

IAS MATHEMATICS (OPT.)-2012

PAPER - I : SOLUTIONS

2012

1(b) Let p and q be positive real numbers such that $\frac{1}{p} + \frac{1}{q} = 1$. Show that for real numbers $a, b \geq 0$

$$\frac{a^p}{p} + \frac{b^q}{q} \geq ab.$$

Sol:

If each $a, b > 0$ and each $p, q > 1$

and $\frac{1}{p} + \frac{1}{q} = 1$; then.

$$\frac{a^p}{p} + \frac{b^q}{q} \geq ab. \quad (1)$$

where the equality occurs only when $a^p = b^q$

from the following way-

let $f(\alpha) = \alpha^x(1-\alpha)^{1-x}$; where $x \in (0,1)$ and $\alpha \in [0,1]$.

Since $f(\alpha)$ is continuous on $[0,1]$ and,

$$f'(\alpha) = \alpha^x(1-\alpha)^{1-x} \left[\frac{x}{\alpha} - \left(\frac{1-x}{1-\alpha} \right) \right] = \alpha^x(1-\alpha)^{1-x} \left[\frac{x-\alpha}{\alpha(1-\alpha)} \right]$$

gives: $f'(\alpha) > 0$ or < 0 on $(0,1)$ according as $\alpha < x$, or $> x$, therefore; $\alpha^x(1-\alpha)^{1-x}$ is increasing or decreasing according as $\alpha < x$, or $> x$;

i.e. $x^x(1-x)^{1-x} > \alpha^\alpha(1-\alpha)^{1-\alpha}$ for $\alpha < x$ and $\alpha > x$

when $x, \alpha \in (0,1)$. for $x = \alpha$

$$x^x(1-x)^{1-x} = \alpha^\alpha(1-\alpha)^{1-\alpha}. \text{ — Hence the result } (2)$$

The (1) result is equivalent to that of above (2) proceeding, for

$$x = \frac{1}{P} ; \alpha = \frac{qa^p}{qa^p + pb^q}$$

On replacing x by $x_1/(x_1+x_2)$ and α by $a_1(a_1+a_2)$
 $\forall x_1, x_2, a_1, a_2 \in R^+$, we get

$$\frac{\frac{x_1}{x_1+x_2} \cdot \frac{x_2}{x_1+x_2}}{(x_1+x_2)} \geq \frac{a_1 \cdot a_2}{(a_1+a_2)}$$

$$\text{i.e. } \left(\frac{x_1}{a_1}\right)^{x_1} \left(\frac{x_2}{a_2}\right)^{x_2} \geq \left(\frac{x_1+x_2}{a_1+a_2}\right)^{x_1+x_2} \quad (3)$$

where the equality occurs only when

$$\frac{x_1}{x_1+x_2} = \frac{a_1}{a_1+a_2} ; \text{i.e. only when } \frac{x_1}{a_1} = \frac{x_2}{a_2}$$

An obvious extension of (3) $\forall x_1, \dots, x_n$ and $a_1, \dots, a_n \in R^+$

$$\left(\frac{x_1}{a_1}\right)^{x_1} \cdots \left(\frac{x_n}{a_n}\right)^{x_n} \geq \left(\frac{x_1+x_2+\dots+x_n}{a_1+a_2+\dots+a_n}\right)^{x_1+x_2+\dots+x_n}$$

where the equality holds only when $\frac{x_1}{a_1} = \dots = \frac{x_n}{a_n}$.

Replacing a_i by $\frac{x_i^2}{a_1}, \dots, a_n$ by $\frac{x_n^2}{a_n} \quad \forall \begin{cases} x_1, \dots, x_n \\ a_1, \dots, a_n \end{cases} \in R^+$

we get;

$$\left(\frac{a_1}{x_1}\right)^{x_1} \cdots \left(\frac{a_n}{x_n}\right)^{x_n} \geq \left(\frac{x_1+\dots+x_n}{x_1^2/a_1+\dots+x_n^2/a_n}\right)^{x_1+x_2+\dots+x_n}$$

On combining the preceding two equalities,
 where the equality occurs only, when

$$\frac{x_1}{x_1^2/a_1} = \dots = \frac{x_n}{x_n^2/a_n} ; \text{i.e. only when } \frac{x_1}{a_1} = \frac{x_2}{a_2} = \dots = \frac{x_n}{a_n}$$

On combining the preceding two inequalities.

If x_1, \dots, x_n and $a_1, \dots, a_n \in \mathbb{R}^+$, we get

$$\left[\frac{x_1^2/a_1 + \dots + x_n^2/a_n}{x_1 + x_2 + \dots + x_n} \right]^{x_1 + \dots + x_n} \geq \left(\frac{x_1}{a_1} \right)^{x_1} \cdots \left(\frac{x_n}{a_n} \right)^{x_n} \geq \left(\frac{x_1 + x_2 + \dots + x_n}{a_1 + a_2 + \dots + a_n} \right)^{x_1 + x_2 + \dots + x_n} \quad (4)$$

where the equality occurs only when

$$\frac{x_1}{a_1} = \frac{x_2}{a_2} = \dots = \frac{x_n}{a_n}$$

Replacement of a_i by $x_i/a_1, \dots, a_n$ by x_n/a_n

in (4), it equivalently gives Roger's form of
the generalized law of Means :

Ques) Prove or disprove the following statement
 1(6) if $B = \{b_1, b_2, b_3, b_4, b_5\}$ is a basis for \mathbb{R}^5 and
 V is a two-dimensional subspace of \mathbb{R}^5 , then
 V has a basis made of just two members
 of B .

Sol:

Given that $B = \{b_1, b_2, b_3, b_4, b_5\}$
 is a basis for $\mathbb{R}^5 = \{(a, b, c, d, e) / a, b, c, d, e \in \mathbb{R}\}$
 Let $S = \{b_1, b_2, b_3, b_4, b_5\}$ be a basis
 of \mathbb{R}^5 where $b_1 = (1, 0, 0, 0, 0)$, $b_2 = (0, 1, 0, 0, 0)$
 $b_3 = (0, 0, 1, 0, 0)$, $b_4 = (0, 0, 0, 1, 0)$, $b_5 = (0, 0, 0, 0, 1)$.

Let the two elements of V be a
 $\alpha = (1, 0, 0, 1, 1)$ and $\beta = (1, 0, 1, 1, 0)$.

Clearly these vectors are linearly
 independent and V is a two dimensional
 vector space.

$$\therefore \text{span } V = \left\{ x(1, 0, 0, 1, 1) + y(1, 0, 1, 1, 0) / x, y \in \mathbb{R} \right\}.$$

$$= \left\{ (x+y, 0, y, x+y, x) / x, y \in \mathbb{R} \right\}.$$

Clearly V is not forming
 by taking any two vectors

of b_1, b_2, b_3, b_4, b_5 .

as there are ten possibilities of the
 span of any two vectors of B i.e.

~~QUESTION~~

~~ANSWER~~

$$b_1 + b_2, b_2 + b_3, b_3 + b_4, b_4 + b_5, b_5 + b_1, b_1 + b_3,$$

$$b_3 + b_5, b_2 + b_4, b_2 + b_5, b_1 + b_4$$

then,

$$\text{span}(b_1 + b_2) = \{x(1, 0, 0, 0, 0) + y(0, 1, 0, 0, 0) \mid x, y \in \mathbb{R}\} = \{(x, y, 0, 0, 0)\}$$

$$\text{span}(b_2 + b_3) = \{(0, x, y, 0, 0) \mid x, y \in \mathbb{R}\}$$

$$\text{span}(b_3 + b_4) = \{(0, 0, x, y, 0)\}$$

$$\text{span}(b_4 + b_5) = \{(0, 0, 0, y, z) \mid y, z \in \mathbb{R}\}$$

$$\text{span}(b_5 + b_1) = \{(x, 0, 0, 0, y)\}$$

$$\text{span}(b_1 + b_3) = \{(x, 0, y, 0, 0)\}$$

$$\text{span}(b_3 + b_5) = \{(0, 0, x, 0, y)\} \quad \forall x, y \in \mathbb{R}$$

$$\text{span}(b_2 + b_4) = \{(0, x, 0, y, 0)\}$$

$$\text{span}(b_2 + b_5) = \{(0, x, 0, 0, y)\}$$

$$\text{span}(b_1 + b_4) = \{(x, 0, 0, y, 0)\}$$

The span of any one vector of B is

not contained in the span of V i.e.

$$\text{span}(b_i + b_j) \not\subseteq \text{span } V \quad \forall i, j = 1, 2, 3, 4, 5, \quad i \neq j.$$

Neither, $\text{span}(V) \not\subseteq \text{span}(b_i + b_j)$.

thus, V does not have a basis made of just two members of B .

Ques

1(f)

Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be the linear transformation defined by $T(\alpha, \beta, \gamma) = (\alpha + 2\beta - 3\gamma, 2\alpha + 5\beta - 4\gamma, \alpha + 4\beta + \gamma)$. — (1)

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— 2012*

Find a basis and the dimension of the image of T and the kernel of T .

Sol: Let, $S = \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$ be the standard basis of \mathbb{R}^3 (domain).
Now take transformation on S .

$$\left. \begin{array}{l} T(1, 0, 0) = (1, 2, 1) \\ T(0, 1, 0) = (2, 5, 4) \\ T(0, 0, 1) = (-3, -4, 1) \end{array} \right\} \text{Using equation (1)}$$

Now, consider $S_1 = \{(1, 2, 1), (2, 5, 4), (-3, -4, 1)\} \subseteq \mathbb{R}^3$
(co-domain)

Now, ^{to} check whether S_1 is L.I or not
let us consider a matrix A whose rows are vectors of S_1 .

$$\Rightarrow A = \begin{bmatrix} 1 & 2 & 1 \\ 2 & 5 & 4 \\ -3 & -4 & 1 \end{bmatrix} \quad \begin{array}{l} R_2 \rightarrow R_2 - 2R_1 \\ R_3 \rightarrow R_3 + 3R_1 \end{array} \sim \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 2 \\ 0 & 2 & 4 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - \frac{1}{2}R_2 \quad A \sim \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

Clearly, this is echelon form of matrix A
and here 2 non-zero rows

$$\therefore f(A) = \text{no. of non-zero rows} = 2$$

$$f(A) = \dim[R(T)] \Rightarrow \text{Dim } R(T) = 2.$$

& Basis₁ = { (1, 2, 1), (0, 1, 2) } forms the basis of R(T).

Now, to find Basis and dimension of Nullspace of T:

$$N(T) = \{ (a, b, c) \mid T(a, b, c) = \vec{0} \}$$

$$T(a, b, c) = \vec{0}$$

Using equation ①

$$\Rightarrow (a+2b-3c, 2a+5b-4c, a+4b+c) = (0, 0, 0)$$

$$\Rightarrow a+2b-3c = 0 \quad \text{---(i)}$$

$$2a+5b-4c = 0 \quad \text{---(ii)}$$

$$a+4b+c = 0 \quad \text{---(iii)}$$

Its Matrix form [Co-efficient Matrix]

$$B = \begin{bmatrix} 1 & 2 & -3 \\ 2 & 5 & -4 \\ 1 & 4 & 1 \end{bmatrix} \quad \begin{array}{l} R_2 \rightarrow R_2 - 2R_1 \\ R_3 \rightarrow R_3 - R_1 \end{array}$$

$$B \sim \begin{bmatrix} 1 & 2 & -3 \\ 0 & 1 & 2 \\ 0 & 2 & 4 \end{bmatrix} \quad \begin{array}{l} R_3 \rightarrow R_3 - 2R_2 \\ \end{array} \sim \begin{bmatrix} 1 & 2 & -3 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix} \sim B$$

Corresponding to the system is

$$\begin{aligned} a+2b-3c &= 0 \quad \text{---(iv)} \\ b+2c &= 0 \quad \text{---(v)} \end{aligned} \quad \begin{array}{l} \text{from (v)} \Rightarrow b = -2c \\ \text{from (iv)} \Rightarrow a = -7c \end{array}$$

Here, only one free variable 'c' and ab are dependent on 'c'.

Hence; $\dim(N(T)) = \text{No. of free variables} = 1$

$$\therefore \boxed{\dim[N(T)] = 1}$$

Choose; $c = 1$; and $a = -7, b = -2$.

$$\Rightarrow (a, b, c) = (-7, -2, 1)$$

Thus; Basis₂ = { (-7, -2, 1) } is Basis for N(T).

Qu.
g(c)(q)
8/18
Date: 12/12/2012

Let V be the vector space of all 2×2 matrices over the field of real numbers. Let W be the set consisting of all matrices with zero determinant. Is W a subspace of V ? Justify your answer.

Sol:- let $V = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix}_{2 \times 2} \mid a, b, c, d \in \mathbb{R} \right\}$

& $W = \left\{ A = \begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix} \mid \det A = 0 \right\} \subseteq V$

let $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ & $B = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$

$\det A = 0$ & $\det B = 0$

Clearly ; $A, B \in W$

$$A+B = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A+B = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\det(A+B) = 1 \neq 0$$

$$\Rightarrow A+B \notin W.$$

Hence, W is not the subspace of V .

Ques)

2c(ii)

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find the dimension and a basis for the space 'w' of all solutions of the following homogeneous system using matrix notation:

$$x_1 + 2x_2 + 3x_3 - 2x_4 + 4x_5 = 0$$

$$2x_1 + 4x_2 + 8x_3 + x_4 + 9x_5 = 0$$

$$3x_1 + 6x_2 + 13x_3 + 4x_4 + 14x_5 = 0$$

Sol'

Given homogeneous system is :

$$x_1 + 2x_2 + 3x_3 - 2x_4 + 4x_5 = 0 \quad \text{--- (1)}$$

$$2x_1 + 4x_2 + 8x_3 + x_4 + 9x_5 = 0 \quad \text{--- (2)}$$

$$3x_1 + 6x_2 + 13x_3 + 4x_4 + 14x_5 = 0 \quad \text{--- (3)}$$

coefficient matrix of given system is -

$$A = \begin{bmatrix} 1 & 2 & 3 & -2 & 4 \\ 2 & 4 & 8 & 1 & 9 \\ 3 & 6 & 13 & 4 & 14 \end{bmatrix} \quad R_2 \rightarrow R_2 - 2R_1, \quad R_3 \rightarrow R_3 - 3R_1$$

$$A \sim \begin{bmatrix} 1 & 2 & 3 & -2 & 4 \\ 0 & 0 & 2 & 5 & 1 \\ 0 & 0 & 4 & 10 & 2 \end{bmatrix} \quad R_3 \rightarrow R_3 - 2R_2$$

$$A \sim \begin{bmatrix} 1 & 2 & 3 & -2 & 4 \\ 0 & 0 & 2 & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

so, corresponding homogeneous system is

$$x_1 + 2x_2 + 3x_3 - 2x_4 + 4x_5 = 0 \quad \text{--- (4)}$$

$$2x_3 + 5x_4 + x_5 = 0 \quad \text{--- (5)}$$

Here, 3 variables x_2, x_4, x_5 , and

values of x_1 and x_3 depend upon x_2, x_4, x_5

from (5) $x_3 = -\frac{(5x_4 + x_5)}{2} \quad \text{--- (6)}$

from (4) $x_1 = -2x_2 - 3x_3 + 2x_4 - 4x_5$

$$x_1 = (-2x_2) + \frac{19x_4 - 5x_5}{2}$$

$$\Rightarrow x_1 = \frac{-4x_2 + 19x_4 - 5x_5}{2} \quad \text{--- (7)}$$

Now, put $x_2 = 1, x_4 = 0, x_5 = 0$

$$\Rightarrow x_3 = 0, x_1 = -2$$

$$\text{Then } (x_1, x_2, x_3, x_4, x_5) = (-2, 1, 0, 0, 0) \quad \text{--- (8)}$$

put $x_2 = 0, x_4 = 1, x_5 = 0$

$$\Rightarrow x_3 = -\frac{5}{2}, x_1 = \frac{19}{2}$$

$$\text{then } (x_1, x_2, x_3, x_4, x_5) = \left(\frac{19}{2}, 0, -\frac{5}{2}, 1, 0\right) \quad \text{--- (9)}$$

Put $x_2 = 0, x_4 = 0, x_5 = 1$

$$\Rightarrow x_3 = -\frac{1}{2}; x_1 = -\frac{5}{2}$$

$$\text{then } (x_1, x_2, x_3, x_4, x_5) = \left(-\frac{5}{2}, 0, -\frac{1}{2}, 0, 1\right) \quad \text{--- (10)}$$

Hence, from (8), (9) & (10)

$$B = \left\{ (-2, 1, 0, 0, 0), \left(\frac{19}{2}, 0, -\frac{5}{2}, 1, 0\right), \left(-\frac{5}{2}, 0, -\frac{1}{2}, 0, 1\right) \right\}$$

is the basis for the space W.

4 Dim W = 3

Q.

 $\begin{pmatrix} 2 \\ 1 \end{pmatrix} \times \begin{pmatrix} 1 \\ 2 \end{pmatrix}$
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Consider the linear mapping

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \text{ by}$$

$f(x,y) = (3x+4y, 2x-5y)$; find the matrix 'A' relative to the basis $\{(1,0), (0,1)\}$ and the matrix 'B' relative to the basis $\{(1,2), (2,3)\}$

Solt-Given: linear mapping $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by

$$f(x,y) = (3x+4y, 2x-5y) \quad \text{--- (1)}$$

To find the matrix 'A' relative to basis

$$\{(1,0), (0,1)\}$$

$$\text{Consider } B_1 = \{(1,0), (0,1)\} = \{\alpha_1, \alpha_2\}.$$

$$(a,b) \in \mathbb{R}^2 \Rightarrow (a,b) = a(1,0) + b(0,1) \quad \text{--- (2)}$$

$$f(\alpha_1) = (3,2) \quad \text{--- Using eq(1)}$$

$$f(\alpha_1) = 3(1,0) + 2(0,1) \quad (\text{using eq(2)}) \quad \text{--- (3)}$$

$$\text{Similarly; } f(\alpha_2) = (4, -5)$$

$$f(\alpha_2) = 4(1,0) + (-5)(0,1) \quad \text{--- (4)}$$

from (3) & (4) matrix 'A', relative to B_1 ,

$$A = [f: B_1] = \begin{bmatrix} 3 & 4 \\ 2 & -5 \end{bmatrix} \quad \text{--- (5)}$$

Now, to find matrix B relative to the basis $\{(1,2), (2,3)\}$

$$\text{consider } B_2 = \{(1,2), (2,3)\} = \{\beta_1, \beta_2\}$$

$$\text{where; } \beta_1 = (1,2) \quad \beta_2 = (2,3)$$

$$(a,b) \in \mathbb{R}^2 \quad (a,b) = x\beta_1 + y\beta_2$$

$$\Rightarrow (a, b) = x(1, 2) + y(2, 3)$$

$$(a, b) = (x+2y, 2x+3y)$$

$$x+2y = a \quad \text{--- (6)}$$

$$2x+3y = b \quad \text{--- (7)}$$

on solving (6) & (7), we get

$$y = 2a - b \quad \& \quad x = -3a + 2b$$

$$\Rightarrow (a, b) = (-3a+2b)(1, 2) + (2a-b)(2, 3) \quad \text{--- (8)}$$

$$\text{now, } f(\beta_1) = (11, -8) \text{ using eq (1)}$$

$$f(\beta_1) = (-49)(1, 2) + 30(2, 3) \quad \text{using (6)} \quad \text{using (8)}$$

$$f(\beta_2) = (18, -11) \quad \text{--- using eq (1)}$$

$$f(\beta_2) = (-76)(1, 2) + 47(2, 3) \quad \text{--- (10)}$$

from (9) & (10),

matrix 'B' relative to basis β_2

$$\text{is } B = [f; \beta_2] = \begin{bmatrix} -49 & -76 \\ 30 & 47 \end{bmatrix} \quad \underline{\underline{A}}$$

Q. If λ is a characteristic root of a non-singular matrix A , then prove that $\frac{|A|}{\lambda}$ is a characteristic root of $\text{Adj } A$.
 2(b)(ii)
BMS-WL

Sol: Let A be a non-singular matrix,
 let λ be an eigen value of A

$$\Rightarrow AX = \lambda X \quad \text{--- (1)}$$

$$\therefore A^{-1} = \frac{\text{Adj } A}{|A|}$$

$$\Rightarrow \frac{(\text{Adj } A) \cdot A}{|A|} = A^{-1} A$$

$$(\text{Adj } A) A = |A| I \quad \text{--- (2)}$$

$$|(\text{Adj } A) A| X = |A| I X$$

$$\text{Adj } A \cdot (AX) = |A| X$$

$$\text{Adj } A \cdot (\lambda X) = |A| X$$

$$(\text{Adj } A) X = \frac{|A|}{\lambda} X$$

[By associativity
of matrix multi-
plication]

$\Rightarrow \frac{|A|}{\lambda}$ is a characteristic root of $\text{Adj } A$.

8AJS
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2(c) \rightarrow Let $H = \begin{bmatrix} 1 & i & 2+i \\ -i & 2 & 1-i \\ 2-i & 1+i & 2 \end{bmatrix}$ be

p-II

a Hermitian Matrix. Find a non-singular matrix P such that $D = P^T H \bar{P}$ is diagonal.

so let us construct a block

$$\text{Matrix } [H | I] = \left[\begin{array}{ccc|ccc} 1 & i & 2+i & 1 & 0 & 0 \\ -i & 2 & 1-i & 0 & 1 & 0 \\ 2-i & 1+i & 2 & 0 & 0 & 1 \end{array} \right]$$

$$\sim \left[\begin{array}{ccc|ccc} 1 & i & 2+i & 1 & 0 & 0 \\ 0 & 1 & i & i & 1 & 0 \\ 0 & -i & -3 & -(2-i) & 0 & 1 \end{array} \right] \quad R_2 \rightarrow R_2 + iR_1 \\ R_3 \rightarrow R_3 + (2-i)R_1$$

$$\sim \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & -i & -(2+i) \\ 0 & 1 & i & i & 2 & -(2i-1) \\ 0 & -i & -3 & -(2-i) & 2+i & -4 \end{array} \right] \quad C_2 \rightarrow C_2 - iC_1 \\ C_3 \rightarrow C_3 - (2+i)C_2$$

$$\sim \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & -i & -(2+i) \\ 0 & 1 & i & i & 2 & -(2i-1) \\ 0 & 0 & -4 & -3+i & 4i+1 & -2+i \end{array} \right] \quad R_3 \rightarrow R_3 + iR_2$$

$$C_3 \rightarrow C_3 - iC_1$$

$$[H|I] \sim \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & -i & -3-i \\ 0 & 1 & 0 & i & 2 & -4i+1 \\ 0 & 0 & -4 & -3+i & 4i+1 & 2 \end{array} \right]$$

$$P = \begin{bmatrix} 1 & -i & -3-i \\ i & 2 & -4i+1 \\ -3+i & 4i+1 & 2 \end{bmatrix}$$

and $P^T H P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -4 \end{bmatrix} = D$

5(a). Solve $\frac{dy}{dx} = \frac{2xye^{(x/y)^2}}{y^2(1+e^{(x/y)^2}) + 2x^2e^{(x/y)^2}}$

SOLUTION

Clearly given equation is homogenous

$$\text{Let } \frac{y}{x} = t \Rightarrow \frac{dy}{dx} = t + x \frac{dt}{dx}$$

$$\therefore t + x \frac{dt}{dx} = \frac{2te^{1/t^2}}{t^2(1+e^{1/t^2}) + 2e^{1/t^2}}$$

$$\frac{x dt}{dx} = \frac{2te^{1/t^2}}{t^2(1+e^{1/t^2}) + 2e^{1/t^2}} - t$$

$$\frac{x dt}{dx} = \frac{-t^3(1+e^{1/t^2})}{t^2(1+e^{1/t^2}) + 2e^{1/t^2}}$$

$$-\frac{dx}{x} = \frac{(1+e^{1/t^2})t^2 + 2e^{1/t^2}}{t^3(1+e^{1/t^2})} \cdot dt$$

$$-\frac{dx}{x} = \frac{dt}{t} + \frac{d(1+e^{1/t^2})}{(1+e^{1/t^2})}$$

integrating both sides

$$-\ell n x = \ell n t - \ell n (1+e^{1/t^2}) C$$

$$\ell n tx = \ell n (1+e^{1/t^2}) C$$

$$\therefore y = C(1+e^{(x/y)^2})$$

Required solution.

5(b). Find the orthogonal trajectories of the family of curves $x^2 + y^2 = ax$.

SOLUTION

Given equation $x^2 + y^2 = ax$

differentiating w.r.t to x

$$2x + 2y \frac{dy}{dx} = a$$

eliminating the arbitrary constant a

$$\therefore (x^2 + y^2) = \left(2x + xy \frac{dy}{dx}\right)x$$

for orthogonal trajectories replace

$$\frac{dy}{dx} \text{ by } -\frac{1}{dy/dx}$$

$$x^2 + y^2 = 2x^2 + 2xy \frac{(-1)}{dy/dx}$$

$$2xy \frac{dx}{dy} = (x^2 - y^2)$$

$$\frac{dy}{dx} = \frac{2xy}{x^2 - y^2}$$

Take common x^2 from N^r and D^r

$$\frac{dy}{dx} = \frac{2(y/x)}{1 - (y/x)^2}$$

Clearly given equation is homogenous, then

$$\text{put } \frac{y}{x} = t \Rightarrow \frac{dy}{dx} = \frac{d}{dx}(tn) = t + x \frac{dt}{dx}$$

$$\therefore t + x \frac{dt}{dx} = \frac{2t}{1-t^2}$$

$$x \frac{dt}{dx} = \frac{t+t^3}{1-t^2}$$

$$\frac{dx}{x} = \frac{(1-t^2)dt}{t+t^3}$$

$$\frac{dx}{x} = \left[\frac{1}{t} - \frac{2t}{1+t^2} \right] dt$$

$$\ln x = \ln t - \ln(1+t^2) + C$$

$$x = \frac{Ct}{1+t^2}$$

Put

$$t = y/x$$

$$\boxed{x^2 + y^2 = Cy}$$

5(c). Using Laplace transforms, solve the intial value problem

$$y'' + 2y' + y = e^{-t}, y(0) = -1, y'(0) = 1$$

SOLUTION

Given equation $y'' + 2y' + y = e^{-t}$

Applying Laplace transform as both sides

$$\mathcal{L}(y'' + 2y' + y) = \mathcal{L}(e^{-t})$$

$$s^2\mathcal{L}(y) - sy(0) - y'(0) + 2s\mathcal{L}(y) - 2y(0) + \mathcal{L}(y) = \frac{1}{s+1}$$

(given, $y(0) = -1, y'(0) = 1$)

$$(s^2 + 2s + 1) \mathcal{L}(y) + s - 1 + 2 = \frac{1}{s+1}$$

$$(s+1)^2 \mathcal{L}(y) = \frac{1}{s+1} - (s+1)$$

$$\mathcal{L}(y) = \frac{1}{(s+1)^3} - \frac{1}{(s+1)}$$

Applying inverse transform

$$y(t) = e^{-t} \frac{t^2}{2} - e^{-t}$$

$$y(t) = e^{-t} \left(\frac{t^2}{2} - 1 \right)$$

5(d) A particle whose mass is m is acted upon by a force $m\mu \left[x + \frac{a^4}{x^3} \right]$ towards origin, if it starts from rest at a distance a . show that it will arrive at origin in time $\pi/(4\sqrt{\mu})$.

Sol'n: Given $\frac{d^2x}{dt^2} = -\mu \left[x + \frac{a^4}{x^3} \right]$, — (1)

the -ve sign being taken because the force is attractive multiply on bothside by $2(\frac{dx}{dt})$ and integrating we get

$$\left(\frac{dx}{dt} \right)^2 = \mu \left[-x^2 + \frac{a^4}{x^2} \right] + C$$

when $x=a$, $\frac{dx}{dt}=0$, so that $C=0$

$$\therefore \left(\frac{dx}{dt} \right)^2 = \mu \left[\frac{a^4 - x^4}{x^2} \right]$$

$$\frac{dx}{dt} = \pm \frac{\sqrt{\mu(a^4 - x^4)}}{x} \quad (2)$$

the -ve sign is taken because the particle is moving in the direction of x decreasing.

If t_1 be the time taken to reach the origin, then integrating (2), we get-

$$t_1 = \frac{1}{\sqrt{\mu}} \int_{a}^{0} \frac{x}{a\sqrt{a^4 - x^4}} dx = \frac{1}{\sqrt{\mu}} \int_{0}^{a} \frac{adx}{\sqrt{a^4 - x^4}}$$

put $x^2 = a^2 \sin\theta$ so that $2x dx = a^2 \cos\theta d\theta$. when $x=0$, $\theta=0$ and when $x=a$, $\theta=\pi/2$

$$\begin{aligned} \therefore t_1 &= \frac{1}{\sqrt{\mu}} \int_{0}^{\pi/2} \frac{\frac{1}{2} a^2 \cos\theta d\theta}{a^2 \cos\theta} = \frac{1}{2\sqrt{\mu}} \int_{0}^{\pi/2} d\theta \\ &= \frac{1}{2\sqrt{\mu}} \left[\theta \right]_{0}^{\pi/2} = \frac{1}{2\sqrt{\mu}} \cdot \frac{\pi}{2} = \frac{\pi}{4\sqrt{\mu}} \end{aligned}$$

5.(e) If $\vec{A} = x^2yz\hat{i} - 2xz^3\hat{j} + xz^2\hat{k}$

$$\vec{B} = 2z\hat{i} + y\hat{j} - x^2\hat{k}$$

Find the value of $\frac{\partial^2}{\partial x \partial y}(\vec{A} \times \vec{B})$ at (1, 0, -2).

SOLUTION

$$\text{Given } \vec{A} = x^2yz\hat{i} - 2xz^3\hat{j} + xz^2\hat{k}$$

$$\vec{B} = 2z\hat{i} + y\hat{j} - x^2\hat{k}$$

Then the value of $\frac{\partial^2}{\partial x \partial y}(\vec{A} \times \vec{B}) = ?$

$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ x^2yz & -2xz^3 & xz^2 \\ 2z & y & -x^2 \end{vmatrix}$$

$$\vec{A} \times \vec{B} = (2x^3z^3 - xyz^2)\hat{i} + (x^4yz + 2xz^3)\hat{j} + (x^2y^2z + 4xz^4)\hat{k} \quad \dots\dots(1)$$

Partially differentiating (1) w.r.t. 'y'

$$\Rightarrow \frac{\partial(\vec{A} \times \vec{B})}{\partial y} = -xz^2\hat{i} + x^4z\hat{j} + 2x^2zy\hat{k} \quad \dots\dots(2)$$

Now partially differentiating (2) w.r.t.'x'

$$\frac{\partial^2(\vec{A} \times \vec{B})}{\partial x \partial y} = -z^2\hat{i} + 4x^3z\hat{j} + 4xyz\hat{k}$$

At (1, 0, -2)

$$\frac{\partial^2(\vec{A} \times \vec{B})}{\partial x \partial y} = -(-2)^2\hat{i} + 4 \times 1 \times (-2)\hat{j} + 0$$

$$\frac{\partial^2(\vec{A} \times \vec{B})}{\partial x \partial y} = -4\hat{i} - 8\hat{j}$$

is the required answer

6(a). Show that the differential equation

$$(2xy \log y)dx + \left(x^2 + y^2 \sqrt{y^2 + 1}\right)dy = 0$$

is not exact. Find an integrating factor and hence, the solution of the equation.

SOLUTION

Given equation is

$$(2xy \log y)dx + \left(x^2 + y^2 \sqrt{1+y^2}\right)dy = 0$$

comparing with standard exact equation $Mdx + Ndy = 0$

$$\therefore M = 2xy \log y$$

$$N = x^2 + y^2 \sqrt{1+y^2}$$

$$\frac{\partial M}{\partial y} = 2x \log y + 2x.$$

$$\frac{\partial N}{\partial x} = 2x$$

$$\sin u \frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$$

\therefore Given equation is not exact

$$\frac{\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}}{M} = \frac{-2x \log y}{2xy \log y} = \frac{-1}{y} = f(y)$$

$$\therefore I.F. = e^{-\int \frac{1}{y} dy} = e^{-\log y} = e^{\log \frac{1}{y}}$$

$$I.F. = \frac{1}{y}$$

Multiply by integrating factors we have

$$(2x \log y)dx + \left(\frac{x^2}{y} + y \sqrt{1+y^2}\right)dy = 0$$

this is exact differential equation.

$$\therefore \int (2x \log y)dx + \int y \sqrt{y^2 + 1} dy = C$$

$$x^2 \log y + \frac{(y^2 + 1)^{3/2}}{3} = C$$

\therefore Solution of given equation

$$\boxed{x^2 \log y + \frac{(y^2 + 1)^{3/2}}{3} = C}$$

6(b). Find the general solution of the equation

$$y''' - y'' = 12x^2 + 6x.$$

SOLUTION

$$\text{Given equation } y'' - y' = 12x^2 + 6x$$

$$\Rightarrow (D^3 - D^2)y = 12x^2 + 6x$$

Homogenous equation of given problem is

$$D^3 - D^2 = 0$$

$$\text{Auxillary equation of given equation } m^3 - m^2 = 0$$

$$m = 0, 0, 1$$

∴ Complementary function

$$CF = C_1 + C_2 x + C_3 e^x$$

Particular integral

$$\begin{aligned} P.I &= \frac{(12x^2 + 6x)}{D^3 - D^2} \\ &= \frac{-1}{D^2} [1 - D]^{-1} (12x^2 + 6x) \\ &= \frac{-1}{D^2} [1 + D + D^2 + \dots] (12x^2 + 6x) \\ &= \frac{-1}{D^2} [12x^2 + 6x + 24x + 6 + 24] \\ &\boxed{y_p = -x^4 - 5x^3 - 15x^2} \end{aligned}$$

$$\therefore \text{General solution} = C_1 + C_2 x + C_3 e^x - x^4 - 5x^3 - 15x^2$$

6(c). Solve the ordinary differential equation

$$x(x-1)y'' - (2x-1)y' + 2y = x^2(2x-3)$$

SOLUTION

$$\text{Given } y'' - \frac{(2x-1)}{x(x-1)}y' + \frac{2y}{x(x-1)} = \frac{x(2x-3)}{(x-1)}$$

comparing with $y'' + Py' + Qy = R$, we have

$$P = \frac{-(2x-1)}{x(x-1)}$$

$$Q = \frac{2}{x(x-1)}$$

$$R = \frac{x(2x-3)}{(x-1)}$$

Clearly $2 + 2P x + Qx^2 = 0$

$u = x^2$ is the part of complementary function when the part of complementary function is known.

Let

$$\text{when } u = x^2$$

\therefore new equation is v.

$$\frac{d^2v}{dx^2} + \left(P + \frac{2u'}{u}\right) \frac{dv}{dx} = \frac{R}{u}$$

$$\frac{d^2v}{dx^2} + \left[\frac{-(2x-1)}{x(x-1)} + \frac{4}{x}\right] \frac{dv}{dx} = \frac{(2x-3)}{x(x-1)}$$

$$\frac{d^2v}{dx^2} + \frac{(2x-3)}{x(x-1)} \frac{dv}{dx} = \frac{2x-3}{x(x-1)}$$

Let

$$\frac{dv}{dx} = t$$

$$\therefore \frac{dt}{dx} + \frac{2x-3}{x(x-1)}t = \frac{2x-3}{x(x-1)}$$

$$\frac{dt}{1-t} = \left[\frac{2x-3}{x(x-1)}\right] dx$$

integrating on both sides

$$-\ell n(1-t) = \int \left[\frac{3}{x} + \frac{-1}{x-1} \right] dx + c$$

$$-\ell n(1-t) = 3 \ell n x - \ell n(x-1) + c$$

$$(1-t) = c \frac{(x-1)}{x^3}$$

$$\frac{dv}{dx} = 1 - \frac{c}{x^2} + \frac{c}{x^3}$$

$$v = x + \frac{c_1}{x} - \frac{c_1}{2x^2} + c_2$$

\therefore general solution $y = uv$

$$y = x^3 + c_1 x - \frac{c_1}{2} + c_2 x^2$$

$$y = c_1 \left(\frac{x-1}{2} \right) + c_2 x^2 + x^3$$

8.(a) Derive the Frenet-Serret formulae.

Define the curvature and torsion for a space curve. Compute them for the space

$$\text{curve } x=t, y=t^2, z=\frac{2}{3}t^3$$

Show that the curvature and torsion are equal for this curve.

SOLUTION

8(a)
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* Serret-frenet formulae:-

The set of relations involving the derivatives of the fundamental vectors T, N, B is known collectively as the serret-frenet formulae given by

$$① \frac{dT}{ds} = kN, \quad ② \frac{dB}{ds} = -TN$$

$$③ \frac{dN}{ds} = \tau B - kT$$

where τ is a scalar called the torsion.

The quantity $\rho = \frac{1}{\tau}$ is called the radius of the torsion.

* Principled Normal vector:-

Any line perpendicular to the tangent to a curve at a point 'P' is called a normal line at 'P'.

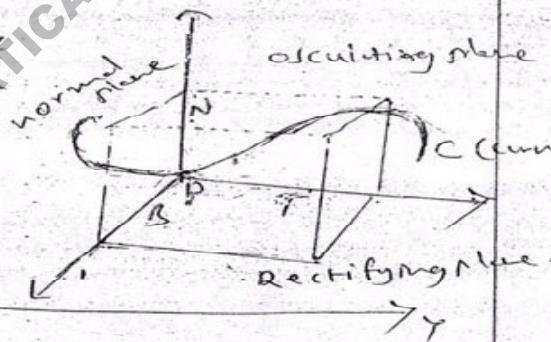
The normal line lying in the osculating plane is called the principled normal at 'P'.

The unit principled normal is denoted by N .

The osculating plane to a curve at a point is the plane containing the tangent and principled normal at 'P'.

Normal Plane:-

The plane through the point 'P' perpendicular to the tangent at 'P' is called the normal plane at 'P'.



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Rectifying plane :-

The plane through the point 'P' perpendicular to the principal normal is called rectifying plane.

Binormal!

Let T be the unit tangent vector, N be the unit principal normal vector to the curve at a point 'P'.

If B is the unit vector perpendicular to both T and N such that T, N, B form a right handed system then B is called binormal vector to the curve at 'P'.

Then the binormal is the perpendicular to the osculating plane:

* Right-handed system of T, N, B :-

The vectors T, N, B form a right-handed system of unit vectors.

$$\therefore T \cdot T = 1, N \cdot N = 1, B \cdot B = 1; T \cdot N = N \cdot B = B \cdot T = 0.$$

$$\text{and } T \times N = B, N \times B = T, B \times T = -N.$$

$$T \times T = N \times N = B \times B = 0.$$

Proof of Serret-Frenet formulae:

$$\textcircled{1} \quad \frac{dT}{ds} = kN.$$

Let $\vec{r}(t)$ be the position vector of the point 'P' on the curve $(\vec{r}(t) = \vec{r}(s))$, then the unit vector T at 'P' is given by $\frac{d\vec{r}}{ds} = T$.

Since $|T| = 1$ i.e. T is of constant magnitude

$$\text{we have } T \cdot \frac{dT}{ds} = 0.$$

$\therefore \frac{dT}{ds}$ is perpendicular to T . (28)

But we know that $\frac{dT}{ds}$ lies in the osculating plane.

$\therefore \frac{dT}{ds}$ is parallel to $N \Rightarrow \frac{dT}{ds} = \pm \text{scalar } N$
By convention, we take +ve sign,
 $\Rightarrow \frac{dT}{ds} = kN$ for some scalar k . (i)

Curvature:— If T is the unit tangent vector to the curve $\vec{r}(s)$ at a point then the rate of change of 'T' w.r.t 's' is called curvature of the curve at 'P'. It is denoted by k .
The reciprocal of k is called radius of curvature of the curve at 'P'. It is denoted

$$\text{by } r \text{ i.e. } r = \frac{1}{k}$$

Note: $|\frac{dT}{ds}| = k$. (from (i), $|N| = 1$).

$$(2) \frac{dR}{ds} = -T N$$

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since $|N| = 1$.

i.e. R is of constant magnitude.

$$\therefore R \cdot \frac{dR}{ds} = 0$$

$\therefore \frac{dR}{ds}$ is perpendicular to R .

We know that $\frac{dR}{ds}$ lies in the osculating plane.

Now we have

$$R \cdot T = 0$$

$$\Rightarrow R \cdot \frac{dT}{ds} + \frac{dR}{ds} \cdot T = 0 \quad (\text{by diff. w.r.t.})$$

$$\Rightarrow R \cdot (kN) + \frac{dR}{ds} \cdot T = 0. \quad (\because \frac{dT}{ds} = kN)$$

$$\Rightarrow \frac{d\alpha}{ds} \cdot T + (a \cdot N) k = 0.$$

$$\Rightarrow \frac{d\alpha}{ds} \cdot T = 0. (\because a \cdot N = 0)$$

$$\Rightarrow T \cdot \frac{d\alpha}{ds} = 0.$$

$\Rightarrow \frac{d\alpha}{ds}$ is \perp to T .

Since $\frac{d\alpha}{ds}$ lies in the osculating plane
so it must be parallel to N .

$$\therefore \frac{d\alpha}{ds} = \mp \tau N.$$

By convention, $\frac{d\alpha}{ds} = -\tau N$. (ii)

Torsion:- If B is the binormal vector to the curve $\vec{r}(s)$ at a point 'p' then the rate of change of B w.r.t. 's' is called torsion of the curve at 'p'. It is denoted by τ .

The reciprocal of τ is called the radius of torsion and is denoted by σ .

$$\text{i.e. } \sigma = \frac{1}{\tau}.$$

Note:- $\left| \frac{d\beta}{ds} \right| = \tau$ (from (ii), $|N| = 1$).

$$(3) \frac{dN}{ds} = \tau N - kT$$

Now we have $B \times T = N$.

$$\Rightarrow N \times \frac{dT}{ds} + \frac{dN}{ds} \times T = \frac{dN}{ds} \quad (\text{by diff. wrt. s})$$

$$\Rightarrow N \times (kN) + (\tau N) \times T = \frac{dN}{ds}$$

$$\Rightarrow \frac{dN}{ds} = k(N \times N) - \tau (N \times T)$$

$$= k(-N) - \tau (-N)$$

$$= \tau N - kT$$

Hence the

Part-2

Given curve is

$$x = t, y = t^2, z = \frac{2}{3}t^3$$

$$\therefore \vec{r}(t) = \hat{x}\hat{i} + \hat{y}\hat{j} + \hat{z}\hat{k}$$

$$= t\hat{i} + t^2\hat{j} + \frac{2}{3}t^3\hat{k}$$

$$\therefore \frac{d\vec{r}}{dt} = \hat{i} + 2t\hat{j} + 2t^2\hat{k} \quad \dots\dots(1)$$

$$\therefore \left| \frac{d\vec{r}}{dt} \right| = \frac{ds}{dt} = \sqrt{1 + 4t^2 + 4t^4}$$

$$\frac{d^3\vec{r}}{dt^3} = 4\hat{k}$$

$$\therefore k = \frac{\left| \frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} \right|}{\left| \frac{d\vec{r}}{dt} \right|^3}$$

$$\begin{aligned} \therefore \frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 2t & 2t^2 \\ 0 & 2 & 4t \end{vmatrix} \\ &= \hat{i}(8t^2 - 4t^2) - \hat{j}(4t) + \hat{k}(2) \\ &= (4t^2)\hat{i} - (4t)\hat{j} + 2\hat{k} \end{aligned}$$

$$k = \frac{2\sqrt{1 + 4t^2 + 4t^4}}{\left(\sqrt{1 + 4t^2 + 4t^4}\right)^3} = \frac{2}{1 + 4t^2 + 4t^4}$$

$$T = \text{Torsion} = \frac{\left[\frac{d\vec{r}}{dt} \frac{d^2\vec{r}}{dt^2} \frac{d^3\vec{r}}{dt^3} \right]}{\left| \frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} \right|^2}$$

$$= \frac{\begin{vmatrix} 1 & 2t & 2t^2 \\ 0 & 2 & 4t \\ 0 & 0 & 4 \end{vmatrix}}{4(1 + 4t^2 + 4t^4)}$$

$$= \frac{4(2)}{4(1 + 4t^2 + 4t^4)}$$

$$T = \frac{2}{1 + 4t^2 + 4t^4}$$

$$K = T$$

8(b). Verify Green's theorem in the plane for

$$\oint_C \{ \{xy + y^2\} dx + x^2 dy\}$$

where C is the closed curve of the region bounded by $y = x$ and $y = x^2$.

SOLUTION

Given integral is

$$\oint_C [(xy + y^2) dx + x^2 dy]$$

Comparing above integral with

$$\oint_C (P dx + Q dy)$$

we get

$$P = xy + y^2$$

$$Q = x^2$$

According to Green's theorem

$$\oint_C P dx + Q dy = \iint_S \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy$$

$$\begin{aligned} \text{L.H.S.} &= \oint_C P dx + Q dy \\ &= \oint_C (dy + y^2) dx + x^2 dy \end{aligned} \quad \dots\dots(2)$$

where C(curve) is region bounded by

$$\text{Let } \left. \begin{array}{l} C_2 : y = x \\ C_1 : y = x^2 \end{array} \right\} \quad \dots\dots(1)$$

Along the curve $C_1 : y = x^2$

$$dy = 2x dx$$

$$(2) \Rightarrow \text{L.H.S.} \int_{C_1} (x \cdot x^2 + x^4) dx + x^2 (2x dx)$$

$$= \int_0^1 (x^4 + x^3 + 2x^3) dx$$

$$= \int_0^1 (x^4 + 3x^3) dx$$

$$= \left. \frac{x^5}{5} + \frac{3x^4}{4} \right|_0^1 = \frac{1}{5} + \frac{3}{4} = \frac{19}{20}$$

Along the curve C_2

$$= \int_C (xy + y^2) dx + x^2 dy$$

Now put $y = x$

$$= \int_{C_2} (x^2 + x^2) dx + x^2 dx$$

$$= \int_1^0 3x^2 dx = 3 \frac{x^3}{3} \Big|_1^0 = -1$$

$$\therefore \int_C P dx + Q dy = +\frac{19}{20} - 1 = \frac{-1}{20}$$

$$R.H.S. = \iint_S \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy$$

$$= \int_{x=0}^{x=1} \int_{y=x^2}^{y=x} \left[\frac{\partial}{\partial x} (x^2) - \frac{\partial}{\partial y} (xy + y^2) \right] dy \cdot dx$$

$$= \int_{x=0}^1 \int_{y=x^2}^x (2x - x - 2y) dy \cdot dx$$

$$= \int_{x=0}^1 xy - y^2 \Big|_{x^2}^x \cdot dx$$

$$= \int_{x=0}^1 (-x^3 + x^4 + x^2 - x^2) dx = \int_{x=0}^1 x^4 - x^3 dx$$

$$= \frac{-x^4}{4} + \frac{x^5}{5} \Big|_0^1$$

$$= \frac{-1}{4} + \frac{1}{5} = \frac{-1}{20}$$

Hence L.H.S. = R.H.S.

Green's theorem verified

8.(c) If $\vec{F} = y\hat{i} + (x - 2xz)\hat{j} - xy\hat{k}$, evaluate

$$\iint_S (\vec{\nabla} \times \vec{F}) \cdot \vec{n} d\bar{s}$$

where S is the surface of the sphere $x^2 + y^2 + z^2 = a^2$ above the xy -plane.

SOLUTION

$$\vec{F} = y\hat{i} + (x - 2xz)\hat{j} - xy\hat{k}$$

$$I = \iint_S (\vec{\nabla} \times \vec{F}) \cdot \vec{n} d\bar{s}$$

where S : $x^2 + y^2 + z^2 = a^2$ above xy plane

$$\therefore \vec{\nabla} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y & x - 2xz & -xy \end{vmatrix}$$

$$\begin{aligned} &= \hat{i} \left(\frac{\partial(-xy)}{\partial y} - \frac{\partial}{\partial z}(x - 2xz) \right) - \hat{j} \left(\frac{\partial}{\partial z}(y) + \frac{\partial}{\partial x}(-xy) \right) + \hat{k} \left(\frac{\partial}{\partial x}(x - 2xz) - \frac{\partial}{\partial y}(y) \right) \\ &= (-x + 2x)\hat{i} - \hat{j}(-y) + \hat{k}(1 - 2z - 1) \\ &= x\hat{i} + y\hat{j} - 2x\hat{k} \end{aligned}$$

$$\hat{n} = \frac{\nabla S}{|\nabla S|} = \frac{2x\hat{i} + 2y\hat{j} + 2z\hat{k}}{\sqrt{4x^2 + 4y^2 + 4z^2}} = \frac{2x\hat{i} + 2y\hat{j} + 2z\hat{k}}{2\sqrt{x^2 + y^2 + z^2}}$$

$$= \frac{x\hat{i} + y\hat{j} + z\hat{k}}{a}$$

$$\therefore (\vec{\nabla} \times \vec{F}) = \left(\frac{x^2 + y^2 - 2z^2}{a} \right)$$

$$dS = \frac{dx dy}{|\hat{n} - \hat{k}|} = \frac{dx dy}{\left| (x\hat{i} + y\hat{j} + z\hat{k})(-\hat{k}) \right|} = \frac{dx dy}{\left| \left(\frac{-z}{a} \right) \right|} = \frac{dx dy}{\frac{z}{a}}$$

$$\therefore I = \int \left(\frac{x^2 + y^2 - 2z^2}{a} \right) \frac{dx dy}{z/a} \quad \because z \neq x^2 - y^2$$

$$= \iint \frac{x^2 + y^2 - 2(x^2 - y^2)}{\sqrt{a^2 - x^2 - y^2}} dx dy = \iint \frac{3(x^2 + y^2) - 2a^2}{\sqrt{a^2 - x^2 - y^2}} dx dy$$

In xy -plane

$$x^2 + y^2 = r^2 \text{ & } z = 0$$

Let

$$x = r \cos\theta$$

$$y = r \sin\theta$$

$$dx dy = r dr d\theta$$

$$\Rightarrow I = \iint \frac{3r^2 - 2z^2}{a^2 - r^2} dx dy$$

$$= \iint \frac{3r^2 - 2z^2}{a^2 - r^2} r dr d\theta$$

$$= \int_{\theta=0}^{\pi/2} \left(\int_{r=0}^a \frac{3r^2 - 2a^2}{\sqrt{a^2 - r^2}} r dr \right) d\theta \frac{\pi}{2} \times \int_{r=0}^a \frac{3r^2 - 2a^2 r}{\sqrt{a^2 - r^2}}$$

Let

$$r = a \sin t$$

$$dr = a \cos t dt$$

$$= \frac{\pi}{2} \int_0^{\pi/2} \frac{3a^2 \sin t - 2a^2}{a \cos t} \times a \sin t \times a \cos t dt$$

$$= \frac{\pi}{2} - \int_0^{\pi/2} \left[3a^3 (1 - \cos^2 t) - 2a^3 \right] d(\cot)$$

$$= \frac{-\pi}{2} \int_0^{\pi/2} \left[3a^3 \cot - 3a^3 \frac{\cos^3 t}{3} - 2a^3 \cot \right] dt$$

$$= \frac{-\pi}{2} [a^3 \cot - a^3 \cos^3 t] = 0$$

Hence value of integral

$$\boxed{\iint_S (\vec{\nabla} \times \vec{F}) \cdot \vec{n} ds = 0}$$

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