Qs (1) Limiting ODE of the TD(0) algorithm with linear function approximation:

where,

$$b = \phi^T DR$$

$$A = \phi^T D [I - Y P] \phi$$

Global Lyapunov function for the limiting ODE

Verification:

To show: V(x) >0 +x with equality iss

w.k.t w; > w\*;.

with 
$$V(\omega) = 0$$
 iff  $\omega_i = \omega_{\Phi_i}$   $\forall i$ 

$$=) \omega = \omega_{\Phi}$$

## 2) To show: lim V(w) = +0

Q8 (2) Given: \$(1)=1 \$(2)=2

 $\Rightarrow \phi = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ 

Tanget policy & m and Behavior policy ? + p(sight(1)) = 0.5

: 7 (left | 1) = 1 - 7 (right | 1) = 1 - 0.5 = 0.5

+ 7 ( right 12) = 0.5

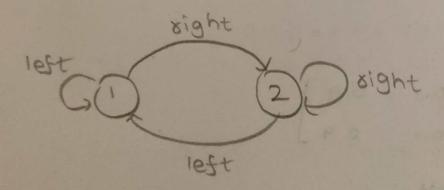
=) p(left 12) = 1 - p(right 12) = 1-0.5 = 0.5

\* M(xight | 1) = 0.9

=) \(\(\left\) = 1 - \(\left\) \(\sight\) = 1 - 0,9 = 0.1

\* \(\pi(\sight | 2) = 0.9\)

=)  $\mu(xight|2) = 1 - \mu(xight|2) = 1 - 0.9 = 0.1$ left



QS (2) @ To find: PM

PM(st,=11st=1) = M(xight 1st=1) PM(st,=11st=1, at=xight)
+ M(left 1st=1) IPM(st,=11st=1, at=left)

= 0.9 \* 0 + 0.1 \* 1 = 0.1

 $PM(S_{t+1}=2|S_{t}=1) = \mu(sight|_{1})PM(2|_{1}, sight) + \mu(left|_{1})PM(2|_{1}, left)$ 

=0.9 \*1 + 0.1 \*0 = 0.9

 $PH(S_{t+1}=1|S_t=2) = H(xight|2)PH(1|2,xight) +$  H(left|2)PH(1|2,left)

=0.9+0+0.1+1 = 0.1

Ph(St+1=21St=2)= H(xight12) IPH(212, xight) + M(left12) IPH(212, left)

=0,9\*1+0.1\*0=0,9

 $PM = \begin{cases} 0.1 & 0.9 \\ 0.1 & 0.9 \end{cases}$ 

To find: dM

we know dht ph = dht that

=) [dH(1) dH(2)][0.1 0.9] = [dH(1) dH(2)]

=) 0.1 dm(1) + 0.1 dm(2) = dm(1)

we also dm(1) + dm(2) = 1
Know that

Subs Eq 1

From (1) dM(2)=9 + 0.1=0.9

To find : A

$$= \begin{bmatrix} 1 & 2 \end{bmatrix} \begin{bmatrix} 0.1 & 0 \\ 0 & 0.9 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} - Y \begin{bmatrix} 0.1 & 0.9 \\ 0.1 & 0.9 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$= [0.1 \ 1.8] \left( [0.09 \ 0.81] \right) \left( [0] - [0.09 \ 0.81] \right) \left( [0] \right)$$

$$= [0.1 \ 1.8] [0.91 \ -0.81] [1] \left[-0.09 \ 0.19] [2]$$

As the entry in A is positive, here, A is a positive definite matrix.

:. The limiting ODE associated with the on-policy to(0) has a globally asymptotically Stable equilibrium.

To find: d?

=) 
$$[d^{n}(1) d^{n}(2)][0.5 0.5] = [d^{n}(1) d^{n}(2)]$$

=) 
$$0.5d^{2}(1) + 0.5d^{2}(2) = d^{2}(1)$$

$$=$$
  $d^{\gamma}(1) = d^{\gamma}(2) \longrightarrow 2$ 

Subs Eq 2

To find: A'

W.K.+ A' =  $\phi^T D^7 (I - Y P^H) \phi$ =  $[1 \ 2][0.6 \ 0][[1 \ 0] - 0.9[0.1 \ 0.9][2]$ =  $[0.5 \ 1][0.91 \ -0.81][1]$ =  $[0.365 \ -0.215][1]$ =  $[0.365 \ -0.215][1]$ 

The entry in A' is negative.

= [-0,065]

.. Here, A' is not a positive definite matrix
.. The limiting ODE associated with the naive
off-policy algorithm been does not have a

globally asymptotically stable equilibrium.

Here, Ft = Pt-17Kt-1 + 1

=) 
$$[f(1) f(2)][[1 0] - 0.9[0.1 0.9]] = [0.5 0.5]$$

=) [
$$f(1)$$
  $f(2)$ ] [ $0.91$   $-0.81$ ] = [ $0.5$   $0.5$ ]

=) 
$$0.91f(1) - 0.09f(2) = 0.5 \longrightarrow 3$$
  
- $0.81f(1) + 0.19f(2) = 0.5 \longrightarrow 4$ 

Multiplying 3 by 0.19 and 4 by 0.09

Adding the two equations

: 
$$f(1) = 1.4$$
  $f(2) = 8.6$ 

To find : A"

$$= [12][1.40][[0]-0.9[0.10.9]][1]$$

$$= [1.4 17.2) [0.91 -0.81] [1] [-0.09 0.19] [2]$$

As the entry in A" is positive. Here, A" is a positive definite matrix.

:. The limiting ODE associated with emphatic TD(0) has a globally asymptotically stable equilibrium.

$$=) \sum_{S} f(S) \left[ 1 - Y \right] = 1$$

$$=) \sum_{S} f(S) = 1$$

Yes, we can identify  $\Sigma f(s)$ , which is

## Q9 (4) Optimization Problem: min $\varepsilon(\omega)$ $\varepsilon(\omega) = \frac{1}{2} ||QH(s,a) - Q*(s,a)||_D^2$

Intuition: The optimization problem tries to reduce the difference between the true (or target) Q value and the auroent estimate of the Q-value, which is what we want we want our estimate of Q-value to be as close as to value of true Q-value.

\* But, the problem (or difficulty) in doing this is, we don't know the 2+(s,a) value

i. We try to approximate the Qr(s,a) value by

Q+(9,a) = \$\psi^{\psi}(9,a).w

where,

φ - apriori known feature matrix ω - parameter.

: min & (w) = min 1 11 2H (s,a) - \$T(s,a) w 112

Convex Optimization:

Here,  $E(\omega) = \frac{1}{2} \sum_{\alpha,\beta} d_{\mu}(\beta) \mu(\alpha) (Q^{M}(\beta,\alpha) - \phi^{T}(\beta,\alpha)\omega)^{2}$ 

where,  $s_t \sim d\mu$   $a_t \sim \mu$   $a_t \sim \mu$ 

From Bellman Equation, we know that  $Q^{M}(s,a) = IE[x(s_{t},a_{t},s_{t+1})+\gamma Q^{M}(s_{t+1},a_{t+1})|s_{t}=s, a_{t}=a)$   $= \sum IP\{a_{t+1}=a',s_{t+1}=s'|s_{t}=s,a_{t}=a\}$  a',s'  $[x(s,a,s')+\gamma Q^{M}(s',a')]$ 

Subs value of QH(s,a) in 1

∇ε(ω) = - Σ pqst=93μ(at=a) [Qμ(s,a) - φτ(s,a)ω] α,s

Φ(s,a)

= - EPfs3 M(a) EPfs', a' 15, a3 (8(s,a,s'))
a,s
+ (QM(s',a') - bT(s,a)w) d(s,a)

=  $-\sum_{\alpha,s} P\{s_{t}=s, a_{t}=a, s_{t+1}=s', a_{t+1}=a'\},$   $a_{t}, a'$  (8(s, a, s') + Y QM(s', a') - $\phi^{T}(s, a)$  W)  $\phi(s, a)$ 

=-IE [(8(5,a,s')+YQM(5',a')-\$T(5,a)w)\$(5,a)]

where, Study Strup(.18t.at)

atup(.18t)

atup(.18t)

Hence, the SGD algorithm would be:

 $w_{t+1} = w_t + \alpha_t \{ x (s, a, s') + \gamma Q M (s', a') \}$ - $\phi T (s, a) w J \phi (s, a)$ 

where,  $\alpha_{+} \rightarrow step size$