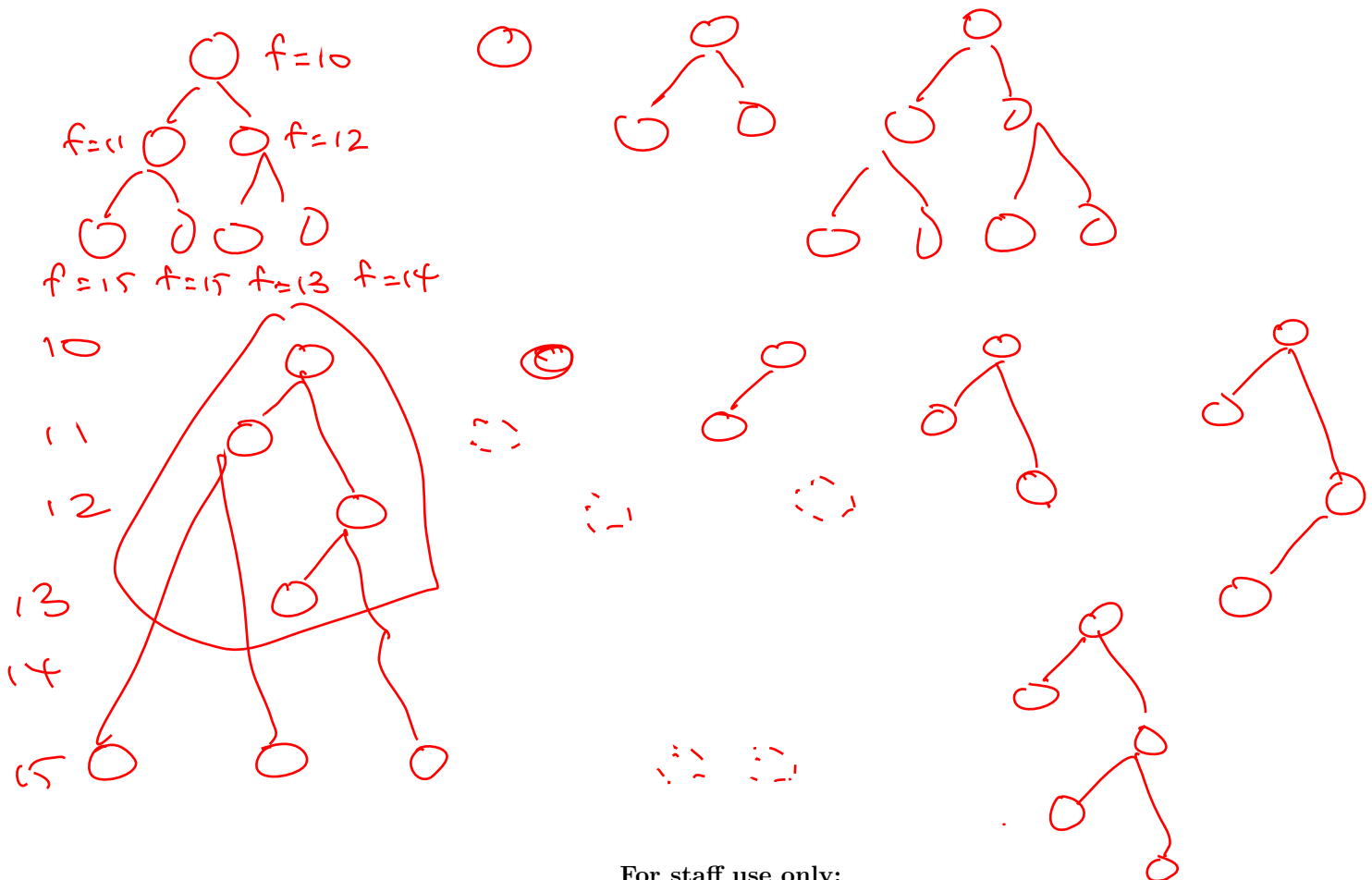


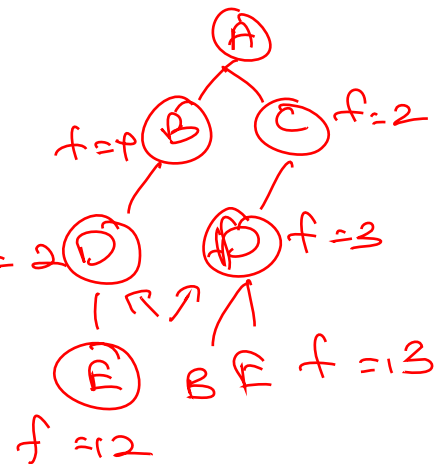
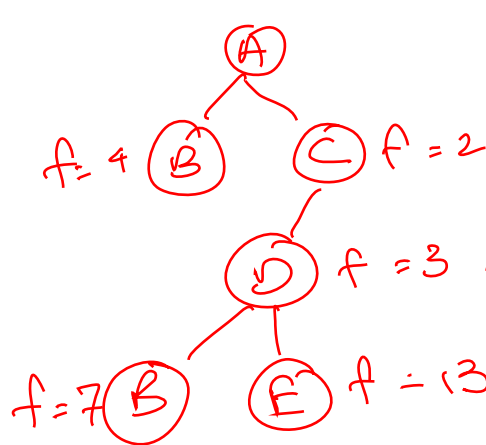
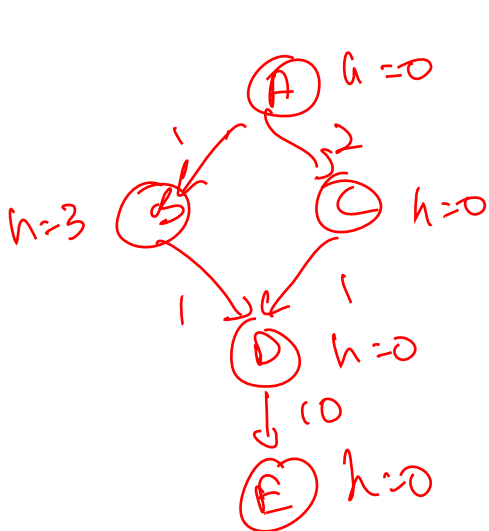
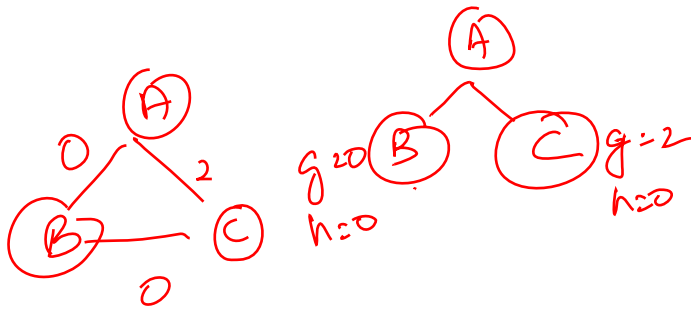
- You have approximately as many minutes as there are points.
- Mark your answers ON THE EXERCISE ITSELF. If you are not sure of your answer you may wish to provide a *brief* explanation. All short answer sections can be successfully answered in a few sentences AT MOST.
- For True/False questions, please *circle* your answer.

First name	
Last name	
WUSTL ID	

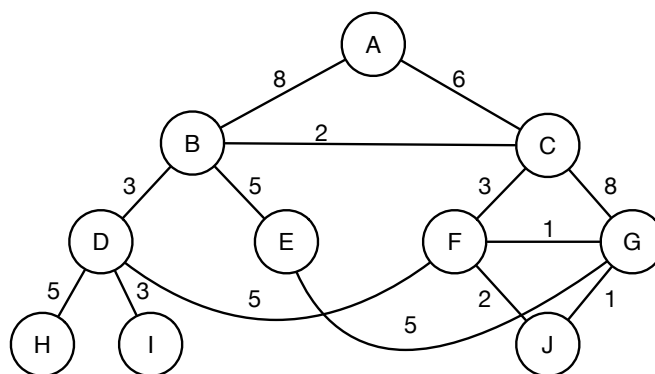


**For staff use only:**

Q1.	Search	/17
	Total	/17



# Q1. [17 pts] Search



The questions on this page refer to the graph above, where the start state is  $A$  and the goal state is  $G$ . The number on an edge corresponds to the cost of traversing that edge. Additionally, assume that we have the following heuristic values:

State	A	B	C	D	E	F	G	H	I	J
Heuristic value	5	3	2	3	2	0	0	5	4	0

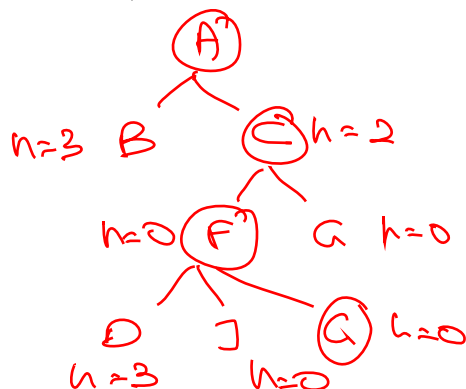
Assume that each algorithm re-generates states that are not yet expanded, does not re-expand states, breaks ties in lexicographical ordering, and terminates after expanding the goal state.

*Note: These assumptions may differ with the operations of some of the algorithms in the textbook.*

- (a) [5 pts] What is the order of state expansions if you used Greedy Best-First Search?  
(If state  $A$  is expanded before state  $B$ , which is expanded before state  $C$ , then write " $A, B, C$ ".)

What path would the algorithm return?

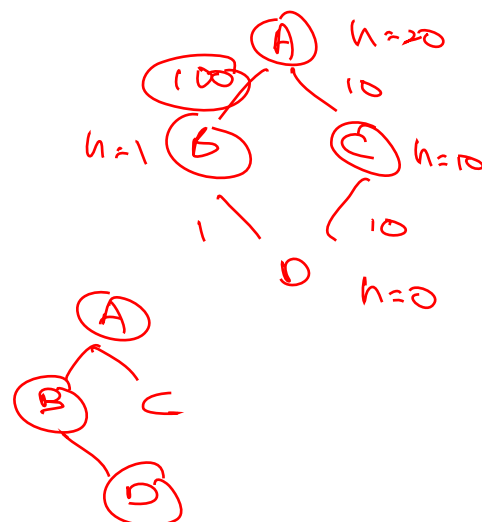
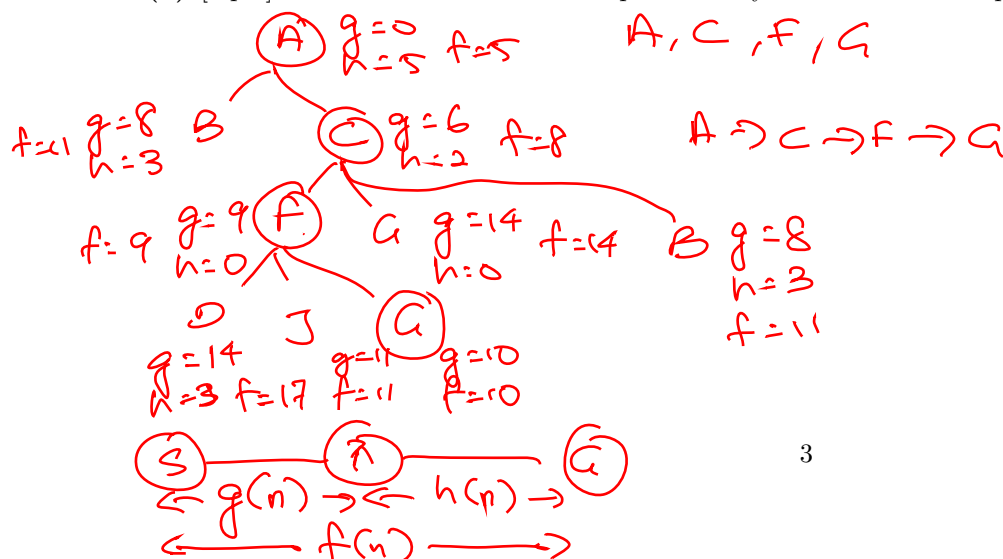
(If the path is from state  $A$  to state  $B$  to state  $C$ , then write " $A \rightarrow B \rightarrow C$ ".)



$A, C, F, G$

$A \rightarrow C \rightarrow F \rightarrow G$

- (b) [5 pts] What is the order of state expansions if you used A\*? What path would the algorithm return?

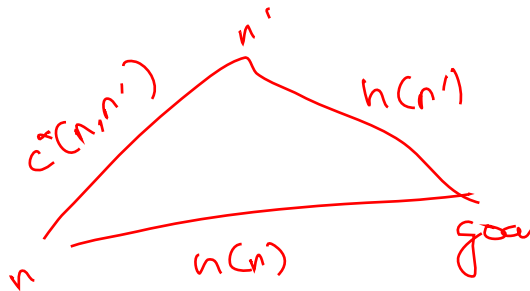


- (c) Each question is worth 1 point. Leaving a question blank is worth 0 points. **Answering a question incorrectly is worth -1 point.** This gives you an expected value of 0 for random guessing.
- (i) [1 pt] [~~true~~ or ~~false~~] With the same tie-breaking criteria, uniform-cost search will always expand more nodes than A\* search.
  - (ii) [1 pt] [~~true~~ or ~~false~~] With the same tie-breaking criteria, greedy best-first search will always expand more nodes than A\* search.
  - (iii) [1 pt] [~~true~~ or ~~false~~] The heuristic  $h(n) = 0$  is admissible for every search problem with non-negative costs.
  - (iv) [1 pt] [~~true~~ or ~~false~~] The heuristic  $h(n) = 0$  is consistent for every search problem with non-negative costs.
  - (v) [1 pt] [~~true~~ or ~~false~~] A\* search with an admissible and consistent heuristic is correct and complete without re-generating and re-expanding nodes.
  - (vi) [1 pt] [~~true~~ or ~~false~~] A\* search with an admissible but inconsistent heuristic is correct and complete without re-generating and re-expanding nodes.
  - (vii) [1 pt] [~~true~~ or ~~false~~] A\* search with an admissible but inconsistent heuristic is correct and complete when it re-generates and re-expands nodes.

$$h(n) \leq c^*(n, \text{goal})$$

$$\begin{cases} 0 < c^*(n, \text{goal}) & \text{if } n \neq \text{goal} \\ 0 = c^*(\text{goal}, \text{goal}) \end{cases}$$

$$\hookrightarrow c^*(n, \text{goal}) \geq 0 = h(n)$$



$$\Rightarrow h(n) \leq \overbrace{c^*(n, n')}^{\geq 0} + \overbrace{h(n')}^0 \Leftarrow ?$$

$$\Rightarrow h(\text{goal}) = 0 \Leftarrow$$

$$h(n) = c^*(n, \text{goal})$$