# Homework 1 (due Wednesday, August 29th, 2018)

## I: Linear Systems

- 1. Give a simple example of a  $3 \times 3$  matrix A of rank 2 and demonstrate that a non-zero vector  $\mathbf{z}$  exists for which  $A\mathbf{z} = \mathbf{0}$ .
- 2. The condition number of a matrix A is defined as

$$cond(A) = ||A|| \cdot ||A^{-1}||.$$
(1)

Beginning with the definition of the matrix norm given in the cheat sheet, show that the condition number of A can be re-expressed as

$$\operatorname{cond}(A) = \left(\max_{\mathbf{x} \neq \mathbf{0}} \frac{\|A\mathbf{x}\|}{\|\mathbf{x}\|}\right) \left(\min_{\mathbf{x} \neq \mathbf{0}} \frac{\|A\mathbf{x}\|}{\|\mathbf{x}\|}\right)^{-1}.$$
 (2)

### II. Taylor series approximation

- 1. What is the second-order Taylor polynomial  $p_2(x)$  for  $f(x) = x^{\frac{1}{x}}$  about  $x_0 = 1$ .
- 2. Plot f(x) and  $p_2(x)$  in the interval (0,5] using MATLAB or equivalent.
- 3. Where does f(x) attain its maximum value in  $(0, \infty)$ ? Do this analytically and computationally by writing a MATLAB program (or equivalent) to find the maximum.
- 4. Evaluate f'(x) analytically and approximately using a finite difference approximation. Plot both the analytic and computational derivatives in the interval (0,5].

## III. Computing with finite fields

1. In GF(p) where p=43, show (i) by direct computational checking through all possible field elements and (ii) by using gfdiv (or non-MATLAB equivalent) that each element of GF(43) except 0 has a multiplicative inverse in the same field.

#### Cheat Sheet

Taylor series approximation:  $f(x) = \sum_{i=0}^{n} \frac{(x-x_0)^i f^{(i)}(x_0)}{i!} + \frac{(x-x_0)^{n+1} f^{(n+1)}(\theta_{[x_0,x]})}{(n+1)!}$  with  $\theta_{[x_0,x]}$  in the interval  $[x_0,x]$ . Also,  $f(x+h) = \sum_{i=0}^{n} \frac{h^i f^{(i)}(x)}{i!} + \frac{h^{n+1} f^{(n+1)}(\theta)}{(n+1)!}$  where  $x \leq \theta \leq (x+h)$ .  $f^{(0)}(t) \stackrel{\text{def}}{=} f(t)$ . Integral form of the remainder:  $R_n(x) = \frac{1}{n!} \int_{x_0}^x (x-t)^n f^{(n+1)}(t) dt$ .

Chain rule for differentiation:  $\frac{d}{dx}(f(x)g(x)) = f'(x)g(x) + f(x)g'(x)$ .  $\frac{d}{dx}\frac{f(x)}{g(x)} = \frac{f'(x)g(x) - f(x)g'(x)}{g^2(x)}$ . Difference Approximations of Derivatives:  $f'(x) \approx \frac{f(x+h) - f(x)}{h}$ ,  $f''(x) \approx \frac{f(x+h) - 2f(x) + f(x-h)}{h^2}$ .

**Nonsingular matrices:** An  $n \times n$  matrix is said to be nonsingular if it satisfies any one of the following equivalent conditions:

- 1. A has an inverse (i.e., there is a matrix, denoted by  $A^{-1}$ , such that  $AA^{-1} = A^{-1}A = I$ , the identity
- 2.  $det(A) \neq 0$  (i.e., the determinant of A is nonzero).
- 3. rank(A) = n (the rank of a matrix is the maximum number of linearly independent rows or columns it contains). For an *n*-vector  $\mathbf{b} \notin \text{span}(A)$ , there does not exist a vector  $\mathbf{x}$  such that  $A\mathbf{x} = \mathbf{b}$ .
- 4. For any vector  $\mathbf{z} \neq \mathbf{0}$ ,  $A\mathbf{z} \neq \mathbf{0}$  (i.e., A annihilates no nontrivial vector).

**Matrix norm:** The matrix norm of an  $m \times n$  matrix A is defined as  $||A|| = \max_{\mathbf{x} \neq \mathbf{0}} \frac{||A\mathbf{x}||}{||\mathbf{x}||}$  where  $||A\mathbf{x}||$ and  $\|\mathbf{x}\|$  are vector norms. For an  $m \times n$  matrix A with matrix elements  $\{a_{ij}\}$ ,  $\|A\|_1 = \max_j \sum_{i=1}^m |a_{ij}|$ ,  $||A||_{\infty} = \max_{i} \sum_{j=1}^{m} |a_{ij}|$ 

**Vector norm:** For an integer p > 0 and an n-vector  $\mathbf{x}$ , the vector p-norm is defined by  $\|\mathbf{x}\|_p = (\sum_{i=1}^n |x_i|^p)^{\frac{1}{p}}$ .  $\|\mathbf{x}\|_1 = \sum_{i=1}^n |x_i|$  and  $\|\mathbf{x}\|_{\infty} = \max_{1 \le i \le n} |x_i|$ . For any vector p-norm,  $\|\mathbf{x} + \mathbf{y}\| \le \|\mathbf{x}\| + \|\mathbf{y}\|$  for all vectors  $\mathbf{x}, \mathbf{y}$ .