

MAINS TEST SERIES-2021
TEST-15 (BATCH-I)
FULL SYLLABUS (PAPER-I)

Answer Key

1.(a) → Let V be the vector space of functions from \mathbb{R} into \mathbb{R} . Show that $f, g, h \in V$ are linearly independent where $f(t) = e^{2t}$, $g(t) = t^2$, $h(t) = t$.

Sol: Set a linear combination of the functions equal to the zero function 0 using unknown scalars x, y and z .

$$xf + yg + zh = 0$$

and then show that $x=0, y=0, z=0$.

We emphasize that $xf + yg + zh = 0$ means that, for every value of t ,

$$xf(t) + yg(t) + zh(t) = 0.$$

In the equation

$$xe^{2t} + yt^2 + zt = 0, \text{ substitute}$$

$$t=0 \text{ to obtain } xe^0 + y0 + z0 = 0 \text{ or } x=0$$

$$t=1 \text{ to obtain } xe^2 + y + z = 0$$

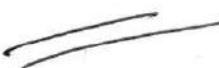
$$t=2 \text{ to obtain } xe^4 + 4y + 2z = 0$$

Solve the system

$$\left\{ \begin{array}{l} x=0 \\ xe^2 + y + z = 0 \\ xe^4 + 4y + 2z = 0 \end{array} \right.$$

to obtain only the zero solution: $x=0, y=0, z=0$.

Hence f, g and h are independent



1.(b)

Let $A = \begin{bmatrix} 1 & -3 & -4 \\ -4 & 6 & -2 \\ -3 & 7 & 6 \end{bmatrix}$ and $b = \begin{bmatrix} 3 \\ 3 \\ -4 \end{bmatrix}$. Determine

Whether b is in the column space of A .

Sol: The vector b is a linear combination of the columns of A if and only if b can be written as AX for some x , that is, if and only if the equation $AX = b$ has a solution.

Row reducing the augmented matrix $[A \ b]$,

$$\left[\begin{array}{ccc|c} 1 & -3 & -4 & 3 \\ -4 & 6 & -2 & 3 \\ -3 & 7 & 6 & -4 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & -3 & -4 & 3 \\ 0 & -6 & -18 & 15 \\ 0 & -2 & -6 & 5 \end{array} \right]$$

$$\sim \left[\begin{array}{ccc|c} 1 & -3 & -4 & 3 \\ 0 & -6 & -18 & 15 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

We conclude that $AX = b$ is consistent and b is in $\text{col } A$.

The above solution shows that when a system of linear equations is written in the form $AX = b$, the column space of A is the set of all b for which the system has a solution.

1.(c) → Find the asymptotes of the curve:

$$x^3 + 2x^2y + xy^2 - x^2 - xy + 2 = 0.$$

Solⁿ: $\phi_3(x, y) = x^3 + 2x^2y + xy^2$, $\phi_2(x, y) = -x^2 - xy$,
and $\phi_1(x, y) = 0$.

Let the asymptotes be given by $y = mx + c$.

Step 1. Putting $x=1$ and $y=m$, we obtain

$$\phi_3(m) = 1 + 2m + m^2, \phi_2(m) = -1 - m, \phi_1(m) = 0.$$

Step 2. The slopes of asymptotes are given by $\phi_3(m)=0$.

$$\text{i.e., } 1 + 2m + m^2 = 0$$

$$\Rightarrow (m+1)^2 = 0 \Rightarrow m = -1, -1.$$

Step 3. We have $c = -\frac{\phi_2(m)}{\phi_3'(m)} = \frac{1+m}{2+2m}$

We notice that c is $\frac{0}{0}$ form for $m = -1$.

Now c is determined by

$$\frac{c^2}{2} \phi_3''(m) + c \phi_2'(m) + \phi_1(m) = 0.$$

$$\text{or } \frac{c^2}{2} \times 2 + c(-1) + 0 = 0$$

$$\text{or } c^2 - c = 0 \Rightarrow c = 0, 1.$$

Hence the two asymptotes corresponding to
 $m = -1, -1$ are

$$y = -x + 0 \quad \text{and} \quad y = -x + 1$$

$$\text{or } x + y = 0 \quad \text{and} \quad x + y = 1.$$

1.(d)

Evaluate $\int_0^4 \int_{x=y/2}^{x=(y/2)+1} \frac{2x-y}{2} dx dy$

by applying the transformation $u = \frac{2x-y}{2}$, $v = \frac{y}{2}$
and integrating over an appropriate region in the
uv-plane.

Soln: We know that

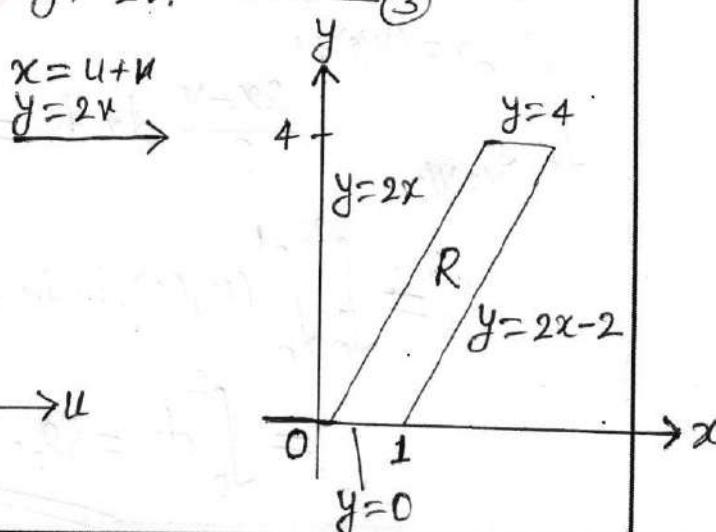
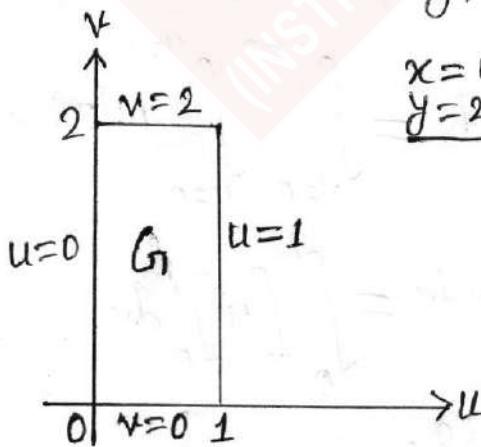
$$\iint_R f(x,y) dx dy = \iint_G f(g(u,v), h(u,v)) |J(u,v)| du dv. \quad (1)$$

$$\text{and given that } u = \frac{2x-y}{2}, v = \frac{y}{2} \quad (2)$$

Now we sketch the region R of integration in
the xy-plane and identify its boundaries.

To apply eqs. (1), we need to find the corresponding
uv-region G and the jacobian of the transformation.
To find them, we first solve eqs. (2) for x and y
in terms of u and v. Routine algebra gives

$$x = u + v, \quad y = 2v. \quad (3)$$



We then find the boundaries of G_1 by substituting these expressions into the equations for the boundaries of R .

xy-equations for the boundary of R	corresponding uv-equations for the boundary of G_1	Simplified uv-equations.
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$$x = y/2 \quad u+v = 2v/2 = v \quad u=0$$

$$x = (y/2) + 1 \quad u+v = (2v/2) + 1 = v+1 \quad u=1$$

$$y = 0 \quad 2v = 0 \quad v=0$$

$$y = 4 \quad 2v = 4 \quad v=2$$

The Jacobian of the transformation is

$$\begin{aligned} J(u, v) &= \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \begin{vmatrix} \frac{\partial}{\partial u}(u+v) & \frac{\partial}{\partial v}(u+v) \\ \frac{\partial}{\partial u}(2v) & \frac{\partial}{\partial v}(2v) \end{vmatrix} \\ &= \begin{vmatrix} 1 & 1 \\ 0 & 2 \end{vmatrix} = 2. \end{aligned}$$

We now have everything we need to apply Eq.①:

$$\begin{aligned} &\int_0^4 \int_{x=y/2}^{x=(y/2)+1} \frac{2x-y}{2} dx dy = \int_{v=0}^2 \int_{u=0}^{u=v} u / |J(u, v)| du dv \\ &= \int_0^2 \int_0^1 (u)(2) du dv = \int_0^2 [u^2]_0^1 dv \\ &= \int_0^2 dv = 2. \end{aligned}$$

1(c) A Square ABCD of diagonal $2a$ is folded along the diagonal AC so that the planes DAC, BAC are at right angles. Find the S.D between DC and AB.

Soln: Let O the centre of the square be taken as the origin and OA, OB and OD be taken as x, y and z-axis respectively.

Then the coordinates of A, B, C

and D are $(a, 0, 0)$, $(0, a, 0)$, $(-a, 0, 0)$

and $(0, 0, a)$ respectively.

Therefore equations of AB are

$$\frac{x-a}{a} = \frac{y-0}{-a} = \frac{z-0}{0} \quad \text{--- (1)}$$

$$\text{Equations of DC are } \frac{x-0}{a} = \frac{y-0}{-a} = \frac{z-a}{a} \quad \text{--- (2)}$$

Now any point on the line DC is $(0, 0, a)$ and the equation of the plane through the line AB and

parallel to DC.

i.e., through (1) and parallel to (2) is

$$\begin{vmatrix} x-a & y-0 & z-0 \\ a & -a & 0 \\ a & 0 & a \end{vmatrix} = 0$$

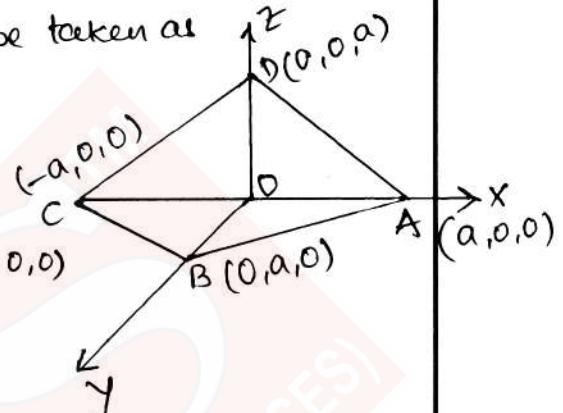
$$\Rightarrow (x-a)(-a)(a) - y(a \cdot a) + z(a \cdot a) = 0$$

$$\Rightarrow (x-a)(-a) - y + z = 0 \Rightarrow x + y - z - a = 0 \quad \text{--- (3)}$$

\Rightarrow length of perpendicular from $(0, 0, a)$ to the plane (3)

$$= \frac{|0+0-a-a|}{\sqrt{1^2+1^2+(-1)^2}}$$

$$= \frac{2a}{\sqrt{3}}$$



2.a(i)

Find the dimension and a basis of the solution space W of the system

$$x + 2y - 4z + 3\gamma - s = 0$$

$$x + 2y - 2z + 2\gamma + s = 0$$

$$2x + 4y - 2z + 3\gamma + 4s = 0$$

Soln: Reduce the system to echelon form:

$$x + 2y - 4z + 3\gamma - s = 0$$

$$2z - \gamma + 2s = 0$$

$$6z - 3\gamma + 6s = 0$$

and then $x + 2y - 4z + 3\gamma - s = 0$
 $2z - \gamma + 2s = 0$

These are five unknowns and two (nonzero) equations in echelon form.

Hence there are $5-2=3$ free variables. y, γ and s . Thus $\dim W=3$.

Set (i) $y=1, \gamma=0, s=0$ to obtain the solution

$$v_1 = (-2, 1, 0, 0, 0)$$

(ii) $y=0, \gamma=2, s=0$ to obtain the solution

$$v_2 = (-2, 0, 1, 2, 0)$$

(iii) $y=0, \gamma=0, s=1$ to obtain the solution

$$v_3 = (-3, 0, -1, 0, 1)$$

The set $\{v_1, v_2, v_3\}$ is a basis of the solution space W .

2.b(i) → For what value of a does $\frac{\sin 2x + a \sin x}{x^3}$ tends to a finite limit as $x \rightarrow 0$?

$$\text{Soln: } \lim_{x \rightarrow 0} \frac{\sin 2x + a \sin x}{x^3} \left(\frac{0}{0} \right)$$

$$= \lim_{x \rightarrow 0} \frac{2 \cos 2x + a \cos x}{3x^2} \left(\frac{2+a}{0} \right)$$

To get the finite limit, we take

$$2+a = 0 \Rightarrow a = -2.$$

$$\text{Thus } \lim_{x \rightarrow 0} \frac{2 \cos 2x + a \cos x}{3x^2}$$

$$= \lim_{x \rightarrow 0} \frac{2 \cos 2x - 2 \cos x}{3x^2} \left(\frac{0}{0} \right)$$

$$= \lim_{x \rightarrow 0} \frac{-4 \sin 2x + 2 \sin x}{6x} \left(\frac{0}{0} \right)$$

$$= \lim_{x \rightarrow 0} \frac{-8 \cos 2x + 2 \cos x}{6} = -1.$$

Hence for $a = -2$, $\lim_{x \rightarrow 0} \frac{\sin 2x + a \sin x}{x^3} = -1.$

2. b(ii), If $I_{p,q} = \int_0^{\pi/2} \sin^p x \cos^q x dx$, Prove that

$$I_{p,q} = \frac{p-1}{p+q} \cdot \frac{p-3}{p+q-2} \cdot \frac{p-5}{p+q-4} \cdots \frac{2}{3+q} \cdot \frac{1}{1+q},$$

Where p is an odd positive integer and q is a positive integer, even or odd.

Soln: $\int_0^{\pi/2} \sin^p x \cos^q x dx = \frac{p-1}{p+q} \int_0^{\pi/2} \sin^{p-2} x \cos^q x dx$

$$\therefore I_{p,q} = \frac{p-1}{p+q} I_{p-2,q}.$$

Replacing p by p-2, p-4, ..., 3; we obtain

$$I_{p-2,q} = \frac{p-3}{p+q-2} I_{p-4,q}$$

$$I_{p-4,q} = \frac{p-5}{p+q-4} I_{p-6,q}$$

⋮

$$I_{3,q} = \frac{2}{3+q} I_{1,q}; \text{ if } p \text{ is odd.}$$

NOW $I_{1,q} = \int_0^{\pi/2} \sin x \cos^q x dx = - \left[\frac{\cos^{q+1} x}{q+1} \right]_0^{\pi/2} = \frac{1}{q+1}.$

Hence from these relations, we obtain

$$I_{p,q} = \frac{p-1}{p+q} \cdot \frac{p-3}{p+q-2} \cdot \frac{p-5}{p+q-4} \cdots \frac{2}{3+q} \cdot \frac{1}{1+q}.$$

2.(c)(1) find the distance of the point $(1, -2, 3)$ from the plane $x - y + z = 5$ measured parallel to the line

$$\frac{x}{2} = \frac{4}{3} = -\frac{2}{6}$$

Soln: The given line is $\frac{x}{2} = \frac{y}{3} = \frac{z}{6}$ → ①
 Its direction ratios are proportional to

Dividing each by $\sqrt{4q+9+36} = \sqrt{4q+45} = 7$, the actual d.c.'s of the line ① are $\left(\frac{1}{2}, -\frac{2}{3}, \frac{3}{2} \right)$.

the actual d.c.'s of the line ① are

$$\frac{2}{7}, \frac{3}{7}, -\frac{6}{7},$$

(iii) equations of the line through

$(1, -2, 3)$ and parallel to ① are

$$\frac{x-1}{y/x} = \frac{y+2}{3/x} = \frac{z-3}{-6/x} = r \text{ (say)} \quad \text{--- (2)}$$

Now any point on the line (2)

$$\textcircled{Q} \left(\frac{2}{7}x+1, \frac{3}{7}x-2, -\frac{6}{7}x+3 \right) \leftarrow \textcircled{3}$$

If this lies on the plane $x-y+z=5$.

$$\text{then } \frac{2}{7}x+1 - \frac{3}{7}x+2 - \frac{6}{7}x+3 = 5$$

$$\Rightarrow -x + 6 = 5$$

Substituting $\Rightarrow r = 1$ the value of r in ① , the point

is $Q\left(\frac{9}{7}, -\frac{11}{7}, \frac{15}{7}\right)$ and therefore the required distance of this point from the given

$$\text{point } (1, -2, 3) = \sqrt{\left(\frac{9}{4}-1\right)^2 + \left(-\frac{11}{4}+2\right)^2 + \left(\frac{15}{4}-3\right)^2}$$

$$= \sqrt{\frac{4}{49} + \frac{9}{49} + \frac{36}{49}} = 1$$

x

2.(c)(ii)

Prove that the plane $x+2y-z=4$ cuts the sphere $x^2+y^2+z^2-x+2z-2=0$ in a circle of radius unity and find the equations of the sphere which has this circle for one of its great circles.

Soln: The centre of the given sphere is $(\frac{1}{2}, 0, -1)$

and its radius $= \sqrt{(\frac{1}{2})^2 + (0)^2 + (-\frac{1}{2})^2 - (-1)} = \sqrt{\frac{5}{2}} = R$ (say)

Also length of perpendicular from $(\frac{1}{2}, 0, -1)$ to

$$x+2y-z-4=0 \text{ is } \frac{\frac{1}{2}+2(0)-(-\frac{1}{2})-4}{\sqrt{x^2+y^2+z^2}} = \frac{3}{\sqrt{6}} = p \text{ (say)}$$

$$\text{Then radius of the circle} = \sqrt{R^2-p^2} = \sqrt{\frac{5}{2}-\frac{9}{6}} = 1$$

The equations of the circle are

$$x^2+y^2+z^2-x+2z-2=0, \quad x+2y-z-4=0$$

\therefore The equation of a sphere through this circle

$$\text{is } (x^2+y^2+z^2-x+2z-2)+\lambda(x+2y-z-4)=0$$

$$\Rightarrow x^2+y^2+z^2+(\lambda-1)x+2\lambda y+(1-\lambda)z-(2+4\lambda)=0 \quad \textcircled{1}$$

Its centre is $[-\frac{1}{2}(\lambda-1), -\lambda, -\frac{1}{2}(1-\lambda)]$.

If this circle is a great circle of the sphere $\textcircled{1}$, then the centre of $\textcircled{1}$ should lie on the plane of the circle. i.e. the plane $x+2y-z-4=0$

$$-\frac{1}{2}(\lambda-1)+2(-\lambda)+\frac{1}{2}(1-\lambda)-4=0$$

$$\Rightarrow -3\lambda-2=0$$

$$\Rightarrow \lambda=-\frac{2}{3}$$

\therefore from $\textcircled{1}$, the equation of the required

$$\text{sphere is } x^2+y^2+z^2-2x-2y+2z+\frac{25}{9}=0$$

3.a(i)

Find a basis for the column space of the matrix

$$B = \begin{bmatrix} 1 & 0 & -3 & 5 & 0 \\ 0 & 1 & 2 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Soln: Denote the columns of B by b_1, b_2, b_3, b_4, b_5 and note that $b_3 = -3b_1 + 2b_2$ and $b_4 = 5b_1 - b_2$. The fact that b_3 and b_4 are combinations of the pivot columns means that any combination of b_1, b_2, \dots, b_5 is actually just a combination of b_1, b_2 and b_5 . Indeed, if v is any vector in $\text{col } B$, say,

$$v = c_1 b_1 + c_2 b_2 + c_3 b_3 + c_4 b_4 + c_5 b_5$$

then, substituting for b_3 and b_4 , we can write v in the form of

$$v = c_1 b_1 + c_2 b_2 + c_3(-3b_1 + 2b_2) + c_4(5b_1 - b_2) + c_5 b_5$$

which is a linear combination of b_1, b_2 and b_5 . So $\{b_1, b_2, b_5\}$ spans $\text{col } B$.

Also, b_1, b_2 and b_5 are linearly independent, because they are columns from an identity matrix. So the pivot columns of B form a basis for $\text{col } B$.

The matrix B is in reduced echelon form. To handle a general matrix A , recall that linear dependence relations among the columns of A can be expressed in the form $AX=0$ for some x . (If some columns are not involved for a particular

dependence relation, then the corresponding entries in x are zero.)

When A is now reduced to echelon form B , the columns are drastically changed, but the equations $AX=0$ and $BX=0$ have the same set of solutions. That is, the columns of A have exactly the same linear dependence relationships as the columns of B .

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3.b(i)

State Euler's theorem for homogeneous functions and verify it for the function $z = \sin u$, where $u = \sin^{-1}\left(\frac{\sqrt{x^2+y^2}}{x+y}\right)$.

$$\text{Sol}: \text{We have } z = \sin u = \frac{\sqrt{x^2+y^2}}{x+y} = \frac{\sqrt{1+y^2/x^2}}{(1+y/x)}.$$

Thus z is a homogeneous function of x and y of degree 0. We shall verify that $x \frac{\partial z}{\partial x} + y \frac{\partial z}{\partial y} = 0$.

$$\text{We have } \frac{\partial z}{\partial x} = \frac{(x+y) \frac{x}{\sqrt{x^2+y^2}} - \sqrt{x^2+y^2}}{(x+y)^2},$$

$$\frac{\partial z}{\partial y} = \frac{(x+y) \frac{y}{\sqrt{x^2+y^2}} - \sqrt{x^2+y^2}}{(x+y)^2}.$$

$$\therefore x \frac{\partial z}{\partial x} + y \frac{\partial z}{\partial y} = \frac{(x+y)\left(\frac{x+y}{\sqrt{x^2+y^2}}\right) - (x+y)\sqrt{x^2+y^2}}{(x+y)^2} = 0.$$

3.b(ii)

The plane $x+y+z=1$ cuts the cylinder $x^2+y^2=1$ in an ellipse. Find the points on the ellipse that lie closest to and farthest from the origin.

Solⁿ: We find the extreme values of

$$f(x, y, z) = x^2 + y^2 + z^2$$

(the square of the distance from (x, y, z) to the origin)
Subject to the constraints.

$$g_1(x, y, z) = x^2 + y^2 - 1 = 0 \quad \text{--- (1)}$$

$$g_2(x, y, z) = x + y + z - 1 = 0. \quad \text{--- (2)}$$

We know that gradient equation

$$\nabla f = \lambda \nabla g_1 + \mu \nabla g_2,$$

$$\text{where } g_1(x, y, z) = 0, g_2(x, y, z) = 0.$$

then gives

$$2xi + 2yj + 2zk = \lambda(2xi + 2yj) + \mu(i + j + k).$$

$$2xi + 2yj + 2zk = (2\lambda x + \mu)i + (2\lambda y + \mu)j + \mu k$$

$$\text{or } 2x = 2\lambda x + \mu, 2y = 2\lambda y + \mu, 2z = \mu \quad \text{--- (3)}$$

The scalar equations in (3) yield

$$2x = 2\lambda x + 2z \Rightarrow (1-\lambda)x = z, \quad \left. \begin{array}{l} \\ \end{array} \right\} \quad \text{--- (4)}$$

$$2y = 2\lambda y + 2z \Rightarrow (1-\lambda)y = z, \quad \left. \begin{array}{l} \\ \end{array} \right\}$$

Equations (4) are satisfied simultaneously if either $\lambda = 1$ and $z = 0$ or $\lambda \neq 1$ and $x = y = \frac{z}{1-\lambda}$.

If $z = 0$, then solving eqs. (1) and (2) simultaneously

to find the corresponding points on the ellipse gives the two points $(1, 0, 0)$ and $(0, 1, 0)$.

If $x = y$, then eqs. ① and ② give

$$x^2 + x^2 - 1 = 0 \Rightarrow 2x^2 = 1 \Rightarrow x = \pm \frac{\sqrt{2}}{2}$$

$$x + x + z - 1 = 0 \Rightarrow z = 1 - 2x \Rightarrow z = 1 \pm \sqrt{2}.$$

The corresponding points on the ellipse are

$$P_1 = \left(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 1 - \sqrt{2} \right) \text{ and}$$

$$P_2 = \left(-\frac{\sqrt{2}}{2}, -\frac{\sqrt{2}}{2}, 1 + \sqrt{2} \right).$$

But here we need to be careful. While P_1 and P_2 both give local maxima of f on the ellipse, P_2 is farther from the origin than P_1 .

The points on the ellipse closest to the origin are $(1, 0, 0)$ and $(0, 1, 0)$. The point on the ellipse farthest from the origin is P_2 .

3.(c) A tangent plane to the ellipsoid $x^2/a^2 + y^2/b^2 + z^2/c^2 = 1$ meets the coordinate axes in the points P, Q and R. Find the locus of the centroid of the triangle PQR.

Sol: Any tangent plane to the given ellipsoid

$$lx + my + nz = \sqrt{a^2l^2 + b^2m^2 + c^2n^2} \quad \text{--- (1)}$$

This plane meets the x-axis at P, so the coordinates

$$P \text{ are } \left[\left(\frac{1}{l} \right) \sqrt{a^2l^2 + b^2m^2 + c^2n^2}, 0, 0 \right] \text{ Putting}$$

$$y=0=z \text{ in (1).}$$

Similarly Q and R are

$$\left[0, \frac{1}{m} \sqrt{a^2l^2 + b^2m^2 + c^2n^2}, 0 \right] \text{ and } \left[0, 0, \frac{1}{n} \sqrt{a^2l^2 + b^2m^2 + c^2n^2} \right]$$

\therefore If (x_1, y_1, z_1) be the centroid of ΔPQR , then

$$x_1 = \frac{1}{3} \left[\frac{1}{l} \sqrt{a^2l^2 + b^2m^2 + c^2n^2} + 0 + 0 \right]$$

$$= \frac{1}{3l} \sqrt{a^2l^2 + b^2m^2 + c^2n^2}$$

Similarly,

$$y_1 = \frac{1}{3m} \sqrt{a^2l^2 + b^2m^2 + c^2n^2}$$

$$\text{and } z_1 = \frac{1}{3n} \sqrt{a^2l^2 + b^2m^2 + c^2n^2}.$$

$$\therefore (3lx_1)^2 = a^2l^2 + b^2m^2 + c^2n^2$$

$$\text{or } 9l^2x_1^2 = a^2l^2 + b^2m^2 + c^2n^2$$

$$\text{or } q \frac{a^2 l^2}{(a^2 l^2 + b^2 m^2 + c^2 n^2)} = a^2/x_1^2$$

Similarly,

$$q \frac{b^2 m^2}{(a^2 l^2 + b^2 m^2 + c^2 n^2)} = b^2/y_1^2$$

$$q \frac{c^2 n^2}{(a^2 l^2 + b^2 m^2 + c^2 n^2)} = c^2/z_1^2$$

Adding these we get

$$\frac{q(a^2 l^2 + b^2 m^2 + c^2 n^2)}{(a^2 l^2 + b^2 m^2 + c^2 n^2)} = (a^2/x_1^2) + (b^2/y_1^2) + (c^2/z_1^2)$$

$$\text{or } q = (a^2/x_1^2) + (b^2/y_1^2) + (c^2/z_1^2)$$

\therefore The required locus of (x_1, y_1, z_1) is

$$(a^2/x_1^2) + (b^2/y_1^2) + (c^2/z_1^2) = \underline{\underline{q}}.$$

4.(a) Let $A = \begin{pmatrix} 1 & 2 & -3 \\ 2 & 5 & -4 \\ -3 & -4 & 8 \end{pmatrix}$, a symmetric matrix. Find the non-singular matrix P such that P^TAP is diagonal and find P^TAP .

Solⁿ: first form the block matrix (A, I) :

$$(A, I) = \left(\begin{array}{ccc|ccc} 1 & 2 & -3 & 1 & 0 & 0 \\ 2 & 5 & -4 & 0 & 1 & 0 \\ -3 & -4 & 8 & 0 & 0 & 1 \end{array} \right)$$

Apply the operations $R_2 \rightarrow -2R_1 + R_2$ and $R_3 \rightarrow 3R_1 + R_3$ to (A, I) and then the corresponding operations $C_2 \rightarrow -2C_1 + C_2$ and $C_3 \rightarrow 3C_1 + C_3$ to A to obtain

$$\left(\begin{array}{ccc|ccc} 1 & 2 & -3 & 1 & 0 & 0 \\ 0 & 1 & 2 & -2 & 1 & 0 \\ 0 & 2 & -1 & 3 & 0 & 1 \end{array} \right)$$

and then $\left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 2 & -2 & 1 & 0 \\ 0 & 2 & -1 & 3 & 0 & 1 \end{array} \right)$

Next apply the operation $R_3 \rightarrow -2R_2 + R_3$ and then the corresponding operation $C_3 \rightarrow -2C_2 + C_3$ to obtain

$$\left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 2 & -2 & 1 & 0 \\ 0 & 0 & -5 & 7 & -2 & 1 \end{array} \right)$$

and then $\left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & -2 & 1 & 0 \\ 0 & 0 & -5 & 7 & -2 & 1 \end{array} \right)$

Now A has been diagonalized. set

$$P = \begin{pmatrix} 1 & -2 & 7 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{pmatrix}$$

and then $P^T AP = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -5 \end{pmatrix}$

$$\xrightarrow{4.(b)} I = \iiint \frac{dx dy dz}{\sqrt{x^2 + z^2 + (z-1)^2}} = \frac{\pi}{6}.$$

Where the integration is taken over the region
 $4(x^2 + y^2 + z^2) \leq 1$.

Soln: With change of variables to spherical coordinates

$$x = r \sin \theta \cos \phi, y = r \sin \theta \sin \phi, z = r \cos \theta$$

$$\text{We have } \frac{\partial(x, y, z)}{\partial(r, \theta, \phi)} = r^2 \sin \theta$$

Where $0 \leq \theta \leq \pi$, $0 \leq \phi \leq 2\pi$, and $0 \leq r \leq 1/2$.

$$\begin{aligned} \text{So that } I &= \int_{r=0}^{1/2} \int_{\theta=0}^{\pi} \int_{\phi=0}^{2\pi} \frac{r^2 \sin \theta d\phi d\theta}{\sqrt{r^2 - 2r \cos \theta + 1}} \\ &= 2\pi \int_{r=0}^{1/2} (\gamma \sqrt{r^2 - 2r \cos \theta + 1})_{\theta=0}^{\pi} dr \\ &= 2\pi \int_0^{1/2} \{r(r+1) - r(1-r)\} dr \\ &= 2\pi \frac{1}{3} \cdot \frac{2}{2^3} \\ &= \frac{\pi}{6}. \end{aligned}$$

=====

4.(c) →

Prove that the equations of the generating lines, through the point (θ, ϕ) on the hyperboloid of one sheet are

$$\frac{x - a \cos \theta \sec \phi}{a \sin(\theta \pm \phi)} = \frac{y - b \sin \theta \sec \phi}{-b \cos(\theta \pm \phi)} = \frac{z - c \tan \phi}{\pm c}$$

Soln: The point $P(\theta, \phi)$ on the hyperboloid of one sheet $\left(\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2}\right) = 1$ ————— (1)

is $(a \cos \theta \sec \phi, b \sin \theta \sec \phi, c \tan \phi)$.

Now we know that the generating lines through P are the lines of intersection of the hyperboloid (1) with the tangent plane at P whose equation is

$$\left(\frac{x}{a}\right) \cos \theta \sec \phi + \left(\frac{y}{b}\right) \sin \theta \sec \phi - \left(\frac{z}{c}\right) \tan \phi = 1. \quad (2)$$

This plane (2) meets the plane $z=0$ in the line given by

$$\left(\frac{x}{a}\right) \cos \theta \sec \phi + \left(\frac{y}{b}\right) \sin \theta \sec \phi = 1, z=0$$

$$\text{or } \left(\frac{x}{a}\right) \cos \theta + \left(\frac{y}{b}\right) \sin \theta = \cos \phi, z=0 \quad (3)$$

Also the section of the hyperboloid (1) by the plane $z=0$ is

$$\left(\frac{x^2}{a^2}\right) + \left(\frac{y^2}{b^2}\right) = 1, z=0 \quad (4)$$

Let the line (3) meet the section (4) of the hyperboloid (1) in the points $A(a \cos \alpha, b \sin \alpha, 0)$ and $B(a \cos \beta, b \sin \beta, 0)$. Then the equation of AB is

$$\frac{x}{a} \cos\left(\frac{\alpha+\beta}{2}\right) + \frac{y}{b} \sin\left(\frac{\alpha+\beta}{2}\right) = \cos\left(\frac{\alpha-\beta}{2}\right), z=0. \quad (5)$$

composing ③ and ⑤, we get

$$\theta = \frac{\alpha + \beta}{2} \text{ and } \phi = \frac{\alpha - \beta}{2}$$

Adding and subtracting, these, we get

$$\alpha = \theta + \phi \text{ and } \beta = \theta - \phi \quad \text{--- ⑥}$$

Hence the two generators through P are AP and BP.
Now the direction ratios of AP are

$$a(\cos\alpha - \cos\theta \sec\phi), b(\sin\alpha - \sin\theta \sec\phi), c(0 - \tan\phi).$$

$$\text{or } a\left[\frac{\cos(\theta + \phi)\cos\phi - \cos\theta}{\cos\phi}\right], b\left[\frac{\sin(\theta + \phi)\cos\phi - \sin\theta}{\cos\phi}\right]$$

$$\frac{-c \sin \phi}{\cos \phi} \quad \text{from ⑥}$$

$$\text{or } a\left[\frac{\cos\theta \cos^2\phi - \sin\theta \sin\phi \cos\phi - \cos\theta}{\cos\phi}\right],$$

$$b\left[\frac{\sin\theta \cos^2\phi + \cos\theta \sin\phi \cos\phi - \sin\theta}{\cos\phi}\right], \frac{-c \sin \phi}{\cos \phi}$$

$$\text{or } a\left[\frac{-\cos\theta(1-\cos^2\phi) - \sin\theta \sin\phi \cos\phi}{\sin\phi}\right],$$

$$b\left[\frac{\cos\theta \sin\phi \cos\phi - \sin\theta(1-\cos^2\phi)}{\sin\phi}\right], -c,$$

multiplying each term by $(\cos\phi)/\sin\phi$.

$$\text{or } a(-\cos\theta \sin\phi - \sin\theta \cos\phi), b(\cos\theta \cos\phi - \sin\theta \sin\phi), -c$$

$$\text{or } a \sin(\theta + \phi), -b \cos(\theta + \phi), c,$$

Where $\theta + \phi$ is constant from ⑥ for all points

on the generator AP, whose equations therefore are

$$\frac{x - a \cos \theta \sec \phi}{a \sin(\theta + \phi)} = \frac{y - b \sin \theta \sec \phi}{-b \cos(\theta + \phi)} = \frac{z - c \tan \phi}{c} \quad (7)$$

Similarly we can show that the equations of the generator BP are

$$\frac{x - a \cos \theta \sec \phi}{a \sin(\theta - \phi)} = \frac{y - b \sin \theta \sec \phi}{-b \cos(\theta - \phi)} = \frac{z - c \tan \phi}{c}, \quad (8)$$

where $\theta - \phi$ is constant from (6) for all points on the generator.

Combining (7) and (8) we get the required result.



5.(a) Find the orthogonal trajectories of $r = a(1 + \cos n\theta)$.

Sol: Given family is $r = a(1 + \cos n\theta)$, where a is parameter. ①

Taking logarithm of both sides,

$$\log r = \log a + \log(1 + \cos n\theta) \quad \text{--- ②}$$

Differentiating ② w.r.t θ

$$\frac{1}{r} \left(\frac{dr}{d\theta} \right) = - (n \sin n\theta) / (1 + \cos n\theta) \quad \text{--- ③}$$

which is differential equation of the family of curves ①. Replacing $dr/d\theta$ by $-r^2(d\theta/dr)$ in ③ the differential equation of the required trajectories is

$$\frac{1}{r} \left(-r^2 \frac{d\theta}{dr} \right) = - \frac{n \sin n\theta}{1 + \cos n\theta}$$

$$\Rightarrow \frac{n dr}{r} = \frac{1 + \cos n\theta}{\sin n\theta} d\theta$$

$$\Rightarrow \frac{n dr}{r} = \frac{2 \cos^2 \left(\frac{n\theta}{2} \right) d\theta}{2 \sin \left(\frac{n\theta}{2} \right) \cos \left(\frac{n\theta}{2} \right)}$$

$$\Rightarrow n \frac{dr}{r} = \cot \left(\frac{n\theta}{2} \right) d\theta.$$

Integrating, $n \log r = \frac{2}{n} \times \log \sin \left(\frac{n\theta}{2} \right) + \frac{1}{n} \log C$, C being arbitrary constant.

$$n \log r = \log \sin^2 \left(\frac{n\theta}{2} \right) + \log C$$

$$\Rightarrow r^{n^2} = C \sin^2 \left(\frac{n\theta}{2} \right)$$

$$\Rightarrow r^{n^2} = \frac{C}{2} (1 - \cos n\theta)$$

$$\Rightarrow r^{n^2} = b(1 - \cos n\theta), \text{ taking } b = \frac{C}{2}$$

which is the equation of required orthogonal trajectories with b as parameter.

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→ 5.(b)(i)

$$\text{If } L^{-1} \left\{ \frac{e^{-1/p}}{p^{1/2}} \right\} = \frac{\cos 2\sqrt{t}}{\sqrt{\pi t}}, \text{ find } L^{-1} \left\{ \frac{e^{-ap}}{p^{1/2}} \right\}$$

where $a > 0$.

Solution:

$$(i) \text{ Since } L^{-1} \left\{ \frac{e^{-1/p}}{p^{1/2}} \right\} = \frac{\cos 2\sqrt{t}}{\sqrt{\pi t}}$$

$$\therefore L^{-1} \left\{ \frac{e^{-1/pk}}{(pk)^{1/2}} \right\} = \frac{1}{k} \cdot \frac{\cos 2\sqrt{(t/k)}}{\sqrt{\pi t}/k}$$

$$\Rightarrow L^{-1} \left\{ \frac{e^{-1/pk}}{p^{1/2}} \right\} = \frac{\cos 2\sqrt{(t/k)}}{\sqrt{\pi t}}$$

Taking $k = 1/a$, we have,

$$L^{-1} \left\{ \frac{e^{-a/p}}{p^{1/2}} \right\} = \frac{\cos 2\sqrt{at}}{\sqrt{\pi t}} \quad \text{--- (1)}$$

5 b(ii) → Find $L^{-1} \left\{ \frac{e^{4-3p}}{(p+4)^{5/2}} \right\}$

Solⁿ: We have $L^{-1} \left\{ \frac{1}{(p+4)^{5/2}} \right\} = e^{-4t} L^{-1} \left\{ \frac{1}{p^{5/2}} \right\}$
 $= e^{-4t} \frac{t^{5/2-1}}{\Gamma(5/2)} = \frac{4t^{3/2} e^{-4t}}{3\sqrt{\pi}}$.

$$\therefore L^{-1} \left\{ \frac{e^{4-3p}}{(p+4)^{5/2}} \right\} = e^4 L^{-1} \left\{ \frac{e^{-3p}}{(p+4)^{5/2}} \right\}$$

$$= \begin{cases} e^4 \frac{4}{3\sqrt{\pi}} (t-3)^{3/2} e^{-4(t-3)}, & t > 3 \\ , & t < 3 \end{cases}$$

$$= \begin{cases} \frac{4}{3\sqrt{\pi}} (t-3)^{3/2} e^{-4(t-3)}, & t > 3 \\ , & t < 3 \end{cases}$$

$$= \frac{4}{3\sqrt{\pi}} (t-3)^{3/2} e^{-4(t-3)} H(t-3).$$

in terms of the Heaviside unit step function.



5-C

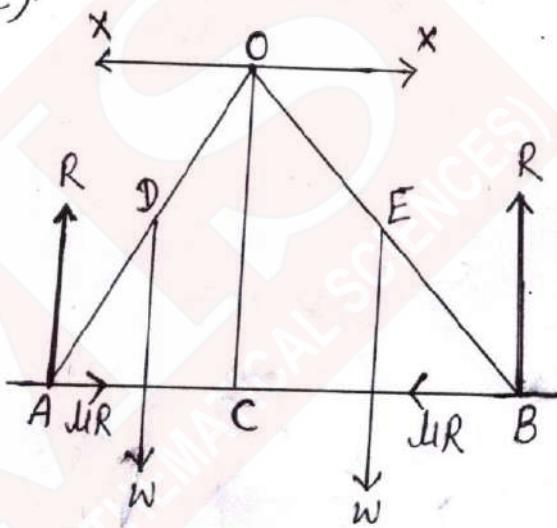
Two equal uniform rods AB, BC, each of weight W , lean against each other and rest in vertical plane with ends A and B on a rough horizontal plane. The angle ACB is 2α and the co-efficient of friction μ . Find what weight placed at C would cause them to slip.

Solⁿ: Let w be the weight placed at C. (w acts vertically downwards at C).

Resolving vertically for the whole system

$$2W + w = 2R \quad \text{--- ①}$$

Taking moments about C for the equilibrium of rod AC only, we have



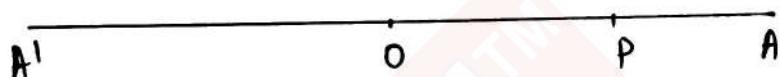
$$\begin{aligned}
 & W \cdot CD \sin \alpha + \mu R \cdot AC \cos \alpha = R \cdot AC \sin \alpha \\
 \Rightarrow & W \cdot CD \sin \alpha + \mu R \cdot 2CD \cos \alpha = R \cdot 2CD \sin \alpha \\
 \Rightarrow & W \sin \alpha + 2\mu R \cos \alpha = 2R \sin \alpha \\
 \Rightarrow & W \sin \alpha + \mu(2W + w) \cos \alpha = (2W + w) \sin \alpha \quad [\text{by using ①}] \\
 \Rightarrow & \mu(2W + w) \cos \alpha = (w + w) \sin \alpha \\
 \Rightarrow & \mu(2W + w) = (w + w) \tan \alpha \\
 \Rightarrow & 2\mu W - W \tan \alpha = w(\tan \alpha - \mu) \\
 \therefore & w = \frac{W(2\mu - \tan \alpha)}{\tan \alpha - \mu}.
 \end{aligned}$$

Q 5(d)

A particle is performing a simple harmonic motion of period T about a centre O and it passes through a point P where $OP = b$ with velocity v in the direction OP; Prove that the time which elapses before it returns to P is $\frac{T}{\pi} \tan^{-1} \left(\frac{vT}{2\pi b} \right)$.

Sol'n

Let the eqn of the S.H.M with centre O as origin be $\frac{d^2x}{dt^2} = -\mu x$



The time period $T = 2\pi / \sqrt{\mu}$, let amplitude be a . Then $(dx/dt)^2 = \mu(a^2 - x^2)$ (1)

When particle passes through P its Velocity is given to be v in the direction OP. Also $OP = b$. So putting $x = b$ and $dx/dt = v$ in (1)

$$\text{We get } v^2 = \mu(a^2 - b^2).$$

In S.H.M the time from P to A is equal to the time from A to P.

\therefore The required time = 2 . Time from A to P.

Now Motion from A to P, we have

$$\frac{dx}{dt} = -\sqrt{\mu} \sqrt{a^2 - x^2} \Rightarrow dt = -\frac{1}{\sqrt{\mu}} \frac{dx}{\sqrt{a^2 - x^2}}$$

Let t_1 be the time from A to P. Then at A, $t=0, x=a$ and at P, $t=t_1$ and $x=b$, Therefore integrating (3)

$$\text{We get } \int_0^{t_1} dt = \frac{1}{\sqrt{\mu}} \int_a^b \frac{-dx}{\sqrt{a^2 - x^2}} \Rightarrow t_1 = \frac{1}{\sqrt{\mu}} \left[\cos^{-1} \frac{x}{a} \right]_a^b$$

$$\text{Hence required time } = \alpha t_1 = \frac{2}{\sqrt{\mu}} \cos^{-1} \left(\frac{b}{a} \right)$$

$$= \frac{2}{\sqrt{\mu}} \tan^{-1} \left\{ \frac{\sqrt{(a^2 - b^2)}}{b} \right\} = \frac{2}{\sqrt{\mu}} \tan^{-1} \left(\frac{v}{b\sqrt{\mu}} \right) \quad \left[\text{from (2)} \right]$$

$$= \frac{2}{2\pi/T} \tan^{-1} \left\{ \frac{V}{b(2\pi/T)} \right\} \quad \left[\because T = 2\pi / \sqrt{\mu} \text{ so that } \sqrt{\mu} = 2\pi / T \right]$$

$$= \frac{T}{\pi} \tan^{-1} \left(\frac{vT}{2\pi b} \right)$$

5.(e) If $f = y\mathbf{i} + (x - 2xz)\mathbf{j} - xy\mathbf{k}$, evaluate $\int_S (\nabla \times f) \cdot n \, dS$, where S is the surface of the sphere $x^2 + y^2 + z^2 = a^2$ above the xy -plane.

Solⁿ: Let $F = \nabla f = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y & x - 2xz & -xy \end{vmatrix}$

$$= xi + yj - 2zk$$

$\phi = c$ is given by $x^2 + y^2 + z^2 = a^2$

grad ϕ is along the normal and

$$\text{grad } \phi = \sum i \frac{\partial \phi}{\partial x} = 2xi + 2yj + 2zk$$

$$\therefore n = \text{a unit normal} = \frac{2xi + 2yj + 2zk}{\sqrt{(4x^2 + 4y^2 + 4z^2)}}$$

$$= \frac{xi + yj + zk}{a}$$

$$\therefore F \cdot n = (xi + yj - 2zk) \cdot \frac{(xi + yj + zk)}{a}$$

$$= \frac{x^2 + y^2 + 2z^2}{a}$$

Also, we know that

$$\int_S F \cdot n \, dS = \iint_{S_3} F \cdot n \frac{dx dy}{n \cdot k}$$

where S_3 is the projection of S on xy -plane.

$$n \cdot k = \frac{xi + yj + zk}{a} \cdot k = \frac{z}{a} = \frac{\sqrt(a^2 - x^2 - y^2)}{a}$$

$$\text{Also } F \cdot n = \frac{x^2 + y^2 - 2z^2}{a} = \frac{x^2 + y^2 - 2(a^2 - x^2 - y^2)}{a}$$

$$= \frac{3(x^2 + y^2) - 2a^2}{a}$$

$$\therefore \int_S F \cdot n dS = \iint_{S_3} \frac{3(x^2 + y^2) - 2a^2}{a} \cdot \frac{dx dy}{\sqrt{a^2 - x^2 - y^2}} a \quad \text{①}$$

Now, S_3 is the projection of $x^2 + y^2 + z^2 = a^2$ in the xy -plane and is given by

$$x^2 + y^2 = a^2.$$

In order to integrate ① put $x = r \cos \theta, y = r \sin \theta$.

$\therefore dx dy = r d\theta dr$ and limits of θ are from 0 to 2π and that of r from 0 to a .

$$\therefore \int_S F \cdot n dS = \int_0^{2\pi} \int_0^a \frac{3r^2 - 2a^2}{\sqrt{a^2 - r^2}} r d\theta dr$$

$$= 2\pi \int_0^a \frac{3r^2 - 2a^2}{\sqrt{a^2 - r^2}} r dr.$$

$$\text{put } a^2 - r^2 = t, \quad \therefore -2r dr = 2t dt$$

$$\therefore \int_S F \cdot n dS = 2\pi \int_0^a \frac{3(a^2 - t^2) - 2a^2}{t} (-t) dt$$

$$= 2\pi \int_0^a (a^2 - 3t^2) dt$$

$$= 2\pi (a^3 - a^3) = 0.$$

6.a(i) Solve $y(1+xy)dx + x(1-xy)dy = 0$.

Solⁿ: Given $(1+xy)ydx + (1-xy)x dy = 0$. —①

Comparing ① with $Mdx + Ndy = 0$,

$$M = (1+xy)y \text{ and } N = (1-xy)x,$$

Showing that ① is of the form

$$f_1(xy)ydx + f_2(xy)x dy = 0.$$

$$\text{Again, } Mx - Ny = xy(1+xy) - xy(1-xy) = 2x^2y^2 \neq 0.$$

$$\text{Showing that P.F. of ①} = \frac{1}{Mx - Ny} = \frac{1}{2x^2y^2}.$$

on multiplying ① by $1/(2x^2y^2)$, we have

$$\frac{1}{2}\left(\frac{1}{x^2y} + \frac{1}{x}\right)dx + \frac{1}{2}\left(\frac{1}{xy^2} - \frac{1}{y}\right)dy = 0, \quad \text{②}$$

which must be exact and so by the usual rule,

solution of ② is

$$\int\left(\frac{1}{2x^2y} + \frac{1}{2x}\right)dx + \int\left(-\frac{1}{2y}\right)dy = \frac{1}{2}\log c$$

[Treating y as constant.]

$$\text{or } \frac{1}{-2xy} + \frac{1}{2}\log x - \frac{1}{2}\log y = \frac{1}{2}\log c$$

$$\text{or } \log(x/y) - \log c = 1/(xy)$$

$$\text{or } \log(x/cy) = 1/(xy)$$

$$\text{or } x = cye^{1/(xy)}$$

(34)

$$b(a)(ii) \rightarrow \text{Solve } (D^4 + D^2 + 1) y = e^{-x/2} \cos\left(\frac{\sqrt{3}}{2}x\right)$$

$$\text{Soln: Given that } (D^4 + D^2 + 1) y = e^{-x/2} \cos\left(\frac{\sqrt{3}}{2}x\right)$$

The auxiliary equation is $D^4 + D^2 + 1 = 0$

$$\Rightarrow (D^2 + 1)^2 - D^2 = 0$$

$$\Rightarrow (D^2 + D + 1)(D^2 - D + 1) = 0$$

$$\Rightarrow D^2 + D + 1 = 0, (\text{or}) D^2 - D + 1 = 0$$

$$\Rightarrow D = \frac{-1 \pm i\sqrt{3}}{2}, \frac{1 \pm i\sqrt{3}}{2}$$

$$\therefore C.F. = e^{-x/2} \left[C_1 \cos\left(\frac{\sqrt{3}}{2}x\right) + C_2 \sin\left(\frac{\sqrt{3}}{2}x\right) \right] \\ + e^{-x/2} \left[C_3 \cos\left(\frac{\sqrt{3}}{2}x\right) + C_4 \sin\left(\frac{\sqrt{3}}{2}x\right) \right]$$

$$P.D. = \frac{1}{D^4 + D^2 + 1} e^{-x/2} \cos\left(\frac{\sqrt{3}}{2}x\right) \\ = e^{-x/2} \frac{1}{(D - \frac{1}{2})^4 + (D + \frac{1}{2})^2 + 1} \cos\left(\frac{\sqrt{3}}{2}x\right) \\ = e^{-x/2} \frac{1}{D^4 - 2D^3 + \frac{5}{2}D^2 - \frac{3}{2}D + \frac{21}{16}} \cos\left(\frac{\sqrt{3}}{2}x\right)$$

$$= e^{-x/2} \frac{1}{(D^2 - \frac{3}{4})(D^2 + 2D + \frac{7}{4})} \cos\left(\frac{\sqrt{3}}{2}x\right) \quad \therefore$$

$$= e^{-x/2} \frac{1}{(D^2 + \frac{3}{4})} \frac{1}{(D^2 - 2D + \frac{7}{4})} \cos\left(\frac{\sqrt{3}}{2}x\right)$$

$$= e^{-x/2} \frac{1}{(D^2 + 3/4)} \frac{1}{(1 - 2D^2)} \cos\left(\frac{\sqrt{3}}{2}x\right)$$

$$= e^{-x/2} \frac{1}{(D^2 + \frac{3}{4})} \frac{1+2i}{(1-4D^2)} \cos\left(\frac{\sqrt{3}}{2}x\right)$$

$$= e^{-x/2} \frac{1}{(D^2 + 3/4)} \frac{1}{4} (1+2i) \cos\left(\frac{\sqrt{3}}{2}x\right)$$

$$= e^{-x/2} \frac{1}{(D^2 + 3/4)} \left(\cos\left(\frac{\sqrt{3}}{2}x\right) - \sqrt{3} \sin\left(\frac{\sqrt{3}}{2}x\right) \right)$$

$$\begin{aligned}
 &= \frac{1}{4} e^{-\sqrt{3}/2} \left[\frac{1}{D^2 + (\frac{\sqrt{3}}{2})^2} \cos \frac{\sqrt{3}}{2} x - \frac{\sqrt{3}}{D^2 + (\frac{\sqrt{3}}{2})^2} \sin \frac{\sqrt{3}}{2} x \right] \quad (35) \\
 &= \frac{1}{4} e^{-\sqrt{3}/2} \left[\frac{x}{2(\sqrt{3}/2)} \sin \frac{\sqrt{3}}{2} x - \frac{\sqrt{3}x}{2(\sqrt{3}/2)} (-\cos \frac{\sqrt{3}}{2} x) \right] \\
 &= \frac{x}{4\sqrt{3}} e^{-\sqrt{3}/2} \left[\sin \frac{\sqrt{3}}{2} x + \sqrt{3} \cos \frac{\sqrt{3}}{2} x \right].
 \end{aligned}$$

$$\therefore y = C.F + P.I$$

$$\begin{aligned}
 &= e^{-\sqrt{3}/2} \left[C_1 \cos \frac{\sqrt{3}}{2} x + C_2 \sin \frac{\sqrt{3}}{2} x \right] \\
 &\quad + e^{-\sqrt{3}/2} \left[C_3 \cos \frac{\sqrt{3}}{2} x + C_4 \sin \frac{\sqrt{3}}{2} x \right] \\
 &\quad + \frac{x}{4\sqrt{3}} e^{-\sqrt{3}/2} \left[\sin \frac{\sqrt{3}}{2} x + \sqrt{3} \cos \frac{\sqrt{3}}{2} x \right]
 \end{aligned}$$

6.(b) →

Solve the differential equation:

$$y'' + (\tan x - 3 \cos x)y' + 2y \cos^2 x = \cos^4 x.$$

Solⁿ: please do yourself.

ANS:

$$y = c_1 e^{\sin x} + c_2 e^{-\sin x} - (5/4) - (3/2)x \sin x - (1/2) x \sin^2 x.$$

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Ques: 6 (c) } Solve $y'' + 3y' + 2y = x + \cos x$ by the
method of variation of parameters.

Solution: Given; $y'' + 3y' + 2y = x + \cos x$ — (1)

Compare (1) with $y'' + P y' + Q y = R$

$$\text{here; } R = x + \cos x$$

$$P = 3, Q = 2$$

consider $y'' + 3y' + 2y = 0$

$$(D^2 + 3D + 2)y = 0 \quad D \equiv \frac{d}{dx} \quad — (3)$$

Its auxillary equation

$$m^2 + 3m + 2 = 0$$

$$(m+1)(m+2) = 0$$

$$m = -1, -2$$

\therefore C.F of (1) = $C_1 e^{-x} + C_2 e^{-2x}$

C_1 & C_2 being arbitrary constants

$$\text{Let; } u = e^{-x} \quad \text{and} \quad v = e^{-2x} \quad — (4)$$

$$\text{Here; } W = \begin{vmatrix} u & v \\ u' & v' \end{vmatrix} = \begin{vmatrix} e^{-x} & e^{-2x} \\ -e^{-x} & -2e^{-2x} \end{vmatrix}$$

$$W = -2e^{-x} \cdot e^{-2x} + e^{-x} \cdot e^{-2x}$$

$$W = -2e^{-3x} + e^{-3x} = -e^{-3x} \neq 0 \quad — (5)$$

Then, P.I of (1) = $uf(x) + vg(x)$, where — (6)

$$f(x) = -\int \frac{vR}{W} dx = -\int \frac{e^{-2x}(x + \cos x)}{(-e^{-3x})} dx$$

$$f(x) = \int e^x (x + \cos x) dx \quad — \text{by (2), (4) \& (5)}$$

$$= \int xe^x dx + \int e^x \cos x dx \\ = xe^x - \int (1 \cdot e^x) dx + \frac{1}{2} x e^x (\cos x + \sin x)$$

$$\left[\because \int e^{ax} \cos bx dx = \left\{ \frac{1}{a^2+b^2} \right\} x e^{ax} (a \cos bx + b \sin bx) \right]$$

$$\text{Thus; } f(x) = xe^x - e^x + \frac{1}{2} e^x (\cos x + \sin x) \quad \text{--- (7)}$$

$$\text{and } g(x) = \int \frac{UR}{W} dx = \int \frac{e^{-x}(x+\cos x)}{(-e^{-3x})} dx$$

$$g(x) = - \int e^{2x} (x+\cos x) dx = - \int xe^{2x} dx - \int e^{2x} \cos x dx$$

$$g(x) = \left[x \cdot \frac{1}{2} \cdot e^{2x} - \int \left(\frac{1}{2} \cdot \frac{1}{2} \right) x e^{2x} dx \right] - \frac{1}{5} e^{2x} (2 \cos x + \sin x)$$

$$\therefore g(x) = -\frac{x}{2} \cdot e^{2x} + \frac{1}{4} e^{2x} - \frac{1}{5} e^{2x} (2 \cos x + \sin x) \quad \text{--- (8)}$$

from (4), (6), (7) and (8), we have

$$\text{P.I of (1)} = e^{-x} \{ xe^x - e^x + \frac{1}{2} e^x (\cos x + \sin x) \}$$

$$+ e^{-2x} \{ -\left(\frac{x}{2}\right) x e^{2x} + \frac{1}{4} x e^{2x} - \frac{1}{5} x e^{2x} (2 \cos x + \sin x) \}$$

$$\text{P.I of (1)} = x - 1 + \frac{(\cos x + \sin x)}{2} - \frac{x}{2} + \frac{1}{4} - \frac{(2 \cos x + \sin x)}{5}.$$

$$\text{P.I of (1)} = \frac{x}{2} - \frac{3}{4} + \frac{1}{10} (3 \sin x + \cos x)$$

\therefore Required solution; $y = C.F + P.I$

$$y = C_1 e^{-x} + C_2 e^{-2x} + \frac{x}{2} - \frac{3}{4} + \frac{1}{10} (3 \sin x + \cos x)$$

which is required solution

6.(d) → By using Laplace transform method solve

$(D^2 + 2D + 1) y = 3te^{-t}$, $t > 0$, subject to the conditions,
 $y = 4$, $Dy = 2$ when $t = 0$.

Solⁿ: Taking the Laplace transform of both sides of the given equation, we have

$$L\{y''\} + 2L\{y'\} + L\{y\} = 3L\{te^{-t}\}$$

$$\text{or } P^2 L\{y\} - py(0) - y'(0) + 2[PL\{y\} - y(0)] + L\{y\} \\ = 3L\{te^{-t}\}$$

$$\text{or } (P^2 + 2P + 1) L\{y\} - 4P - 10 = -3 \frac{d}{dp} [L\{e^{-t}\}]$$

$$\text{or } (P+1)^2 L\{y\} - 4P - 10 = -3 \frac{d}{dp} \left(\frac{1}{P+1} \right)$$

$$\text{or } (P+1)^2 L\{y\} = \frac{3}{(P+1)^2} + 4P + 10$$

$$\text{or } L\{y\} = \frac{3}{(P+1)^4} + \frac{4(P+1)+6}{(P+1)^2}$$

$$= \frac{3}{(P+1)^4} + \frac{4}{(P+1)} + \frac{6}{(P+1)^2}$$

$$\therefore y = 3L^{-1}\left\{\frac{1}{(P+1)^4}\right\} + 4L^{-1}\left\{\frac{1}{P+1}\right\} + 6L^{-1}\left\{\frac{1}{(P+1)^2}\right\}$$

$$= 3e^{-t} L^{-1}\left\{\frac{1}{P^4}\right\} + 4e^{-t} + 6e^{-t} L^{-1}\left\{\frac{1}{P^2}\right\}$$

$$= 3e^{-t} \frac{t^3}{3!} + 4e^{-t} + 6e^{-t} \cdot t = \frac{1}{2} e^{-t} \cdot t^3 + 4e^{-t} + 6te^{-t},$$

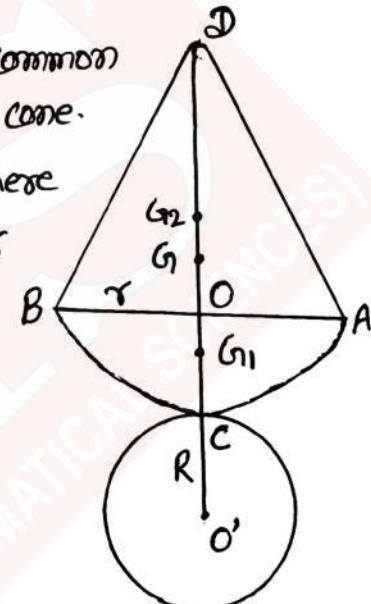
which is the required solution.

Q. 7 a.)

A solid homogeneous hemisphere of radius σ has a solid right circular cone of the same substance constructed on the bases; the hemisphere rests on the convex side of the fixed sphere of radius R . Show that the length of the axis of the cone consistent with stability for a small rolling displacement is

$$\frac{\sigma}{R+\sigma} \left[\sqrt{\{(3R+\sigma)(R-\sigma)\}} - 2\sigma \right]$$

Sol: Let O be the centre of the common base AB of the hemisphere and the cone. The hemisphere rests on a fixed sphere of radius R and centre O' , their point of contact being C . For equilibrium the line $O'CQ$ must be vertical. Let H be the length of the axis OD of the cone. It is given that $OB-OC=\sigma$ the radius of the hemisphere.



If G_1 and G_2 are the centres of gravity of the hemisphere and the cone respectively, then

$$OG_1 = 3\sigma/8 \text{ and } OG_2 = H/4$$

Let G be the centre of gravity of the combined body composed of the hemisphere and the cone. If h be the height of G above the point of contact C , then

$$\begin{aligned} h &= \frac{\frac{2}{3}\pi\sigma^3 \cdot \frac{5}{8}\sigma + \frac{1}{3}\pi\sigma^2 H \cdot (\sigma + \frac{1}{4}H)}{\frac{2}{3}\pi\sigma^3 + \frac{1}{3}\pi\sigma^2 H} \\ &= \frac{H(\sigma + \frac{1}{4}H) + \frac{5}{4}\sigma^2}{H + 2\sigma} \end{aligned}$$

Here $P_1 =$ the radius of curvature at the point of contact C of the upper body $= \sigma$.

and P_2 = the radius of curvature at C of the laser body = R

The equilibrium will be stable if

$$\frac{1}{h} > \frac{1}{P_1} + \frac{1}{P_2} \quad \text{i.e., } \frac{1}{h} > \frac{1}{\gamma} + \frac{1}{R}$$

$$\text{i.e., } \frac{H+2\gamma}{H(\gamma+\frac{1}{4}H)+\frac{5}{4}\gamma^2} > \frac{R+\gamma}{\gamma R}$$

$$\text{i.e., } (R+\gamma) \left\{ H\gamma + \frac{1}{4}H^2 + \frac{5}{4}\gamma^2 \right\} - \gamma R (H+2\gamma) < 0$$

$$\text{i.e., } \frac{1}{4}H^2(R+\gamma) + H \left\{ (R+\gamma)\gamma - \gamma R \right\} + \frac{5}{4}\gamma^2(R+\gamma) - 2\gamma^2R < 0$$

$$\text{i.e., } H^2(R+\gamma) + 4\gamma^2H + 5\gamma^3 - 3\gamma^2R < 0$$

$$\text{i.e., } H^2(R+\gamma) + 4\gamma^2H - \gamma^2(3R-5\gamma) < 0$$

$$\text{i.e., } H^2 + \frac{4\gamma^2}{R+\gamma}H - \frac{\gamma^2(3R-5\gamma)}{R+\gamma} < 0$$

$$\text{i.e., } \left(H + \frac{2\gamma^2}{R+\gamma} \right)^2 - \frac{4\gamma^4}{(R+\gamma)^2} - \frac{\gamma^2(3R-5\gamma)}{R+\gamma} < 0$$

$$\text{i.e., } \left(H + \frac{2\gamma^2}{R+\gamma} \right)^2 - \frac{4\gamma^4 + \gamma^2(3R-5\gamma)(R+\gamma)}{(R+\gamma)^2} < 0$$

$$\text{i.e., } \left(H + \frac{2\gamma^2}{R+\gamma} \right)^2 - \frac{\gamma^2[4\gamma^2 + 3R^2 - 2\gamma R - 5\gamma^2]}{(R+\gamma)^2} < 0$$

$$\text{i.e., } \left(H + \frac{2\gamma^2}{R+\gamma} \right)^2 - \frac{\gamma^2(3R^2 - 2\gamma R - \gamma^2)}{(R+\gamma)^2} < 0$$

$$\text{i.e., } \left(H + \frac{2\gamma^2}{R+\gamma} \right)^2 < \frac{\gamma^2(3R+\gamma)(R-\gamma)}{(R+\gamma)^2}$$

$$\text{i.e., } H + \frac{2\gamma^2}{R+\gamma} < \frac{\gamma}{R+\gamma} \sqrt{\{(3R+\gamma)(R-\gamma)\}}$$

$$\text{i.e., } H < \frac{\gamma}{R+\gamma} \sqrt{\{(3R+\gamma)(R-\gamma)\}} - \frac{2\gamma^2}{R+\gamma}$$

$$\text{i.e., } H < \frac{\gamma}{R+\gamma} [\sqrt{\{(3R+\gamma)(R-\gamma)\}} - 2\gamma]$$

therefore the greatest value of H consistent with the stability of equilibrium is

$$\frac{\gamma}{R+\gamma} [\sqrt{\{(3R+\gamma)(R-\gamma)\}} - 2\gamma].$$

7(b): A uniform chain of length l hangs between two points A and B which are at a horizontal distance a from one another, with B at a vertical distance b above A. Prove that the parameter of the catenary is given by

$$2c \sinh(a/2c) = \sqrt{l^2 - b^2}.$$

Prove also that, if the tensions at A and B are T_1 and T_2 respectively,

$$T_1 + T_2 = W\sqrt{1 + \frac{4c^2}{l^2 - b^2}} \text{ and } T_2 - T_1 = Wb/l,$$

where W is the weight of the chain.

Sol: A uniform chain of length l and weight W

hangs between two points

A and B. Let c be the vertex, ox the

axis and oy the

ordinate, o

the catenary

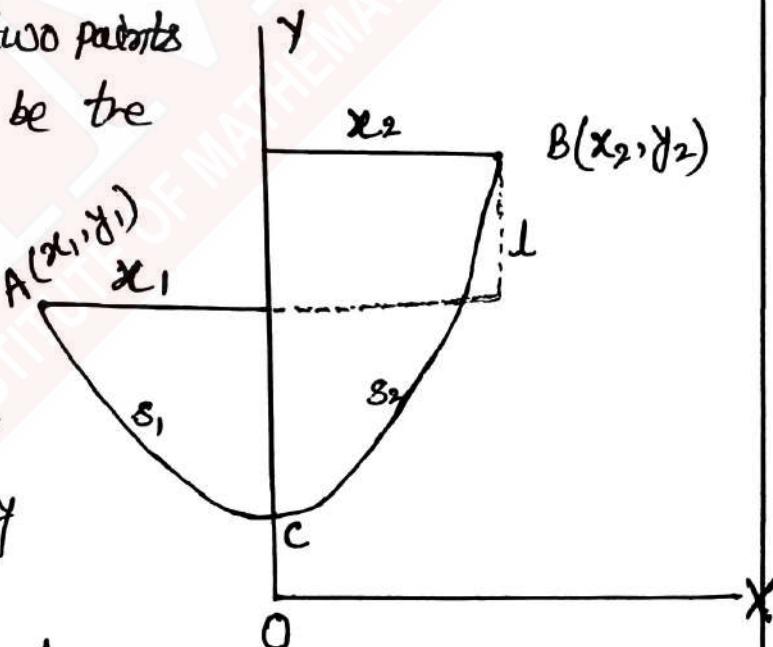
in which the

chain hangs. Let (x_1, y_1) and (x_2, y_2) be the

coordinates of the points A and B respectively

and let arc CA = s_1 and arc CB = s_2 .

We have $s_1 + s_2 = l$.



Since the horizontal distance between A and B is a , therefore

$$x_1 + x_2 = a.$$

Again since the vertical distance of B above A is b , therefore

$$y_2 - y_1 = b.$$

Let w be the weight per unit length of the chain. Then

$$W = Iw, \text{ or } w = W/I.$$

By the formula $s = c \sinh(x/c)$, we have

$$s_1 = c \sinh(x_1/c) \text{ and}$$

$$s_2 = c \sinh(x_2/c).$$

$$\therefore I = s_1 + s_2 = c [\sinh(x_1/c) + \sinh(x_2/c)] \quad \text{--- (1)}$$

Again by the formula $y = c \cosh(x/c)$, we have

$$y_1 = c \cosh(x_1/c) \text{ and}$$

$$y_2 = c \cosh(x_2/c)$$

$$\therefore b = y_2 - y_1 = c [\cosh(x_2/c) - \cosh(x_1/c)] \quad \text{--- (2)}$$

Squaring and subtracting (1) and (2), we have

$$\begin{aligned} I^2 - b^2 &= c^2 \left[-\{\cosh^2(x_1/c) - \sinh^2(x_1/c)\} - \right. \\ &\quad \left. \{\cosh^2(x_2/c) - \sinh^2(x_2/c)\} + \right. \\ &\quad \left. 2\{\cosh(x_1/c) \cosh(x_2/c) + \sinh(x_1/c) \sinh(x_2/c)\} \right] \end{aligned}$$

$$= c^2 [-1 - 1 + 2 \cosh(x_1/c + x_2/c)]$$

$$= c^2 [-2 + 2 \cosh \{ (x_1 + x_2)/c \}]$$

$$= 2c^2 \left\{ \cosh \frac{a}{c} - 1 \right\}$$

$$= c^2 \left\{ 1 + 2 \sinh^2 \frac{a}{2c} - 1 \right\}$$

$$= 4c^2 \sinh^2 \frac{a}{2c} \quad \text{--- (3)}$$

$\therefore c$ is given by $2c \sinh(a/2c) = \sqrt(l^2 - b^2)$.

[Remember that

$$\cosh(\alpha + \beta) = \cosh \alpha \cdot \cosh \beta + \sinh \alpha \cdot \sinh \beta$$

$$\text{and } \cosh 2\alpha = 1 + 2 \sinh^2 \alpha]$$

Now let T_1 and T_2 be the tensions at the points A and B respectively. Then by the formula

$T = w y$, we have

$$T_1 = w y_1, \quad T_2 = w y_2.$$

$$\therefore T_2 - T_1 = w(y_2 - y_1) = wb = (w/l)b = Wb/l.$$

$$\text{Also, } T_1 + T_2 = w(y_1 + y_2) = \frac{W}{l}(y_1 + y_2) = W \frac{y_1 + y_2}{S_1 + S_2}$$

$$= W \frac{c \cosh(x_1/c) + c \cosh(x_2/c)}{c \sinh(x_1/c) + c \sinh(x_2/c)}$$

$$= W \frac{\cosh(x_1/c) + \cosh(x_2/c)}{\sinh(x_1/c) + \sinh(x_2/c)}$$

$$= W \frac{2 \cosh \frac{1}{2}(x_1/c + x_2/c) \cosh \frac{1}{2}(x_1/c - x_2/c)}{2 \sinh \frac{1}{2}(x_1/c + x_2/c) \sinh \frac{1}{2}(x_1/c - x_2/c)}$$

$$= W \coth \left(\frac{x_1 + x_2}{2c} \right)$$

$$= W \coth \frac{a}{2c}$$

$$= W \sqrt{1 + \operatorname{cosech}^2 \frac{a}{2c}} \quad [\because \coth^2 a = 1 + \operatorname{cosech}^2 a]$$

$$= W \sqrt{1 + \frac{4c^2}{J^2 - b^2}}$$

Substituting for $\operatorname{cosech}^2(a/2c)$ from ③.

7(C) →

A particle moves with a central acceleration which varies inversely as the cube of the distance. If it be projected from an apse at a distance a from the origin with a velocity which is $\sqrt{2}$ times the velocity for a circle of radius a , show that the equation to its path is
 $r \cos(\theta/\sqrt{2}) = a$.

Soln →

Here a central acceleration varies inversely as the cube of the distance

$$\text{i.e., } \rho = \frac{\mu}{r^3} = \mu r^3, \text{ where } \mu \text{ is constant.}$$

If V is the velocity for a circle of radius a , then, $\frac{V^2}{a} = [\rho]_{r=a} = \frac{\mu}{a^3}$

$$\text{or } V = \sqrt{(\mu/a^2)}$$

∴ the velocity of projection

$$v_i = \sqrt{2}V = \sqrt{(2\mu/a^2)}.$$

The differential equation of the path is-

$$h^2 \left[u + \frac{d^2 u}{d\theta^2} \right] = \rho = \frac{\mu u^3}{u^2} = \mu u.$$

Multiplying both sides by $2(du/d\theta)$ and integrating we have,

$$v^2 = h^2 \left[u^2 + \left(\frac{du}{d\theta} \right)^2 \right]$$

$$v^2 = \mu u^2 + A \quad \text{--- --- --- ①}$$

where A is a constant.

But initially when $r=a$

i.e., $u = \frac{1}{a}$, $\frac{du}{d\theta} = 0$ (at origin)

and $v = v_1 = \sqrt{(2u/a^2)}$

from ①, we have.

$$\frac{2u}{a^2} = h^2 \left[\frac{1}{a^2} \right] = \frac{u}{a^2} + A$$

$$\therefore h^2 = 2u \text{ and } A = u/a^2$$

Substituting the values of h^2 and A in ①, we have,

$$2u \left[u^2 + \left(\frac{du}{d\theta} \right)^2 \right] = uu^2 + \frac{u}{a^2}$$

$$\text{or}, \quad 2 \left(\frac{du}{d\theta} \right)^2 = \frac{1}{a^2} + u^2 - 2u^2 = \frac{1-a^2u^2}{a^2}$$

$$\text{or}, \quad \sqrt{2}a \frac{du}{d\theta} = \sqrt{(1-a^2u^2)}$$

$$\text{or}, \quad \frac{d\theta}{\sqrt{2}} = \frac{a du}{\sqrt{(1-a^2u^2)}}$$

Integrating, $(\theta/\sqrt{2}) + B = \sin^{-1}(au)$,

where B is constant.

But initially, when $u = \frac{1}{a}$, $\theta = 0$.

$$\therefore B = \sin^{-1} 1 = \frac{1}{2}\pi$$

$$\therefore (\theta/\sqrt{2}) + \frac{1}{2}\pi = \frac{1}{2}\sin^{-1}(au)$$

$$\text{or}, \quad au = \frac{a}{\sin \left\{ \frac{1}{2}\pi + (\theta/\sqrt{2}) \right\}}$$

$$\text{or}, \quad a = \sin \left(\frac{\theta}{\sqrt{2}} \right)$$

which is the required equation of the path.

8.(b)

If u_1, u_2, u_3 are orthogonal curvilinear co-ordinates, Show that, $\partial r / \partial u_1, \partial r / \partial u_2, \partial r / \partial u_3$ and $\nabla u_1, \nabla u_2, \nabla u_3$ are reciprocal systems of vectors.

Solⁿ: We know that

$$\nabla u_1 = e_1/h_1, \nabla u_2 = e_2/h_2, \nabla u_3 = e_3/h_3.$$

$$\therefore [\nabla u_1 + \nabla u_2 + \nabla u_3] = (\nabla u_1 \times \nabla u_2) \cdot \nabla u_3$$

$$= \left(\frac{1}{h_1} e_1 \times \frac{1}{h_2} e_2 \right) \times \frac{1}{h_3} e_3$$

$$= \frac{1}{h_1 h_2 h_3} e_3 \cdot e_3 = \frac{1}{h_1 h_2 h_3} \quad \text{--- (1)}$$

$$\text{Also, } \frac{\partial r}{\partial u_1} = h_1 e_1, \frac{\partial r}{\partial u_2} = h_2 e_2, \frac{\partial r}{\partial u_3} = h_3 e_3 \quad \text{--- (2)}$$

$$\begin{aligned} \text{Now, } \frac{\nabla u_2 \times \nabla u_3}{[\nabla u_1 \nabla u_2 \nabla u_3]} &= \frac{(1/h_2) e_2 \times (1/h_3) e_3}{1/h_1 h_2 h_3} \\ &= h_1 e_1 = \frac{\partial r}{\partial u_1} \quad (\text{by (2)}) \end{aligned}$$

Proceeding similarly, we get

$$\frac{\partial r}{\partial u_2} = \frac{\nabla u_3 \times \nabla u_1}{[\nabla u_1 \nabla u_2 \nabla u_3]}, \quad \frac{\partial r}{\partial u_3} = \frac{\nabla u_1 \times \nabla u_2}{[\nabla u_1 \nabla u_2 \nabla u_3]}$$

Hence, $\partial r / \partial u_1, \partial r / \partial u_2, \partial r / \partial u_3$ and $\nabla u_1, \nabla u_2, \nabla u_3$ form reciprocal systems of vectors.

8C Q)

Find the value of

$$\int \operatorname{curl} F \cdot d\alpha.$$

taken over the portion of the surface

$$x^2 + y^2 - 2ax + az = 0 \text{ for which } z \geq 0 \text{ when}$$

$$F = (y^2 + z^2 - x^2) \mathbf{i} + (z^2 + x^2 - y^2) \mathbf{j} + (x^2 + y^2 - z^2) \mathbf{k}$$

Soln

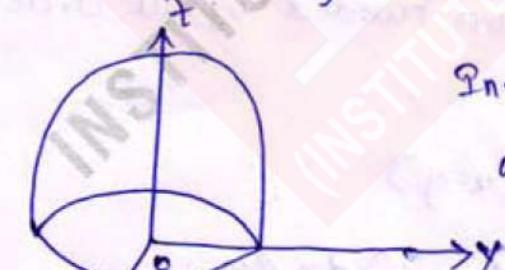
Re writing the equation

$$x^2 + y^2 - 2ax + az = 0$$

$$\text{or } (x-a)^2 + y^2 = -a(z-a).$$

we see that the surface is a paraboloid with its vertex at $(a, 0, a)$ and axis parallel to z -axis and turned toward the negative direction of the same it meets the plane $z=0$ in the circle C given by

$$x^2 + y^2 - 2ax = 0, z=0$$



In the figure O is the point $(a, 0, 0)$ and ox, oy, oz are the lines parallel to the co-ordinate axes.

By Stoke's theorem, the given surface integral is equal to the line integral

$$\int_C F \cdot d\alpha.$$

The circle 'c' is given by

$$x = a(1+\cos\theta), y = a\sin\theta, \theta = 0$$

Along c.

$$\mathbf{F} = \left[a^2 \sin^2\theta - a^2(1+\cos\theta)^2 \right] \mathbf{i} + \left[a^2(1+\cos\theta)^2 - a^2 \sin^2\theta \right] \mathbf{j} + \left[a^2(1+\cos\theta)^2 + a^2 \sin^2\theta \right] \mathbf{k}$$

$$\therefore \mathbf{F} \cdot \left(\frac{dx}{d\theta} \mathbf{i} + \frac{dy}{d\theta} \mathbf{j} + \frac{dz}{d\theta} \mathbf{k} \right) \\ = [a^2 \sin^2\theta - a^2(1+\cos\theta)^2] [-a\sin\theta - a\cos\theta].$$

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_0^{2\pi} \mathbf{F} \cdot \frac{d\mathbf{r}}{d\theta} \cdot d\theta = 2a^3\pi$$

Another method: By a further application of Stokes' theorem, we see that the given integral

$$= \iint_{S_1} \operatorname{curl} \mathbf{F} \cdot \mathbf{n} dS.$$

where S_1 is the plane region bounded by the circle c.

$$\text{Here } \mathbf{n} = \mathbf{k}$$

$$\text{Then } \operatorname{curl} \mathbf{F} \cdot \mathbf{n} = 2(x-y)$$

$$\therefore \text{The integral} = 2 \iint (x-y) dx dy.$$

taken over S_1 , changing to polar co-ordinates

$$\text{so that } x = r\cos\theta, y = r\sin\theta$$

we see that the integral

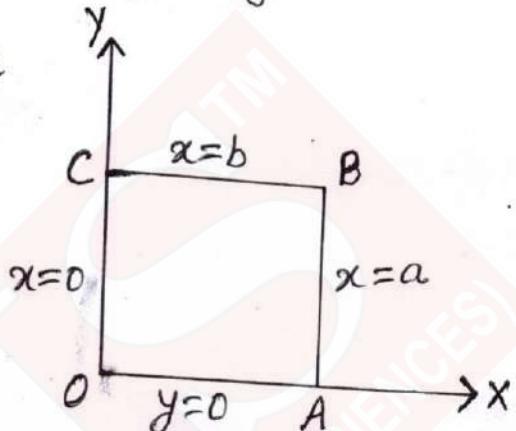
$$= 2 \iint (a+r\cos\theta - r\sin\theta) r d\theta dr = \underline{2a^3\pi - 4ay}.$$

8.(d)

Verify Stoke's theorem for the function $F = x(ix + jy)$, integrated round the square in the plane $z=0$. Whose sides are along the lines $x=0, y=0, x=a, y=a$.

Soln: We have $\text{curl } x(ix + jy) = ky$.

$$\begin{aligned} & \therefore \int_S \text{curl } x(ix + jy) \cdot da \\ &= \int_0^a \int_0^a ky \cdot k dx dy \\ &= \int_0^a \int_0^a y dx dy = \frac{a^3}{2} \end{aligned}$$



Again,

$$+ \int_{BC} F \cdot dr + \int_{CO} F \cdot dr + \int_{BC} F \cdot dr + \int_{CO} F \cdot dr.$$

$$\text{Now } \int_{OA} F \cdot dr = \int_0^a x(ix + jy) \cdot i dx = \int_0^a x^2 dx = \frac{1}{3} a^3,$$

$$\int_{AB} F \cdot dr = \int_0^a x(ix + jy) \cdot j dy = \int_0^a ay dy = \frac{1}{2} a^3,$$

$$\int_{BC} F \cdot dr = \int_a^0 x(ix + jy) \cdot i dx = - \int_0^a x^2 dx = -\frac{1}{3} a^3,$$

$$\int_{CO} F \cdot dr = \int_a^0 x(ix + jy) \cdot j dy = 0.$$

$$\therefore \int_C F \cdot dr = \frac{1}{3} a^3 + \frac{1}{2} a^3 - \frac{1}{3} a^3 + 0 = \frac{1}{2} a^3.$$

Hence verified.