

1. Verify Green's Theorem in plane to

$$\oint_C [(3x^2 - 8y^2)dx + (4y - 6xy)dy]$$

C = boundary of region

enclosed by $y = \sqrt{x}$ and $y = x^2$

The point of intersection of curve

$$C = y = \sqrt{x} = x^2$$

$$\Rightarrow x^2 = \sqrt{x} \Rightarrow x^4 = x$$

$$\Rightarrow x(x^3 - 1) = 0 \Rightarrow \boxed{x=0, x=1}$$

so, Region R is bounded

by curve $C = C_1 + C_2$

C_1 : $(0,0)$ to $(1,1)$ along $y = x^2$ and

C_2 : $(1,1)$ to $(0,0)$ along $y = \sqrt{x}$.

so, By Green's Thm in plane -

$$\oint_C (Pdx + Qdy) = \iint_R \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy$$

$$= \iint_R (-6y + 16y) dx dy = \iint_R 10y dx dy$$

$$= \int_{x=0}^1 \left(\int_{y=x^2}^{\sqrt{x}} 10y dy \right) dx$$

$$= \int_0^1 \left(5y^2 \Big|_{x^2}^{\sqrt{x}} \right) dx$$

$$= \int_0^1 5(x - x^4) dx = 5 \left[\frac{x^2}{2} - \frac{x^5}{5} \right]_0^1$$

$$= 5 \left[\frac{1}{2} - \frac{1}{5} \right] = \boxed{\frac{3}{2}}$$

crout.

2 $m = 2 \text{ unit}$, $\vec{r} = (t^2 - 2t)\hat{i} + \left(\frac{1}{2}t^2 + 1\right)\hat{j} + t^2\hat{k}$

At $t=1$, find K.E, angular momentum, time rate of change of angular momentum and moment of resultant force, acting at particle, about origin.

$$L = \vec{r} \times \vec{p} = m \vec{r}^2 \omega = I \omega$$

$$\vec{r} = (t^2 - 2t)\hat{i} + \left(\frac{1}{2}t^2 + 1\right)\hat{j} + t^2\hat{k}$$

$$\vec{r}|_{t=1} = -\hat{i} + \frac{3}{2}\hat{j} + \hat{k}$$

$$\vec{u} = \frac{d\vec{r}}{dt} = (2t - 2)\hat{i} + (t)\hat{j} + 2t\hat{k}$$

$$\vec{u}|_{t=1} = 0\hat{i} + \hat{j} + 2\hat{k}$$

$$\vec{a} = \frac{d\vec{u}}{dt} = 2\hat{i} + \hat{j} + 2\hat{k}$$

$$m = 2 \text{ unit}$$

$$KE = \frac{1}{2} m u^2 = \frac{1}{2} m |\vec{u}|^2 = \frac{1}{2} \times 2 \times (\sqrt{5})^2 = 5 \text{ unit}$$

$$\text{angular momentum} = m r u = m \times |\vec{r}| \times |\vec{u}| = m \times \sqrt{17} \times \sqrt{5} = \sqrt{85} \text{ unit}$$

Time rate of change of angular momentum = moment of force

moment of resultant force = $\vec{r} \times \vec{F}$

$$\vec{F} = m \frac{d\vec{v}}{dt} = 4\hat{i} + 2\hat{j} + 4\hat{k}$$

$$\vec{r} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -1 & \frac{3}{2} & 1 \\ 4 & 2 & 4 \end{vmatrix} = 4\hat{i} + 8\hat{j} - 8\hat{k}$$

$$\text{Moment} = |\vec{r} \times \vec{F}| = \sqrt{144} = 12 \text{ unit}$$

3. Find curvature, torsion and relation b/w arc length s and parameter u for the curve:

$$\vec{r} = \vec{r}(u) = 2 \log_e u \hat{i} + 4u\hat{j} + (2u^2 + 1)\hat{k}$$

$$\frac{d\vec{r}}{du} = \frac{2}{u}\hat{i} + 4\hat{j} + 4u\hat{k}$$

$$\left| \frac{d\vec{r}}{du} \right| = \sqrt{16 + 16u^2 + \frac{4}{u^2}} = \sqrt{16u^2 + 16u^4 + 4}$$

$$= \frac{2}{u} \sqrt{1 + 4(u^2 + u^4)} = \frac{2 + 4u^2}{u}$$

$$\text{Curvature } K = \frac{\left| \frac{d\vec{r}}{du} \times \frac{d^2\vec{r}}{du^2} \right|}{\left| \frac{d\vec{r}}{du} \right|^3}$$

$$\Rightarrow \frac{d^2\vec{r}}{du^2} = -\frac{2}{u^2}\hat{i} + 0\hat{j} + 4\hat{k}$$

$$\frac{d^3\vec{r}}{du^3} = \frac{4}{u^3}\hat{i} + 0\hat{j} + 0\hat{k}$$

ROUGH

$$\frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{2}{u} & 4 & 4u \\ -\frac{2}{u^2} & 0 & 4 \end{vmatrix}$$

$$= \hat{i} (16) + \hat{j} \left(\frac{-16}{u} \right) + \hat{k} \left(\frac{8}{u^2} \right)$$

$$\left| \frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} \right| = \sqrt{\left(\frac{16}{u} \right)^2 + \left(\frac{8}{u^2} \right)^2} = \frac{8}{u} \sqrt{4 + \frac{1}{u^2}}$$

$$\left(\frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} \right) \cdot \frac{d^3\vec{r}}{dt^3} = \frac{16 \times 4}{u^3} = \frac{64}{u^3}$$

$$\Rightarrow K = \frac{\left| \frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} \right|}{\left| \frac{d\vec{r}}{dt} \right|^3} = \frac{\sqrt{16^2 \times u^4 + 64}}{\frac{8}{u^3} (1 + 4(u^2 + u^4))^{3/2}}$$

$$\neq \frac{8}{u} \sqrt{4u^2 + 1}$$

$$\left| \frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} \right| = \sqrt{\frac{16 \times 16}{u \times u} + \frac{8 \times 8}{u^2 \times u^2}} = \frac{8}{u^2} \sqrt{4u^2 + 4u^4 + 1} = \frac{8(2u^2 + 1)}{u^2}$$

$$\text{So } K = \frac{\frac{8}{u^2} (2u^2 + 1)}{\left(\frac{2}{u} + 4u \right)^3} = \frac{\frac{8}{u^2} (2u^2 + 1)}{\frac{8}{u^3} (1 + 2u^2)^3}$$

$$= \frac{u}{(1 + 2u^2)^2}$$

$$r = \begin{bmatrix} \frac{dr}{du} & \frac{dr}{du^2} & \frac{dr}{du^3} \end{bmatrix}$$

$$\left| \frac{dr}{du} \times \frac{dr}{du^2} \right|^2$$

$$= \frac{64}{4^3}$$

$$= \frac{64}{4^3} (2u^2+1)^2$$

$$= \frac{4}{(2u^2+1)^2} = k$$

$$\text{Now } s = \int dr = \int \frac{ds}{du} du = \int \left| \frac{dr}{du} \right| du$$

$$s = \int \left(\frac{2}{u} + 4u \right) du = 2 \ln u + 2u^2 + c$$

Put $c=0$.

$$\text{Q-4 } \text{curl} (\vec{f} \times \vec{g}) = \vec{f} \text{div} \vec{g} - \vec{g} \text{div} \vec{f} + (\vec{g} \cdot \nabla) \vec{f} - (\vec{f} \cdot \nabla) \vec{g}$$

verify it for $\vec{f} = x\hat{i} + y\hat{j} + z\hat{k}$,
 $\vec{g} = y\hat{i} + z\hat{k}$

$$\text{curl} (\vec{f} \times \vec{g}) = \sum_i \hat{i} \times \frac{\partial}{\partial x} (\vec{f} \times \vec{g})$$

$$= \sum_i \hat{i} \times \left(\frac{\partial \vec{f}}{\partial x} \times \vec{g} \right) + \sum_i \hat{i} \times \left(\vec{f} \times \frac{\partial \vec{g}}{\partial x} \right)$$

$$\left[\text{using } \frac{d}{dx} (\vec{f} \times \vec{g}) = \left(\frac{d\vec{f}}{dx} \times \vec{g} \right) + \left(\vec{f} \times \frac{d\vec{g}}{dx} \right) \right]$$

$$\text{using } \vec{a} \times (\vec{b} \times \vec{c}) = (\vec{a} \cdot \vec{c}) \vec{b} - (\vec{a} \cdot \vec{b}) \vec{c}$$

$$= \sum_i (\hat{i} \cdot \vec{g}) \frac{\partial \vec{f}}{\partial x} - \sum_i (\hat{i} \cdot \frac{\partial \vec{f}}{\partial x}) \vec{g}$$

$$+ \sum_i (\hat{i} \cdot \vec{f}) \frac{\partial \vec{g}}{\partial x} - \sum_i (\hat{i} \cdot \frac{\partial \vec{g}}{\partial x}) \vec{f}$$

$$= \sum_i \left(\vec{g} \cdot \hat{i} \frac{\partial}{\partial x} \right) \vec{f} - (\text{div} \vec{f}) \vec{g} - \sum_i \left(\vec{f} \cdot \hat{i} \frac{\partial}{\partial x} \right) \vec{g} + (\text{div} \vec{g}) \vec{f}$$

ROUGH

$$= (\vec{g} \cdot \nabla) \vec{f} - (\text{div } \vec{f}) \vec{g} - (\vec{f} \cdot \nabla) \vec{g} + (\text{div } \vec{g}) \vec{f}$$

$$\vec{f} = x\hat{i} + 2y\hat{j} + y\hat{k}$$

$$\vec{g} = y\hat{i} + 0\hat{j} + z\hat{k}$$

$$\text{div } \vec{f} = 1 ; \text{div } \vec{g} = 1$$

$$(\vec{g} \cdot \nabla) \vec{f} = \sum (\vec{g} \cdot \hat{i} \frac{\partial}{\partial x}) \vec{f} = \left(y \frac{\partial}{\partial x} + z \frac{\partial}{\partial z} \right) (\vec{f})$$

$$= y\hat{i} + z\hat{j}$$

$$(\vec{f} \cdot \nabla) \vec{g} = z\hat{i} + y\hat{k}$$

$$\vec{f} \times \vec{g} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ x & 2y & y \\ y & 0 & z \end{vmatrix}$$

$$\nabla \times (\vec{f} \times \vec{g}) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -z & y^2 - xz & -yz \end{vmatrix}$$

$$= \hat{i} (-z + x) + \hat{j} (2z) + \hat{k} (-z)$$

$$\begin{aligned} & (\vec{g} \cdot \nabla) \vec{f} - (\text{div } \vec{f}) \vec{g} - (\vec{f} \cdot \nabla) \vec{g} + (\text{div } \vec{g}) \vec{f} \\ &= y\hat{i} + z\hat{j} - y\hat{i} - z\hat{k} - z\hat{i} - y\hat{k} \\ & \quad + x\hat{i} + z\hat{j} + y\hat{k} \end{aligned}$$

$$= \hat{i} (-z + x) + \hat{j} (2z) + \hat{k} (-z)$$

Hence proved

ROUGH

Q-5 $\oint_C \sin x dx + y^2 dy - dz$ Stokes's Thm
 $C = \text{Circle } x^2 + y^2 = 16, z = 3$

Stoke's Thm

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_S (\nabla \times \vec{F}) \cdot \vec{n} dS$$

$$\vec{F} = \sin x \hat{i} + y^2 \hat{j} - \hat{k}$$

$$\nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \sin x & y^2 & -1 \end{vmatrix}$$

$$= 0\hat{i} + 0\hat{j} + 0\hat{k}$$

so $\oint_C \sin x dx + y^2 dy - dz$

$$= 0.$$