we get  $0 = c_2 k + 0$  so that  $c_2=0$ , as  $k \neq 0$

Putting  $c_1=0$  and  $c_2=0$  (10), the required solution is

$$y = \frac{1}{k} \int_0^x \phi(t) \sin k(x-t) dt$$

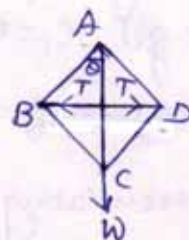
5(c)  $\rightarrow$  A frame work ABCD consists of four equal, light rods smoothly jointed together to form a square, it is suspended from a peg at A, and a weight W is attached to C, the frame work being kept in shape by a light rod connecting B and D. Determine the thrust in this rod.

Sol'n: Let T be the thrust in the rod and  $AB = AD = BC = DC = a$ . Let  $\angle BAC = \theta$ . Consider a virtual displacement in which  $\theta$  increases by  $\delta\theta$ .

$$\begin{aligned} \text{Virtual work done by the weight } W &= W \cdot \delta(AC) \\ &= W \delta (a \cos \theta + a \cos \theta) \\ &= W \delta (2a \cos \theta), \text{ along AC} \end{aligned}$$

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**MATHEMATICS** by K. Venkanna

Virtual work done by the thrust  $T = T \cdot \delta(BD)$   
 $= T\delta(a \sin \theta + a \sin \theta)$   
 $= T\delta(2a \sin \theta).$



Sum of the virtual works done by  $W$  and  $T$  is  $= W\delta(2a \cos \theta) + T\delta(2a \sin \theta)$

By the principle of virtual work, we have  
 $W\delta(2a \cos \theta) + T\delta(2a \sin \theta) = 0$

$$\Rightarrow -2aw \sin \theta d\theta + 2aT \cos \theta d\theta = 0$$

$$\Rightarrow (-w \sin \theta + T \cos \theta) d\theta = 0$$

Since  $d\theta$  is arbitrary,  $-w \sin \theta + T \cos \theta = 0.$

$$T = w \tan \theta$$

In equilibrium,  $\theta = 45^\circ$ , Hence  $T = w.$

5(d) A particle of mass  $m$ , is falling under the influence of gravity through a medium whose resistance equals  $\mu$  times the velocity. If the particle were released from rest, determine the distance fallen through in time  $t$ .

Sol'n: Let a particle of mass  $m$  falling under gravity be at a distance  $x$  from the starting point, after time  $t$ . If  $v$  is its velocity at this point, then the resistance on the particle is  $\mu v$  acting vertically upwards i.e. in the direction of  $x$  decreasing. The weight  $mg$  of the particles acts vertically downwards i.e., in the direction of  $x$  increasing.

$\therefore$  the equation of motion of the particle is

$$m \frac{d^2 x}{dt^2} = mg - \mu v$$



$$\Rightarrow \frac{dv}{dt} = g - \frac{\mu}{m} v \quad \left[ \because \frac{d^2x}{dt^2} = \frac{dv}{dt} \right]$$

$$\Rightarrow dt = \frac{dv}{g - \frac{\mu}{m} v}$$

Integrating we have

$$t = -\frac{m}{\mu} \log \left( g - \frac{\mu}{m} v \right) + A, \text{ where } A \text{ is Constant.}$$

But initially when  $t=0, v=0$ ;

$$\therefore A = \left( \frac{m}{\mu} \right) \log g.$$

$$\therefore t = -\frac{m}{\mu} \log \left( g - \frac{\mu}{m} v \right) + \frac{m}{\mu} \log g$$

$$\Rightarrow t = -\frac{m}{\mu} \log \left\{ \frac{g - \left( \frac{\mu}{m} \right) v}{g} \right\}$$

$$\Rightarrow -\frac{\mu t}{m} = \log \left( 1 - \frac{\mu}{g m} v \right) \Rightarrow 1 - \frac{\mu}{g m} v = e^{-\mu t/m}$$

$$\Rightarrow v = \frac{dx}{dt} = \frac{g m}{\mu} (1 - e^{-\mu t/m})$$

$$\Rightarrow dx = \frac{g m}{\mu} (1 - e^{-\mu t/m}) dt$$

Integrating we have

$$x = \frac{g m}{\mu} \left[ t + \frac{m}{\mu} e^{-\mu t/m} \right] + B \quad \text{where } B \text{ is constant.} \quad (1)$$

But initially when  $t=0, x=0$

$$\therefore 0 = \frac{g m}{\mu} \left[ \frac{m}{\mu} \right] + B \quad (2)$$

Subtracting (2) from (1), we have

$$x = \frac{g m}{\mu} \left[ \frac{m}{\mu} e^{-\mu t/m} - \frac{m}{\mu} + t \right] = \frac{g m^2}{\mu^2} \left[ e^{-\mu t/m} - 1 + \frac{\mu t}{m} \right]$$

5(e)  $\rightarrow$  Represent the vector  $A = z\hat{i} - 2z\hat{j} + y\hat{k}$  in cylindrical coordinates. Then determine  $A_\rho, A_\phi$  and  $A_z$ .

Sol'n: the position vector of any point in cylindrical

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Coordinates is

$$r = x\hat{i} + y\hat{j} + z\hat{k} = \rho \cos\phi \hat{i} + \rho \sin\phi \hat{j} + z\hat{k}$$

The tangent vector to the  $\rho$ ,  $\phi$  and  $z$  curves are given respectively by  $\frac{\partial r}{\partial \rho}$ ,  $\frac{\partial r}{\partial \phi}$  and  $\frac{\partial r}{\partial z}$  where

$$\frac{\partial r}{\partial \rho} = \cos\phi \hat{i} + \sin\phi \hat{j}, \quad \frac{\partial r}{\partial \phi} = -\rho \sin\phi \hat{i} + \rho \cos\phi \hat{j}, \quad \frac{\partial r}{\partial z} = \hat{k}$$

The unit vectors in these directions are

$$e_1 = e_\rho = \frac{\partial r / \partial \rho}{|\partial r / \partial \rho|} = \frac{\cos\phi \hat{i} + \sin\phi \hat{j}}{\sqrt{\cos^2\phi + \sin^2\phi}} = \cos\phi \hat{i} + \sin\phi \hat{j} \quad \text{--- (1)}$$

$$e_2 = e_\phi = \frac{\partial r / \partial \phi}{|\partial r / \partial \phi|} = \frac{-\rho \sin\phi \hat{i} + \rho \cos\phi \hat{j}}{\sqrt{\rho^2 \sin^2\phi + \rho^2 \cos^2\phi}} = -\sin\phi \hat{i} + \cos\phi \hat{j} \quad \text{--- (2)}$$

$$e_3 = e_z = \frac{\partial r / \partial z}{|\partial r / \partial z|} = \hat{k} \quad \text{--- (3)}$$

Solving (1) & (2)

$$\hat{i} = \cos\phi e_\rho - \sin\phi e_\phi, \quad \hat{j} = \sin\phi e_\rho + \cos\phi e_\phi$$

$$\text{Then } A = z\hat{i} - 2x\hat{j} + y\hat{k}$$

$$= z(\cos\phi e_\rho - \sin\phi e_\phi) - 2\rho \cos\phi (\sin\phi e_\rho + \cos\phi e_\phi) + \rho \sin\phi e_z$$

$$= (z \cos\phi - 2\rho \cos\phi \sin\phi) e_\rho - (z \sin\phi + 2\rho \cos^2\phi) e_\phi + \rho \sin\phi e_z$$

$$\text{and } A_\rho = z \cos\phi - 2\rho \cos\phi \sin\phi$$

$$A_\phi = -z \sin\phi + 2\rho \cos^2\phi$$

$$A_z = \rho \sin\phi$$



6(a) → solve  $(D^2-1)y = \cosh x \cos x + a^x$ .

Sol'n: Given  $(D^2-1)y = \cosh x \cos x + a^x = \frac{1}{2} x (e^x + e^{-x}) \cos x + a^x$

$$(D^2-1)y = \frac{1}{2} x e^x \cos x + \frac{1}{2} x e^{-x} \cos x$$

Here auxiliary equation is  $D^2-1=0 \Rightarrow D=1, -1$ .

so C.F. =  $C_1 e^x + C_2 e^{-x}$ .

P.I corresponding to  $\frac{1}{2} (e^x \cos x)$

$$= \frac{1}{2} \frac{1}{D^2-1} e^x \cos x$$

$$= \frac{e^x}{2} \frac{1}{(D+1)^2-1} \cos x = \frac{e^x}{2} \frac{1}{D^2+2D} \cos x$$

$$= \frac{e^x}{2} \frac{1}{-1^2+2D} \cos x = \frac{e^x}{2} (2D+1) \frac{1}{(2D+1)(2D-1)} \cos x$$

$$= \frac{e^x}{2} (2D+1) \frac{1}{4D^2-1} \cos x$$

$$= \frac{e^x}{2} (2D+1) \frac{1}{-4-1} \cos x = -\frac{e^x}{10} (2D+1) \cos x$$

$$= \left(-\frac{1}{10}\right) \times e^x (2D \cos x + \cos x) = \left(-\frac{1}{10}\right) \times e^x (-2 \sin x + \cos x)$$

P.I corresponding to  $\frac{1}{2} e^{-x} \cos x$

$$= \frac{1}{2} \frac{1}{D^2-1} e^{-x} \cos x = \frac{1}{2} e^{-x} \frac{1}{(D-1)^2-1} \cos x$$

$$= \frac{e^{-x}}{2} \frac{1}{D^2-2D} \cos x = \frac{e^{-x}}{2} \frac{1}{(-1^2-2D)} \cos x$$

$$= -\frac{e^{-x}}{2} (2D-1) \frac{1}{(2D-1)(2D+1)} \cos x$$

$$= -\frac{e^{-x}}{2} (2D-1) \frac{1}{4D^2-1} \cos x = -\frac{e^{-x}}{2} (2D-1) \frac{1}{4(-1)^2-1} \cos x$$

$$= \frac{1}{10} e^{-x} (2D-1) \cos x = \frac{1}{10} e^{-x} (-2 \sin x - \cos x)$$

Now P.I corresponding to  $a^x$

$$= \frac{1}{D^2-1} a^x = \frac{1}{D^2-1} e^{x \log a} = \frac{1}{(\log a)^2-1} e^{x \log a}$$

$$= \frac{1}{(\log a)^2-1} a^x$$

$\therefore$  solution is

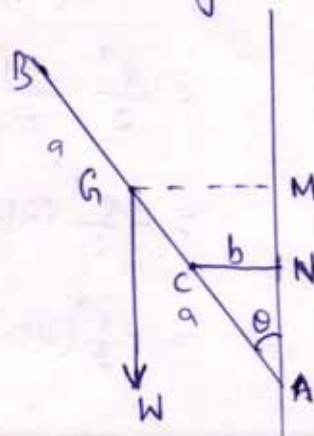
$$y = c_1 e^x + c_2 e^{-x} + \frac{2}{5} \sinh x \sin x - \frac{1}{5} \cosh x \cos x + \frac{a^x}{\{(\log a)^2-1\}}$$

6(b)

A uniform beam of length  $2a$ , rests in equilibrium against a smooth vertical wall and upon a smooth peg at a distance  $b$  from the wall. Show that in the position of equilibrium the beam is inclined to the wall at an angle  $\sin^{-1} (b/a)^{1/3}$ .

Sol'n: A uniform beam AB of length  $2a$  rests in equilibrium against smooth vertical wall and upon a smooth peg C whose distance CN from the wall is  $b$ . Suppose the rod makes an angle  $\theta$  with the wall. i.e.  $\angle BAM = \theta$ . The weight  $W$  of the rod acts at its middle point G. Give the rod a small displacement in which  $\theta$  changes to  $\theta + \delta\theta$ . The peg C remains fixed. The only force that contributes to the sum of virtual work is the weight of the rod acting at G. The reactions at A and C do not work.

We have, the height of G above the fixed point C





$$= NM = AM - AN = AG \cos \theta - CN \cot \theta$$

$$= a \cos \theta - b \cot \theta.$$

The equation of virtual work is

$$-W \delta (a \cos \theta - b \cot \theta) = 0$$

$$\Rightarrow \delta (a \cos \theta - b \cot \theta) = 0$$

$$\Rightarrow -a \sin \theta \delta \theta + b \operatorname{cosec}^2 \theta \delta \theta = 0$$

$$\Rightarrow (-a \sin \theta + b \operatorname{cosec}^2 \theta) \delta \theta = 0$$

$$\Rightarrow -a \sin \theta + b \operatorname{cosec}^2 \theta = 0$$

$[\because \delta \theta \neq 0]$

$$\Rightarrow -a \sin \theta = b \operatorname{cosec}^2 \theta$$

$$\Rightarrow \sin^3 \theta = b/a$$

$$\Rightarrow \theta = \sin^{-1} (b/a)^{1/3}$$

giving the inclination of the rod to the vertical in the position of equilibrium.

600. The end links of a uniform chain slide along a fixed rough horizontal rod. Prove that the ratio of the maximum span to the length of the chain is  $\mu \log \left\{ \frac{1 + \sqrt{1 + \mu^2}}{\mu} \right\}$ .

Sol'n: Let the ends links A & B of a uniform chain slide along a fixed rough horizontal rod. If AB is the maximum span, then A and B are in the state of limiting equilibrium.

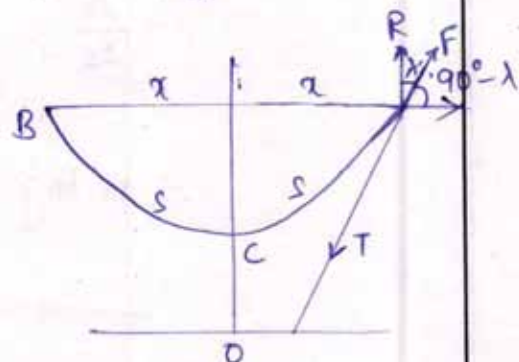
Let R be the reaction of the rod at A acting  $\perp$ lar to the rod.

Then the frictional force  $\mu R$  will act at A along the rod

in the outward direction BA.

The resultant F of the forces

R and  $\mu R$  at A will make



an angle  $\lambda$  (where  $\tan \lambda = \mu$ ) with the direction of R.  
 For the equilibrium of A the resultant F of R and  $\mu R$  at A will be equal & opposite to the tension T at A.  
 Since the tension at A acts along the tangent to the chain at A, therefore the tangent to the catenary at A makes an angle  $\psi_A = \frac{1}{2}\pi - \lambda$  to the horizontal.  
 Thus for the point A of the catenary,  
 we have  $\psi = \psi_A = \frac{1}{2}\pi - \lambda$

$\therefore$  the length of the chain

$$= 2s = 2c \tan \psi_A = 2c \tan \left( \frac{1}{2}\pi - \lambda \right)$$

$$= 2c \cot \lambda = \frac{2c}{\mu} \quad [\because \tan \lambda = \mu]$$

If  $(x_A, y_A)$  are coordinates of the point A, then the maximum span  $AB = 2x_A$

$$= 2c \log (\tan \psi_A + \sec \psi_A)$$

$$= 2c \log \{ \tan \psi_A + \sqrt{1 + \tan^2 \psi_A} \}$$

$$= 2c \log \{ \cot \lambda + \sqrt{1 + \cot^2 \lambda} \} \quad [\because \psi_A = \frac{1}{2}\pi - \lambda]$$

$$= 2c \log \left\{ \frac{1}{\mu} + \sqrt{1 + \frac{1}{\mu^2}} \right\}$$

$$= 2c \log \left\{ \frac{1 + \sqrt{1 + \mu^2}}{\mu} \right\}$$

Hence the required ratio

$$= \frac{2x}{2s} = \frac{2c \log \left\{ \frac{1 + \sqrt{1 + \mu^2}}{\mu} \right\}}{(2c/\mu)}$$

$$= \mu \log \left\{ \frac{1 + \sqrt{1 + \mu^2}}{\mu} \right\}$$

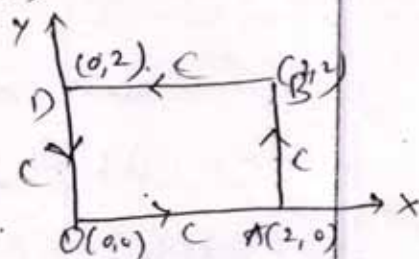


6(c) verify Stokes' theorem for  $A = (y-z+2)\hat{i} + (yz+4)\hat{j} - xz\hat{k}$ , where  $S$  is the surface of the cube  $x=0, y=0, z=0, x=2, y=2, z=2$  above the  $xy$ -plane.

Sol: The  $xy$ -plane cuts the surface of the cube in a square. Thus the curve  $C$  bounding the surface  $S$  is the square, say  $OABD$ , in the  $xy$ -plane whose vertices in the  $xy$ -plane are points  $O(0,0), A(2,0), B(2,2), D(0,2)$ .

By Stokes' theorem, we have.

$$\iint_S (\nabla \times A) \cdot \hat{n} \, dS = \oint_C A \cdot d\mathbf{r}$$



$$\oint_C A \cdot d\mathbf{r} = \int_C [(y-z+2)\hat{i} + (yz+4)\hat{j} - xz\hat{k}] \cdot (dx\hat{i} + dy\hat{j} + dz\hat{k})$$

$$= \int_C (y-z+2)dx + (yz+4)dy - xzdz$$

$$= \int_C (y+2)dx + 4dy \quad (\because \text{on } C, z=0 \text{ and } dz=0)$$

$$= \int_{OA} (y+2)dx + 4dy + \int_{AB} (y+2)dx + 4dy + \int_{BD} (y+2)dx + 4dy + \int_{DO} (y+2)dx + 4dy$$

$$= \int_0^2 2dx + \int_0^2 4dy + \int_2^0 4dx + \int_2^0 4dy$$

( $\because$  on  $OA$ ,  $y=0, dy=0$  &  $x$  varies from 0 to 2  
on  $AB$ ,  $x=2, dx=0$  &  $y$  varies from 0 to 2  
on  $BD$ ,  $y=2, dy=0$  &  $x$  varies from 2 to 0  
on  $DO$ ,  $x=0, dx=0$  &  $y$  varies from 2 to 0)

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$$= 2[x]_0^2 + 4[y]_0^2 + 4[x]_2^0 + 4[y]_2^0$$

$$= 4 + 8 - 8 - 8 = -4.$$

Now  $\text{curl } \mathbf{A} = \nabla \times \mathbf{A} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y-2+z & yz+4 & -xz \end{vmatrix}$

$$= \mathbf{i}(0-y) + \mathbf{j}(-1+z) + \mathbf{k}(0-1)$$

$$= -y\hat{\mathbf{i}} + (z-1)\hat{\mathbf{j}} - \hat{\mathbf{k}}$$

$\hat{\mathbf{n}}$  = unit normal vector to  $S = \hat{\mathbf{k}}$

$$\therefore ds = \frac{dx dy}{|\mathbf{n} \cdot \mathbf{k}|} = dx dy$$

$$(\nabla \times \mathbf{F}) \cdot \hat{\mathbf{n}} = [-y\hat{\mathbf{i}} + (z-1)\hat{\mathbf{j}} - \hat{\mathbf{k}}] \cdot \hat{\mathbf{k}} = -1$$

$$\iint (\nabla \times \mathbf{F}) \cdot \hat{\mathbf{n}} ds = \int_{x=0}^2 \int_{y=0}^2 (-1) dx dy$$

$$= - \int_{x=0}^2 [y]_0^2 dx$$

$$= - \int_{x=0}^2 2 dx$$

$$= -2[x]_0^2$$

$$= -2(2) = -4.$$

$$\therefore \iint (\nabla \times \mathbf{F}) \cdot \hat{\mathbf{n}} ds = \int_C \mathbf{F} \cdot d\mathbf{r} = -4.$$

Hence, the Stokes' theorem  
is verified.



7(a) Find the general and singular solution of  $y^2(y-xp) = x^4p^2$ .

Sol<sup>n</sup>: Given equation is  $y^2(y-xp) = x^4p^2$  ——— ①  
 Putting  $x = \frac{1}{u}$ ,  $y = \frac{1}{v}$  so that  $dx = -(\frac{1}{u^2})du$ ,  $dy = -(\frac{1}{v^2})dv$

we get  $\frac{dy}{dx} = \frac{u^2}{v^2} \frac{dv}{du} \Rightarrow p = \frac{u^2}{v^2} P$

where  $P = \frac{dv}{du}$  and  $p = \frac{dy}{dx}$

$\therefore$  putting  $x = \frac{1}{u}$ ,  $y = \frac{1}{v}$ ,  $p = (u^2P)/v^2$  in ①, we have

$$(\frac{1}{v^2}) \{ (\frac{1}{v}) - (\frac{1}{u}) (u^2P/v^2) \} = (\frac{1}{u^4}) (u^4P^2/v^4)$$

$$\Rightarrow v = uP + P^2$$

which is in Clairaut's form. Replacing  $P$  by  $c$ , the required general solution is  $v = uc + c^2$

$$\Rightarrow \frac{1}{y} = \frac{c}{x} + c^2$$

$$\Rightarrow x = cy + c^2xy$$

$$\Rightarrow xyc^2 + yc - x = 0, \text{ ——— ②}$$

which is a quadratic equation in  $c$  and so its  $c$ -discriminant relation is

$$y^2 - 4(xy)(-x) = 0 \Rightarrow y(y+4x^2) = 0$$

Now  $y=0$  gives  $p = dy/dx = 0$ . These values satisfy ①. so  $y=0$  is a singular solution. Again  $y = -4x^2$  gives  $p = dy/dx = -8x$ . These values satisfy ①. Hence  $y+4x^2=0$  is also singular solution.

7(b) (i) solve  $(y^2e^{xy^2} + 4x^3)dx + (2xye^{xy^2} - 3y^2)dy = 0$

(ii) Solve  $(y + y^3/3 + x^2/2)dx + (\frac{1}{4})x(x + 2y^2)dy = 0$

Sol<sup>n</sup>: (i) comparing the given equation with  $Mdx + Ndy = 0$   
 here  $M = y^2e^{xy^2} + 4x^3$  and  $N = 2xye^{xy^2} - 3y^2$

$$\frac{\partial M}{\partial y} = 2ye^{xy^2} + y^2 \cdot 2xye^{xy^2} = \frac{\partial N}{\partial x}$$

Hence, the given equation is exact and so its solution is

$$\int M dx + \int (\text{terms in } N \text{ not containing } x) dy = c$$

(y is constant)

$$\Rightarrow \int (y^2 e^{xy^2} + 4x^3) dx + \int (-3y^2) dy = 0$$

$$\Rightarrow y^2 \times \frac{1}{y^2} \times e^{xy^2} + 4 \times \frac{1}{4} \times x^4 - 3 \times \frac{y^3}{3} = 0$$

$$\Rightarrow e^{xy^2} + x^4 - y^3 = c$$

(ii) Given  $(y + y^3/3 + x^2/2) dx + \frac{1}{4} x (x + xy^2) dy = 0$  — (1)

Comparing (1) with  $Mdx + Ndy = 0$ ,  $M = y + y^3/3 + x^2/2$   
 $N = \frac{1}{4} x (x + xy^2)$

Here  $\frac{\partial M}{\partial y} = 1 + y^2$  and  $\frac{\partial N}{\partial x} = \frac{1}{4} x (1 + y^2)$

$$\therefore \frac{1}{N} \left( \frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) = \frac{4}{x(1+y^2)} \left\{ (1+y^2) - \frac{1}{4} (1+y^2) \right\}$$

$$= \frac{4}{x} \left( 1 - \frac{1}{4} \right) = \frac{3}{x}$$

which is a function of  $x$  alone. so I.F. =  $e^{\int \frac{3}{x} dx}$   
 $= e^{3 \log x} = e^{\log x^3} = x^3$

Multiplying (1) with  $x^3$ , we have

$$\{x^3y + \frac{1}{3}x^3y^3 + \frac{1}{2}x^5\} dx + (\frac{1}{4}) (x^4 + x^4y^2) dy = 0 \text{ whose}$$

solution as usual is

$$\int \{x^3y + \frac{1}{3}x^3y^3 + \frac{1}{2}x^5\} dx = c/12$$

(y is constant)  
 $\Rightarrow \frac{1}{4} x^4y + \frac{1}{12} x^4y^3 + \frac{1}{12} x^6 = c/6$

$$\Rightarrow 3x^4y + x^4y^3 + x^6 = c, \text{ where } c \text{ is an arbitrary constant.}$$



7(c) A shot fired at an elevation  $\alpha$  is observed to strike the foot of a tower which rises above a horizontal plane through the point of projection. If  $\theta$  be the angle subtended by the tower at this point, show that the elevation required to make the shot strike the top of the tower is  $\frac{1}{2} [\theta + \sin^{-1}(\sin \theta + \sin 2\alpha \cos \theta)]$ .

Soln. Let AB be the tower and O the point of projection. It is given that  $\angle AOB = \theta$ .  
 Let  $u$  be the velocity of projection of the shot. when the shot is fired at an elevation  $\alpha$  from O, it strikes the foot A of the tower AB. Let  $OA = R$

$$\text{Then } R = \frac{u^2 \sin 2\alpha}{g}$$

Referred to the horizontal and vertical lines OX and OY lying in the plane of motion as the coordinate axes, the coordinates of the top B of the tower are  $(R, R \tan \theta)$

If  $\beta$  be the angle of projection to hit B from O, then the point B lies on the trajectory whose equation is

$$y = x \tan \beta - \frac{1}{2} g \frac{x^2}{u^2 \cos^2 \beta}$$

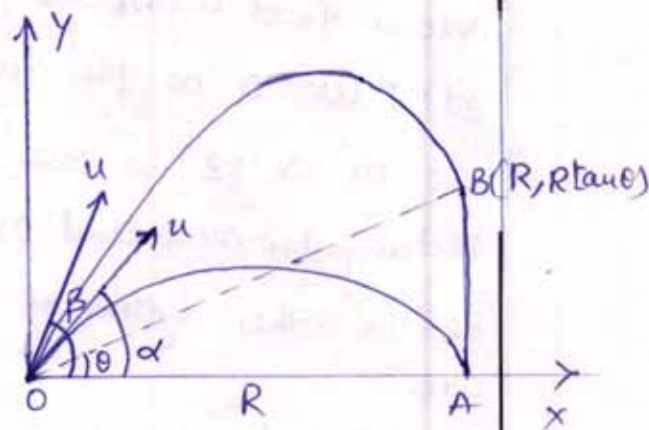
$$\therefore R \tan \theta = R \tan \beta - \frac{1}{2} g \frac{R^2}{u^2 \cos^2 \beta}$$

$$\Rightarrow \tan \theta = \tan \beta - \frac{1}{2} g \frac{R}{u^2 \cos^2 \beta} \quad [\because R \neq 0]$$

Substituting the value of  $R$  from (1), we get

$$\tan \theta = \tan \beta - \frac{1}{2} g \frac{u^2 \sin 2\alpha}{g} \cdot \frac{1}{u^2 \cos^2 \beta}$$

$$\Rightarrow \tan \theta = \tan \beta - \frac{\sin 2\alpha}{2 \cos^2 \beta}$$





$$\Rightarrow \frac{\sin \theta}{\cos \theta} = \frac{\sin \beta}{\cos \beta} - \frac{\sin 2\alpha}{2 \cos^2 \beta}$$

Multiplying both sides by  $2 \cos^2 \beta \cos \theta$ , we get

$$2 \cos^2 \beta \sin \theta = 2 \sin \beta \cos \beta \cos \theta - \cos \theta \sin 2\alpha$$

$$\Rightarrow (1 + \cos 2\beta) \sin \theta = \sin 2\beta \cos \theta - \cos \theta \sin 2\alpha$$

$$\Rightarrow \sin 2\beta \cos \theta - \cos 2\beta \sin \theta = \sin \theta + \cos \theta \sin 2\alpha$$

$$\Rightarrow \sin(2\beta - \theta) = \sin \theta + \cos \theta \sin 2\alpha$$

$$\Rightarrow 2\beta - \theta = \sin^{-1}(\sin \theta + \cos \theta \sin 2\alpha)$$

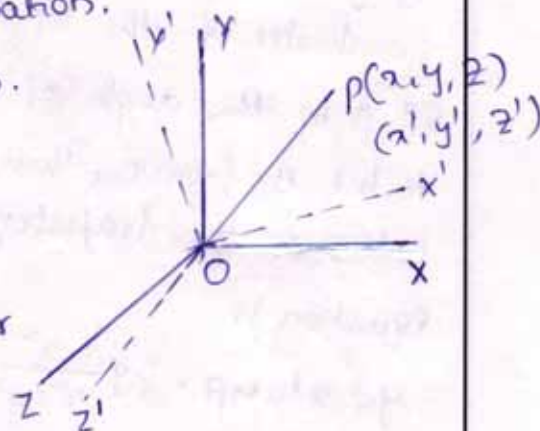
$$\Rightarrow 2\beta = \theta + \sin^{-1}(\sin \theta + \cos \theta \sin 2\alpha)$$

$$\Rightarrow \beta = \frac{1}{2} [\theta + \sin^{-1}(\sin \theta + \sin 2\alpha \cos \theta)]$$

7(d)  $\rightarrow$  If  $A(x, y, z)$  is an invariant differentiable vector field w.r.t a rotation of axes, Prove that  $\text{Curl } A$  is invariant vector field under the transformation.

Sol'n: Let  $O$  be the fixed origin.

Let  $OX, OY, OZ$  be one system of rectangular axes and  $OX', OY', OZ'$  be the other system of rectangular axes.



Let  $i, j, k$  be the unit vectors along  $OX, OY, OZ$  and  $i', j', k'$  be the unit vectors along  $OX', OY', OZ'$ .

Let  $P$  be any point in space whose coordinate axes are  $(x, y, z)$  or  $(x', y', z')$  with respect to the two systems of axes.

Let  $l_1, m_1, n_1; l_2, m_2, n_2; l_3, m_3, n_3$  be the direction



Cosines of the lines  $Ox', Oy', Oz'$  w.r.t the Coordinate axes  $Ox, Oy, Oz$ .

The scheme of transformation will be as follows:

$$\left. \begin{aligned} x' &= l_1x + m_1y + n_1z \\ y' &= l_2x + m_2y + n_2z \\ z' &= l_3x + m_3y + n_3z \end{aligned} \right\} \text{--- (1)}$$

Also we know that if  $l, m, n$  are the direction cosines of a line, then a unit vector along that line is  $li + mj + nk$ , where  $i, j, k$  are unit vectors along coordinate axes.

$$\left. \begin{aligned} \therefore i' &= l_1i + m_1j + n_1k \\ j' &= l_2i + m_2j + n_2k \\ k' &= l_3i + m_3j + n_3k \end{aligned} \right\} \text{--- (2)}$$

Now suppose the function  $A(x, y, z)$  becomes  $A'(x', y', z')$  after rotation of axes.

Then by hypothesis  $A(x, y, z) = A'(x', y', z')$ .

By chain rule of differentiation, we have

$$\frac{\partial A}{\partial x} = \frac{\partial A'}{\partial x'} \frac{\partial x'}{\partial x} + \frac{\partial A'}{\partial y'} \frac{\partial y'}{\partial x} + \frac{\partial A'}{\partial z'} \frac{\partial z'}{\partial x}$$

But from (1),  $\frac{\partial x'}{\partial x} = l_1, \frac{\partial y'}{\partial x} = l_2, \frac{\partial z'}{\partial x} = l_3$

$$\therefore \frac{\partial A}{\partial x} = l_1 \frac{\partial A'}{\partial x'} + l_2 \frac{\partial A'}{\partial y'} + l_3 \frac{\partial A'}{\partial z'}$$

$$\left. \begin{aligned} \text{Similarly } \frac{\partial A}{\partial y} &= m_1 \frac{\partial A'}{\partial x'} + m_2 \frac{\partial A'}{\partial y'} + m_3 \frac{\partial A'}{\partial z'} \\ \frac{\partial A}{\partial z} &= n_1 \frac{\partial A'}{\partial x'} + n_2 \frac{\partial A'}{\partial y'} + n_3 \frac{\partial A'}{\partial z'} \end{aligned} \right\} \text{--- (3)}$$

Now taking cross product of these three equations by  $i, j, k$  respectively, adding and using the results ②, we get

$$\begin{aligned} i \times \frac{\partial A}{\partial x} + j \times \frac{\partial A}{\partial y} + k \times \frac{\partial A}{\partial z} &= (l_1 i + m_1 j + n_1 k) \times \frac{\partial A'}{\partial x'} \\ &\quad + (l_2 i + m_2 j + n_2 k) \times \frac{\partial A'}{\partial y'} \\ &\quad + (l_3 i + m_3 j + n_3 k) \times \frac{\partial A'}{\partial z'} \\ &= i' \times \frac{\partial A'}{\partial x'} + j' \times \frac{\partial A'}{\partial y'} + k' \times \frac{\partial A'}{\partial z'} \end{aligned}$$

$$\therefore \nabla \times A = \nabla \times A'$$

$$\Rightarrow \boxed{\text{Curl } A = \text{Curl } A'}$$



8(a) By using Laplace transform method solve the

$$(D^3 - 2D^2 + 5D)y = 0 \text{ if } y(0) = 0, y'(0) = 1, y(\pi/8) = 1.$$

Sol'n: Taking the Laplace transform of both sides of given equation, we have

$$L\{y'''\} - 2L\{y''\} + 5L\{y'\} = 0$$

$$\Rightarrow p^3 L\{y\} - p^2 y(0) - py'(0) - y''(0) - 2[p^2 L\{y\} - py(0) - y'(0)] + 5[pL\{y\} - y(0)] = 0$$

$$\Rightarrow (p^3 - 2p^2 + 5p)L\{y\} - p - A - 2[-1] + 5 \cdot 0 = 0 \text{ where } y'(0) = A$$

$$\Rightarrow L\{y\} = \frac{A - 2 + p}{p^3 - 2p^2 + 5p}$$

$$= \frac{A - 2}{p(p^2 - 2p + 5)} + \frac{1}{p^2 - 2p + 5}$$

$$= \frac{A - 2}{5p} - \frac{A - 2}{5} \cdot \frac{p - 2}{p^2 - 2p + 5} + \frac{1}{p^2 - 2p + 5}$$

$$= \frac{A - 2}{5p} - \frac{A - 2}{5} \cdot \frac{(p - 1) - 1}{(p - 1)^2 + 4} + \frac{1}{(p - 1)^2 + 4}$$

$$= \frac{A - 2}{5p} - \frac{A - 2}{5} \cdot \frac{(p - 1)}{(p - 1)^2 + 4} + \frac{A + 3}{10} \cdot \frac{2}{(p - 1)^2 + 4}$$

$$\therefore y = \frac{A - 2}{5} \cdot L^{-1}\left\{\frac{1}{p}\right\} - \frac{A - 2}{5} L^{-1}\left\{\frac{p - 1}{(p - 1)^2 + 4}\right\} + \frac{A + 3}{10} L^{-1}\left\{\frac{2}{(p - 1)^2 + 4}\right\}$$

$$= \frac{A - 2}{5} - \frac{A - 2}{5} e^t \cdot \cos 2t + \frac{A + 3}{10} e^t \sin 2t$$

$$\text{Since } y(\pi/8) = 1$$

$$\therefore 1 = \frac{A - 2}{5} - \frac{A - 2}{5} \cdot e^{\pi/8} \cdot \frac{1}{\sqrt{2}} + \frac{A + 3}{10} \cdot e^{\pi/8} \cdot \frac{1}{\sqrt{2}}$$

$$\Rightarrow \frac{7-A}{5} = \frac{e^{\pi/8}}{10\sqrt{2}} (-2A+4+A+3)$$

$$\Rightarrow \left(\frac{7-A}{5}\right) \left[1 - \frac{e^{\pi/8}}{2\sqrt{2}}\right] = 0$$

$$\Rightarrow A = 7$$

Hence the required solution is

$$y = 1 + e^t (\sin 2t - \cos 2t)$$

8(b) A heavy particle hanging vertically from a fixed point by a light inextensible cord of length  $l$  is struck by a horizontal blow which imparts it a velocity  $2\sqrt{gl}$ . Prove that the cord becomes slack when the particle has risen to a height  $\frac{2}{3}l$  above the fixed point.

Sol'n: Take  $R=T$  (i.e. the tension in the string)  
 Let a particle tied to a cord OA of length  $l$  be struck by a horizontal blow which imparts it a velocity  $2\sqrt{gl}$ . If P is the position of the particle at time  $t$  such that  $\angle AOP = \theta$ , then the equations of motion are.

$$m \frac{d^2 s}{dt^2} = -mg \sin \theta \quad \text{--- (1)}$$

$$\text{and } m \frac{v^2}{l} = T - mg \cos \theta \quad \text{--- (2)}$$

$$\text{Also } s = l\theta$$

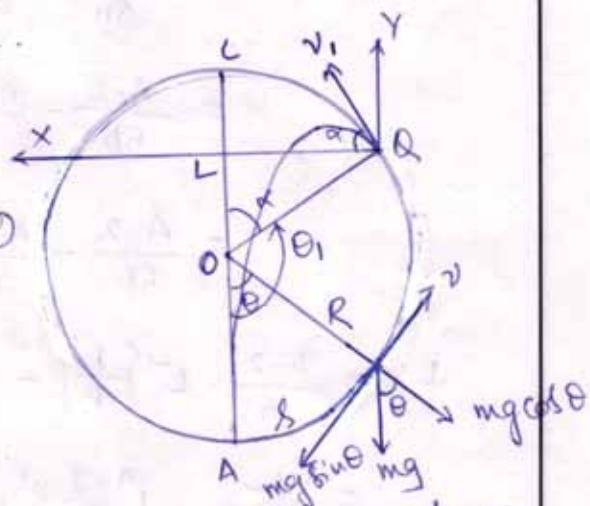
From (1) & (3), we have

$$l \frac{d^2 \theta}{dt^2} = -g \sin \theta$$

Multiplying both sides by  $2l \frac{d\theta}{dt}$  and integrating, we have

$$v^2 = \left( l \frac{d\theta}{dt} \right)^2 = 2lg \cos \theta + A$$

But at the point A,  $\theta = 0$  and  $v = 2\sqrt{gl}$





$$\therefore 4gl = 2lg + A \text{ so that } A = 2gl$$

$$\therefore v^2 = 2lg (\cos\theta + 1) \text{ ————— (4)}$$

from (2) and (4), we have

$$T = \frac{m}{l} (v^2 + gl \cos\theta) = mg (3\cos\theta + 2) \text{ ————— (5)}$$

If the cord becomes slack at the point Q, where  $\theta = \theta_1$ , then from (5), we have

$$T = 0 = mg (3\cos\theta_1 + 2)$$

$$\text{giving as } \cos\theta_1 = -2/3.$$

If  $\angle COQ = \alpha$ , then  $\alpha = \pi - \theta_1$ , and  $\cos\alpha = 2/3$

If  $v_1$  is the velocity of the particle at Q, then  $v = v_1$ , where  $\theta = \theta_1$ . Therefore from (4), we have

$$v_1^2 = 2lg (1 + \cos\theta_1) = 2lg (1 - 2/3) = 2lg/3$$

$$\text{Now } OL = l \cos\alpha = 2/3 l$$

Thus the particle leaves the circular path at the point Q at a height  $2/3 l$  above the fixed point O with velocity  $v_1 = \sqrt{2lg/3}$  at an angle  $\alpha$  to the horizontal and subsequently it describes a parabolic path.

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8(c) show that  $A = (2x^2 + 8xy^2z)\hat{i} + (3x^3y - 3xy)\hat{j} - (4y^2z^2 + 2x^3z)\hat{k}$  is not solenoidal but  $B = xyz^2 A$  is solenoidal.

Sol<sup>n</sup>:  $\nabla \cdot A = \left( \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \cdot \left[ (2x^2 + 8xy^2z)\hat{i} + (3x^3y - 3xy)\hat{j} - (4y^2z^2 + 2x^3z)\hat{k} \right]$

$$= \frac{\partial}{\partial x} (2x^2 + 8xy^2z) + \frac{\partial}{\partial y} (3x^3y - 3xy) - \frac{\partial}{\partial z} (4y^2z^2 + 2x^3z)$$

$$= 4x + 8y^2z + 3x^3 - 3x - 8y^2z - 2x^3$$

$$= x^3 + x \neq 0$$

$\therefore A$  is not a solenoidal

Now  $B = (xyz^2)A$

$$= (xyz^2) \left[ (2x^2 + 8xy^2z)\hat{i} + (3x^3y - 3xy)\hat{j} - (4y^2z^2 + 2x^3z)\hat{k} \right]$$

$$= (2x^3yz^2 + 8x^2y^3z^3)\hat{i} + (3x^4y^2z^2 - 3x^2y^2z^2)\hat{j} - (4x^3y^3z^4 + 2x^4yz^3)\hat{k}$$

Now  $\nabla \cdot B = \left( \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \cdot \left[ (2x^3yz^2 + 8x^2y^3z^3)\hat{i} + (3x^4y^2z^2 - 3x^2y^2z^2)\hat{j} - (4x^3y^3z^4 + 2x^4yz^3)\hat{k} \right]$

$$= \frac{\partial}{\partial x} (2x^3yz^2 + 8x^2y^3z^3) + \frac{\partial}{\partial y} (3x^4y^2z^2 - 3x^2y^2z^2) - \frac{\partial}{\partial z} (4x^3y^3z^4 + 2x^4yz^3)$$

$$= 6x^2yz^2 + 16x^2y^3z^3 + 6x^4yz^2 - 6x^2yz^2 - 16x^2y^3z^3 - 6x^4yz^2$$

$$= 0$$

$\therefore B$  is a solenoidal



8(d) → Verify Green's theorem in the plane for  
 $\oint_C (3x^2 - 8y^2) dx + (4y - 6xy) dy$ , where  $C$  is the boundary  
of the region defined by:  $y = \sqrt{x}$ ,  $y = x^2$ .

Sol'n: By Green's theorem in plane, we have

$$\iint_R \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx dy = \oint_C (M dx + N dy)$$

Here  $M = 3x^2 - 8y^2$ ,  $N = 4y - 6xy$

The parabola  $y = \sqrt{x}$  i.e.  $y^2 = x$  and the parabola  $y = x^2$  intersect at the points  $(0, 0)$  and  $(1, 1)$ . The closed curve  $C$  consists of the arc  $C_1$  of the parabola  $y = x^2$  and the arc  $C_2$  of the parabola  $y = \sqrt{x}$ . Also  $R$  is the region bounded by the closed curve  $C$ .

we have

$$\iint_R \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx dy$$

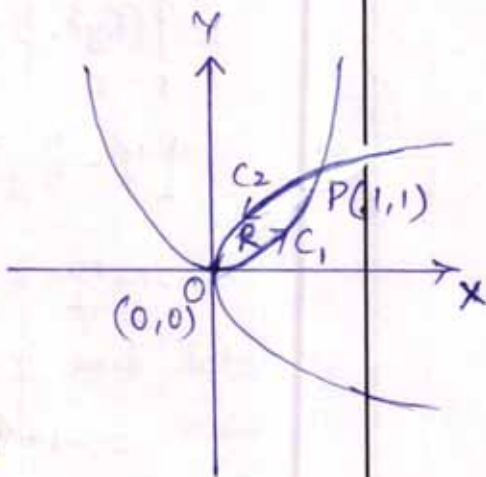
$$= \iint_R \left[ \frac{\partial}{\partial x} (4y - 6xy) - \frac{\partial}{\partial y} (3x^2 - 8y^2) \right] dx dy$$

$$= \iint_R (-6y + 16y) dx dy = \iint_R 10y dx dy$$

$$= \int_{x=0}^1 \int_{y=x^2}^{\sqrt{x}} 10y dx dy \quad \left[ \because \text{for the region } R, x \text{ varies from } 0 \text{ to } 1 \text{ \& } y \text{ varies from } x^2 \text{ to } \sqrt{x} \right]$$

$$= \int_0^1 5 [y^2]_{y=x^2}^{\sqrt{x}} dx = 5 \int_0^1 [x - x^4] dx$$

$$= 5 \left[ \frac{x^2}{2} - \frac{x^5}{5} \right]_0^1 = 5 \left[ \frac{1}{2} - \frac{1}{5} \right] = \frac{15}{10} = \frac{3}{2} \quad \text{--- (1)}$$



Now the line integral along the closed curve  $C$ .

$$= \oint_C (M dx + N dy) = \int_{C_1} (M dx + N dy) + \int_{C_2} (M dx + N dy)$$

Along  $C_1$ ,  $x^2 = y$ ,  $dy = 2x dx$  and  $x$  varies from 0 to 1.

$$\therefore \text{line integral along } C_1 = \int_0^1 [(3x^2 - 8x^4) dx + (4x^2 - 6x^3) 2x dx]$$

$$= \int_0^1 (3x^2 + 8x^3 - 20x^4) dx = [x^3 + 2x^4 - 4x^5]_0^1 = 1 + 2 - 4 = -1.$$

Along  $C_2$ ,  $y^2 = x$ .

$\therefore dx = 2y dy$  and limits for  $y$  are 1 to 0.

$\therefore$  line integral along  $C_2$

$$= \int_1^0 [(3y^4 - 8y^2) 2y dy + (4y - 6y^3) dy]$$

$$= \int_1^0 (6y^5 - 22y^3 + 4y) dy$$

$$= \left[ y^6 - \frac{11}{2} y^4 + 2y^2 \right]_1^0$$

$$= -1 + \frac{11}{2} - 2 = \frac{5}{2}$$

$\therefore$  Total line integral along the closed curve  $C$

$$= -1 + \frac{5}{2} = \frac{3}{2} \quad \text{--- (2)}$$

from ① and ②, we see that Green's theorem is verified.