

Main Test Series - 2018

Test-18 - Paper-II - Answer key

11a) Show that A_4 has no subgroup of order 6.

Solⁿ: Let $S = \{1, 2, 3, 4\}$ then

$S_4 = \{f/f: S \rightarrow S\}$ is a permutation on S

is a permutation group of order $4!$.

Let $A_4 = \{f/f: S \rightarrow S \text{ is even permutation on } S\}$

is an even permutation group of order $\frac{4!}{2}$

If possible suppose that A_4 has a subgroup H of order 6.

i.e., let $H < A_4$ such that $|H| = 6$

\therefore By Lagrange's theorem

$$\frac{|A_4|}{|H|} = \frac{12}{6} = 2$$

$$\therefore (G:H) = 2$$

$\therefore H \trianglelefteq A_4$ (i.e., H is a normal subgroup of A_4)

$$\therefore \frac{A_4}{H} = \{Hf/f \in A_4\}$$

$= \{He, Hf\}$ is a quotient group

where f is not identity permutation.

let $\phi: A_4 \rightarrow \frac{A_4}{H}$ be a homomorphism and onto.

such that $\phi(x) = Hx \quad \forall x \in A_4$. ①

let $x \in A_4$ be a 3-cycle permutation (i.e., even permutation)

such that $O(x) = 3$ then $\frac{O(x)}{O(\phi(x))} = \frac{3}{O(\phi(x))}$ — (2)

Since $\frac{O(A_4)}{|H|} = 2$

$$\therefore O(\phi(x)) = 1$$

$$\Rightarrow \phi(x) = H \Rightarrow \phi(x) = H$$

$$\Rightarrow Hx = H \quad (\text{by (1)})$$

$$\Rightarrow x \in H$$

$\therefore H$ contains all 3-cycle elements.

but A_4 has 8 3-cycles.

and $8 > 6$ which is a contradiction.

$\therefore A_4$ has no subgroup of order 6.

115)

Prove that every field is an integral domain,
 but every integral domain is not a field.

Give an example of an integral domain
 which is not a field.

Sol: Let F be a field then by definition F is
 a commutative ring with unity and
 every non-zero element is invertible w.r.t \times .

In order to prove that a field is an I.D.

we have to prove that a field F has no zero
 divisors.

Let $a, b \in F$ and $a \neq 0$.

Since F is a field.

for $a \neq 0 \in F \Rightarrow a^{-1}$ exists in F .

$$\therefore a a^{-1} = a^{-1} a = 1$$

Now we have

$$ab = 0$$

$$\Rightarrow a^{-1}(ab) = a^{-1} \cdot 0$$

$$\Rightarrow (a^{-1}a)b = 0$$

$$\Rightarrow 1b = 0$$

$$\Rightarrow b = 0$$

Similarly we can prove that $a, b \in F$
 $b \neq 0$ and $ab = 0 \Rightarrow a = 0$

$\therefore a, b \in F$ and $ab = 0$

\Rightarrow either $a = 0$ or $b = 0$

$\therefore F$ has no zero divisors.

\therefore A field is an ID

The converse of the above need not be true
 i.e., every ID need not be a field.

For example, the set of integers \mathbb{Z} is an
 integral domain which is not a field.
 Since $a \neq 0 \in \mathbb{Z}$ does not have the multiplicative
 inverse in \mathbb{Z} .

The ring $\mathbb{Z}_5 = \{0, 1, 2, 3, 4\}$ of integers modulo
 5 is both an integral domain and a
 field.

Q.E.D.

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100) prove that b/w any two real roots of the equation $e^x \sin x + 1 = 0$ there is at least one real root of the equation $\tan x + 1 = 0$.

sol Let $x=a$ & $x=b$ be the roots of $e^x \sin x + 1 = 0$ then
 $e^a \sin a + 1 = 0$ & $e^b \sin b + 1 = 0$ ①

Let $f(x) = e^x \sin x + 1 \quad x \in [a, b]$
 since e^x & $\sin x$ are continuous and differentiable for all x real.

$\therefore f(x) = e^x \sin x + 1$ is continuous and differentiable in $[a, b]$

and $f(a) = f(b) = 0$ (by ①)

$\therefore f$ has been satisfied the conditions of Rolle's theorem.

\therefore at least one $\lambda \in (a, b)$ s.t. $f'(\lambda) = 0$ ②

$$\therefore f'(\lambda) = e^\lambda \sin \lambda + e^\lambda \cos \lambda$$

$$\Rightarrow f'(\lambda) = e^\lambda (\sin \lambda + \cos \lambda)$$

$$\therefore \textcircled{1} \Rightarrow e^\lambda (\sin \lambda + \cos \lambda) = 0 \quad \forall \lambda \in (a, b)$$

$$\Rightarrow \sin \lambda + \cos \lambda = 0 \quad (\because e^\lambda \neq 0 \quad \forall \lambda)$$

$$\Rightarrow \tan \lambda + 1 = 0$$

$$\Rightarrow \tan \lambda + 1 = 0 \quad \lambda \in (a, b)$$

1(d) Use Cauchy's theorem and/or Cauchy integral formula to evaluate the following integrals.

$$(i) \int_{|z|=1} \frac{\cos z}{z(z-4)} dz$$

Sol: Given that $\int_{|z|=1} \frac{\cos z}{z(z-4)} dz.$

Comparing the given integral with

$$\int \frac{f(z)}{z-z_0} dz \text{ where } C: |z|=1$$

Since $f(z) = \frac{\cos z}{z-4}$ and $z_0 = 0$ is a point inside $|z|=1$.

\therefore we can apply Cauchy's integral formula

$$\begin{aligned} \int_{|z|=1} \frac{f(z)}{z-z_0} dz &= 2\pi i f(z_0) \\ &= 2\pi i f(0) \\ &= 2\pi i \left[\frac{\cos(0)}{0-4} \right] \\ &= \frac{2\pi i}{-4} \\ &= \frac{-\pi i}{2} \end{aligned}$$

1(d) (ii) $\int_C \frac{3z^2+z}{z^2-1} dz$, where C is the circle $|z-1|=1$.

Soln: The integrand has singularities, where $z^2-1=0$ i.e. at $z=1$ and $z=-1$.

The circle $|z-1|=1$ has center at $z=1$, $f(z) = \frac{3z^2+z}{z^2-1}$ is an analytic function

Also, $\frac{1}{z^2-1} = \frac{1}{(z-1)(z+1)} = \frac{1}{2} \left(\frac{1}{z-1} - \frac{1}{z+1} \right)$

$$\int_C \frac{3z^2+z}{z^2-1} dz = \frac{1}{2} \int_C \frac{3z^2+z}{z-1} dz - \frac{1}{2} \int_C \frac{3z^2+z}{z+1} dz$$

By Cauchy's integral formula $\int_C \frac{3z^2+z}{z-1} dz = 2\pi i f(1) = 8\pi i$

By Cauchy's theorem $\int_C \frac{3z^2+z}{z+1} dz = 0$ where $f(z) = 3z^2+z$

\therefore from (1), we have $\int_C \frac{3z^2+z}{z^2-1} dz = 4\pi i$

1(e) An automobile dealer wishes to put four repairmen to four different jobs. The repairmen have somewhat different kinds of skills and they exhibit different levels of efficiency from one job to another. The dealer has estimated the number of manhours that would be required for each job-man combination. This is given in the matrix form in adjacent table.

Find the optimum assignment that will result in minimum manhours needed.

Man \ Job	A	B	C	D
1	5	3	2	8
2	7	9	2	6
3	6	4	5	7
4	5	7	7	8

Step (i):

(i) After subtracting the minimum of each row from all elements of that row, the reduced matrix is given by

3	1	0	6
5	7	0	4
2	0	1	3
0	2	2	3

(ii) Subtracting the minimum element of column from elements of that column, we get

3	1	0	3
5	2	0	1
2	0	1	0
0	2	2	0

Step (ii): Cover all the zeros by minimum no. of horizontal and vertical lines. A systematic approach for this is to look for a row or column containing maximum no. of zeros.

We can cover all the zeros by 3 lines only

So, $r=3 < 4=n$

So, go to step (3)

3	1	0	3
5	2	0	1
2	0	1	0
0	2	2	0

Step (3):

1 is the least uncovered element. Subtract 1 from all the uncovered elements. Add 1 to elements at intersection of the covering lines namely 1 at position (3,3) and 2 at (4,3). Leave other uncovered elements unchanged and the reduced matrix so obtained is

2	0	0	2
4	1	0	0
1	0	2	0
0	2	3	0

Again, cover the zeros by minimum no. of horizontal and vertical lines. we required exactly 4 lines to cover all the zeros. As $r=4=n$, optimal assignment can be made at this stage.

2	0	0	2
4	1	0	0
1	0	2	0
0	2	3	0

It may be noted that an assignment problem can have more than one optimum solution.

2	X	0	2
4	1	X	0
1	0	2	X
0	2	3	X

Optimum solution-I

Man	Job	Man. hours
1	B	3
2	C	2
3	D	7
4	A	5

Optimum solution II

Man	Job	Man. hours
1	C	2
2	D	6
3	B	4
4	A	5

(i) If $\beta \in S_7$ and $\beta^4 = (2143567)$ then find β .

(ii) Let $GL(2, R)$ be the group of all non singular 2×2 matrices over R . Show that each of the following set is a ^{sub}group of $GL(2, R)$.

$$H = \left\{ \begin{bmatrix} a & 0 \\ c & d \end{bmatrix} \in GL(2, R) \mid ad \neq 0 \right\}$$

Solⁿ: $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \in H$, Hence $H \neq \emptyset$. Let $A = \begin{bmatrix} a & 0 \\ c & d \end{bmatrix} \in H$

and $B = \begin{bmatrix} a_1 & 0 \\ c_1 & d_1 \end{bmatrix} \in H$. Since $B \in H$, $a_1 d_1 \neq 0$.

Hence

$$B^{-1} = \begin{bmatrix} \frac{d_1}{a_1 d_1} & 0 \\ -\frac{c_1}{a_1 d_1} & \frac{1}{a_1 d_1} \end{bmatrix} = \begin{bmatrix} \frac{1}{a_1} & 0 \\ -\frac{c_1}{a_1 d_1} & \frac{1}{d_1} \end{bmatrix}$$

Then

$$\begin{aligned} AB^{-1} &= \begin{bmatrix} a & 0 \\ c & d \end{bmatrix} \begin{bmatrix} \frac{1}{a_1} & 0 \\ -\frac{c_1}{a_1 d_1} & \frac{1}{d_1} \end{bmatrix} \\ &= \begin{bmatrix} \frac{a}{a_1} & 0 \\ \frac{c}{a_1} - \frac{dc_1}{a_1 d_1} & \frac{d}{d_1} \end{bmatrix} \end{aligned}$$

Since $ad \neq 0$, $a_1 d_1 \neq 0$ we find that $\frac{a}{a_1} \frac{d}{d_1} = \frac{ad}{a_1 d_1} \neq 0$

Hence $AB^{-1} \in H$. Consequently, H is a subgroup of G .

(1)

Since $\beta^{28} = (\beta^4)^7 = I$ (identity permutation)

We know that $o(\beta) \mid 28$.

So that $o(\beta) \neq 2, 4$ (or) 7 .

If $o(\beta) = 14$ then β is written in disjoint cycle form would need at least one 7-cycle and one 2-cycle.

But that requires atleast 9 symbols and we have only 7.

Like wise $o(\beta) = 28$ requires at least one 7-cycle and one 4-cycle.

So $o(\beta) = 7$.

Ans.

2(b) → Prove that-

$$\int_0^1 \left(\sum_{n=1}^{\infty} \frac{x^n}{n^2} \right) dx = \sum_{n=1}^{\infty} \frac{1}{n^2(n+1)}$$

Solⁿ : Let $f_n(x) = \frac{x^n}{n^2}$

$$|f_n(x)| = \left| \frac{x^n}{n^2} \right| \leq \frac{1}{n^2} = M_n \text{ for } 0 \leq x \leq 1$$

Since $\sum_{n=1}^{\infty} M_n = \sum_{n=1}^{\infty} \frac{1}{n^2}$ is convergent

∴ By Weierstrass's M-test, the series

$\sum_{n=1}^{\infty} f_n(x) = \sum_{n=1}^{\infty} \frac{x^n}{n^2}$ is uniformly convergent for $0 \leq x \leq 1$.

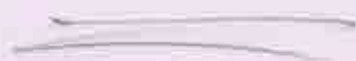
∴ The series can be integrated term by term

$$\Rightarrow \int_0^1 \left(\sum_{n=1}^{\infty} \frac{x^n}{n^2} \right) dx = \sum_{n=1}^{\infty} \int_0^1 \frac{x^n}{n^2} dx$$

$$= \sum_{n=1}^{\infty} \frac{x^{n+1}}{n^2(n+1)}$$

$$= \sum_{n=1}^{\infty} \frac{1}{n^2(n+1)}$$

$$\therefore \int_0^1 \left(\sum_{n=1}^{\infty} \frac{x^n}{n^2} \right) dx = \sum_{n=1}^{\infty} \frac{1}{n^2(n+1)}$$



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280. A function f is defined on $[0,1]$ by

$$f(x) = \begin{cases} \frac{1}{2^n} & \frac{1}{2^{n+1}} < x \leq \frac{1}{2^n} \quad (n=0,1,2,\dots) \\ 0 & x=0. \end{cases}$$

prove that (i) f is integrable on $[0,1]$ (ii) $\int_0^1 f = \frac{2}{3}$

Sol Let $f(x) = \begin{cases} \frac{1}{2^n} & \text{when } \frac{1}{2^{n+1}} < x \leq \frac{1}{2^n} \quad (n=0,1,2,\dots) \\ 0 & \text{when } x=0. \end{cases}$

then $f(x) = \begin{cases} \frac{1}{2^0} = 1 & \text{when } \frac{1}{2^1} < x \leq \frac{1}{2^0} = 1 \\ \frac{1}{2^1} & \text{when } \frac{1}{2^2} < x \leq \frac{1}{2^1} \\ \frac{1}{2^2} & \text{when } \frac{1}{2^3} < x \leq \frac{1}{2^2} \\ \vdots \\ \frac{1}{2^{n-1}} & \text{when } \frac{1}{2^n} < x \leq \frac{1}{2^{n-1}} \\ \vdots \\ 0 & \text{when } x=0. \end{cases}$

Since f is bounded and continuous on $[0,1]$ except at the points

$$\frac{1}{2}, \frac{1}{4}, \frac{1}{8}, \dots$$

\therefore The set of points of discontinuity of f on $[0,1]$ is $\left\{ \frac{1}{2}, \frac{1}{4}, \frac{1}{8}, \dots \right\}$

which has only one limit point.
 Since the set of points of discontinuity of f on $[0,1]$ has a finite number of limit points.

$\therefore f$ is integrable on $[0,1]$.

now $\int_{\frac{1}{2^n}}^1 f(x) dx = \int_{\frac{1}{2}}^1 f(x) dx + \int_{\frac{1}{2^2}}^{\frac{1}{2}} f(x) dx +$

$\dots + \int_{\frac{1}{2^n}}^{\frac{1}{2^{n-1}}} f(x) dx$

$= (1 - \frac{1}{2}) + \frac{1}{2} (\frac{1}{2} - \frac{1}{2^2}) + \frac{1}{2^2} (\frac{1}{2^2} - \frac{1}{2^3}) +$

$\dots + \frac{1}{2^{n-1}} (\frac{1}{2^{n-1}} - \frac{1}{2^n})$
 $= (1 - \frac{1}{2}) + \frac{1}{2} (\frac{1}{2}) + \frac{1}{2^2} (\frac{1}{2}) + \dots$

$\dots + \frac{1}{2^{n-1}} (\frac{1}{2^n})$

$= \frac{1}{2} \left[1 + \frac{1}{2^2} + \left(\frac{1}{2^2}\right)^2 + \dots + \left(\frac{1}{2^2}\right)^{n-1} \right]$

$\int_{\frac{1}{2^n}}^1 f(x) dx = \frac{1}{2} \left[\frac{1 - \left(\frac{1}{2^2}\right)^n}{1 - \frac{1}{2^2}} \right] = \frac{2}{3} \left(1 - \frac{1}{4^n} \right)$

$\Rightarrow \lim_{n \rightarrow \infty} \int_{\frac{1}{2^n}}^1 f(x) dx = \lim_{n \rightarrow \infty} \frac{2}{3} \left(1 - \frac{1}{4^n} \right) \Rightarrow \int_0^1 f(x) dx = \frac{2}{3}$

2d) Use the method of Contour integration to prove that $\int_{-\pi}^{\pi} \frac{a \cos \theta}{a + \cos \theta} d\theta = 2\pi a \left\{ 1 - \frac{a}{\sqrt{a^2 - 1}} \right\}$, where $a > 1$. 10

Sol'n:
$$I = \int_{-\pi}^{\pi} \frac{a \cos \theta}{a + \cos \theta} d\theta = \int_0^{2\pi} \frac{2a \cos \theta}{2a + 2 \cos \theta} d\theta$$

$$I = \text{real part of } \int_0^{2\pi} \frac{2ae^{i\theta}}{2a + (e^{i\theta} + e^{-i\theta})} d\theta$$

$$= \text{real part of } \int_C \frac{2az}{2a + z + \frac{1}{z}} \frac{dz}{iz} \text{ writing } e^{i\theta} = z, d\theta = \frac{dz}{iz}$$

where C is the unit circle $|z| = 1$

$$= \text{real part of } \int_C \frac{-2iaz}{z^2 + 2az + 1} dz$$

$$= \text{real part of } \int_C \frac{-2iaz}{(z - \alpha)(z - \beta)}$$

where $\alpha = -a + \sqrt{a^2 - 1}$, $\beta = -a - \sqrt{a^2 - 1}$

$$= \text{real part of } \int_C f(z) dz \text{ where } f(z) = \frac{-2iaz}{(z - \alpha)(z - \beta)}$$

Poles of $f(z)$ are given by $(z - \alpha)(z - \beta) = 0$

i.e. $z = \alpha$ and $z = \beta$ are the two simple poles.

The value of β is obviously greater than unity while that of α is less than unity only the pole α lies within the Contour.

Residue of $f(z)$ at the simple pole $z = \alpha$ is

$$= \lim_{z \rightarrow \alpha} (z - \alpha) f(z)$$

$$= \lim_{z \rightarrow \alpha} (z - \alpha) \frac{-2iaz}{(z - \alpha)(z - \beta)} = \frac{-2ai\alpha}{\alpha - \beta}$$

$$= \frac{-2ia \{-a + \sqrt{a^2 - 1}\}}{2\sqrt{a^2 - 1}} = ai \left[\frac{a}{\sqrt{a^2 - 1}} - 1 \right]$$

Hence by Cauchy's residue theorem we have

$$= 2\pi i \cdot a i \left\{ \frac{a}{\sqrt{a^2-1}} - 1 \right\}$$

$$= 2\pi a \left\{ 1 - \frac{a}{\sqrt{a^2-1}} \right\} \text{ which is purely real.}$$

Hence $\mathcal{I} = \text{real part of } \int_C f(z) dz$

$$= 2\pi a \left\{ 1 - \frac{a}{\sqrt{a^2-1}} \right\}$$

- 3(a) → (i) Let G be a group. show that if $G/Z(G)$ is cyclic, then G is abelian.
 (ii) show that the ring \mathbb{Z}_p of integers mod p is a field if and only if p is prime.

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Soln:

(i) Let n be an integer

Define $f: \mathbb{Z} \rightarrow \mathbb{Z}$ by $f(t) = nt \quad \forall t \in \mathbb{Z}$

Let $r, s \in \mathbb{Z}$. Then $f(r+s) = n(r+s)$
 $= nr + ns$

Hence f is a homomorphism.

we denote this homomorphism by f_n .

we show that any homomorphism from

\mathbb{Z} to \mathbb{Z} is one of these $f_n, n \in \mathbb{Z}$.

To show this, let us consider an integer $m \in \mathbb{Z}$.

Now if f is a homomorphism from \mathbb{Z} to \mathbb{Z} ,

then $f(m) = f(m \cdot 1) = m f(1)$.

so we find that f is completely determined
 if we know $f(1)$.

If $f(1) = n$, then $f(m) = nm = f_n(m)$.

Hence $f = f_n$ and all the homomorphism
 of \mathbb{Z} into \mathbb{Z} are given by $f_n, n = 0, \pm 1, \pm 2, \dots$

(ii) Let us write $z(G) = N$. Then $\frac{G}{N}$ is cyclic.

suppose it is generated by Ng .

Let $a, b \in G$ be any two elements

then $Na, Nb \in \frac{G}{N}$

$\Rightarrow Na = (Ng)^n, Nb = (Ng)^m$ for some n, m

$$\Rightarrow Na = Ng \cdot Ng \cdots Ng = Ng^n$$

$$\text{and } Nb = Ng^m.$$

$$\Rightarrow ag^{-n} \in N, bg^{-m} \in N$$

$$\Rightarrow ag^{-n} = x, bg^{-m} = y \text{ for some } x, y \in N.$$

$$\Rightarrow a = xg^n, b = yg^m$$

$$\begin{aligned} \Rightarrow ab &= (xg^n)(yg^m) = x(g^n y)g^m \\ &= x(yg^m)g^n \quad \text{as } g^n y = y g^n \\ &= xy g^{n+m} \end{aligned}$$

$$\begin{aligned} \text{Similarly, } ba &= (yg^m)(xg^n) = y(g^m x)g^n \\ &= y(xg^n)g^m \\ &= yx g^{m+n} \end{aligned}$$

$$\Rightarrow ab = ba \text{ as } xy = yx \text{ as } x, y \in Z(G)$$

$\therefore G$ is abelian

3(b) Show that the sequence $\{f_n\}$ where

$$f_n(x) = \begin{cases} n^2x, & 0 \leq x \leq \frac{1}{n} \\ -n^2x + 2n, & \frac{1}{n} \leq x \leq \frac{2}{n} \\ 0, & \frac{2}{n} \leq x \leq 1 \end{cases}$$

is not uniformly convergent on $[0, 1]$.

Soln The sequence converges to f , where $f(x) = 0$, for all $x \in [0, 1]$. Each function f_n and f are continuous on $[0, 1]$.

$$\text{Also } \int_0^1 f_n dx = \int_0^{\frac{1}{n}} n^2x dx + \int_{\frac{1}{n}}^{\frac{2}{n}} (-n^2x + 2n) dx + \int_{\frac{2}{n}}^1 0 dx = 1$$

But

$$\int_0^1 f dx = 0$$

$$\lim_{n \rightarrow \infty} \int_0^1 f_n dx \neq \int_0^1 f dx$$

So by the theorem

(i) If a sequence $\{f_n\}$ converges uniformly to f on $[a, b]$ and each function f_n is integrable, then f is integrable on $[a, b]$ and the sequence $\left\{ \int_a^b f_n dt \right\}$ converges.

uniformly to $\int_a^x f dt$ on $[a, b]$ i.e.

$$\int_a^x f dt = \lim_{n \rightarrow \infty} \int_a^x f_n dt \quad \forall x \in [a, b]$$

(B) If a series $\sum f_n$ converges uniformly to f on $[a, b]$ and each term $f_n(x)$ is integrable then f is integrable on $[a, b]$ and the series

$\sum \left(\int_a^x f_n dt \right)$ converges uniformly to

$\int_a^x f dt$ on $[a, b]$ i.e.

$$\int_a^x f dt = \sum_{n=1}^{\infty} \left(\int_a^x f_n dt \right), \quad \forall x \in [a, b]$$

\therefore from the above theorem the sequence $\{f_n\}$ cannot converge uniformly on $[0, 1]$.

4(a) In the ring $\mathbb{Z}[i]$, show that $I = \{a+bi \in \mathbb{Z}[i] \mid a, b \text{ are both even}\}$ is an ideal of $\mathbb{Z}[i]$, but not a maximal ideal of $\mathbb{Z}[i]$.

Solⁿ: Let $x = a+bi, y = c+di \in I$ and $u = r+si \in \mathbb{Z}[i]$.

Then exist $r_1, r_2, r_3, r_4 \in \mathbb{Z}$ such that

$$a = 2r_1, b = 2r_2, c = 2r_3, d = 2r_4$$

$$\begin{aligned} \text{Then } x-y &= (a+ib) - (c+id) = (a-c) + (b-d)i \\ &= 2(r_1-r_3) + 2(r_2-r_4)i \in I \end{aligned}$$

$$\begin{aligned} \text{and } ux &= (r+si)(a+bi) = (ra-sb) + (rb+sa)i \\ &= 2(r_1r_1 - r_2r_2) + 2(r_1r_2 + r_2r_1)i \in I \end{aligned}$$

Since $\mathbb{Z}[i]$ is a commutative ring, it follows that I is an ideal of $\mathbb{Z}[i]$.

Let $J = \{a+bi \in \mathbb{Z}[i] \mid 2 \text{ divides } a^2+b^2\}$.

Since $0+0i \in J$, $J \neq \emptyset$.

Let $x = a+ib, y = c+id \in J$ and $u = r+si \in \mathbb{Z}[i]$.

Then $2 \mid a^2+b^2$ and $2 \mid c^2+d^2$.

$$\text{Now } x-y = (a-c) + (b-d)i$$

$$\text{Since } (a-c)^2 + (b-d)^2 = a^2 + b^2 + c^2 + d^2 - 2(ac+bd),$$

it follows that $2 \mid (a-c)^2 + (b-d)^2$.

$$\text{Again } ux = (r+si)(a+bi) = (ra-sb) + (rb+sa)i$$

$$\text{and } (ra-sb)^2 + (rb+sa)^2 = r^2(a^2+b^2) + s^2(c^2+d^2)$$

Hence $2 \mid (ra-sb)^2 + (rb+sa)^2$ implies that

$$ux = xu \in J.$$

Consequently J is an ideal.

Now $1+2i \in \mathbb{Z}[i]$, but $1+2i \notin J$.

Hence $J \neq \mathbb{Z}[i]$.

Again $1+i \in J$ but $1+i \notin I$.

Hence we find that $I \subset J \subset \mathbb{Z}[i]$.

Consequently, I is not a maximal ideal.

4(b) → Prove that the function f defined by $f(x) = \sin \frac{1}{x} \forall x > 0$ is continuous but not uniformly continuous on \mathbb{R}^+ .

Solⁿ: let 'a' be any arbitrary +ve real number

$$\therefore f(a) = \sin \frac{1}{a} \forall a \in \mathbb{R}^+ \quad \text{--- (1)}$$

$$\text{Now } \lim_{x \rightarrow a^-} f(x) = \lim_{x \rightarrow a^-} \sin \frac{1}{x}$$

$$\text{put } x = a - h, h > 0$$

$$\begin{aligned} \lim_{x \rightarrow a^-} f(x) &= \lim_{h \rightarrow 0^+} \sin \frac{1}{a-h} \\ &= \sin \frac{1}{a} \quad \text{--- (2)} \end{aligned}$$

Similarly

$$\lim_{x \rightarrow a^+} f(x) = \lim_{x \rightarrow a^+} \sin \frac{1}{x}$$

$$\text{put } x = a + h, h > 0$$

$$\begin{aligned} \therefore \lim_{x \rightarrow a^+} f(x) &= \lim_{h \rightarrow 0^+} \sin \frac{1}{a+h} \\ &= \sin \frac{1}{a} \quad \text{--- (3)} \end{aligned}$$

\therefore from (1), (2) and (3)

$$\lim_{x \rightarrow a^+} f(x) = f(a) = \lim_{x \rightarrow a^-} f(x)$$

$\therefore f$ is continuous at 'a'

Since 'a' is arbitrary & $a \in \mathbb{R}^+$, f is continuous on \mathbb{R}^+
Now, let $\epsilon > 0$, we shall show that for each $\delta > 0$

$\exists x_1, x_2 \in \mathbb{R}^+$ such that

$$|x_1 - x_2| < \delta \Rightarrow |f(x_1) - f(x_2)| \geq \epsilon$$

Consider for any $\delta > 0 \exists m \in \mathbb{N}$ such that

$$\frac{1}{2n(n\pi + \pi/2)} < \delta \quad \forall n \geq m$$

Take $x_1 = \frac{1}{m\pi + \pi/2}$ and $x_2 = \frac{1}{m\pi}$

$\therefore x_1, x_2 \in \mathbb{R}^+$ and

$$|x_1 - x_2| = \left| \frac{1}{m\pi + \pi/2} - \frac{1}{m\pi} \right| = \left| \frac{-\pi/2}{m\pi(m\pi + \pi/2)} \right|$$

$$= \frac{1}{2m(m\pi + \pi/2)} < \delta$$

But $|f(x_1) - f(x_2)| = |\sin(m\pi + \pi/2) - \sin m\pi|$

$$= |\cos m\pi - 0|$$

$$= |(-1)^m| = 1$$

which is not less than each $\epsilon > 0$
Hence, f is not uniformly continuous on \mathbb{R}^+

4(d) Obtain the dual of the LP Problem.

$$\min z = x_1 + x_2 + x_3$$

Subject to the constraints: $x_1 - 3x_2 + 4x_3 = 5,$

$$x_1 - 2x_2 \leq 3$$

$$2x_2 - x_3 \geq 4$$

$x_1, x_2 \geq 0$, and x_3 is unrestricted.

Solⁿ. Since the problem is of minimization type all constraints should be of (\geq) type. Multiply the second constraint throughout by -1 , so that $-x_1 + 2x_2 \geq -3$, and we write the first equality constraint in the form of two inequalities of \geq type.

∴ The given problem can be written as

$$\text{Minimize } Z = x_1 + x_2 + x_3$$

Subject to

$$\left. \begin{aligned} x_1 - 3x_2 + 4x_3 &\geq 5 \\ -x_1 + 3x_2 - 4x_3 &\geq -5 \\ -x_1 + 2x_2 &\geq -3 \\ 2x_2 - x_3 &\geq 4 \end{aligned} \right\} \quad \text{--- (1)}$$

$$x_1, x_2 \geq 0, \quad x_3 \text{ is unrestricted.}$$

Since x_3 is unrestricted

$$\text{put } x_3 = x_3' - x_3''$$

The equation (1) can be written as

$$\text{Min } Z = x_1 + x_2 + x_3' - x_3''$$

Subject to

$$\left. \begin{aligned} x_1 - 3x_2 + 4x_3' - 4x_3'' &\geq 5 \\ -x_1 + 3x_2 - 4x_3' + 4x_3'' &\geq -5 \\ -x_1 + 2x_2 &\geq -3 \\ 2x_3' - x_3'' &\geq 4 \end{aligned} \right\}$$

$$x_1, x_2, x_3', x_3'' \geq 0.$$

Let y_1, y_2, y_3 and y_4 be the dual variables associated with the above 4 constraints.

Then the dual is given by

$$\text{Maximize } W = 5y_1 - 5y_2 - 3y_3 + 4y_4$$

Subject to

$$y_1 - y_2 - y_3 + 0y_4 \leq 1$$

$$-3y_1 + 3y_2 + 2y_3 + 2y_4 \leq 1$$

$$4y_1 - 4y_2 - y_4 \leq 1$$

$$-4y_1 + 4y_2 + y_4 \leq -1$$

$$y_i \geq 0.$$

This dual can be written in more compact form as:

$$\text{Max } W = 5y_1 - 3y_3 + 4y_4$$

Subject to

$$y_1 - y_3 \leq 1$$

$$-3y_1 + 2y_3 + 2y_4 \leq 1$$

$$4y_1 - y_4 \leq 1$$

$$-4y_1 + y_4 \leq -1$$

$$y_1, y_3, y_4 \geq 0 \text{ and } y_2 (= y_1 - y_3) \text{ unrestricted}$$

(or)

$$\text{Max } W = 5y_1 - 3y_3 + 4y_4$$

subject to.

$$y_1 - y_3 \leq 1$$

$$-3y_1 + 2y_3 + 2y_4 \leq 1$$

$$4y_1 - y_4 \leq 1$$

$$y_3, y_4 \geq 0 \text{ and } y_1 \text{ is unrestricted.}$$

40

$$f^+(a) = \frac{1}{\pi i} \int_C P(\theta) e^{-i\theta} d\theta, \text{ where } P(\theta) \text{ real part of } (a + re^{i\theta})$$

Hence $f(z)$ can be expanded in a Taylor's Series within the circle $|z-a|=8$

i.e. $f(z) = \sum_0^{\infty} a_m (z-\alpha)^m$

$$= \sum_m a_m x^m (e^{i\theta})^m$$

So that $\overline{f(z)} = \sum_{m=0}^{\infty} \bar{a}_m z^m (e^{i\theta})^m$

Now, consider the integral $\int_C \frac{\overline{f(z)} dz}{(z-a)^{n+1}}$

$$\int_C \sqrt{z} \cdot \frac{dz}{(z-a)^{n+1}} = \int_0^{2\pi} \sum_{n=0}^{\infty} \bar{a}_n r^n e^{-in\theta} \frac{r^{1/2} e^{i\theta/2} i r d\theta}{2^{n+1/2} e^{i(n+1)\theta}}$$

$$\frac{d}{dx} \left(\frac{1}{x^m} \right) = -\frac{m}{x^{m+1}} \quad \int_0^{\infty} x^{-m-1} e^{-x} dx = 0 \text{ for all values of } m$$

Particularly $\int \frac{dz}{f(z) (z-a)^2} = 0 \quad \text{--- (1)}$

we know that $f'(a) = \frac{1}{2\pi i} \int_C \frac{f(z) dz}{(z-a)^2}$

$$= \frac{1}{2\pi i} \int_C \frac{f(z) + \overline{f(z)}}{(z-0)^2} dz \quad \text{from (1)}$$

$$= \frac{1}{2\pi i} \int_{\gamma} \frac{f(z+re^{i\theta}) + f(z+re^{i\theta})}{z^2 - a^2} re^{i\theta} d\theta$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{2 \operatorname{Re} f(a + re^{i\theta})}{r^2 e^{2i\theta}} r e^{i\theta} d\theta$$

$$= \frac{1}{\pi i} \int_0^{2\pi} P(e^{it}) e^{-it} dt \quad [\text{Since } P(z) = \operatorname{Re} f(z + \pi i)]$$

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5(a) → Find the integral surface of the linear partial differential equation $x(y^2+z)p - y(x^2+z)q = (x^2-y^2)z$ which contains the straight line $x+y=0, z=1$.

Sol

Given $x(y^2+z)p - y(x^2+z)q = (x^2-y^2)z$

Lagrange's equation $Pp + Qq = R \Rightarrow \frac{dx}{P} = \frac{dy}{Q} = \frac{dz}{R}$

$$\frac{dx}{x(y^2+z)} = \frac{dy}{-y(x^2+z)} = \frac{dz}{(x^2-y^2)z}$$

$$\Rightarrow \frac{\frac{dx}{x} + \frac{dy}{y} + \frac{dz}{z}}{y^2+z - (x^2+z) + x^2-y^2} = \frac{\frac{dx}{x} + \frac{dy}{y} + \frac{dz}{z}}{0}$$

$$\therefore \frac{dx}{x} + \frac{dy}{y} + \frac{dz}{z} = 0$$

Integrating $\ln(xyz) = C$
 $xyz = C_1 \quad \text{--- (1)}$

$$\frac{x dx + y dy}{x^2(y^2+z) - y^2(x^2+z)} = \frac{dz}{(x^2-y^2)z}$$

$$x dx + y dy = dz$$

$$\Rightarrow x^2 + y^2 = 2z + C_2 \quad \text{--- (2)}$$

Given $x+y=0, z=1 \quad \text{--- (3)}$

from (1) $xyz = C_1$

from (2) $2x^2 = 2 + C_2 \Rightarrow 2C_1 + C_2 + 2 = 0$

$$\boxed{2xyz + x^2 + y^2 - 2z + 2 = 0} \quad \text{Integral Surface}$$

5(b) Find the complete integral $z(p, q) = x - y$

Sol

Rewriting $\left(\sqrt{2} \frac{\partial z}{\partial x}\right)^2 - \left(\sqrt{2} \frac{\partial z}{\partial y}\right)^2 = x - y$

Let $\sqrt{2} dz = dZ \Rightarrow \frac{2}{3} Z^{3/2} = z \quad \text{--- (1)}$

$p = \frac{\partial z}{\partial x} \quad q = \frac{\partial z}{\partial y}$

$\therefore p^2 - q^2 = x - y$

$p^2 - x = q^2 - y$

Let $p^2 - x = a \quad ; \quad q^2 - y = a$

$p = (x+a)^{1/2} \quad q = (y+a)^{1/2}$

$\therefore dz = p dx + q dy$

$dz = (x+a)^{1/2} dx + (y+a)^{1/2} dy$

$z = \frac{2}{3} (x+a)^{3/2} + \frac{2}{3} (y+a)^{3/2} + b$

from (1) $\frac{2}{3} z^{3/2} = \frac{2}{3} (x+a)^{3/2} + \frac{2}{3} (y+a)^{3/2} + b$

$\therefore z = (x+a)^{3/2} + (y+a)^{3/2} + b$

a, b are arbitrary constants

5(c)

Compute the integral

$$I = \sqrt{\frac{2}{\pi}} \int_0^1 e^{-x^2/2} dx.$$

using Simpson's $\frac{1}{3}$ rule, taking $h = 0.125$.

Solⁿ Given that $f(x) = \sqrt{\frac{2}{\pi}} e^{-x^2/2}$
 $a = 0, b = 1$

x	0	0.125	0.250	0.375	0.5	0.625	0.750	0.875	1.0
$y = f(x)$ $\sqrt{\frac{2}{\pi}} e^{-x^2/2}$	0.7979	0.7917	0.7733	0.7437	0.7041	0.6563	0.6023	0.5441	0.4835
	y_0	y_1	y_2	y_3	y_4	y_5	y_6	y_7	y_8

By using Simpson's $\frac{1}{3}$ rule, we have

$$\begin{aligned}
 \sqrt{\frac{2}{\pi}} \int_0^1 e^{-x^2/2} dx &= \frac{h}{3} \left[y_0 + y_8 + 4(y_1 + y_3 + y_5 + y_7) \right. \\
 &\quad \left. + 2(y_2 + y_4 + y_6) \right] \\
 &= \frac{0.125}{3} \left[0.7979 + 0.4835 \right. \\
 &\quad \left. + 4(0.7917 + 0.7437 + 0.6563 + 0.5441) \right. \\
 &\quad \left. + 2(0.7733 + 0.7041 + 0.6023) \right] \\
 &= \frac{0.125}{3} (1.2818 + 10.9432 + 4.1594) \\
 &= 0.6827
 \end{aligned}$$

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5(d) → Give a Boolean expression for the following statements.

(i) Y is a 1 only if A is a 1 and B is a 1 or A is a 0 and B is a 0.

(ii) Y is a 1 only if A, B and C are all 1s or if only one of the variables is a 0.

Solⁿ: (i) Truth table for given conditions.

A	B	Y
0	0	1
0	1	0
1	0	0
1	1	1

$$Y = A'B' + AB$$

(ii)

A	B	C	Y
0	0	0	0
0	0	1	0
0	1	0	0
0	1	1	1
1	0	0	0
1	0	1	1
1	1	0	1
1	1	1	1

$$Y = A'BC' + AB'C + ABC' + ABC$$

Simplify the expression

$$= A'BC + ABC' + AB'C + ABC + A'BC' + ABC$$

$$= BC(A' + A) + AC(B' + B) + A(C' + C) = BC + AC + AB$$

$$\therefore Y = BC + AC + AB$$

5(e)

If the velocity potential of a fluid is $\phi = (z/r^2) \tan^{-1}(y/x)$ where $r^2 = x^2 + y^2 + z^2$, then show that the streamlines lies on the surface $x^2 + y^2 + z^2 = c(x^2 + y^2)^{2/3}$, c being an arbitrary constant.

Soln

The velocity potential ϕ is given by
 $\phi(x, y, z) = (x^2 + y^2 + z^2)^{-3/2} z \tan^{-1}(y/x)$
 $= r^{-3} z \tan^{-1}(y/x) \quad \text{--- (1)}$

where $r^2 = x^2 + y^2 + z^2 \quad \text{--- (2)}$

so that $\frac{\partial r}{\partial x} = \frac{x}{r}$, $\frac{\partial r}{\partial y} = \frac{y}{r}$, $\frac{\partial r}{\partial z} = \frac{z}{r} \quad \text{--- (3)}$

$$u = -\frac{\partial \phi}{\partial x} = 3zxr^{-5} \tan^{-1} \frac{y}{x} + \frac{zyr^{-3}}{x^2 + y^2}$$

$$v = -\frac{\partial \phi}{\partial y} = 3zyr^{-5} \tan^{-1} \frac{y}{x} - \frac{zxr^{-3}}{x^2 + y^2}$$

$$w = -\frac{\partial \phi}{\partial z} = 3z^2r^{-5} \tan^{-1} \frac{y}{x} - r^{-3} \tan^{-1} \frac{y}{x}$$

The equation of line flow are given by

$$\frac{dx}{u} = \frac{dy}{v} = \frac{dz}{w}$$

$$\begin{aligned} \text{i.e. } \frac{dx}{3zxr^{-5} \tan^{-1} \frac{y}{x} + \frac{zyr^{-3}}{x^2 + y^2}} &= \frac{dy}{3zyr^{-5} \tan^{-1} \frac{y}{x} - \frac{zxr^{-3}}{x^2 + y^2}} \\ &= \frac{dz}{(3z^2r^{-5} - r^{-3}) \tan^{-1} \frac{y}{x}} \end{aligned} \quad \text{--- (4)}$$

each member of equation (4) is

$$= \frac{x dx + y dy + z dz}{(3x^2 + 3y^2 + 3z^2)^{1/2}} = \frac{x dx + y dy}{(3x^2 + 3y^2)^{1/2}}$$

$$\text{or, } \frac{x dx + y dy + z dz}{2} = \frac{z^2 (x dx + y dy)}{3(x^2 + y^2)}$$

$$\text{or, } \frac{2x dx + 2y dy + 2z dz}{x^2 + y^2 + z^2} = \frac{2}{3} \frac{2x dx + 2y dy}{x^2 + y^2} \quad \text{--- (5)}$$

Integrating (5)

$$\log(x^2 + y^2 + z^2) = \left(\frac{2}{3}\right) \log(x^2 + y^2) + \log c$$

$$\text{or, } x^2 + y^2 + z^2 = c (x^2 + y^2)^{2/3}, \text{ c being an arbitrary constant} \quad \text{--- (6)}$$

(6) gives the required series of the surface.

==

6(a) → Find a Partial differential equation by eliminating a, b, c from $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$.

Soln: Given that $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$ ——— (1)

Differentiating (1) w.r.t x and y , we get-

$$\frac{2x}{a^2} + \frac{2z}{c^2} \frac{dz}{dx} = 0 \Rightarrow c^2 x + a^2 z \frac{dz}{dx} = 0 \text{ ——— (2)}$$

and $\frac{2y}{b^2} + \frac{2z}{c^2} \frac{dz}{dy} = 0 \Rightarrow c^2 y + b^2 z \frac{dz}{dy} = 0$ ——— (3)

Differentiating (2) w.r.t x and (3) w.r.t y , we have

$$c^2 + a^2 \left(\frac{dz}{dx} \right)^2 + a^2 z \frac{d^2 z}{dx^2} = 0 \text{ ——— (4)}$$

$$\& c^2 + b^2 \left(\frac{dz}{dy} \right)^2 + b^2 z \frac{d^2 z}{dy^2} = 0 \text{ ——— (5)}$$

-from (2), $c^2 = -\frac{a^2 z}{x} \left(\frac{dz}{dx} \right)$

Putting this value of c^2 in (4) and dividing by a^2 , we obtain $-\frac{z}{x} \frac{dz}{dx} + \left(\frac{dz}{dx} \right)^2 + z \frac{d^2 z}{dx^2} = 0$ ——— (6)

Similarly, from (3) & (5)

$$zy \frac{d^2 z}{dy^2} + y \left(\frac{dz}{dy} \right)^2 - z \frac{dz}{dy} = 0 \text{ ——— (7)}$$

Differentiating (2) partially w.r.t y , we get

$$a^2 \left\{ \left(\frac{dz}{dy} \right) \left(\frac{dz}{dx} \right) + z \frac{d^2 z}{dx dy} \right\} = 0$$

i.e. $\frac{dz}{dx} \frac{dz}{dy} + z \frac{d^2 z}{dx dy} = 0$ ——— (8)

∴ (6), (7) and (8) are three possible forms of the required Partial differential equation.

$$6(b) \rightarrow (D_x^3 - 7D_x D_y - 6D_y^3)z = \sin(x+2y) + e^{3x+y}$$

sol

Auxiliary equation $m^3 - 7m - 6 = 0$

$$(m+2)(m-3)(m+1) = 0$$

$$m = -1, -2, 3$$

$$\therefore C.F. = \phi_1(y-x) + \phi_2(y-2x) + \phi_3(y+3x)$$

$$\text{Particular Integral} = \frac{\sin(x+2y) + e^{3x+y}}{(D_x+2D_y)(D_x-3D_y)(D_x+D_y)}$$

$$\frac{\sin(x+2y)}{D_x^3 - 7D_x D_y - 6D_y^3} = \frac{1}{1^3 - 7(1)(2) - 6(2)^3} \iiint \sin v \, dv \, dv \, dv \quad v = x+2y$$

$$= \frac{-1/25 \cos(x+2y)}{1}$$

$$\frac{e^{3x+y}}{(D_x+2D_y)(D_x-3D_y)(D_x+D_y)} = \frac{1}{(D_x-3D_y)} \left[\frac{1}{(3+2)(3+1)} \int e^v \, dv \, dv \right] \quad v = 3x+y$$

$$= \frac{1}{20} \frac{e^{3x+y}}{D_x-3D_y}$$

$$= \frac{1}{20} \frac{x \cdot e^{(3x+y)}}{1-1}$$

$$= \frac{x}{20} e^{3x+y}$$

$$\therefore y = C.F. + P.I. = \phi_1(y-x) + \phi_2(y-2x) + \phi_3(y+3x) - \frac{1}{25} \cos(x+2y) + \frac{x}{20} e^{3x+y}$$

6(c) Reduce $\frac{\partial^2 z}{\partial x^2} = (1+y)^2 \frac{\partial^2 z}{\partial y^2}$ to canonical form.

Sol Comparing with $Rx + S_1 + T_1 + f(x, y, z, p, q) = 0$

here $R=1$ $S=0$ and $T = -(1+y)^2$

$S^2 - 4RT = (1+y)^2 > 0$ hyperbolic

Quadratic reduces to $\lambda^2 - (1+y)^2 = 0$

$\lambda = 1+y, -(1+y)$

Corresponding characteristic equations are

$$\frac{dy}{dx} + 1+y = 0 \quad \frac{dy}{dx} - (1+y) = 0$$

$$\ln(1+y) + x = C_1 \quad \ln(1+y) - x = C_2$$

$$u = \ln(1+y) + x$$

$$v = \ln(1+y) - x$$

$$p = \frac{\partial z}{\partial x} = \frac{\partial z}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial z}{\partial v} \frac{\partial v}{\partial x} = \frac{\partial z}{\partial u} - \frac{\partial z}{\partial v}$$

$$q = \frac{\partial z}{\partial y} = \frac{\partial z}{\partial u} \frac{\partial u}{\partial y} + \frac{\partial z}{\partial v} \frac{\partial v}{\partial y} = \frac{1}{1+y} \left(\frac{\partial z}{\partial u} + \frac{\partial z}{\partial v} \right)$$

$$\begin{aligned} r = \frac{\partial^2 z}{\partial x^2} &= \frac{\partial}{\partial x} \left(\frac{\partial z}{\partial x} \right) = \frac{\partial}{\partial x} \left(\frac{\partial z}{\partial u} - \frac{\partial z}{\partial v} \right) \\ &= \frac{\partial^2 z}{\partial u^2} - 2 \frac{\partial^2 z}{\partial u \partial v} + \frac{\partial^2 z}{\partial v^2} \end{aligned} \quad - (2)$$

$$\begin{aligned} t = \frac{\partial^2 z}{\partial y^2} &= \frac{\partial}{\partial y} \left(\frac{\partial z}{\partial y} \right) = \frac{\partial}{\partial y} \left(\frac{1}{1+y} \left(\frac{\partial z}{\partial u} + \frac{\partial z}{\partial v} \right) \right) \\ &= -\frac{1}{(1+y)^2} \left(\frac{\partial z}{\partial u} + \frac{\partial z}{\partial v} \right) + \frac{1}{(1+y)} \frac{\partial}{\partial y} \left(\frac{\partial z}{\partial u} + \frac{\partial z}{\partial v} \right) \\ &= -\frac{1}{(1+y)^2} \left(\frac{\partial z}{\partial u} + \frac{\partial z}{\partial v} \right) + \frac{1}{(1+y)^2} \left(\frac{\partial^2 z}{\partial u^2} + 2 \frac{\partial^2 z}{\partial u \partial v} + \frac{\partial^2 z}{\partial v^2} \right) \end{aligned}$$

from ①, ② and ③

$$\left(\frac{\partial^2 z}{\partial u^2} - 2 \frac{\partial^2 z}{\partial u \partial v} + \frac{\partial^2 z}{\partial v^2} \right) = \frac{(1+y)^2}{(1+y)^2} \left(\frac{\partial^2 z}{\partial u^2} + \frac{\partial^2 z}{\partial v^2} + \frac{2 \partial^2 z}{\partial u \partial v} - \frac{\partial z}{\partial u} - \frac{\partial z}{\partial v} \right) = 0$$

$$\boxed{4 \frac{\partial^2 z}{\partial u \partial v} = \frac{\partial z}{\partial u} + \frac{\partial z}{\partial v}} \quad \text{Required Canonical form.}$$

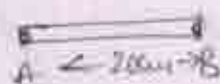
6(d) → The ends A and B of a rod 20cm long have the temperatures at 30° and 80° until steady state prevails. The temperatures of the ends are changed to 40° and 60° respectively. Find the temperature distribution in the rod at time t .

Solⁿ: Let the equation for conduction of heat is $\frac{du}{dt} = k \frac{d^2u}{dx^2}$ — (1)

Prior to temperature change at the end B when $t=0$, the heat flow was independent of time (steady state condition, for which $\frac{du}{dt}=0$) when u depends only on x , (1) reduces to

$$\frac{d^2u}{dx^2} = 0 \Rightarrow u = C_1x + C_2 \text{ — (2)}$$

Given that $u = 30$ for $x = 0$
 and $u = 80$ for $x = 20\text{cm}$ } — (3).



by using (3) ✓

(2) becomes $u = \frac{5}{2}x + 30$

∴ The initial condition is given by

$$u(x, 0) = \frac{5}{2}x + 30 \text{ — (4)}$$

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Given that the boundary conditions are

$$u(0, t) = 40 \quad \forall t \quad \text{--- (5)}$$

$$u(20, t) = 60 \quad \forall t \quad \text{--- (6)}$$

Now the boundary values are non-zero, so we modify the procedure as follows.

We split the temperature function $u(x, t)$ into two parts as

$$u(x, t) = u_1(x) + u_2(x, t) \quad \text{--- (7)}$$

where $u_1(x)$ is a solution of (1) involving x only and satisfying the boundary conditions (5) and (6)

$u_2(x, t)$ is then a function defined by (7). Hence $u_1(x)$ is a steady state solution of the form (2) and $u_2(x, t)$ may be treated as a transient part of the solution, which decreases with increase of t .

Since $u_1(x) = 40$ for $x=0$ & $u_1(x) = 60$ for $x=20$

Using (2), we get $u_1(x) = x + 40$ (8)

$$\begin{aligned} u_1 &= C_1 x + C_2 \\ \therefore 40 &= C_1(0) + C_2 \\ &= C_2 = 40 \\ \& \ 60 &= C_1(20) + 40 \\ \Rightarrow C_1 &= 1 \\ u_1(x) &= x + 40 \end{aligned}$$

Putting $x=0$ in (7) and using (8), we get

$$u_2(0, t) = u(0, t) - u_1(0) = 40 - 40 = 0 \quad \text{--- (9)}$$

Putting $x=20$ in (7) and using (8), we get

$$u_2(20, t) = u(20, t) - u_1(20) = 60 - 60 = 0 \quad \text{--- (10)}$$

$$\begin{aligned} \text{Also, } u_2(x, 0) &= u(x, 0) - u_1(x) \\ &= \frac{5}{2}x + 30 - (x + 40) \\ u_2(x, 0) &= \frac{3}{2}x - 10 \quad \text{--- (11)} \end{aligned}$$

Hence the boundary conditions and initial condition to the transient solution $u_2(x, t)$ are given by (9), (10) and (11).

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So we now solve $\frac{\partial u_2}{\partial t} = k \frac{\partial^2 u_2}{\partial x^2}$ — (12)

Subject to boundary conditions (9) & (10) and initial condition (11).

Now taking $u_2(x, t) = X(x)T(t)$

∴ From (12), we have $X''T' = k X''T$

$\Rightarrow \frac{X''}{X} = \frac{T'}{kT} = \mu$ (say)

$\Rightarrow X'' - \mu X = 0$ & $T' = \mu kT$ — (13) — (14)

Using (9) & (11), (13) gives

$X(0)T(t) = 0$ & $X(20)T(t) = 0$ — (15)

$\Rightarrow X(0) = 0$ & $X(20) = 0$ (∵ $T(t) \neq 0$ otherwise leads to $u=0$)

we now solve (13) under B.C (15).

Three cases arise:

Case (1) Let $\mu = 0$, the solution of (13) is $X(x) = Ax + B$

Using B.C. (15), we get $A = B = 0$

∴ $X(x) = 0$ so that $u = 0$ which doesn't satisfy (11)

So we reject $\mu = 0$.

Case (2) : Let $\mu = \lambda^2$, $\lambda \neq 0$. Then $X(x) = Ae^{\lambda x} + Be^{-\lambda x}$.

Using B.C. (15), we get

$A = B = 0$ since

$X(x) = 0$ and hence $u = 0$

which doesn't satisfy (11).

So we reject $\mu = \lambda^2$.

Case (3) : Let $\mu = -\lambda^2$, $\lambda \neq 0$. Then $X(x) = A \cos \lambda x + B \sin \lambda x$.

Using B.C. (15), we get

$A = 0$ & $A \cos 20\lambda + B \sin 20\lambda = 0$

$\Rightarrow B \sin 20\lambda = 0$

$\Rightarrow \sin 20\lambda = 0$ ($B \neq 0$)

$\Rightarrow 20\lambda = n\pi$, $n = 1, 2, \dots$

$$\Rightarrow \lambda = \frac{n\pi}{20}, n=1,2,\dots \quad \text{--- (16)}$$

Hence non-zero solutions $X_n(x)$ of (13) are given

$$\text{by } X_n(x) = B_n \sin\left(\frac{n\pi x}{20}\right).$$

$$\text{Using (16), (14) gives } \frac{dT}{T} = -\frac{n^2 \pi^2 k}{400} dt$$

$$\Rightarrow T_n(t) = C_n e^{-\frac{n^2 \pi^2 k t}{400}} \quad \left(\because \mu = -\lambda^2 c = -\frac{n^2 \pi^2}{400} \right)$$

$$\therefore u_2(x,t) = \sum_{n=1}^{\infty} C_n(x,t) = \sum_{n=1}^{\infty} D_n \sin\left(\frac{n\pi x}{20}\right) e^{-\frac{n^2 \pi^2 k t}{400}}$$

$$\text{where } D_n = B_n C_n.$$

$$\text{where } D_n = \frac{2}{20} \int_0^{20} \left(\frac{3x}{2} - 10\right) \sin \frac{n\pi x}{20} dx$$

$$= \frac{1}{10} \left[\left(\frac{3x}{2} - 10\right) \left(-\cos \frac{n\pi x}{20}\right) \frac{20}{n\pi} + \frac{3}{2} \sin \frac{n\pi x}{20} \cdot \left(\frac{20}{n\pi}\right)^2 \right]$$

$$= \frac{1}{10} \left[\frac{20}{n\pi} \left[20 (-\cos n\pi) - 10 \right] + 0 \right]$$

$$= -\frac{20}{n\pi} [2 \cos n\pi + 1]$$

$$= -\frac{20}{n\pi} [2(-1)^n + 1]$$

$$\therefore u_2(x,t) = -\frac{20}{\pi} \sum_{n=1}^{\infty} \frac{[2(-1)^n + 1]}{n} \sin\left(\frac{n\pi x}{20}\right) e^{-\frac{n^2 \pi^2 k t}{400}} \quad \text{--- (17)}$$

\therefore from (8) & (17), (18) gives

$$u(x,t) = x + 40 - \frac{20}{\pi} \sum_{n=1}^{\infty} \frac{[2(-1)^n + 1]}{n} \sin \frac{n\pi x}{20} e^{-\frac{n^2 \pi^2 k t}{400}}$$

which is the required solution

(i) A NOR gate has three inputs A, B, C. which combination of inputs will give High output?

(ii) Implement the expression $Y = AB + CD$ using only NAND gates.

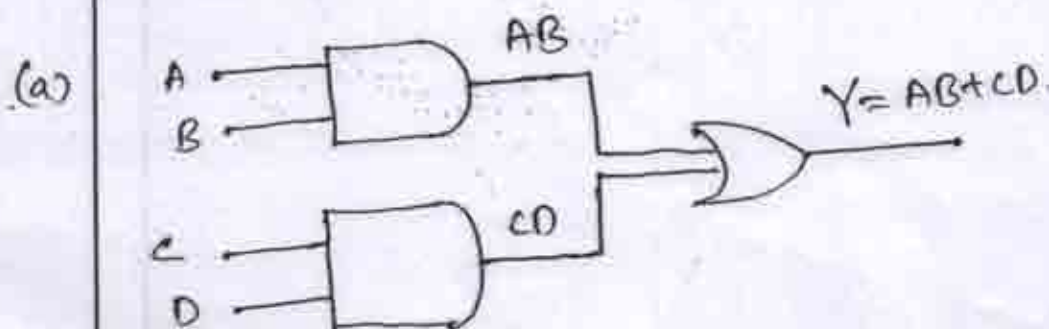
Soln: (i) Given that NOR gate has three inputs A, B, C
 i.e. $Y = 1 = \overline{A+B+C}$ For high output (Y) be 1

$$\text{Since } \overline{A+B+C} = 1$$

$$\Rightarrow A+B+C = 0$$

This is possible only if $A=B=C=0$.

(ii) The straight forward implementation uses two AND gates and one OR gate as shown in Fig. 4.51(a). Each AND gate can be replaced by a NAND gate and NOR gate in series. The OR gate can be also replaced by NAND gates. This is shown in Fig. 4.51(b). It is seen that NOR gates 1 and 2 are in series and can be eliminated (because $\overline{\overline{A}} = A$). Similarly NOR gates 3 and 4 are in series and can be eliminated. Thus we get the logic circuit shown in Fig. 4.51(c).



Hand-drawn logic diagram for the expression $Y = AB + CD$. The diagram shows two 2-input AND gates. The first AND gate has inputs A and B, and its output is AB . This output is connected to a NOT gate, which produces the complement \overline{AB} . The second AND gate has inputs C and D, and its output is CD . This output is connected to a NOT gate, which produces the complement \overline{CD} . The outputs of these two NOT gates, \overline{AB} and \overline{CD} , are connected to the inputs of a third 2-input AND gate. The output of this final AND gate is \overline{Y} . The expression $Y = AB + CD$ is written next to the output \overline{Y} .

Diagram illustrating the implementation of the Boolean expression $Y = AB + CD$ using two 2-input OR gates and two 2-input AND gates.

The inputs are A, B, C, and D. The first 2-input AND gate takes inputs A and B, producing output AB. The second 2-input AND gate takes inputs C and D, producing output CD. These two outputs, AB and CD, are connected to the inputs of a 2-input OR gate, which produces the final output Y.

The Boolean expression for the output is $Y = AB + CD$.

7(b) Find the solution of the following system of equations

$$x_1 - \frac{x_2}{4} - \frac{x_3}{4} = \frac{1}{2}$$

$$-\frac{x_1}{4} + x_2 - \frac{x_4}{4} = \frac{1}{2}$$

$$-\frac{x_1}{4} + x_2 - \frac{x_4}{4} = \frac{1}{4}$$

$$-\frac{x_2}{4} - \frac{x_3}{4} + x_4 = \frac{1}{4}$$

using Gauss-Seidel method and perform the first five iterations.

Soln: The given system of equations can be written as

$$\begin{aligned} x_1 &= 0.5 + 0.25x_2 + 0.25x_3 \\ x_2 &= 0.5 + 0.25x_1 + 0.25x_4 \\ x_3 &= 0.25 + 0.25x_1 + 0.25x_4 \\ x_4 &= 0.25 + 0.25x_2 + 0.25x_3 \end{aligned} \quad \rightarrow (1)$$

By Gauss-Seidel method, system (1) can be written as

$$\begin{aligned} x_1^{(k+1)} &= 0.5 + 0.25x_2^{(k)} + 0.25x_3^{(k)} \\ x_2^{(k+1)} &= 0.5 + 0.25x_1^{(k+1)} + 0.25x_4^{(k)} \\ x_3^{(k+1)} &= 0.25 + 0.25x_1^{(k+1)} + 0.25x_4^{(k)} \\ x_4^{(k+1)} &= 0.25 + 0.25x_2^{(k+1)} + 0.25x_3^{(k+1)} \end{aligned}$$

where $k = 0, 1, 2, 3, \dots$

Now taking $x^{(0)} = 0$ (i.e. $x_2^{(0)} = 0, x_3^{(0)} = 0, x_4^{(0)} = 0$)
 (which is the initial solution)

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$$K=0$$

$$x_1^{(1)} = 0.5 + 0.25 x_2^{(0)} + 0.25 x_3^{(0)} = 0.5 + 0 + 0 = 0.5$$

$$x_2^{(1)} = 0.5 + 0.25 x_1^{(1)} + 0.25 x_4^{(0)} = 0.5 + (0.25)(0.5) + 0 = 0.625$$

$$x_3^{(1)} = 0.25 + 0.25 x_1^{(1)} + 0.25 x_4^{(0)} = 0.25 + (0.25)(0.5) + (0.25)(0) = 0.375$$

$$x_4^{(1)} = 0.25 + 0.25 x_2^{(1)} + 0.25 x_3^{(1)} = 0.25 + (0.25)(0.625) + (0.25)(0.375) = 0.5$$

$$K=1$$

$$x_1^{(2)} = 0.5 + 0.25 x_2^{(1)} + 0.25 x_3^{(1)} = 0.5 + (0.25)(0.625) + (0.25)(0.375) = 0.75$$

$$x_2^{(2)} = 0.5 + 0.25 x_1^{(2)} + 0.25 x_4^{(1)} = 0.5 + (0.25)(0.75) + (0.25)(0.5) = 0.8125$$

$$x_3^{(2)} = 0.25 + 0.25 x_1^{(2)} + 0.25 x_4^{(1)} = 0.25 [1 + 0.75 + 0.5] = 0.5625$$

$$x_4^{(2)} = 0.25 + 0.25 x_2^{(2)} + 0.25 x_3^{(2)} = (0.25) [1 + 0.8125 + 0.5625] = 0.59375$$

$$K=2$$

$$x_1^{(3)} = 0.5 + 0.25 x_2^{(2)} + 0.25 x_3^{(2)} = 0.5 + (0.25)(0.8125) + (0.25)(0.5625) = 0.84375$$

$$x_2^{(3)} = 0.5 + 0.25 x_1^{(3)} + 0.25 x_4^{(2)} = 0.5 + (0.25)(0.84375) + (0.25)(0.59375) = 0.85938$$

$$x_3^{(3)} = 0.25 + 0.25 x_1^{(3)} + 0.25 x_4^{(2)} = 0.25 [1 + 0.84375 + 0.59375] = 0.60938$$

$$x_4^{(3)} = 0.25 + 0.25 x_2^{(3)} + 0.25 x_3^{(3)} = 0.25 [1 + 0.85938 + 0.60938] = 0.61719$$

$K=3$

$$\begin{aligned} x_1^{(4)} &= 0.5 + 0.25x_2^{(3)} + 0.25x_3^{(3)} = 0.5 + (0.25)(0.85928) + \\ &\quad (0.25)(0.60938) \\ &= 0.86719 \end{aligned}$$

$$x_2^{(4)} = 0.5 + 0.25x_1^{(4)} + 0.25x_4^{(3)} = 0.5 + 0.25(0.86719) + (0.25)(0.61719)$$

$$= 0.87110$$

$$x_3^{(4)} = 0.25 + 0.25x_1^{(4)} + 0.25x_4^{(3)} = 0.25 [1 + 0.46719 + 0.61719]$$

$$= 0.62110$$

$$\begin{aligned} x_4^{(4)} &= 0.25 + 0.25x_2^{(4)} + 0.25x_3^{(4)} = 0.25 [1 + 0.8711 + 0.6211] \\ &= 0.62305 \end{aligned}$$

 $K=4$

$$\begin{aligned} x_1^{(5)} &= 0.5 + 0.25x_2^{(4)} + 0.25x_3^{(4)} = 0.5 + (0.25)(0.8711) + (0.25)(0.6211) \\ &= 0.87305 \end{aligned}$$

$$\begin{aligned} x_2^{(5)} &= 0.5 + 0.25x_1^{(5)} + 0.25x_4^{(4)} = 0.5 + 0.25 \times 0.87305 + 0.25 \times 0.62305 \\ &= 0.87402 \end{aligned}$$

$$\begin{aligned} x_3^{(5)} &= 0.25 + 0.25x_1^{(5)} + 0.25x_4^{(4)} = 0.25 [1 + 0.87305 + 0.62305] \\ &= 0.62402 \end{aligned}$$

$$\begin{aligned} x_4^{(5)} &= 0.25 + 0.25x_2^{(5)} + 0.25x_3^{(5)} = 0.25 [1 + 0.87402 + 0.62402] \\ &= 0.62451 \end{aligned}$$

The solution is given by

$$x_1 = 0.87305; \quad x_2 = 0.87402$$

$$x_3 = 0.62402; \quad x_4 = 0.62451$$

7(c) → Using Runge-Kutta method of order 4, find y for $x=0.1, 0.2, 0.3$
 given that $dy/dx = xy + y^2$, $y(0)=1$.

Sol'n : Given that $f(x, y) = \frac{dy}{dx} = xy + y^2$; $y(0)=1$ ∴ ∴ ∴

To find $y(0.1)$

Here $x_0 = 0$, $y_0 = 1$, $h = 0.1$

$$K_1 = hf(x_0, y_0) = (0.1)f(0, 1) = 0.1$$

$$K_2 = hf\left(x_0 + \frac{h}{2}, y_0 + \frac{K_1}{2}\right) = (0.1)f(0.05, 1.05) = 0.1155$$

$$K_3 = hf\left(x_0 + \frac{h}{2}, y_0 + \frac{K_2}{2}\right) = (0.1)f(0.05, 1.0577) = 0.1172$$

$$K_4 = hf(x_0 + h, y_0 + K_3) = (0.1)f(0.1, 1.172) = 0.13598$$

$$\begin{aligned} K &= \frac{1}{6}(K_1 + 2K_2 + 2K_3 + K_4) \\ &= \frac{1}{6}(0.1 + 0.231 + 0.2343 + 0.13598) \\ &= 0.11687 \end{aligned}$$

$$\therefore y(0.1) = y_1 = y_0 + K = 1.1169$$

To find $y(0.2)$: Here $x_1 = 0.1$, $y_1 = 1.1169$, $h = 0.1$

$$K_1 = hf(x_1, y_1) = (0.1)f(0.1, 1.1169) = 0.1359$$

$$K_2 = hf\left(x_1 + \frac{h}{2}, y_1 + \frac{K_1}{2}\right) = (0.1)f(0.15, 1.1848) = 0.1581$$

$$K_3 = hf\left(x_1 + \frac{h}{2}, y_1 + \frac{K_2}{2}\right) = (0.1)f(0.15, 1.1959) = 0.1609$$

$$K_4 = hf(x_1 + h, y_1 + K_3) = (0.1)f(0.2, 1.2778) = 0.1888$$

$$K = \frac{1}{6}(K_1 + 2K_2 + 2K_3 + K_4) = 0.1605$$

$$y(0.2) = y_2 = y_1 + K = 1.2773$$

To find $y(0.3)$: Here $x_2 = 0.2$, $y_2 = 1.2773$, $h = 0.1$

$$K_1 = hf(x_2, y_2) = (0.1)f(0.2, 1.2773) = 0.1887$$

$$K_2 = hf\left(x_2 + \frac{h}{2}, y_2 + \frac{K_1}{2}\right) = (0.1)f(0.25, 1.3716) = 0.2224$$

$$K_3 = hf\left(x_2 + \frac{h}{2}, y_2 + \frac{K_2}{2}\right) = (0.1)f(0.25, 1.3885) = 0.2275$$

$$K_4 = hf(x_2 + h, y_2 + K_3) = (0.1)f(0.3, 1.5048) = 0.2267$$

$$K = \frac{1}{6}(K_1 + 2K_2 + 2K_3 + K_4) = 0.2267$$

$$\therefore y(0.3) = y_3 = y_2 + K = 1.504$$

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7(a) (i) Simplify the expression $A = XY + \bar{X}\bar{Z} + X\bar{Y}Z (XY + Z)$

(ii) Simplify the Boolean expression $Y = \overline{A \cdot B} + \overline{A} + B$. Prepare truth table to show that the simplified expression is correct.

Solⁿ: (i) $A = XY + \bar{X}\bar{Z} + X\bar{Y}Z (XY + Z)$

$$= XY + \bar{X}\bar{Z} + XX\bar{Y}YZ + X\bar{Y}ZZ$$

$$= XY + \bar{X}\bar{Z} + X\bar{Y}Z \quad (\because ZZ = Z \text{ and } Y\bar{Y} = 0)$$

$$= XY + \bar{X} + \bar{Z} + X\bar{Y}Z$$

$$= XY + \bar{Z} + \bar{X} + X\bar{Y}Z \quad (\text{by commutative law})$$

$$= XY + \bar{Z} + \bar{X} + \bar{Y}Z$$

$$= \bar{X} + Y + \bar{Z} + \bar{Y}$$

$$= 1$$

(ii) $Y = \overline{A \cdot B} + \overline{A} + B$

$$= \bar{A} + \bar{B} + \bar{A} + B$$

$$= \bar{A} + B$$

$$= \overline{A \cdot B}$$

(Using De Morgan's theorem)

A	B	$A \cdot B$	$\overline{A \cdot B}$	\bar{A}	$\bar{A} + B$	$\overline{A \cdot B}$	$\overline{A \cdot B} + \bar{A} + B$
0	0	0	1	1	1	1	1
0	1	0	1	1	1	1	1
1	0	0	1	0	0	1	1
1	1	1	0	0	1	0	0

turn through angles θ and ϕ respectively from the verticals, i.e. at time t B & D correspond to the point B_0 and D_0 at time $t=0$.

Since there is no slipping b/w sphere and cavity, therefore if P is their point of contact at time t , then,

$$\text{Arc AP} = \text{Arc PB} \quad \text{i.e. } a\theta = b(\theta + \phi)$$

$$\text{or } b\phi = (a-b)\theta = c\theta, \text{ where } a-b=c \text{ (say)}$$

$$\therefore b\phi = c\theta \quad \text{--- (1)}$$

Referred to the centre O as origin, horizontal and vertical lines OX and OY as axes, the coordinates (x_c, y_c) of C and (x_D, y_D) of D respectively are

$$x_c = c \sin \theta, \quad y_c = c \cos \theta$$

$$x_D = c \sin \theta + b \sin \phi, \quad y_D = c \cos \theta - b \cos \phi$$

$$\therefore \dot{v}_c^2 = \dot{x}_c^2 + \dot{y}_c^2 = (c \cos \theta \dot{\theta})^2 + (-c \sin \theta \dot{\theta})^2 = c^2 \dot{\theta}^2$$

$$\text{and } \dot{v}_D^2 = \dot{x}_D^2 + \dot{y}_D^2 = (c \cos \theta \dot{\theta} + b \cos \phi \dot{\phi})^2 + (-c \sin \theta \dot{\theta} + b \sin \phi \dot{\phi})^2$$

$$= c^2 \dot{\theta}^2 + b^2 \dot{\phi}^2 + 2bc \dot{\theta} \dot{\phi} \cos(\theta + \phi) = c^2 \dot{\theta}^2 + b^2 \dot{\phi}^2 + 2bc \dot{\theta} \dot{\phi}$$

$$(\because \theta \text{ and } \phi \text{ are small})$$

If T be the kinetic energy and W the work function of the system, then we have.

$$\begin{aligned}
 T &= \text{K.E. of the sphere} + \text{K.E. of the particle} \\
 &= \left[\frac{1}{2} m \cdot \frac{2}{3} b^2 \dot{\phi}^2 + \frac{1}{2} m v_c^2 \right] + \left[\frac{1}{2} m' v_D^2 \right] \\
 &= \frac{1}{2} m \left(\frac{2}{3} b^2 \dot{\phi}^2 + c^2 \dot{\theta}^2 \right) + \frac{1}{2} m' (c^2 \dot{\theta}^2 + b^2 \dot{\phi}^2 + 2bc\dot{\theta}\dot{\phi}) \\
 &= \frac{1}{2} m \left(\frac{2}{3} b^2 \dot{\phi}^2 + b^2 \dot{\phi}^2 \right) + \frac{1}{2} m' (b^2 \dot{\phi}^2 + b^2 \dot{\phi}^2 + 2b \cdot b \dot{\phi} \cdot \dot{\phi}) \\
 &= \frac{1}{10} b^2 (7m + 20m') \dot{\phi}^2 \quad (\text{using (1)})
 \end{aligned}$$

$$\begin{aligned}
 \text{and } W &= -mg(OC' - y_c) + m'g(y_D - OD_0) \\
 &= -mg(c - c \cos \theta) + m'g \{ c \cos \theta - b \cos \phi - (a - 2b) \} \\
 &= (m + m') cg \cos \theta - m' bg \cos \phi + c \\
 &= (m + m') cg \cos(b\phi/c) - m' bg \cos \phi + c \\
 &\quad (\because c\theta = b\phi)
 \end{aligned}$$

\therefore Lagrange's ϕ -equation is $\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{\phi}} \right) - \frac{\partial T}{\partial \phi} = \frac{\partial W}{\partial \phi}$

$$\text{i.e. } \frac{d}{dt} \left[\frac{1}{5} b^2 (7m + 20m') \dot{\phi} \right] - 0 = -(m + m') cg \cdot \frac{b}{c} \sin\left(\frac{b}{c}\phi\right) + m' bg \sin \phi$$

$$\text{or } \frac{1}{5} b^2 (7m + 20m') \ddot{\phi} = -(m + m') bg \cdot \frac{b}{c} \phi + m' bg \phi \quad (\because \phi \text{ is small})$$

$$\text{or } b \left(\frac{7}{5} m + 4m' \right) \ddot{\phi} = -\frac{g}{c} \left[(m + m') - \frac{c}{b} m' \right] \phi$$

$$\text{on } b \left(4m' + \frac{5}{7}m \right) \phi = -\frac{g}{b} \left[(m+m') - \frac{a-b}{b} m' \right]$$

$$[\because a=b]$$

$$\phi = -\frac{g}{b} \cdot \frac{m + (2-a/b)m'}{4m' + \frac{5}{7}m} \quad \phi = -\mu \phi(\text{say})$$

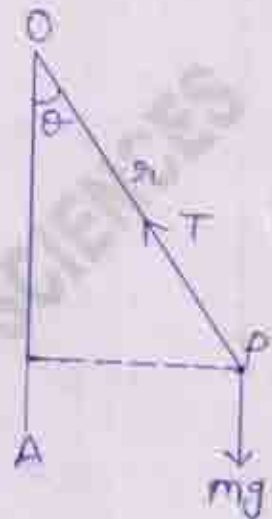
which represent S.H.M.

\therefore The length of simple equivalent pendulum is

$$\frac{g}{\mu} = (a-b) \frac{4m' + \frac{5}{7}m}{m + m' (2-a/b)}$$

Q(b) Use Hamilton's equations to write down the equations of motion of a pendulum bob suspended from a coil spring and allowed to swing in a vertical plane.

Soln At time t , let x be the stretched length of the spring of natural length x_0 . If θ is the inclination of the spring to the vertical at this time t , then the velocity of m at P is along and perpendicular to OP respectively.



$$\therefore \text{Velocity of } m \text{ at } P = \dot{x}^2 + (x\dot{\theta})^2$$

Thus if T and V are the kinetic and the potential energies of the system, at time t , then $T = \frac{1}{2} M (\dot{x}^2 + x^2 \dot{\theta}^2)$

and $V = \text{Workdone against the forces}$
 $= \text{Workdone against the force } Mg$
 $+ \text{workdone against the tension in the spring}$

$$= -Mg \cdot x \cos \theta \int_0^x \frac{(x-x_0)}{x_0} dx$$

$$\therefore \text{Tension} = \lambda \left(\frac{x-x_0}{x_0} \right)$$

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λ is the modulus of elasticity of the spring.

$$= -Mg \sin \theta + (k/2)(x_1 - x_{10})^2, \text{ where } K = (\lambda/x_{10})$$

$$\therefore L = T - V = \frac{1}{2} M (\dot{x}_1^2 + x_1^2 \dot{\theta}^2) + mgx_1 \cos \theta - (k/2)(x_1 - x_{10})^2$$

Hence x_1 and θ are the generalised coordinates.

$$\therefore p_{x_1} = \frac{\partial L}{\partial \dot{x}_1} = M \dot{x}_1 \text{ and } p_{\theta} = \frac{\partial L}{\partial \dot{\theta}} = M x_1^2 \dot{\theta} \quad \text{--- (1)}$$

Since L does not contain t explicitly.

$$\therefore H = T + V = \frac{1}{2} M (\dot{x}_1^2 + x_1^2 \dot{\theta}^2) - mgx_1 \cos \theta + (k/2)(x_1 - x_{10})^2$$

Substituting $\dot{x}_1 = p_{x_1}/M$ and $\dot{\theta} = p_{\theta}/(M x_1^2)$ from (1)

$$H = \left(\frac{1}{2M} \right) \left(p_{x_1}^2 + \frac{p_{\theta}^2}{x_1^2} \right) + mgx_1 \cos \theta + \left(\frac{k}{2} \right) (x_1 - x_{10})^2 \quad \text{--- (2)}$$

Hence the four Hamilton's equations are

$$\dot{p}_{x_1} = - \frac{\partial H}{\partial x_1} \text{ i.e. } \dot{p}_{x_1} = \frac{p_{\theta}^2}{m x_1^3} + mg \cos \theta - k(x_1 - x_{10}) \quad \text{--- (H}_1\text{)}$$

$$\dot{x}_1 = \frac{\partial H}{\partial p_{x_1}} \text{ i.e. } \dot{x}_1 = \frac{p_{x_1}}{M} \quad \text{--- (H}_2\text{)}$$

$$\dot{p}_{\theta} = - \frac{\partial H}{\partial \theta} \text{ i.e. } \dot{p}_{\theta} = -Mg x_1 \sin \theta \quad \text{--- (H}_3\text{)}$$

$$\text{and } \dot{\theta} = \frac{\partial H}{\partial p_{\theta}} = \frac{p_{\theta}}{Mg r^2} \quad (H_1)$$

Differentiating (H_2) , we have

$$\ddot{r} = \frac{1}{m} \dot{p}_r \quad \text{or } m\ddot{r} = \dot{p}_r = \frac{p_r^2}{Mr^3} + Mg \cos \theta - k(r-r_0)$$

[from (H_1)]

$$\therefore m\ddot{r} = \frac{(Mr^2\dot{\theta})^2}{Mr^3} + Mg \cos \theta - k(r-r_0)$$

(substituting from (H_1))

$$\text{or } m\ddot{r} - Mr^2\dot{\theta}^2 - Mg \cos \theta + k(r-r_0) = 0 \quad (3)$$

Also from (H_2) , we have $Mr^2\dot{\theta} = p_{\theta}$

Differentiating $M(r^2\dot{\theta} + 2r\dot{r}\dot{\theta}) = \dot{p}_{\theta}$

$$\text{or } M(r^2\ddot{\theta} + 2r\dot{r}\dot{\theta}) = -Mg r \sin \theta \quad [\text{from } (H_2)]$$

$$\text{or } r\ddot{\theta} + 2\dot{r}\dot{\theta} + g \sin \theta = 0 \quad (4)$$

Equations (3) & (4) are the required equations of motion.

Q(c)

If the fluid fills the region of space on the positive side of x -axis is a rigid boundary, and if there be a source $+m$ at the point $(0, a)$ and an equal sink at $(0, b)$ and if the pressure on the negative side of the boundary be the same as the pressure of the fluid at infinity, show that the resultant pressure on the boundary is $\pi \rho m^2 (a-b)^2 / ab(a+b)$, where ρ is the density of the fluid.

Solⁿ

The object system consists of source $+m$ at $A(0, a)$, i.e. at $z = ia$ and sink

$-m$ at $z = ib$. The image

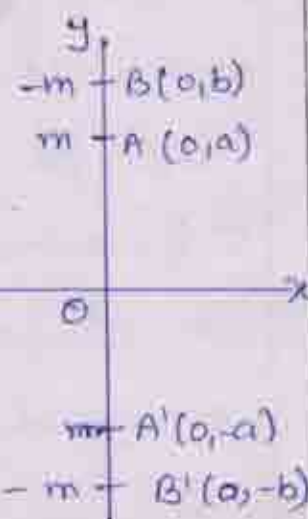
system consist of source $+m$ at $A'(z = -ia)$ and sink $-m$ at $B'(z = -ib)$ w.r.t.

the positive line OX which is

rigid boundary. The complex potential due to object system with rigid boundary is equivalent to the object system and its image system with no rigid boundary.

$$w = -m \log(z - ia) + m \log(z - ib) - m \log(z + ia) + m \log(z + ib)$$

$$\text{or } w = -m \log(z^2 + a^2) + m \log(z^2 + b^2)$$



$$\frac{dw}{dz} = -2mz \left[\frac{1}{z^2+a^2} - \frac{1}{z^2+b^2} \right] = \frac{2mz(a^2-b^2)}{(z^2+a^2)(z^2+b^2)}$$

$$q = \left| \frac{dw}{dz} \right| = \frac{2m(a^2-b^2)|z|}{|z^2+a^2||z^2+b^2|}$$

for any point on x -axis, we have $z=x$
so that

$$q = \frac{2mx(a^2-b^2)}{(x^2+a^2)(x^2+b^2)}$$

This is expression for velocity at any point on x -axis. Let p_0 be the pressure at $x=\infty$. By Bernoulli's equation for steady motion.

$$\therefore \frac{p}{\rho} + \frac{1}{2}q^2 = C$$

In view of $p=p_0$, $q=0$ when $x=\infty$, we get $C = p_0/\rho$.

$$\frac{p_0-p}{\rho} = \frac{1}{2}q^2$$

Required pressure p on boundary is given by,

$$\begin{aligned} p &= \int_{-\infty}^{\infty} (p_0-p) dx = \int_{-\infty}^{\infty} \frac{1}{2} \rho q^2 dx \\ &= \frac{1}{2} \rho \int_{-\infty}^{\infty} \frac{4m^2 x^2 (a^2-b^2)^2}{(x^2+a^2)^2 (x^2+b^2)^2} dx. \end{aligned}$$

$$\begin{aligned}
 &= 4 \int m^2 (a^2 - b^2)^2 \int_0^\infty \frac{x^2 dx}{(x^2 + a^2)^2 (x^2 + b^2)^2} \\
 &= 4 m^2 \int_0^\infty \left[\frac{a^2 + b^2}{a^2 - b^2} \left\{ \frac{1}{x^2 + b^2} - \frac{1}{x^2 + a^2} \right\} - \frac{a^2}{(x^2 + a^2)^2} \right. \\
 &\quad \left. - \frac{b^2}{(x^2 + b^2)^2} \right] dx. \\
 &= 4 m^2 \int \left[\frac{a^2 + b^2}{a^2 - b^2} \left\{ \frac{\pi}{2b} - \frac{\pi}{2a} \right\} - \frac{\pi}{4a} - \frac{\pi}{4b} \right] \\
 &= \frac{\pi \int m^2 (a - b)^2}{ab(a + b)} \quad (\text{Ans.})
 \end{aligned}$$

$$\text{for } \int_0^\infty \frac{dx}{x^2 + a^2} = \left[\frac{1}{a} \tan^{-1} \frac{x}{a} \right]_0^\infty = \frac{\pi}{2a}$$

$$\int_0^\infty \frac{dx}{(x^2 + a^2)^2} = \frac{1}{a^3} \int_0^\infty \cos^2 \theta d\theta, \quad x = a \tan \theta$$

$$= \frac{1}{2a^3} \int_0^{\pi/2} (1 + \cos 2\theta) d\theta = \frac{\pi}{2} \cdot \frac{1}{2a^3}$$

$$= \frac{\pi}{4a^3}$$