

## Numerical Methods Course # PHY 203

Chapter #: 6: Least-Square Approximation

Lecture # 9.2: Polynomial Data Fitting

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 Discrete Least Squares: This is a method to solve an over-determined linear system.



• Recall that an over determined linear system is defined by the linear equation Ax = b

where A is an  $m \times n$  matrix with m > n, x is an  $n \times 1$  column vector and b is an  $m \times 1$  constant column vector.

- Since A is no longer a square matrix, we can not invert and solve the linear system. The basic idea is to make a square matrix out of A, and then solve the system.
- We multiply by  $A^T$ , and find:  $(A^TA)x = A^Tb$ which are known as the `normal equations.  $A^T = n \times m \times A = n \times m$   $A^T = n \times m \times A = n \times m$   $A^T = n \times m \times A = n \times m$   $A^T = n \times m \times A = n \times m$   $A^T = n \times m \times A = n \times m$   $A^T = n \times m \times A = n \times m$   $A^T = n \times m \times A = n \times m$
- Here now  $(A^TA)$  is an  $n \times n$  square matrix. If the  $\det(A^TA) \neq 0$ , then  $A^TA$  is invertible, and we can approximately solve the linear system.
- It is an approximate solution because we are solving for n number of unknown variables that satisfies m number of conditions and here m > n.



Theorem: The matrix  $A^TA$  is invertible iff the columns of A are linearly independent, in which case Ax = b has a unique least-squares solutions



$$x = (A^T A)^{-1} A^T b$$
.  $\Rightarrow$  solution  $da(A^T A) \neq 0$ 

Example: Polynomial Data fitting.

An overdetermined system arise if we try to fit a polynomial

$$p_n(x) = a_0 + a_1 x + \dots + a_n x^n$$

to a function f(x) at m+1 nodes  $x_0, x_1, \cdots, x_m$  with m>n. IN the natural basis, we can write:

$$\frac{p_n(x_0) = a_0 + a_1 x_0 + \dots + a_n x_0^n = \underline{f(x_0)}}{p_n(x_1) = a_0 + a_1 x_1 + \dots + a_n x_1^n = \underline{f(x_1)}}$$

•

$$p_n(x_m) = a_0 + a_1 x_m + \dots + a_n x_m^n = f(x_m)$$

At the nodes  $P_n(x_0) = f(x_0)$   $P_n(x_1) = f(x_1)$ 



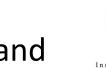
• In matrix form, we can write,



Verdermord
$$\underbrace{\begin{pmatrix}
1 & x_0 & \cdots & x_0^n \\
1 & x_1 & \cdots & x_1^n \\
1 & x_2 & \cdots & x_2^n \\
\vdots & \vdots & & \vdots \\
1 & x_m & \dots & x_m^n
\end{pmatrix}}_{m \times n}
\underbrace{\begin{pmatrix}
a_0 \\
a_1 \\
\vdots \\
a_n
\end{pmatrix}}_{n \times 1} = \underbrace{\begin{pmatrix}
f(x_0) \\
f(x_1) \\
f(x_2) \\
\vdots \\
f(x_m)
\end{pmatrix}}_{m \times 1}$$

- Here A in an  $m \times n$  matrix. To solve we multiply from left by  $A^T$  such that  $(A^TA)$  is now an  $n \times n$  square matrix.
- The right-hand side in now a constant matrix of order  $n \times 1$ .
- If  $A^TA$  is invertible, the above linear system can be solved by Gaussian elimination method, or by QR-decomposition method (see next lecture). L
- If n is 2 or 3, we can also find the inverse matrix, and solve.





- Let us fit a least-squares straight-line to the data: f(-3) = f(0) = 0, and
- Solution: Here n=1, because we are fitting a straight line. Therefore,

$$p_1(x) = a_0 + a_1 x$$
  $\Rightarrow a_0 = ? & a_1 = ??$ 

- And we have three nodes:  $x_0 = -3$ ,  $x_1 = 0$ ,  $x_2 = 6$ . So, m = 2. (: m > n).
- At the nodes we, have the following:

$$p_1(x_0) = a_0 + a_1x_0 = f(x_0)$$

$$p_1(x_1) = a_0 + a_1x_1 = f(x_1)$$

$$p_1(x_2) = a_0 + a_1x_2 = f(x_2)$$

• In matric form, we write after using the values of the nodes and their functions:

$$A = \begin{pmatrix} 3 \times 2 \end{pmatrix} = \begin{pmatrix} 1 & -3 \\ 1 & 0 \\ 1 & 6 \end{pmatrix} \begin{pmatrix} a_0 \\ a_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix}$$

$$A = 2 \times 1 \qquad (m \times 1)$$



• Multiplying by  $A^T$  from left, we find:



$$\begin{pmatrix}
1 & 1 & 1 \\
-3 & 0 & 6
\end{pmatrix}
\begin{pmatrix}
1 & -3 \\
1 & 0 \\
1 & 6
\end{pmatrix}
\begin{pmatrix}
a_0 \\
a_1
\end{pmatrix} = \begin{pmatrix}
1 & 1 & 1 \\
-3 & 0 & 6
\end{pmatrix}
\begin{pmatrix}
0 \\
0 \\
2
\end{pmatrix}$$

$$\begin{pmatrix}
3 & 3 \\
3 & 45
\end{pmatrix}
\begin{pmatrix}
a_0 \\
a_1
\end{pmatrix} = \begin{pmatrix}
2 \\
12
\end{pmatrix}$$

• Here: 
$$\underline{A^T A} = \begin{pmatrix} 3 & 3 \\ 3 & 45 \end{pmatrix}$$
 and  $\det(A^T T) = 126 \neq 0$ . The inverse is

$$(A^T A)^{-1} = \frac{1}{126} \begin{pmatrix} 45 & -3 \\ -3 & 3 \end{pmatrix}$$

• Therefore: 
$$\begin{pmatrix} a_0 \\ a_1 \end{pmatrix} = \frac{1}{126} \begin{pmatrix} 45 & -3 \\ -3 & 3 \end{pmatrix} \begin{pmatrix} 2 \\ 12 \end{pmatrix} = \begin{pmatrix} 3/7 \\ 5/21 \end{pmatrix} \implies \boxed{a_0 = \frac{3}{7}, a_1 = \frac{5}{21}}.$$

• Hence, the solution is:  $p_1(x) = \frac{3}{7} + \frac{5}{21}x$ .

