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# **ELEC3310:**

# **Electrical Energy Conversion and Utilisation**

**Topic 2: Three Phase System**

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# Three phase fundamentals

## Three Phase AC Circuits

- Phasor Notation
- Single Phase Power
- Complex Power
- Direction of Power Flow
- Wye Connected Load
- Delta Connected Load
- Power in Balanced 3-Phase Load
- Per-Unit systems

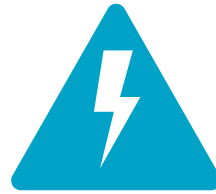
# System Parameters



## Frequency

The standard frequency of operation of power systems either 50 or 60 Hz (cycles per second).

In Australia, the frequency is 50 Hz,



## Voltages

The line (line – line) voltages is **ALWAYS** used when discussing three phase systems.



## Power Rating

Total 3 phase power rating **ALWAYS** assumed

# Phasor Notation

All electrical parameters can be expressed in form shown

This is equivalent to a vector with a magnitude of  $V_m/\sqrt{2}$  (i.e. rms value of  $V(t)$ ) rotated clockwise by an angle of  $\Phi$  radians from the reference vector as described by:

$$(V_m/\sqrt{2}) * [\cos(\Phi) + j * \sin(\Phi)]$$

This is commonly represented as  $V \angle \Phi$

rms: “root mean square”

$$V(t) = V_m \cos(\omega t + \phi)$$

$V_m$  – *peak value*

$\omega$  – *angular frequency* =  $2\pi f$

$f$  – *50Hz in Australia*

$\phi$  – *phase shift*

$1/f = T$  – *period of waveform*

## RMS of Effective Value

$$V_{rms} = \sqrt{\frac{1}{T} \int v^2(t) dt} \quad V(t) = V_m \cos(\omega t + \phi)$$

$$= \sqrt{\frac{V_m^2}{2\pi / \omega} \int_0^{2\pi / \omega} \cos^2(\omega t + \phi) dt} = \frac{V_m}{\sqrt{2}}$$

$V_{rms}$  – effective voltage of AC quantity, would produce same heating effect in resistor as DC voltage with same magnitude

# Power in Single Phase Circuit

$$V(t) = V_m \cos(\omega t + \Phi)$$

$$I(t) = I_m \cos(\omega t + \theta)$$

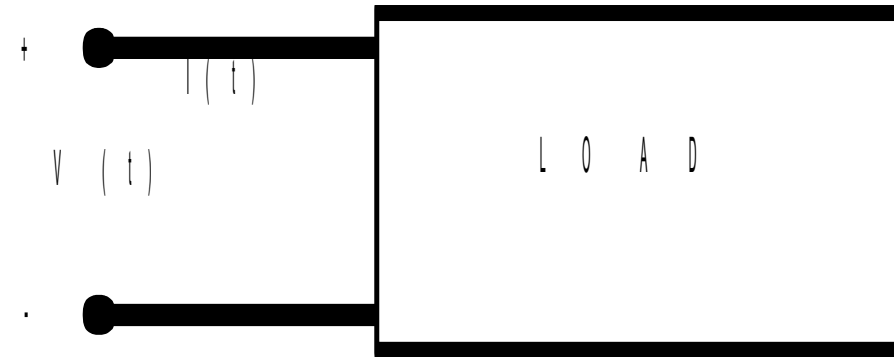
Instantaneous power

$$\begin{aligned} p(t) &= V(t)I(t) \\ &= V_m I_m \cos(\omega t + \Phi) \cos(\omega t + \theta) \\ &= 0.5 V_m I_m \cos(2\omega t + \Phi + \theta) + 0.5 V_m I_m \cos(\Phi - \theta) \end{aligned}$$

- Two components

$0.5 V_m I_m \cos(2\omega t + \Phi + \theta)$  – double frequency component

$0.5 V_m I_m \cos(\Phi - \theta)$  – time invariant component



# Power in Single Phase Circuit

## Real power

- of greater interest is average power dissipated in load, or mean value of  $p(t)$ ,

$$P = 0.5V_m I_m \cos(\Phi - \theta)$$
$$= V_{\text{rms}} I_{\text{rms}} \cos(\Phi - \theta) \quad [\text{watts}], [W]$$

- $P$  – real power, active power
  - “useful” energy dissipated in load

## Apparent power

- $S = V_{\text{rms}} I_{\text{rms}}$  [volt-amperes], [VA]

## Reactive power

- $Q = V_{\text{rms}} I_{\text{rms}} \sin(\Phi - \theta)$  [volt-amps reactive], [VAr]



# Power factor

Power factor =  $\cos (\Phi - \theta) = P/VI$

- proportion of apparent power capable of doing “useful” work
- $(\Phi - \theta)$  – power factor angle
  - +ve – *lagging* power factor – mainly inductive load
  - - ve – *leading* power factor – mainly capacitive load
- Power factor lies between 0 - 1



# Complex Power

Consider arbitrary load

$$\bullet v(t) = V_m \cos(\omega t + \theta_v) \rightarrow \mathbf{V} = V \angle \theta_v$$

$$\bullet i(t) = I_m \cos(\omega t + \theta_i) \rightarrow \mathbf{I} = I \angle \theta_i$$

“Complex” power – i.e. vector quantity

- $\mathbf{S} = \mathbf{V} \mathbf{I}^* = (V \angle \theta_v) (I \angle -\theta_i) = VI \angle (\theta_v - \theta_i)$
- Magnitude given by apparent power –  $VI$
- Phase angle given by phase angle difference between voltage and current, i.e. the power factor angle

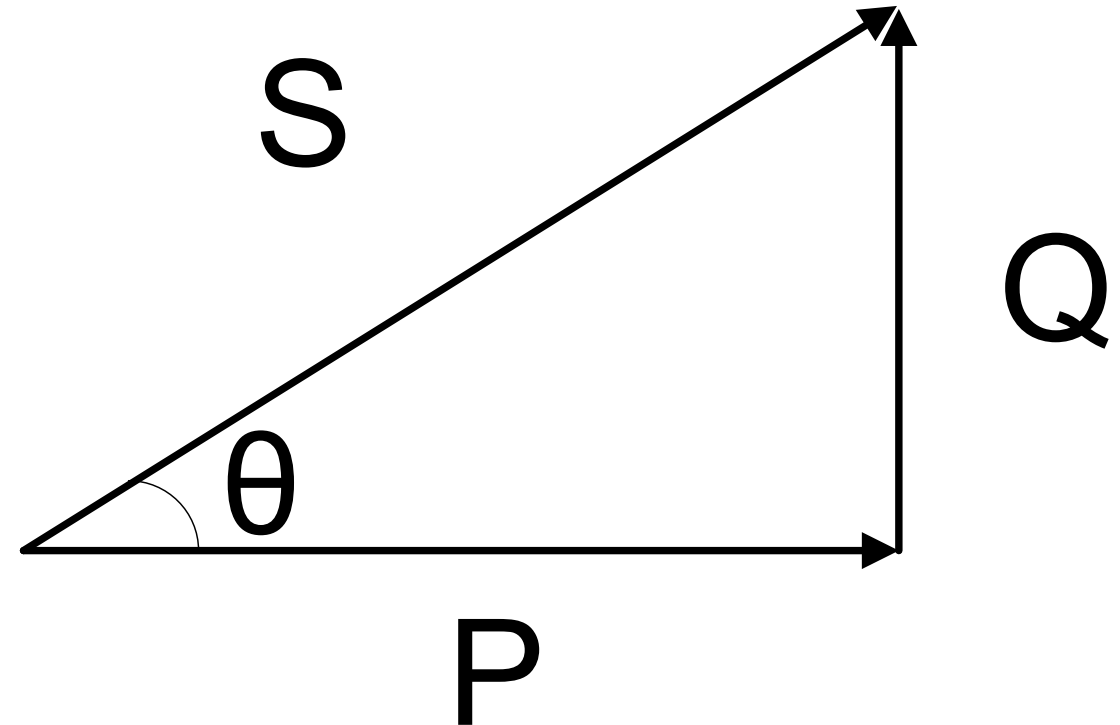
# Power Triangle

If  $\theta_v > \theta_i$ , power factor angle +ve, Q also +ve

- Current lagging voltage as in inductive load

If  $\theta_v < \theta_i$ , power factor angle -ve, Q also -ve

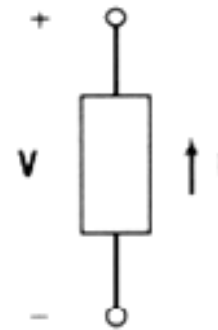
- Current leading voltage as in capacitive load



# Direction of Power Flow

Direction of current flow assumed to be different for generator or load

- Generator
  - Current assumed to flow out in direction of voltage rise
- Load
  - Current assumed to flow into direction of voltage drop



$$\mathbf{S} = \mathbf{V}\mathbf{I}^* = P + jQ$$

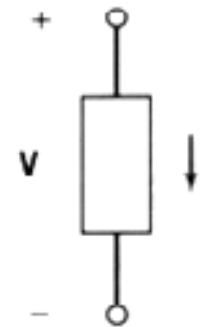
If  $P$  is positive, then real power is delivered

If  $Q$  is positive, then reactive power is delivered

If  $P$  is negative, then real power is absorbed

If  $Q$  is negative, then reactive power is absorbed

(a) Generator condition



$$\mathbf{S} = \mathbf{V}\mathbf{I}^* = P + jQ$$

If  $P$  is positive, then real power is absorbed

If  $Q$  is positive, then reactive power is absorbed

If  $P$  is negative, then real power is delivered

If  $Q$  is negative, then reactive power is delivered

(b) Load condition

# Tutorial #1

**Q1.** The instantaneous voltage  $v(t)$  across an electrical device and the instantaneous current  $i(t)$  entering the positive terminal of the circuit element are given by the following expressions:

$$v(t) = 110\cos(\omega t + 65^\circ)$$

$$i(t) = 15\sin(\omega t - 20^\circ)$$

Determine:

- (a) The maximum or peak value of the voltage and current
- (b) The rms value of the voltage and current
- (c) The phasor expression for the voltage and current



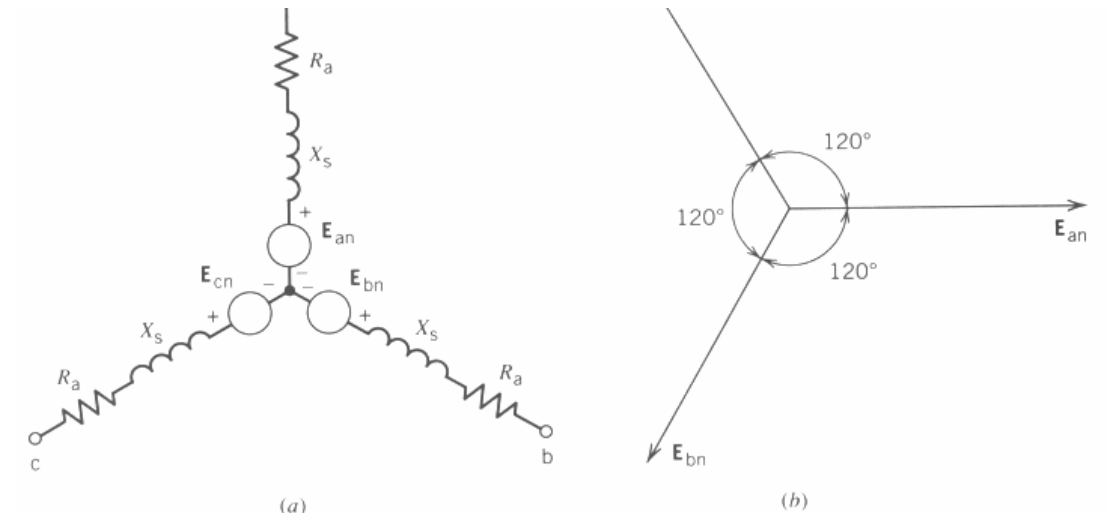
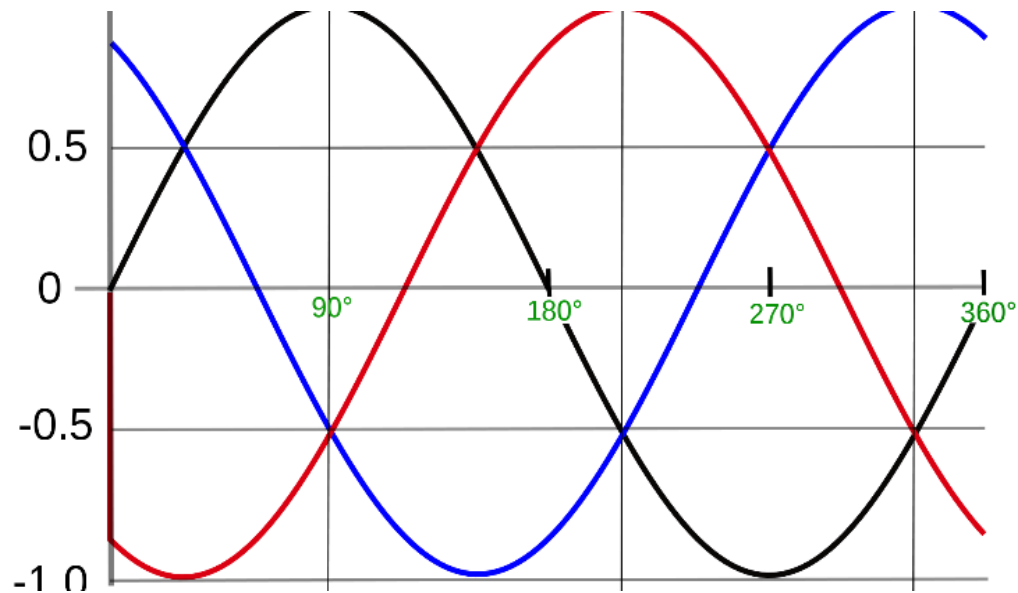
# 3 Phase Systems

Bulk power generation, transmission and distribution accomplished using 3 phases

- Lightning and small motors can be connected single phase
  - Assigned equally to three phase distribution systems to maintain balance

Following slide shows positive phase sequence connection, or *a-b-c* sequence

# 3 Phase Systems



$$v_a(t) = V_m \cos(\omega t) - \text{Black}$$

$$v_b(t) = V_m \cos(\omega t - 120^\circ) - \text{Red}$$

$$v_c(t) = V_m \cos(\omega t - 240^\circ) - \text{Blue}$$

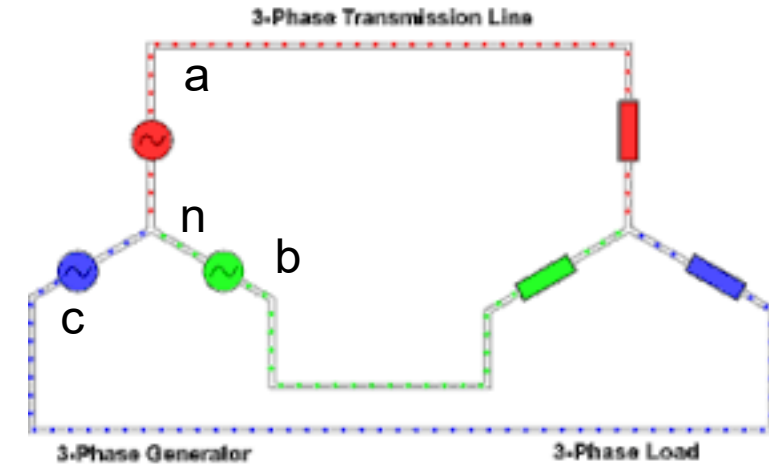
# 3 Phase Systems

## Three Phase Wye Source

- Terminals a, b, c called line terminals
- n – neutral terminal

Source balanced if voltages  $V_{an}$ ,  $V_{bn}$ ,  $V_{cn}$ , i.e. *phase voltages*, have same magnitude and sum (vector sum) to zero

- $|V_{an}| = |V_{bn}| = |V_{cn}|$
- $V_{an} + V_{bn} + V_{cn} = 0$



## Wye connected load

$$V_{an} = V \angle 0^\circ$$

$$V_{bn} = V \angle -120^\circ$$

$$V_{cn} = V \angle -240^\circ$$

$$I_{an} = V \angle 0^\circ / Z_Y \angle \theta$$

$$I_{bn} = V \angle -120^\circ / Z_Y \angle \theta$$

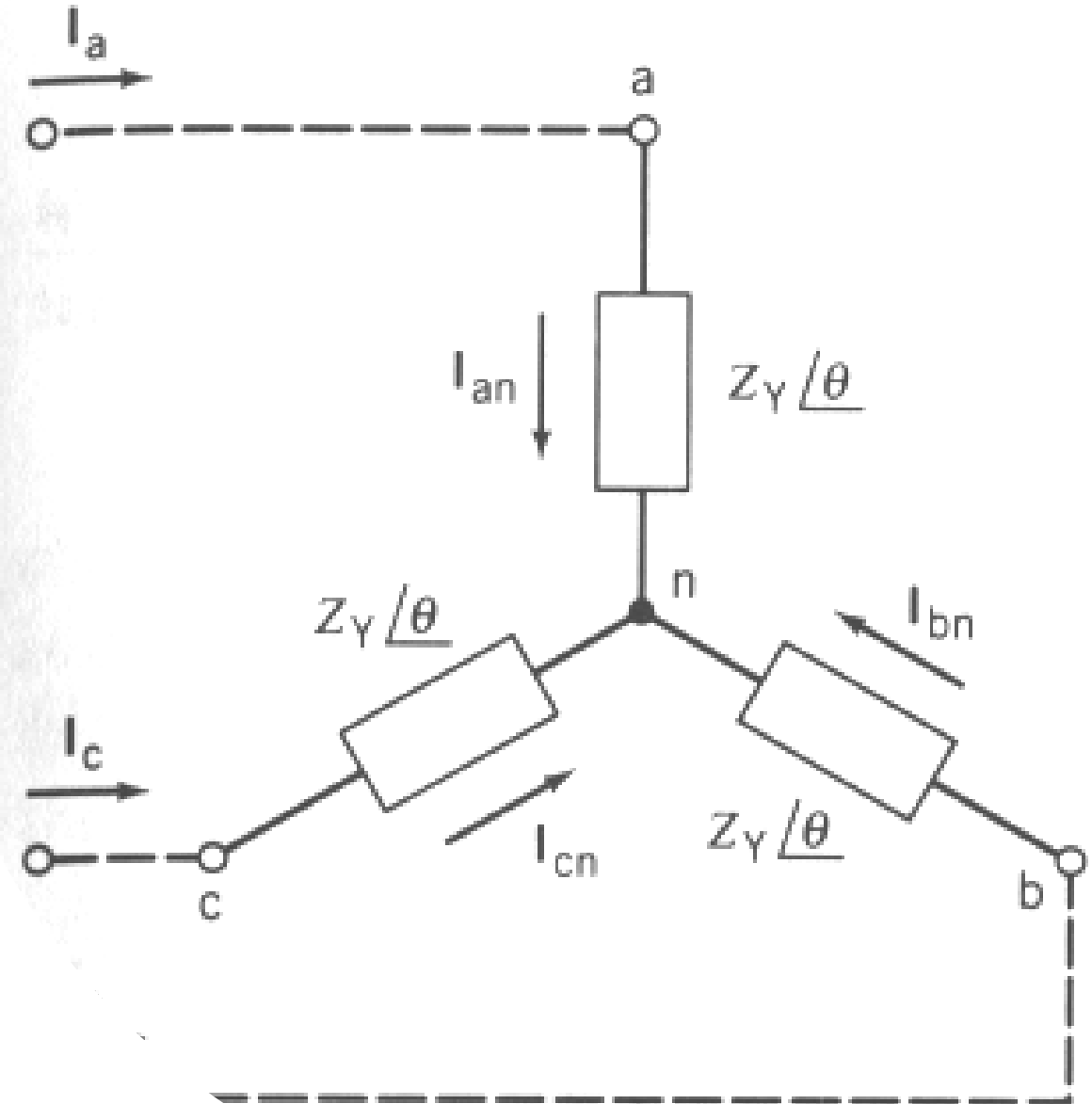
$$I_{cn} = V \angle -240^\circ / Z_Y \angle \theta$$

Phase currents and line current are identical

- Both determined by applied phase voltages and load impedances

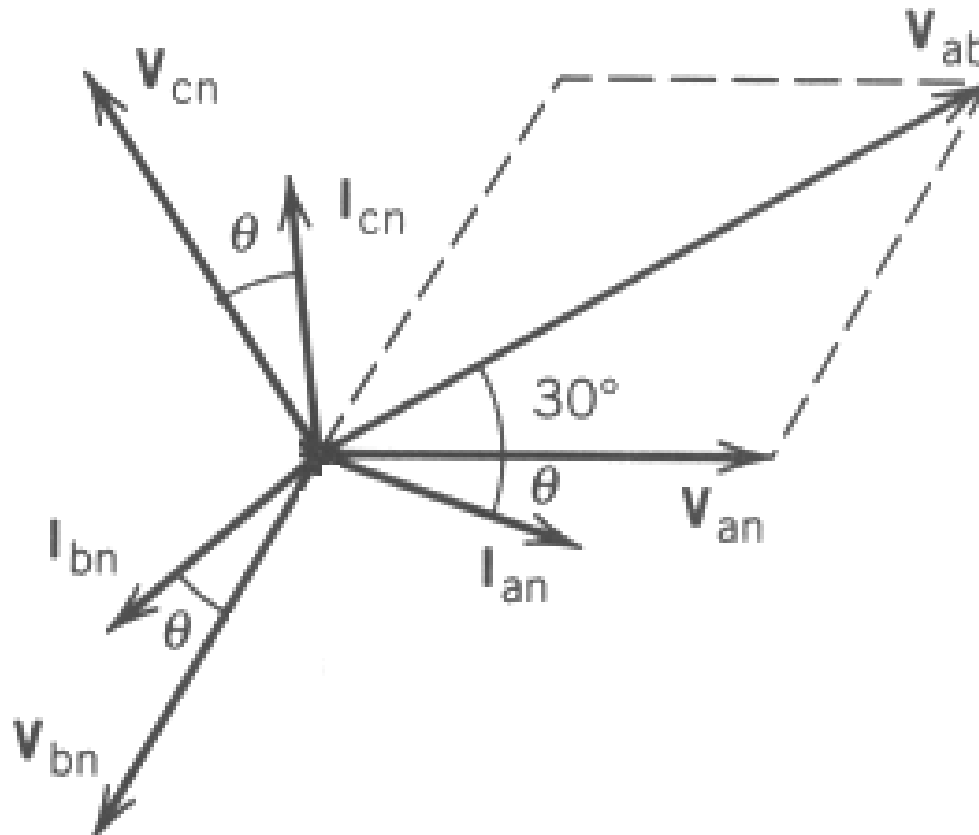
Currents form balanced set of phasors which sum to zero

$$I_{an} + I_{bn} + I_{cn} = 0$$





# Wye connected load – line-to-line voltages

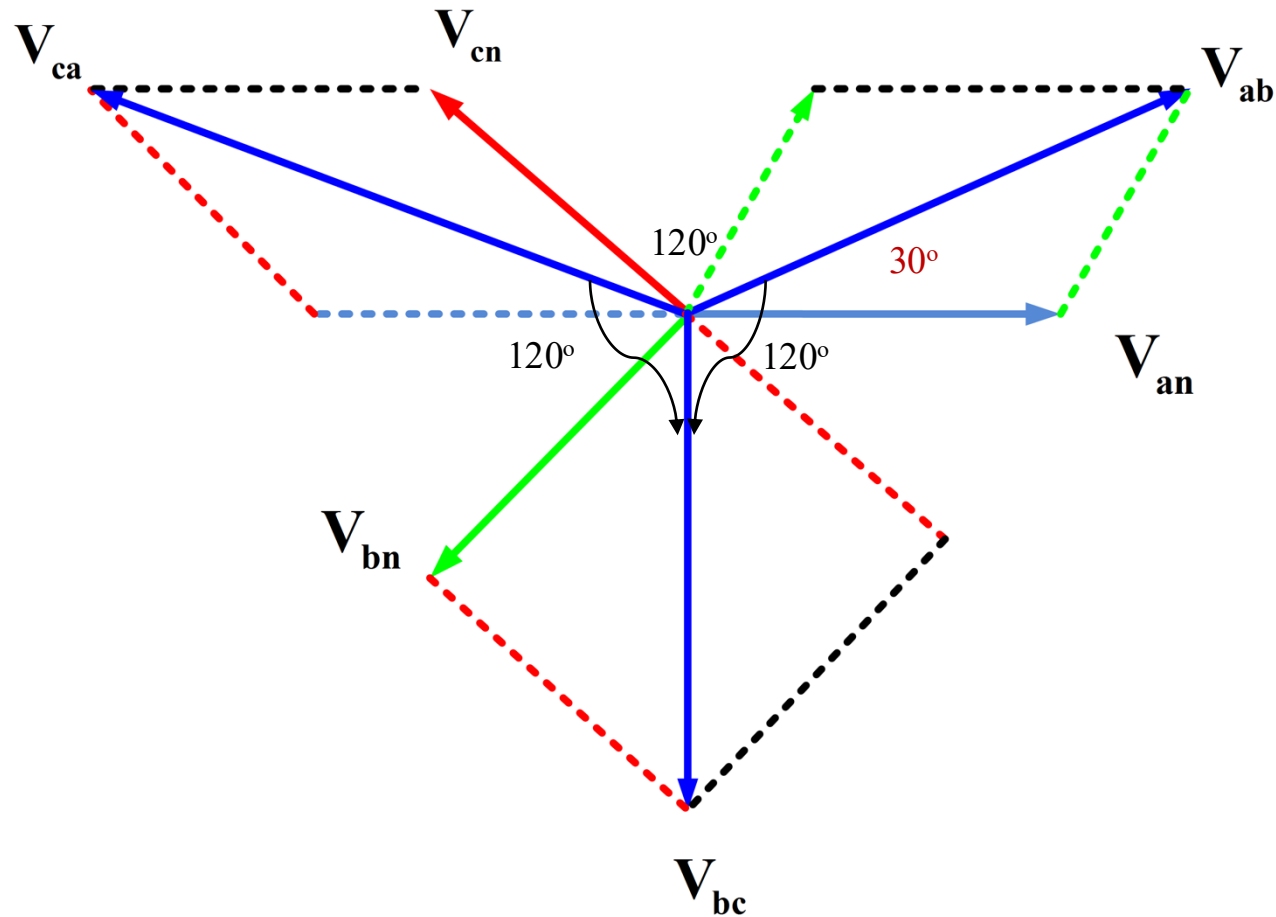


$$\begin{aligned}
 V_{ab} &= V_{an} + V_{nb} \\
 &= V_{an} - V_{bn} \\
 &= |V_{an}| * [1 - 1 \angle -120^\circ] \\
 &= \sqrt{3} |V_{an}| \angle +30^\circ
 \end{aligned}$$

Line-to-line voltage:

- Has magnitude  $\sqrt{3}$  times magnitude of phase voltage
- Leads corresponding phase voltage by  $30^\circ$

# Wye connected load – line-to-line voltages



# Delta Connected Load

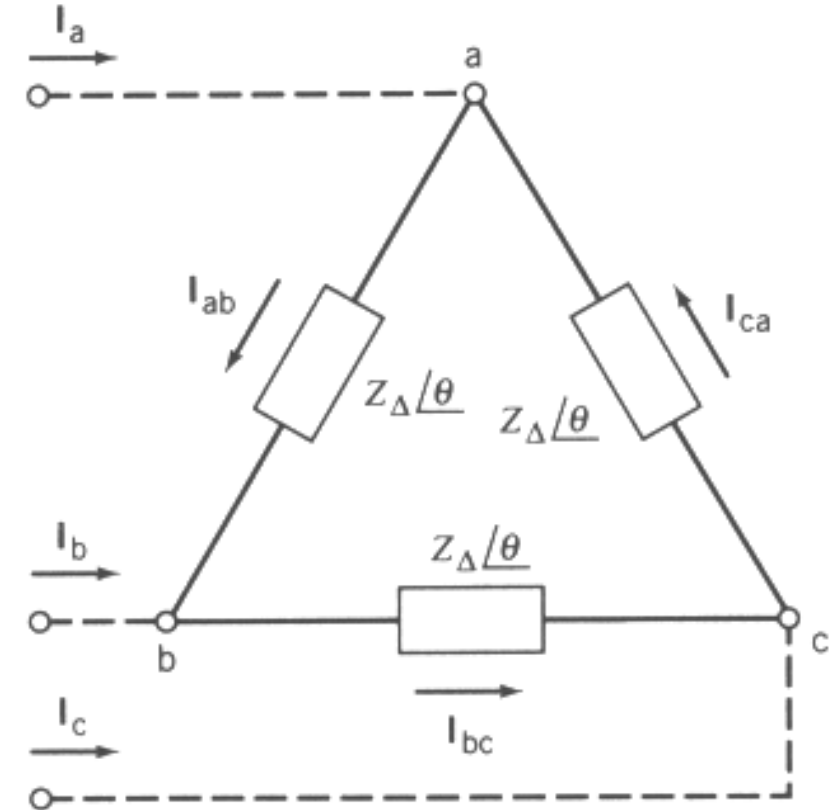
Line-to-line voltages identical to voltage across each load

Phase currents determined according to applied voltage and load. E.g.

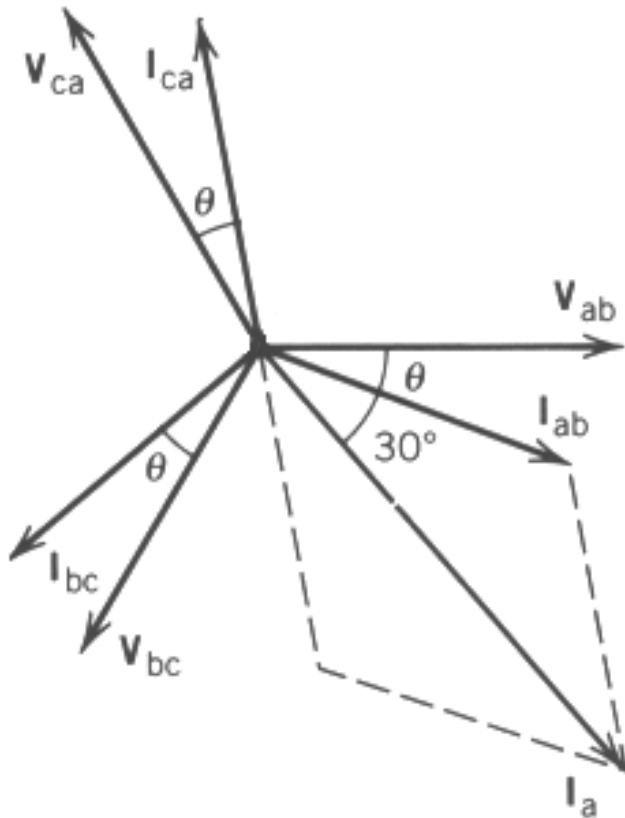
$$I_{ab} = V_{ab}/Z_{\Delta}\angle\theta = I \angle -\theta$$

$$I_{bc} = V_{bc}/Z_{\Delta}\angle\theta = I \angle -\theta - 120^{\circ}$$

$$I_{ca} = V_{ca}/Z_{\Delta}\angle\theta = I \angle -\theta - 240^{\circ}$$



# Delta Connected Load - Line currents



To calculate line current, apply KCL at any terminal

E.g. at point “a”

- $-I_a + I_{ab} - I_{ca} = 0$

$$I_a = I_{ab} - I_{ca}$$

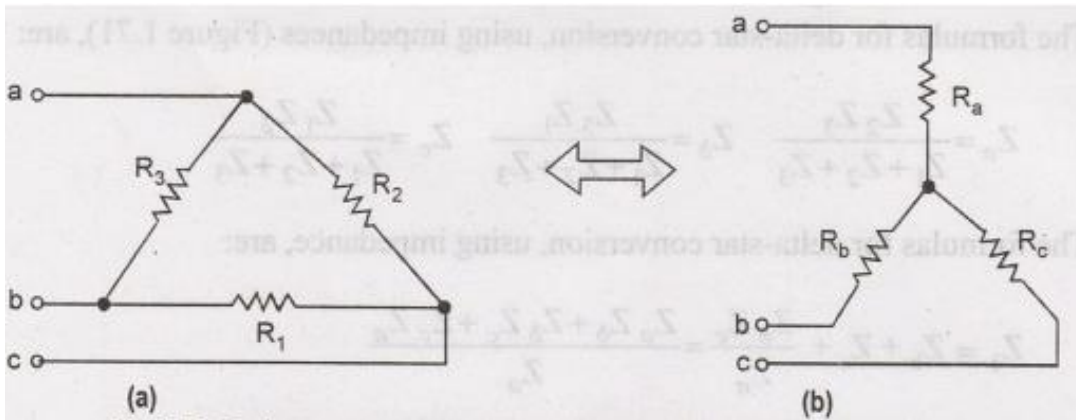
$$I_a = I_{ab} - I_{ab} \angle -240^\circ$$

$$= \sqrt{3}I_{ab} \angle -30^\circ$$

Line current

- Has magnitude  $\sqrt{3}$  times phase current
- Lags corresponding phase current by  $30^\circ$

# STAR to Delta Conversion



$$R_a = \frac{R_2 R_3}{R_1 + R_2 + R_3} \quad R_b = \frac{R_3 R_1}{R_1 + R_2 + R_3} \quad R_c = \frac{R_1 R_2}{R_1 + R_2 + R_3}$$

**For a Balanced Load**

$$R_1 = R_b + R_c + \frac{R_b R_c}{R_a} = \frac{R_a R_b + R_b R_c + R_c R_a}{R_a}$$

$$R_2 = R_c + R_a + \frac{R_c R_a}{R_b} = \frac{R_a R_b + R_b R_c + R_c R_a}{R_b}$$

$$R_3 = R_a + R_b + \frac{R_a R_b}{R_c} = \frac{R_a R_b + R_b R_c + R_c R_a}{R_c}$$

$$R_{STAR} = \frac{1}{3} R_{DELTA}$$

# Analysis of Balanced 3 Phase Systems

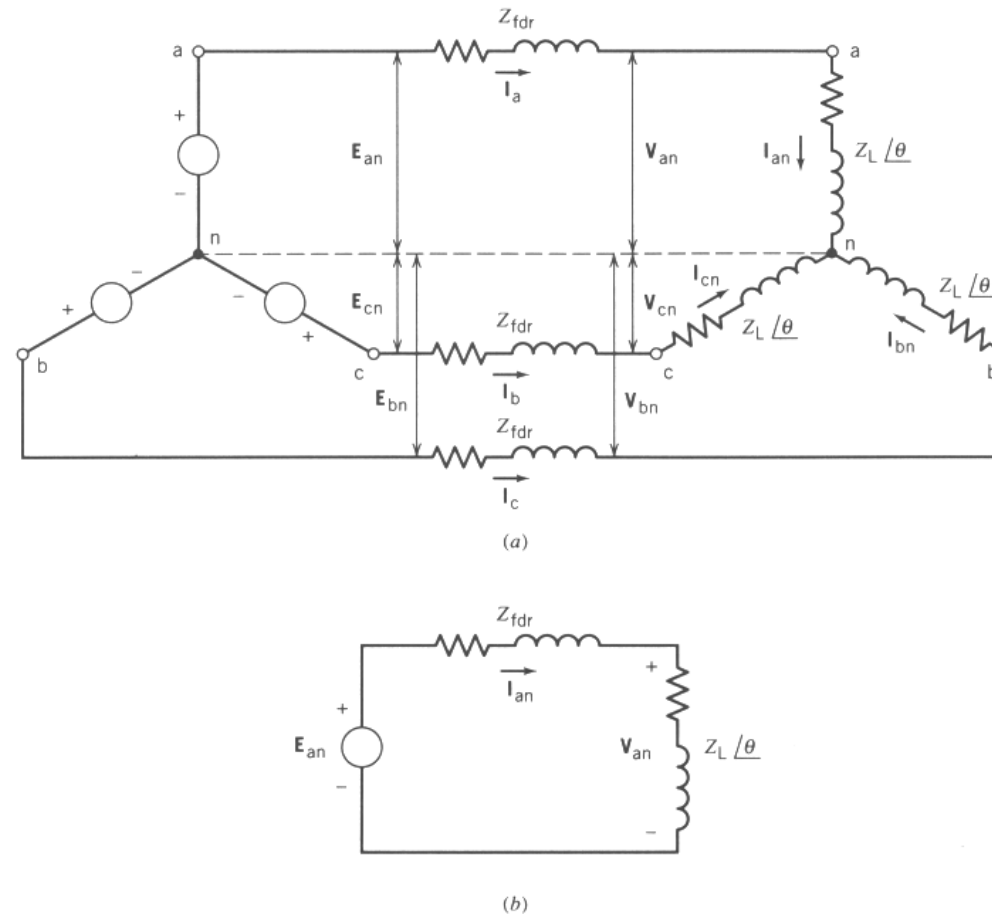


FIGURE 3.9 (a) Three-phase power system; (b) single-phase equivalent circuit.

# Analysis of Balanced 3 Phase Systems

3 Phase circuits analysed using single phase equivalents

- Voltage/Currents in each phase identical to corresponding parameters in other phases, except shifted by  $120^\circ$
- Neutral wire contains sum of return current from each phase  $I_a + I_b + I_c = I_n = 0$  – for balanced systems neutral wire can be ignored

Delta connected loads can be transformed into wye connected loads for which line-to-line voltages and line currents unchanged by assuming:

$$Z_Y = (1/3) * Z_\Delta$$

# Power in Balanced Three Phase Systems

Total average power absorbed by a three-phase balanced load (or delivered by three phase generator) equal to the sum of the powers in each phase.

Power absorbed in phase A

$$P_a = |V_{an}| |I_{an}| \cos(\theta_p)$$

where  $\theta_p$  is the phase angle between the voltage and the current determined by the load

$$|V_{an}| = |V_{bn}| = |V_{cn}| = |V_p|, \quad |I_{an}| = |I_{bn}| = |I_{cn}| = |I_p|$$

$$P_a = |V_p| |I_p| \cos(\theta_p) = P_b = P_c = P_p$$

Total three-phase real power:

$$P_T = 3P_p = 3|V_p| |I_p| \cos(\theta_p)$$

Total three-phase reactive power:

$$Q_T = 3Q_p = 3|V_p| |I_p| \sin(\theta_p)$$



# Power in Balanced Three Phase Systems

Total 3 Phase apparent power

- $S_T = 3S_p = 3\sqrt{(P_p^2 + Q_p^2)} = \sqrt{(P_T^2 + Q_T^2)}$

For wye connected load

- $\sqrt{3}|V_p| = |V_{l-l}|$  - line-to-line voltage  $\sqrt{3}$  time larger than phase voltage
- $|I_p| = |I_L|$  - line current and phase current identical

- Thus

$$\begin{aligned}P_T &= \sqrt{3} |V_{l-l}| |I_L| \cos(\theta_p) \\Q_T &= \sqrt{3} |V_{l-l}| |I_L| \sin(\theta_p) \\S_T &= \sqrt{3} |V_{l-l}| |I_L|\end{aligned}$$

For delta connected load

- $|V_{l-l}|$  - line-to-line voltage across load
- $\sqrt{3}|I_p| = |I_L|$  - line current  $\sqrt{3}$  time larger than phase current

- Thus

$$\begin{aligned}P_T &= 3P_p = \sqrt{3} |V_{l-l}| |I_L| \cos(\theta_p) \\Q_T &= 3Q_p = \sqrt{3} |V_{l-l}| |I_L| \sin(\theta_p) \\S_T &= \sqrt{3} |V_{l-l}| |I_L|\end{aligned}$$

# Power in Balanced Three Phase Systems

## Irrespective of load type

- $P_T = 3|V_p||I_p| \cos(\theta_p) = \sqrt{3} |V_{l-l}| |I_L| \cos(\theta_p)$
- $Q_T = 3|V_p||I_p| \sin(\theta_p) = \sqrt{3} |V_{l-l}| |I_L| \sin(\theta_p)$
- $S_T = 3|V_p||I_p| = \sqrt{3} |V_{l-l}| |I_L|$

where  $\theta_p$  is the phase angle of the load impedance of each phase

# Instantaneous Power in Balanced Three Phase Systems

For a balanced three phase load, total instantaneous power equal to sum of the powers of three phases.

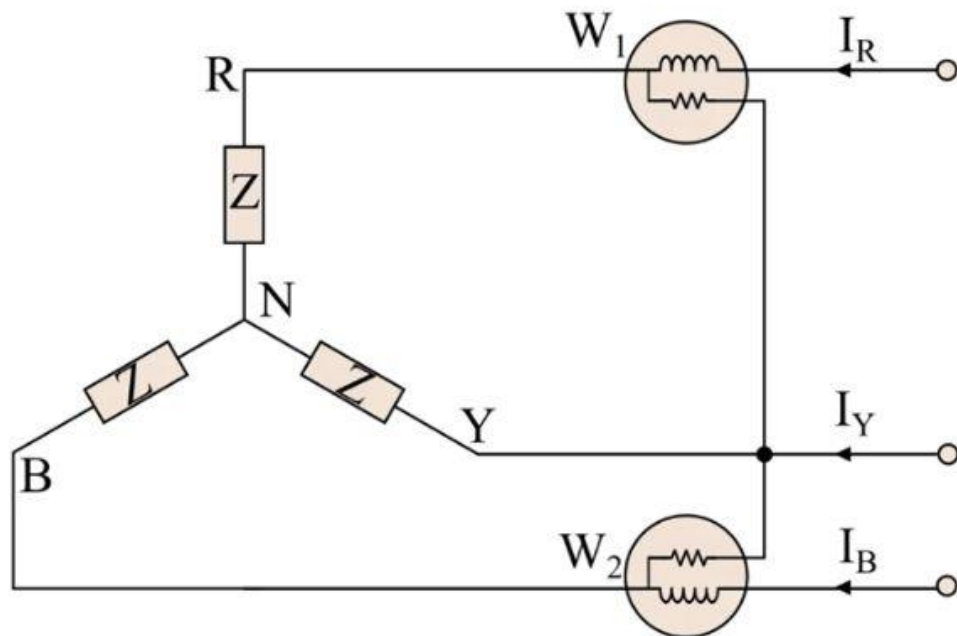
$$\begin{aligned} \bullet P_T &= P_a + P_b + P_c = v_{an} i_a + v_{bn} i_b + v_{cn} i_c \\ &= 1.5 * [V_m I_m \cos(\theta_p)] \\ &\quad + 0.5 * V_m I_m [\cos(2\omega t - \theta_p) + \cos(2\omega t - \theta_p + 120^\circ) \\ &\quad + \cos(2\omega t - \theta_p - 120^\circ)] \end{aligned}$$

Second term reduces to zero, thus

$$P_T = (3/2) * [V_m I_m \cos(\theta_p)]$$

**Total instantaneous power is time invariant.**

# Power Measurements in Three-Phase System



Assuming line-to-line voltage is  $V$  and line current is  $I$  for a balanced system Power factor angle is  $\phi$

$$W_1 = VI \cos(30 + \phi)$$

$$W_2 = VI \cos(30 - \phi)$$

$$W_1 + W_2 = \sqrt{3} VI \cos(\phi)$$

$$W_2 - W_1 = VI \sin(\phi)$$

# Advantages of 3 Phase Systems

1. Each separate single-phase system requires both forward and return conductors to have current capacity at least as high as load current
  - Balanced three phase system can deliver same power to three single phase loads but requires only half number of conductors
    - Line losses potentially reduced by 50%
    - Reduced capital and operating costs of transmission and distribution, along with better voltage control (regulation)

# Advantages of 3 Phase Systems

2. Total instantaneous power delivered under balanced conditions nearly constant
  - Three phase generator will have nearly constant mechanical input power and consequently near constant shaft torque
  - Instantaneous power in single phase systems has constant component **AND** double frequency component
    - High frequency component causes variation mechanical power to generator and shaft torque leading to shaft vibration and noise, and even shaft failure

# Recap

Have reviewed three phase fundamentals

- AC power
- Line and phase voltages and currents
- Wye and delta connected loads and generators
- Three phase power

Now will finally look at per-unit quantities

# Per unit fundamentals

## Per Unit Quantities

- Definition
- Advantages
- Formulation
- Change of Base
- Examples



# Per-Unit Quantities

Any electrical quantity may be expressed in “per-units” as a ratio of actual quantity to a chosen base value of that quantity

E.g.

$$\text{per-unit quantity} = \frac{\text{actual quantity}}{\text{base value quantity}}$$

- Actual quantity
  - value of quantity in actual units (such as volts, amps)
- Base quantity
  - reference value with same units as actual quantity

# Base Quantity

Reference level

Always has same units as actual quantity being measured

- PER-UNIT QUANTITY IS DIMENSIONLESS

Always a real number – e.g. 100, or 1.5

- Phase angle of per-unit quantity always the same as the phase-angle of the actual quantity being measured

# Advantages of Per-Unit

Eliminates need for conversion of voltages, current and impedances across every transformer

- Per-unit quantities same on both sides of transformer
  - Reduces chance of computational error

Many network quantities lies within narrow numerical bounds when expressed in per-units

- Nominal voltage or rated voltage of system usually chosen as voltage base → per-unit value of voltage usually  $\sim 1.0$  p.u.
  - Per-unit data can be checked rapidly for gross errors
- Manufacturers usually specify impedance of machines and transformers in per-unit or percent based on name-plate ratings

# Per-Unit Quantities – Single Phase Systems

Network behaviour characterised by 4 base quantities

- Power (apparent power)
- Voltage
- Current
- Impedance

Base quantities must satisfy electrical laws

- $S_{\text{base}} = V_{\text{base}} I_{\text{base}}$
- $V_{\text{base}} = I_{\text{base}} Z_{\text{base}}$

Necessary to select two base values from which remaining quantities will be specified

# Per-Unit Quantities – Single Phase Systems

Usual to specify Power and Voltage bases

- These parameter often determined according to rated values or nominal values network

E.g. – for transmission line nominal voltage 132 kV  
and power rating 100 MVA

Current and Impedance bases calculated from Power and Voltage bases

$$I_{base} = \frac{S_{base}}{V_{base}}, \quad Z_{base} = \frac{V_{base}}{I_{base}} = \frac{(V_{base})^2}{S_{base}}$$

# Per-Unit Quantities – Single Phase Systems

Per-unit electrical quantities calculated as:

$$S_{per-unit} = \frac{P + jQ}{S_{base}} = P_{per-unit} + jQ_{per-unit}$$

$$V_{per-unit} = \frac{V \angle \phi_v}{V_{base}} = \frac{|V|}{V_{base}} \angle \phi_v$$

$$I_{per-unit} = \frac{I \angle \phi_i}{I_{base}}$$

$$Z_{per-unit} = \frac{Z \angle \phi_z}{Z_{base}}$$

# Per-Unit Quantities – Three Phase Systems

For 3 phase systems,

- Base power is total 3 phase
- Base voltage is line-to-line voltage
- Base line current assumed equal to base phase current
  - Assumption is that network wye connected
- Base impedance is the same per-phase base quantity

# Per-Unit Quantities – Three Phase Systems

For 3 Phase Systems

- Base power:  $S_{T,base} = 3S_{p,base}$
- Base voltage:  $V_{L,base} = \sqrt{3}V_{p,base}$
- Base current: 
$$I_{p,base} = (S_{T,base})/(\sqrt{3}V_{L,base})$$
$$= (S_{p,base})/(V_{p,base})$$
- Base impedance: 
$$Z_{p,base} = (V_{L,base})^2/(S_{T,base})$$
$$= (V_{p,base})^2/(S_{p,base})$$



# Change of base formula

Impedance characteristics of electrical equipment usually expressed as percentage based on machine ratings

- Machine ratings may be different from system voltage or power bases
- Need formula to convert per-unit impedance or percentage impedance of machine ratings to per-unit impedance for new base

# Change of base formula

$$Z_{per-unit,old} = \frac{Z_{actual}}{Z_{base,old}} = \frac{Z_{actual} \times S_{base,old}}{(V_{base,old})^2}$$

$$Z_{per-unit,new} = \frac{Z_{actual}}{Z_{base,new}} = \frac{Z_{actual} \times S_{base,new}}{(V_{base,new})^2}$$

$$Z_{per-unit,new} = Z_{per-unit,old} \frac{Z_{base,old}}{Z_{base,new}} = Z_{per-unit,old} \frac{(V_{base,old})^2}{(V_{base,new})^2} \times \frac{S_{base,new}}{S_{base,old}}$$

# Recap

Had looked at:

- Energy sources and conversion
- Single phase phasors, power etc.
- Three phase voltages, currents, loads, power
- Per-unit quantities

Coming Up...

- Magnetic circuits





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# Questions?

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