## MCDP formulation and implementation based on multiplicative decomposition of deformation gradient tensor

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## 1 MCDP

The plastic potential function is expressed as (Shunchuan et al., 2017)

Mohr-Coulomb:

$$f(\sigma)^{MC} = \sqrt{J_2^{\sigma}} + \frac{(B_I - 1)I_1^{\sigma} - 3f_c}{3(B_I + 1)\cos\theta^{\sigma} + \sqrt{3}(B_I - 1)\sin\theta^{\sigma}}$$
(1)

Drucker-Pragger:

$$f(\sigma^{DP}) = \sqrt{J_2^{\sigma}} + \frac{(B_I - 1)}{\sqrt{3}B_I + 2\sqrt{3}}I_1^{\sigma} - \frac{\sqrt{3}}{B_I + 2}f_c$$
 (2)

$$B_I = \frac{1 + \sin \theta}{1 - \sin \theta} f_c = \frac{2c \cos \theta}{1 - \sin \theta}$$
 (3)

The plastic potential should be described in terms of intermediate configuration. Therefore, above equations are written as below.

Mohr-Coulomb:

$$f(\bar{\mathbf{M}})^{MC} = \sqrt{J_2^{\bar{M}}} + \frac{(B_I - 1)I_1^{\bar{M}} - 3f_c}{3(B_I + 1)\cos\theta^{\bar{M}} + \sqrt{3}(B_I - 1)\sin\theta^{\bar{M}}}$$
(4)

Drucker-Pragger:

$$f(\bar{\mathbf{M}}^{DP}) = \sqrt{J_2^{\bar{M}}} + \frac{(B_I - 1)}{\sqrt{3}B_I + 2\sqrt{3}}I_1^{\bar{M}} - \frac{\sqrt{3}}{B_I + 2}f_c \tag{5}$$

$$B_I = \frac{1 + \sin \theta}{1 - \sin \theta} f_c = \frac{2c \cos \theta}{1 - \sin \theta} \tag{6}$$

Here,  $\overline{M}$  is the Mandel stress tensor.

The invariant of the yield functions should also be shown as seen in

$$\bar{M}_{\bar{I}\bar{J}} = \bar{C}^{e}_{\bar{I}\bar{K}} \bar{S}_{\bar{K}\bar{J}} = F^{e}_{\bar{I}i} F^{T}_{i\bar{K}} F^{e-1}_{\bar{K}k} \sigma_{kj} F^{e-1}_{i\bar{J}} = J F^{e}_{\bar{I}i} \sigma_{ij} F^{e-1}_{i\bar{J}}$$
 (7)

$$I_1^{\bar{M}} = \bar{M}_{\bar{I}\bar{I}} = JI_1^{\sigma} \tag{8}$$

$$J_2^{\bar{M}} = J^2 J_2^{\sigma} \tag{9}$$

$$J_3^{\bar{M}} = J^3 J_3^{\sigma} \tag{10}$$

$$\theta^{\bar{M}} = \theta^{\sigma} \tag{11}$$

$$\frac{\partial f(\bar{\mathbf{M}})^{DP}}{\partial \bar{M}}) = \frac{1}{2} \left( J_2^{\bar{M}} \right)^{-\frac{1}{2}} \left( \bar{M}^{\frac{I_1^{\bar{\mathbf{M}}}}{3}} \bar{\mathbf{G}} \right) + \frac{B_I - 1}{\sqrt{3}B_I + 2\sqrt{3}} \bar{\mathbf{G}}$$

$$\tag{12}$$