

MAINS TEST SERIES-2021

TEST- 9

FULL SYLLABUS (PAPER- I)

ANSWER KEY

1(a) Suppose U and W are distinct four dimensional subspaces of a vector space V , where $\dim V = 6$. Find the possible dimension of subspace $U \cap W$?

Sol: Given; U and W are distinct Subspaces ; such that
 $\dim(U) = \dim(W) = 4$ } of a vector space V .
 $\dim(V) = 6$ | —— (1)

we know that

$$U, W \subseteq U+W \subseteq V \quad \text{--- (2)}$$

Using formula.

$$\dim(U) + \dim(W) - \dim(U \cap W) = \dim(U+W)$$

$$\dim(U \cap W) = \dim(U+W) - \dim(U) - \dim(W)$$

$$\dim(U \cap W) = 6 - 4 - 4$$

$$\dim(U \cap W) = 2 - \dim(U \cap W) \quad \text{--- (3)}$$

from (2)

$$\dim(U) = 4 \leq \dim(U+W) \leq 6 (= \dim(V)) \quad \text{--- (4)}$$

Using (3) and (4) we get

$$2 \leq \dim(U \cap W) \leq 4$$

Since ; U, W are distinct

$$U \cap W \neq U \text{ or } W \text{ or } \dim(U \cap W) \neq 4$$

Hence ; $\dim(U \cap W) = \underline{\underline{2 \text{ or } 3}}$

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1.(b) find a Hermitian and a skew-Hermitian

matrix each whose sum is the matrix $\begin{bmatrix} 2i & 3 & -1 \\ 1 & 2+3i & 2 \\ -i+1 & 4 & 5i \end{bmatrix}$

Soln: Let $A = \begin{bmatrix} 2i & 3 & -1 \\ 1 & 2+3i & 2 \\ -i+1 & 4 & 5i \end{bmatrix}$

then $A+A^T$ is Hermitian and

$A-A^T$ is skew-Hermitian.

$\therefore \frac{1}{2}(A+A^T)$ is Hermitian and

$\frac{1}{2}(A-A^T)$ is skew-Hermitian.

Given that $A = \frac{1}{2}(A+A^T) + \frac{1}{2}(A-A^T)$

$$= P+Q \text{ (say)}$$

where P is Hermitian and

Q is skew-Hermitian.

To find P and Q :

Now $A^T = (\bar{A})^T$

$$= \begin{bmatrix} -2i & 3 & -1 \\ 1 & 2-3i & 2 \\ -i+1 & 4 & -5i \end{bmatrix}^T$$

$$= \begin{bmatrix} -2i & 1 & i+1 \\ 3 & 2-3i & 4 \\ -1 & 2 & -5i \end{bmatrix}$$

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we have

$$\begin{aligned}
 P &= \frac{1}{2} (A + A^H) \\
 &= \frac{1}{2} \left(\begin{bmatrix} 2i & 3 & -1 \\ 1 & 2+3i & 2 \\ -i+1 & 4 & 5i \end{bmatrix} + \begin{bmatrix} -2i & 1 & i+1 \\ 3 & 2-3i & 4 \\ -1 & 2 & -5i \end{bmatrix} \right) \\
 &= \frac{1}{2} \begin{bmatrix} 0 & 4 & 4 \\ 4 & 4 & 6 \\ -i & 6 & 0 \end{bmatrix} \\
 &= \begin{bmatrix} 0 & 2 & \frac{i}{2} \\ 2 & 2 & 3 \\ -\frac{i}{2} & 3 & 0 \end{bmatrix}
 \end{aligned}$$

now we have

$$\begin{aligned}
 Q &= \frac{1}{2} \left(\begin{bmatrix} 2i & 3 & -1 \\ 1 & 2+3i & 2 \\ -i+1 & 4 & 5i \end{bmatrix} - \begin{bmatrix} -2i & 1 & i+1 \\ 3 & 2-3i & 4 \\ -1 & 2 & -5i \end{bmatrix} \right) \\
 &= \frac{1}{2} \begin{bmatrix} 4i & 2 & -i-2 \\ -2 & 6i & -2 \\ -i+2 & 2 & 10i \end{bmatrix} \\
 &= \begin{bmatrix} 2i & 1 & \frac{-i}{2}-1 \\ -1 & 3i & -1 \\ \frac{i}{2}+1 & 1 & 5i \end{bmatrix}
 \end{aligned}$$

∴ The required Hermitian and skew-Hermitian matrices are $\begin{bmatrix} 0 & 2 & \frac{i}{2} \\ 2 & -2 & 3 \\ -\frac{i}{2} & 3 & 0 \end{bmatrix}$ and

$$\begin{bmatrix} 2i & 1 & \frac{-i}{2}-1 \\ -1 & 3i & -1 \\ \frac{i}{2}+1 & 1 & 5i \end{bmatrix} \quad \text{respectively.}$$

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Q.10)

$$\rightarrow \text{Let } f(x,y) = \begin{cases} \frac{(x+y)^2}{x^2+y^2}; & \text{if } (x,y) \neq (0,0) \\ 1 & \text{if } (x,y) = (0,0) \end{cases}$$

Show that $\frac{\partial f}{\partial x}$ and $\frac{\partial f}{\partial y}$ exist at $(0,0)$

though $f(x,y)$ is not continuous at $(0,0)$.

Solution:-

$$\text{Given; } f(x,y) = \begin{cases} \frac{(x+y)^2}{x^2+y^2} & ; \text{ if } (x,y) \neq (0,0) \\ 1 & ; \text{ if } (x,y) = (0,0) \end{cases}$$

$$\begin{aligned} \frac{\partial f}{\partial x} \Big|_{(0,0)} &= \lim_{h \rightarrow 0} \frac{f(h,0) - f(0,0)}{h} \\ &= \lim_{h \rightarrow 0} \frac{\left[\frac{(h+0)^2}{h^2+0^2} - 1 \right]}{h} \\ &= \lim_{h \rightarrow 0} \frac{\frac{1-1}{h}}{h} = 0 \end{aligned}$$

$$\begin{aligned} \frac{\partial f}{\partial y} \Big|_{(0,0)} &= \lim_{k \rightarrow 0} \frac{f(0,k) - f(0,0)}{k} = \lim_{k \rightarrow 0} \frac{\left[\frac{k^2}{k^2} - 1 \right]}{k} \\ &= \lim_{k \rightarrow 0} \frac{1-1}{k} = 0 \end{aligned}$$

Therefore; $\frac{\partial f}{\partial x}$ and $\frac{\partial f}{\partial y}$ exist at $(0,0)$.

To check continuity

$$\text{Let } f(x,y) = \lim_{(x,y) \rightarrow (0,0)} \frac{x+y}{x^2+y^2}$$

Assuming (x,y) approaches $(0,0)$
 along $y=mx$

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$$\begin{aligned}
 & y = mx \\
 &= \lim_{x \rightarrow 0} \frac{(x+mx)^2}{x^2 + m^2 x^2} \\
 &= \lim_{x \rightarrow 0} \frac{x^2(1+m)^2}{x^2(1+m^2)}
 \end{aligned}$$

$$\lim_{(x,y) \rightarrow (0,0)} f(x,y) = \frac{(1+m)^2}{1+m^2}.$$

Limit depends on 'm' thus limit does not exist and $f(x,y)$ is not continuous at $(0,0)$.

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1.(d) Evaluate $\int_0^{\pi/2} \frac{x \sin x \cos x}{\sin^4 x + \cos^4 x} dx$

Solⁿ $I = \int_0^{\pi/2} \frac{x \sin x \cos x}{\sin^4 x + \cos^4 x} dx \quad \text{--- (1)}$

We know $\int_a^b f(x) dx = \int_a^b f(a+b-x) dx$

$$I = \int_0^{\pi/2} \frac{(\pi/2-x) \sin(\pi/2-x) \cos(\pi/2-x)}{\sin^4(\pi/2-x) + \cos^4(\pi/2-x)} dx$$

$$I = \int_0^{\pi/2} \frac{(\pi/2-x) \cos x \sin x}{\cos^4 x + \sin^4 x} dx \quad \text{--- (2)}$$

Adding eqn (1) and (2), we get -

$$2I = \frac{\pi}{2} \int_0^{\pi/2} \frac{\sin x \cos x}{\cos^4 x + \sin^4 x} dx$$

$$I = \frac{\pi}{4} \int_0^{\pi/2} \frac{\sin x \cos x}{(\sin^2 x + \cos^2 x)^2 - 2 \sin^2 x \cos^2 x} dx$$

$$I = \frac{\pi}{4} \int_0^{\pi/2} \frac{\sin x \cos x}{1 - \frac{\sin^2 x}{2}} dx \quad \left[\begin{array}{l} \because \sin^2 x = 2 \sin x \cos x \\ \& \sin^2 x + \cos^2 x = 1 \end{array} \right]$$

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$$\Rightarrow I = \frac{\pi}{4} \int_0^{\pi/2} \frac{2 \sin x \cos x}{1 + \cos^2 2x} dx$$

$$\Rightarrow I = \frac{\pi}{4} \int_0^{\pi/2} \frac{\sin 2x}{1 + \cos^2 2x} dx$$

Let $\cos 2x = t \Rightarrow -2 \sin 2x dx = dt$

$$\text{at } x=0 \Rightarrow t=1$$

$$x=\pi/2 \Rightarrow t=-1$$

$$\Rightarrow I = \frac{\pi}{4} \int_{-1}^1 \frac{(-2)dt}{1+t^2}$$

$$\Rightarrow I = \frac{\pi}{8} \int_{-1}^1 \frac{dt}{1+t^2} = \frac{\pi}{8} [\tan^{-1} t]_{-1}^1$$

$$\Rightarrow I = \frac{\pi}{8} \left[\frac{\pi}{4} - (-\frac{\pi}{4}) \right]$$

$$\Rightarrow \boxed{I = \frac{\pi^2}{16}}$$

$$\Rightarrow \int_0^{\pi/2} \frac{x \sin x \cos x}{\sin^4 x + \cos^4 x} dx = \frac{\pi^2}{16}$$

Ans

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1.(e)

Find the equations of the straight line through the point $(3, 1, 2)$ to intersect the straight line $x+4 = y+1 = 2(z-2)$ and parallel to the plane $4x+y+5z=0$.

Solution:-

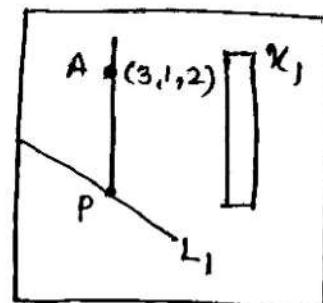
Given, point $(3, 1, 2)$ to intersect the straight line $x+4 = y+1 = 2(z-2)$.

$$\therefore L_1 \Rightarrow \frac{x+4}{2} = \frac{y+1}{2} = \frac{z-2}{1}$$

and the general point on L_1 ,
let P be the point

$$\frac{x+4}{2} = \frac{y+1}{2} = \frac{z-2}{1} = \lambda$$

$$P(2\lambda-4, 2\lambda-1, \lambda+2)$$



Let, straight line through $(3, 1, 2)$ meet the given line 'p', therefore Direction ratios of line AP to be determined by.

$$AP(2\lambda-4-3, 2\lambda-1-1, 2\lambda+2-2) \Rightarrow AP(2\lambda-7, 2\lambda-2, \lambda)$$

The line is parallel to the plane $4x+y+5z=0$
 \therefore Dr's of normal to the plane is 1^r to Dr's of determined line thus

$$(2\lambda-7)4 + 2\lambda-2 + 5\lambda = 0 \Rightarrow 15\lambda = 30 \Rightarrow \boxed{\lambda = 2}$$

$$\therefore \text{Dr's of } AP = (-3, 2, 2)$$

$$\text{And Point } P = (0, 3, 4)$$

Therefore; straight line AP, which intersect $(3, 1, 2)$.

$$\left[\frac{x-3}{-3} = \frac{y-1}{2} = \frac{z-2}{2} \right]_4$$

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2(a) (i) Let V be the vector space of 2×2 matrices over the field of real numbers \mathbb{R} .

Let $W = \{A \in V \mid \text{Trace } A = 0\}$. Show that W is a subspace of V . Find a basis of W and dimension of W .

(ii) Find the dimension and a basis of the solution space W of the system

$$x + 2y + 2z - s + 3t = 0, \quad x + 2y + 3z + s + t = 0,$$

$$3x + 6y + 8z + s + 5t = 0.$$

Sol'n: (iii) we write the single matrix equation is $AX = 0 \quad \text{--- (1)}$

$$\begin{bmatrix} 1 & 2 & 2 & -1 & 3 \\ 1 & 2 & 3 & 1 & 1 \\ 3 & 6 & 8 & 1 & 5 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ s \\ t \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

where $A = \begin{bmatrix} 1 & 2 & 2 & -1 & 3 \\ 1 & 2 & 3 & 1 & 1 \\ 3 & 6 & 8 & 1 & 5 \end{bmatrix}$

$$\sim \begin{bmatrix} 1 & 2 & 2 & -1 & 3 \\ 0 & 0 & 1 & 2 & -2 \\ 0 & 0 & 2 & 4 & -4 \end{bmatrix} \begin{array}{l} R_2 \rightarrow R_2 - R_1 \\ R_3 \rightarrow R_3 - 3R_1 \end{array}$$

$$\sim \begin{bmatrix} 1 & 2 & 2 & -1 & 3 \\ 0 & 0 & 1 & 2 & -2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{array}{l} R_3 \rightarrow R_3 - 2R_2 \end{array}$$

clearly it is in echelon form

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Again we write a single matrix equation
 by using above, we get

$$x + 2y + 2z - s + 3t = 0$$

$$2 + 2s - 2t = 0$$

$$\Rightarrow [2 = 2t - 2s] \text{ and}$$

$$[x = -2y + 5s - 7t]$$

Clearly y, s, t are free variables.

\therefore dimension of $W = 3$

(i) Let $y=1, s=0, t=0$ to obtain the solution

$$v_1 = (-2, 1, 0, 0, 0)$$

(ii) Let $y=0, s=1, t=0$ to obtain the solution

$$v_2 = (5, 0, -2, 1, 0)$$

(iii) Let $y=0, s=0, t=1$ to obtain the solution

$$v_3 = (-7, 0, 2, 0, 1)$$

The set $\{v_1, v_2, v_3\}$ is a basis of the
 solution space W .

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Q(alt) Sol'n: Given, V is a vector space of 2×2 matrices over \mathbb{R} .

i.e., $V = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix} : a, b, c, d \in \mathbb{R} \right\}$

and W is a subset of V such that $\text{Trace}(A) = 0$ when $A \in W$.

clearly $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \in W$

i.e., W is not empty.

Now let $A_1, A_2 \in W$

then, $\text{Trace}(A_1) = 0$

and $\text{Trace}(A_2) = 0$

then $\text{tr}(xA_1 + yA_2) = x\text{tr}(A_1) + y\text{tr}(A_2)$

$$= x \cdot 0 + y \cdot 0 = 0$$

$\Rightarrow xA_1 + yA_2 = 0$

$\Rightarrow xA_1 + yA_2 \in W$

i.e. W is a subspace of

If $\begin{bmatrix} x & y \\ z & w \end{bmatrix} \in W$

then $x+w=0$

i.e., it can have at maximum three free variables.

Hence, dimension of $W = 4-1=3$

and the basis of W are $\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ and $\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$

i.e. $W = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \right\}$

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Q(b)i)

For all real numbers, $f(x)$ is given as

$$f(x) = \begin{cases} e^x + a \sin x & \text{if } x < 0 \\ b(x-1)^2 + x - 2 & \text{if } x \geq 0 \end{cases}, \text{ find values of}$$

a and b for which f is differentiable at $x=0$.

Sol'n: Since f is differentiable at $x=0$
 hence f must be continuous at $x=0$.

$$\text{Now } \lim_{x \rightarrow 0^-} f(x) = \lim_{x \rightarrow 0^-} e^x + a \sin x = 1$$

$$\lim_{x \rightarrow 0^+} f(x) = \lim_{x \rightarrow 0^+} b(x-1)^2 + x - 2 = b-2$$

$$\text{Also } f(0) = b-2$$

Since f is continuous at $x=0$

$$\therefore \lim_{x \rightarrow 0^-} f(x) = \lim_{x \rightarrow 0^+} f(x) = f(0)$$

$$\Rightarrow 1 = b-2$$

$$\Rightarrow b-2 = 1 \Rightarrow b = -3$$

$$\text{Now } Lf'(0) = \lim_{x \rightarrow 0^-} \frac{f(x) - f(0)}{x - 0}$$

$$= \lim_{x \rightarrow 0^-} \frac{e^x + a \sin x - (b-2)}{x}$$

$$= \lim_{x \rightarrow 0^-} \frac{e^x + a \sin x - 1}{x} \quad \left(\frac{0}{0} \text{ form}\right)$$

$$= \lim_{x \rightarrow 0^-} e^x + a \cos x \quad (\text{by using L'Hopital's rule})$$

$$= 1+a$$

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$$\begin{aligned}
 Rf'(0) &= \lim_{x \rightarrow 0^+} \frac{b(x-1)^2 + x-2 - (b-2)}{x} \\
 &= \lim_{x \rightarrow 0^+} \frac{3(x-1)^2 + x-3}{x} \\
 &= \lim_{x \rightarrow 0^+} \frac{3(x-1)^2 + x-3}{x} \quad \left(\frac{0}{0} \text{ form} \right) \\
 &= \lim_{x \rightarrow 0^+} 6(x-1) + 1 \quad (\text{by L'Hospital's rule})
 \end{aligned}$$

$$= -5$$

Since f is differentiable

$$\therefore Lf'(0) = Rf'(0)$$

$$1+a = -5$$

$$\Rightarrow \boxed{a = -6}$$

$$\therefore \boxed{a = -6} \quad \text{and} \quad \boxed{b = 3}$$

————— .

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2010

find the height of the cylinder of maximum volume that can be inscribed in a sphere of radius a .

Sol: Let O be the centre of the sphere of radius 'a'.

Let 'h' be the height and 'r' be the radius of the cylinder.

$$\text{Then } OA = r = \sqrt{a^2 - h^2} \frac{r}{4}$$

The volume V of the cylinder = $\pi r^2 h$

$$= \pi \left(a - \frac{b}{4} \right)^b$$

$$\therefore \frac{dy}{dh} = \pi\left(\tilde{a} - \frac{3}{4}\tilde{h}\right)$$

for v to be maximum or minimum, we must have

$$\frac{dN}{dt} = 0$$

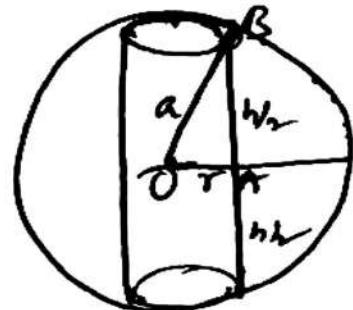
$$\text{i.e., } \frac{c^h}{\pi(a^h - \frac{3}{4}h^2)} \infty \Rightarrow h = \frac{2\alpha}{\sqrt{3}}$$

$$\text{Also, } \frac{dV}{dh} = -\frac{6}{4}h = -\frac{3}{2}h < 0 \quad \text{at } h = \frac{2a}{\sqrt{3}}.$$

Hence V is maximum when $\frac{h}{\sqrt{3}} = \frac{2g}{k}$.

and maximum value = $\pi \left(a - \frac{b^2}{4a} \right) b$

$$= \pi \left[a^2 - \frac{1}{4} \left(\frac{2a}{\sqrt{3}} \right)^2 \right] \frac{2a}{\sqrt{3}} = \frac{4\pi a^3}{\sqrt{3}}$$



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2.(c) A sphere S has points $(0, 1, 0)$, $(3, -5, 2)$ at opposite ends of diameter. Find the eqn of the sphere having the intersection of the sphere S with the plane $5x - 2y + 4z + 7 = 0$ as a great circle.

Solⁿ Equation of the sphere S on joining the two given points $(0, 1, 0)$, $(3, -5, 2)$ is given by

$$S = (x-0)(x-3) + (y-1)(y+5) + (z-0)(z-2) = 0$$

$$\Rightarrow x^2 + y^2 + z^2 - 3x + 4y - 2z - 5 = 0$$

Equation of any sphere having the intersection of the sphere S with the plane $5x - 2y + 4z + 7 = 0$

$$\text{if } S + \lambda P = 0$$

$$\text{i.e., } (x^2 + y^2 + z^2 - 3x + 4y - 2z - 5) + \lambda(5x - 2y + 4z + 7) = 0. \quad \text{--- (1)}$$

$$\Rightarrow x^2 + y^2 + z^2 + (-3 + 5\lambda)x + (4 - 2\lambda)y + (-2 + 4\lambda)z + (-5 + 7\lambda) = 0.$$

Its centre is $\left(\frac{3-5\lambda}{2}, \frac{2\lambda-4}{2}, \frac{-2+4\lambda}{2}\right)$. (2)

Now if the given circle (which is the section of the sphere $x^2 + y^2 + z^2 - 3x + 4y - 2z - 5$ by the plane $5x - 2y + 4z + 7 = 0$) is a great circle of the sphere (1), the centre of the sphere (1) must lie on the plane

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$$5x - 2y + 4z - 17 = 0.$$

$$\Rightarrow 5\left(\frac{3-5\lambda}{2}\right) - 2\left(\frac{2\lambda-4}{2}\right) + 4\left(\frac{2-4\lambda}{2}\right) + 7 = 0$$

$$\Rightarrow 15 - 25\lambda - 4\lambda + \underline{8} + 8 - 16\lambda + 14 = 0$$

$$\Rightarrow 45 - 45\lambda = 0$$

$$\Rightarrow \boxed{\lambda=1} .$$

∴ from (1), we get

$$x^2 + y^2 + z^2 - 3x + 4y - 2z - 5 + (5x - 2y + 4z - 17) = 0$$

$$\Rightarrow x^2 + y^2 + z^2 + 2x + 2y + 2z + 2 = 0$$

which is the required
equation of the sphere

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3.(a)(ii) → find the dimension of the subspace of \mathbb{R}^4 spanned by the set

$$\{(1, 0, 0, 0), (0, 1, 0, 0), (1, 2, 0, 1), (0, 0, 0, 1)\}.$$

Hence find a basis for the subspace.
SOL.

Let $\mathbb{R}^4 = \{(x_1, x_2, x_3, x_4) | x_1, x_2, x_3, x_4 \in \mathbb{R}\}$
 be the given vector space over the field \mathbb{R} .

Let ω be the subspace of \mathbb{R}^4 spanned by S where

$$S = \{(1, 0, 0, 0), (0, 1, 0, 0), (1, 2, 0, 1), (0, 0, 0, 1)\}$$

Let us construct a matrix A whose rows are the given vectors of S and convert it into the echelon form.

$$A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 2 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 2 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_3 \rightarrow R_3 - 2R_1}$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_2 \rightarrow R_2 - 2R_1}$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_4 \rightarrow R_4 - R_3}$$

Clearly which is in echelon form and the number of non-zero rows are equal to 3. Corresponding these rows the vectors of S $(1, 0, 0, 0), (0, 1, 0, 0), (1, 2, 0, 1)$

form a basis of ω .

$$\text{i.e } S' = \{(1, 0, 0, 0), (0, 1, 0, 0), (1, 2, 0, 1)\}$$

is a minimum number of linearly independent subset of ω .

and it forms a basis of ω .

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3.(b)i) If $z = xf(y/x) + g(y/x)$, show that

$$x^2 \frac{\partial^2 z}{\partial x^2} + 2xy \frac{\partial^2 z}{\partial x \partial y} + y^2 \frac{\partial^2 z}{\partial y^2} = 0$$

Soln: Given $z = xf(y/x) + g(y/x)$ — ①

Differentiating ① w.r.t x , partially we get

$$\begin{aligned} \frac{\partial z}{\partial x} &= f(y/x) + xf'(y/x)\left(-\frac{y}{x^2}\right) + g'(y/x)(-y/x^2) \\ &= f(y/x) - \frac{y}{x}f'(y/x) - \frac{y}{x^2}g'(y/x) \end{aligned}$$

Again Differentiating w.r.t x , partially

$$\begin{aligned} \frac{\partial^2 z}{\partial x^2} &= f'(y/x)(-\frac{y}{x^2}) - \left[-\frac{y}{x^2}f'(y/x) + \frac{y}{x}f''(y/x)(-\frac{y}{x^2}) \right] \\ &\quad - \left[\frac{y}{x^2}g''(y/x)(-\frac{y}{x^2}) + (-\frac{2y}{x^3})g'(y/x) \right] \\ &= -\frac{y}{x^2}f'(y/x) + \frac{y}{x^2}f'(y/x) + \frac{y^2}{x^3}f''(y/x) \\ &\quad + \frac{y^2}{x^4}g''(y/x) + \frac{2y}{x^3}g'(y/x) \end{aligned}$$

$$\Rightarrow x^2 \frac{\partial^2 z}{\partial x^2} = \frac{y^2}{x}f''(y/x) + \frac{y^2}{x^2}g''(y/x) + \frac{2y}{x}g'(y/x) — ②$$

Differentiating ① w.r.t y , partially we get

$$\begin{aligned} \frac{\partial z}{\partial y} &= xf'(y/x)(\frac{1}{x}) + g'(y/x)(\frac{1}{x}) \\ &= f'(y/x) + g'(y/x)(\frac{1}{x}) — ③ \end{aligned}$$

Again Differentiating w.r.t y we get-

$$\frac{\partial^2 z}{\partial y^2} = f''(y/x)(\frac{1}{x}) + g''(y/x)(\frac{1}{x^2})$$

$$\Rightarrow y^2 \frac{\partial^2 z}{\partial y^2} = \frac{y^2}{x}f''(y/x) + \frac{y^2}{x^2}g''(y/x) — ④$$

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Differentiating ③ w.r.t x , Partially, we get

$$\begin{aligned}\frac{\partial^2 z}{\partial x \partial y} &= f''(y/x) \left(-\frac{y}{x^2}\right) - \frac{1}{x^2} g'(y/x) + \frac{1}{x^3} g''(y/x) \left(-\frac{y}{x^2}\right) \\ &= -\frac{y}{x^2} f''(y/x) - \frac{1}{x^2} g'(y/x) - \frac{y}{x^3} g''(y/x)\end{aligned}$$

$$\begin{aligned}\Rightarrow 2xy \frac{\partial^2 z}{\partial x \partial y} &= 2xy \left[-\frac{y}{x^2} f''(y/x) - \frac{1}{x^2} g'(y/x) - \frac{y}{x^3} g''(y/x) \right] \\ &= -\frac{2y^2}{x} f''(y/x) - \frac{2y}{x^2} g'(y/x) - \frac{2y^2}{x^2} g''(y/x)\end{aligned}$$
5

from ②, ④ & ⑤

we have

$$\begin{aligned}x^2 \frac{\partial^2 z}{\partial x^2} + 2xy \frac{\partial^2 z}{\partial x \partial y} + y^2 \frac{\partial^2 z}{\partial y^2} &= \frac{y^2}{x} f''(y/x) + \frac{y^2}{x^2} g''(y/x) + \frac{2y}{x} g'(y/x) \\ &\quad - \frac{2y^2}{x} f''(y/x) - \frac{2y}{x} g'(y/x) - \frac{2y^2}{x^2} g''(y/x) \\ &\quad + \frac{y^2}{x} f''(y/x) + \frac{y^2}{x^2} g''(y/x) \\ &= 0\end{aligned}$$

$$\therefore x^2 \frac{\partial^2 z}{\partial x^2} + 2xy \frac{\partial^2 z}{\partial x \partial y} + y^2 \frac{\partial^2 z}{\partial y^2} = 0.$$

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3(b)(ii) Find constant a and b for which

$$f(a,b) = \int_0^{\pi} \{ \sin x - (ax^2 + bx) \}^2 dx \text{ is}$$

a minimum.

$$\begin{aligned} \underline{\text{Soln}} \quad f(a,b) &= \int_0^{\pi} (\sin^2 x + (ax^2 + bx)^2 - 2\sin x(ax^2 + bx)) dx \\ &= \int_0^{\pi} \frac{1 - \cos 2x}{2} dx + \int_0^{\pi} (ax^2 + bx)^2 dx - 2 \int_0^{\pi} \sin x(ax^2 + bx) dx \\ &\quad (I_1) \qquad (I_2) \qquad (I_3) \end{aligned}$$

$$I_1 = \frac{\pi}{2}$$

$$I_2 = \frac{a^2 \pi^5}{5} + \frac{b^2 \pi^3}{3} + \frac{ab \pi^4}{2}$$

$$I_3 = (a\pi^2 + b\pi - 4a)$$

→ solving by parts

$$\begin{aligned} f(a,b) &= \frac{\pi}{2} + \frac{a^2 \pi^5}{5} + \frac{b^2 \pi^3}{3} + \frac{ab \pi^4}{2} - 2a\pi^2 \\ &\quad - 2b\pi + 8a \end{aligned}$$

$$\text{for minimum } \frac{\partial f}{\partial a} = 0, \frac{\partial f}{\partial b} = 0$$

$$\Rightarrow \text{we get } -5\pi^4 b + 4a\pi^5 - 20\pi^2 + 80 = 0 \quad \text{--- (1)}$$

$$\text{solving eqn (1) and (2) we get } \frac{3a\pi^4 + 4b\pi^3}{\pi^4} = 12\pi \quad \text{--- (2)}$$

$$a = \frac{(20\pi^2 - 320)}{\pi^5}, \quad b = \frac{(240 - 12\pi^2)}{\pi^4}$$

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4(a) Let A be a square matrix of order 3 such that each of its diagonal elements is ' a ' and each of its off-diagonal elements is 1 . If $B = bA$ is orthogonal determine the values of a and b .

Sol'n: Given that $A = \begin{bmatrix} a & 1 & 1 \\ 1 & a & 1 \\ 1 & 1 & a \end{bmatrix}$

$$B = bA = \begin{bmatrix} ab & b & b \\ b & ab & b \\ b & b & ab \end{bmatrix}$$

As matrix B is orthogonal matrix.

$$B \cdot B^T = I$$

$$\begin{bmatrix} ab & b & b \\ b & ab & b \\ b & b & ab \end{bmatrix} \begin{bmatrix} ab & b & b \\ b & ab & b \\ b & b & ab \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} a^2b^2+2b^2 & 2ab^2+b^2 & 2ab^2+b^2 \\ 2ab^2+b^2 & a^2b^2+2b^2 & 2ab^2+b^2 \\ 2ab^2+b^2 & 2ab^2+b^2 & a^2b^2+2b^2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\Rightarrow a^2b^2+2b^2=1 \text{ and } 2ab^2+b^2=0$$

$$\text{from } (2a+1)b^2=0 \\ b \neq 0$$

$$\therefore 2a+1=0$$

$$\Rightarrow a=-\frac{1}{2}$$

$$\text{Again, } b^2(a^2+2)=1$$

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$$b^2 \left(\left(-\frac{1}{2} \right)^2 + 2 \right) = 1$$

$$b^2 \left(\frac{9}{4} \right) = 1$$

$$b = \sqrt{\frac{4}{9}}$$

$$b = \pm \frac{2}{3}$$

$$\therefore a = -\frac{1}{2}, \underline{b = \pm \frac{2}{3}}$$

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4(a)(ii)

If $M_2(\mathbb{R})$ is space of real matrices of order 2×2 and $P_2(x)$ is the space of real polynomials of degree at most 2, then find the matrix representation of $T: M_2(\mathbb{R}) \rightarrow P_2(x)$ such that

$$T = \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) = a + c + (a-d)x + (b+c)x^2$$

with respect to the standard bases of $M_2(\mathbb{R})$ and $P_2(x)$. Further find the null space of T .

Solution:- Given that

$$T \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) = a + c + (a-d)x + (b+c)x^2 \quad \text{--- (1)}$$

$$\text{Let } S = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

$T = \{1, x, x^2\}$ be the standard bases of $M_2(\mathbb{R})$ and $P_2(x)$.

$$T \left(\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \right) = 1 + x + 0x^2 = 1(1) + 1(x) + 0(x^2)$$

$$T \left(\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \right) = 0 + 0x + x^2 = 0(1) + 0(x) + 1(x^2)$$

$$T \left(\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \right) = 1 + 0x + 1x^2 = 1(1) + 0(x) + 1(x^2)$$

$$T \left(\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right) = 0 - 1x + 0x^2 = 0(1) + (-1)x + 0(x^2)$$

\therefore The required Matrix of linear transformation.

$$[T: M_2, P_2] = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & -1 \\ 0 & 1 & 1 & 0 \end{bmatrix}$$

$$\text{If } T = \begin{bmatrix} a & b \\ c & d \end{bmatrix} = 0 = 0 + 0x + 0x^2$$

$$\text{Then; } (a+c) + (a-d)x + (b+c)x^2 = 0 + 0x + 0x^2$$

$$\begin{array}{l} a+c=0 \\ a-d=0 \\ b+c=0 \end{array} \left. \begin{array}{l} \hline \\ \hline \end{array} \right. \Rightarrow c+d=0 \quad \text{--- (3)}$$

$$\text{--- (1)} \quad \text{--- (2)}$$

$$(3)-(2) \Rightarrow b-d=0 \Rightarrow \begin{array}{l} b=d \\ \hline a=d \\ \hline c=-d \end{array}$$

\therefore The null space of T

$$N(T) = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix} \mid \begin{bmatrix} b=d \\ a=d \\ c=-d \end{bmatrix} \right\} = \left\{ \begin{bmatrix} d & d \\ -d & d \end{bmatrix} \mid d \in \mathbb{R} \right\}$$

$$\boxed{\therefore N(T) = \left\{ \begin{bmatrix} d & d \\ -d & d \end{bmatrix} \mid d \in \mathbb{R} \right\}}$$

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4.(b)

→ find the minimum distance of the line given by the planes $3x+4y+5z=7$ and $x-z=9$ from the origin, by the method of Lagrange's multipliers.

Solution:-

Let (x, y, z) be the point on line formed by intersection of $\pi_1: 3x+4y+5z=7$ & $\pi_2: x-z=9$

Distance from origin be $d^2 = x^2 + y^2 + z^2$

using Lagrange's method to evaluate minimum value of $x^2 + y^2 + z^2$ subject to π_1 & π_2

$$F(x, y, z) = x^2 + y^2 + z^2 + \lambda_1(3x+4y+5z-7) + \lambda_2(x-z-9)$$

$$\frac{\partial F}{\partial x} = 2x + \lambda_1 3 + \lambda_2 = 0 \quad \dots \quad (1)$$

$$\frac{\partial F}{\partial y} = 2y + 4\lambda_1 = 0 \quad \dots \quad (2) \Rightarrow \boxed{\lambda_1 = -\frac{y}{2}}$$

$$\frac{\partial F}{\partial z} = 2z + \lambda_1(5) - \lambda_2 = 0 \quad \dots \quad (3)$$

Adding (1) and (3), we get

$$2(x+z) + 8\lambda_1 = 0$$

$$\lambda_1 = -\frac{2(x+z)}{8}$$

$$-\frac{y}{2} = -\frac{(x+z)}{4} \Rightarrow \boxed{2y = x+z} \quad \dots \quad (4)$$

Solving (4) & π_2

$$x = \frac{3y+9}{2} ; z = \frac{2y-9}{2}$$

Put these in π_1 .

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4.(c)

(i) The plane $x - 2y + 3z = 0$ is rotated through a right-angle about its line of intersection with the plane $2x + 3y - 4z - 5 = 0$, find the equation of the plane in its new position.

Sol'n: The equation of any plane through the line of intersection of the plane $x - 2y + 3z = 0$ and $2x + 3y - 4z - 5 = 0$ is

$$(x - 2y + 3z) + \lambda (2x + 3y - 4z - 5) = 0$$

$$\Rightarrow (1+2\lambda)x + (3\lambda-2)y + (3-4\lambda)z - 5\lambda = 0 \quad \text{--- (1)}$$

It is given that the angle between the plane $x - 2y + 3z = 0$ and (1) is a right angle, so the angle between their normals is a right angle. Also the d.r.'s of their normals are $1, -2, 3$ and $1+2\lambda, 3\lambda-2, 3-4\lambda$.

$$\therefore 1(1+2\lambda) - 2(3\lambda-2) + 3(3-4\lambda) = 0$$

$$\Rightarrow 1+2\lambda - 6\lambda + 4 + 9 - 12\lambda = 0$$

$$\Rightarrow 16\lambda = 14 \Rightarrow \lambda = 7/8.$$

\therefore from (1) the required equation is

$$[1+2(7/8)]x + [3(7/8)-2]y + [3-4(7/8)]z - 5(7/8) = 0$$

$$\Rightarrow 22x + 5y - 4z - 35 = 0.$$

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5.(a)

Solve: $\frac{dy}{dx} = \frac{y^2(x-y)}{3xy^2 - x^2y - 4y^3}, y(0) = 1.$

SOLUTION

Given equation is

$$\frac{dy}{dx} = \frac{y^2(x-y)}{3xy^2 - x^2y - 4y^3}$$

$$y^2(x-y) dx - (3xy^2 - x^2y - 4y^3) dy = 0$$

We need to check whether above equation is in exact form.

$$Mdx + Ndy = 0$$

∴ Let

$$M = y^2(x-y)$$

$$N = -(3xy^2 - x^2y - 4y^3)$$

$$\frac{\partial M}{\partial y} = 2yx - 3y^2$$

$$\frac{\partial N}{\partial x} = -3y^2 + 2xy$$

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x} \text{ exact form}$$

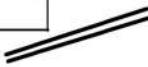
$$\therefore \text{General solution} \Rightarrow \int Mdx + \int Ndy = c$$

y constant y terms not containing X

$$\int y^2(x-y)dx - \int (3xy^2 - x^2y - 4y^3)dy$$

Required solutions

$$y^2 \frac{x^2}{2} - y^3 + y^4 = c$$



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5(b) Find (i) $L\{F(t)\}$ and (ii) $L\{F'(t)\}$ for the function given by $F(t) = \begin{cases} 2t, & 0 \leq t \leq 1 \\ t, & t > 1 \end{cases}$

Sol'n: Given that $F(t) = \begin{cases} 2t, & 0 \leq t \leq 1 \\ t, & t > 1 \end{cases}$ — ①

(i) By definition of Laplace transform, we have

$$L\{F(t)\} = \int_0^\infty e^{-st} F(t) dt = \int_0^1 e^{-st} F(t) dt + \int_1^\infty e^{-st} F(t) dt$$

$$= \int_0^1 e^{-st} (2t) dt + \int_1^\infty e^{-st} t dt, \text{ using } ①$$

$$= \left[(2t) \left(-\frac{1}{s} e^{-st} \right) \right]_0^1 - \int_0^1 2 \left(-\frac{1}{s} e^{-st} \right) dt + \left[(t) \left(-\frac{1}{s} e^{-st} \right) \right]_1^\infty - \int_1^\infty (1) \left(-\frac{1}{s} e^{-st} \right) dt$$

(on integration by parts)

$$= -\frac{2}{s} e^{-s} + \frac{2}{s} \left[-\frac{1}{s} e^{-st} \right]_0^1 - \frac{1}{s} \lim_{t \rightarrow \infty} t e^{-st} + \frac{1}{s} e^{-s} + \frac{1}{s} \left[-\frac{1}{s} e^{-st} \right]_1^\infty$$

$$= -\frac{2}{s} e^{-s} - \frac{2}{s^2} e^{-s} + \frac{2}{s^2} - \frac{1}{s} \lim_{t \rightarrow \infty} \left(\frac{t}{e^{st}} \right) + \frac{1}{s} e^{-s}$$

$$- \frac{1}{s^2} \lim_{t \rightarrow \infty} e^{-st} + \frac{1}{s^2} e^{-s}$$

$$= -\frac{1}{s} e^{-s} + \frac{2}{s^2} - \frac{1}{s^2} e^{-s} \quad [\because \text{If } s > 0, \text{ then } \lim_{t \rightarrow \infty} e^{-st} = 0]$$

and $\lim_{t \rightarrow \infty} \frac{t}{e^{st}} = \lim_{t \rightarrow \infty} \frac{1}{se^{st}} = 0$, by L'Hospital's rule]

$$\therefore L\{F(t)\} = \frac{2}{s^2} - \left(\frac{1}{s} + \frac{2}{s^2} \right) e^{-s}, \quad s > 0 \quad — ②$$

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finding $L\{F'(t)\}$: from ①, we have

$$F'(t) = \begin{cases} 2, & 0 < t < 1 \\ 1, & t > 1 \end{cases}$$

Using the definition of Laplace transform, we get

$$\begin{aligned} L\{F'(t)\} &= \int_0^\infty e^{-st} F'(t) dt = \int_0^1 e^{-st} F'(t) dt + \int_1^\infty e^{-st} F'(t) dt \\ &= \int_0^1 e^{-st} \cdot 2 dt + \int_1^\infty e^{-st} \cdot 1 dt, \text{ using ⑤} \\ &= 2 \left[-\frac{e^{-st}}{s} \right]_0^1 + \left[-\frac{e^{-st}}{s} \right]_1^\infty \\ &= -\frac{2}{s} e^{-s} + \frac{2}{s} - 0 + \frac{e^{-s}}{s}, s > 0 \\ &= \frac{2}{s} - \frac{2}{s} e^{-s} = \frac{1}{s} (2 - e^{-s}), s > 0. \end{aligned}$$

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5.(C), A sphere of weight W and radius a lies within a fixed spherical shell of radius b , and a particle of weight w is fixed to the upper end of the vertical diameter prove that the equilibrium is stable if $\frac{W}{w} > \frac{b-2a}{a}$

Sol: C is the point of contact of the sphere and the spherical shell, O is the centre of the sphere, CA is the vertical diameter of the sphere and B is the centre of the spherical shell.

We have $OC = a$ and $BC = b$.

The weight W of the sphere acts at O and a particle of weight w is attached to A If h be the height of the centre of gravity of the combined body consisting of the sphere and the weight w attached at A, then

$$h = \frac{W \cdot a + w \cdot 2a}{W + w} = \frac{W + 2w}{W + w} a$$

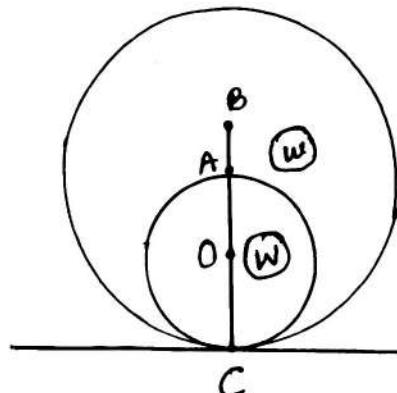
Here $p_1 = a$ and $p_2 = -b$

The equilibrium will be stable if

$$\frac{1}{h} > \frac{1}{p_1} + \frac{1}{p_2}$$

$$\text{i.e. } \frac{1}{h} > \frac{1}{a} - \frac{1}{b}$$

$$\text{i.e. } \frac{W+w}{a(W+2w)} > \frac{b-a}{ab}$$



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i.e. $(W+w)ab > a(b-a)(W+2w)$

i.e. $(W+w)b > (b-a)(W+2w)$

i.e. $W\{b-(b-a)\} > w\{2(b-a)-b\}$

i.e. $Wa > w(b-2a)$

i.e. $\frac{W}{w} > \frac{b-2a}{a}$

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5(d) →

A particle of mass 'm', is falling under the influence of gravity through a medium whose resistance equals μ times the velocity. If the particle were released from rest, determine the distance fallen through in time 't'.

Solution: Let a particle of mass 'm' falling under gravity be at a distance ' x_i ' from the starting point, after time 't'. If v is its velocity at this point, then the resistance on the particle is μv acting vertically upwards i.e., in the direction of ' x_i ' decreasing. The weight mg of the particle acts vertically downwards i.e., in the direction of x increasing.

∴ the equation of motion of the particle is

$$m \frac{d^2x}{dt^2} = mg - \mu v$$

$$\text{or } \frac{dv}{dt} = g - \frac{\mu}{m} v, \quad \left[\because \frac{d^2x}{dt^2} = \frac{dv}{dt} \right]$$

$$\text{or } dt = \frac{dv}{g - (\mu/m)v}$$

Integrating, we have

$$t = -\frac{m}{\mu} \log \left(g - \frac{\mu}{m} v \right) + A; \text{ where } A = \text{constant}$$

But initially, when $t=0, v=0$;

$$\therefore A = (m/\mu) \log g$$

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$$\therefore t = -\frac{m}{\mu} \log \left(g - \frac{\mu}{m} v \right) + \frac{m}{\mu} \log g$$

$$t = -\frac{m}{\mu} \log \left\{ \frac{g - (\mu/m)v}{g} \right\}$$

$$-\frac{\mu t}{m} = \log \left(1 - \frac{\mu}{gm} \cdot v \right)$$

$$1 - \frac{\mu}{gm} \cdot v = e^{-\frac{\mu t}{m}}$$

$$\Rightarrow v = \frac{dx}{dt} = \frac{gm}{\mu} (1 - e^{-\mu t/m})$$

$$dx = \frac{gm}{\mu} (1 - e^{-\mu t/m}) dt$$

Integrating, we have.

$$x = \frac{gm}{\mu} \left[t + \frac{m}{\mu} e^{-\mu t/m} \right] + B \quad \text{--- (1)}$$

B = constant

But initially, when $t=0, x=0$

$$\therefore 0 = \frac{gm}{\mu} \left[\frac{m}{\mu} \right] + B \quad \text{--- (2)}$$

Subtracting (2) from (1), we have

$$x = \frac{gm}{\mu} \left[\frac{m}{\mu} e^{-\mu t/m} - \frac{m}{\mu} + t \right]$$

$$\therefore x = \frac{gm^2}{\mu^2} \left[e^{-\mu t/m} - 1 + \frac{\mu t}{m} \right]$$

which is required result

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5(e)

Show that $\vec{F} = (2xy + z^3)\hat{i} + x^2\hat{j} + 3x^2z^2\hat{k}$ is a conservative force. Hence, find the scalar potential. Also find the work done in moving a particle of unit mass in the force field from $(1, -2, 1)$ to $(3, 1, 4)$.

Sol'n: The field F will be conservative if

$$\nabla \times F = 0$$

we have

$$\nabla \times F = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2xy + z^3 & x^2 & 3x^2z^2 \end{vmatrix}$$

$$= \hat{i}(0-0) - \hat{j}(3z^2 - 3z^2) + \hat{k}(2x - 2x) \\ = 0$$

$\therefore F$ is conservative force field.

$$\text{Let } F = \nabla \phi$$

$$\Rightarrow (2xy + z^3)\hat{i} + x^2\hat{j} + 3x^2z^2\hat{k} = \hat{i} \frac{\partial \phi}{\partial x} + \hat{j} \frac{\partial \phi}{\partial y} + \hat{k} \frac{\partial \phi}{\partial z}$$

$$\Rightarrow \frac{\partial \phi}{\partial x} = 2xy + z^3$$

Integrating partially w.r.t x

$$\phi = x^2y + z^3x + f_1(y, z) \quad \text{--- (1)}$$

where $f_1(y, z)$ is arbitrary function.

$$\frac{\partial \phi}{\partial y} = x^2 \quad \text{Integrating partially w.r.t } y$$

$$\phi = x^2y + f_2(x, z) \quad \text{--- (2)}$$

$$\frac{\partial \phi}{\partial z} = 3x^2z^2 \quad \text{Integrating partially w.r.t } z$$

$$\phi = x^2z^3 + f_3(x, y) \quad \text{--- (3)}$$

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Equn ①, ②, ③ each represents ϕ .

These agree if we choose

$$f_1(y, z) = 0, \quad f_2(x, z) = z^3 x, \quad f_3(x, y) = x^2 y$$

$\therefore \phi = x^2 y + xz^3$ to which may be added any constant.

$$\therefore \phi = x^2 y + xz^3 + C$$

$(3, 1, 4)$

$$\text{workdone} = \int_{(1, -2, 1)}^{(3, 1, 4)} F \cdot d\gamma$$

$$(1, -2, 1)$$

$$= \int_{(1, -2, 1)}^{(3, 1, 4)} d\phi$$

$$(1, -2, 1)$$

$$= [\phi]_{(1, -2, 1)}^{(3, 1, 4)}$$

$$= [x^2 y + xz^3]_{(1, -2, 1)}^{(3, 1, 4)}$$

$$= 202$$

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6(a) find the orthogonal trajectories of the family of curves $\frac{x^2}{a^2+\lambda} + \frac{y^2}{b^2+\lambda} = 1$, where λ is a parameter

Sol The given family of curves is

$$\frac{x^2}{a^2+\lambda} + \frac{y^2}{b^2+\lambda} = 1, \text{ where } \lambda \text{ as a parameter}$$

Differentiating ① w.r.t. x , we get

$$\frac{2x}{a^2+\lambda} + \frac{2y}{b^2+\lambda} \frac{dy}{dx} = 0$$

$$\Rightarrow x(b^2+\lambda) + y(a^2+\lambda) \frac{dy}{dx} = 0$$

$$\Rightarrow \lambda(a+4 \frac{dy}{dx}) = -(b^2x + a^2y \frac{dy}{dx})$$

$$\Rightarrow \lambda = -\frac{(b^2x + a^2y \frac{dy}{dx})}{a+4 \frac{dy}{dx}}$$

$$\therefore a^2+\lambda = a^2 - \frac{(b^2x + a^2y \frac{dy}{dx})}{a+4 \frac{dy}{dx}}$$

$$= \frac{(a^2-b^2)x}{a+4 \frac{dy}{dx}}$$

$$\text{and } b^2+\lambda = b^2 - \frac{(b^2x + a^2y \frac{dy}{dx})}{a+4 \frac{dy}{dx}}$$

$$= \frac{-(a^2-b^2)y \frac{dy}{dx}}{(a+4 \frac{dy}{dx})}$$

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putting the above values of α^2 and β^2

in ①, we have

$$\frac{x^2 \left\{ x + y \frac{dy}{dx} \right\}}{(x-b)x} - \frac{y^2 \left\{ x + y \frac{dy}{dx} \right\}}{(x-b)y \frac{dy}{dx}} = 1.$$

$$\Rightarrow \left\{ x + y \frac{dy}{dx} \right\} \left\{ x - y \frac{dx}{dy} \right\} = x^2 - b^2 \quad \text{--- ②}$$

which is the differential equation of the given family of curves ①

Replacing $\frac{dy}{dx}$ by $-\frac{dx}{dy}$ in ②, the differential equation of the required orthogonal trajectories is

$$\left\{ x + y \left(-\frac{dx}{dy} \right) \right\} \left\{ x - y \left\{ -\frac{dy}{dx} \right\} \right\} = a^2 - b^2$$

$$\Rightarrow \left(x - y \frac{dx}{dy} \right) \left(x + y \frac{dy}{dx} \right) = a^2 - b^2$$

which is same as the differential equation ② of the given family of curves ①.

Hence the system of given curves ① is self orthogonal, i.e., each member of the given family of curves intersects its own members orthogonally.

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6(6)

$$\text{Solve } (1+2x)^2 \frac{d^2y}{dx^2} - 6(1+2x) \frac{dy}{dx} + 16y = 8(1+2x)^2$$

$$y(0)=0 \text{ and } y'(0)=2.$$

Sol: Given $[(1+2x)^2 D^2 - 6(1+2x)D + 16]y = 8(1+2x)^2$ —①

$$\text{Let } (1+2x) = e^z$$

$$\log(1+2x) = z$$

$$\text{Also let } D_1 \equiv \frac{d}{dz} \quad \text{—②}$$

$$\text{Then } (1+2x)D = 2D_1, \quad (1+2x)^2 D^2 = 2^2 D_1 (D_1 - 1)$$

and so ① becomes

$$[2^2 D_1 (D_1 - 1) - 6 \cdot 2 D_1 + 16]y = 8e^{2z}$$

$$\Rightarrow (D_1 - 2)^2 y = 2e^{2z} \quad \text{—③}$$

Its auxiliary equation is $(D_1 - 2)^2 = 0$

$$\Rightarrow D_1 = 2, 2$$

$$\therefore C.F = (C_1 + C_2 z)e^{2z} = (C_1 + C_2 z)(e^z)^2$$

$$= [C_1 + C_2 \log(1+2x)] \cdot (1+2x)^2$$

where C_1 and C_2 are arbitrary constants.

$$P.I = \frac{1}{(D_1 - 2)^2} 2e^{2z} = 2 \frac{z^2}{2!} e^{2z}, \text{ as } \frac{1}{(D_1 - a)^n} e^{az} = \frac{z^n}{n!} e^{az}$$

$$= z^2 (e^z)^2 = [\log(1+2x)]^2 (1+2x)^2, \text{ using ②}$$

$$\therefore \text{solution is } y = [C_1 + C_2 \log(1+2x)] (1+2x)^2 + [\log(1+2x)]^2 (1+2x)^2$$

$$y = (1+2x)^2 [C_1 + C_2 \log(1+2x) + \{\log(1+2x)\}^2] \quad \text{—④}$$

$$y(x) = (1+2x)^2 [C_1 + C_2 \log(1+2x) + \log(1+2x)^2] \quad \text{—⑤}$$

Differentiating both sides of ⑤ w.r.t x we have

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$$y'(x) = (2 \times 2) (1+2x)^2 [C_1 + C_2 \log(1+2x) + \{ \log(1+2x) \}^2] \\ + (1+2x)^2 \left[\frac{2C_2}{1+2x} + \frac{2 \log(1+2x) \times 2}{1+2x} \right] \quad \text{--- (6)}$$

$$y'(x) = (2 \times 2) (1+2x)^2 [C_1 + C_2 \log(1+2x) + \{ \log(1+2x) \}^2] \\ + (1+2x)^2 \left[\frac{2C_2}{1+2x} + \frac{2 \log(1+2x) \times 2}{(1+2x)} \right] \quad \text{--- (6)}$$

putting $x=0$ in (5) & noting that $y(0)=0$ (given), we get

$$0 = 1 [C_1 + (C_2 \times 0) + 0^2] \text{ so that } C_1 = 0$$

putting $x=0$ in (6) and noting that $y'(0)=2$ (given)

we get

$$2 = 4 [C_1 + (C_2 \times 0) + 0^2] + 1 [2C_2 + (2 \times 0 \times 2)]$$

so that $C_2 = 1$, as $C_1 = 0$

putting the above values of C_1 and C_2 in (5), the required solution is

$$y(x) = (1+2x)^2 \log(1+2x) [1 + \log(1+2x)].$$



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(6c) Solve the differential equation $(x^2+y^2)(1+p)^2 - 2(x+y)(1+p)(x+yp) = 0$, where $p = \frac{dy}{dx}$, by reducing it to Clairaut's form $(x+yp)^2 = 0$, using suitable substitution.

Sol'n: Given that

$$(x^2+y^2)(1+p)^2 - 2(x+y)(1+p)(x+yp) + (x+yp)^2 = 0$$

$$\text{Put } x+y=u, x^2+y^2=v.$$

$$\Rightarrow 1+\frac{dy}{dx} = \frac{du}{dx}; 2x+2y\frac{dy}{dx} = \frac{dv}{dx}$$

$$\Rightarrow 1+p = \frac{du}{dx}; 2x+2yp = \frac{dv}{dx}$$

$$\therefore \frac{dv}{dx} = \frac{2(x+yp)}{1+p}$$

$$\Rightarrow p = \frac{2(x+yp)}{1+p}; \text{ where } P = \frac{dv}{dx}, P = \frac{du}{dx}$$

$$\Rightarrow P(1+p) = 2(x+yp)$$

$$\Rightarrow P + Pp = 2x + 2yp \Rightarrow P - 2x = P(2y - P)$$

$$\Rightarrow P = \frac{P-2x}{2y-P} \quad \text{--- (1)}$$

using (1) the given equation becomes

$$(x^2+y^2) \left[1 + \frac{P-2x}{2y-P} \right]^2 - 2(x+y) \left(1 + \frac{P-2x}{2y-P} \right) \left(x+y \frac{P-2x}{2y-P} \right) + \left(x+y \frac{P-2x}{2y-P} \right)^2 = 0$$

$$\Rightarrow (x^2+y^2) \left[\frac{2y-2x}{2y-P} \right]^2 - 2(x+y) \left[\frac{2y-2x}{2y-P} \right] P \frac{(y-x)}{2y-P} + P^2 \left(\frac{y-x}{2y-P} \right)^2 = 0$$

$$\Rightarrow (x^2+y^2) 4(y-x)^2 - 4(x+y)(y-x)^2 P + P^2 (y-x)^2 = 0$$

$$\Rightarrow 4(x^2+y^2) - 4P(x+y) + P^2 = 0$$

$$\Rightarrow 4v - 4pu + p^2 = 0$$

$$\Rightarrow v = pu - \frac{p^2}{4}$$

which is of Clairaut's form and its solution is

$$v = uc - \frac{c^2}{4}$$

$$\text{i.e., } x^2+y^2 = (x+y)c - \underline{\underline{\frac{c^2}{4}}}$$

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6.(d) Use Laplace transform method to solve the following initial value problem:

$$\frac{d^2x}{dt^2} - 2\frac{dx}{dt} + x = e^t, \quad x(0) = 2 \text{ and } \left.\frac{dx}{dt}\right|_{t=0} = -1$$

SOLUTION

$$\text{Given } x'' - 2x' + x = e^t$$

Applying Laplace transform on both sides

$$s^2 \mathcal{L}(x) - sx(0) - x'(0) - 2s \mathcal{L}(x) + 2x(0) + \mathcal{L}(x) = \frac{1}{s-1}$$

$$(\text{Given } x(0) = 2 \text{ and } x'(0) = -1)$$

$$(s^2 - 2s + 1) \mathcal{L}(x) - 2s + 1 + 4 = \frac{1}{s-1}$$

$$\mathcal{L}(x) = \frac{1}{(s-1)(s-1)^2} + \frac{2s-5}{(s-1)^2}$$

$$\mathcal{L}(x) = \frac{1}{(s-1)^3} + \frac{2}{(s-1)} - \frac{3}{(s-1)^2}$$

$$X(t) = \mathcal{L}^{-1} \left[\frac{1}{(s-1)^3} + \frac{2}{s-1} - \frac{3}{(s-1)^2} \right]$$

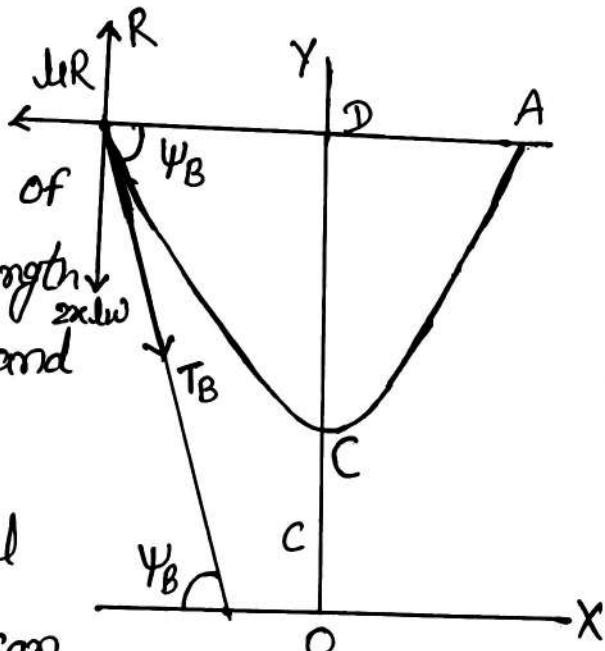
$$= e^t \left(\frac{t^2}{2} - 3t + 2 \right)$$



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7.(a). A heavy chain, of length $2l$, has one end tied at A and the other is attached to a small heavy ring which can slide on a rough horizontal rod which passes through A . If the weight of the ring be n times the weight of the chain, show that its greatest possible distance from A is $\frac{2l}{\lambda} \log \left\{ \lambda + \sqrt{1+\lambda^2} \right\}$, where $1/\lambda = \mu(2n+1)$ and μ is the coefficient of friction.

Sol: Let one end of a heavy chain of length $2l$ be fixed at A and the other end be attached to a small heavy ring which can slide on a rough horizontal rod ADB through A . Let B be the position of limiting equilibrium of the ring when it is at



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greatest possible distance from A.

In this position of limiting equilibrium the forces acting on the ring are:

- (i) the weight $2\pi l w$ of the ring acting vertically downwards,
- (ii) the normal reaction R of the rod,
- (iii) the force of limiting friction μR of the rod acting in the direction AB, and
- (iv) the tension T_B in the string at B acting along the tangent to the string at B.

For the equilibrium of the ring at B. resolving the forces acting on it horizontally and vertically, we have

$$\mu R = T_B \cos \psi_B \quad \dots \quad ①$$

$$\text{and } R = 2\pi l w + T_B \sin \psi_B, \quad \dots \quad ②$$

where ψ_B is the angle of inclination of the tangent at B to the horizontal.

Let C be the lowest point of the catenary formed by the chain, OX be the

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directrix and $OC = c$ be the parameter. We have $\text{arc } CB = SB = l$. By the formula $T \cos \psi = \omega c$, we have $T_B \cos \psi_B = \omega c$. Also by the formula $T \sin \psi = \omega s$, we have

$$T_B \sin \psi_B = \omega s_B = \omega l.$$

Putting these values in ① and ②, we have

$$\begin{aligned} \mu R &= \omega c \text{ and } R = 2\pi l \omega + \omega l \\ &= (2n+1) \omega l. \end{aligned}$$

$$\therefore \mu(2n+1)\omega l = \omega c$$

$$\text{or } \mu(2n+1)l = c.$$

But it is given that

$$\mu(2n+1) = 1/\lambda$$

$$\therefore 1/\lambda = c \quad \text{--- } ③$$

Using the formula $s = c \tan \psi$ for the point B, we have

$$l = c \tan \psi_B$$

$$\therefore \tan \psi_B = l/c = \lambda \quad \text{--- } ④$$

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Now the required greatest possible distance
of the ring from A

$$= AB = 2DB = 2x_B$$

$$= 2c \log(\sec \psi_B + \tan \psi_B)$$

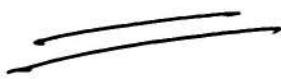
$$\left[\because x = c \log(\sec \psi + \tan \psi) \right]$$

$$= 2c \log \left[\tan \psi_B + \sqrt{1 + \tan^2 \psi_B} \right]$$

$$= \frac{2l}{\lambda} \log \left[\lambda + \sqrt{(1+\lambda)^2} \right]$$

$$\left[\because \text{from } ③, c = l/\lambda \text{ and} \right.$$

$$\left. \text{from } ④, \tan \psi_B = \lambda \right]$$



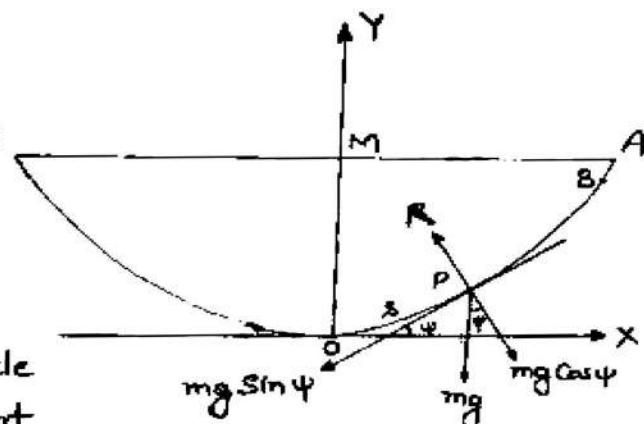
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7.(b)

A particle is projected with velocity V from the cusp of a smooth inverted cycloid down the arc, show that the time of reaching the vertex is $2\sqrt{a/g} \tan^{-1}[\sqrt{(4ag)/V^2}]$.

Solⁿ →

Let a Particle be projected with velocity V from the cusp A of a smooth inverted cycloid down the arc. If P is the position of the particle at time t such that



the tangent at P is inclined at an angle ψ to the horizontal and $OP = s$ then the equations of motion of the particle are

$$m \frac{d^2s}{dt^2} = -mg \sin \psi \quad \text{--- (1)}$$

$$\text{and } m \frac{v^2}{s} = R - mg \cos \psi \quad \text{--- (2)}$$

$$\text{for the cycloid, } s = 4a \sin \psi \quad \text{--- (3)}$$

from eqn (1) and (3) we have —

$$\frac{d^2s}{dt^2} = -\frac{g}{4a} s.$$

Multiplying both sides by $2(ds/dt)$ and integrating we have,

$$v^2 = \left(\frac{ds}{dt} \right)^2 = -\frac{g}{4a} s^2 + A.$$

But initially at the cusp A ,

$$s = 4a \text{ and } \left(\frac{ds}{dt} \right)^2 = V^2$$

$$\therefore V^2 = -\left(\frac{g}{4a}\right) \cdot 16a^2 + A \text{ or } A = V^2 + 4ag.$$

$$\therefore v^2 = \left(\frac{ds}{dt} \right)^2 = V^2 + 4ag - \frac{g}{4a} s^2 = \left(\frac{g}{4a} \right) \left[\frac{4a(V^2 + 4ag)}{s^2} - s^2 \right]$$

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or. $\frac{ds}{dt} = -\frac{1}{2} \sqrt{\left(\frac{g}{a}\right)} \sqrt{\left[\frac{4a}{g}(v^2 + 4ag) - s^2\right]}$

(-ve sign is taken because the particle is moving in the direction of s decreasing)

or. $dt = -2 \sqrt{\left(\frac{a}{g}\right)} \frac{ds}{\sqrt{\left[\left(\frac{4a}{g}\right)(v^2 + 4ag) - s^2\right]}}$

Integrating, the time t_1 , from the cusp A to the vertex O is given by -

$$\begin{aligned} t_1 &= -2 \sqrt{\left(\frac{a}{g}\right)} \int_{s=4a}^0 \frac{ds}{\sqrt{\left[\left(\frac{4a}{g}\right)(v^2 + 4ag) - s^2\right]}} \\ &= 2 \sqrt{\left(\frac{a}{g}\right)} \int_0^{4a} \frac{ds}{\sqrt{\left[\left(\frac{4a}{g}\right)(v^2 + 4ag) - s^2\right]}} \\ &= 2 \sqrt{\left(\frac{a}{g}\right)} \left[\sin^{-1} \frac{s}{2\sqrt{\left(\frac{4a}{g}\right)} \sqrt{v^2 + 4ag}} \right]_0^{4a} \\ &= 2 \sqrt{\left(\frac{a}{g}\right)} \sin^{-1} \left\{ \frac{2\sqrt{ag}}{\sqrt{v^2 + 4ag}} \right\} \\ &= 2 \sqrt{\left(\frac{a}{g}\right)} \cdot \theta \quad \text{--- (4)} \end{aligned}$$

Where $\theta = \sin^{-1} \left\{ \frac{2\sqrt{ag}}{\sqrt{v^2 + 4ag}} \right\}$

We have $\sin \theta = \frac{2\sqrt{ag}}{\sqrt{v^2 + 4ag}}$

$$\therefore \cos \theta = \sqrt{(1 - \sin^2 \theta)} = \sqrt{\left[1 - \frac{4ag}{v^2 + 4ag}\right]} = \frac{v}{\sqrt{v^2 + 4ag}}$$

$$\therefore \tan \theta = \frac{\sin \theta}{\cos \theta} = \frac{2\sqrt{ag}}{v} = \frac{\sqrt{4ag}}{v}$$

or. $\theta = \tan^{-1} \left[\sqrt{4ag}/v \right]$

∴ from (4), the time of reaching the vertex is $= 2 \sqrt{\left(\frac{a}{g}\right)} \tan^{-1} \left[\sqrt{4ag}/v \right]$.

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7.(C) A shot fired at an elevation α is observed to strike the foot of a tower which raise above a horizontal plane through the point of projection. If θ be the angle subtended by the tower at this point, show that the elevation required to make the shot strike the top of the tower is $\frac{1}{2}[\theta + \sin^{-1}(\sin\theta + \sin 2\alpha \cos\theta)]$.

Sol'n: Let AB be the tower and O the point of projection. It is given that $\angle AOB = \theta$.

Let u be the velocity of projection of the shot. When the shot is fired at an elevation α from O, it strikes the foot A of the tower AB, let $OA = R$.

$$\text{Then } R = \frac{u^2 \sin 2\alpha}{g}.$$

Referred to the horizontal & vertical lines OX & OY lying in the plane of motion as the coordinate axes, the coordinates of the top B of the tower are $(R, R\tan\theta)$. If β be the angle of projection to hit B from O, then the point B lies on the trajectory whose equation is

$$y = R\tan\beta - \frac{1}{2}g \frac{x^2}{u^2 \cos^2 \beta}$$

$$\therefore R\tan\theta = R\tan\beta - \frac{1}{2}g \frac{R^2}{u^2 \cos^2 \beta}$$

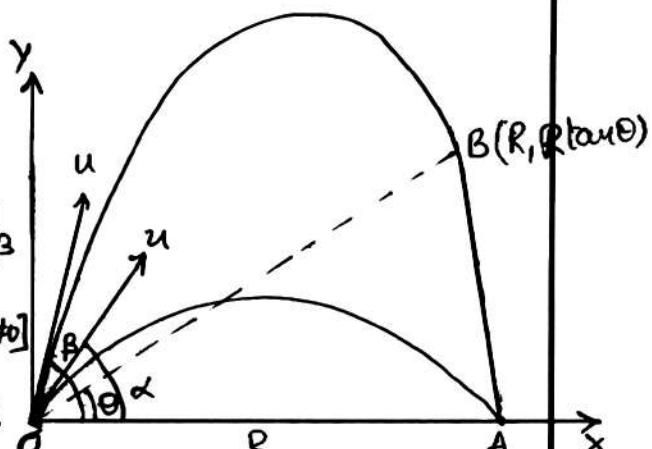
$$\tan\theta = \tan\beta - \frac{1}{2}g \frac{R}{u^2 \cos^2 \beta} \quad [:: R \neq 0]$$

Substituting the value of R

from ①, we get

$$\tan\theta = \tan\beta - \frac{1}{2}g \frac{u^2 \sin 2\alpha}{g} \cdot \frac{1}{u^2 \cos^2 \beta}$$

$$\Rightarrow \tan\theta = \tan\beta - \frac{\sin 2\alpha}{2 \cos^2 \beta}$$



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$$\Rightarrow \frac{\sin\theta}{\cos\theta} = \frac{\sin\beta}{\cos\beta} - \frac{\sin 2\alpha}{2\cos^2\beta}$$

Multiplying both sides by $2\cos^2\beta \cos\theta$, we get

$$2\cos^2\beta \sin\theta = 2\sin\beta \cos\beta \cos\theta - \cos\theta \sin 2\alpha$$

$$\Rightarrow (1 + \cos 2\beta) \sin\theta = \sin 2\beta \cos\theta - \cos\theta \sin 2\alpha$$

$$\Rightarrow \sin 2\beta \cos\theta - \cos 2\beta \sin\theta = \sin\theta + \cos\theta \sin 2\alpha$$

$$\Rightarrow \sin(2\beta - \theta) = \sin\theta + \cos\theta \sin 2\alpha$$

$$\Rightarrow 2\beta - \theta = \sin^{-1}(\sin\theta + \cos\theta \sin 2\alpha)$$

$$\Rightarrow 2\beta = \theta + \sin^{-1}(\sin\theta + \cos\theta \sin 2\alpha)$$

$$\Rightarrow \beta = \underline{\underline{\frac{1}{2} [\theta + \sin^{-1}(\sin\theta + \cos\theta \sin 2\alpha)]}}$$

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8(a) Find the angle b/w the tangents to the curve $\vec{r} = t^2 \hat{i} - 2t \hat{j} + t^3 \hat{k}$ at the points $t=1$ and $t=2$.

Sol'n : Given that $\vec{r} = t^2 \hat{i} - 2t \hat{j} + t^3 \hat{k}$
 Tangent vector is given by

$$\frac{d\vec{r}}{dt} = 2t \hat{i} - 2 \hat{j} + 3t^2 \hat{k}$$

$$\text{At } t=1, \frac{d\vec{r}}{dt} = 2\hat{i} - 2\hat{j} + 3\hat{k} = T_1 \text{ (say)}$$

$$t=2, \frac{d\vec{r}}{dt} = 4\hat{i} - 2\hat{j} + 12\hat{k} = T_2 \text{ (say)}$$

Angle b/w the tangents T_1 and T_2 is given by

$$\begin{aligned} \cos \theta &= \frac{T_1 \cdot T_2}{|T_1| |T_2|} \\ &= \frac{(2\hat{i} - 2\hat{j} + 3\hat{k}) (4\hat{i} - 2\hat{j} + 12\hat{k})}{\sqrt{4+4+9} \sqrt{16+4+144}} \end{aligned}$$

$$= \frac{(8+4+36)}{\sqrt{17} \sqrt{164}}$$

$$= \frac{48}{\sqrt{17} \sqrt{164}}$$

$$\cos \theta = \frac{48}{2\sqrt{41}\sqrt{17}}$$

$$\theta = \cos^{-1} \left(\frac{24}{\sqrt{17}\sqrt{41}} \right)$$

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Q.(b)(i) Find $f(r)$ such that $\nabla f = \frac{\vec{r}}{r^5}$ and $f(1) = 0$.

SOLUTION

We know that,

$$\nabla f = f'(r)\nabla r = f'(r)\frac{\vec{r}}{r} \quad \left(\because \nabla r = \frac{\vec{r}}{r}\right)$$

We have,

$$\nabla f = \frac{\vec{r}}{r^5}$$

$$\therefore f'(r)\frac{\vec{r}}{r} = \frac{\vec{r}}{r^5}$$

$$\Rightarrow \vec{r} \left[\frac{f'(r)}{r} - \frac{1}{r^5} \right] = 0$$

Since, $\vec{r} \neq 0$

$$\therefore f'(r) = \frac{1}{r^4}$$

Integrating we get,

$$f(r) = \frac{-1}{3r^3} + C$$

$$f(1) = 0 \Rightarrow 0 = \frac{-1}{3 \cdot 1} + c \Rightarrow c = \frac{1}{3}$$

$$\therefore f(r) = \frac{1}{3} \left(1 - \frac{1}{r^3} \right)$$

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8(b)(ii) Find the curvature and torsion at any point of the curve $x = a \cos 2t$, $y = a \sin 2t$, $z = 2a \sin t$.

Soln: The position vector for any point on the curve is

$$\vec{r} = a \cos 2t \hat{i} + a \sin 2t \hat{j} + 2a \sin t \hat{k}$$

$$\frac{d\vec{r}}{dt} = 2a \sin 2t \hat{i} + 2a \cos 2t \hat{j} + 2a \cos t \hat{k}$$

$$\frac{d^2\vec{r}}{dt^2} = 4a \cos 2t \hat{i} - 4a \sin 2t \hat{j} - 2a \sin t \hat{k}$$

$$\text{and } \frac{d^3\vec{r}}{dt^3} = -8a \sin 2t \hat{i} - 8a \cos 2t \hat{j} - 2a \cos t \hat{k}$$

$$\text{Now } \frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 2a \sin 2t & 2a \cos 2t & 2a \cos t \\ 4a \cos 2t & -4a \sin 2t & -2a \sin t \end{vmatrix}$$

$$= i (-4a^2 \sin t \cos 2t + 8a^2 \cos t \sin 2t)$$

$$+ j (8a^2 \cos t \cos 2t + 4a^2 \sin t \sin 2t)$$

$$+ k (-8a^2 \sin^2 2t - 8a^2 \cos^2 2t)$$

$$= ia^2 (-4 \sin t \cos 2t + 8 \cos t \sin 2t) +$$

$$ja^2 (8 \cos t \cos 2t + 4 \sin t \sin 2t) - 8a^2 k$$

$$\left| \frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} \right| = a^2 \sqrt{(-4 \sin t \cos 2t + 8 \cos t \sin 2t)^2 + (8 \cos t \cos 2t + 4 \sin t \sin 2t)^2 + (8)^2}$$

$$= a^2 \sqrt{16 \sin^2 t (\cos^2 2t + \sin^2 2t) + 64 \cos^2 t (\sin^2 2t + \cos^2 2t) + 64}$$

$$= a^2 \sqrt{16 \sin^2 t + 1 + 64 \cos^2 t + 1 + 64}$$

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$$= a^2 \sqrt{16(\sin^2 t + \cos^2 t) + 48 \cos^2 t + 64}$$

$$= a^2 \sqrt{48 \cos^2 t + 80}$$

$$= 4a^2 \sqrt{3 \cos^2 t + 5}$$

$$\begin{aligned} \left[\frac{d\vec{s}}{dt} \quad \frac{d^2\vec{s}}{dt^2} \quad \frac{d^3\vec{s}}{dt^3} \right] &= \frac{d\vec{s}}{dt} \times \frac{d^2\vec{s}}{dt^2} \cdot \frac{d^3\vec{s}}{dt^3} \\ &= (-8a \sin 2t) [4a^2 \sin t \cos 2t + 8a^2 \cos t \sin 2t] \\ &\quad - 8a \cos 2t [8a^2 \cos t \cos 2t + 4a^2 \sin t \sin 2t] \\ &\quad - 2a \cos t [-8a^2] \\ &= a^3 [-64 \cos t (\sin^2 2t + \cos^2 2t) + 16 \cos t] \\ &= a^3 [-64 \cos t + 16 \cos t] = -48a^3 \cos t \end{aligned}$$

$$\left| \frac{d\vec{s}}{dt} \right| = \sqrt{4a^2 \sin^2 2t + 4a^2 \cos^2 2t + 4a^2 \cos^2 t} = 2a \sqrt{1 + \cos^2 t}$$

$$\therefore \text{Curvature } (K) = \left| \frac{d\vec{s}}{dt} \times \frac{d^2\vec{s}}{dt^2} \right| / \left| \frac{d\vec{s}}{dt} \right|^3$$

$$= \frac{4a^2 \sqrt{3 \cos^2 t + 5}}{2a \sqrt{1 + \cos^2 t}} = \frac{2a \sqrt{3 \cos^2 t + 5}}{\sqrt{1 + \cos^2 t}}$$

$$\text{Torsion } (\tau) = \frac{\left| \frac{d\vec{s}}{dt} \cdot \frac{d^2\vec{s}}{dt^2} \cdot \frac{d^3\vec{s}}{dt^3} \right|}{\left| \frac{d\vec{s}}{dt} \times \frac{d^2\vec{s}}{dt^2} \right|^2}$$

$$= \frac{-48a^3 \cos t}{[4a^2 \sqrt{3 \cos^2 t + 5}]^2} = \frac{-48a^3 \cos t}{16a^4 (3 \cos^2 t + 5)}$$

$$= \frac{-3 \cos t}{3 \cos^2 t + 5}$$

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8(c) Evaluate the integral: $\iint_S \vec{F} \cdot \hat{n} ds$; where

$\vec{F} = 3xy^2\hat{i} + (y^2 - y^3)\hat{j} + 3z^2\hat{k}$ and 'S' is a surface of cylinder $y^2 + z^2 \leq 4$; $-3 \leq x \leq 3$; using divergence theorem.

Sol- Using Gauss divergence theorem.

$$\iiint \nabla \cdot \vec{F} dV = \iint_S \vec{F} \cdot \hat{n} ds$$

$$\text{Now, } \vec{F} = 3xy^2\hat{i} + (y^2 - y^3)\hat{j} + 3z^2\hat{k}$$

$$\nabla \cdot \vec{F} = 3y^2 + x^2 - 3y^2 + 3x^2 = x^2 + 3x^2 = 4x^2$$

$$\therefore \iint_S \vec{F} \cdot \hat{n} ds = \iiint \nabla \cdot \vec{F} dV$$

$$I = \iiint 4x^2 dx dy dz$$

converting to cylinder co-ordinates.

$$y = r \cos \theta \quad ; \quad z = r \sin \theta \quad ; \quad x = x$$

$$I = \int_{0}^{2\pi} \int_{0}^2 \int_{-3}^3 4x^2 dr dx d\theta [H]$$

$$P = \int_{0}^{2\pi} \int_{0}^2 \left[\frac{4r^3}{3} \right]_{-3}^3 = 72 \int_{0}^{2\pi} \int_0^2 r dr d\theta$$

$$Q = 72 \int_0^{2\pi} \left[\frac{r^2}{2} \right]_0^2 d\theta = 144 \int_0^{2\pi} d\theta$$

$\boxed{Q = 288 \pi}$

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8(d)

Verify Stoke's theorem for the vector

$A = 3y \hat{i} - xz \hat{j} + yz^2 \hat{k}$, where 'S' is the surface of the paraboloid ; $2z = x^2 + y^2$ bounded by $z=2$ and 'C' is its boundary.

Solution:-

The boundary 'C' of the surface 'S' is the circle in the plane $z=2$, whose equations are $x^2 + y^2 = 4$, $z=2$.

The radius of this circle is 2 and centre (0,0,2). Suppose $x = 2 \cos t$, $y = 2 \sin t$, $z = 2$; $0 \leq t < 2\pi$ are parametric equations of 'C'. By Stoke's theorem

$$\oint_C A \cdot d\mathbf{r} = \iint_S (\operatorname{curl} A) \cdot \mathbf{n} dS,$$

when \mathbf{n} is a unit vector along outward drawn normal to the surface S.

We have;

$$\begin{aligned}\oint_C A \cdot d\mathbf{r} &= \oint_C (3y \hat{i} - xz \hat{j} + yz^2 \hat{k}) (dx \hat{i} + dy \hat{j} + dz \hat{k}) \\ &= \oint_C (3y dx - xz dy + yz^2 dz) \\ &= \oint_C (3y dx - 2x dy),\end{aligned}$$

Since, on C; $z=2$ and $dz=0$

$$= \int_{2\pi}^0 \left(3y \frac{dx}{dt} - 2x \frac{dy}{dt} \right) dt$$

[Note that here the surface 'S' lies below the curve 'C' and so direction of 'C' is positive if 'C' is traversed in clockwise sense].

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$$\begin{aligned}
 &= - \int_0^{2\pi} [3 \cdot 2 \sin t \cdot (-2 \sin t) - 2 \cdot 2 \cos t \cdot 2 \cos t] dt \\
 &= - \int_0^{2\pi} [-12 \sin^2 t - 8 \cos^2 t] dt \\
 &= 4 \left[12 \int_0^{\pi/2} \sin^2 t dt + 8 \int_0^{\pi/2} \cos^2 t dt \right] \\
 &= 4 \left[12 \cdot \frac{1}{2} \cdot \frac{\pi}{2} + 8 \cdot \frac{1}{2} \cdot \frac{\pi}{2} \right] = \frac{4\pi}{4} [12\pi + 8\pi] \\
 &= 20\pi. \quad \text{--- (1)}
 \end{aligned}$$

Let, S_1 be the plane region bounded by the circle 'C'. If S' is the surface consisting of the surface S and S_1 , then S' is a closed surface.

Let, V be the volume bounded by S' .

By Gauss divergence theorem, we have

$$\begin{aligned}
 \iint_{S'} (\operatorname{curl} A) \cdot n ds &= \iiint_V \operatorname{div} \operatorname{curl} A dv \\
 &= 0; \quad [\text{since } \operatorname{div} \operatorname{curl} A = 0].
 \end{aligned}$$

$$\begin{aligned}
 \therefore \iint_S (\operatorname{curl} A) \cdot n ds + \iint_{S_1} (\operatorname{curl} A) \cdot n ds &= 0 \\
 [\because S' \text{ consists of } S \text{ and } S_1]
 \end{aligned}$$

$$\begin{aligned}
 \iint_S (\operatorname{curl} A) \cdot n ds &= - \iint_{S_1} (\operatorname{curl} A) \cdot n ds \\
 &= - \iint_{S_1} (\operatorname{curl} A) \cdot k ds \\
 [\because \text{on } S_1, n = k]
 \end{aligned}$$

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$$\text{Now; } \text{curl } A = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 3y & -xz & yz^2 \end{vmatrix}$$

$$\begin{aligned} \text{curl } A &= i \left[\frac{\partial}{\partial y} (yz^2) + \frac{\partial}{\partial z} (-xz) \right] - j \left[\frac{\partial}{\partial x} (yz^2) - \frac{\partial}{\partial z} (3y) \right] \\ &\quad + k \left[\frac{\partial}{\partial x} (-xz) - \frac{\partial}{\partial y} (3y) \right] \end{aligned}$$

$\text{curl } A = (z^2 + x)i - (z+3)k$

$$\begin{aligned} \therefore \iint_S (\text{curl } A) \cdot n \, ds &= - \iint_{S_1} [(z^2 + x)i - (z+3)k] \cdot k \, ds \\ &= \iint_{S_1} (z+3) \, ds = \iint_{S_1} 5 \, ds \quad [\because n \, S_1, z=2] \\ &= 5S_1, \text{ where } S_1 \text{ is the area of a circle of} \\ &\quad \text{radius 2.} \\ &= 5 \cdot \pi \cdot (2)^2 = 20\pi. \end{aligned}$$

$\therefore \oint_C A \cdot d\alpha = \iint_S (\text{curl } A) \cdot n \, ds = 20\pi$

Hence proved.