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import numpy as np
import matplotlib.pyplot as plt
class TwoLayerNet (object):
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 A two-layer fully-connected neural network. The net has an input dimension of
 D, a hidden layer dimension of H, and performs classification over C classes.
 We train the network with a softmax loss function and L2 regularization on the
 weight matrices. The network uses a ReLU nonlinearity after the first fully
 connected layer.
 In other words, the network has the following architecture:
  input - fully connected layer - ReLU - fully connected layer - softmax
  The outputs of the second fully-connected layer are the scores for each class.
  def init (self, input size, hidden size, output size, std=1e-4):
   Initialize the model. Weights are initialized to small random values and
   biases are initialized to zero. Weights and biases are stored in the
   variable self.params, which is a dictionary with the following keys:
   W1: First layer weights; has shape (H, D)
   b1: First layer biases; has shape (H,)
   W2: Second layer weights; has shape (C, H)
   b2: Second layer biases; has shape (C,)
   Inputs:
    - input size: The dimension D of the input data.
    - hidden size: The number of neurons H in the hidden layer.
    - output size: The number of classes C.
   self.params = {}
   self.params['W1'] = std * np.random.randn(hidden size, input size)
   self.params['b1'] = np.zeros(hidden size)
   self.params['W2'] = std * np.random.randn(output size, hidden size)
   self.params['b2'] = np.zeros(output size)
  def loss(self, X, y=None, reg=0.0):
   Compute the loss and gradients for a two layer fully connected neural
   network.
   Inputs:
    - X: Input data of shape (N, D). Each X[i] is a training sample.
    - y: Vector of training labels. y[i] is the label for X[i], and each y[i] is
     an integer in the range 0 \le y[i] \le C. This parameter is optional; if it
     is not passed then we only return scores, and if it is passed then we
     instead return the loss and gradients.
    - reg: Regularization strength.
   Returns:
    If y is None, return a matrix scores of shape (N, C) where scores[i, c] is
    the score for class c on input X[i].
   If y is not None, instead return a tuple of:
    - loss: Loss (data loss and regularization loss) for this batch of training
     samples.
    - grads: Dictionary mapping parameter names to gradients of those parameters
     with respect to the loss function; has the same keys as self.params.
    # Unpack variables from the params dictionary
   W1, b1 = self.params['W1'], self.params['b1']
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W2, b2 = self.params['W2'], self.params['b2']
N, D = X.shape
# Compute the forward pass
scores = None
# ----- #
# YOUR CODE HERE:
  Calculate the output scores of the neural network. The result
 should be (N, C). As stated in the description for this class,
  there should not be a ReLU layer after the second FC layer.
 The output of the second FC layer is the output scores. Do not
# use a for loop in your implementation.
# ------ #
# Compute the forward pass
scores = X.dot(W1.T) + b1 # First FC layer
scores relu = np.maximum(0, scores) # ReLU activation
scores = scores_relu.dot(W2.T) + b2 # Second FC layer
# ------ #
# END YOUR CODE HERE
# If the targets are not given then jump out, we're done
if y is None:
 return scores
# Compute the loss
loss = None
# ------ #
# YOUR CODE HERE:
 Calculate the loss of the neural network. This includes the
 softmax loss and the L2 regularization for W1 and W2. Store the
  total loss in teh variable loss. Multiply the regularization
  loss by 0.5 (in addition to the factor reg).
# ----- #
# Compute the loss
exp_scores = np.exp(scores - np.max(scores, axis=1, keepdims=True))
probs = exp_scores / np.sum(exp_scores, axis=1, keepdims=True)
correct logprobs = -np.log(probs[range(N), y])
data loss = np.sum(correct logprobs) / N
reg_loss = 0.5 * reg * (np.sum(self.params['W1'] ** 2) + np.sum(self.params['W2'] ** 2))
loss = data loss + reg loss
# ----- #
# END YOUR CODE HERE
# ------ #
grads = \{\}
# ----- #
# YOUR CODE HERE:
# Implement the backward pass. Compute the derivatives of the
 weights and the biases. Store the results in the grads
# dictionary. e.g., grads['W1'] should store the gradient for
 W1, and be of the same size as W1.
# Compute gradient
dscores = probs.copy()
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dscores[np.arange(N), y] -= 1
 dscores /= N
 # print(dscores)
 # Layer 2
 grad 2 = np.dot(scores relu.T, dscores).T
 grads['b2'] = np.sum(dscores, axis=0)
 grads['W2'] = grad 2 + reg * W2 # Add regularization gradient
 # Layer 1
 dhidden = np.dot(dscores, W2)
 dhidden[scores_relu <= 0] = 0</pre>
 grad 1 = np.dot(X.T, dhidden).T
 grads['b1'] = np.sum(dhidden, axis=0)
 grads['W1'] = grad_1 + reg * W1 # Add regularization gradient
 # ------ #
 # END YOUR CODE HERE
 # ============= #
 return loss, grads
def train(self, X, y, X_val, y_val,
        learning_rate=1e-3, learning_rate_decay=0.95,
        reg=1e-5, num_iters=100,
        batch size=200, verbose=False):
 Train this neural network using stochastic gradient descent.
 Inputs:
 - X: A numpy array of shape (N, D) giving training data.
 - y: A numpy array f shape (N,) giving training labels; y[i] = c means that
  X[i] has label c, where 0 <= c < C.
 - X_val: A numpy array of shape (N_val, D) giving validation data.
 - y_val: A numpy array of shape (N_val,) giving validation labels.
 - learning rate: Scalar giving learning rate for optimization.
 - learning rate decay: Scalar giving factor used to decay the learning rate
  after each epoch.
 - reg: Scalar giving regularization strength.
 - num iters: Number of steps to take when optimizing.
 - batch_size: Number of training examples to use per step.
 - verbose: boolean; if true print progress during optimization.
 num train = X.shape[0]
 iterations per epoch = max(num train / batch size, 1)
 # Use SGD to optimize the parameters in self.model
 loss history = []
 train_acc_history = []
 val acc history = []
 for it in np.arange(num iters):
   X batch = None
   y batch = None
                 ------ #
   # YOUR CODE HERE:
   # Create a minibatch by sampling batch size samples randomly.
   # ----- #
   batch_idxs = np.random.choice(num_train, batch_size, replace=True)
   X \text{ batch} = X[\text{batch idxs}]
   y batch = y[batch idxs]
   # ------ #
   # END YOUR CODE HERE
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# Compute loss and gradients using the current minibatch
   loss, grads = self.loss(X_batch, y=y_batch, reg=reg)
   loss history.append(loss)
   # ------ #
   # YOUR CODE HERE:
     Perform a gradient descent step using the minibatch to update
     all parameters (i.e., W1, W2, b1, and b2).
   for param name in self.params.keys():
    self.params[param name] -= learning rate * grads[param name]
   # ----- #
   # END YOUR CODE HERE
   if verbose and it % 100 == 0:
    print('iteration {} / {}: loss {}'.format(it, num iters, loss))
   # Every epoch, check train and val accuracy and decay learning rate.
   if it % iterations per epoch == 0:
    # Check accuracy
    train acc = (self.predict(X batch) == y batch).mean()
    val acc = (self.predict(X_val) == y_val).mean()
    train acc history.append(train acc)
    val acc history.append(val acc)
    # Decay learning rate
    learning_rate *= learning_rate_decay
 return {
   'loss history': loss history,
   'train_acc_history': train_acc history,
   'val_acc_history': val_acc_history,
def predict(self, X):
 Use the trained weights of this two-layer network to predict labels for
 data points. For each data point we predict scores for each of the C
 classes, and assign each data point to the class with the highest score.
 Inputs:
 - X: A numpy array of shape (N, D) giving N D-dimensional data points to
   classify.
 Returns:
 - y_pred: A numpy array of shape (N,) giving predicted labels for each of
  the elements of X. For all i, y pred[i] = c means that X[i] is predicted
  to have class c, where 0 \ll c \ll c.
 y pred = None
 # ----- #
 # YOUR CODE HERE:
   Predict the class given the input data.
 # ----- #
 scores = self.loss(X)
 y_pred = np.argmax(scores, axis=1)
 # END YOUR CODE HERE
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