



Elmore Family School of Electrical
and Computer Engineering

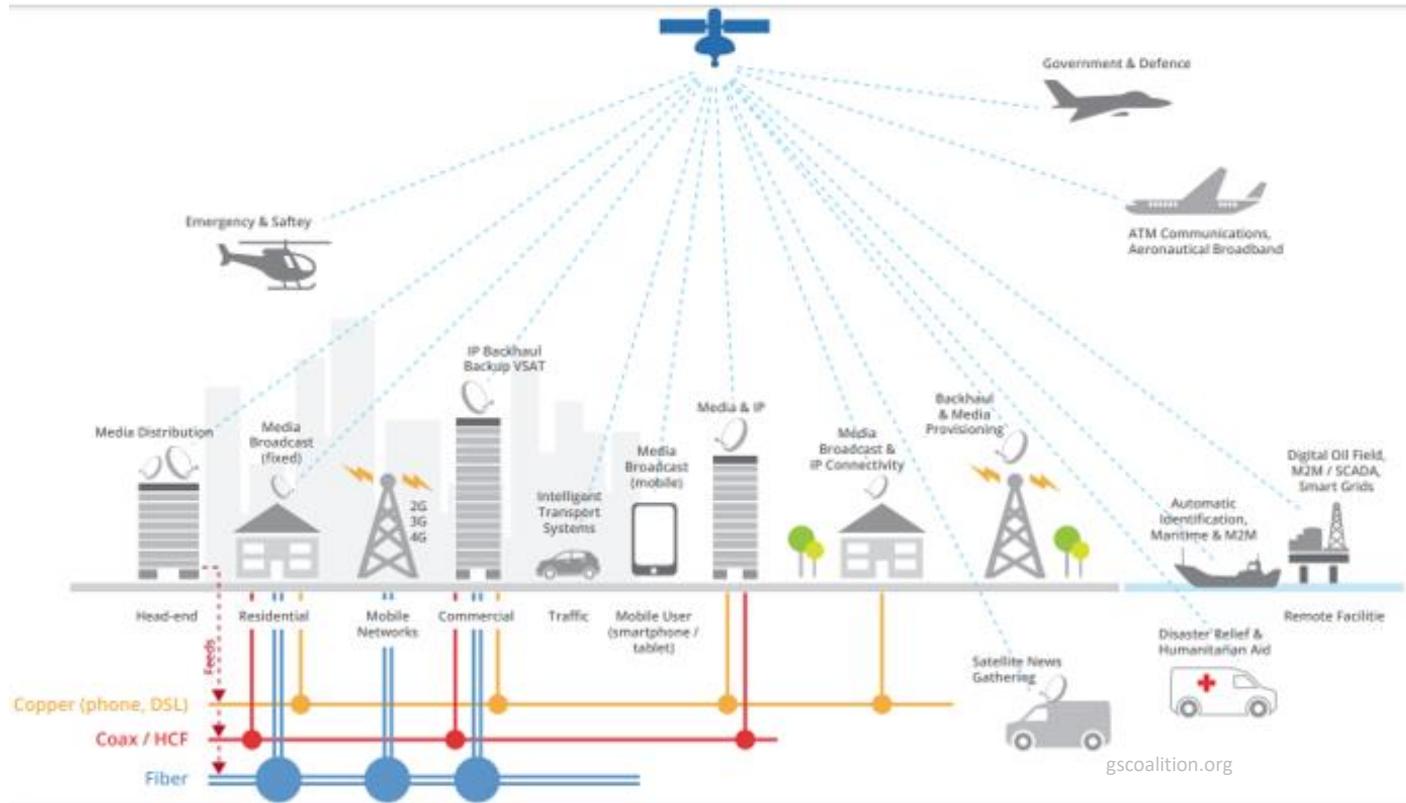
Structured and Resource-Constrained Collaborative Learning

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ML Seminar, Purdue University

September 22, 2021

The Era of Collaborative Systems



Satellite mesh network

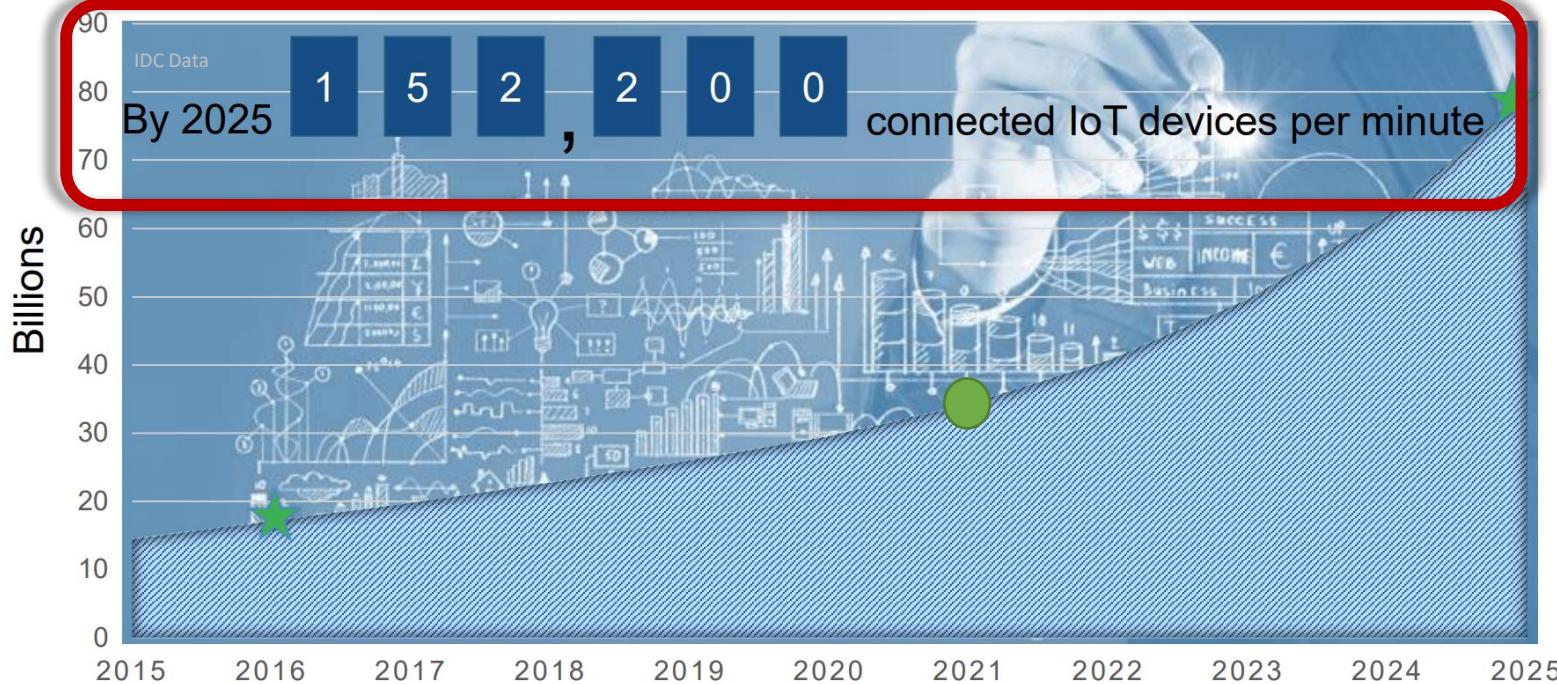


Smart grids



Creating reliable and effective collaborative systems that are highly secure, robust and economically viable

Collaborative Systems: Large-Scale and Heterogenous

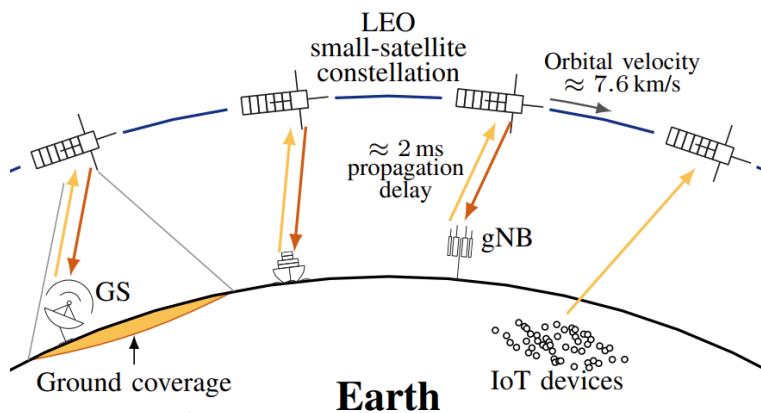
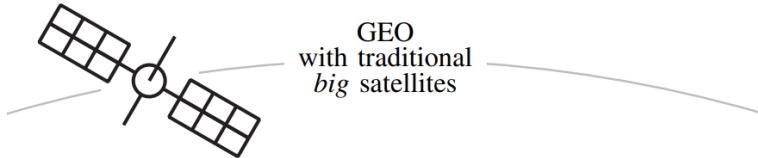


Rapidly increasing network size

High degree of heterogeneity

How can we enable **scalable** deployment of collaborative learning in **presence of heterogeneity**?

Collaborative Systems: Embodied Agents

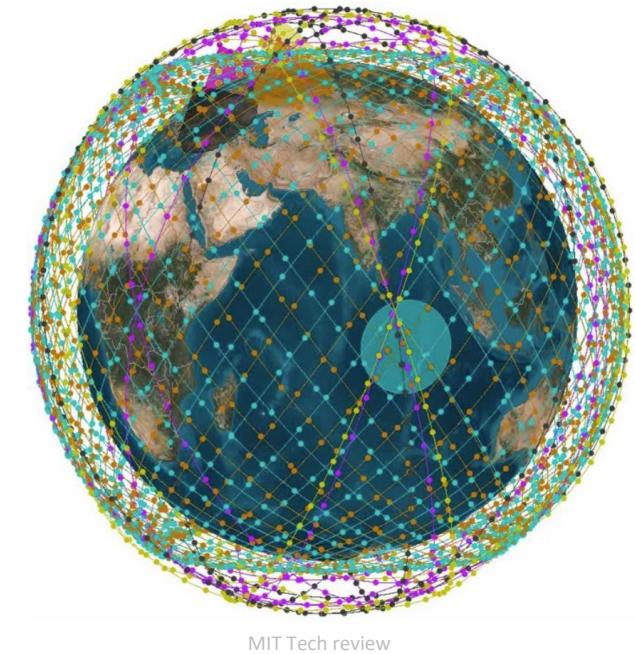


Rapidly evolving environments

Limited energy budgets

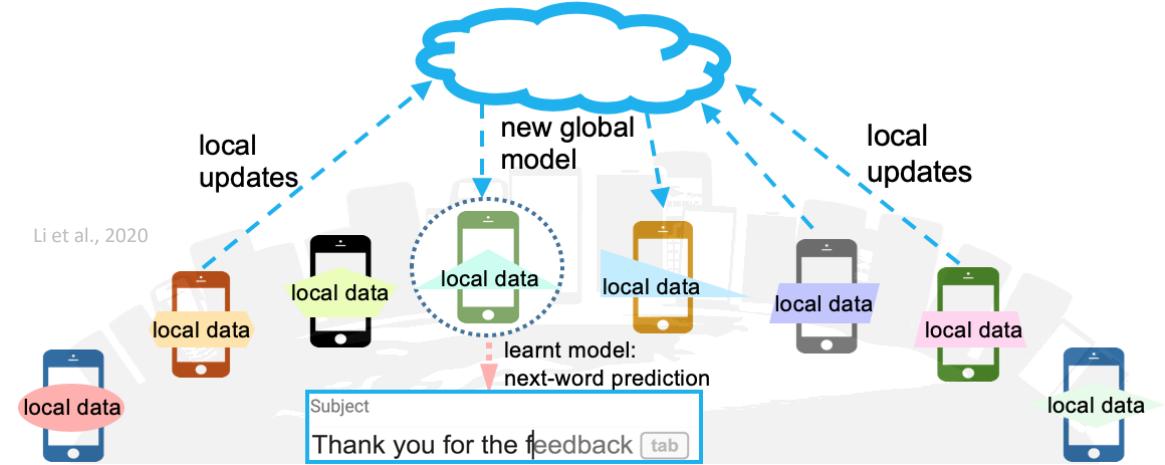
Costly observation gathering

4000+ LEO satellites in SpaceX network



How can we design **low-cost and energy-efficient** collaborative learning systems capable of operating in **rapidly evolving environments**?

Collaborative Systems: Limited Communication Budget

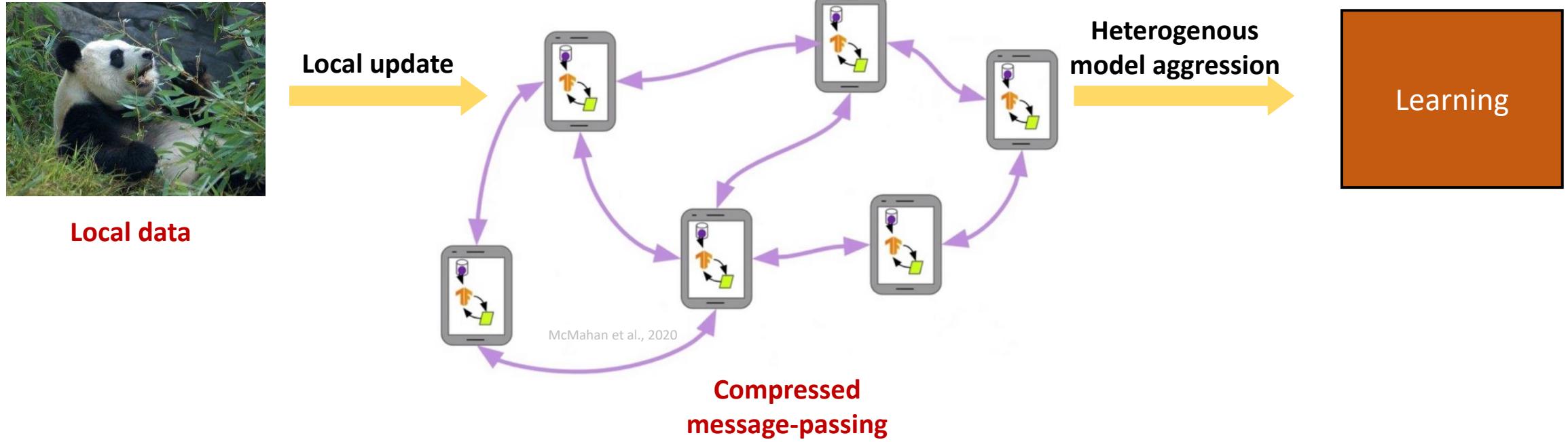


Unreliable communication

Limited bandwidth

How can we design **robust and communication-efficient collaborative learning systems?**

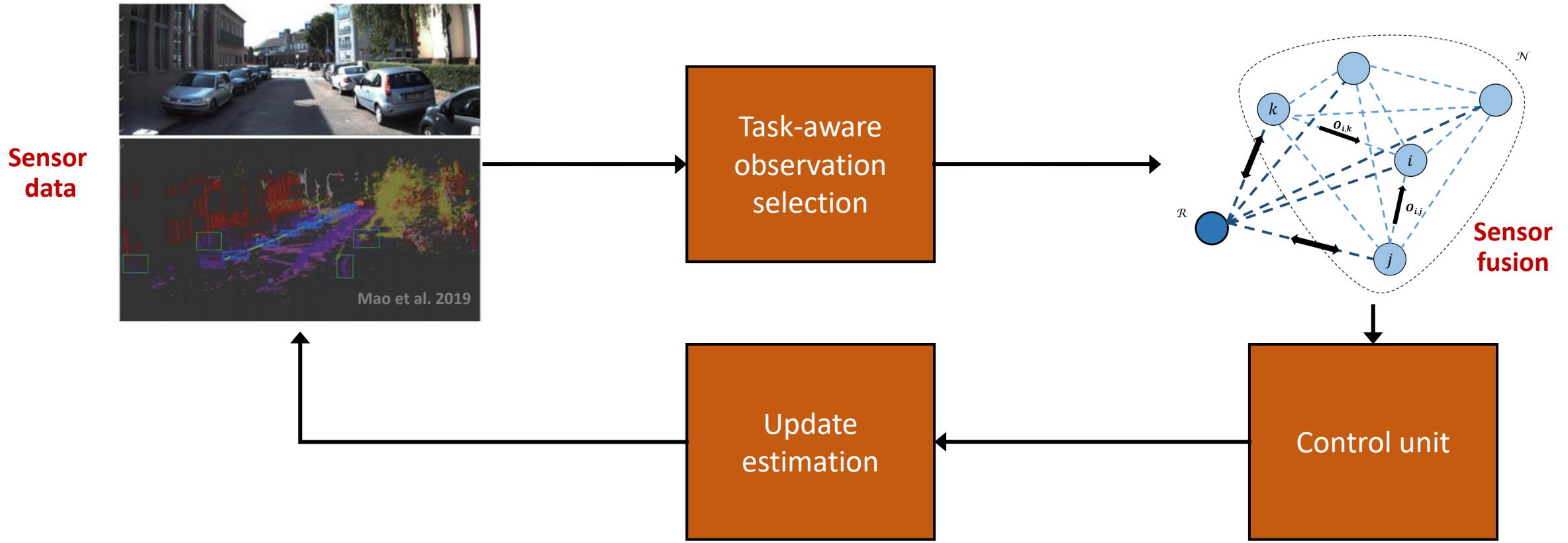
Communication-Efficient Federated and Distributed Learning



Contributions:

- Model aggregation and communication strategies for distributed learning
- Developing communication-efficient algorithms with provable guarantees

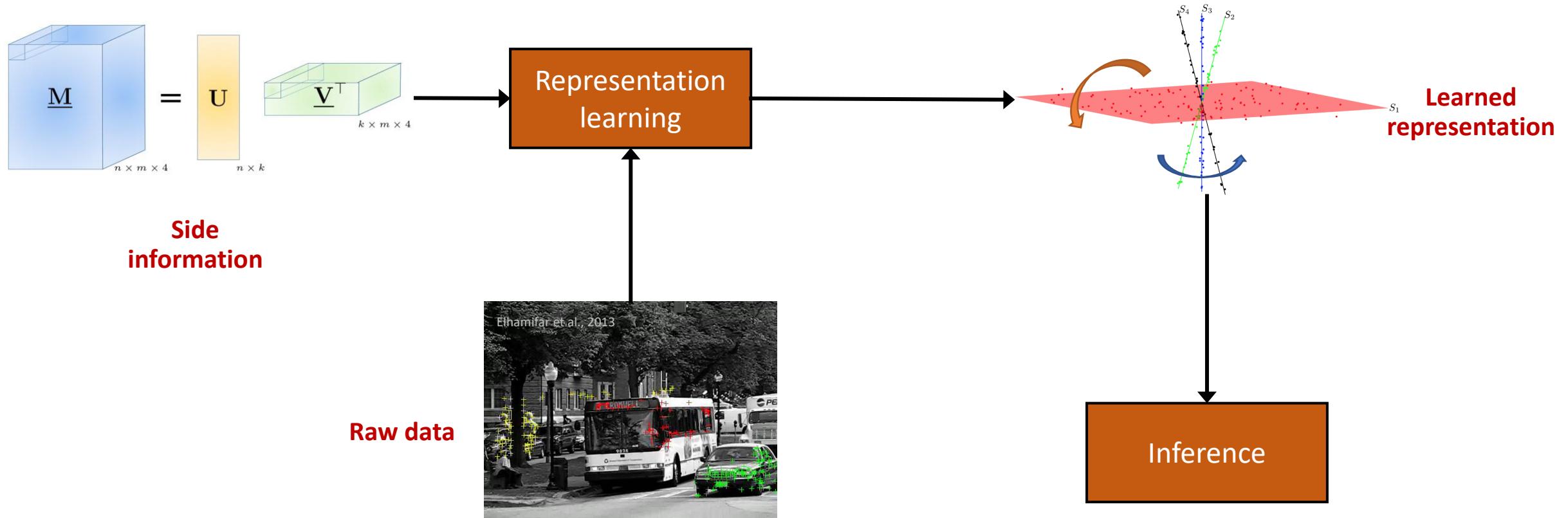
Efficient Observation Selection and Information Gathering



Contributions:

- Task-aware **observation selection criteria** for sensing networks
- Developing efficient feature selection algorithms with **near-optimal utilities**

Data-Scarce Parsimonious Representation Learning



Contributions:

- Representation learning for unsupervised inference from **structured data**
- **Sparse approximation algorithms** for function approximation and regression

Communication-Efficient Federated and Distributed Learning



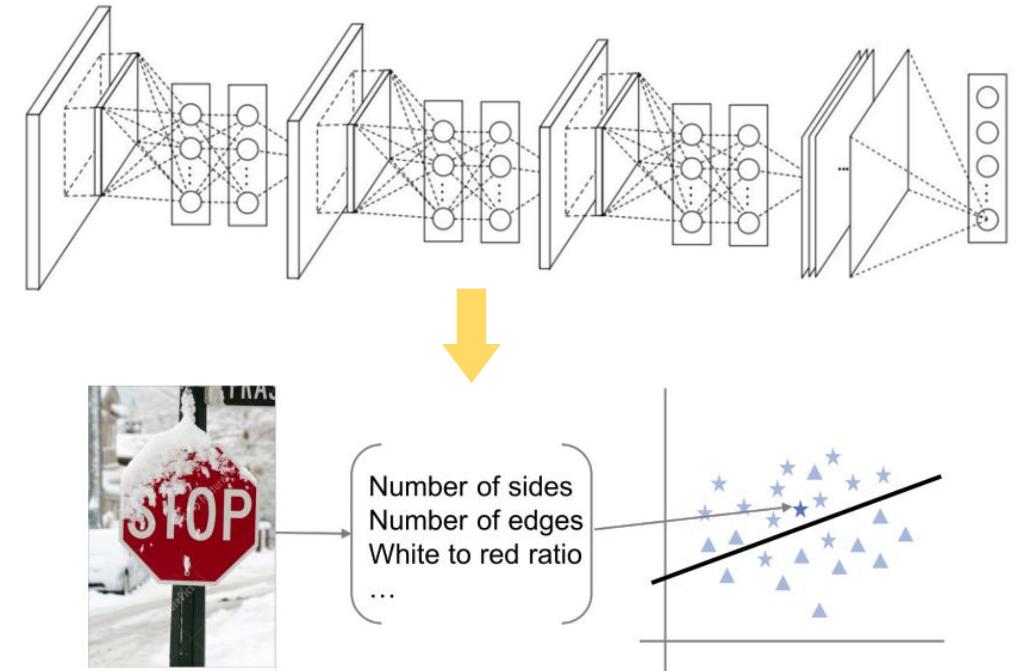
[Das, R., Hashemi, A., Acharya, A., Sanghavi, S., Dhillon, I., Topcu, U., “Faster Non-Convex Federated Learning via Global and Local Momentum,” Submitted, 2021.]

[Chen, Y., Hashemi, A., Vikalo, H., “Communication-Efficient Variance-Reduced Decentralized Stochastic Optimization over Time-Varying Directed Graphs,” Submitted, 2021.]

[Hashemi, A., Acharya, A., Das, R., Vikalo, H., Sanghavi, S., Dhillon, I., “On the Benefits of Multiple Gossip Steps in Communication-Constrained Decentralized Optimization,” Submitted, 2021.]

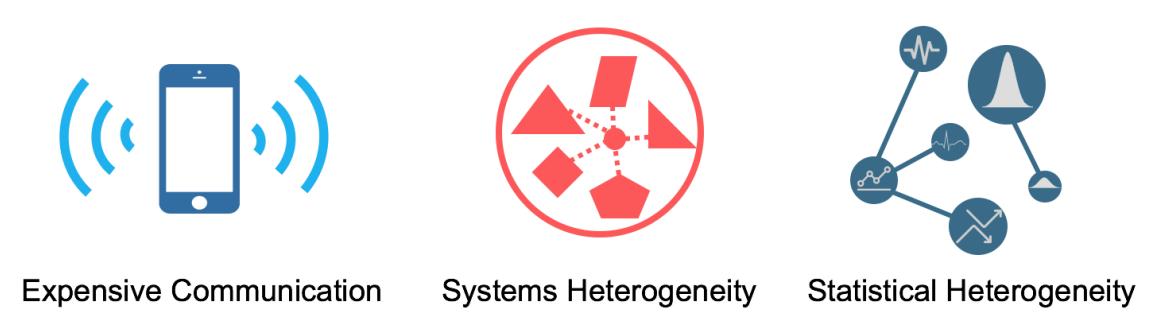
[Chen, Y., Hashemi, A., Vikalo, H., “Decentralized Optimization on Time-Varying Directed Graphs under Communication Constraints,” International Conference on Acoustic, Speech and Signal Processing (ICASSP), 2021.]

Collaborative Learning in Connected Systems



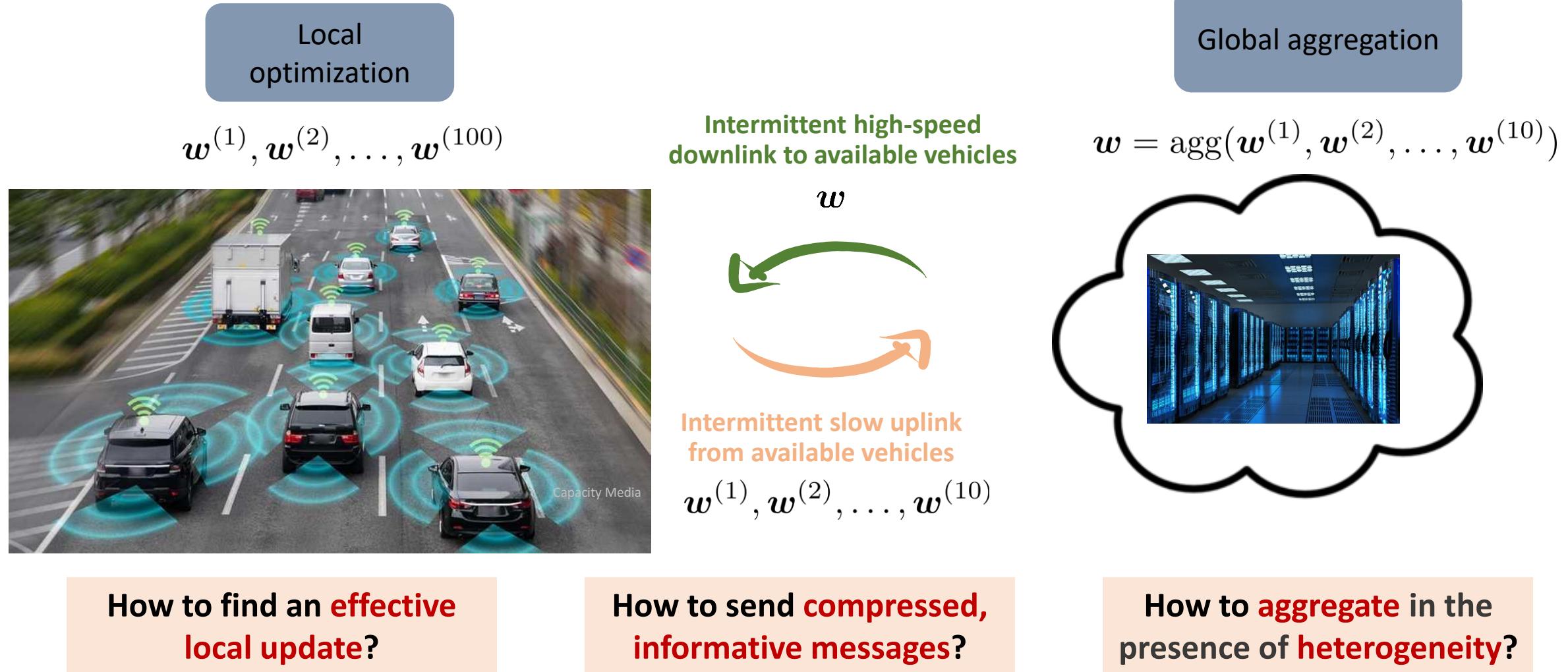
Limited local data

Collaboration via cloud

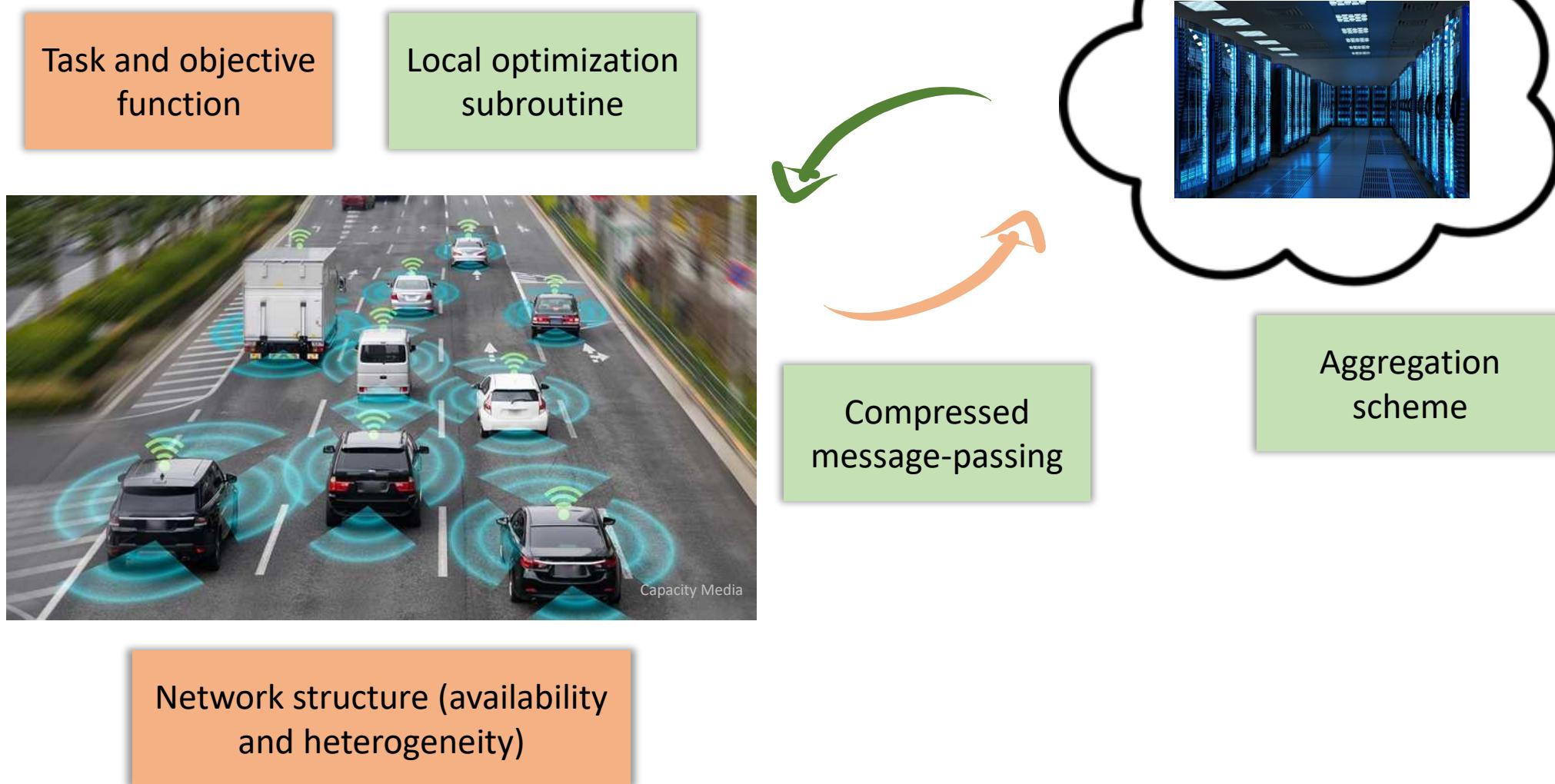


Li et al., 2019

Communication-Efficient Federated Learning



Components of the Problem



Task and Objective Function

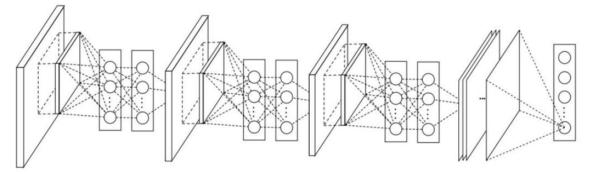
Empirical Risk Minimization (ERM)



$$\min_{\mathbf{w}} \quad f(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^n f_i(\mathbf{w}) \quad \text{where} \quad \hat{f}_i(\mathbf{w}) = \frac{1}{n_i} \sum_{j=1}^{n_i} \hat{f}_{i,j}(\mathbf{w})$$

Number of devices

Model parameters



Number data points
at device i

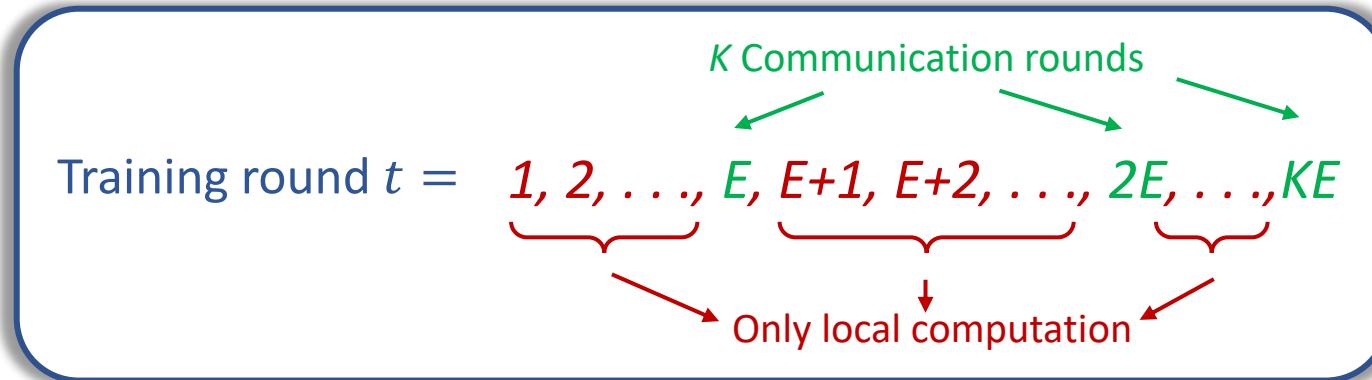
Smooth loss functions

$$\|\nabla \hat{f}_{i,j}(\mathbf{x}) - \nabla \hat{f}_{i,j}(\mathbf{y})\| \leq L \|\mathbf{x} - \mathbf{y}\|$$



Network Structure and Heterogeneity

Periodic message-passing: devices communicate with the server **intermittently**



Partial participation: only r out of n devices available each communication round ($r \ll n$)

$$\|\tilde{\nabla} f_i(\mathbf{w}; \mathcal{B}) - \nabla f_i(\mathbf{w})\| \leq \sigma_b$$

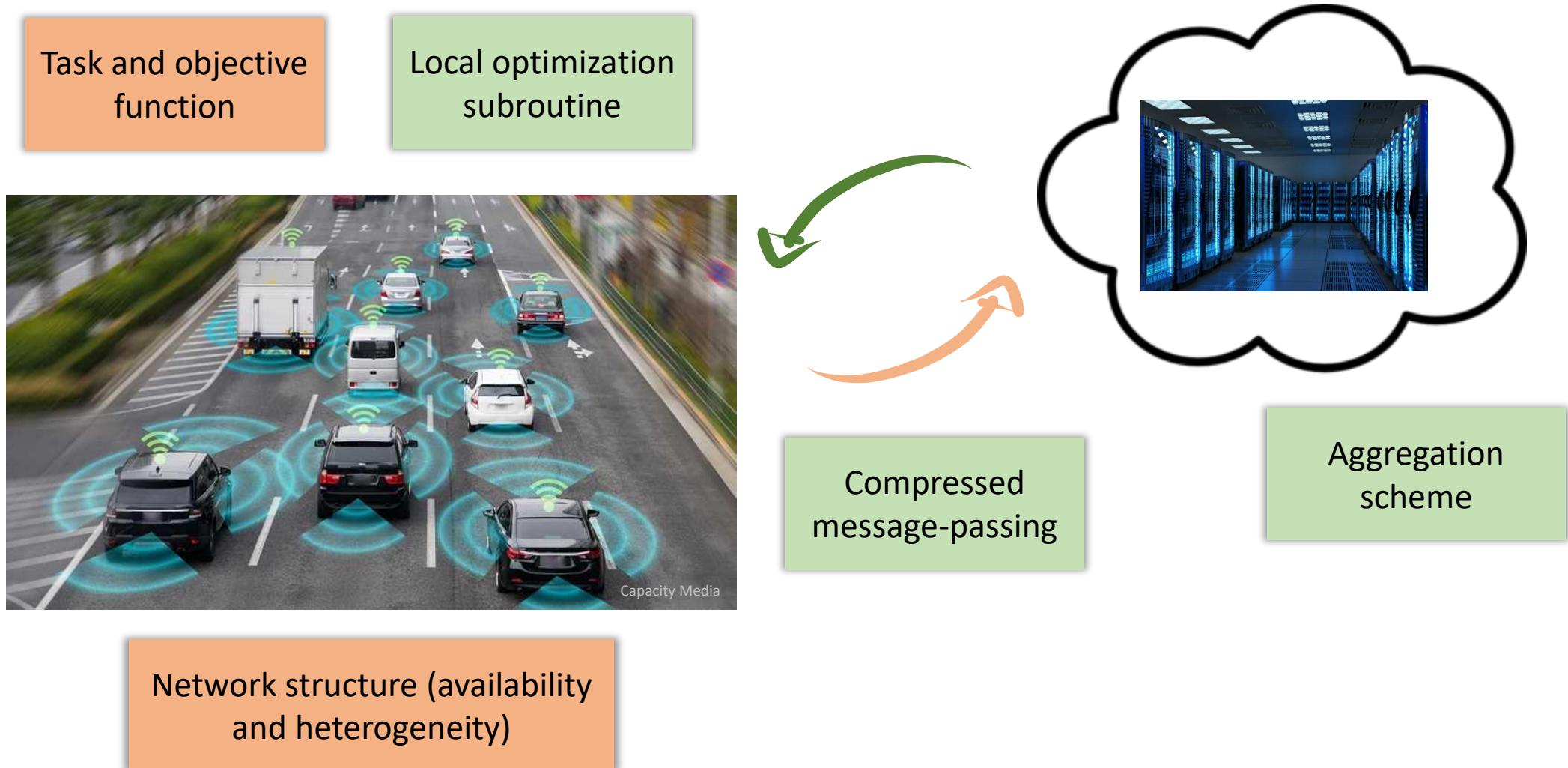
Stochastic gradient
approximation error

**Bounded
dissimilarity**

$$\|\nabla f_i(\mathbf{w}) - \nabla f(\mathbf{w})\|^2 \leq \sigma_r^2$$

Local functions Global function

Components of the Problem



Stochastic Gradient Descent (SGD)

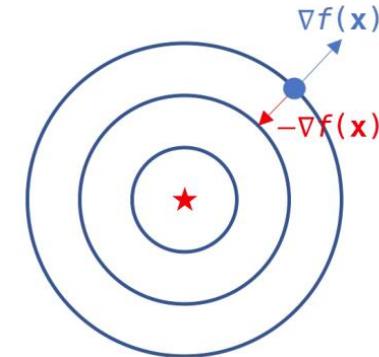
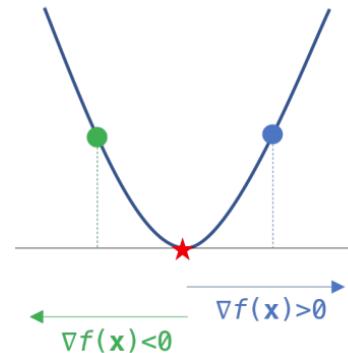
Search for a point where the gradient is small

$$\|\nabla f(\mathbf{w})\|^2 \leq \epsilon$$

Stochastic first-order update

$$\mathbf{w}_{t+1} = \mathbf{w}_t - \eta \tilde{\nabla} f_i(\mathbf{w}_t; \mathcal{B}_t)$$

Intuition: Take a step in the direction opposite to the gradient



What do we know about the performance of SGD?

Theorem (Convergence of SGD)

$$T = \mathcal{O}\left(\frac{\sigma_b^2}{\epsilon^2} + \frac{1}{\epsilon}\right)$$

Bottou 2018

Theorem (Lower bounds)

$$T = \mathcal{O}\left(\frac{1}{\epsilon^{1.5}}\right)$$

Arjevani et al. 2019

Local Momentum-Based Variance Reduction

A recursive stochastic first-order update

$$\mathbf{v}_\tau^{(i)} = \tilde{\nabla} f_i(\mathbf{w}_\tau^{(i)}; \mathcal{B}_\tau^{(i)}) + (\mathbf{v}_{\tau-1}^{(i)} - \tilde{\nabla} f_i(\mathbf{w}_{\tau-1}^{(i)}; \mathcal{B}_\tau^{(i)}))$$

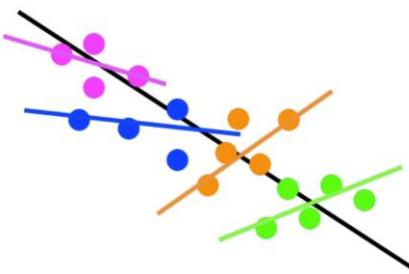
$$\mathbf{w}_{\tau+1}^{(i)} = \mathbf{w}_\tau^{(i)} - \eta \mathbf{v}_\tau^{(i)}$$

Lemma: Reduces the variance of stochastic gradient

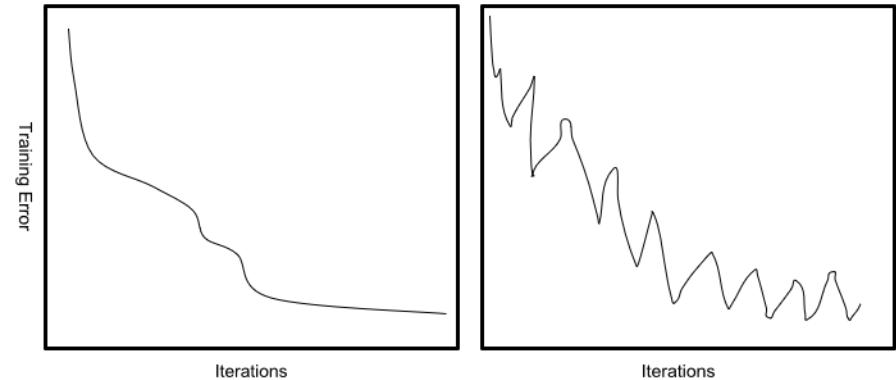
$$\sum_{\tau=0}^{E-1} \mathbb{E}[\|\mathbf{v}_\tau^{(i)} - \nabla f_i(\mathbf{w}_\tau^{(i)})\|^2] \leq O(E^2 \eta^2)$$

Hashemi et al., 2021

$$\underbrace{\|\nabla f_i(\mathbf{w}) - \nabla f(\mathbf{w})\|^2}_{\text{Local functions}} \leq \sigma_r^2$$



How about heterogeneity?



Proposed

SGD

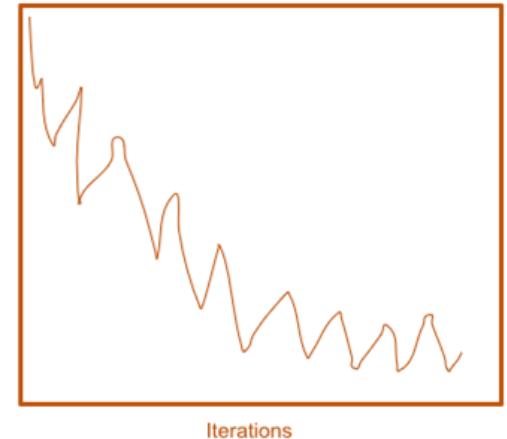
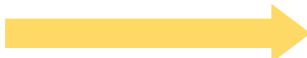
Global Momentum-Based Variance Reduction

Simple aggregation: $\mathbf{w} \leftarrow \frac{1}{r} \sum_{i \in \mathcal{S}} \mathbf{w}_E^{(i)}$

$$\mathbf{w} \leftarrow \mathbf{w} - \frac{\eta}{r} \sum_{i \in \mathcal{S}_k} \frac{\mathbf{w} - \mathbf{w}_E^{(i)}}{\eta}$$

A **generalized stochastic gradient**

Similar issue, but now
because of **heterogeneity**



**Using momentum-based variance reduction
for model parameters**

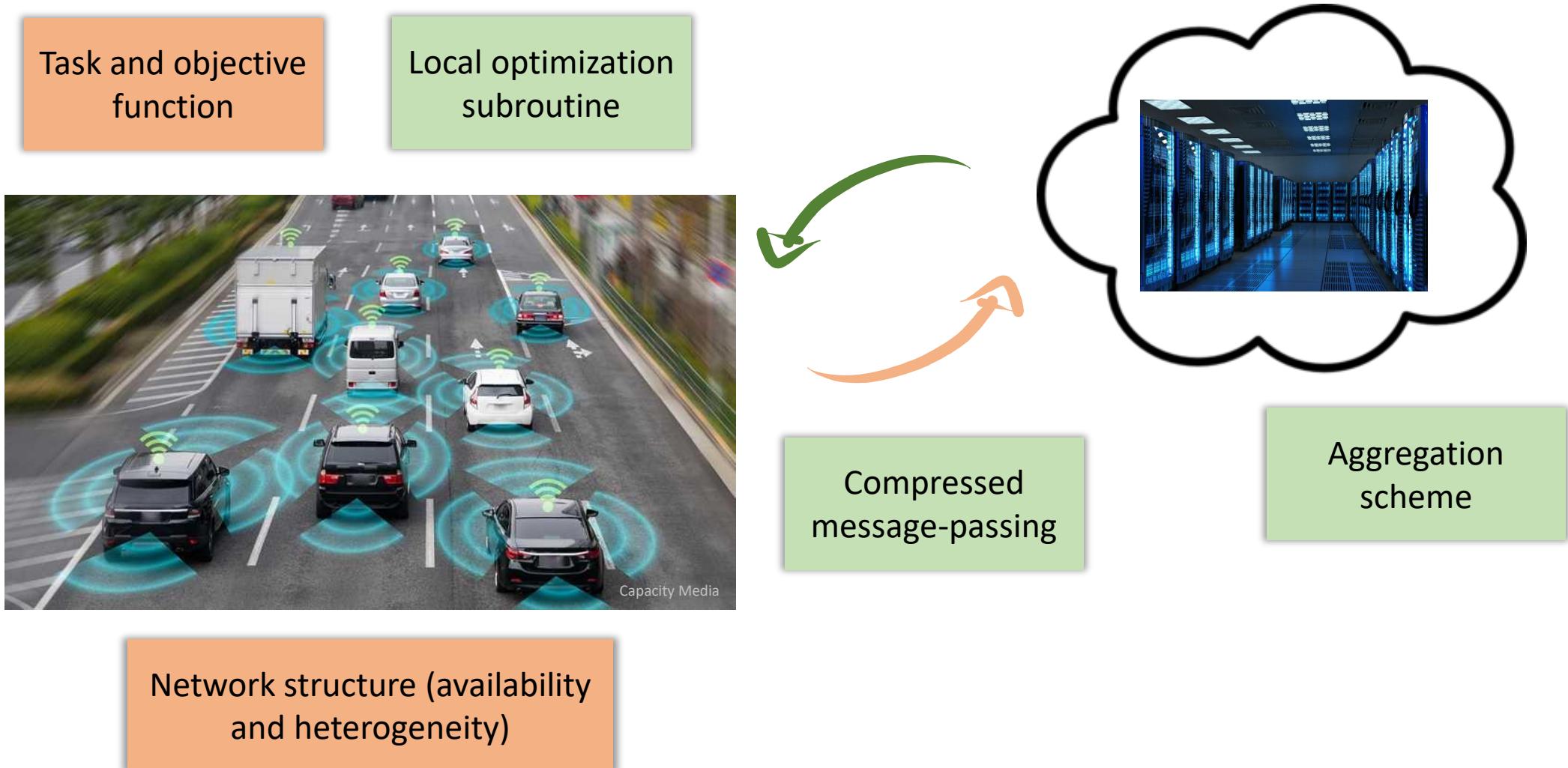
Theorem (optimal rate)

To get $\mathbb{E}\|\nabla f(\mathbf{w}_K)\|^2 \leq \epsilon$ we need

$$K = \mathcal{O}\left(\frac{1}{\epsilon^{1.5}}\right)$$

Hashemi et al., 2021

Components of the Problem

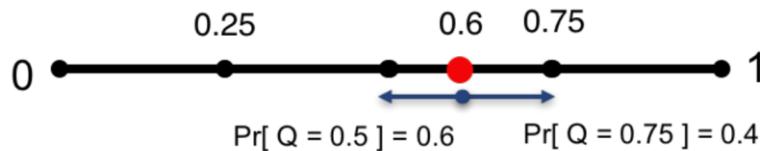


Quantized Uplink Communication

s-level Stochastic quantization

[Alistarh et al., 2017]

$$Q_D(v_i) = \|\mathbf{v}\| \cdot \text{sgn}(v_i) \cdot \xi_i(\mathbf{v}, s)$$



Unbiased with small variance

Uplink messages

Each learner sends

$$Q_D(\underbrace{\mathbf{w}_k - \mathbf{w}_{k,E}^{(i)}}_{\text{previous global model} - \text{current local model}})$$

previous global model – current local model

Local and Global Momentum-Based Variance Reduction

Local momentum-based variance reduction

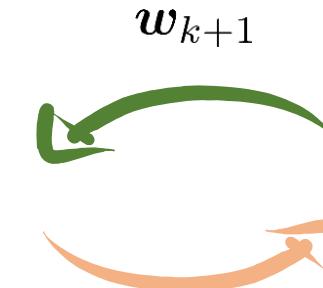
$$\boldsymbol{v}_\tau^{(i)} = \tilde{\nabla} f_i(\boldsymbol{w}_\tau^{(i)}; \mathcal{B}_\tau^{(i)}) + (\boldsymbol{v}_{\tau-1}^{(i)} - \tilde{\nabla} f_i(\boldsymbol{w}_{\tau-1}^{(i)}; \mathcal{B}_\tau^{(i)}))$$

$$\boldsymbol{w}_{\tau+1}^{(i)} = \boldsymbol{w}_t^{(i)} - \eta \boldsymbol{v}_\tau^{(i)}$$



Global momentum-based variance reduction

$$\boldsymbol{w}_{k+1} = \text{agg}(\{Q_D(\boldsymbol{w}_k - \boldsymbol{w}_{k,E}^{(i)})\})$$



Intermittent slow uplink
from available vehicles

$$Q_D(\boldsymbol{w}_k - \boldsymbol{w}_{k,E}^{(i)})$$



Collaborative Learning of Multiclass Classifiers

10 classes, 50,000 images

$n = 50$ collaborative learners

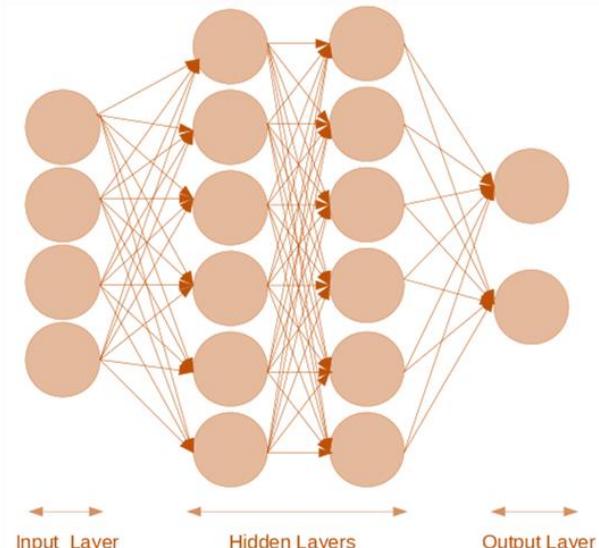
Communication protocol:
50% dropout rate ($r=25$)

Communication **every 10 rounds**
(Intermittency)

Heterogenous case:
2% of data available locally, from at most two classes

Homogenous case:
2% of data available locally, i.i.d. among the devices

CIFAR-10



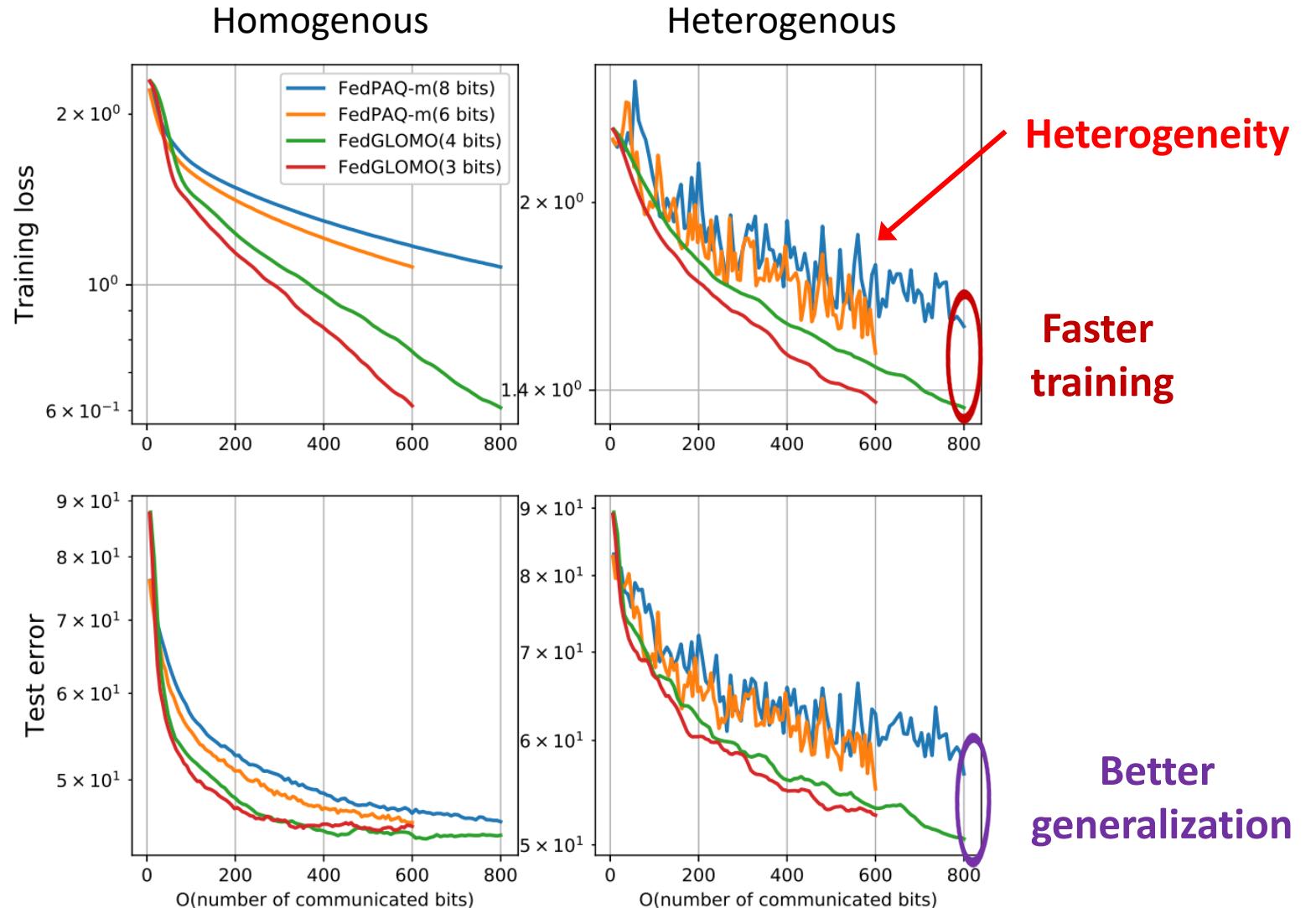
600 neurons

Efficacy of Quantization and Momentum Mechanisms

Baseline: FedPaQ

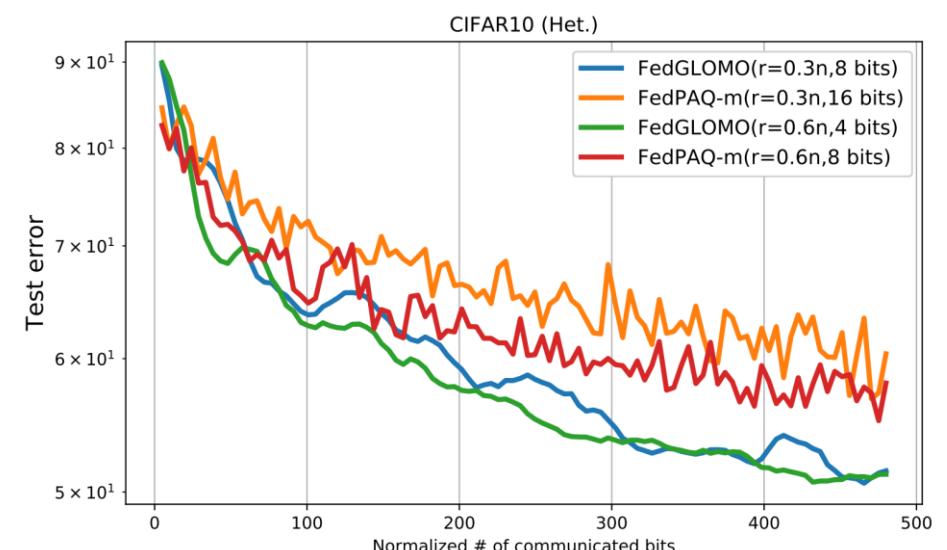
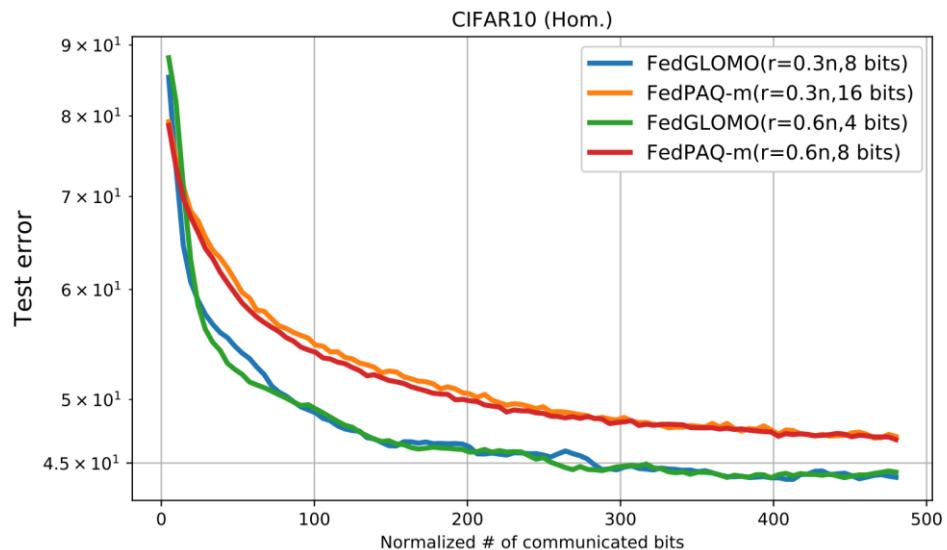
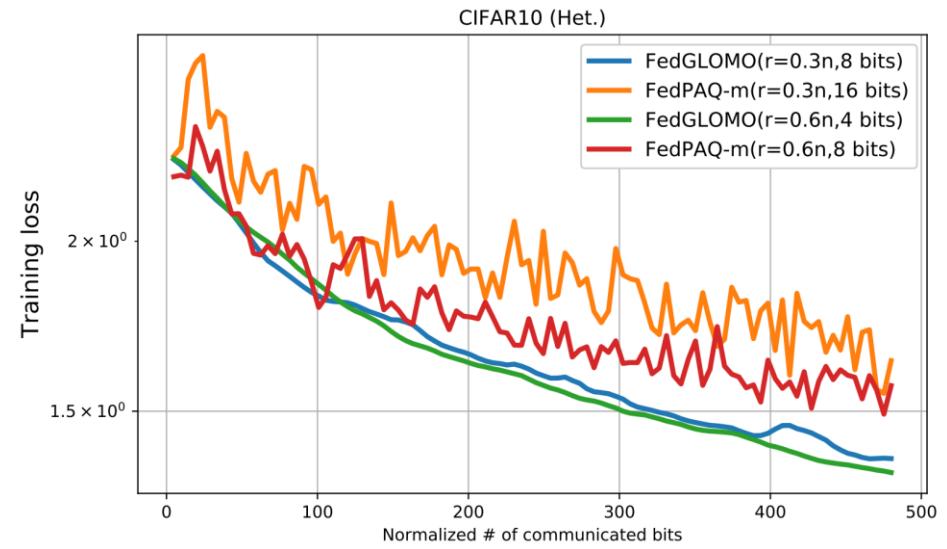
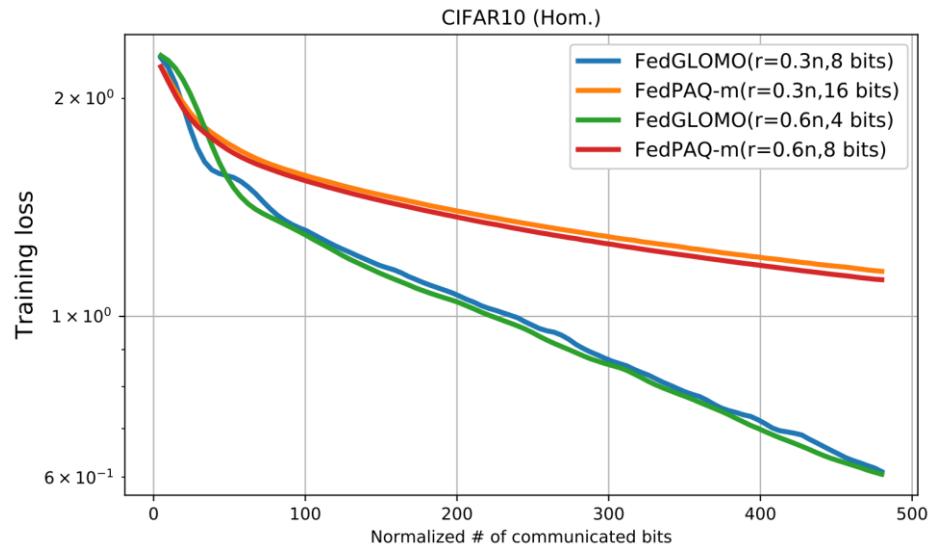
Proposed: FedGLOMO

An order of magnitude savings
in communication resources



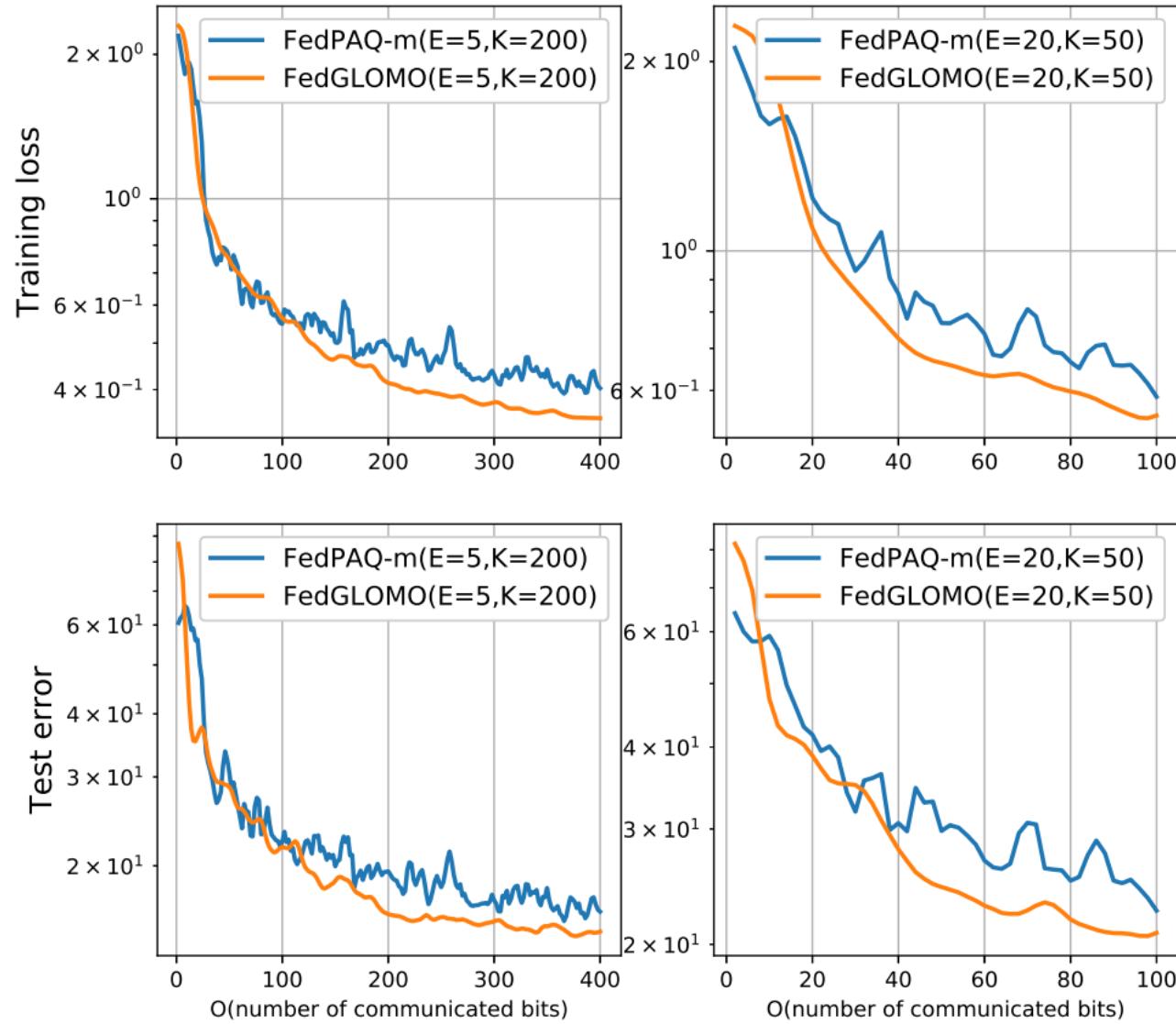
Robustness to Unreliable Communication

Resiliency to device dropout (smaller r)

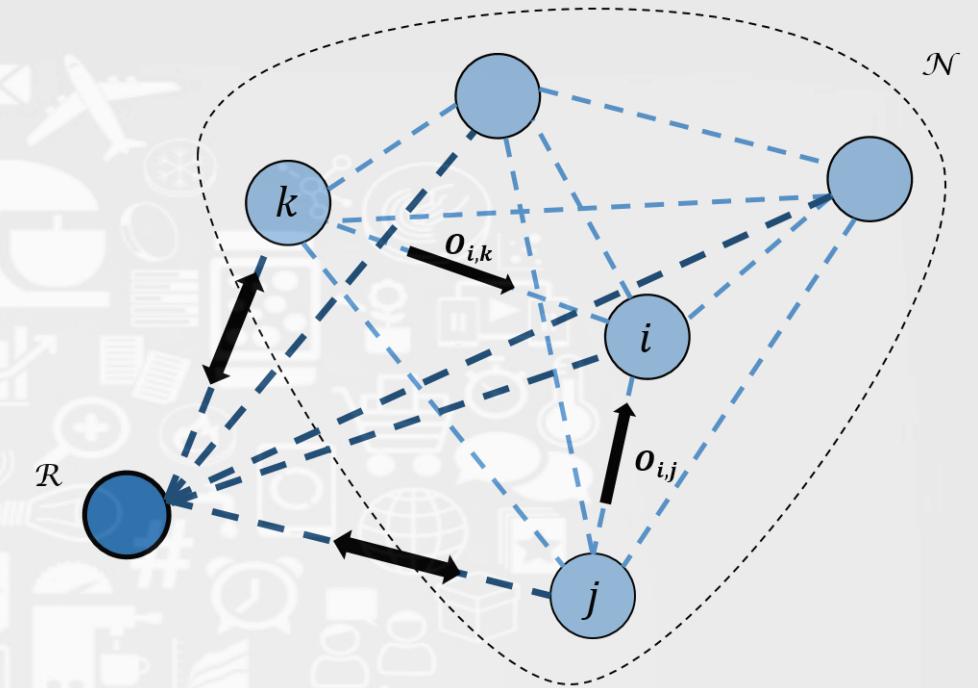


Robustness to Unreliable Communication

Resiliency to device
intermittent availability (larger E)



Information Management in Resource-Constrained Sensing Networks



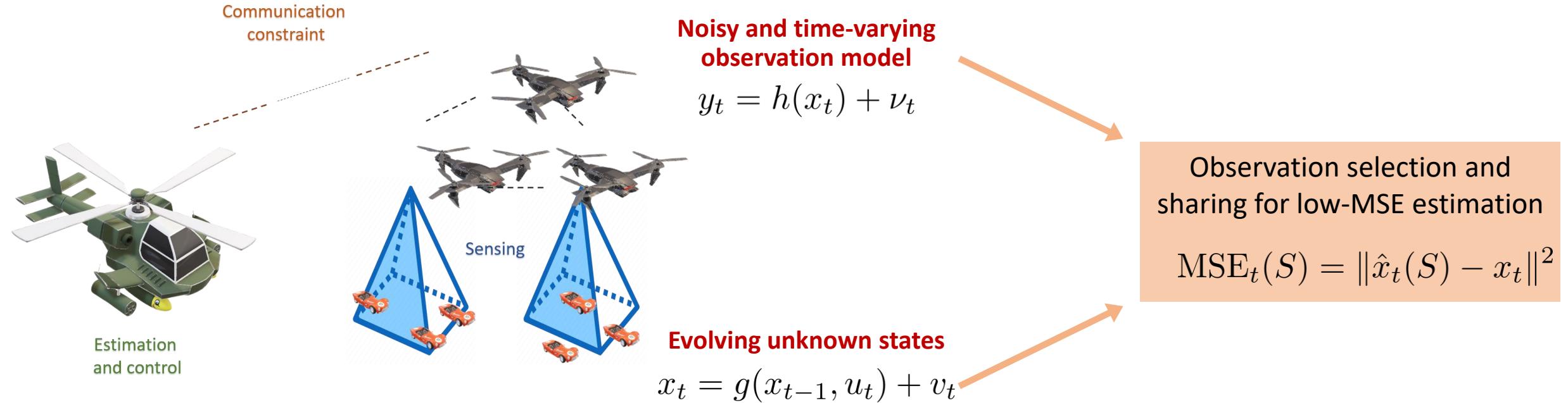
[Hashemi, A., Vikalo, H., de Veciana, G., “Progressive Stochastic Greedy Sparse Reconstruction and Support Selection,” Submitted, 2021.]

[Hashemi, A., Ghasemi, M., Vikalo, H., Topcu, U., “Randomized greedy sensor selection: Leveraging weak submodularity,” IEEE Transactions on Automatic Control, Jan. 2021.]

[Hashemi, A., Vikalo, H., de Veciana, G., “On the Performance-Complexity Tradeoff in Stochastic Greedy Weak Submodular Optimization,” International Conference on Acoustic, Speech and Signal Processing (ICASSP), 2021.]

[Hashemi, A., Ghasemi, M., Vikalo, H., Topcu, U., “Submodular Observation Selection and Information Gathering for Quadratic Models,” International Conference on Machine Learning (ICML), Long Beach, CA, June 2019.]

Observation Selection for Sensing Networks



Questions

- What should be the selection **criteria**?
- How can we perform the selection **efficiently** and with **guaranteed performance**?

Observation Selection Criteria

Scalar functions of the predicted error covariance matrix $f(P_t(S))$

Constrained combinatorial optimization

$$\hat{S} = \arg \max_{|S| \leq k} f(S)$$

NP-hard

Krause, 2011

$$f(\hat{S}) \geq (1 - e^{-\alpha}) f(S^*)$$

Weak-submodularity
constant $0 < \alpha \leq 1$

Optimal approximation guarantee

Krause, 2011

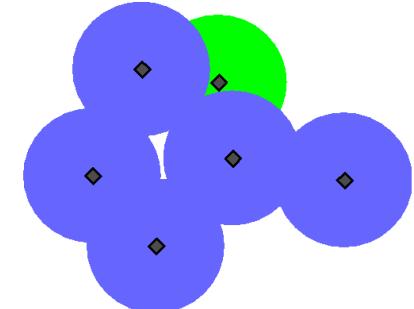
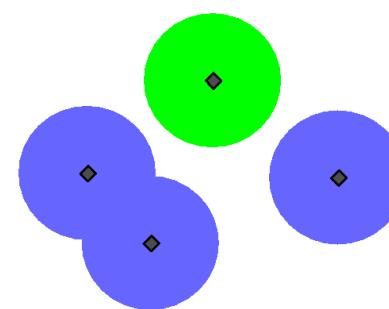
Approximate
greedy solution



$f(S)$ has nice properties:

- Monotonicity
- Weak-submodularity

Hashemi et al., 2018



$$f(A \cup \{d\}) - f(A) \geq f(B \cup \{d\}) - f(B)$$

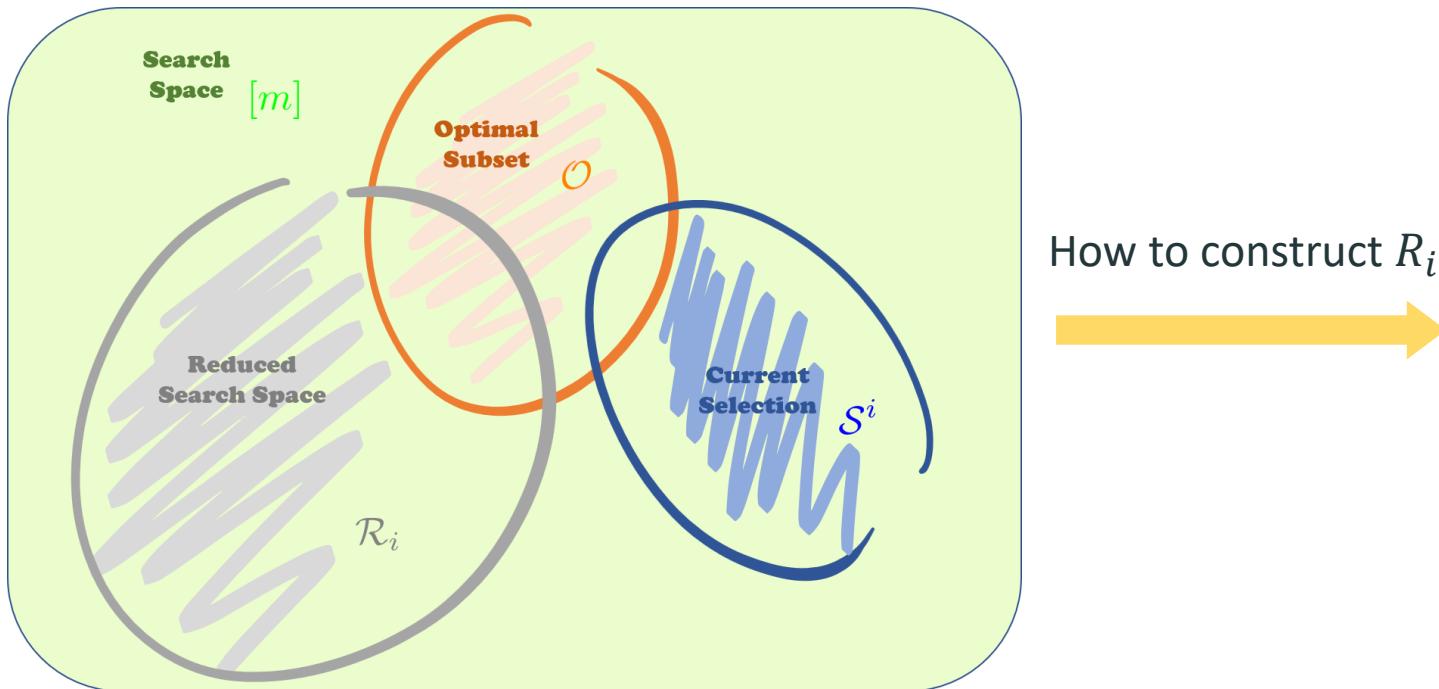
Observation Selection in Large-Scale Networks

Greedy selection

Tight approximation guarantee

Prohibitive computational cost

Reduce the space of greedy by **random sampling**



How to construct R_i

Theorem

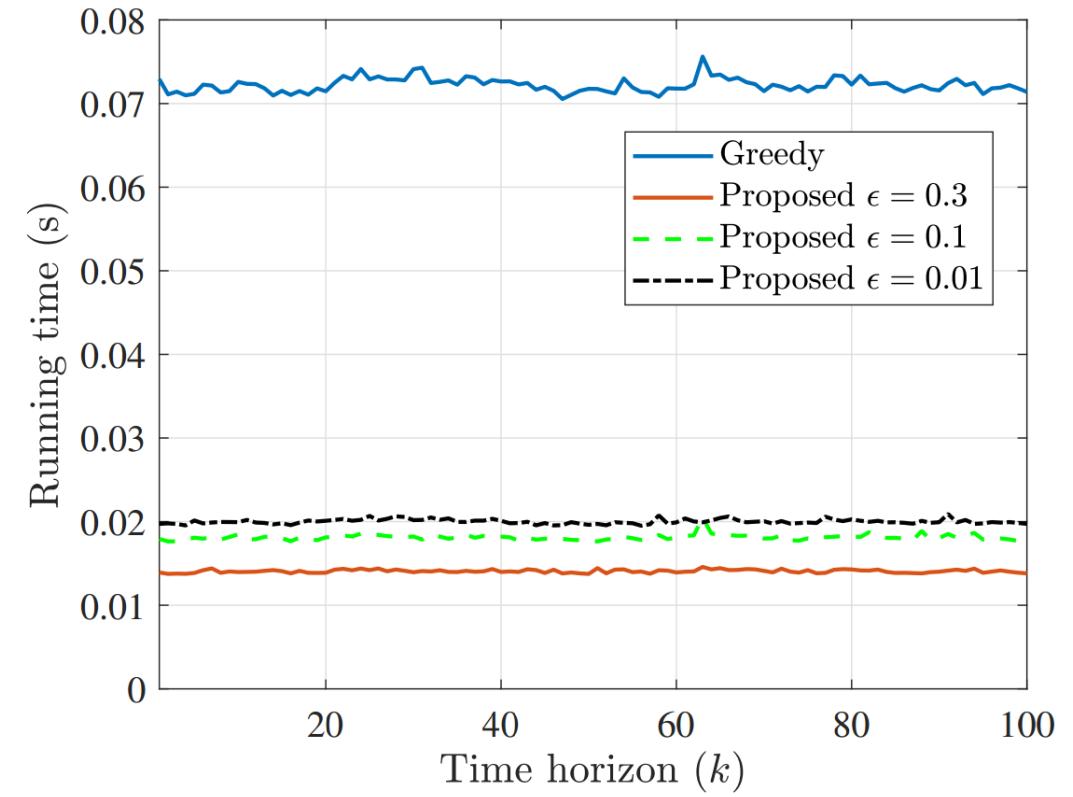
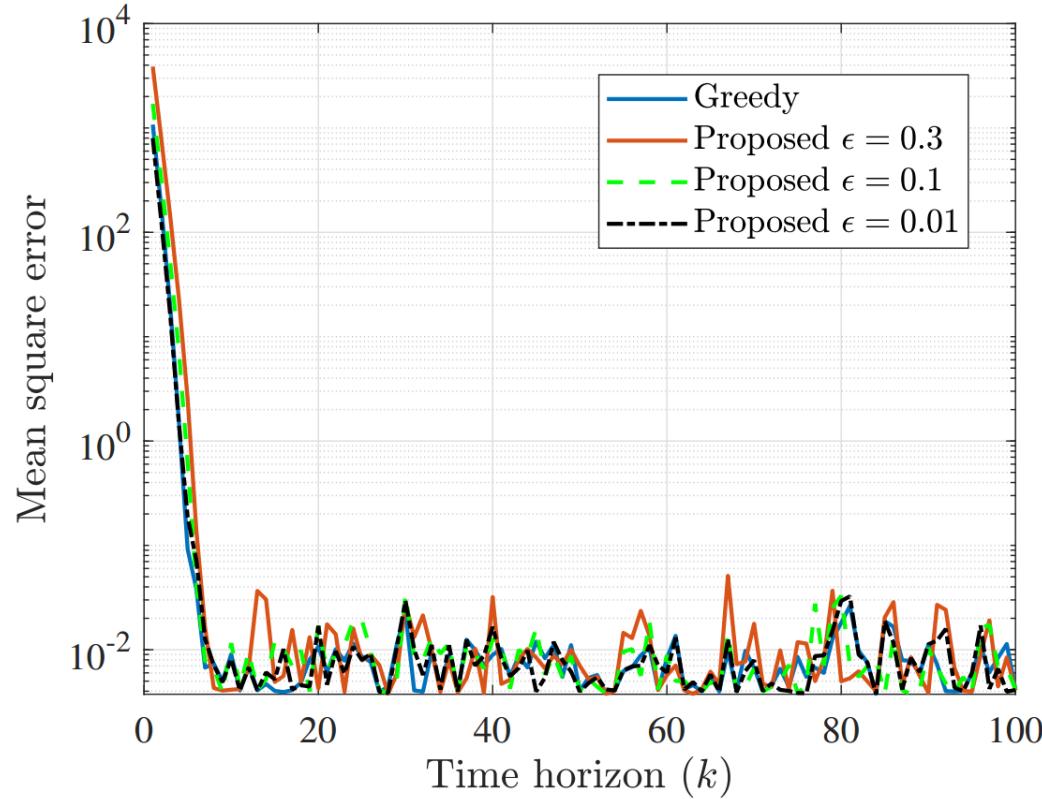
An increasing schedule is required to ensure the intersection is nonempty

Theorem

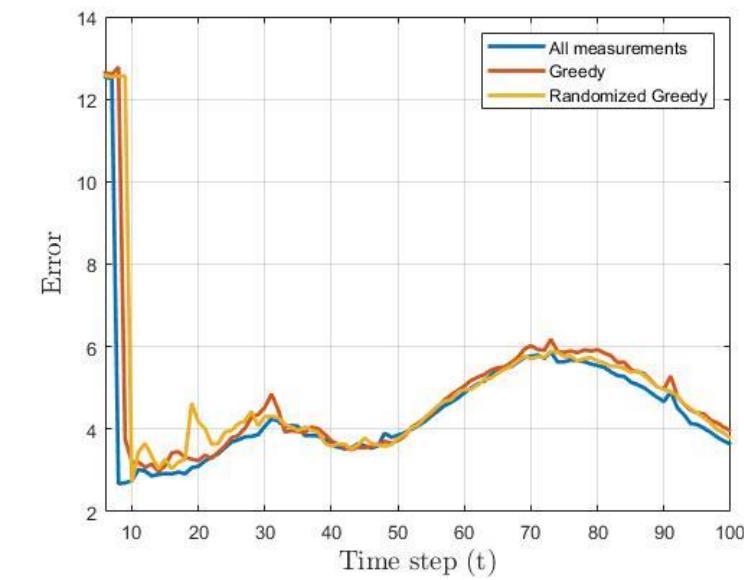
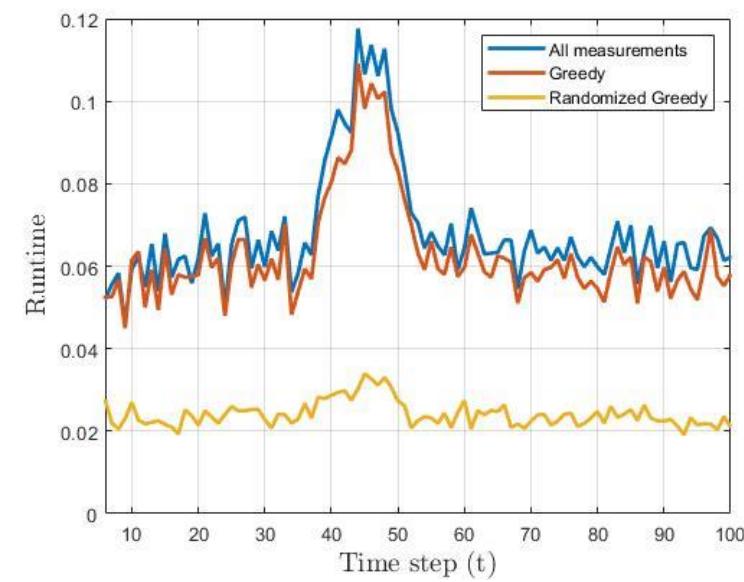
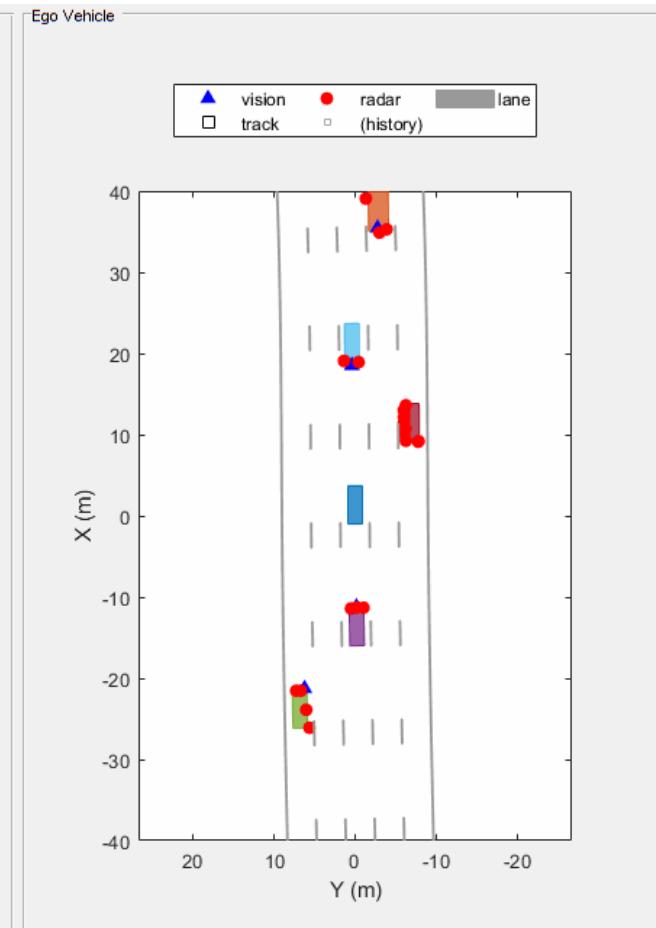
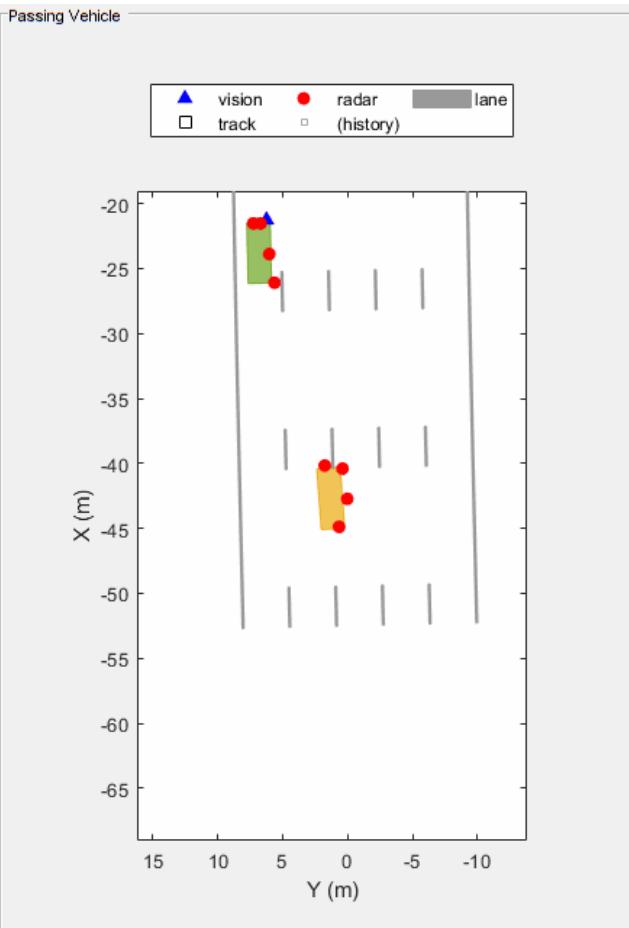
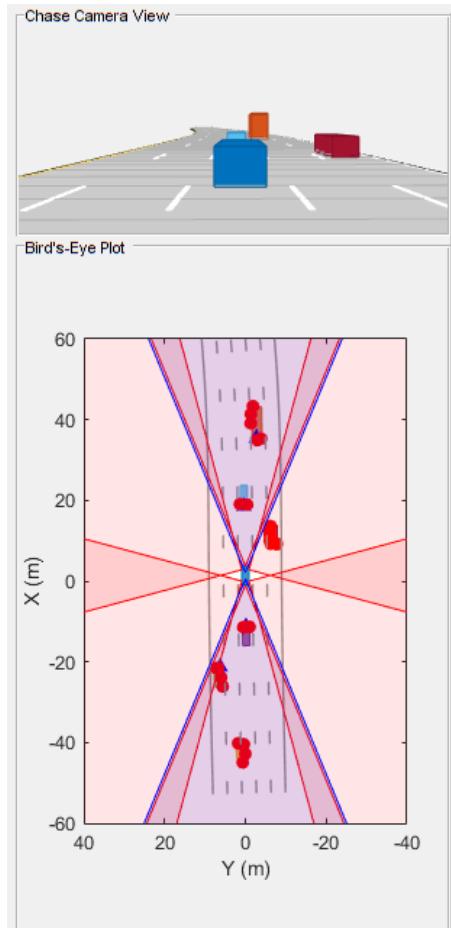
Near-optimal expected approximation guarantee

$$\mathbb{E}[f(\hat{S})] \geq (1 - e^{-\alpha} - \alpha\epsilon) f(S^*)$$

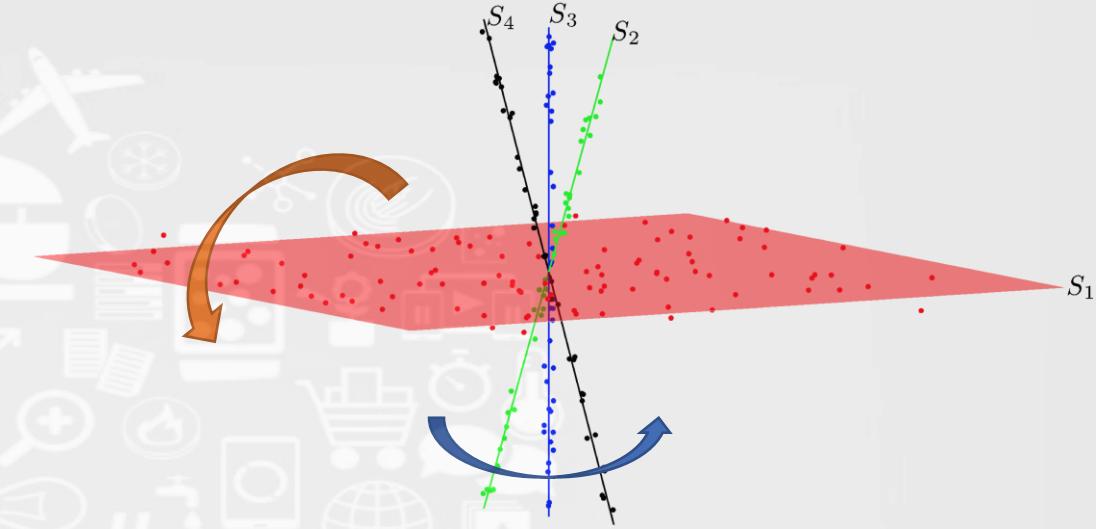
UAV-Based Target Tracking



Application in Autonomous Driving



Data-Scarce Parsimonious Representation Learning



[Hashemi, A., Schaeffer, H., Shi, B., Tran, G., Ward, R., “Generalization Bounds for Sparse Random Features Expansions”, 2021.]

[Hashemi, A., Zhu, B., Vikalo, H., “Sparse Tensor Decomposition for Haplotype Assembly of Diploids and Polyploids,” BMC Genomics, Mar. 2018.]

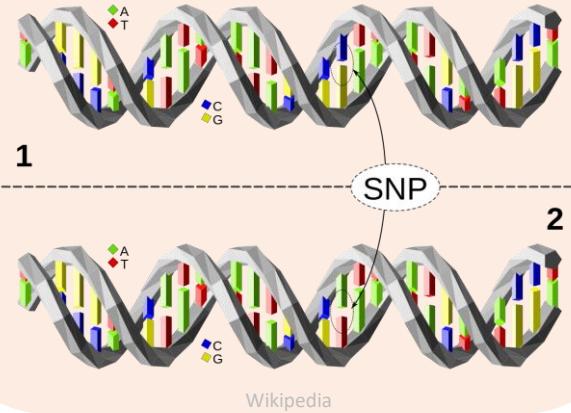
[Hashemi, A. and Vikalo, H., “Evolutionary Self-Expressive Models for Subspace Clustering,” IEEE Journal of Selected Topics in Signal Processing, Dec. 2018.]

[Hashemi, A. and Vikalo, H., “Accelerated Orthogonal Least-Squares for Large-Scale Sparse Reconstruction,” Digital Signal Processing, Nov. 2018.]

Structured Function Approximation

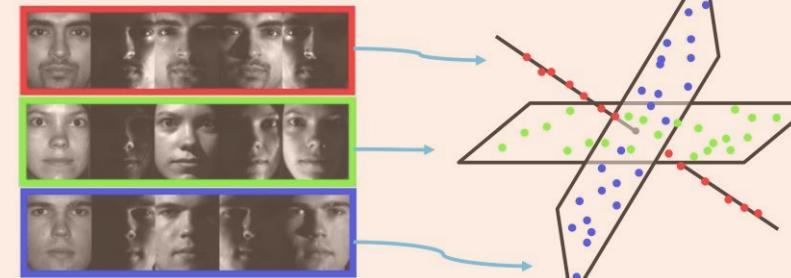
Low-rank structure

Genome sequencing



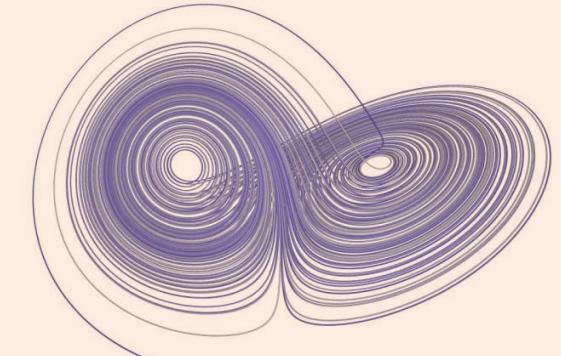
Sparsity

Clustering



Low-order structure

Dynamical systems



$$\dot{x}_i = x_{i+1}x_{i-1} - x_{i-1}x_{i-2} - x_i + 8, \quad i = 1, \dots, d$$

Wikipedia

Goal

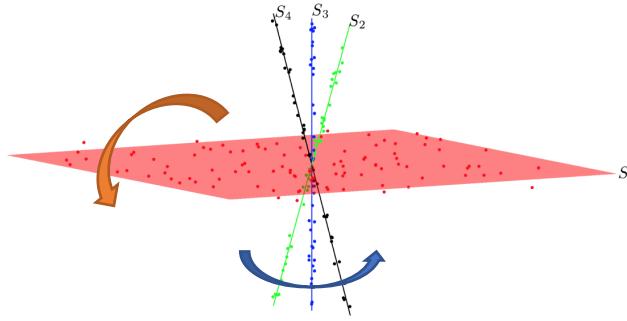
- Learning **structured unknown functions** from **limited measurements**

$$\min_{\theta} \sum_{i=1}^m \text{dist}(y_i, f(x_i; \theta)) \quad s.t. \quad f(x; \theta) \in \mathcal{F}$$

Parsimonious Representation Learning



Data X_t



Desired
structures

Structure-aware
representation
learning

Multi-variate,
non-convex problems

Alternating
minimization

Subspace
structure

Evolutionary
structure

$$\begin{aligned} \min_{\mathbf{U}, \alpha} \quad & \|\mathbf{X}_t - \mathbf{X}_t(\alpha \mathbf{U} + (1 - \alpha) \mathbf{C}_{t-1})\|_F^2 \\ \text{s.t.} \quad & \text{diag}(\mathbf{U}) = \mathbf{0}, \quad \|\mathbf{U}\|_0 \leq k, \quad 0 \leq \alpha \leq 1 \end{aligned}$$

Subspace
structure

Theorem

Bound on amount of required data for a target accuracy

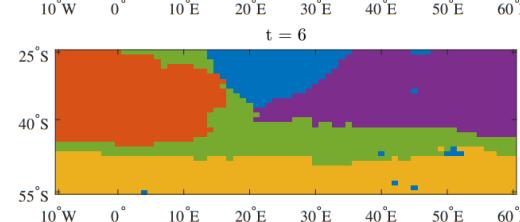
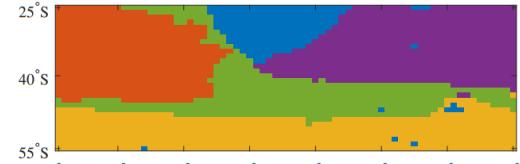
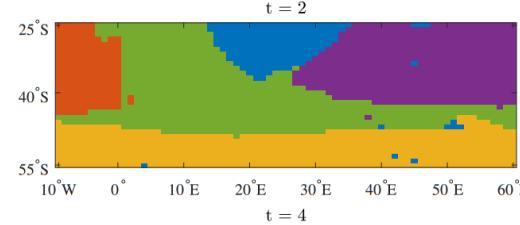
Empirical Applications in Unsupervised Learning

Real-time motion segmentation

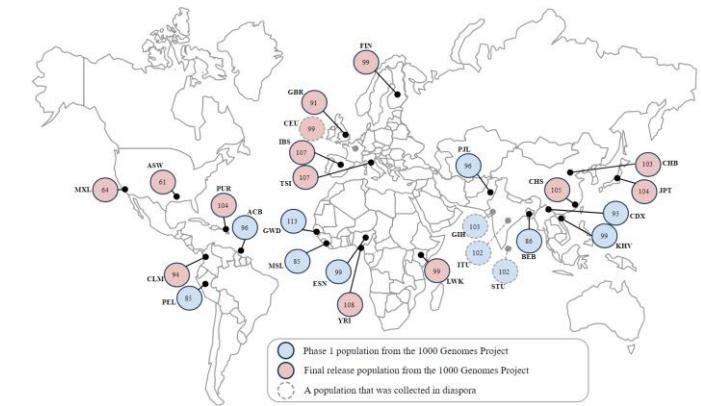


Method	Error (%)	Runtime (s)
Proposed	5.60	1.69
Baseline	10.76	46.16

Tracking water masses near South Africa



Study of genetic variation



Method	Error (%)	Runtime (s)
Proposed	0.042	4.60
Baseline	0.152	11.42

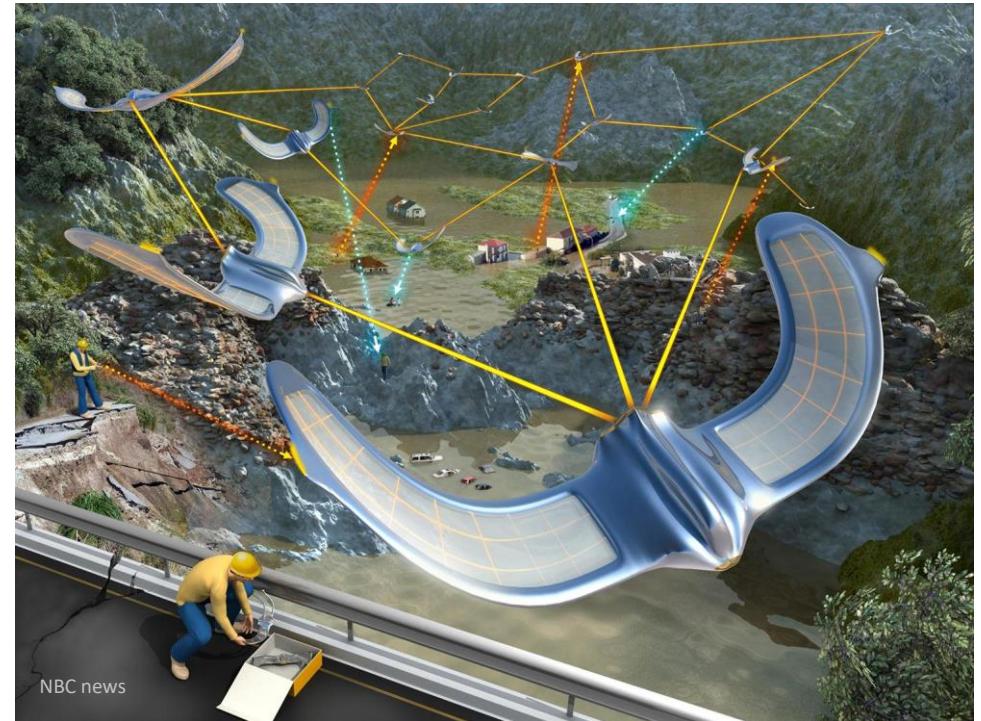


Ongoing and Future Work

Collaborative Learning in Dynamic Environments

Adaptive **representation learning** of dynamic data

Resource-constrained collaborative learning under **uncertainty and dynamic heterogeneity**



[Ghasemi, M., Hashemi, A., Vikalo, H., Topcu, U., "No-Regret Learning with High-Probability in Adversarial Markov Decision Processes," Conference on Uncertainty in Artificial Intelligence (UAI), 2021]

[Ghasemi, M., Hashemi, A., Topcu, U., Vikalo, H., "Online Learning with Implicit Exploration in Episodic Markov Decision Processes," American Control Conference (ACC), 2021]

Robustness and Security

Collaboration against **unexpected contingencies and adversaries**

Integrating **robust hypothesis testing** into information acquisition and representation learning

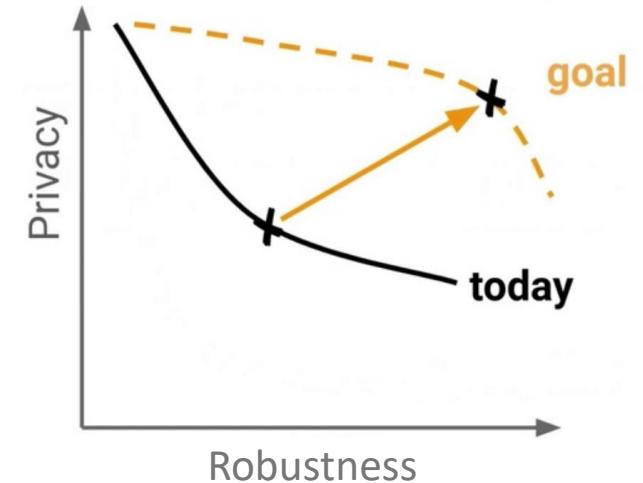
Exploring the **trade-off between privacy and robustness**

[Acharya, A., Hashemi, A., Jain, P., Sanghavi, S., Dhillon, I., Topcu, U., “Robust Training in High Dimensions via Block Coordinate Geometric Median Descent,” Preprint, 2021]

[Das, R., Hashemi, A., Sanghavi, S., Dhillon, I., “DP-NormFedAvg: Normalizing Client Updates for Privacy-Preserving Federated Learning,” Preprint, 2021]

Update: Chrysler recalls 1.4M vehicles after Jeep hack

COMPUTERWORLD



Structured and Resource-Constrained Collaborative Learning

Abolfazl Hashemi

