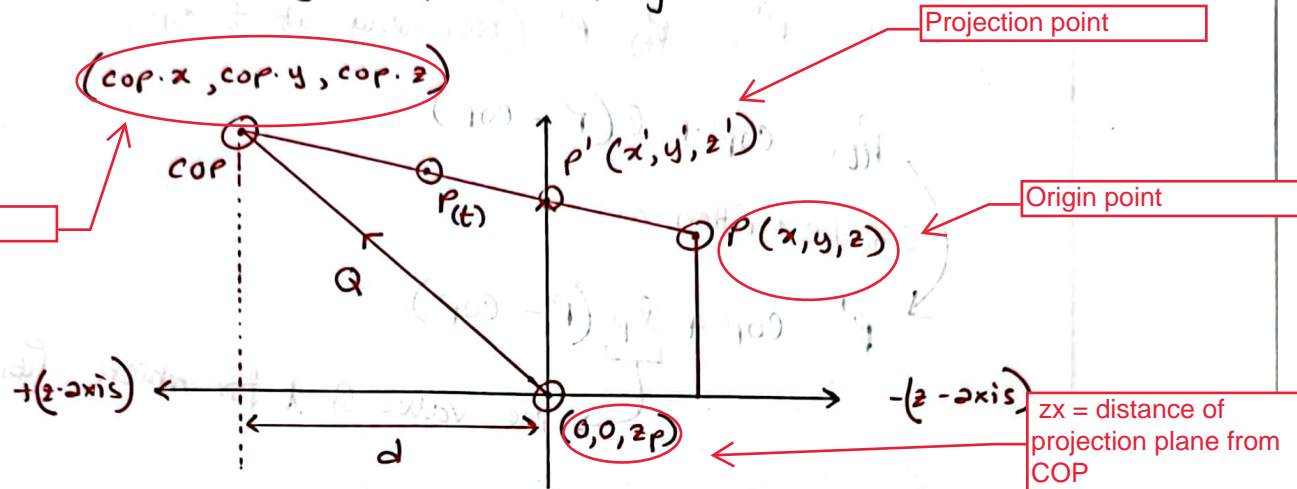


### 3) Derivation of a general purpose projection matrix:



Representing the line that goes from the bottom of the projection plane to the COP as a vector  $Q$ .

$$Q := (Q_{dx}, Q_{dy}, Q_{dz})$$

We can say,

$$Q = \text{COP} - (0, 0, z_p) \quad \text{--- (i)}$$

$$\therefore Q = (\text{cop.x}, \text{cop.y}, \text{cop.z}) - (0, 0, z_p)$$

So,

$$(1) \quad Q_{dx} = \text{cop.x}$$

$$(2) \quad Q_{dy} = \text{cop.y}$$

$$(3) \quad Q_{dz} = \text{cop.z} - z_p$$

OR

$$\text{cop.x} = Q_{dx}$$

$$\text{cop.y} = Q_{dy}$$

$$\text{cop.z} = z_p + Q_{dz} \quad \text{--- (ii)}$$

Suppose  $P$  to COP, a parametric line

→ then  $P(t)$  is any point on the line.

$$\therefore P(t) = \text{COP} + t(P - \text{COP}) \quad \text{--- (iii)}$$

can be written the other way around as well.

$$P(t) = P + t(\text{COP} - P) \rightarrow \text{if } P \text{ is considered the starting point.}$$

∅ We can assume that for a certain value of  $t$ ,  $P_t$  will be equal to  $P'$ ,  $P_t = P'$  (assuming at  $t = t_p$ )

$$P_t = \text{cop} + t(P - \text{cop})$$

can be written as

$$P' = \text{cop} + t_p(P - \text{cop})$$

the value of  $t$  for which  $P_t = P'$

So,

$$P' = \text{cop} + t_p(P - \text{cop}) \quad \text{--- (iii)}$$

∅ substituting in the (ii) equation.

$$x' = \text{cop} \cdot x + t_p(x - \text{cop} \cdot x)$$

we know,  $\text{cop} \cdot x = Qdx$

$$(1) \quad x' = Qdx + t_p(x - Qdx)$$

$$(2) \quad y' = Qdy + t_p(y - Qdy)$$

$$(3) \quad z' = Qdz + z_p + t_p(z - Qdz - z_p)$$

∅ we'll be getting an eqn for  $t_p$  from  $z'$  and substitute it in  $x'$  &  $y'$

$$\Rightarrow t_p = \frac{z' - Qdz - z_p}{z - Qdz - z_p}$$

We know,  $z' = z_p \rightarrow$  From the diagram, as  $z'$  is on one projection plane, it equals  $z_p$ .

$$l_p = \frac{z' - Q_{dz} - z_p}{z - Q_{dz} - z_p}$$

$$= \frac{-Q_{dz}}{z - Q_{dz} - z_p} \quad \leftarrow \text{bring the numerator below}$$

$$= \frac{1}{-\frac{z}{Q_{dz}} + 1 + \frac{z_p}{Q_{dz}}} \quad \text{--- (V) ---}$$

$$\text{(iv)} \rightarrow \left\{ \frac{s/b}{s/b} \cdot s + \frac{s/b}{s/b} \cdot s - s \right\}$$

$$\text{--- (V) ---} \quad \text{P.T.O.} \rightarrow \left\{ \frac{s/b}{s/b} \cdot s + \frac{s/b}{s/b} \cdot s - s \right\}$$

$$\text{--- (V) ---} \quad \left\{ \frac{s/b}{s/b} \cdot s + \frac{s/b}{s/b} \cdot s - s \right\}$$

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$$\text{(iv)} \rightarrow \left\{ \frac{s/b}{s/b} \cdot s + \frac{s/b}{s/b} \cdot s - s \right\}$$

$$\left\{ \frac{s/b}{s/b} \cdot s + \frac{s/b}{s/b} \cdot s - s \right\}$$

Substituting eqn (v),  $z_p$  in all of eqn (iv)

$$x'_1 = Q dx + \left( \frac{1}{-\frac{z}{Q_{d2}} + 1 + \frac{z_p}{Q_{d2}}} \right) (x - Q dx)$$

$$= \frac{Q dx}{1} + \left( \frac{x - Q dx}{-\frac{z}{Q_{d2}} + 1 + \frac{z_p}{Q_{d2}}} \right)$$

$$= \frac{\cancel{\frac{z}{Q_{d2}}} \cdot Q dx + \cancel{Q} dx + z_p \cdot \frac{Q dx}{Q_{d2}} + x - \cancel{Q} dx}{-\frac{z}{Q_{d2}} + 1 + \frac{z_p}{Q_{d2}}}$$

$$= \frac{x - z \cdot \frac{Q dx}{Q_{d2}} + z_p \cdot \frac{Q dx}{Q_{d2}}}{-\frac{z}{Q_{d2}} + 1 + \frac{z_p}{Q_{d2}}} \quad \text{--- (vi)}$$

$$y' = \frac{y - z \cdot \frac{Q dy}{Q_{d2}} + z_p \cdot \frac{Q dy}{Q_{d2}}}{-\frac{z}{Q_{d2}} + 1 + \frac{z_p}{Q_{d2}}} \quad \text{--- (vii)}$$

$$z' = z_p$$

$$= z_p \left( \frac{-\frac{z}{Q_{d2}} + 1 + \frac{z_p}{Q_{d2}}}{-\frac{z}{Q_{d2}} + 1 + \frac{z_p}{Q_{d2}}} \right)$$

$$= \frac{-z \cdot \frac{z_p}{Q_{d2}} + z_p \left( 1 + \frac{z_p}{Q_{d2}} \right)}{-\frac{z}{Q_{d2}} + 1 + \frac{z_p}{Q_{d2}}} \quad \text{--- (viii)}$$

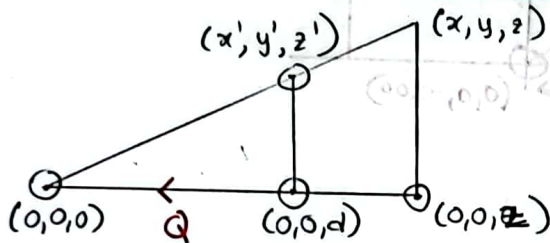
Keeping the denominator same, so that it is easier to represent in a matrix.



Ø The Matrix:

$$\begin{bmatrix} x' \\ y' \\ z' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & -\frac{Qdx}{Qdz} \\ 0 & 1 & 0 & -\frac{Qdy}{Qdz} \\ 0 & 0 & 1 & -\frac{z_p}{Qdz} \\ 0 & 0 & 0 & 1 + \frac{z_p}{Qdz} \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

Ø Derivation of origin at COP (from general matrix)



$$Qdx = 0$$

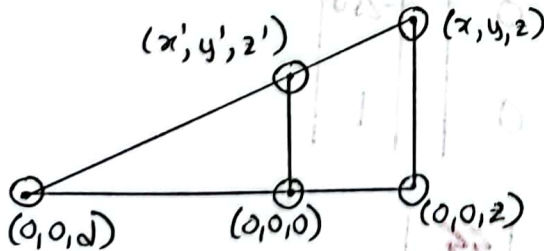
$$Qdy = 0$$

$$Qdz = -d$$

$$z_p = d$$

$$= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1/d & 0 \end{bmatrix}$$

Ø Derivation of origin at PP (from general matrix)



$$Qdx = 0$$

$$Qdy = 0$$

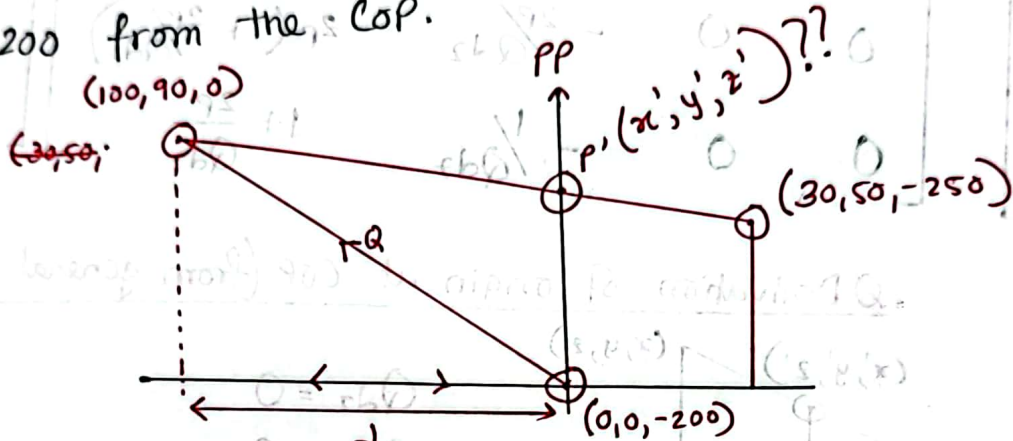
$$Qdz = d$$

$$z_p = 0$$

$$= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & -1/d & 1 \end{bmatrix}$$

Q) Calculate the projected point coordinates for a point  $(30, 50, -250)$ , where COP is at  $(100, 90, 0)$  and the projecting plane is at a distance of 200 from the COP.

Ans:



So,

$$Qdx = 100$$

$$Qdy = 90$$

$$Qdz = 200$$

$$z_p = -200$$

$$\begin{vmatrix} x' \\ y' \\ z' \\ 1 \end{vmatrix} = \begin{vmatrix} 1 & 0 & -1/2 & -100 \\ 0 & 1 & -9/20 & -90 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1/200 & 0 \end{vmatrix} \begin{vmatrix} 30 \\ 50 \\ -250 \\ 1 \end{vmatrix}$$

$$= \begin{vmatrix} 30 + 125 & -100 \\ 50 + 112.5 & -90 \\ -250 & 5/4 \end{vmatrix} = \begin{vmatrix} 44 \\ 58 \\ -200 \end{vmatrix}$$

try to keep fractions to decrease the error.

$$\therefore P' = (44, 58, -200)$$

Ans//