

6(a) solve $x \frac{d^2 y}{dx^2} - \frac{dy}{dx} - 4x^3 y = 8x^3 \sin x^2$

by changing the independent variable. (10)

$$\frac{d^2 y}{dx^2} - \frac{1}{x} \frac{dy}{dx} - (4x^2) y = 8x^2 \sin x^2$$

Comparing it with

$$\frac{d^2 y}{dx^2} + P \frac{dy}{dx} + Q y = R$$

$$P = -\frac{1}{x}, \quad Q = -4x^2, \quad R = 8x^2 \sin x^2$$

$$\text{Let } \left(\frac{dz}{dx} \right)^2 = \pm a^2 Q = 4x^2 \quad (\text{for } a=1)$$

$$\frac{dz}{dx} = 2x \Rightarrow \boxed{z = x^2}$$

(Note that $\frac{dz}{dx} = e^{-\int P dx}$ is not working here)

$$\text{Now, } P_1 = \frac{\frac{d^2 z}{dx^2} + P \frac{dz}{dx}}{\left(\frac{dz}{dx} \right)^2} = \frac{2 + \left(-\frac{1}{x} \right) 2x}{4x^2}$$

$$P_1 = \frac{0}{\left(\frac{dz}{dx} \right)^2} = \frac{-4x^2}{4x^2} = -1$$

$$R_1 = \frac{R}{\left(\frac{dz}{dx} \right)^2} = \frac{8x^2 \sin x^2}{4x^2} = 2 \sin x^2 = 2 \sin z$$

Transformed Eqn is:

$$\frac{d^2 y}{dz^2} + P_1 \frac{dy}{dz} + Q_1 y = R_1$$

$$\frac{d^2 y}{dz^2} - 1(y) = 2 \sin z$$

$$\text{i.e. } (D'^2 - 1)y = 2 \sin z$$

$$\text{Auxiliary Eqn: } D'^2 - 1 = 0$$

$$D' = 1, -1$$

$$\begin{aligned} \text{C.F.} &= C_1 e^z + C_2 e^{-z} \\ &= C_1 e^{x^2} + C_2 e^{-x^2} \end{aligned}$$

$$\text{P.I.} = \frac{1}{D'^2 - 1} 2 \sin z$$

$$= \frac{2}{(-1^2) - 1} \sin z = -\sin z$$

$$= -\sin x^2$$

Hence Complete Solution is:

$$y = \text{CF} + \text{PI}$$

$$y = C_1 e^{x^2} + C_2 e^{-x^2} - \sin x^2$$

Example 3. Forces X, Y, Z act along the three straight lines $y = b, z = -c$; $z = c, x = -a$; and $x = a, y = -b$ respectively. Show that they will have a single resultant if $\frac{a}{X} + \frac{b}{Y} + \frac{c}{Z} = 0$ and that the equations of its line of action are any two of the three

$$\frac{y}{Y} - \frac{z}{Z} - \frac{a}{X} = 0, \quad \frac{z}{Z} - \frac{x}{X} - \frac{b}{Y} = 0, \quad \frac{x}{X} - \frac{y}{Y} - \frac{c}{Z} = 0.$$

Solution. The forces X, Y, Z act along the lines

$$y = b, z = -c; \quad z = c, x = -a; \quad x = a, y = -b.$$

The equations of these lines are

$$\frac{x-0}{1} = \frac{y-b}{0} = \frac{z+c}{0}, \quad \frac{x+a}{0} = \frac{y-0}{1} = \frac{z-c}{0}, \quad \frac{x-a}{0} = \frac{y+b}{0} = \frac{z-0}{1}$$

The forces acting on the body are as follows :

(i) A force X acting at the point $(0, b, -c)$ along the line whose d.c.'s are $\langle 1, 0, 0 \rangle$

(ii) A force Y acting at the point $(-a, 0, c)$ along the line whose d.c.'s are $\langle 0, 1, 0 \rangle$

(iii) A force Z acting at the point $(a, -b, 0)$ along the line whose d.c.'s are $\langle 0, 0, 1 \rangle$.

\therefore The components of the forces parallel to the axes are

$$X_1 = X \cdot 1 = X, \quad X_2 = Y \cdot 0 = 0, \quad X_3 = Z \cdot 0 = 0$$

$$Y_1 = X \cdot 0 = 0, \quad Y_2 = Y \cdot 1 = Y, \quad Y_3 = Z \cdot 0 = 0$$

$$Z_1 = X \cdot 0 = 0, \quad Z_2 = Y \cdot 0 = 0, \quad Z_3 = Z \cdot 1 = Z$$

If the system reduces to a single force $R = (X, Y, Z)$ acting at O and a couple $G = (L, M, N)$, then

$$X = \Sigma X_i = X_1 + X_2 + X_3 = X + 0 + 0 = X$$

$$Y = \Sigma Y_i = 0 + Y + 0 = Y$$

and $Z = \Sigma Z_i = 0 + 0 + Z = Z$

To find L, M, N

(i) Consider

$$\begin{aligned} \hat{i}L_1 + \hat{j}M_1 + \hat{k}N_1 &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ x_1 & y_1 & z_1 \\ X_1 & Y_1 & Z_1 \end{vmatrix} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 0 & b & -c \\ X & 0 & 0 \end{vmatrix} \\ &= \hat{i}(0) - \hat{j}(cX) + \hat{k}(-bX) \end{aligned}$$

$$\therefore L_1 = 0, \quad M_1 = -cX, \quad N_1 = -bX$$

$$\begin{aligned} \text{(ii) } \hat{i}L_2 + \hat{j}M_2 + \hat{k}N_2 &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ x_2 & y_2 & z_2 \\ X_2 & Y_2 & Z_2 \end{vmatrix} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -a & 0 & c \\ 0 & Y & 0 \end{vmatrix} \\ &= \hat{i}(-cY) - \hat{j}(0) + \hat{k}(-aY) \end{aligned}$$

$$\therefore L_2 = -cY, \quad M_2 = 0; \quad N_2 = -aY$$

$$(iii) \quad \hat{i}L_3 + \hat{j}M_3 + \hat{k}N_3 = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ x_3 & y_3 & z_3 \\ X_3 & Y_3 & Z_3 \end{vmatrix} \\ = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a & -b & 0 \\ 0 & 0 & Z \end{vmatrix} \\ = \hat{i}(-bZ) - \hat{j}(aZ) + \hat{k}(0)$$

$$\therefore L_3 = -bZ, \quad M_3 = -aZ, \quad N_3 = 0$$

$$\text{Here } L = \Sigma L_1 = -(bZ + cY), \quad M = \Sigma M_1 = -(cX + aZ)$$

and

$$N = \Sigma N_1 = -(bX + aY)$$

The system is equivalent to a single force if

$$LX + MY + NZ = 0 \quad \dots(1)$$

Substituting the values of L, M, N in (1), we have

$$-[(bZ + cY)X + (cX + aZ)Y + (bX + aY)Z] = 0$$

or

$$2[aYZ + bZX + cXY] = 0$$

or

$$\frac{a}{X} + \frac{b}{Y} + \frac{c}{Z} = 0 \quad \dots(2)$$

which is the required condition.

The equations of the line of action of the single force *i.e.*, of the central axis are

$$\frac{L - yZ + zY}{X} = \frac{M - zX + xZ}{Y} = \frac{N - xY + yX}{Z} = \frac{LX + MY + NZ}{X^2 + Y^2 + Z^2} = 0$$

 \therefore The equations of the line of action of the single resultant force are any two of the following three :

$$L - yZ + zY = 0, \quad M - zX + xZ = 0, \quad N - xY + yX = 0$$

or

$$-(bZ + cY) - yZ + zY = 0$$

$$-(cX + aZ) - zX + xZ = 0$$

$$-(bX + aY) - xY + yX = 0$$

Dividing these equations by YZ, ZX and XY respectively, we get

$$-\left(\frac{b}{Y} + \frac{c}{Z}\right) - \frac{y}{Y} + \frac{z}{Z} = 0, \quad -\left(\frac{c}{Z} + \frac{a}{X}\right) - \frac{z}{Z} + \frac{x}{X} = 0;$$

$$-\left(\frac{b}{Y} + \frac{a}{X}\right) - \frac{x}{X} + \frac{y}{Y} = 0$$

Using (2), we have

$$\frac{a}{X} - \frac{y}{Y} + \frac{z}{Z} = 0; \quad \frac{b}{Y} - \frac{z}{Z} + \frac{x}{X} = 0, \quad \frac{c}{Z} - \frac{x}{X} + \frac{y}{Y} = 0$$

or

$$\frac{y}{Y} - \frac{z}{Z} - \frac{a}{X} = 0, \quad \frac{z}{Z} - \frac{x}{X} - \frac{b}{Y} = 0, \quad \frac{x}{X} - \frac{y}{Y} - \frac{c}{Z} = 0$$

Hence the equations to its line of action are any two of the three

$$\frac{y}{Y} - \frac{z}{Z} - \frac{a}{X} = 0, \quad \frac{z}{Z} - \frac{x}{X} - \frac{b}{Y} = 0, \quad \frac{x}{X} - \frac{y}{Y} - \frac{c}{Z} = 0$$

6(c) Solve

$$(D^4 + D^2 + 1)y = e^{-x/2} \cos\left(\frac{\sqrt{3}x}{2}\right) \quad (10)$$

Auxiliary Eqn:

$$D^4 + D^2 + 1 = 0$$

$$(D^4 + 2D^2 + 1) - D^2 = 0$$

$$(D^2 + 1)^2 - D^2 = 0$$

$$(D^2 + D + 1)(D^2 - D + 1) = 0$$

$$\therefore D = \frac{-1 \pm i\sqrt{3}}{2}, \quad \frac{1 \pm i\sqrt{3}}{2}$$

$$C.F. = e^{x/2} \left(C_1 \cos \frac{\sqrt{3}x}{2} + C_2 \sin \frac{\sqrt{3}x}{2} \right)$$

$$+ e^{-x/2} \left(C_3 \cos \frac{\sqrt{3}x}{2} + C_4 \sin \frac{\sqrt{3}x}{2} \right)$$

$$= C_1 e^{x/2} \cos\left(\frac{\sqrt{3}x}{2} + C_2\right) + C_3 e^{-x/2} \cos\left(\frac{\sqrt{3}x}{2} + C_4\right)$$

$$P.I. = \frac{1}{D^4 + D^2 + 1} e^{-x/2} \cos \frac{\sqrt{3}x}{2}$$

$$= e^{-x/2} \frac{1}{\left(D - \frac{1}{2}\right)^4 + \left(D - \frac{1}{2}\right)^2 + 1} \cos \frac{\sqrt{3}x}{2}$$

$$= e^{-x/2} \frac{1}{\left(D - \frac{1}{2}\right)^2 \left[\left(D - \frac{1}{2}\right)^2 + 1 \right] + 1} \cos \frac{\sqrt{3}x}{2}$$

$$= e^{-x/2} \frac{1}{\left(D^2 - D + \frac{1}{4}\right) \left[\left(D^2 - D + \frac{1}{4}\right) + 1 \right] + 1} \cos \frac{\sqrt{3}x}{2}$$

$$\text{Put } f(D^2) = f\left(-\frac{3}{4}\right)$$

$$= e^{-x/2} \cdot \frac{1}{\left(\frac{-3}{4} - D + \frac{1}{4}\right) \left[\frac{-3}{4} - D + \frac{5}{4}\right] + 1} \cos \frac{\sqrt{3}x}{2}$$

$$= e^{-x/2} \cdot \frac{1}{\left(-D - \frac{1}{2}\right) \left[-D + \frac{1}{2}\right] + 1} \cos \frac{\sqrt{3}x}{2}$$

$$= e^{-x/2} \cdot \frac{1}{\left(D^2 - \frac{1}{4}\right) + 1} \cos \frac{\sqrt{3}x}{2}$$

$$= e^{-x/2} \cdot \frac{1}{\left(D^2 + \frac{3}{4}\right)} \cos \frac{\sqrt{3}x}{2}$$

$$= x \cdot e^{-x/2} \cdot \frac{1}{2D} \cos \frac{\sqrt{3}x}{2} \quad (\because f(D^2) = f(-a^2) \text{ is zero})$$

$$= \frac{x \cdot e^{-x/2}}{2} \cdot \frac{D}{D^2} \cos \frac{\sqrt{3}x}{2}$$

$$= \frac{x \cdot e^{-x/2}}{2} \cdot \frac{1}{-\frac{3}{4}} \left(-\sin \frac{\sqrt{3}x}{2}\right) \times \frac{\sqrt{3}}{2}$$

$$= \frac{x}{\sqrt{3}} e^{-x/2} \sin \frac{\sqrt{3}x}{2}$$

Hence, complete solution is

$$y = CF + PI$$

$$y = c_1 e^{x/2} \cos\left(\frac{\sqrt{3}x}{2} + c_2\right) + c_3 e^{-x/2} \cos\left(\frac{\sqrt{3}x}{2} + c_4\right) + \frac{x}{\sqrt{3}} e^{-x/2} \sin\left(\frac{\sqrt{3}x}{2}\right).$$

6(d) Examine if the vector field defined by
 $\vec{F} = 2xyz^3\mathbf{i} + x^2z^3\mathbf{j} + 3x^2yz^2\mathbf{k}$

is irrotational. If so find the scalar potential ϕ such that $\vec{F} = \text{grad } \phi$.

\vec{F} is irrotational if $\text{curl } \vec{F} = \nabla \times \vec{F} = 0$ ⁽¹⁰⁾

$$\nabla \times \vec{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2xyz^3 & x^2z^3 & 3x^2yz^2 \end{vmatrix}$$

$$= \mathbf{i}(3x^2z^2 - 3x^2z^2) + \mathbf{j}(6xyz^2 - 6xyz^2) + \mathbf{k}(2xz^3 - 2xz^3) = 0$$

$\therefore \vec{F}$ is irrotational.

$$\vec{F} = \text{grad } \phi = \nabla \phi = \frac{\partial \phi}{\partial x} \mathbf{i} + \frac{\partial \phi}{\partial y} \mathbf{j} + \frac{\partial \phi}{\partial z} \mathbf{k}$$

$$\left. \begin{aligned} \therefore \frac{\partial \phi}{\partial x} &= 2xyz^3 \\ \frac{\partial \phi}{\partial y} &= x^2z^3 \\ \frac{\partial \phi}{\partial z} &= 3x^2yz^2 \end{aligned} \right\} \Rightarrow \phi = x^2yz^3 + C$$

\therefore scalar potential, $\phi = x^2yz^3 + C$.