The stress tensor in the APW based methods and its implementation in the WIEN2k code.



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Outline

- Stress tensor and its importance
- Theoretical explanation
- Results
- Discussion and Outlook





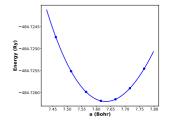
Why is stress $(\sigma_{\alpha\beta})$ so important for solid state DFT?

• Stress tensor: derivative of E with respect to strain

$$\Omega \sigma_{\alpha\beta} \equiv \frac{\partial E}{\partial \epsilon_{\alpha\beta}} \Big|_{\epsilon=0}$$
 $\alpha, \beta = 1, 2, 3$

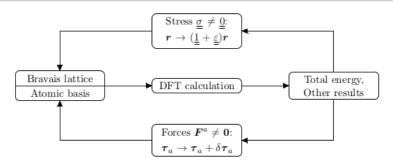
Structure optimization:

- **cubic** solid \Rightarrow only Ω -dependence \Rightarrow easy.
- * perform DFT calculations for a number of volumes V_i
- * fit resulting energies $E_i(\Omega_i)$ to EOS(Murnaghan, Birch Murnaghan, Vinet, ...)



- **tetragonal** solid ⇒ expensive but still feasible.
 - ① for each volume Ω_i : perform a series of DFT calculations to determine the c_i/a_i for which E_i is minimal
 - ② fit resulting E_i and Ω_i to EOS
 - ullet perform final volume optimization for resulting volume $\Omega(P)$ at prescribed pressure P.
- symmetry lower than tetragonal, hexagonal or rhombohedral: possible variations in all six independent components of $\epsilon_{\alpha\beta}$ must be considered \Rightarrow extremely tedious, computationally expensive or even impossible.

Determining the equilibrium state from DFT



- Solid need to relax not only forces $(F^a = -\frac{dE}{dR_a})$ but also determine equilibrium **lattice vectors** at a prescribed external stress $\sigma_{\alpha\beta}$.
- We are looking for the specific unit cell dimensions for which

$$\Omega \sigma_{\alpha\beta} \equiv \frac{\partial E}{\partial \epsilon_{\alpha\beta}}\Big|_{\epsilon=0} \qquad \alpha, \beta = 1, 2, 3$$

In most practical cases stress will be hydrostatic, so we search for a unit cell geometry for which



$$-3\Omega P \delta_{\alpha\beta} \equiv \frac{\partial E}{\partial \epsilon_{\alpha\beta}} \Big|_{\epsilon=0}$$



Review of previous attempts

• For plane wave based methods stress tensor implementation is already available(o. H. Nielsen & R.M. Martin Phys. Rev. Lett. 50 (1983) 697)

many attempts on the full-potential linearized augmented plane-wave (LAPW)

- Thonhauser, Singh & Draxl [1]
 - + only LDA for simple cubic systems
 - missing GGA, APW+lo, and semi core local orbitals.
- Nagasako & Oguchi [2]
 - + LDA and GGA
 - no LOs, no follow-up papers
 - applies to Solar-William LAPW only and can not be applied to the standard LAPW.
- Klüppelberg & Blügel [3]
 - + extensive analytical calculations are presented
 - calculation has a huge error and the source is untraceable
 - only LDA, no LOs, GGA, APW+lo

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1 Solid state comm. 124, 275 (2002)
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³ diploma thesis, Jülich (2012)

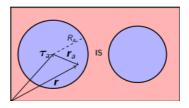




² J. Phys. Soc. Jpn. **80**, 024701 (2011)

Basis function in the APW based methods

• Unit cell is divided into the atomic spheres and the interstitial region.



Basis functions in the augmented plane wave (APW) method [Slater 1937].

$$\phi_{kK}^{APW}(\mathbf{r}) = \begin{cases} \frac{1}{\sqrt{\Omega}} e^{i(\mathbf{k} + \mathbf{K}) \cdot \mathbf{r}} & \mathbf{r} \in IS \\ \sum_{lm} a_{lm}^{akK} u_l^a(\mathbf{r}, E) Y_{lm}(\hat{\mathbf{r}}) & \mathbf{r} \in R_a \end{cases}$$

- $u_i^a(r, E)$ is the numerical solution of the radial Schrödinger equation with the spherically symmetric potential (V_{00}) at the eigenenergy E
- This leads to a non-linear eigenvalue problem and a computationally very expensive process.
- Energy dependency of $u_i^a(r, E)$ needs to be linearized

Basis function: LAPW and APW+lo

 Linearization inside the atomic sphere is introduced by choosing a linear combination of $u_i^a(r, E_i^a)$ at a fixed energy E_i^a and it's energy derivative $\dot{u}_{I}^{a}(r, E_{I}^{a})$ in linearized augmented plane wave (LAPW)[Anderson 1975].

$$\phi_{\mathbf{k}\mathbf{K}}^{LAPW}(\mathbf{r}) = \begin{cases} \frac{1}{\sqrt{\Omega}} e^{i(\mathbf{k} + \mathbf{K}) \cdot \mathbf{r}} & \mathbf{r} \in IS \\ \sum_{lm} \left[a_{lm}^{a\mathbf{k}\mathbf{K}} u_{l}^{a}(\mathbf{r}, E_{l}^{a}) + b_{lm}^{a\mathbf{k}\mathbf{K}} \dot{u}_{l}^{a}(\mathbf{r}, E_{l}^{a}) \right] Y_{lm}(\hat{\mathbf{r}}) & \mathbf{r} \in R_{a} \end{cases}$$

- a_{lm}^{akK} and b_{lm}^{akK} ensure the continuity of the value and slope of the basis functions.
- Another linearization scheme: the APW plus local orbital (APW+lo) method [E. Sjöstedt et. al 2000], where an APW basis is defined at a fixed energy E_i and the energy dependency is linearized by a set of local orbitals (lo).

$$\phi_{lo}^{a}(\mathbf{r}) = \begin{cases} 0 & \mathbf{r} \in \mathit{IS} \\ \left[a_{l,lo}^{a} u_{l,lo}^{a}(r, E_{l}^{a}) + b_{l,lo}^{a} \dot{u}_{l,lo}^{a}(r, E_{l}^{a}) \right] Y_{L}(\hat{\mathbf{r}}), & \mathbf{r} \in R_{a} \end{cases}$$

 Additional basis, the so-called LOs, only to chemically important I are added to describe the semi core states ($E_{l,LO}^a$) [Singh 1991].





Total energy in Kohn-Sham DFT

ullet One-electron Kohn-Sham equation is solved with $V_{ ext{eff}}(m{r}) = V_{ ext{C}}(m{r}) + \mu_{ ext{xc}}(m{r})$

$$[-\frac{1}{2}\nabla^2 + V_{\text{eff}}(\mathbf{r})]\psi_{\upsilon\mathbf{k}}(\mathbf{r}) = \epsilon_{\upsilon\mathbf{k}}\psi_{\upsilon\mathbf{k}}(\mathbf{r})$$

• For a given the charge density $\rho(r)$, the total energy per unit cell volume is

$$E = E_{kin} + E_{es} + E_{xc}$$

$$= \sum_{vk} n_{vk} \epsilon_{vk} - \int_{\Omega} d^3 r \ \rho(\mathbf{r}) V_{eff}(\mathbf{r}) + \frac{1}{2} \int_{\Omega} d^3 r \ \rho(\mathbf{r}) V_{C}(\mathbf{r}) - \frac{1}{2} \sum_{a \in \Omega} Z_a V_M^a(\tau_a)$$

$$+ \int_{\Omega} d^3 r \rho(\mathbf{r}) \epsilon_{xc}(\mathbf{r})$$

* $\mu_{xc}(\mathbf{r}) \stackrel{\mathsf{LDA}}{=} \frac{d}{d\rho} [\rho \epsilon_{xc}(\mathbf{r})]$ and for GGA, $\epsilon_{xc}(\mathbf{r}) \equiv \epsilon_{xc}(\rho, \nabla \rho)$



Effect of strain in the total energy

- A system is in an initial state with the total energy E_0 and the volume Ω_0 .
- An infinitesimal amount of strain $\underline{\epsilon}$ is applied, so that it is no longer in its initial state (E_0,Ω_0) .
- Total energy of the deformed system, $E[\underline{\epsilon}]$, is expanded around the initial state E_0 with a Taylor series expansion.

$$E[\underline{\underline{\epsilon}}] = E_0 + \Omega_0 \sum_{lpha,eta=1}^3 \sigma_{lphaeta}\epsilon_{lphaeta} + \mathcal{O}(\epsilon^2)$$

- $\bullet \ \, \text{Stress tensor} \,\, \sigma_{\alpha\beta} = \frac{1}{\Omega_0} \frac{\partial {\it E}[\underline{\bf e}]}{\partial \epsilon_{\alpha\beta}} \bigg|_{\underline{\underline{\bf e}}=0}$
- $E[\underline{\epsilon}] = \sum_{\mathbf{v}\mathbf{k}} n_{\mathbf{v}\mathbf{k}}[\underline{\epsilon}] \epsilon_{\mathbf{v}\mathbf{k}}[\underline{\epsilon}] \int_{\Omega[\underline{\epsilon}]} d^3 r_{\epsilon} \ \rho[\underline{\epsilon}](\mathbf{r}[\underline{\epsilon}]) V_{eff}[\underline{\epsilon}](\mathbf{r}[\underline{\epsilon}]) + \frac{1}{2} \int_{\Omega[\underline{\epsilon}]} d^3 r_{\epsilon} \ \rho[\underline{\epsilon}](\mathbf{r}[\underline{\epsilon}]) V_{C}[\underline{\epsilon}](\mathbf{r}[\underline{\epsilon}]) \frac{1}{2} \sum_{a \in \Omega} Z_a V_M^a[\underline{\epsilon}](\tau_a[\underline{\epsilon}]) + \int_{\Omega[\underline{\epsilon}]} d^3 r_{\epsilon} \rho[\underline{\epsilon}](\mathbf{r}[\underline{\epsilon}]) \epsilon_{xc}[\underline{\epsilon}](\mathbf{r}[\underline{\epsilon}])$

Frequently used mathematical relationship

- Strain derivative of vectors and volume
 - * A vector r changes as $r \to r[\underline{\epsilon}] = (\underline{1} \pm \underline{\epsilon})r$; + or is for the direct or the reciprocal lattice and the unit cell volume changes as $\Omega \to \Omega[\underline{\epsilon}] = \det(\underline{1} + \underline{\epsilon})\Omega$.

$$\frac{d\mathbf{r}[\underline{\underline{\epsilon}}]}{d\epsilon_{\alpha\beta}}\Big|_{\underline{\underline{\epsilon}}=0} = \pm \frac{r}{2}(\widehat{\mathbf{r}}_{\alpha}\widehat{\mathbf{e}}_{\beta} + \widehat{\mathbf{r}}_{\beta}\widehat{\mathbf{e}}_{\alpha}) = \pm r\widehat{\mathbf{r}}_{\alpha}\widehat{\mathbf{r}}_{\beta}$$

$$\frac{d\Omega[\underline{\underline{\epsilon}}]}{d\epsilon_{\alpha\beta}}\Big|_{\underline{\epsilon}=0} = \delta_{\alpha\beta}\Omega$$

- * The unit vector component \hat{r}_{α} along Cartesian direction α can be expanded as $\hat{r}_{\alpha} = \sum_{t=-1}^{1} c_{\alpha t} Y_{1t}(\hat{r})$.
- * The product of two spherical harmonics is expanded into Gaunt numbers times another spherical harmonics i.e.

$$Y_{1t}(\hat{r})Y_{lm}(\hat{r}) = \sum_{s,\nu} G_{s,1,l}^{\nu,t,m} Y_{s,\nu}(\hat{r})$$

• The gradient component of the spherical harmonics, $\partial_{\alpha} Y_{lm}(\hat{r})$, in the atomic spheres is computed as



$$\partial_{\alpha} Y_{lm}(\hat{\boldsymbol{r}}) = \frac{1}{r} \sum_{s=+1}^{r} \sum_{t=-1}^{1} c_{\alpha}^{st}(l,m) Y_{l+s,m+t}(\hat{\boldsymbol{r}})$$



Strain variation of the total integration

- Strain derivative of integrals over the unit cell volume
 - **1** A generic integral over the unit cell $\int_{\Omega} d^3 r F(r)$ of an arbitrary function F(r), which in practice is the charge density times potential or some other real quantity. In stress calculation

$$\frac{d}{d\epsilon_{\alpha\beta}} \left| \underline{\underline{\epsilon}} = 0 \int_{\Omega[\underline{\underline{\epsilon}}]} d^3 r_{\epsilon} F[\underline{\underline{\epsilon}}](r_{\epsilon}) = \frac{d}{d\epsilon_{\alpha\beta}} \left| \underline{\underline{\epsilon}} = 0 \det(\underline{\underline{1}} + \underline{\underline{\epsilon}}) \int_{\Omega} d^3 r F[\underline{\underline{\epsilon}}](r[\underline{\underline{\epsilon}}]) = \delta_{\alpha\beta} \int_{\Omega} d^3 r F(r) + \int_{\Omega} d^3 r \frac{dF[\underline{\underline{\epsilon}}](r[\underline{\underline{\epsilon}}])}{d\epsilon_{\alpha\beta}} \right| \underline{\underline{\epsilon}} = 0$$

smeared argument $r[\underline{\epsilon}]$,

$$\frac{dF[\underline{e}](r[\underline{e}])}{d\epsilon_{\alpha\beta}}\bigg|_{\underline{\underline{e}}=0} = \frac{dF[\underline{e}](r)}{d\epsilon_{\alpha\beta}}\bigg|_{\underline{\underline{e}}=0} + \frac{dr[\underline{e}]}{d\epsilon_{\alpha\beta}}\bigg|_{\underline{\underline{e}}=0} \cdot \nabla F(r)$$

With these relationship, the strain variation of an integral over the unit cell volume becomes

$$\frac{d}{d\epsilon_{\alpha\beta}}\Big|_{\stackrel{\epsilon}{=}0} \int_{\Omega[\epsilon]} d^3r_{\epsilon} F[\underline{\epsilon}](r_{\epsilon}) = \delta_{\alpha\beta} \int_{\Omega} d^3r F(r) + \int_{\Omega} d^3r \frac{dF[\underline{\epsilon}](r)}{d\epsilon_{\alpha\beta}}\Big|_{\stackrel{\epsilon}{=}0} + \frac{1}{2} \int_{\Omega} d^3r (r_{\beta} \partial_{\alpha} + r_{\alpha} \partial_{\beta}) F(r)$$





Total stress tensor in the APW based methods

$$\sigma_{\alpha\beta} = \frac{1}{\Omega} \frac{dE[\underline{\epsilon}]}{d\epsilon_{\alpha\beta}} \Big|_{\underline{\epsilon}=0} \\
= \sigma_{\alpha\beta}^{\text{val},kin} + \delta_{APW} \sigma_{\alpha\beta}^{APW} + \sigma_{\alpha\beta}^{\text{val},corr} + \sigma_{\alpha\beta}^{\text{core},corr} + \sigma_{\alpha\beta}^{\text{es}} + \sigma_{\alpha\beta}^{\text{xc}}$$

$$\bullet \quad \sigma_{\alpha\beta}^{\mathit{val},kin} = \frac{1}{2} \sum\nolimits_{\upsilon\mathbf{k}} {^{n}}_{\upsilon\mathbf{k}} \int_{\Omega} {^{d^{3}}} r \psi_{\upsilon\mathbf{k}}^{*}(\mathbf{r}) \bigg(\partial_{\alpha}\partial_{\beta} + \partial_{\beta}\partial_{\alpha} \bigg) \psi_{\upsilon\mathbf{k}}(\mathbf{r})$$

$$\bullet \quad \sigma_{\alpha\beta}^{APW} = \frac{1}{\Omega} \oint dS \frac{d}{d\epsilon_{\alpha\beta}} \left(\psi_{\nu k}^* \stackrel{a}{\underline{\ell}} [\underline{\underline{\ell}}] \frac{\partial \psi_{\nu k}^* [\underline{\underline{\ell}}]}{\partial r_a} - \psi_{\nu k}^* [\underline{\underline{\ell}}] \frac{\partial \psi_{\nu k}^{VS} [\underline{\underline{\ell}}]}{\partial r_a} \right)$$

$$\bullet \quad \sigma_{\alpha\beta}^{\mathit{val},\mathit{corr}} = \frac{2}{\Omega} \sum\nolimits_{\mathit{vk}} {n_{\mathit{vk}}} \Re \left\langle \frac{d\psi_{\mathit{vk}}[\underline{e}][\underline{e}](r[\underline{e}])}{d\epsilon_{\alpha\beta}} \right|_{\underline{e}=0} |\widehat{H}_{\mathit{eff}}(r) - \epsilon_{\mathit{vk}}|\psi_{\mathit{vk}}(r) \right\rangle$$

$$\bullet \quad \sigma_{\alpha\beta}^{\text{core,corr}} = -\frac{1}{2\Omega} \sum\nolimits_{a \in \Omega} \int_{R_{a}} d^{3}\mathbf{r}_{a}\rho_{c}^{a}(\mathbf{r}_{a}) \left(\mathbf{r}_{a\alpha}\,\partial_{\beta} + \mathbf{r}_{a\beta}\,\partial_{\alpha}\right) V_{\text{eff}}^{a}(\mathbf{r}_{a})$$

$$\bullet \quad \sigma_{\alpha\beta}^{\text{es}} = -\frac{\delta_{\alpha\beta}}{\Omega} \int_{\Omega} d^{3}\mathbf{r} \rho(\mathbf{r}) V_{C}(\mathbf{r}) + \frac{1}{2\Omega} \frac{d}{d\epsilon_{\alpha\beta}} \left| \underbrace{\underline{\underline{\epsilon}}}_{\underline{\underline{\epsilon}} = 0} \int_{\Omega[\underline{\underline{\epsilon}}]} d^{3}\mathbf{r}_{\epsilon} \rho((\underbrace{\underline{1}}_{\underline{\underline{\epsilon}}} - \underline{\underline{\epsilon}})\mathbf{r}_{\epsilon}) V_{C}[\underline{\underline{\epsilon}}](\mathbf{r}_{\epsilon}) - \frac{1}{2\Omega} \sum_{a \in \Omega} Z_{a} \frac{d}{d\epsilon_{\alpha\beta}} \left| \underbrace{\underline{V}_{a}^{a}[\underline{\underline{\epsilon}}](\mathbf{r}_{a}[\underline{\underline{\epsilon}}])}_{\underline{\underline{\epsilon}} = 0} V_{\underline{A}}^{a}[\underline{\underline{\epsilon}}](\mathbf{r}_{a}[\underline{\underline{\epsilon}}]) \right|$$

$$\bullet \ \ \sigma^{\mathrm{xc}}_{\alpha\beta} = \frac{\delta_{\alpha\beta}}{\Omega} \int_{\Omega} d^3r \rho(\mathbf{r}) \bigg(\epsilon_{\mathrm{xc}}(\rho(\mathbf{r})) - \mu_{\mathrm{xc}}(\rho(\mathbf{r})) \bigg) \\ - \frac{2\delta_{GGA}}{\Omega} \int_{\Omega} d^3r \rho(\mathbf{r}) \partial_{\alpha} \rho(\mathbf{r}) \partial_{\beta} \rho(\mathbf{r}) \frac{\partial \epsilon_{\mathrm{xc}}}{\partial \sigma} \bigg) d^3r \rho(\mathbf{r}) \partial_{\alpha} \rho(\mathbf{r}) \partial_{\beta} \rho(\mathbf{r}) \partial_{\beta}$$





Results

 The results of the stress tensor are compared with the least square fit of total energy vs volume using the Birch-Murnaghan (BM) equation of state.

$$\textit{E}_{\textit{BM}}(\Omega) = \textit{E}_0 + \frac{9\Omega_0\textit{B}_0}{16} \Bigg(\Big[\Big(\frac{\Omega}{\Omega_0}\Big)^{\frac{2}{3}} - 1 \Big]^{3} \textit{B}_0' + \Big[\Big(\frac{\Omega}{\Omega_0}\Big)^{\frac{2}{3}} - 1 \Big]^{2} \Big[6 - 4 \Big(\frac{\Omega}{\Omega_0}\Big)^{\frac{2}{3}} \Big] \Bigg)$$

• With $E_{BM}(\Omega)$ we define the numerical pressure $P^{(E)}$

$$P^{(E)}(\Omega) = -\frac{\partial E_{BM}(\Omega)}{\partial \Omega}$$

• $P^{(E)}(\Omega)$ is compared to one third of the negative trace of the full stress tensor $P^{(\sigma)}(\Omega)$

$$P^{(\sigma)}(\Omega) = -rac{1}{3}\sum_{lpha}\sigma_{lphalpha} = -rac{1}{3}\Big(\sigma_{11}+\sigma_{22}+\sigma_{33}\Big).$$

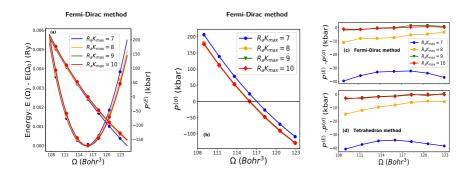
• The difference $P^{(E)}(\Omega)$ - $P^{(\sigma)}(\Omega)$ gives the accuracy of our stress tensor formalism.





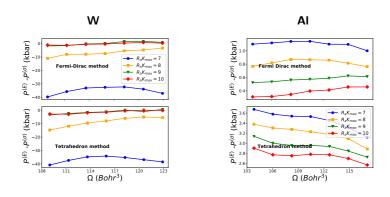
Convergence of the trace of $\sigma_{\alpha\beta}$ with R_aK_{max} for W

• (a) Energy-Volume curve as well as $P^{(E)}$, (b) $P^{(\sigma)}$ and (c) and (d) are $P^{(E)}-P^{(\sigma)}$



• $P^{(E)} - P^{(\sigma)}$ exhibits the same behavior in the tetrahedron method (d) as in the FD method (c).

Stress tensor with the FD and tetrahedron method.

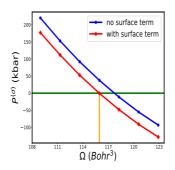


- Left panel: for W. $P^{(E)}$ $P^{(\sigma)}$ for the FD and tetrahedron method is in the same order. With $R_a K_{max} = 10$, $a_0 = 6.143$ (σ , FD), 6.143 (E, FD), 6.145 (σ , Tetra) and 6.144 (E, Tetra).
- Right panel: for Al, $P^{(E)}$ $P^{(\sigma)}$ is larger in the tetrahedron method than in the FD method. With $R_a K_{max} = 10$, $a_0 = 7.633$ (σ , FD), 7.634 (E, FD), 7.626 (σ , Tetra) and 7.635 (E, Tetra).

Importance of the surface term in APW+lo

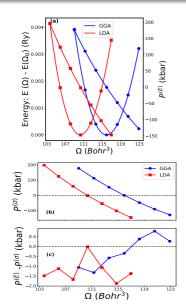
In the APW+lo method

- Basis functions are continuous but not the slope.
 - * This gives an additional surface term in the kinetic energy when calculating the total energy. $s = \oint ds \left(\psi_{vk}^{*\,a} \frac{\partial \psi_{vk}^{a}}{\partial r_{a}} \psi_{vk}^{*\,lS} \frac{\partial \psi_{vk}^{lS}}{\partial r_{a}} \right)$
 - * In stress calculation, \mathcal{S} is defined in the deformed system and differentiated with respect to strain. $\sigma_{\alpha\beta}^{APW} = \frac{1}{\Omega} \oint ds \frac{d}{d\epsilon_{\alpha\beta}} \left(\psi_{vk}^{*\,a} \underbrace{\stackrel{\partial}{\epsilon}_{\underline{l}}}_{\underline{l}} \psi_{vk}^{*\,l} \underbrace{\stackrel{\partial}{\epsilon}_{\underline{l}}}_{\underline{l}} \psi_{vk}^{*\,l} \underbrace{\stackrel{\partial}{\epsilon}_{\underline{l}}}_{\underline{l}} \right)$



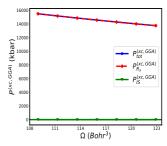
• σ_{11}^{APW} for APW+lo \sim -38 kbar and for LAPW = 0 kbar. $a_0^{(E)}=6.143$ Bohr, $a_0^{(\sigma)}=6.143$ Bohr (red curve) and 6.174 Bohr (blue curve)

Comparison between LDA and GGA for W



- Difference between $P^{(E)}$ and $P^{(\sigma)}$ is just 1-2 kbar.
- $p(E) p(\sigma)$ is smaller for GGA than LDA.
- $lackbox{0} a_0^{(\sigma)} = a_0^{(E)}$ for LDA and GGA up to three decimal place.

The additional GGA contribution is $\sigma_{\alpha\beta}^{xc,GGA} = -\frac{2\delta_{GGA}}{\Omega} \int_{\Omega} d^3r \rho(r) \partial_{\alpha} \rho(r) \partial_{\beta} \rho(r) \frac{\partial \epsilon_{XC}}{\partial \sigma}$

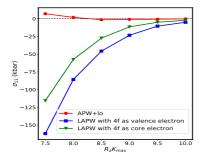


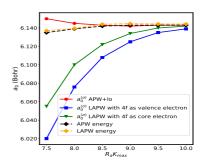
- $P_{tot}^{(\mathrm{xc,GGA})}$ is negative trace of $\sigma_{\alpha\beta}^{\mathrm{xc,GGA}}$.
- $P_{tot}^{(xc,GGA)} = P_{R_a}^{(xc,GGA)} + P_{IS}^{(xc,GGA)}$
- R_a and IS denote the atomic sphere and the interstitial region.
- $P_{R_a}^{(xc,GGA)}$ is the major constituent and $P_{IS}^{(xc,GGA)}$ is within the error limit of the calculation.

J. Phys. Soc. Jap. 82, 044701 (2013)

Comparison of convergences in APW+lo and LAPW

• Convergence of σ_{11} (left panel) and the lattice parameter (right panel) with basis set size $(R_a K_{max})$ for W.





- With APW+lo $R_a K_{max} = 8$ already gives an acceptable result, but for LAPW $R_a K_{max} = 10$ or more is required.
- Both the stress tensor and the lattice parameter in the APW+lo method converge much faster than two different LAPW cases.

Individual contributions of the stress tensor

Stress tensor

$$\sigma_{\alpha\beta} = \sigma_{\alpha\beta}^{\textit{val},\textit{kin}} + \delta_{\textit{APW}} \sigma_{\alpha\beta}^{\textit{APW}} + \sigma_{\alpha\beta}^{\textit{val},\textit{corr}} + \sigma_{\alpha\beta}^{\textit{core},\textit{corr}} + \sigma_{\alpha\beta}^{\textit{es}} + \sigma_{\alpha\beta}^{\textit{xc}}$$

• σ_{11} component of various stress tensor contributions at $\Omega = 115.94 \; Bohr^3$.

stress	APW+lo (kbar)	LAPW (kbar)
$\sigma_{11}^{\mathit{val},\mathit{kin}}$	1102905.56	1102971.88
σ_{11}^{APW}	-37.96	0.00
$\sigma_{11}^{\mathit{val},\mathit{corr}}$	45.09	20.50
$\sigma_{11}^{core,corr}$	24760504.93	24760437.09
σ^{es}_{11}	-25607153.70	-25607170.14
$\sigma_{11}^{xc,LDA}$	-241699.29	-241699.56
$\sigma_{11}^{GGA,corr}$	-14564.88	-14564.78
total	-0.25	-5.01

• Conversion from the *energy per unit volume* to *kbar* for the given volume Ω is achieved by $1\frac{Ry}{Rohr^3} = 147105.16$ kbar.

Importance of non-spherical potential in core correction

Core correction stress tensor

$$\sigma_{\alpha\beta}^{core,corr} = -\frac{1}{\Omega} \sum_{a \in \Omega} \int_{R_a} d^3 r_a \rho_c^a(\mathbf{r}_a) \frac{1}{2} (\mathbf{r}_{a\alpha} \partial_\beta + \mathbf{r}_{a\beta} \partial_\alpha) V_{eff}^a(\mathbf{r}_a)$$
(1)

- $V_{eff}^{a} \equiv V_{tot}^{c} = V_{00}^{c} + V_{2m}^{c}$
- V_{2m}^c is missing in Thonhauser *et al.* (2002)
- Effects due to the non-spherical component (I=2) in the potential exist only in non-cubic crystal structure.
- ullet For the stress tensor, its importance is confirmed with results for anatase TiO $_2$ in body center tetragonal structure.

	a ₀ (Bohr)	c ₀ (Bohr)
energy	7.181	18.309
stress with $V_{\scriptscriptstyle tot}^{\scriptscriptstyle c}$	7.181	18.307
stress with V_{00}^c	7.163	18.404

 The symmetry between the equivalent atoms has been addressed correctly and the code works also for a non-symmorphic space group.

Accuracy of individual components of the stress tensor

- Cubic silicon in the diamond structure at the equilibrium volume (pressure = 0 and $a_0 = 10.209$ Bohr).
- Lattice parameters a_0 and $b_0 = a_0 = 10.209$ Bohr are fixed but only c_0 lattice parameter varies such that $c = c_0(1+\epsilon_{33})$.
- Using a family of tetragonal deformations without volume conserving, the stress component $\sigma_{33}^{(E)}$ is calculated using $\sigma_{33}^{(E)} = \frac{1}{\Omega_0} \frac{\partial E(\epsilon_{33})}{\partial \epsilon_{33}}$ with $\epsilon_{33} = \frac{c}{c_0}$ 1 and compared with $\sigma_{33}^{(\sigma)}$

€33	$\sigma_{33}^{(E)}$	$\sigma_{33}^{(\sigma)}$
-0.020	33.12	34.28
-0.013	21.95	22.63
-0.007	10.90	11.17
0.000	0.00	0.00
0.007	-10.74	-10.99
0.013	-21.29	-21.70
0.020	-31.65	-32.16





Discussion and Outlook

- Stress tensor formalism for LAPW, APW+lo, LDA and GGA has been derived and implemented in the WIEN2k code.
- Stress tensor is accurate enough to be used for structure optimization.
- A bit larger basis set for stress calculations is needed than for total energy calculations.
- With APW+lo compared to LAPW, the stress tensor converges faster and requires a smaller value of $R_a K_{max}$.
- For metallic systems, calculations using the FD method converge faster
- Formalism and the implementation needs to be extended to the scalar relativistic kinetic energy and spin-orbit coupling.
- An automatic optimization of the lattice parameter using the stress tensor can be implemented in a similar way as the automatic optimization with force (L. D. Marks J. Chem. Theory Comput. (2021)).





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Thank you





Non linear eigenvalue problem in the APW method

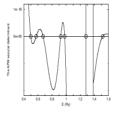


Figure 2.3: The APW determinant $\det \widetilde{T}(E) + V(E) - EC(E)$, must be evaluated for a number of energies E, in order to find the solutions to the secular equation in Eqn. (2.14). The circles indicate the eigeneregies of the valence electrons in riobium, at $\mathbf{k} = \frac{g_E}{\pi}(0.5, 0.25, 0.33)$, for a=6.236 a.u.





Why the Fermi-Dirac smearing method is better for calculating stresses

• For a system with partial occupation, the total energy discussed above is no longer variational. In such a case, the total energy must be replaced by a more general expression as given in Eq. (2). This argument is based on the force calculation and we assume that the same argument is valid for the stress tensor calculation.

$$F = E - \sum_{vk} n_{vk} \sigma S \tag{2}$$

• The derivative of the occupation number with respect to strain will be canceled with a similar expression from the entropy-like term (second term in Eq. (2)).





Linearization in the LAPW method

• Energy dependent radial function $u_l(r, E)$ of APW is expanded in LAPW.

$$u_{l}(r, E) = u_{l}(r, E_{l}^{a} + (E - E_{l}^{a}))$$

= $u_{l}(r, E_{l}^{a}) + (E - E_{l}^{a})\dot{u}_{l}(r, E_{l}^{a}) + \mathcal{O}((E - E_{l}^{a})^{2})$

- All higher order terms are neglected by assuming that the difference $E-E_i^a$ is very small.
- Linearization scheme of LAPW is able to solve the non-linear eigenvalue problem of APW but optimal shape of the basis function inside the atomic spheres is sacrificed.





Total wave function and charge density

• The linear combination of the basis functions $\phi_{\mathbf{k}\mathbf{K}}(\mathbf{r})$ are used to define the total wave function $\psi_{v\mathbf{k}}(\mathbf{r})$ for the band v and given \mathbf{k} vector

$$\psi_{v\mathbf{k}}(\mathbf{r}) = \sum_{\mathbf{K}} c_{v\mathbf{k}\mathbf{K}} \phi_{\mathbf{k}\mathbf{K}}^{(L)APW}(\mathbf{r}) + \sum_{lo} c_{v\mathbf{k},lo} \phi_{lo}^{a}(\mathbf{r}) + \sum_{LO} c_{v\mathbf{k},LO} \phi_{LO}^{a}(\mathbf{r})$$

- c_{vkK} are expansion coefficients and K is the reciprocal lattice vector such that $|K| \leq K_{\text{max}}$.
- $\psi_{vk}(r)$ are used to define the charge density as

$$\rho(\mathbf{r}) = \sum_{\mathbf{v}\mathbf{k}} n_{\mathbf{v}\mathbf{k}} \psi_{\mathbf{v}\mathbf{k}}^*(\mathbf{r}) \psi_{\mathbf{v}\mathbf{k}}(\mathbf{r})$$

ullet After simplification, $ho({m r})$ in the APW based methods can be expressed as follow

$$\rho(\mathbf{r}) = \begin{cases} \sum_{\mathbf{G}}^{G_{\text{max}}} \rho(\mathbf{G}) e^{i\mathbf{G} \cdot \mathbf{r}} & \mathbf{r} \in IR \\ \sum_{\text{LM}} \rho_{\text{LM}}(\mathbf{r}) Y_{\text{LM}}(\hat{\mathbf{r}}_{a}) & \mathbf{r} \in R_{a}, \end{cases}$$

• G_{\max} must be at least $2K_{\max}$. The total potential V(r) is expanded similar to $\rho(r)$.