

# IFoS MATHEMATICS (OPT.)-2009

## PAPER - I : SOLUTIONS

1. @.

Let  $V$  be the vectorspace of polynomials over  $\mathbb{R}$ . Let  $U$  and  $W$  be the subspaces generated by  $\{t^3 + 4t^2 - t + 3, t^3 + 5t^2 + 5, 3t^3 + 10t^2 - 5t + 5\}$  and  $\{t^3 + 4t^2 + 6, t^3 + 2t^2 - t + 5, 2t^3 + 2t^2 - 3t + 9\}$  respectively. Find (i)  $\dim(U+W)$  (ii)  $\dim(U \cap W)$ .

Sol

Let  $S = \{t^3 + 4t^2 - t + 3, t^3 + 5t^2 + 5, 3t^3 + 10t^2 - 5t + 5\} = \{d_1, d_2, d_3\}$  (say)  
and  $T = \{t^3 + 4t^2 + 6, t^3 + 2t^2 - t + 5, 2t^3 + 2t^2 - 3t + 9\} = \{P_1, P_2, P_3\}$  (say.)  
since  $U$  and  $W$  are spanned by the sets  $S$  and  $T$  of all polynomials of degree 3.

$\therefore U$  and  $W$  are subspaces of the vectorspace  $V(\mathbb{R})$  of all real polynomials of degree  $\leq 3$ .

We know that the set  $S = \{1, t, t^2, t^3\}$  is a standard basis for  $V(\mathbb{R})$ .

Now the co-ordinate vectors of  $d_1, d_2$  &  $d_3$  w.r.t the above basis  $S$ , are

$$(3, -1, 4, 1), (5, 0, 5, 1) \text{ and } (5, -5, 10, 3)$$

Again, the co-ordinate vectors of  $P_1, P_2$  &  $P_3$  w.r.t the above basis  $S$ , are

$$(6, 0, 4, 1), (5, -1, 2, 1) \text{ and } (9, -3, 2, 2).$$

Since  $V$  and  $W$  are two subspaces of  $V(\mathbb{R}^2)$

$\therefore V+W$  is also subspace of  $V(\mathbb{R}^2)$

$\therefore V+W$  is the space generated by all the six co-ordinate vectors.

NOW form the matrix  $A$  whose rows are the given six ~~vectors~~ co-ordinate vectors and reduce it to an echelon form.

$$A = \begin{bmatrix} 3 & -1 & 4 & 1 \\ 5 & 0 & 5 & 1 \\ 5 & -5 & 10 & 3 \\ 6 & 0 & 4 & 1 \\ 5 & -1 & 2 & 1 \\ 9 & -3 & 2 & 2 \end{bmatrix}$$

$$\sim \begin{bmatrix} 3 & -1 & 4 & 1 \\ 0 & 5 & -5 & -2 \\ 0 & -10 & 10 & 4 \\ 0 & 2 & -4 & -1 \\ 0 & 2 & -14 & -2 \\ 0 & 0 & -10 & -1 \end{bmatrix} \quad \begin{array}{l} R_2 \rightarrow 3R_2 - 5R_1 \\ R_3 \rightarrow 3R_3 - 5R_1 \\ R_4 \rightarrow R_4 - 2R_1 \\ R_5 \rightarrow 3R_5 - 5R_1 \\ R_6 \rightarrow R_6 - 3R_1 \end{array}$$

$$\sim \begin{bmatrix} 3 & -1 & 4 & 1 \\ 0 & 5 & -5 & -2 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & -10 & -1 \\ 0 & 0 & -60 & -6 \\ 0 & 0 & -10 & -1 \end{bmatrix} \quad \begin{array}{l} R_3 \rightarrow R_3 + 2R_2 \\ R_4 \rightarrow 5R_4 - 2R_2 \\ R_5 \rightarrow 5R_5 - 2R_2 \end{array}$$

$$\sim \left[ \begin{array}{cccc} 3 & -1 & 4 & 1 \\ 0 & 5 & -5 & -2 \\ 0 & 0 & -10 & -1 \\ 0 & 0 & -10 & -1 \\ 0 & 0 & -60 & -6 \\ 0 & 0 & 0 & 0 \end{array} \right] R_3 \leftrightarrow R_6$$

$$\sim \left[ \begin{array}{cccc} 3 & -1 & 4 & 1 \\ 0 & 5 & -5 & -2 \\ 0 & 0 & -10 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] R_4 \rightarrow R_4 - R_3 \\ R_5 \rightarrow R_5 - 6R_3$$

∴ clearly which is in echelon form.  
 ∴ The echelon matrix of A has three non-zero rows.  
 ∴  $\dim(U \cup W) = 3.$

Now we form the matrix 'A' whose rows are the co-ordinate vectors of 'S' and reduce it to an echelon form

$$A = \left[ \begin{array}{cccc} 3 & -1 & 4 & 1 \\ 5 & 0 & 5 & 1 \\ 5 & -5 & 10 & 3 \end{array} \right] \sim \left[ \begin{array}{cccc} 3 & -1 & 4 & 1 \\ 0 & 5 & -5 & -2 \\ 0 & -10 & 10 & 4 \end{array} \right] R_2 \rightarrow 3R_2 - 5R_1 \\ R_3 \rightarrow 3R_3 - 5R_1$$

$$\sim \left[ \begin{array}{cccc} 3 & -1 & 4 & 1 \\ 0 & 5 & -5 & -2 \\ 0 & 0 & 0 & 0 \end{array} \right] R_3 \rightarrow R_3 + 2R_2$$

∴ The echelon matrix of A has two non-zero rows.

$$\therefore \underline{\dim(U) = 2}$$

Again form the matrix 'A' whose rows are the co-ordinate vectors of 'T' and reduce it to an echelon matrix.

$$A = \begin{bmatrix} 6 & 0 & 4 & 1 \\ 5 & -1 & 2 & 1 \\ 9 & -3 & 2 & 2 \end{bmatrix} \sim \begin{bmatrix} 6 & 0 & 4 & 1 \\ 0 & -5 & -8 & 1 \\ 0 & -18 & -24 & 3 \end{bmatrix} \begin{array}{l} R_2 \rightarrow 6R_2 - 5R_1 \\ R_3 \rightarrow 6R_3 - 9R_1 \end{array}$$

$$\sim \begin{bmatrix} 6 & 0 & 4 & 1 \\ 0 & -5 & -8 & 1 \\ 0 & -10 & -16 & 1 \end{bmatrix} \begin{array}{l} R_3 \rightarrow \frac{1}{3}R_3 \\ \text{---} \end{array}$$

$$\sim \begin{bmatrix} 6 & 0 & 4 & 1 \\ 0 & -5 & -8 & 1 \\ 0 & 0 & -16 & 1 \end{bmatrix} \begin{array}{l} R_3 \rightarrow R_3 + 4R_2 \\ R_3 \leftarrow R_3 \end{array}$$

$\therefore$  clearly which is echelon matrix of A and has two non-zero rows.

$$\therefore \dim(w) = 2$$

$$\text{Since } \dim(U \cap W) = \dim U + \dim W - \dim(U + W)$$

$$= 2 + 3 - 3$$

$$= 2$$

$$\therefore \boxed{\dim(U \cap W) = 2}$$

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1(b) Find a linear map  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^4$  whose image is generated by  $(1, 2, 0, -4)$  and  $(2, 0, -1, -3)$

Sol

Given that  $R(T)$  spanned by

$$\{(1, 2, 0, -4), (2, 0, -1, -3)\}.$$

Let us include a vector  $(0, 0, 0, 0)$  in this set which will not effect the spanning property.

$$\text{so that } S = \{(1, 2, 0, -4), (2, 0, -1, -3), (0, 0, 0, 0)\}.$$

Let  $B = \{\alpha_1, \alpha_2, \alpha_3\}$  be the standard basis of  $\mathbb{R}^3$ .

We know that, there exists a transformation  $T$  such that  $T(\alpha_1) = (1, 2, 0, -4)$

$$T(\alpha_2) = (2, 0, -1, -3) \text{ and}$$

$$T(\alpha_3) = (0, 0, 0, 0).$$

$$\text{Now if } \alpha \in \mathbb{R}^3 \Rightarrow \alpha = (a, b, c)$$

$$= a\alpha_1 + b\alpha_2 + c\alpha_3.$$

$$\therefore T(\alpha) = T(a\alpha_1 + b\alpha_2 + c\alpha_3)$$

$$= aT(\alpha_1) + bT(\alpha_2) + cT(\alpha_3)$$

( $\because T$  is a LT)

$$= a(1, 2, 0, -4) + b(2, 0, -1, -3)$$

$$+ c(0, 0, 0, 0)$$

$$= (a+2b, 2a, -b, -4a-3b)$$

$$\therefore T(a, b) = (a+2b, 2a, -b, -4a-3b)$$

which is the required

transformation.

1(c) (i) find the difference between the maximum and the minimum of the function

$(a - \frac{1}{2}x^2 - x)(4 - 3x^2)$  where  $a$  is a constant and greater than zero.

Sol. Let  $f(x) = (a - \frac{1}{2}x^2 - x)(4 - 3x^2)$  (1)  
where  $a$  is a constant and greater than zero.

$$\text{Now } f'(x) = (a - \frac{1}{2}x^2 - x)(-6x) + (-1)(4 - 3x^2).$$

$$\Rightarrow f'(x) = -6(a - \frac{1}{2}x^2 - x)x + 6x^2 - 4 + 3x^2 \\ = 9x^2 - 6(a - \frac{1}{2}x^2 - x) - 4. \quad (2)$$

For maximum or minimum

$$f'(x) = 0.$$

$$9x^2 - 6(a - \frac{1}{2}x^2 - x) - 4 = 0.$$

$$\Rightarrow x = \frac{6(a - \frac{1}{2}x^2 - x) \pm \sqrt{36(a - \frac{1}{2}x^2 - x)^2 + 36(4)}}{18}$$

$$\Rightarrow x = \frac{(a - \frac{1}{2}x^2 - x) \pm \sqrt{(a - \frac{1}{2}x^2 - x)^2 + 4}}{3}$$

$$\Rightarrow x = \frac{(a - \frac{1}{2}x^2 - x) \pm (a + \frac{1}{2}x^2)}{3}$$

$$\Rightarrow \boxed{x = \frac{2a}{3}} \text{ and } \boxed{x = -\frac{2}{3a}}$$

Now from (2),

$$f''(x) = 18x - 6(a - \frac{1}{2}x^2 - x). \quad (3)$$

$$\text{When } x = \frac{2a}{3} : - f''\left(\frac{2a}{3}\right) = \frac{18(2a)}{3} - 6(a - \frac{1}{3})$$

$$\begin{aligned}
 &= 12a - 6a + 6/a \\
 &= 6a + 6/a \\
 &> 0 \quad (\because a > 0).
 \end{aligned}$$

$f$  is minimum at  $x = \frac{2a}{3}$ .

$$\therefore f_{\min} = f\left(\frac{2a}{3}\right)$$

$$= \left(a - \frac{1}{3} - \frac{2a}{3}\right) \left(4 - 2\left(\frac{4a^2}{3}\right)\right)$$

$$= \left(\frac{a}{3} - \frac{1}{3}\right) \left(4 - \frac{4a^2}{3}\right) =$$

$$= \frac{4a}{3} - \frac{4}{3} - \frac{4a^3}{9} + \frac{4a}{3}$$

$$f_{\min} = \frac{8a}{3} - \frac{4}{3} - \frac{4a^3}{9}$$

(4)

$$\text{When } x = -\frac{2}{3a} : - f''\left(-\frac{2}{3a}\right) = 18\left(-\frac{2}{3a}\right) - 6\left(a - \frac{1}{3}\right)$$

$$= -\frac{12}{a} - 6a + 6/a$$

$$= -\frac{6}{a} - 6a$$

$$= -6\left(\frac{1}{a} + a\right)$$

$$< 0 \quad (\because a > 0)$$

$f$  is maximum at  $x = -\frac{2}{3a}$ .

$$\therefore f_{\max} = f\left(-\frac{2}{3a}\right)$$

$$f_{\max} = 4a - \frac{8}{3a} + \frac{4}{9a^2}$$

(5)

Now the difference between the maximum and the minimum value of the function is

$$\left(4\alpha^2 - \frac{8}{3\alpha} + \frac{4}{9\alpha^3}\right) - \left(\frac{8\alpha}{3} - \frac{4}{\alpha} - \frac{4\alpha^3}{9}\right)$$

$$= \frac{4\alpha}{3} + \frac{4}{3\alpha} + \frac{4}{9} \left(\frac{1}{\alpha^3} + \alpha^3\right)$$

$$= \frac{4}{3} (\alpha + \frac{1}{\alpha}) + \frac{4}{9} [(\alpha + \frac{1}{\alpha})(\alpha^2 + 1 + \frac{1}{\alpha^2})]$$

$$= (\alpha + \frac{1}{\alpha}) \left[ \frac{4}{3} + \frac{4}{9} (\alpha^2 + 1 + \frac{1}{\alpha^2}) \right]$$

$$= (\alpha + \frac{1}{\alpha}) \left[ (\alpha^2 + 1) \frac{4}{9} + \frac{16}{9} \right]$$

$$= \frac{4}{9} (\alpha + \frac{1}{\alpha}) \left[ (\alpha^2 + 1) + 4 \right].$$

(ii) If  $f(h) = f(0) + hf'(0) + \frac{h^2}{2!} f''(0h)$ ,  
 $0 < \alpha < 1$ .

Find  $\alpha$ , when  $h=1$  and  $f(x) = (1-x)^{5/2}$ .

Sol Given that  $f(x) = (1-x)^{5/2} \Rightarrow f(h) = (1-h)^{5/2}$

and  $f'(x) = -5/2(1-x)^{3/2} \Rightarrow f'(0) = -5/2$

$\Rightarrow f''(x) = 15/4(1-x)^{1/2} \Rightarrow f''(0h) = \frac{15}{4}(1-\alpha h)^{1/2}$

$$\therefore f(h) = f(0) + h f'(0) + \frac{h^2}{2!} f''(0),$$

$$0 < \theta < 1.$$

$$\Rightarrow (1-h)^{5/2} = 1 + h(-\frac{5}{2}) + \frac{h^2}{2!} (\frac{15}{4})(1-\theta h)^{1/2}.$$

$$\text{when } h=1$$

$$\therefore 0 = 1 + 1(-\frac{5}{2}) + \frac{1}{2} (\frac{15}{4}) - (1-\theta)^{1/2}$$

$$\Rightarrow 0 = 1 - \frac{5}{2} + \frac{15}{8} - (1-\theta)^{1/2}$$

$$\Rightarrow 0 = \frac{3}{8} - (1-\theta)^{1/2}$$

$$\Rightarrow (1-\theta)^{1/2} = \frac{3}{8}$$

$$\Rightarrow 1-\theta = \frac{9}{64}$$

$$\Rightarrow 1 - \frac{9}{64} = \theta$$

$$\Rightarrow \frac{55}{64} = \theta$$

$$\Rightarrow \theta = \frac{55}{64} \in (0, 1).$$

                      =

1(d) Evaluate

$$(i) \int_0^{\pi/2} \frac{\sin x}{\sin x + \cos x} dx$$

$$(ii) \int_1^\infty \frac{x^2}{(1+x^2)^2} dx.$$

Sol (i) Let  $I = \int_0^{\pi/2} \frac{\sin x}{\sin x + \cos x} dx$ . (clearly, which is a proper integral)

Then  $I = \int_0^{\pi/2} \frac{\sin(\frac{\pi}{2}-x)}{\sin(\frac{\pi}{2}-x) + \cos(\frac{\pi}{2}-x)} dx$  ( $\because \int_a^b f(x) dx = \int_0^a f(a-x) dx$ )

$$= \int_0^{\pi/2} \frac{\cos^2 x}{\sin x + \cos x} dx.$$

$$\begin{aligned} \Rightarrow 2I &= \int_0^{\pi/2} \frac{\sin x}{\sin x + \cos x} dx + \int_0^{\pi/2} \frac{\cos x}{\sin x + \cos x} dx \\ &= \int_0^{\pi/2} \frac{\sin x + \cos x}{\sin x + \cos x} dx \\ &= \int_0^{\pi/2} 1 dx. \end{aligned}$$

$$= \frac{1}{\sqrt{2}} \int_0^{\pi/2} \frac{1}{\frac{1}{\sqrt{2}} \sin x + \frac{1}{\sqrt{2}} \cos x} dx$$

$$= \frac{1}{\sqrt{2}} \int_0^{\pi/2} \frac{1}{\cos(\frac{\pi}{4}) \sec(x - \frac{\pi}{4})} dx$$

$$= \frac{1}{\sqrt{2}} \int_0^{\pi/2} \sec(x - \frac{\pi}{4}) dx.$$

$$\begin{aligned}
 &= \frac{1}{\sqrt{2}} \left[ \log \left( \sec \left( \alpha - \frac{\pi}{4} \right) + \tan \left( \alpha - \frac{\pi}{4} \right) \right) \right]^{\pi/2} \quad (6) \\
 &= \frac{1}{\sqrt{2}} \left[ \log \left( \sec \frac{\pi}{4} + \tan \frac{\pi}{4} \right) - \log \left[ \sec \left( -\frac{\pi}{4} \right) + \tan \left( -\frac{\pi}{4} \right) \right] \right] \\
 &= \frac{1}{\sqrt{2}} \left[ \log (\sqrt{2}+1) - \log (\sqrt{2}-1) \right] \quad \left( \because \sec \left( -\frac{\pi}{4} \right) = \sec \frac{\pi}{4} \right) \\
 &= \frac{1}{\sqrt{2}} \log \left( \frac{\sqrt{2}+1}{\sqrt{2}-1} \right) \\
 &= \frac{1}{\sqrt{2}} \log (\sqrt{2}+1)^2 \\
 &= \sqrt{2} \log (\sqrt{2}+1)
 \end{aligned}$$

$$\therefore 2I = \sqrt{2} \log (\sqrt{2}+1)$$

$$\Rightarrow I = \frac{1}{\sqrt{2}} \log (\sqrt{2}+1)$$

$$(ii) \int_1^{\infty} \frac{x^{\alpha}}{(1+x^{\alpha})^2} dx = \text{let } t = x^{\alpha} \quad \int_1^{\infty} \frac{x^{\alpha}}{(1+t^{\alpha})^2} dt \quad (i)$$

NOW putting  $x = t^{\alpha}$

$$\Rightarrow dx = \sec^{\alpha} \alpha d\alpha$$

$$\int \frac{x^{\alpha}}{(1+x^{\alpha})^2} dx = \int \frac{\tan^{\alpha} \alpha}{(1+\tan^{\alpha} \alpha)^2} \cdot \sec^{\alpha} \alpha d\alpha.$$

$$= \int \frac{\tan^{\alpha} \alpha}{(\sec^2 \alpha)^2} \cdot \sec^{\alpha} \alpha d\alpha$$

$$= \int \frac{\tan^{\alpha} \alpha}{\sec^{\alpha} \alpha} d\alpha.$$

$$= \int \frac{\sin^{\alpha} \alpha}{\cos^{\alpha} \alpha} \cdot \frac{\cos \alpha}{1} d\alpha$$

$$= \int \left( 1 - \frac{\cos 2\alpha}{2} \right) d\alpha$$

$$\begin{aligned}&= \frac{1}{2} \int (1 - \cos x) dx \\&= \frac{1}{2} \left( x - \frac{\sin x}{2} \right). \\&= \frac{1}{2} \left( \tan^{-1} x - \frac{x}{1+x^2} \right) \quad (\because x = \tan^{-1} t) \\&= \frac{1}{2} \left( \tan^{-1} x - \frac{x}{1+x^2} \right).\end{aligned}$$

Now from ①,

$$\begin{aligned}\int_1^\infty \frac{x}{(1+x^2)^{3/2}} dx &= \lim_{t \rightarrow \infty} \int_1^t \frac{x}{(1+x^2)^{3/2}} dx \\&= \lim_{t \rightarrow \infty} \left[ \frac{1}{2} \left( \tan^{-1} x - \frac{x}{1+x^2} \right) \right]_1^t \\&= \frac{1}{2} \lim_{t \rightarrow \infty} \left[ \left( \tan^{-1} t - \frac{t}{1+t^2} \right) - \left( \frac{\pi}{4} - \frac{1}{2} \right) \right] \\&= \frac{1}{2} \left[ \frac{\pi}{4} - 0 - \frac{\pi}{4} + \frac{1}{2} \right] \\&= \frac{1}{2} \left[ \frac{1+\pi}{4} \right].\end{aligned}$$

$= \frac{\pi}{4} + \frac{\pi}{8}$ , which is finite.

$\int_1^\infty \frac{x}{(1+x^2)^{3/2}} dx$  is convergent and its value is  $\frac{1}{2} + \frac{\pi}{8}$

→ Qe. Show that the plane  $x+2y-z=4$  cuts the sphere  $x^2+y^2+z^2-x+y=2$  in a circle of radius unity and find the equation of the sphere which has this circle as one of its great circles.

Sol: The given sphere

$$x^2+y^2+z^2-x+y-2=0 \quad \textcircled{1}$$

and the plane

$$x+2y-z-4=0 \quad \textcircled{2}$$

Centre of the sphere  $\textcircled{1}$

$$C\left(\frac{1}{2}, 0, -\frac{1}{2}\right)$$

and its radius is

$$CP = \sqrt{\frac{1}{4} + 0 + \frac{1}{4} + 2}$$

$$= \sqrt{3\frac{1}{2}}$$

$CA =$  distance from  $C(k_1, 0, -k_2)$

to the plane  $\textcircled{2}$

$$= \frac{\left| \frac{1}{2} + 2(0) - \left(-\frac{1}{2}\right) - 4 \right|}{\sqrt{1+4+1}}$$

$$= \frac{3}{\sqrt{6}} = \sqrt{3\frac{1}{2}}$$

∴ Radius of circle

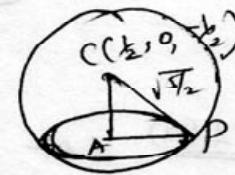
$$AP = \sqrt{CP^2 - CA^2}$$

$$= \sqrt{3\frac{1}{2} - 3\frac{1}{2}}$$

$$= \sqrt{1} = 1$$

∴ The plane  $\textcircled{2}$  meets the sphere  $\textcircled{1}$  in a circle of radius unity.

Now any sphere through the intersection of  $\textcircled{1}$  &  $\textcircled{2}$  is



$$x^2 + y^2 + z^2 - x + z - 2 + k(x + 2y - z - 4) = 0 \quad \textcircled{3}$$

If the circle of intersection of ① & ② is a great circle of sphere ③;

then the centre  $\left(\frac{1-k}{2}, -k, \frac{k-1}{2}\right)$  lies on the plane ②.

$$\therefore \frac{1-k}{2} + 2(-k) - \left(\frac{k-1}{2}\right) - 4 = 0$$

$$\Rightarrow k = -1$$

$$\therefore \textcircled{3} \underline{\underline{x^2 + y^2 + z^2 - 2x - 2y + 2z + 2 = 0}}$$

→ 2(a). Let  $T$  be the linear operator on  $\mathbb{R}^3$  defined by  $T(x, y, z) = (2x, 4x-y, 2x+3y-z)$ .

- (i) Show that  $T$  is invertible.
- (ii) Find a formula for  $T^{-1}$ .

Soln: Let  $(x, y, z) \in \ker T$  be arbitrary.

$$\text{Then } T(x, y, z) = (0, 0, 0)$$

$$\Rightarrow (2x, 4x-y, 2x+3y-z) = (0, 0, 0)$$

$$\Rightarrow 2x = 0, 4x-y = 0 \text{ & } 2x+3y-z = 0.$$

$$\Rightarrow x = 0, y = 0, z = 0.$$

$$\text{and so } (x, y, z) = (0, 0, 0)$$

$$\Rightarrow \ker T = \{(0, 0, 0)\}$$

Hence  $T$  is invertible.

(i) Now we shall find  $T^{-1}$ .

Since  $T$  invertible.

$\therefore T$  is onto.

(8)

for any  $(a, b, c) \in \mathbb{R}^3$ , there exists some  $(x, y, z) \in \mathbb{R}^3$  such that

$$\begin{aligned} T(x, y, z) &= (a, b, c) \\ \Rightarrow (2x, 4x-y, 2x+3y-z) &= (a, b, c) \\ \Rightarrow 2x &= a, \quad 4x-y = b, \quad 2x+3y-z = c \\ \Rightarrow x &= \frac{a}{2}, \quad y = 2a-b \end{aligned}$$

$$\text{from } 2x+3y-z=c$$

$$\begin{aligned} 2\left(\frac{a}{2}\right) + 3(2a-b) - z &= c \\ a + 6a - 3b - z &= c \\ \Rightarrow z &= 7a - 3b - c \end{aligned}$$

$$\text{Hence } T(x, y, z) = (a, b, c)$$

$$\Rightarrow T^{-1}(a, b, c) = (x, y, z)$$

$$\Rightarrow T^{-1}(a, b, c) = \left( \frac{a}{2}, 2a-b, 7a-3b-c \right). \quad \forall (a, b, c) \in \mathbb{R}^3.$$

2(b)

→ find the rank of the matrix:

$$A = \begin{bmatrix} 1 & 3 & 1 & -2 & -3 \\ 1 & 4 & 3 & -1 & -4 \\ 2 & 3 & -4 & -7 & -3 \\ 3 & 8 & 1 & -7 & -8 \end{bmatrix}$$

$$\overset{\text{Soln.}}{A} = \begin{bmatrix} 1 & 3 & 1 & -2 & -3 \\ 1 & 4 & 3 & -1 & -4 \\ 2 & 3 & -4 & -7 & -3 \\ 3 & 8 & 1 & -7 & -8 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 3 & 1 & -2 & -3 \\ 0 & 1 & 2 & -1 & -1 \\ 0 & -3 & -6 & -3 & 3 \\ 0 & -1 & -2 & -1 & 1 \end{bmatrix} \quad \begin{array}{l} R_2 \rightarrow R_2 - R_1 \\ R_3 \rightarrow R_3 - 3R_1 \\ R_4 \rightarrow R_4 - R_1 \end{array}$$

$$\sim \left[ \begin{array}{ccccc} 1 & 3 & 1 & -2 & -3 \\ 0 & 1 & 2 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \quad \begin{array}{l} R_3 \rightarrow R_3 + 3R_2 \\ R_4 \rightarrow R_4 + R_2 \end{array}$$

which is in echelon form.

The number of non-zero rows of this echelon form is 2.

$$\therefore \text{r}(A) = 2.$$

Q2(C) Let  $A = \begin{bmatrix} 1 & -3 & 3 \\ 3 & -5 & 3 \\ 6 & -6 & 4 \end{bmatrix}$ . Is A similar to a diagonal matrix? If so, find an invertible matrix P such that  $P^{-1}AP$  is a diagonal matrix.

Soln: The characteristic equation of A is

$$\begin{aligned} |A - \lambda I| &= 0 \\ \begin{vmatrix} 1-\lambda & -3 & 3 \\ 3 & -5-\lambda & 3 \\ 6 & -6 & 4-\lambda \end{vmatrix} &= 0 \\ \Rightarrow (1-\lambda)[-(5+\lambda)(4-\lambda) + 18] &+ 3[3(4-\lambda) - 18] \\ &+ 3[-18 + 6(5+\lambda)] = 0 \\ \Rightarrow (1-\lambda)[-20-\lambda-\lambda^2] &+ 18 + 9\lambda = 0 \\ &+ 3[12+6\lambda] = 0 \\ \Rightarrow (1-\lambda)[-2+\lambda+\lambda^2] &+ 18 + 9\lambda = 0 \\ \Rightarrow (1-\lambda)[(\lambda+2)(\lambda-1)] &+ 9(\lambda+2) = 0 \\ \Rightarrow (\lambda+2)[-(\lambda-1)^2 + 9] &= 0 \\ \Rightarrow (\lambda+2)(-\lambda^2+2\lambda+8) &= 0. \end{aligned}$$

(9)

$$\begin{aligned}
 &\Rightarrow (\lambda+2) [-\lambda^2 + 4\lambda - 2\lambda + 8] = 0 \\
 &\Rightarrow (\lambda+2) [-\lambda(\lambda-4) - 2(\lambda-4)] = 0 \\
 &\Rightarrow (\lambda+2) [(-\lambda-2)(\lambda-4)] = 0 \\
 &\Rightarrow (\lambda+2)(\lambda+2)(\lambda-4) = 0 \\
 &\Rightarrow \lambda = -2, -2, 4.
 \end{aligned}$$

$\therefore$  The characteristic roots of A  
are  $-2, -2, 4$ .

The eigen vectors  $x$  of A corresponding  
to the eigen value  $-2$  are given by

$$(A - (-2)\mathbf{I})x = 0.$$

$$\Rightarrow \begin{bmatrix} 3 & -3 & 3 \\ 3 & -3 & 3 \\ 6 & -6 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 3 & -3 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{array}{l} R_2 \rightarrow R_2 - R_1 \\ R_3 \rightarrow R_3 - 2R_1 \end{array}$$

The rank of coefficient matrix = 1.

$\therefore$  The equations have  $3-1=2$  L.I  
solutions corresponding to eigen  
value  $-2$ .

$\therefore$  we have

$$3x_1 - 3x_2 + 3x_3 = 0$$

$$\Rightarrow x_1 - x_2 + x_3 = 0$$

Let  $x_2 = k_1$  and  $x_3 = k_2$ :

where  $k_1, k_2$  are  
arbitrary constants.

$$\therefore x_1 = k_1 - k_2$$

$$\therefore x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} k_1 - k_2 \\ k_1 \\ k_2 \end{bmatrix} = k_1 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + k_2 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

$$x = k_1 x_1 + k_2 x_2$$

Here  $x_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$  &  $x_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$  are L.S.

vectors of A corresponding to characteristic root -2.

$\therefore$  The geometric multiplicity of eigenvalue is equal to its algebraic multiplicity.

NOW the eigen vectors x of A corresponding to the eigen value 4 are given by

$$(A - 4I)x = 0$$

$$\Rightarrow \begin{bmatrix} -3 & -3 & 3 \\ 3 & -9 & 3 \\ 6 & -6 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -3 & -3 & 3 \\ 0 & -12 & 6 \\ 0 & -12 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad R_2 \rightarrow R_2 + R_1 \\ R_3 \rightarrow R_3 + 2R_1$$

$$\sim \begin{bmatrix} -3 & -3 & 3 \\ 0 & -12 & 6 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad R_3 \rightarrow R_3 - R_2$$

The rank of the coefficient matrix = 2

$\therefore$  The equations have  $3 - 2 = 1$  L.I solution.

(1D)

∴ we have

$$-3x_1 - 3x_2 + 3x_3 = 0$$

$$-12x_2 + 6x_3 = 0$$

$$\Rightarrow -x_1 - x_2 + x_3 = 0$$

$$-2x_1 + x_3 = 0$$

$$2x_1 = x_3$$

Take  $x_1 = 1$  then  $x_3 = 2$   
and  $x_2 = 1$ .

∴  $x_3 = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$  is an eigen vector of A

corresponding to the eigen value 4.

∴ The geometric multiplicity of eigen value 4 is 1 and its algebraic multiplicity is also 1.

Since the geometric multiplicity of each eigen value of A is equal to its algebraic multiplicity.

∴ A is similar to diagonal matrix.

$$\text{Let } P = \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \\ = \begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 1 \\ 0 & 2 & 1 \end{bmatrix}$$

The columns of P are 3 eigen vectors of A corresponding to the eigen values -2, -1, 4 respectively.

The matrix P will transform A to diagonal form D is given by the relation  $P^{-1}AP = D$

$$= \begin{bmatrix} 0 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

$$\text{The transforming matrix } P = \begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}$$

$$\text{and diagonal matrix } D = \begin{bmatrix} -2 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

(11)

→ H(a) obtain the equations of the planes which pass through the point  $(3, 0, 3)$ , touch the sphere  $x^2 + y^2 + z^2 = 9$  and are parallel to the line  $x = 2y = -z$ .

Sol The given line is  

$$x = 2y = -z \quad \text{--- (1)}$$

any line parallel to (1) passing through  $(3, 0, 3)$  is  $\frac{x-3}{2} = \frac{y-0}{1} = \frac{z-3}{-2} \quad \text{--- (2)}$ .

Now the general form of the line (2)  
is given by

$$\begin{aligned} x-3 &= 2y \quad , \quad -2y = z-3 \\ \Rightarrow x-2y-3 &= 2y+z-3 \end{aligned}$$

Now any plane through the line (3) is  

$$(x-2y-3) + \lambda(2y+z-3) = 0 \quad \text{--- (4)}$$

$$\Rightarrow x + (-2+2\lambda)y + \lambda z + (-3-3\lambda) = 0$$

clearly, it will be the tangent plane to the given sphere  $x^2 + y^2 + z^2 - 9 = 0$   
if the perpendicular distance of the plane from centre  $(0, 0, 0)$  of the sphere  
is equal to the radius of the sphere.

p.e 
$$\frac{|0+0+0-3-3\lambda|}{\sqrt{1+(-2+2\lambda)^2+\lambda^2}} = 3 \quad (\because \text{radius} = 3)$$

$$1+\lambda = \sqrt{5+5\lambda^2 - 8\lambda}$$

$$\Rightarrow (1+\lambda)^2 = 5 + 5\lambda^2 - 8\lambda$$

$$\Rightarrow \lambda^2 + 2\lambda + 1 = 5\lambda^2 - 8\lambda + 5$$

$$\Rightarrow 4\lambda^2 - 10\lambda + 4 = 0$$

$$\Rightarrow 2\lambda^2 - 5\lambda + 2 = 0$$

$$\Rightarrow 2\lambda(\lambda-2) - 1(\lambda-2) = 0$$

$$\Rightarrow (2\lambda-1)(\lambda-2) = 0$$

$$\Rightarrow \boxed{\lambda = 2}, \boxed{\lambda = \frac{1}{2}}$$

If  $\lambda = 2$ : Then from (4) we get,

$$\begin{aligned} x - 2y - 3 + 2(2y + z - 3) &= 0 \\ \Rightarrow \boxed{x + 2y + 2z - 9 = 0} \end{aligned} \quad (5)$$

If  $\lambda = \frac{1}{2}$ : Then from (4) we get,

$$\begin{aligned} x - 2y - 3 + \frac{1}{2}(2y + z - 3) &= 0 \\ \Rightarrow \boxed{2x - 2y + z - 9 = 0} \end{aligned} \quad (6)$$

. The equations (5) & (6) are required planes, which are parallel to the given line.

(12)

→ Q(6) The section of the cone whose vertex is P and guiding curve is the ellipse

$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1, z=0$  by the plane  $x=0$  is a rectangular hyperbola. Show that the locus of P is  $\frac{x^2}{a^2} + \frac{y^2+z^2}{b^2} = 1$ .

Soln: Let the vertex P be  $(\alpha, \beta, \gamma)$  and given guiding curve the ellipse  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1, z=0$  ①

Now the equation of any line through

$P(\alpha, \beta, \gamma)$  are

$$\frac{x-\alpha}{l} = \frac{y-\beta}{m} = \frac{z-\gamma}{n} \quad \text{--- 2}$$

it meets the plane  $z=0$

$$\therefore \frac{x-\alpha}{l} = \frac{y-\beta}{m} = \frac{0-\gamma}{n}$$

$$\Rightarrow x-\alpha = -\frac{l}{n}, y-\beta = -\frac{m}{n}, z=0.$$

$$\Rightarrow x = \alpha - \frac{l}{n}, y = \beta - \frac{m}{n}, z=0$$

This point lies on the ellipse ①

$$\therefore \frac{1}{a^2} \left( \alpha - \frac{l}{n} \right)^2 + \frac{1}{b^2} \left( \beta - \frac{m}{n} \right)^2 = 1 \quad \text{--- 3}$$

Now eliminating l, m, n from ② & ③.

$$\frac{1}{a^2} \left( \alpha - \frac{(x-\alpha)}{z-y} \right)^2 + \left( \beta - \frac{(y-\beta)}{z-y} \right)^2 = 1$$

$$\Rightarrow \frac{1}{a^2} (xz-yx)^2 + \frac{1}{b^2} (\beta z - yz)^2 = (z-y)^2 \quad \text{--- 4}$$

which is the required equation of the cone.

This meets the plane  $x=0$ .

$$\therefore (4) \equiv \frac{1}{a^2} (\alpha z - \alpha)^2 + \frac{1}{b^2} (\beta z - \gamma y)^2 = (z - \gamma)^2$$

$$\Rightarrow \frac{\alpha^2 z^2}{a^2} + \frac{\beta^2 z^2 + \gamma^2 y^2 - 2\beta\gamma zy}{b^2} = z^2 + y^2 - 2zy.$$

This will be a rectangular hyperbola

in  $yz$ -plane

if coefficient of  $y^2$  + coefficient of  $z^2 = 0$

$$\Rightarrow \frac{\gamma^2}{b^2} + \frac{\alpha^2}{a^2} + \frac{\beta^2}{b^2} - 1 = 0$$

$$\Rightarrow \frac{\alpha^2}{a^2} + \frac{\beta^2 + \gamma^2}{b^2} - 1 = 0$$

$\therefore$  The locus of  $P(\alpha, \beta, \gamma)$  is

$$\frac{x^2}{a^2} + \frac{y^2 + z^2}{b^2} = 1$$

at the poles of the

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→ 4(c) prove that the locus of the poles of the tangent planes of the conicoid  $ax^2+by^2+cz^2=1$  with respect to the conicoid  $\alpha x^2+\beta y^2+\gamma z^2=1$  is the conicoid  $\frac{\alpha^2 x^2}{a} + \frac{\beta^2 y^2}{b} + \frac{\gamma^2 z^2}{c} = 1$ .

Sol: Let  $lx+my+nz=p$  be the tangent plane to the conicoid

$$ax^2+by^2+cz^2=1 \quad \text{--- (ii)}$$

$$\text{Then } \frac{l^2}{a} + \frac{m^2}{b} + \frac{n^2}{c} = p^2 \quad \text{--- (iii)}$$

Let  $(\alpha', \beta', \gamma')$  be the pole of the plane (i)

$$\text{w.r.t } \alpha x^2+\beta y^2+\gamma z^2=1$$

$$\text{Then we have } \alpha' \alpha x + \beta' \beta y + \gamma' \gamma z = 1. \quad \text{--- (iv)}$$

Comparing (i) & (iv), we get

$$\frac{\alpha' \alpha}{l} = \frac{\beta' \beta}{m} = \frac{\gamma' \gamma}{n} = \frac{1}{p} \quad \text{--- (v)}$$

Eliminating  $\alpha, \beta, \gamma$  between (iii) and (v),

we get

$$\frac{(\alpha' \alpha p)^2}{a} + \frac{(\beta' \beta p)^2}{b} + \frac{(\gamma' \gamma p)^2}{c} = p^2.$$

$$\frac{(\alpha' \alpha)^2}{a} + \frac{(\beta' \beta)^2}{b} + \frac{(\gamma' \gamma)^2}{c} = 1.$$

∴ The required locus of  $(\alpha', \beta', \gamma')$  is

$$\frac{(\alpha x)^2}{a} + \frac{(\beta y)^2}{b} + \frac{(\gamma z)^2}{c} = 1.$$

Q1(d) Show that the lines drawn from the origin parallel to the normals to the central conicoid  $ax^2 + by^2 + cz^2 = 1$  at its points of intersection with the planes  $lx + my + nz = p$  generate the cone

$$p^2 \left( \frac{x^2}{a} + \frac{y^2}{b} + \frac{z^2}{c} \right) = \left( \frac{lx}{a} + \frac{my}{b} + \frac{nz}{c} \right)^2.$$

Soln: Let  $(\alpha, \beta, \gamma)$  be the point of intersection of the given conicoid and given plane,

$$\text{given conicoid and given plane, } ax^2 + by^2 + cz^2 = 1 \quad \text{(i)}$$

$$\text{then we have } ad^2 + bd^2 + cd^2 = 1 \quad \text{(ii)}$$

$$\text{and } lx + my + nz = p \quad \text{(iii)}$$

and

Also the equations of the normals to the given conicoid at  $(\alpha, \beta, \gamma)$  are

$$\frac{x-\alpha}{a} = \frac{y-\beta}{b} = \frac{z-\gamma}{c}.$$

$\therefore$  The equations of the line through the origin parallel to this line are

$$\frac{x}{ad} = \frac{y}{bd} = \frac{z}{cd} \quad \text{(iv)}$$

from (i) & (iv), we have

$$ax^2 + by^2 + cz^2 = \left( \frac{lx + my + nz}{p} \right)^2$$

$$\Rightarrow p^2(ax^2 + by^2 + cz^2) = (lx + my + nz)^2$$

$$\Rightarrow p^2 \left( \frac{ad^2}{a} + \frac{bd^2}{b} + \frac{cd^2}{c} \right) = \left( \frac{l(ad)}{a} + \frac{m(bd)}{b} + \frac{n(cd)}{c} \right)^2$$

$$\Rightarrow p^2 \left[ \frac{(ad)^2}{a} + \frac{(bd)^2}{b} + \frac{(cd)^2}{c} \right] = \left( \frac{l(ad)}{a} + \frac{m(bd)}{b} + \frac{n(cd)}{c} \right)^2$$

$$\Rightarrow p^2 \left( \frac{x^2}{a} + \frac{y^2}{b} + \frac{z^2}{c} \right) = \left( \frac{lx}{a} + \frac{my}{b} + \frac{nz}{c} \right)^2$$

from (iv) eliminating  $\alpha, \beta, \gamma$

Hence the line (iv) generates the above cone.

Section-B

→ 5(a) solve  $\sec y \frac{dy}{dx} + 2x \tan y = x^3$ .

Soln: Given that  $\sec y \frac{dy}{dx} + 2x \tan y = x^3$ . ①

put  $\tan y = t$

$$\therefore \sec y \frac{dy}{dx} = \frac{dt}{dx}$$

$$\therefore ① \Leftrightarrow \frac{dt}{dx} + 2xt = x^3$$

which is linear in  $t$  and  $x$ .

$$I.F = \int e^{2x} dx = e^{2x}$$

∴ General solution of ① is

$$te^{2x} = \int x^3 e^{2x} dx + C$$

$$= \frac{1}{2} \int z e^z dz + C$$

$$= \frac{1}{2} e^z (z-1) + C.$$

$$\tan y e^{2x} = \frac{1}{2} e^{2x} (x^2 - 1) + C \quad (\because t = \tan y)$$

$$\begin{aligned} &\text{Let } x^2 = z \\ &\Rightarrow 2x dx = dz \\ &\Rightarrow x dx = \frac{1}{2} dz \end{aligned}$$

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5.(b) Find the 2nd order ODE for which  $e^x$  and  $x^2 e^x$  are solutions.

Sol Let  $y_1 = x$  and  $y_2 = x^2 e^x$ . Then their

wronskian  $w(x)$  is given by

$$\begin{aligned} w(x) &= \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} \\ &= \begin{vmatrix} x & x^2 e^x \\ 1 & x^2 e^x + 2x e^x \end{vmatrix} \end{aligned}$$

$$= x^3 e^x + 2x^2 e^x - x^2 e^x$$

$$= x^3 e^x + x^2 e^x. \text{ which is not identically equal to zero on } \mathbb{R} = (-\infty, \infty).$$

To find the required differential equation:

The general solution of the required differential equation may be written as

$$y = c_1 y_1 + c_2 y_2 \quad \text{where } c_1 \text{ and } c_2 \text{ are arbitrary constants.}$$

$$\Rightarrow y = c_1 e^x + c_2 x^2 e^x \quad \textcircled{1}$$

Differentiating (1) w.r.t 'x' we get

$$y' = c_1 e^x + c_2 x^2 e^x + c_2 (2x e^x).$$

$$\Rightarrow y' = y + 2c_2 x e^x. \text{ (from ①)}$$

$$\Rightarrow y' - y = 2c_2 x e^x \quad \textcircled{2}$$

Again differentiating w.r.t 'x', we get

$$y'' - y' = 2c_2 e^x + 2c_2 x e^x.$$

$$y'' - y' = 2c_2 e^x + 2c_2 x e^x$$

$$\Rightarrow y'' - 2y' + y = 2c_2 e^x. \quad \textcircled{3}$$

Now we eliminate  $c_1$  and  $c_2$  from  
①, ② and ③. For this, substitute  
③ in ②, we get

$$y^1 - y = \alpha(y^{11} - 2y^1 + y)$$

$$\Rightarrow \alpha y^{11} - (2\alpha + 1)y^1 + (\alpha + 1)y = 0$$

which is the required differential  
equation.

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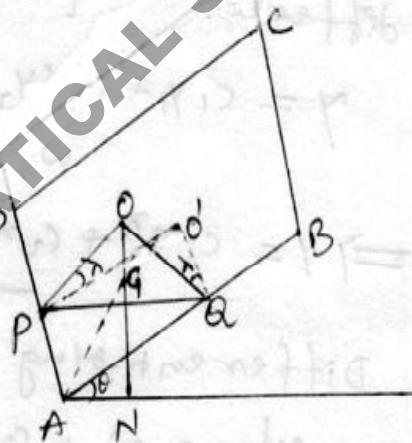
75(c): A uniform rectangular board, whose sides are  $2a$  and  $2b$ , rests in limiting equilibrium in contact with two rough pegs in the same horizontal line at a distance  $d$  apart. Show that the inclination  $\theta$  of the side  $2a$  to the horizontal is given by the equation  $d \cos \lambda [\cos(\lambda + 2\theta)] = a \cos \theta - b \sin \theta$  where  $\lambda$  is the angle of friction.

SOL:

Let  $ABCD$  be the rectangle resting on the two pegs  $P$  and  $Q$ .

Suppose that the resultants of the reactions and the frictional forces  $P$  and  $Q$  meet at  $O$ . Then the centre of gravity  $G$  of the rectangle must be vertically below  $O$ .

Let  $AN$  be the perpendicular from  $A$  on  $OG$ . Suppose that the normals at  $P$  and  $Q$  meet at  $O'$ .



(15)

The angles  $\angle OPO'$  and  $\angle QO'$  are equal, hence  $O, P, Q, O'$  are concyclic. Again  $O', P, A, Q$  are concyclic, hence  $O, Q, A, P$  are concyclic.

$$\text{It follows that } \angle OAO' = \lambda, \angle OAQ = \angle AQP = \angle QAN = \theta.$$

$$\text{and } \angle OAN = \angle O'PA = \frac{\pi}{2}.$$

Also from the rectangle  $O'PAQ$ ,  $O'A = PQ$ .

We will now find  $AN$  in two ways.

$$\begin{aligned} \text{Firstly } AN &= OA \cos(\lambda + 2\theta) \\ &= O'A \cos \lambda \cos(\lambda + 2\theta) \\ &= d \cos \lambda \cos(\lambda + 2\theta). \end{aligned}$$

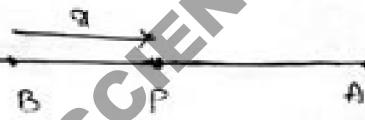
$$\begin{aligned} \text{Again } AN &= AG \cos(GAQ + QAN) \\ &= \frac{AG \cos GAQ \cos \theta - AG \sin GAQ \sin \theta}{a \cos \theta - b \sin \theta}. \end{aligned}$$

$$\text{Hence } d \cos \lambda \cos(\lambda + 2\theta) = a \cos \theta - b \sin \theta.$$

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(d) A particle rests in equilibrium under the attraction of two centres of force which attract directly as the distance, their intensities being  $\mu$  and  $\mu'$ . The particle is slightly displaced towards one of them, show that the time of small oscillation is  $\frac{2\pi}{\sqrt{\mu+\mu'}}$ .

Sol'n :- Suppose  $A$  and  $A'$  are the two centres of force, their intensities being  $\mu$  and  $\mu'$  respectively. Let a particle of mass  $m$  be in equilibrium



at  $B$  under the attraction of these two centres. If  $AB=a$  and  $A'B=a'$ , the forces of attraction at  $B$  due to the centres  $A$  and  $A'$  are  $m\mu a$  &  $m\mu' a'$  respectively in opposite directions. As these two forces balance, we have

$$m\mu a = m\mu' a' \quad \text{--- (1)}$$

Now suppose the particle is slightly displaced towards  $A$  and then let go. Let  $P$  be the position of the particle after time  $t$ , where  $BP=x$ .

The attraction at  $P$  due to the centre  $A$  is  $m\mu AP$  or  $m\mu(a-x)$  in the direction  $PA$  i.e., in the direction of  $x$  increasing. Also the attraction  $P$  due to the centre  $A'$  is  $m\mu' AP$  or  $m\mu' (a'+x)$  in the direction  $PA'$  i.e., in the direction of  $x$  decreasing. Hence by Newton's second law of motion, the equation of motion of the particle at  $P$  is

$$m \left( \frac{d^2x}{dt^2} \right) = m\mu(a-x) - m\mu'(a'+x) \quad \text{--- (2)}$$

where the force in the direction of  $x$  increasing has been taken with +ve sign and the force in the direction of  $x$  decreasing has been taken with -ve sign.

Simplifying the equation (2), we get

$$m \left( \frac{d^2x}{dt^2} \right) = m(\mu a - \mu' a' - \mu' x)$$

$$(or) \quad \frac{d^2x}{dt^2} = -(\mu + \mu')x \quad [ : by (1), m\mu a = m\mu' a' ]$$

this is the equation of a S.H.M with centre at the origin. Hence the motion of the particle is simple harmonic with centre at B and its time period is  $2\pi/\sqrt{\mu + \mu'}$ .

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→ 5(e) verify Green's theorem in the plane for  
 $\oint_C (xy + y^2) dx + x^2 dy$  where  $C$  is the closed  
 curve of the region bounded by  $y=x$  and  $y=x^2$ .

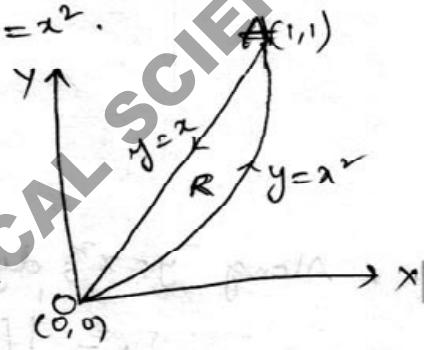
21: By Green's theorem in plane,

we have

$$\iint_R \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dxdy = \oint_C M dx + N dy.$$

$$\text{Here } M = xy + y^2 \quad \text{and} \quad N = x^2.$$

The curves  $y=x$  and  
 $y=x^2$  intersect at  $(0,0)$   
 and  $(1,1)$ . The positive  
 direction in traversing  $C$  is  
 as shown in the figure.



$$\begin{aligned}
 \text{we have } & \iint_R \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dxdy \\
 &= \iint_R \left[ \frac{\partial}{\partial x} (x^2) - \frac{\partial}{\partial y} (xy + y^2) \right] dxdy \\
 &= \iint_R (2x - x^2 - 2y) dxdy \\
 &= \iint_R (x - 2y) dxdy \\
 &= \int_{x=0}^1 \int_{y=x^2}^{x} (x - 2y) dy dx \\
 &= \int_{x=0}^1 \left( xy - y^2 \right) \Big|_{x^2}^x dx \\
 &= \int_{x=0}^1 (x^2 - x^3 - x^3 + x^4) dx
 \end{aligned}$$

$$\begin{aligned}
 &= \int_{x=0}^1 (x^4 - x^8) dx \\
 &= \left( \frac{x^5}{5} - \frac{x^9}{9} \right)_0^1 = \frac{1}{5} - \frac{1}{4} = -\frac{1}{20}.
 \end{aligned}$$

Now let us evaluate the line integral along C.

$$\begin{aligned}
 \text{The Line integral along } C &= \text{Line integral along } y=x^2 \text{ (from } 0 \text{ to } 1) \\
 &\quad + \text{line integral along } y=x \text{ (from } 1 \text{ to } 0) \\
 &= I_1 + I_2.
 \end{aligned}$$

Along  $y=x^2$ ;  $dy=2xdx$ .

$$\begin{aligned}
 \therefore I_1 &= \int_0^1 [x(x^2) + x^4] dx + x^2(2x) dx \\
 &= \int_0^1 (3x^3 + x^4) dx \\
 &= \left[ 3 \frac{x^4}{4} + \frac{x^5}{5} \right]_0^1 \\
 &= \frac{3}{4} + \frac{1}{5} = \frac{19}{20}.
 \end{aligned}$$

Along  $y=x$ ;  $dy=dx$

$$\begin{aligned}
 \therefore I_2 &= \int_0^1 \{x(x) + x^2\} dx + x^2 dx \\
 &= \int_0^1 3x^2 dx \\
 &= \frac{3x^3}{3} = 0 - 1 = -1.
 \end{aligned}$$

$$\therefore I_1 + I_2 = \frac{19}{20} - 1 = -\frac{1}{20}.$$

Hence the theorem is verified

6(a)

$$\text{Solve } (y^3 - 2xy^2) dx + (2xy^2 - x^3) dy = 0$$

Sol: Given that  $(y^3 - 2xy^2) dx + (2xy^2 - x^3) dy = 0 \quad \textcircled{1}$

clearly  $\textcircled{1}$  is a homogeneous diff. equation.

Comparing  $\textcircled{1}$  with  $M dx + N dy = 0$ .

$$\text{we have } M = y^3 - 2xy^2; N = 2xy^2 - x^3$$

$$\begin{aligned} \therefore Mx + Ny &= y^3x - 2x^2y + 2xy^2 - x^3y \\ &= 3xy^3 - 3x^3y \\ &= 3xy(y^2 - x^2) \neq 0. \end{aligned}$$

$$\Rightarrow \frac{1}{Mx+Ny} = \frac{1}{3xy(y^2-x^2)}$$

Multiplying  $\textcircled{1}$  by  $\frac{1}{3xy(y^2-x^2)}$ ,

we get

$$\frac{y(y^2 - 2x^2)}{3xy(y^2 - x^2)} dx + \frac{(2y^2 - x^2)x}{3xy(y^2 - x^2)} dy = 0$$

$$\Rightarrow \frac{y^2 - 2x^2}{3x(y^2 - x^2)} dx + \frac{(2y^2 - x^2)}{3y(y^2 - x^2)} dy = 0. \quad \textcircled{2}$$

Comparing  $\textcircled{2}$  with  $P dx + Q dy = 0$

$$\therefore P = \frac{y^2 - 2x^2}{3xy^2 - 3x^3}, Q = \frac{2y^2 - x^2}{3y^2 - 3x^2y}$$

$$\frac{\partial P}{\partial y} = \frac{6xy}{(3y^2 - 3x^2)^2}, \quad \frac{\partial Q}{\partial x} = \frac{6xy}{(3y^2 - 3x^2)^2}.$$

$$\therefore \frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}.$$

$\therefore \textcircled{2}$  is an exact.

and its solution is given by

$$\int_{y-\text{constant}} p dx + \int (\text{terms in } N \text{ not containing } x) dy = C_1$$

$$\Rightarrow \int \frac{y^2 - x^2}{3x(y-x)} dx + \int \frac{1}{3y} dy = C_1$$

$$\Rightarrow \int \frac{y^2 - x^2 - x^2}{3x(y-x)} dx + \int \frac{1}{3y} dy = C_1$$

$$\Rightarrow \int \frac{1}{3x} dx + \int \frac{x}{3(y-x)} dx + \int \frac{1}{3y} dy = C_1$$

$$\Rightarrow \frac{1}{3} \log x + \frac{1}{6} \log(y-x) + \frac{1}{3} \log y = \log C_2 \quad \text{where } C_1 = \log C_2$$

$$\Rightarrow (xy)^{\frac{1}{3}} (y-x)^{\frac{1}{6}} = C_2$$

$$\Rightarrow (xy)(y-x)^{\frac{1}{2}} = C_2^3$$

$$\Rightarrow (x^2 y^2)(y-x)^2 = C_2^6$$

$$\Rightarrow x^2 y^2 (y-x^2) = C, \quad \text{where } C = C_2^6$$

~~which is the required solution~~

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$$\rightarrow \underline{\underline{G(b)}} \text{ Solve } \left(\frac{dy}{dx}\right)^2 - 2 \frac{dy}{dx} \cosh x + 1 = 0.$$

Sol: The given equation is

$$\left(\frac{dy}{dx}\right)^2 - 2 \frac{dy}{dx} \cosh x + 1 = 0$$

$$\therefore p^2 - 2p \cosh x + 1 = 0 \quad \text{where } \frac{dy}{dx} = p.$$

Solving for  $p$ ,

$$p = \frac{2 \cosh x \pm \sqrt{4 \cosh^2 x - 4}}{2}$$

$$= \cosh x \pm \sqrt{\cosh^2 x - 1}$$

$$= \cosh x \pm \sinh x.$$

$$\Rightarrow p = \cosh x + \sinh x ; p = \cosh x - \sinh x.$$

$$\Rightarrow \frac{dy}{dx} = \cosh x + \sinh x ; \frac{dy}{dx} = \cosh x - \sinh x.$$

Integrating

$$y = \sinh x + \cosh x + C ; y = \sinh x - \cosh x + C.$$

Hence the general solution is

$$(y - \sinh x + \cosh x - C)(y - \sinh x + \cosh x - C) = 0$$

$$\Rightarrow \left(y - \frac{(e^x + e^{-x})}{2} - \frac{e^x + e^{-x}}{2} - C\right) \left(y - \frac{(e^x + e^{-x})}{2} + \frac{e^x + e^{-x}}{2} - C\right) = 0$$

$$\Rightarrow (y - e^x - C)(y + e^{-x} - C) = 0.$$

$\therefore$  The general solution is

$$\boxed{(y - e^x - C)(y + e^{-x} - C) = 0}$$

→ Q(3)  
Solve  $\frac{d^3y}{dx^3} + 3\frac{dy}{dx^2} + 3\frac{dy}{dx} + y = x^2 e^{-x}$ .

Sol<sup>n</sup>: The given can be written as

$$(D^3 + 3D^2 + 3D + 1)y = x^2 e^{-x}.$$

The auxiliary equation is

$$\begin{aligned} D^3 + 3D^2 + 3D + 1 &= 0 \\ \Rightarrow (D+1)^3 &= 0 \\ \Rightarrow D &= -1, -1, -1. \end{aligned}$$

$$\therefore \text{C.F. is } y_c = (c_1 + c_2 x + c_3 x^2) e^{-x}.$$

Particular integral:

$$\begin{aligned} y_p &= \frac{1}{D^3 + 3D^2 + 3D + 1} x^2 e^{-x} \\ &= \frac{1}{(D+1)^3} x^2 e^{-x} \\ &= e^{-x} \frac{1}{(D-1+1)^3} x^2 \\ &= e^{-x} \frac{1}{D^3} x^2 \\ y_p &= e^{-x} \frac{x^2}{60}. \end{aligned}$$

$$\begin{aligned} y &= y_c + y_p \\ y &= (c_1 + c_2 x + c_3 x^2) e^{-x} + \frac{e^{-x} x^2}{60} \end{aligned}$$

is the general solution of the given differential equation.

→ 6(d)

Show that  $e^{x^2}$  is a solution of

$$\frac{d^2y}{dx^2} - 4x \frac{dy}{dx} + (4x^2 - 2)y = 0$$

Find a second independent solution.

Sol: Given that  $\frac{d^2y}{dx^2} - 4x \frac{dy}{dx} + (4x^2 - 2)y = 0$  ①

To show:  $y = e^{x^2}$  is a solution of ①.

$$y' = e^{x^2} \cdot 2x$$

$$\text{and } y'' = 2[e^{x^2} + 2x^2 e^{x^2}]$$

$$= 2e^{x^2}[1 + 2x^2]$$

$$\begin{aligned} \text{L.H.S. of ①} &= 2e^{x^2}(1+2x^2) - 4x(e^{x^2} \cdot 2x) + (4x^2 - 2)e^{x^2} \\ &= 2e^{x^2} + 4x^2 e^{x^2} - 8x^2 e^{x^2} + 4x^2 e^{x^2} - 2e^{x^2} \\ &= 0 \end{aligned}$$

Showing that  $y = e^{x^2}$  is a solution of ①

since  $y = e^{x^2}$  is a solution of ①.  
 $\therefore y = u = e^{x^2}$  is in a part of C.F. of ①.

Comparing ① with  $\frac{d^2y}{dx^2} + P \frac{dy}{dx} + Qy = R$ .

$$P = -4x; Q = 4x^2 - 2; R = 0$$

Let  $y = uv$  be the general solution of ①.

Then  $v$  is obtained by

$$\frac{d^2v}{dx^2} + \left(P + \frac{2}{u} \frac{du}{dx}\right) \frac{dv}{dx} = \frac{R}{u} \quad ②$$

$$\text{Since } u = e^{x^2} \Rightarrow \frac{du}{dx} = 2x e^{x^2}$$

$$\therefore P + \frac{2}{u} \frac{du}{dx} = -4x + \frac{2}{e^{x^2}}(2x e^{x^2})$$

$$= -4x + 4x$$

$$= 0$$

→ 7(c) : A shell, lying in a straight smooth horizontal tube, suddenly explodes and breaks into portions of masses  $m$  and  $m'$ . If  $d$  is the distance apart of the masses after a time  $t$ , show that the work done by the explosion is  $\frac{1}{2} \frac{mm'}{m+m'} \frac{d^2}{t^2}$ .

Sol: Since the shell is lying in the tube, its velocity before explosion is zero.  
Let  $u_1$  and  $u_2$  be the velocities of the masses  $m$  and  $m'$  respectively after explosion. Then the relative velocity of the masses after explosion is  $u_1+u_2$ . Since the tube is smooth and horizontal,  $u_1+u_2$  will remain constant.

$$\therefore (u_1+u_2)t = d \quad \textcircled{1}$$

Also by the principle of conservation of linear momentum, we have  $m u_1 - m' u_2 = 0$   
 $\Rightarrow m u_1 = m' u_2 \quad \textcircled{2}$

Substituting for  $u_2$  from  $\textcircled{2}$  in  $\textcircled{1}$ ,

we get  $(u_1 + \frac{m u_1}{m'}) t = d$ .

$$u_1 \left( \frac{m+m'}{m'} \right) t = d$$

$$\Rightarrow u_1 = \frac{m'd}{(m+m')t}$$

$$\therefore \text{from } \textcircled{2}, u_2 = \frac{m}{m'} u_1$$

$$= \frac{m}{m'} \frac{m'd}{(m+m')t}$$

$$u_2 = \frac{md}{(m+m')t}$$

explosion

Now the work done by the explosion  
 = the kinetic energy released  
 due to the explosion

$$= \frac{1}{2} m u_1^2 + \frac{1}{2} m' u_2^2$$

$$= \frac{1}{2} m \left[ \frac{m'^2 d^2}{(m+m')^2 t^2} \right] + \frac{1}{2} m' \left[ \frac{m^2 d^2}{(m+m')^2 t^2} \right]$$

$$= \frac{1}{2} \frac{d^2}{t^2} \frac{1}{(m+m')^2} [mm'^2 + m'^2 m^2]$$

$$= \frac{1}{2} \frac{d^2}{t^2} \frac{mm'}{(m+m')^2} [m+m']$$

$$= \frac{1}{2} \frac{d^2}{t^2} \left( \frac{mm'}{m+m'} \right)$$

~~=====~~

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Now from ②, we have

$$\frac{d^2v}{dx^2} + (0) \frac{dv}{dx} = 0$$

$$\Rightarrow \frac{d^2v}{dx^2} = 0$$

$$\Rightarrow \frac{dv}{dx} = C_1$$

$$\Rightarrow v = C_1 x + C_2$$

∴ General solution of ① if  $y = ve$ .

$$\Rightarrow y = e^x (C_1 x + C_2)$$

$$= C_1 x e^x + C_2 e^x$$

~~.....~~

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→ 8(a) Show that  $\vec{A} = (6xy + z^3)\hat{i} + (3x^2 - z)\hat{j} + (3xz^2 - y)\hat{k}$  is irrotational. find a scalar function  $\phi$  such that  $\vec{A} = \text{grad } \phi$ .

Sol: Given that  $\vec{A} = (6xy + z^3)\hat{i} + (3x^2 - z)\hat{j} + (3xz^2 - y)\hat{k}$ .

$$\text{curl } \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 6xy + z^3 & 3x^2 - z & 3xz^2 - y \end{vmatrix}$$

$$\begin{aligned} &= \cancel{\hat{i}}(-1+1) + \hat{j}(3z^2 - 3z^2) + \hat{k}(6x - 6x) \\ &= \hat{i}(0) + \hat{j}(0) + \hat{k}(0) \\ &= 0. \end{aligned}$$

∴ The vector  $\vec{A}$  is irrotational.

Let  $\vec{A} = \text{grad } \phi$

i.e.,  $\vec{A} = \nabla \phi$ .

$$\Rightarrow (6xy + z^3)\hat{i} + (3x^2 - z)\hat{j} + (3xz^2 - y)\hat{k} = \frac{\partial \phi}{\partial x}\hat{i} + \frac{\partial \phi}{\partial y}\hat{j} + \frac{\partial \phi}{\partial z}\hat{k}$$

$$\Rightarrow \text{Then } \frac{\partial \phi}{\partial x} = 6xy + z^3 \quad \text{--- ①}$$

$$\frac{\partial \phi}{\partial y} = 3x^2 - z \quad \text{--- ②}$$

$$\frac{\partial \phi}{\partial z} = 3xz^2 - y \quad \text{--- ③}$$

① partially w.r.t x treating y, z as constants.

$$\therefore \text{①} \phi = 3x^2y + z^3x + f_1(y, z) \quad \text{--- ④}$$

② partially w.r.t y treating x, z as constants

$$\therefore \text{②} \phi = 3x^2y - zy + f_2(x, z) \quad \text{--- ⑤}$$

③ partially w.r.t z treating x, y as constants

$$\therefore \text{③} \phi = xz^3 - yz + f_3(x, y) \quad \text{--- ⑥}$$

④, ⑤, ⑥ each represents  $\phi$ . These agree  
if we choose  $f_1(y, z) = -yz$ ,  $f_2(x, z) = xz^3$ ,  $f_3(x, y) = 3xy$ .

(20)

$$\therefore \phi = 3xy + xz^3 - yz + c$$

where  $c$  is any arbitrary constant.

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8.6 Let  $\psi(x, y, z)$  be a scalar function.  
Find grad  $\psi$  and  $\nabla^2 \psi$  in spherical co-ordinates.

Sol. We know that

$$\nabla \psi = \text{grad } \psi \\ = \frac{1}{h_1} \frac{\partial \psi}{\partial u_1} e_1 + \frac{1}{h_2} \frac{\partial \psi}{\partial u_2} e_2 + \frac{1}{h_3} \frac{\partial \psi}{\partial u_3} e_3. \quad (1)$$

for spherical co-ordinates  $(r, \theta, \phi)$

$$u_1 = r, u_2 = \theta, u_3 = \phi; \quad$$

$$e_1 = e_r, e_2 = e_\theta, e_3 = e_\phi;$$

$$h_1 = h_r = 1, h_2 = h_\theta = r, h_3 = h_\phi = r \sin \theta.$$

$$\therefore \text{from (1)} \\ \nabla \psi = \frac{1}{1} \frac{\partial \psi}{\partial r} e_r + \frac{1}{r} \frac{\partial \psi}{\partial \theta} e_\theta + \frac{1}{r \sin \theta} \frac{\partial \psi}{\partial \phi} e_\phi. \\ = \frac{\partial \psi}{\partial r} e_r + \frac{1}{r} \frac{\partial \psi}{\partial \theta} e_\theta + \frac{1}{r \sin \theta} \frac{\partial \psi}{\partial \phi} e_\phi.$$

We know that:

$$\begin{aligned} \nabla^2 \psi &= \frac{1}{h_1 h_2 h_3} \left[ \frac{2}{h_1} \left( \frac{h_2 h_3}{h_1} \frac{\partial^2 \psi}{\partial u_1^2} \right) + \frac{2}{h_2} \left( \frac{h_1 h_3}{h_2} \frac{\partial^2 \psi}{\partial u_2^2} \right) + \right. \\ &\quad \left. - \frac{2}{h_3} \left( \frac{h_1 h_2}{h_3} \frac{\partial^2 \psi}{\partial u_3^2} \right) \right] \\ &= \frac{1}{(1)(r)(r \sin \theta)} \left[ \frac{\partial}{\partial r} \left( \frac{(r)(r \sin \theta)}{1} \frac{\partial^2 \psi}{\partial r^2} \right) + \frac{\partial}{\partial \theta} \left( \frac{(r \sin \theta)(1)}{r} \frac{\partial^2 \psi}{\partial \theta^2} \right) \right. \\ &\quad \left. + \frac{\partial}{\partial \phi} \left( \frac{(1)(r)}{r \sin \theta} \frac{\partial^2 \psi}{\partial \phi^2} \right) \right] \\ &= \frac{1}{r \sin \theta} \left[ \frac{\partial}{\partial r} \left( r^2 \sin \theta \frac{\partial^2 \psi}{\partial r^2} \right) + \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial^2 \psi}{\partial \theta^2} \right) + \right. \\ &\quad \left. \frac{\partial}{\partial \phi} \left( \frac{1}{\sin \theta} \frac{\partial^2 \psi}{\partial \phi^2} \right) \right] \\ &= \frac{1}{r \sin \theta} \left[ \sin \theta \frac{\partial}{\partial r} \left( r^2 \frac{\partial^2 \psi}{\partial r^2} \right) + \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial^2 \psi}{\partial \theta^2} \right) + \frac{1}{\sin \theta} \frac{\partial}{\partial \phi} \left( \frac{\partial^2 \psi}{\partial \phi^2} \right) \right] \\ &= \frac{1}{r} \frac{\partial}{\partial r} \left( r^2 \frac{\partial^2 \psi}{\partial r^2} \right) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial^2 \psi}{\partial \theta^2} \right) + \frac{1}{r \sin^2 \theta} \frac{\partial^2 \psi}{\partial \phi^2}. \end{aligned}$$

8(c) verify Stokes theorem for

$$\vec{A} = (y-z+2)\hat{i} + (yz+4)\hat{j} - xz\hat{k},$$

where  $S$  is the surface of the cube  $x=0, y=0,$

$z=0, x=2, y=2, z=2$  above the  $xy$ -plane.

Soln:

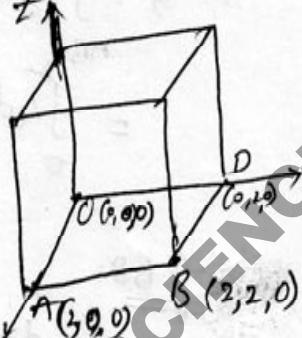
The  $xy$ -plane cuts the surface of the cube in a square.

Thus the curve  $C$  bounding

the surface  $S$  is the square,

say,  $OABD$ , in the  $xy$ -plane whose vertices in the  $xy$ -plane are the points.

$O(0,0), A(2,0), B(2,2), D(0,2).$



$$\text{Then } \oint_C \vec{F} \cdot d\vec{r} = \int_C [(y-z+2)\hat{i} + (yz+4)\hat{j} - xz\hat{k}] \cdot (dx\hat{i} + dy\hat{j} + dz\hat{k})$$

$$= \int_C (y-z+2) dx + (yz+4) dy - xz dz$$

$$= \int_C (y+2) dx + 4 dy \quad (\because \text{on } C, z=0. \\ \text{and } dz=0)$$

$$= \int_{OA} + \int_{AB} + \int_{BD} + \int_{DO} .$$

$$= I_1 + I_2 + I_3 + I_4 . \quad \text{①}$$

Along OA:

$$y=0 \Rightarrow dy=0.$$

and  $x$  varies from 0 to 2.

$$\begin{aligned}\therefore I_1 &= \int_{OA} (y+2) dx + 4 dy \\ &= \int_0^2 2 dx \\ &= [2x]_0^2 = 4.\end{aligned}$$

Along AB: $x=2$ ,  $dx=0$  and  $y$  varies from 0 to 2

$$\begin{aligned}\therefore I_2 &= \int_{AB} (y+2) dx + 4 dy \\ &= \int_0^2 4 dy = [4y]_0^2 = 8.\end{aligned}$$

Along BD: $y=2$ ,  $dy=0$  &  $x$  varies from 2 to 0.

$$\begin{aligned}\therefore I_3 &= \int_{BD} (y+2) dx + 4 dy \\ &= \int_2^0 4 dx = [4x]_2^0 \\ &= -8\end{aligned}$$

Along DO: $x=0$ ,  $dx=0$  &  $y$  varies from 2 to 0.

$$\begin{aligned}\therefore I_4 &= \int_{DO} (y+2) dx + 4 dy \\ &= \int_2^0 4 dy = [4y]_2^0 = -8\end{aligned}$$

 $\therefore \text{OEM}$ 

$$\begin{aligned}\int \vec{F} \cdot d\vec{r} &= I_1 + I_2 + I_3 + I_4 \\ &= 4 + 8 - 8 - 8 \\ &= -4\end{aligned}$$

(2)

$$\text{Now } \nabla \times F = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y-2+x & yz+4 & -xz \end{vmatrix}$$

$$= \hat{i}(0-y) + \hat{j}(-1+z) + \hat{k}(0-1)$$

$$= -y\hat{i} + (-1+z)\hat{j} - \hat{k}.$$

$\hat{n}$  = unit normal vector to  $S = \hat{k}$ .

$$\therefore dS = \frac{dxdy}{\sqrt{1+x^2+y^2}} = dxdy.$$

$$(\nabla \times F) \cdot \hat{n} = [(-y\hat{i} + (-1+z)\hat{j} - \hat{k}) \cdot \hat{k}]$$

$$= -1.$$

$$\iint_S (\nabla \times F) \cdot \hat{n} dS = \int_{x=0}^2 \int_{y=0}^2 (-1) dxdy$$

$$= - \int_{x=0}^2 [y]_0^2 dx$$

$$= - \int_{x=0}^2 2 dx$$

$$= -2 \int_0^2 dx$$

$$= -2 [x]_0^2$$

$$= -2[2]$$

$$= -4. \quad \text{--- (2)}$$

∴ from (2) & (3)

$$\iint_S (\nabla \times F) \cdot \hat{n} dS = \int_C \vec{F} \cdot d\vec{r} = -4.$$

Hence the Stokes theorem is verified

Q.(d) Show that, if  $\vec{r} = x(s)\vec{i} + y(s)\vec{j} + z(s)\vec{k}$  is a space curve,  $\frac{d\vec{r}}{ds} \cdot \frac{d^2\vec{r}}{ds^2} \times \frac{d^3\vec{r}}{ds^3} = \frac{T}{\rho^2}$ , where  $T$  is the torsion and  $\rho$  is the radius of curvature.

Sol:

$$\text{we know that } T = \frac{d\vec{\tau}}{ds}$$

$$\text{and } KN = \frac{d^2\vec{r}}{ds^2} \quad \text{Here } K \text{ is the curvature.}$$

$$\text{Now } \frac{d\vec{\tau}}{ds} \times \frac{d^2\vec{r}}{ds^2} = -T \times KN$$

$$= K(T \times N)$$

$$= KB \quad (\because TXN = B)$$

$$\therefore K = \left| \frac{d\vec{\tau}}{ds} \times \frac{d^2\vec{r}}{ds^2} \right|$$

$$\frac{d^2\vec{r}}{ds^2} = \frac{d}{ds} \left( \frac{d\vec{r}}{ds} \right) = \frac{d}{ds}(KN)$$

$$= K \frac{dN}{ds} + \frac{dK}{ds} N$$

$$= K(TB - KT) + \frac{dK}{ds} N$$

$$(\because \frac{dN}{ds} = TB - KT)$$

$$= KT B - KT + \frac{dK}{ds} N.$$

$$\frac{d\vec{r}}{ds} \cdot \left( \frac{d\vec{\tau}}{ds} \times \frac{d^2\vec{r}}{ds^2} \right) = T \cdot \left[ KN \times (KT B - KT + \frac{dK}{ds} N) \right]$$

$$= T \cdot \left[ K^2 (NXTB) - K^3 (NXT) + \frac{dK}{ds} (N \times N) \right]$$

$$= T \cdot \left[ K^2 T (N \times B) - K^3 (-B) + \frac{dK}{ds} (0) \right]$$

$$(\because NXT = -B \text{ &} N \times N = 0)$$

$$= T \cdot \left( K^2 T (T) + K^3 B \right)$$

$$(\because N \times B = T)$$

(22)

$$= k^2 T \cdot (T \cdot T) - k^3 (T \cdot B)$$

$$= k^2 T \cdot (1) - k^3 (0) \quad (\because T \cdot T = 1 \\ \text{& } T \cdot B = 0)$$

w.r.t radius of curvature i.e. the reciprocal of curvature  $k$ :

$$\text{i.e., } r = \frac{1}{k}$$
$$\Rightarrow k = \frac{1}{r}$$

$$\therefore \frac{d\vec{r}}{ds} \cdot \left( \frac{d\vec{r}}{ds} \times \frac{d^2\vec{r}}{ds^2} \right) = \frac{1}{r^2} T.$$

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