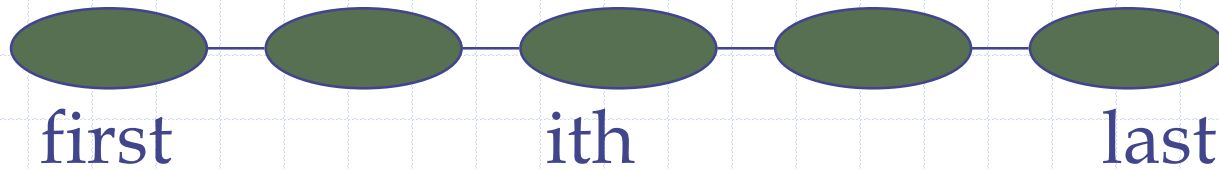
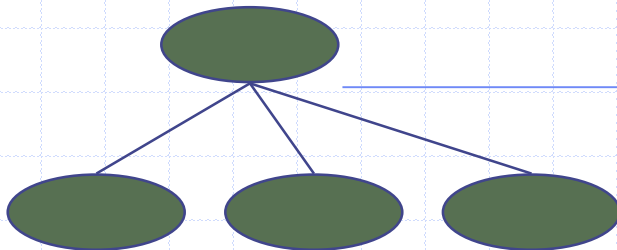


Graphs

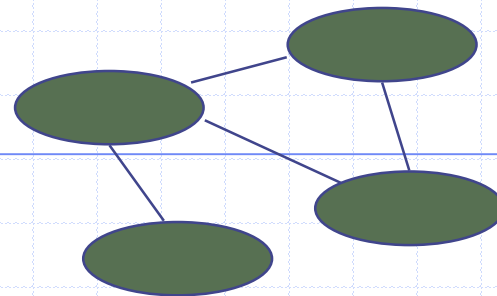
sequence/linear (1 to 1)



hierarchical
(1 to many)

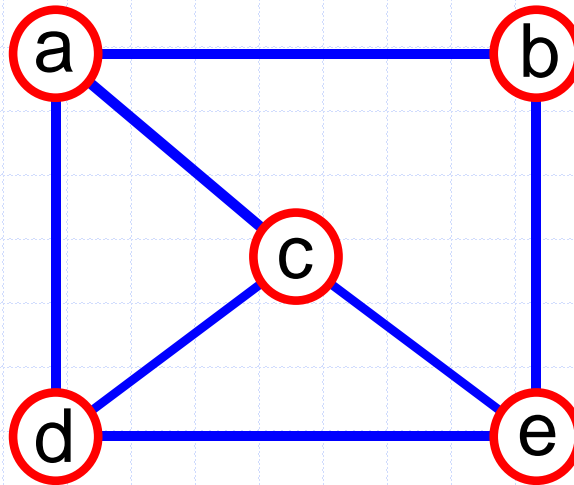


graph (many to many)



What is a Graph?

- ◆ A graph is a pair (V, E) , where
 - V is a set of nodes, called **vertices**
 - E is a collection of pairs of vertices, called **edges**
- ◆ $V(G)$ and $E(G)$ represent the sets of vertices and edges of G , respectively
- ◆ Example:



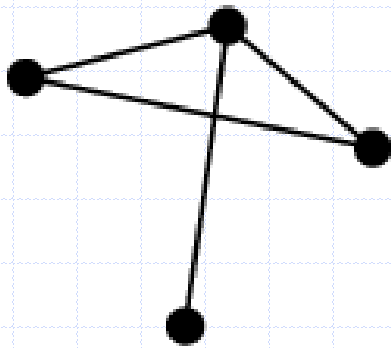
$V = \{a, b, c, d, e\}$

$E = \{(a,b), (a,c), (a,d), (b,e), (c,d), (c,e), (d,e)\}$

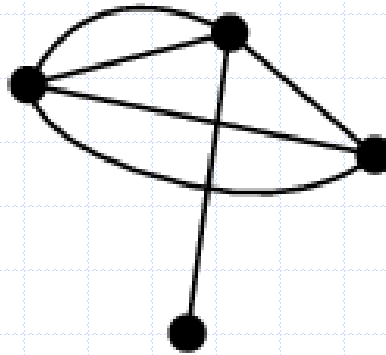
- ◆ **A tree is a special type of graph!**

What is a Graph?

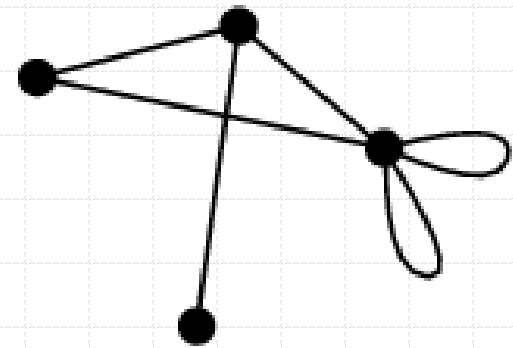
- ◆ A **simple graph**, also called a strict **graph** is an unweighted, undirected **graph** containing no **graph** loops or multiple edges



simple graph



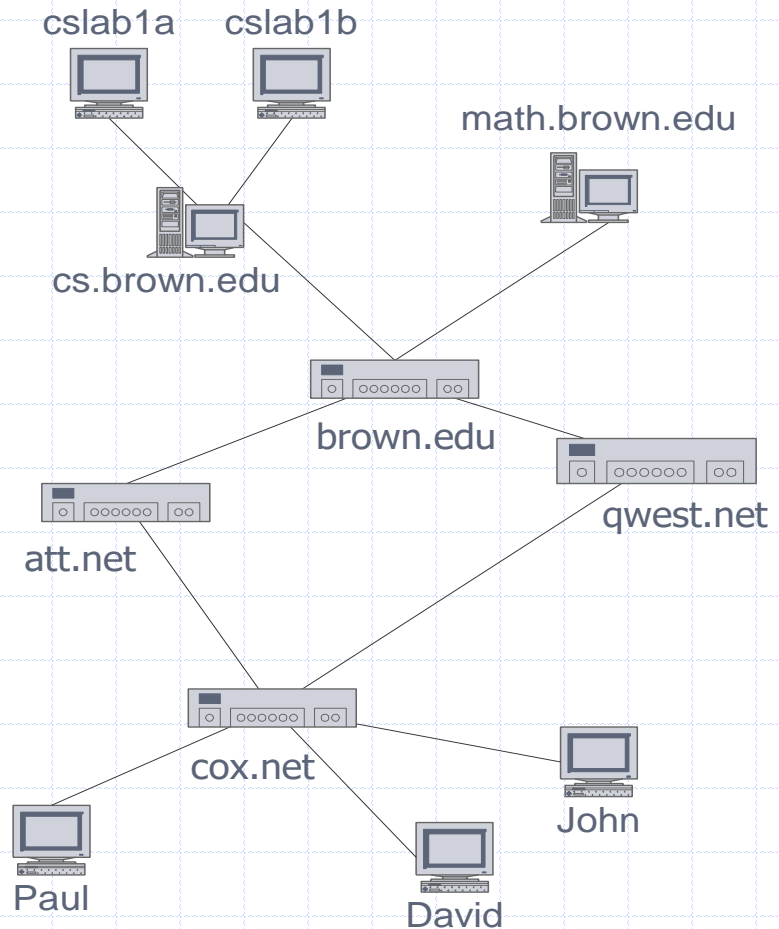
*nonsimple graph
with multiple edges*



*nonsimple graph
with loops*

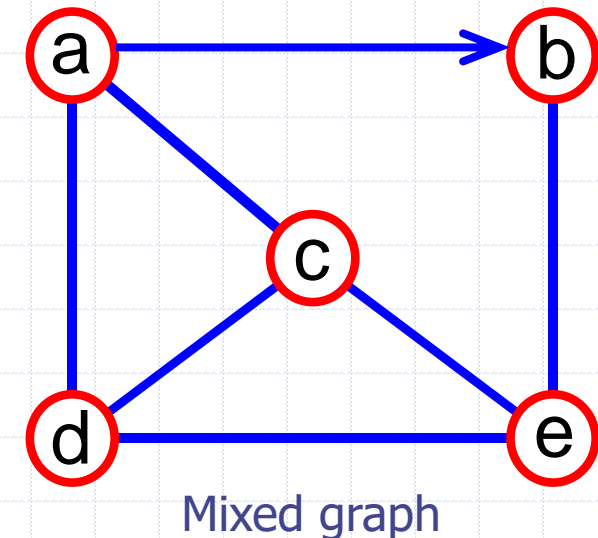
Applications

- ◆ Electronic circuits
 - Printed circuit board
 - Integrated circuit
- ◆ Transportation networks
 - Highway network
 - Flight network
- ◆ Computer networks
 - Local area network
 - Internet
 - Web
- ◆ Databases
 - Entity-relationship diagram



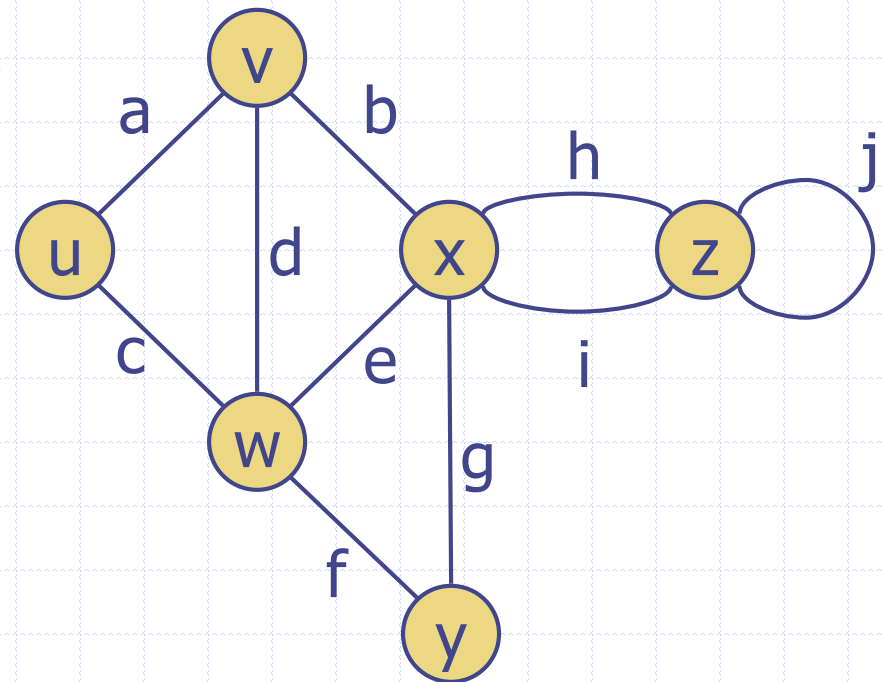
Edge and Graph Types

- ◆ Directed edge
 - ordered pair of vertices (u,v)
 - first vertex u is the origin
 - second vertex v is the destination
- ◆ Undirected edge
 - unordered pair of vertices (u,v)
- ◆ Directed graph (Digraph)
 - all the edges are directed
 - e.g., route network
- ◆ Undirected graph
 - all the edges are undirected
 - e.g., flight network
- ◆ Mixed graph
 - some edges are undirected and some edges are directed
 - e.g., a graph modeling a city map



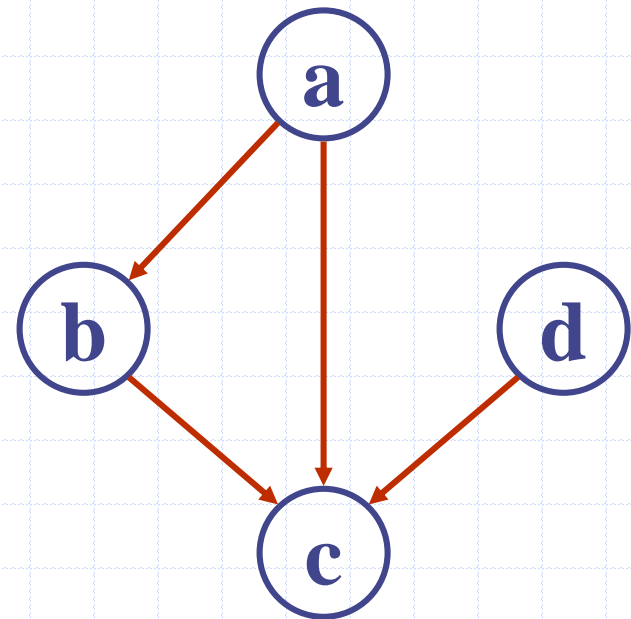
Terminology

- ◆ End vertices (or endpoints) of an edge
 - u and v are the *endpoints* of a
- ◆ Edges incident to a vertex
 - a, d, and b are *incident* to v
- ◆ Adjacent vertices
 - u and v are *adjacent*
- ◆ Degree of a vertex
 - x has *degree* 5
- ◆ Parallel edges
 - h and i are *parallel edges*
- ◆ Self-loop
 - j is a *self-loop*



Terminology (cont.)

- ◆ Outgoing edges of a vertex
 - (a, b) and (a, c) are outgoing edges of vertex a
- ◆ Incoming edges of a vertex
 - (b, c) , (d, c) and (a, c) are incoming edges of vertex c
- ◆ In-degree of a vertex
 - c has *in-degree* 3
 - b has *in-degree* 1
- ◆ Out-degree of a vertex
 - a has *out-degree* 2
 - b has *out-degree* 1



Terminology (cont.)

◆ Path

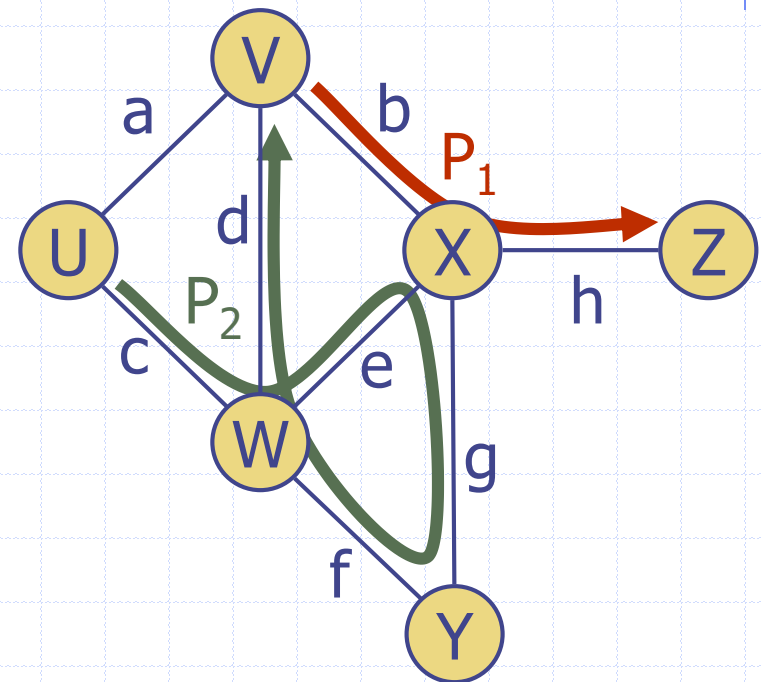
- sequence of alternating vertices and edges
- begins with a vertex
- ends with a vertex
- each edge is preceded and followed by its endpoints

◆ Simple path

- path such that all its vertices and edges are distinct

◆ Examples

- $P_1 = (V, b, X, h, Z)$ is a simple path
- $P_2 = (U, c, W, e, X, g, Y, f, W, d, V)$ is a path that is not simple



Terminology (cont.)

◆ Cycle

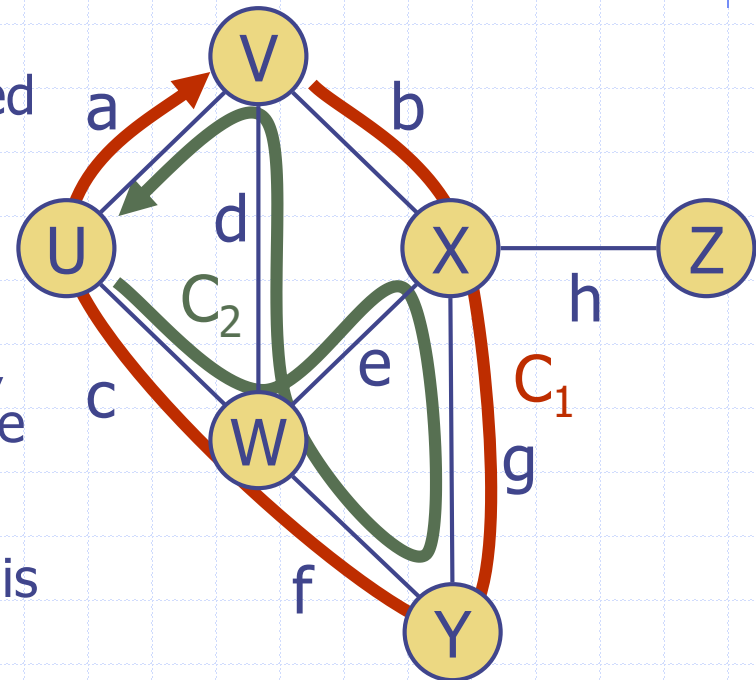
- A cycle is a path whose start and end vertices are the same
- each edge is preceded and followed by its endpoints

◆ Simple cycle

- A cycle is simple if each edge is distinct and each vertex is distinct, except for the first and the last one

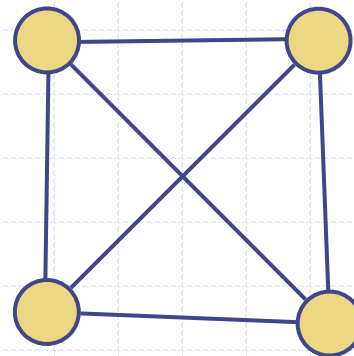
◆ Examples

- $C_1 = (V, b, X, g, Y, f, W, c, U, a, V)$ is a simple cycle
- $C_2 = (U, c, W, e, X, g, Y, f, W, d, V, a, U)$ is a cycle that is not simple



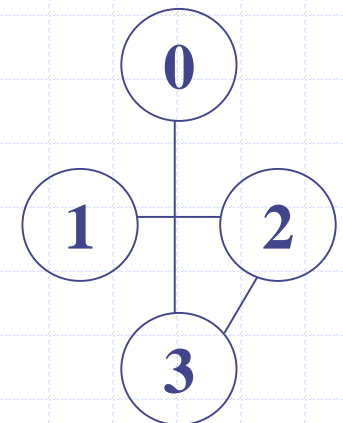
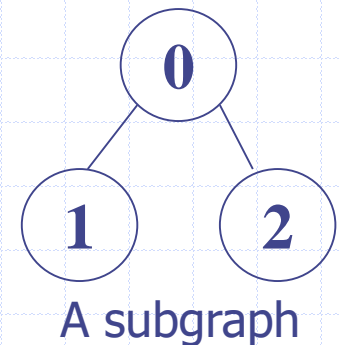
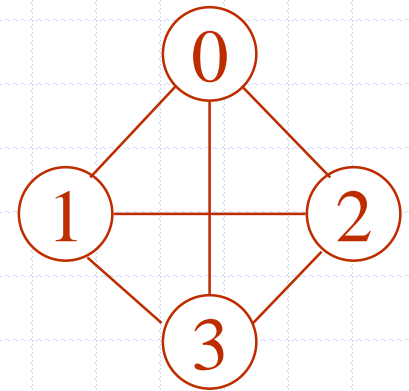
Terminology (cont.)

- ◆ *Dense* graph: $|E| \approx |V|^2$; *Sparse* graph: $|E| \approx |V|$
- ◆ A *weighted graph* associates weights with either the edges or the vertices
- ◆ A *complete graph* is a graph that has the maximum number of edges
 - for *undirected graph* with n vertices, the maximum number of edges is $n(n-1)/2$
 - for *directed graph* with n vertices, the maximum number of edges is $n(n-1)$



Terminology (cont.)

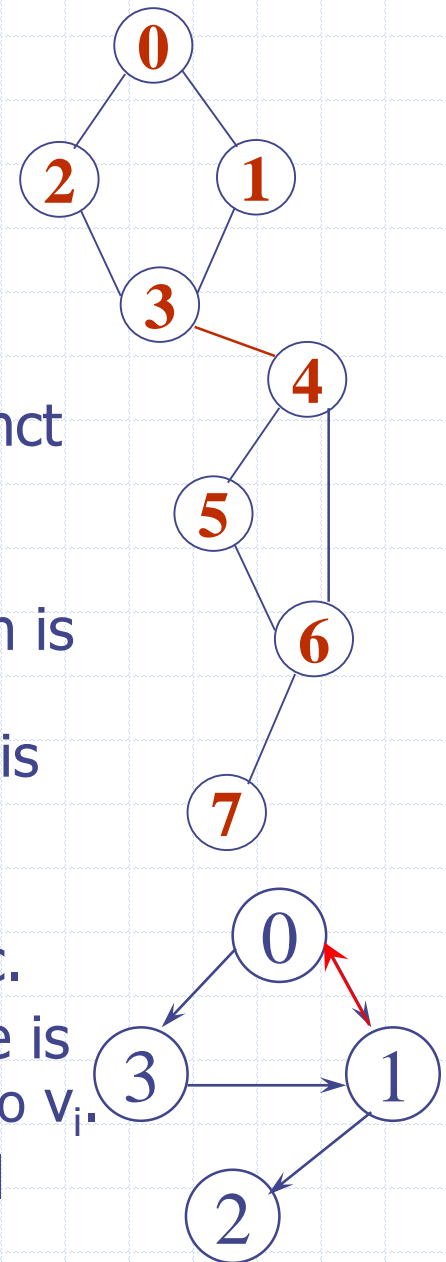
- ◆ A **subgraph** of G is a graph G' such that
 - $V(G')$ is a subset of $V(G)$ [$V(G') \subseteq V(G)$] and
 - $E(G')$ is a subset of $E(G)$ [$E(G') \subseteq E(G)$]
- ◆ A **spanning subgraph** G' of G is a subgraph of G that contains all the vertices of G , that is
 - $V(G')$ is equal to $V(G)$ [$V(G') = V(G)$] and
 - $E(G')$ is a subset of $E(G)$ [$E(G') \subseteq E(G)$]
- ◆ A **forest** is a graph without cycles.
- ◆ A **(free) tree** is a connected forest, that is, a connected graph without cycles.
- ◆ A **spanning tree** of a graph G is a spanning subgraph that is a (free) tree.



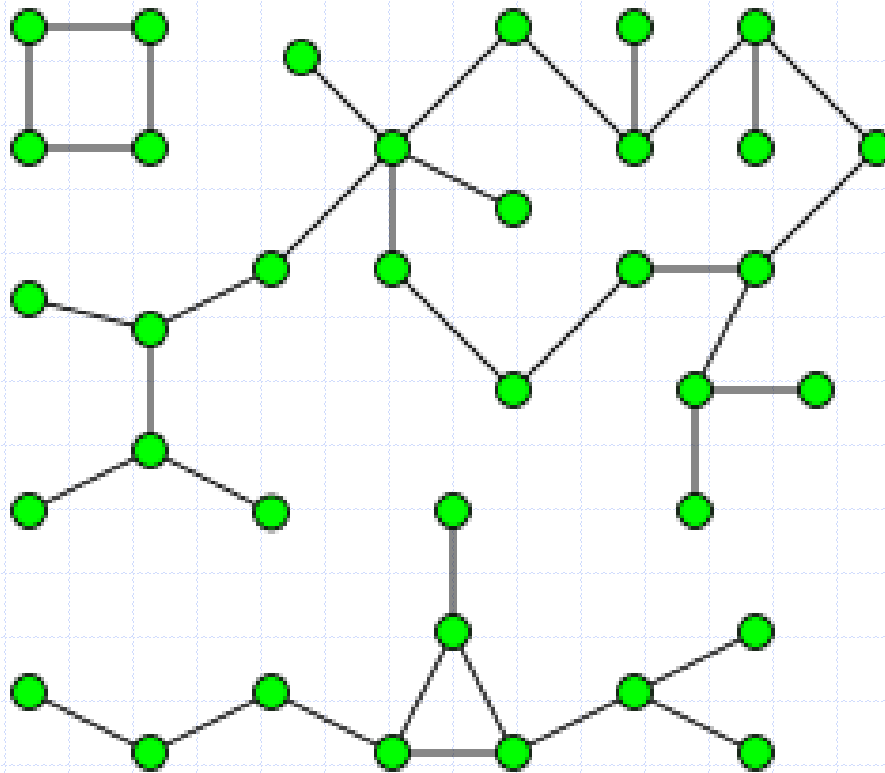
A spanning subgraph (tree)

Terminology (cont.)

- ◆ In a graph G , two vertices, v_0 and v_1 , are **connected** if there is a path in G from v_0 to v_1
- ◆ A graph is **connected** if, for every pair of distinct vertices v_i and v_j , there is a path from v_i to v_j
- ◆ A component (sometimes referred to as connected component) of an undirected graph is a subgraph in which any two vertices are connected to each other by paths, and which is connected to no additional vertices in the supergraph.
- ◆ A **tree** is a graph that is connected and acyclic.
- ◆ A directed graph is **strongly connected** if there is a directed path from v_i to v_j and also from v_j to v_i .
- ◆ A **strongly connected component** is a maximal subgraph that is strongly connected.



Terminology (cont.)



A graph with three components.

What can we do with graphs?

- ◆ Find a *path* from one place to another
- ◆ Find the *shortest path* from one place to another
- ◆ Determine connectivity
- ◆ Find the “weakest link” (min cut)
 - check amount of redundancy in case of failures
- ◆ Find the amount of flow that will go through them

Properties

Property 1

For an undirected graph

$$\sum_v \deg(v) = 2m$$

Proof: each edge is counted twice

Property 2

For a directed graph

$$\sum_v \text{indeg}(v) = \sum_v \text{outdeg}(v) = m$$

Proof: each edge is counted once for in-degree and once for out-degree

Property 3

If G is a simple undirected graph, then $m \leq n(n-1)/2$, and if G is a simple directed graph, then $m \leq n(n-1)$.

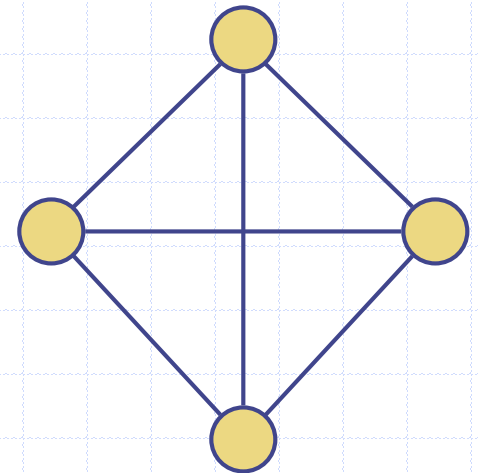
Proof: each vertex has degree at most $(n-1)$. Then use Property 1 and Property 2.

Notation

n number of vertices

m number of edges

$\deg(v)$ degree of vertex v



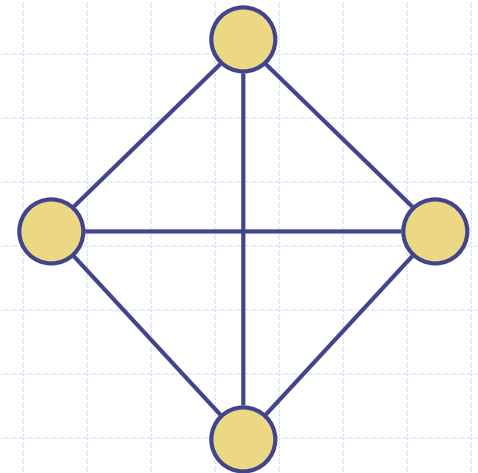
Properties

Property 4

Let G be an undirected graph with n vertices and m edges. Then we have the following:

- If G is connected, then $m \geq n - 1$,
- If G is a tree, then $m = n - 1$,
- If G is a forest, then $m \leq n - 1$.

Proof: Let G be a connected graph. Delete edges one by one from G keeping G connected. At last there will remain $n - 1$ edges.

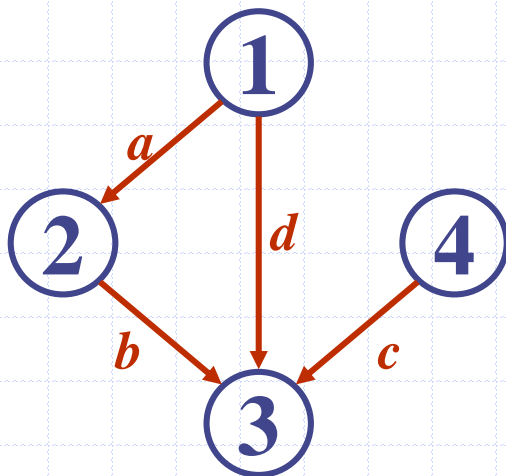


Graph Representation

- ◆ For graphs to be computationally useful, they have to be conveniently represented in programs
- ◆ There are two computer representations of graphs:
 - Adjacency matrix representation
 - Adjacency lists representation

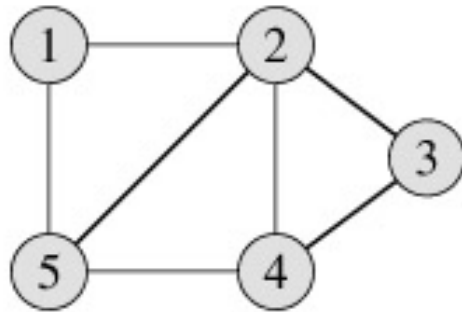
Adjacency Matrix Representation

- ◆ Assume $V = \{1, 2, \dots, n\}$
- ◆ An *adjacency matrix* represents the graph as a $n \times n$ matrix A :
 - $A[i, j] = 1$ if edge $(i, j) \in E$ (or weight of edge)
= 0 if edge $(i, j) \notin E$



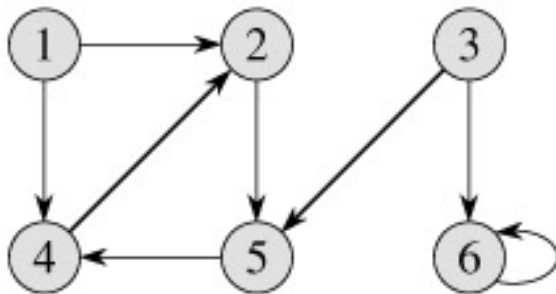
A	1	2	3	4
1	0	1	1	0
2	0	0	1	0
3	0	0	0	0
4	0	0	1	0

Adjacency Matrix Representation



Undirected Graph

	1	2	3	4	5
1	0	1	0	0	1
2	1	0	1	1	1
3	0	1	0	1	0
4	0	1	1	0	1
5	1	1	0	1	0



Directed Graph

	1	2	3	4	5	6
1	0	1	0	1	0	0
2	0	0	0	0	1	0
3	0	0	0	0	1	1
4	0	1	0	0	0	0
5	0	0	0	1	0	0
6	0	0	0	0	0	1

The adjacency matrix for an undirected graph is symmetric; the adjacency matrix for a digraph need not be symmetric

Adjacency Matrix Representation

◆ Pros:

- Simple to implement
- Easy and fast to tell if a pair (i, j) is an edge: simply check if $A[i, j]$ is 1 or 0
- Can be very efficient for small graphs

◆ Cons:

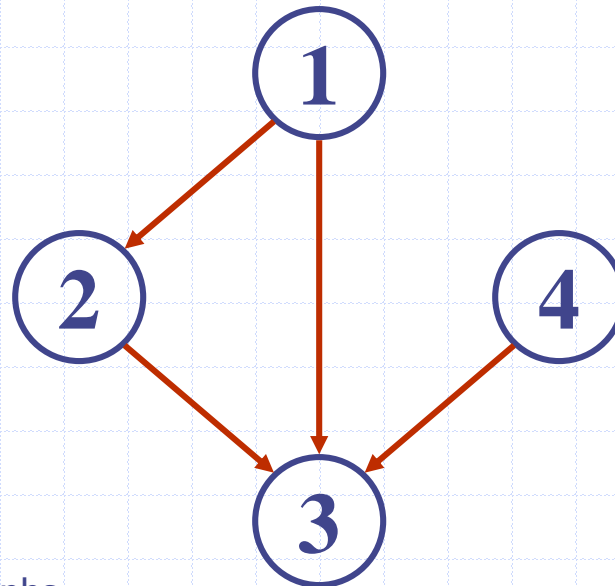
- No matter how few edges the graph has, the matrix takes $O(n^2)$ in memory

Adjacency Lists Representation

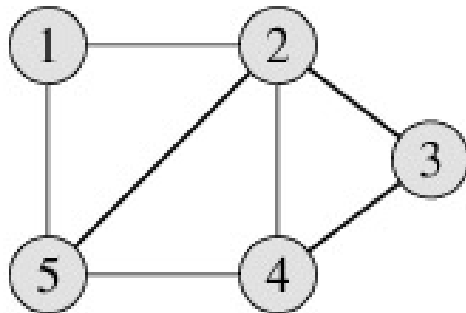
- ◆ A graph is represented by a one-dimensional array L of linked lists, where
 - $L[i]$ is the linked list containing all the nodes adjacent to node i .
 - The nodes in the list $L[i]$ are in no particular order

- ◆ Example:

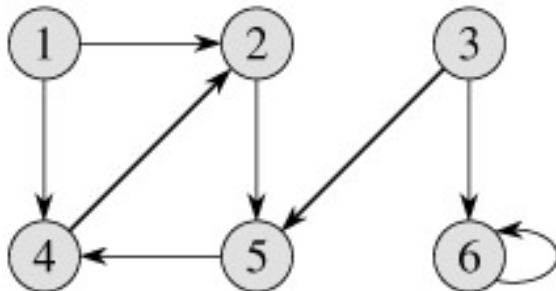
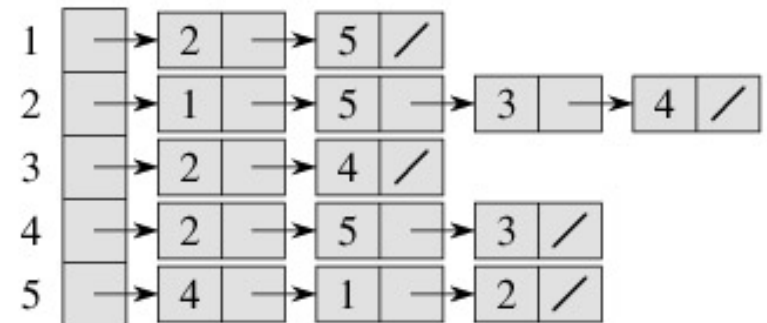
- $\text{Adj}[1] = \{2,3\}$
- $\text{Adj}[2] = \{3\}$
- $\text{Adj}[3] = \{\}$
- $\text{Adj}[4] = \{3\}$



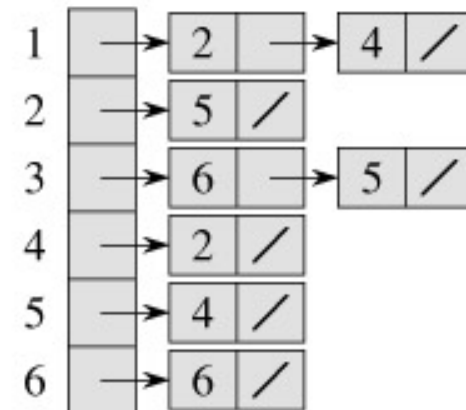
Adjacency Lists Representation



Undirected Graph



Directed Graph



Adjacency Lists Representation

◆ Pros:

- Saves on space (memory): the representation takes $O(|V| + |E|)$ memory.
- Good for large, sparse graphs (e.g., planar maps)

◆ Cons:

- It can take up to $O(n)$ time to determine if a pair of nodes (i, j) is an edge: one would have to search the linked list $L[i]$, which takes time proportional to the length of $L[i]$.

Graph ADT members?

Graph ADT members?

◆ Variables

- `int V;`
- `LinkedList * E;`
- `bool directed;`

◆ Common Methods:

- `AddEdge(u, v);`
- `RemoveEdge(u, v);`
- `isEdge(u, v);`
- `getAdjacentNodes(u);`