

~\Documents\UIUC Courses\ECE420\ECE420\_FinalProject\iCardScanner.py

```
1 # Import libraries
2 import cv2
3 import numpy as np
4 import imageio.v3 as iio
5 import matplotlib.pyplot as plt
6 import sys
7 import os
8 import pytesseract
9
10 #%%
11
12 # Function that returns the contour of the largest rectangular object in the frame
13 def get_bounding_quadangle(img):
14     kernel = np.ones((3,3), np.uint8)
15     img_dilate = cv2.dilate(img, kernel, iterations=1)
16     # cv2.imshow("Dilate", img_dilate)
17
18     # Perform Canny Edge detection
19     img_edgedetect = cv2.Canny(img_dilate, threshold1=100, threshold2=200)
20     cv2.imshow('Edges', img_edgedetect)
21
22     # Get Contours
23     img_contours, hierarchy = cv2.findContours(img_edgedetect, cv2.RETR_EXTERNAL, cv2.CHAIN_APPROX_SIMPLE)
24
25     img_with_contours = np.ones_like(img, dtype=np.uint8) * 255
26
27     # Find the contour with the maximum area
28     max_area = 0
29     max_idx = -1
30
31     for idx, contour in enumerate(img_contours):
32         contour_convex_hull = cv2.convexHull(contour)
33         convex_hull_area = cv2.contourArea(contour_convex_hull)
34         # print(contour_convex_hull)
35
36         if(max_area < convex_hull_area):
37             max_idx = idx
38             max_area = convex_hull_area
39
40     if (max_idx >= 0):
41         cv2.drawContours(img_with_contours, [img_contours[max_idx]], 0, (0,255,0), 2)
42         # cv2.imshow('Contours no hull', img_with_contours)
43         cv2.drawContours(img_with_contours, [cv2.convexHull(img_contours[max_idx])], 0, (0,255,0), 2)
44         cv2.imshow('Contours', img_with_contours)
45     else:
46         print("No max contour found")
47         return -1
48
49     # Apply polygon approximation
50     for err in np.linspace(0.005, 0.09, 80):
51         approx_contour = cv2.approxPolyDP(cv2.convexHull(img_contours[max_idx]), err * cv2.arcLength(img_contours[max_idx], True), True)
52         # print(f"err: {err}, numpoints: {approx_contour.shape}")
53         if(approx_contour.shape[0] == 4):
54             break
55
56     return approx_contour
57
58 # Uses Tesseract OCR to return all the characters in an image, thresholding applied as pre processing for tesseract
59 def extract_text_from_image(image):
60     # Threshold the image
61     blur = cv2.GaussianBlur(image,(3,3),0)
62     ret3,img_uin = cv2.threshold(blur,0,255,cv2.THRESH_BINARY+cv2.THRESH_OTSU)
63
64     # Convert the image to RGB (Tesseract requires RGB images)
65     rgb_image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
66
67     # Use Tesseract to extract text, single line mode (psm7)
68     text = pytesseract.image_to_string(rgb_image, config='--psm 7')
69
70     cv2.imshow("thresh_crop", img_uin)
71
72     return text
73
74 #%%
75
76 IMG_DIR = 'imgs/'
77
78 # Video for testing: Change the video to test and the accurate UIN
79 video = cv2.VideoCapture(f'{IMG_DIR}icard0_still.mp4')
80 TRUE_UIN = "659758250"
81
82 if not video.isOpened():
83     print('Cannot open video')
84     sys.exit()
85
86 # Set up output video file writer (records annotated frames to an mp4 file, for presentation)
87 # output_video_path = f'{IMG_DIR}icard0_outputvid_1.mp4'
88 # frame_width = int(video.get(cv2.CAP_PROP_FRAME_WIDTH))
89 # frame_height = int(video.get(cv2.CAP_PROP_FRAME_HEIGHT))
90 # fps = 2 #video.get(cv2.CAP_PROP_FPS)
91 # fourcc = cv2.VideoWriter_fourcc(*'mp4v') # MP4 file
92 # out = cv2.VideoWriter(output_video_path, fourcc, fps, (frame_width, frame_height))
93
94 # TESTING: variables to store accuracy measurement in each frame
95 user_input_accurate_frames = [] # We manually indicate 1 for an accurately detected card and 0 if not
96 accurate_uin = [] # Records if text detected in the frame matches the true UIN (1) or not (0)
97 false_uin = [] # Records if the text detected contains digits of the expected length of a UIN, but is incorrect (1)
98
99
100 # for filename in jpg_names:
101 #     img = cv2.imread(f'{IMG_DIR}{filename}', cv2.IMREAD_GRAYSCALE)
102
103 # Loop through each frame of the video
104 while True:
105     read_success, img_color = video.read()
106     if not read_success:
107         # We have reached the last frame of the video
108         print('End of video')
109         cv2.waitKey(0)
110         cv2.destroyAllWindows()
111
112         # For the output annotated video
113         #out.release()
114
115         # TESTING: accuracy metrics
116         # user_input_accurate_frames = user_input_accurate_frames[:]:]
117         # accurate_uin = accurate_uin[:1]
118         # print(f'Card Detection Accuracy = {sum(user_input_accurate_frames) / len(user_input_accurate_frames)}')
119         # print(f'UIN Detection Accuracy = {sum(accurate_uin) / sum(user_input_accurate_frames)}')
120         # print(f'False UIN Detection = {sum(false_uin) / len(user_input_accurate_frames)}')
121         # print(f'Num frames = {len(user_input_accurate_frames)}')
122
123         sys.exit()
124
125 # Switch to grayscale for processing
126 img = cv2.cvtColor(img_color, cv2.COLOR_BGR2GRAY)
127
128 img_poly_contour = img_color
129 approx_contour = get_bounding_quadangle(img)
130
131 if(type(approx_contour) == np.ndarray and approx_contour.shape[0] == 4):
132     cv2.drawContours(img_poly_contour, [approx_contour], -1, (0,255,0), 2)
133
134     # Get top left corner based on side lengths
135     vec1 = approx_contour[0,0] - approx_contour[1,0]
136     vec2 = approx_contour[0,0] - approx_contour[-1,0]
137
138     # Get CW/CCW by cross product magnitude
139     if(vec1[0]*vec2[1] - vec1[1]*vec2[0] > 0):
140         approx_contour = approx_contour[::-1]
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143 vec1 = approx_contour[0,0] - approx_contour[1,0]
144 vec2 = approx_contour[0,0] - approx_contour[-1,0]
145 if(np.linalg.norm(vec1) > np.linalg.norm(vec2)):
146     approx_contour = np.roll(approx_contour, 1, axis=0)
147
148 # Get perspective transformation
149 W = 480
150 H = int(W // 1.6)
151 M_perspective = cv2.getPerspectiveTransform(np.float32(approx_contour), np.float32([[0, 0], [0, H], [W, H], [W, 0]]))
152
153 hh, ww = img.shape[:2]
154 perspective_img = cv2.warpPerspective(img, M_perspective, (ww,hh))[0:H,0:W]
155
156
157
158 # Tesseract text recognition
159 # Crop the card to the UIN text
160 uin_x_start = (int)(W*2/11)
161 uin_width = (int)(W/4)
162 uin_y_start = H - (int)(H/18)
163 uin_height = (int)(H/10)
164 img_uin = perspective_img[uin_y_start : uin_y_start + uin_height, uin_x_start : uin_x_start + uin_width]
165 uin_text = extract_text_from_image(img_uin)
166 uin_text = uin_text.replace("\n","")
167 cv2.imshow("NetID Cropped", img_uin)
168
169 # If the text identified is not the uin, try flipping the image
170 if(not uin_text.isdigit() or len(uin_text) != 9):
171     perspective_img = perspective_img[::-1, ::1]
172     img_uin = perspective_img[uin_y_start : uin_y_start + uin_height, uin_x_start : uin_x_start + uin_width]
173     uin_text = extract_text_from_image(img_uin)
174     uin_text = uin_text.replace("\n","")
175     cv2.imshow("NetID Cropped flipped", img_uin)
176     cv2.imshow('Perspectived', perspective_img)
177     print("rotated")
178
179 if(not uin_text.isdigit() or len(uin_text) != 9):
180     uin_text = "not found"
181
182
183
184 # If the text still does not resemble a uin, print no text detected
185 if(not uin_text.isdigit() or len(uin_text) != 9):
186     print("No UIN Detected")
187
188 print(f"UIN: {uin_text}, length: {len(uin_text)}")
189
190 cv2.putText(img_poly_contour, f"UIN: {uin_text}", (10, 30), cv2.FONT_HERSHEY_SIMPLEX, 0.75, (0, 255, 0), 2)
191
192 cv2.imshow('Perspectived', perspective_img)
193 cv2.imshow("Annotated", img_poly_contour)
194
195 #out.write(img_poly_contour)
196
197 # TESTING: user input for card detection accuracy
198 # user_input = input("Enter 1 for correct identification of a card and 0 if not: ")
199 # user_in = False
200 # while(user_in == False):
201 #     if user_input.isdigit():
202 #         user_input_accurate_frames.append(int(user_input))
203 #         user_in = True
204 #     else:
205 #         user_input = input("Invalid input, please enter a digit between 0-1: ")
206
207 # TESTING record if UIN is correct
208 if(uin_text == TRUE_UIN):
209     print("Correct UIN")
210     accurate_uin.append(1)
211     false_uin.append(0)
212 else:
213     accurate_uin.append(0)
214     if(len(uin_text) == len(TRUE_UIN) and uin_text.isdigit()):
215         false_uin.append(1)
216     else:
217         false_uin.append(0)
218
219
220 else:
221     print("No card detected")
222
223
224 # cv2.waitKey(0)
225 cv2.waitKey(1)
226
227 #%%
228 cv2.waitKey(0)
229
230 cv2.destroyAllWindows()

```