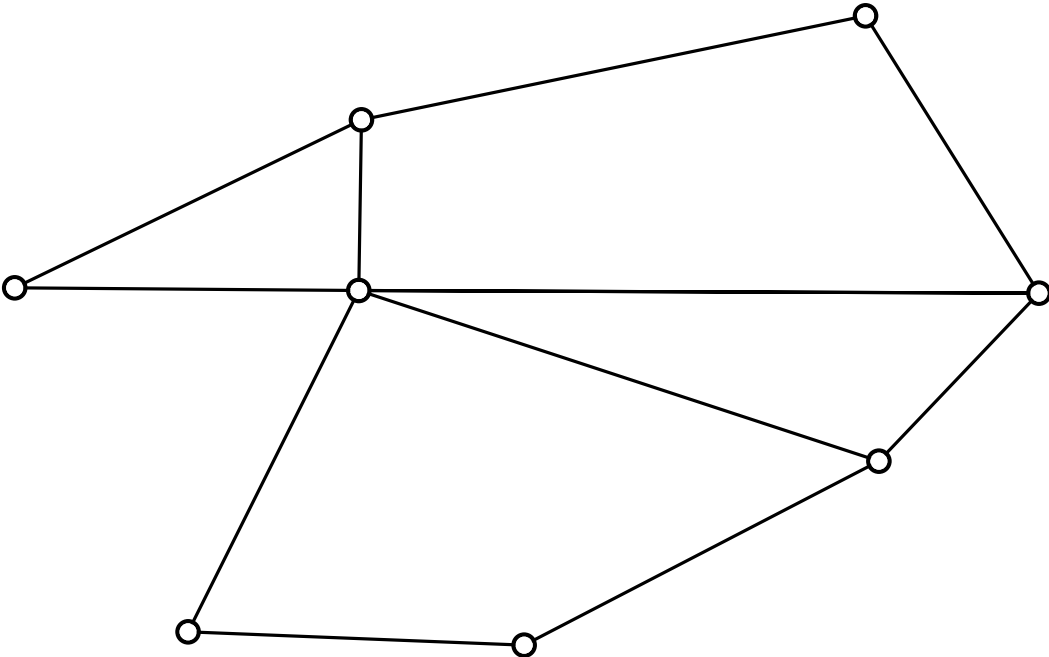


Applications of Duality

Total Unimodularity

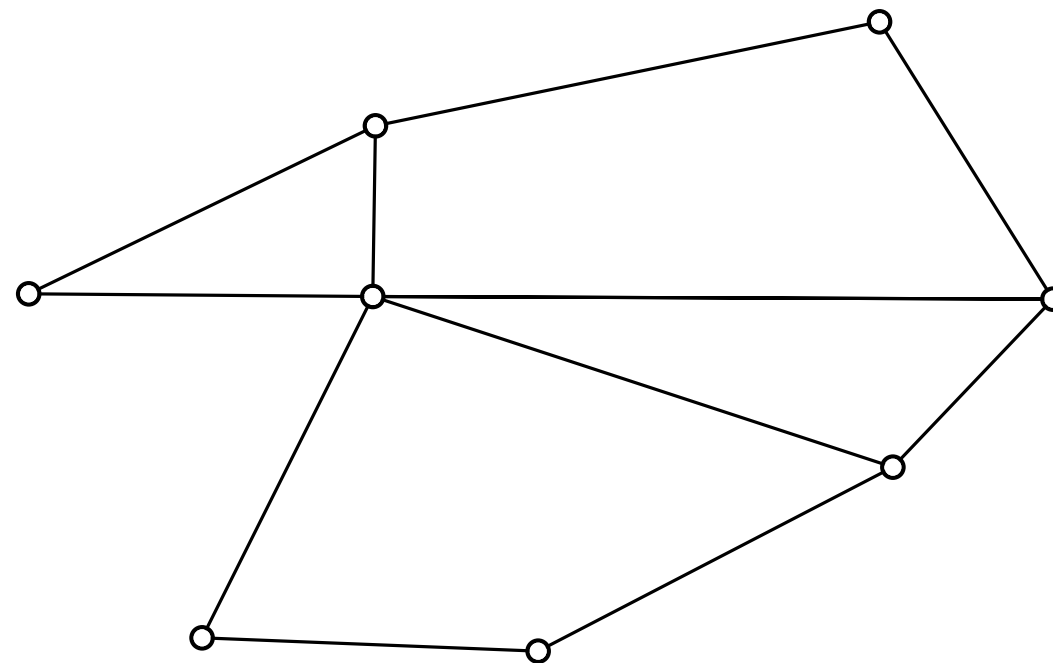
Matchings, Flows, and Shortest paths

Matchings



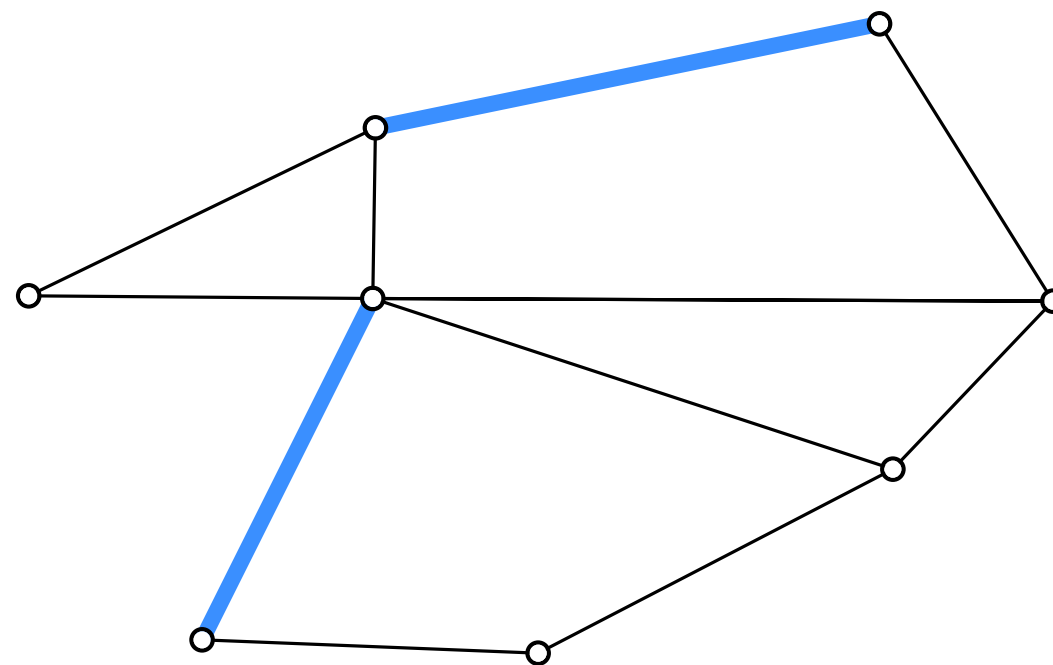
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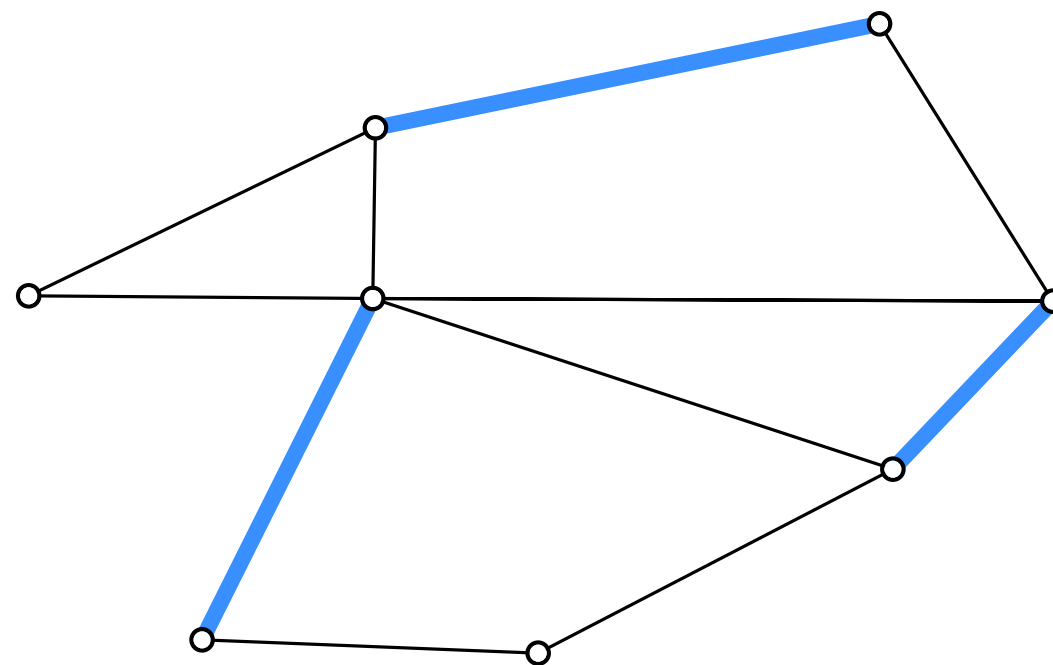
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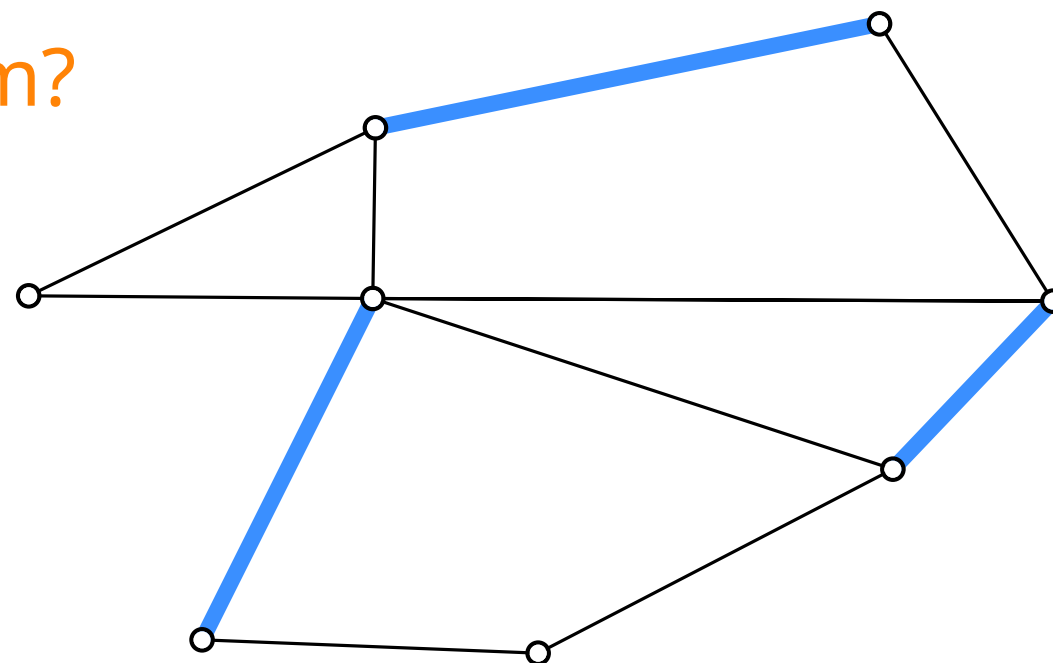
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Is this maximum?

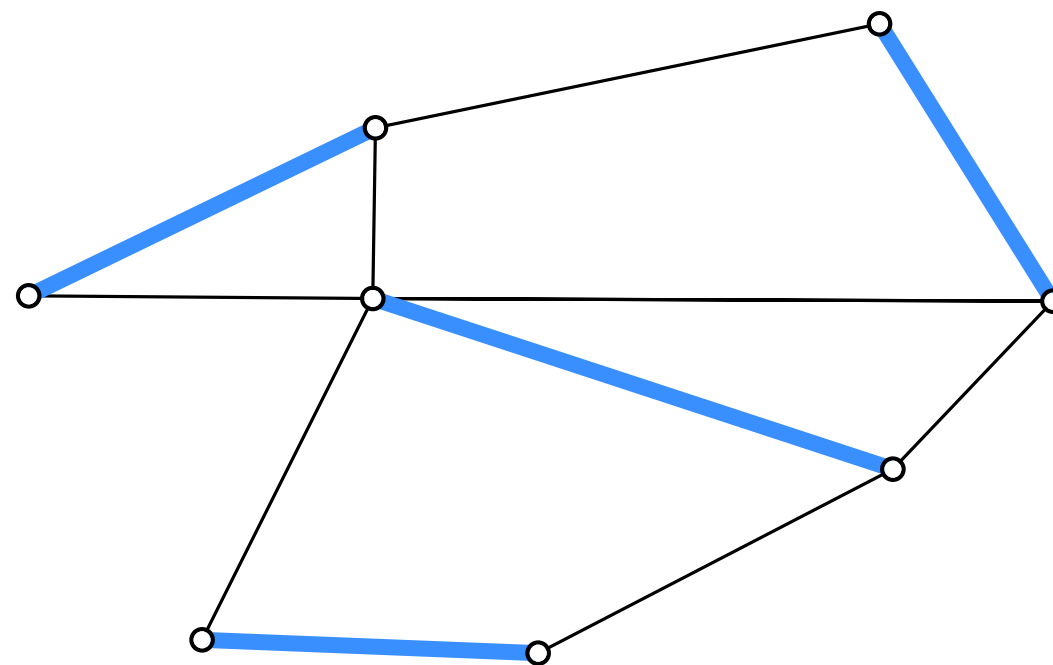


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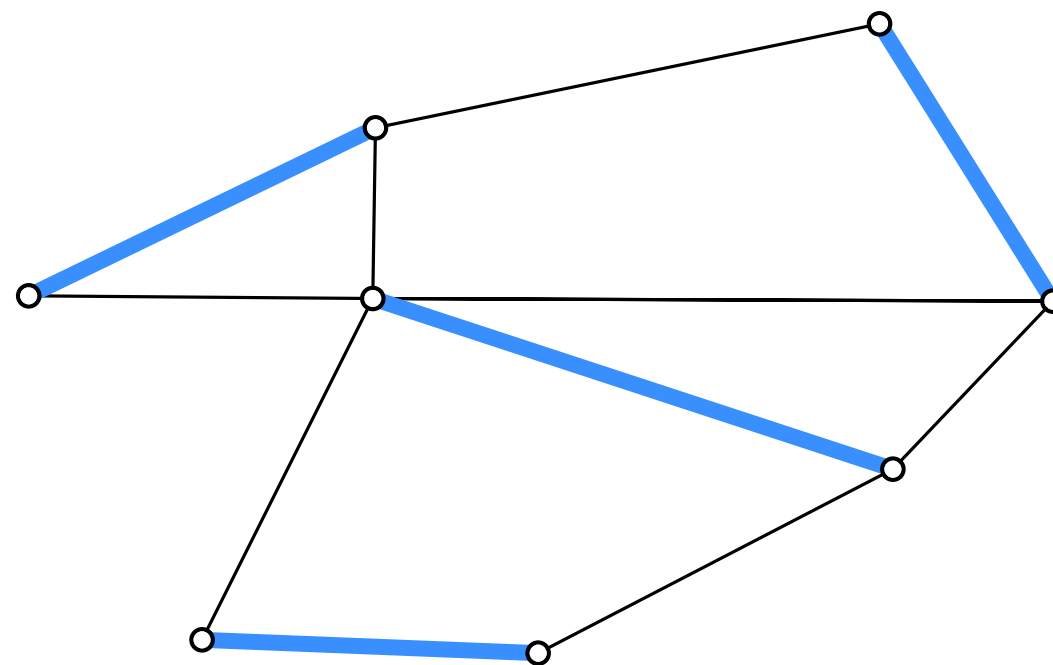
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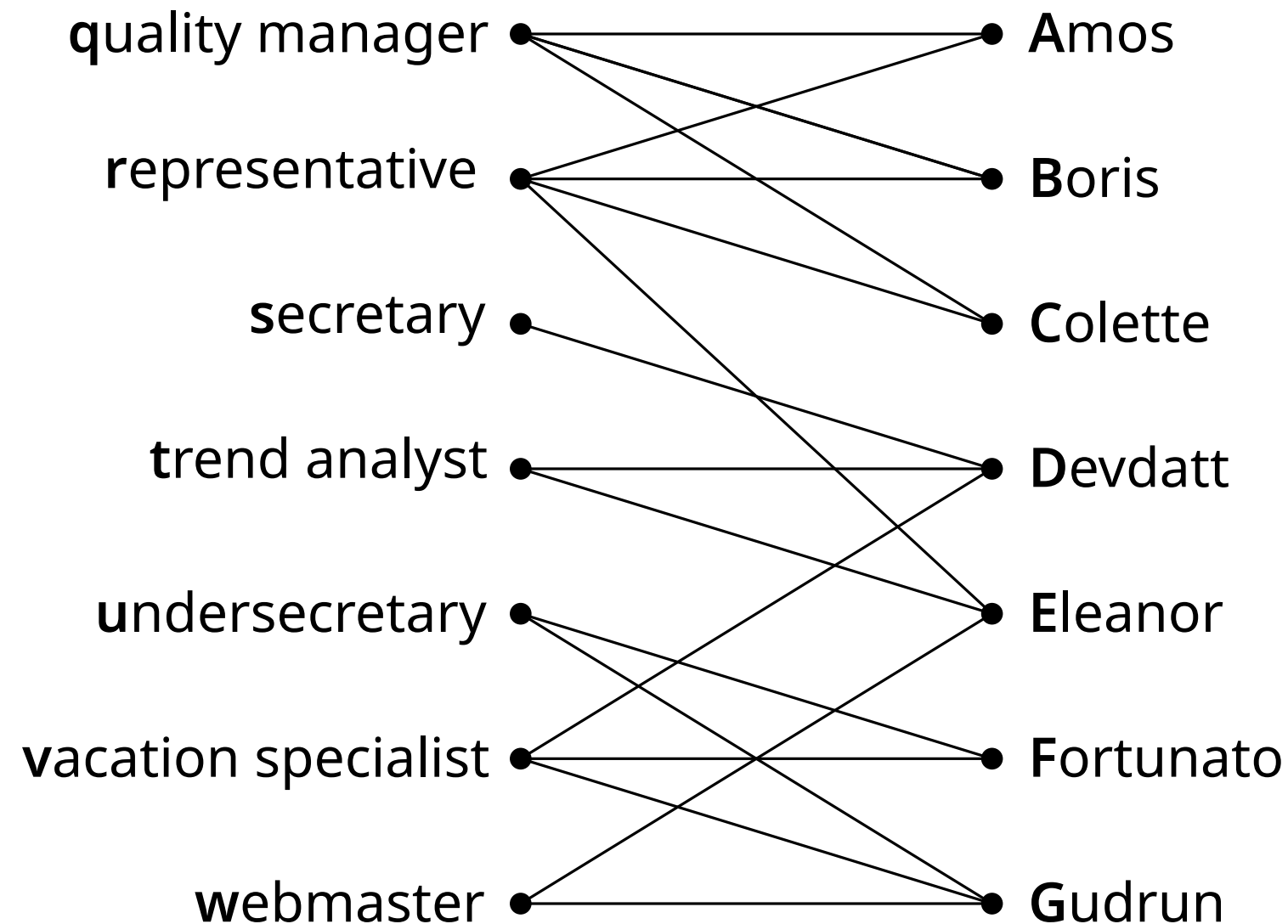
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Remark: Not every matching can be extended to a maximum one.



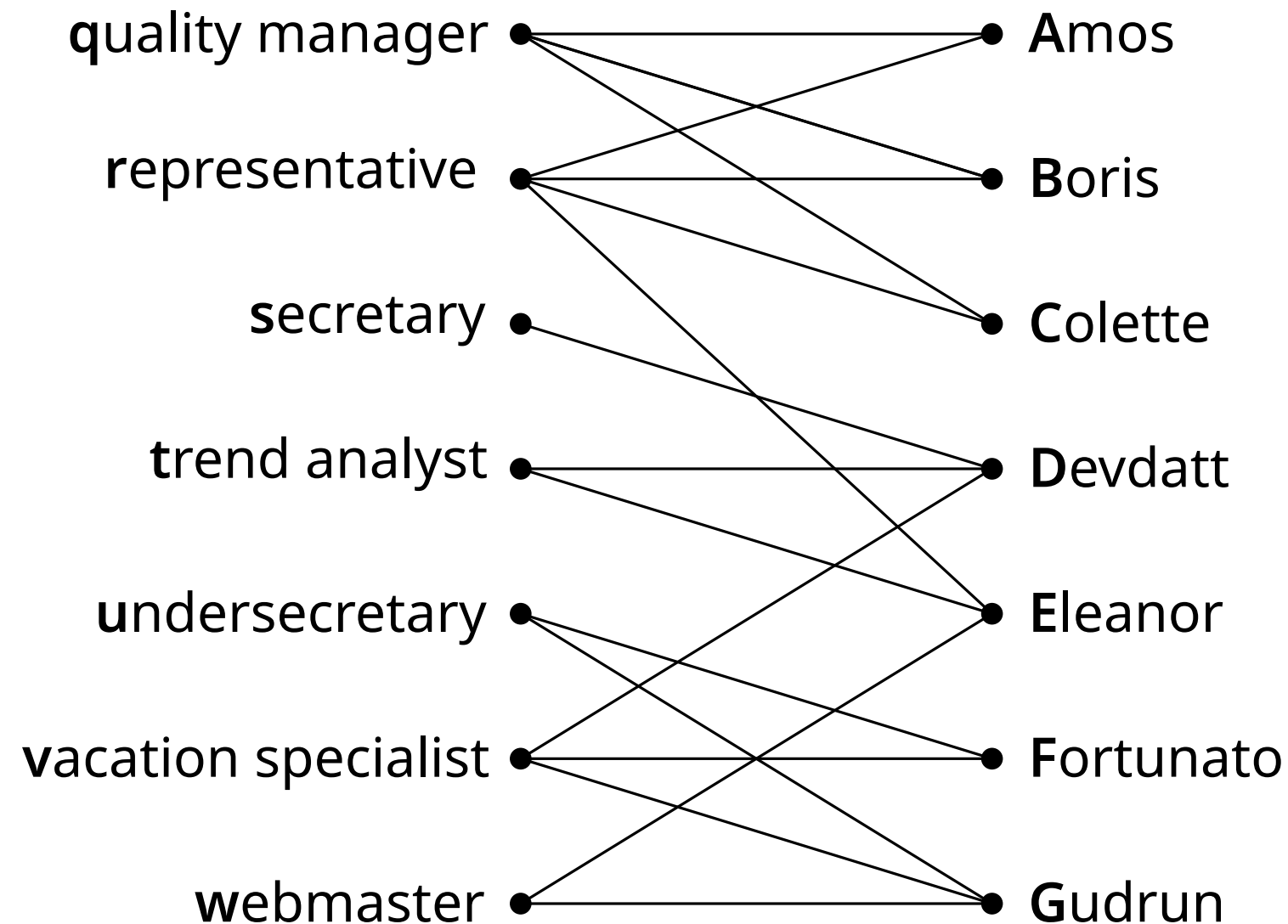
Perfect matching

A company is assigning workers to jobs. In the bipartite graph an edge connects a worker to a job they are willing to take.



Perfect matching

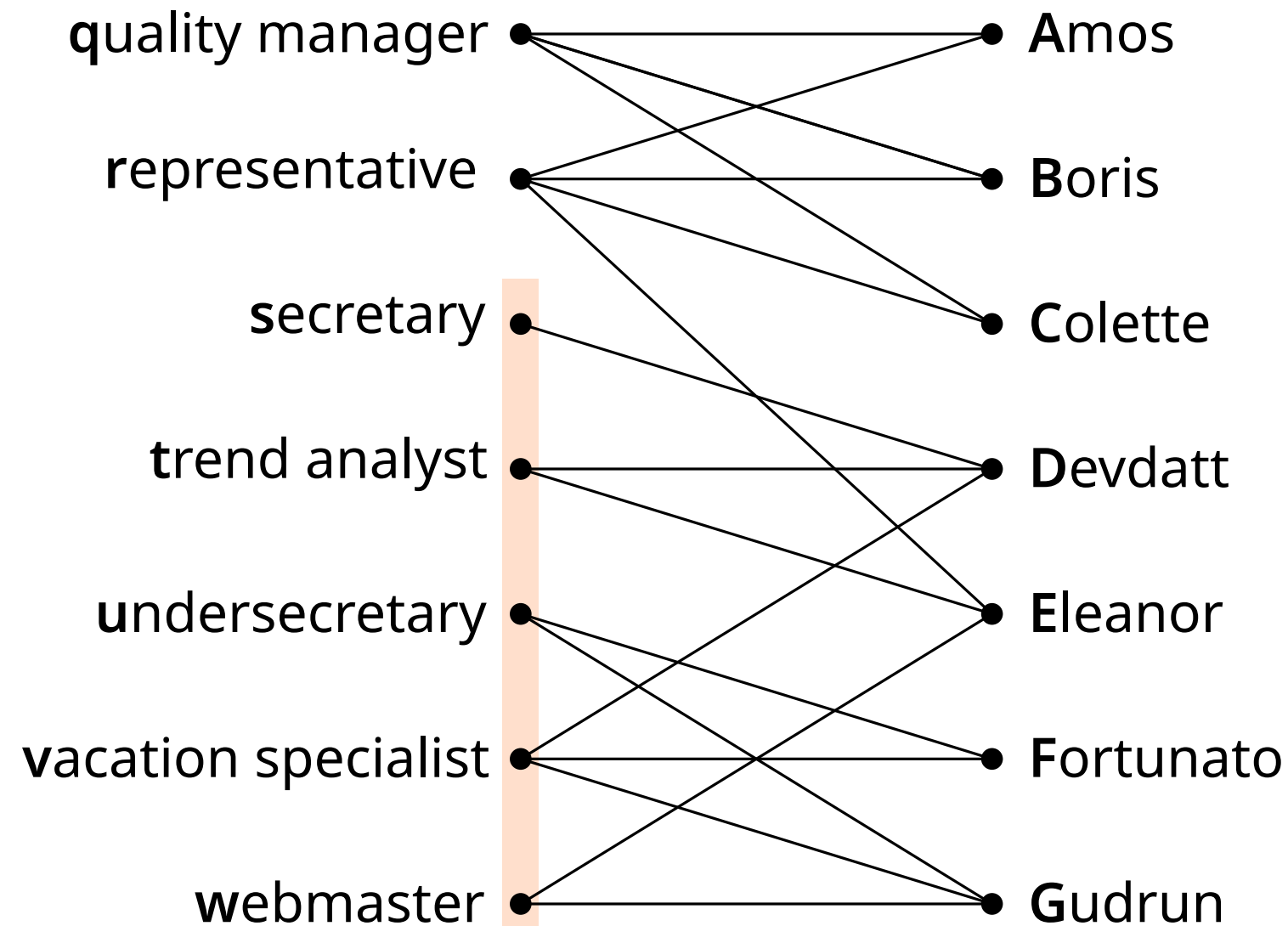
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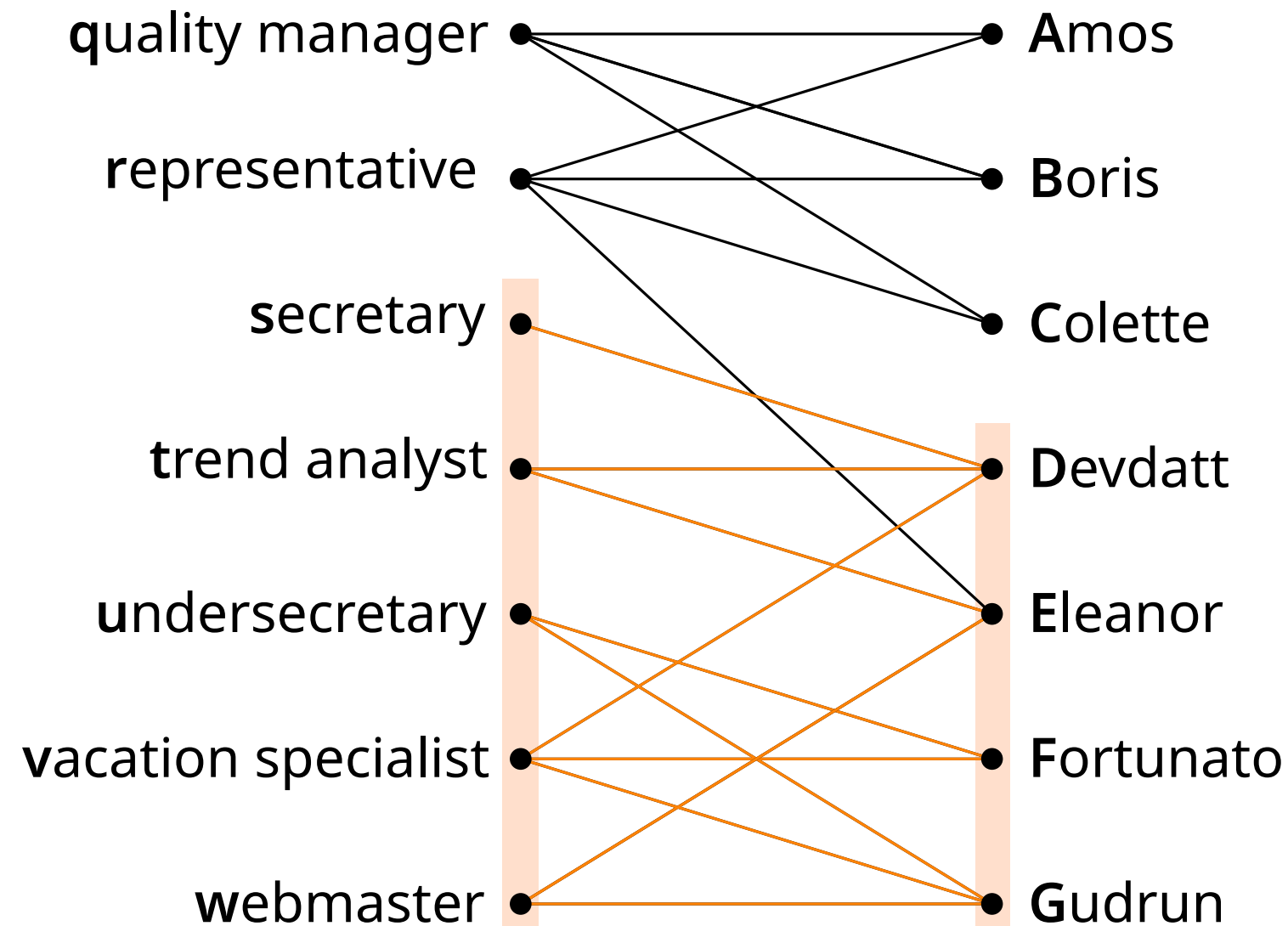


Neighborhood $\{s, t, u, v, w\} =$

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Hall's Theorem: Let G be a bipartite graph with bipartition $V = X \cup Y$.
Then G has a matching covering $X \iff |\text{Neighborhood}(X')| \geq |X'|$
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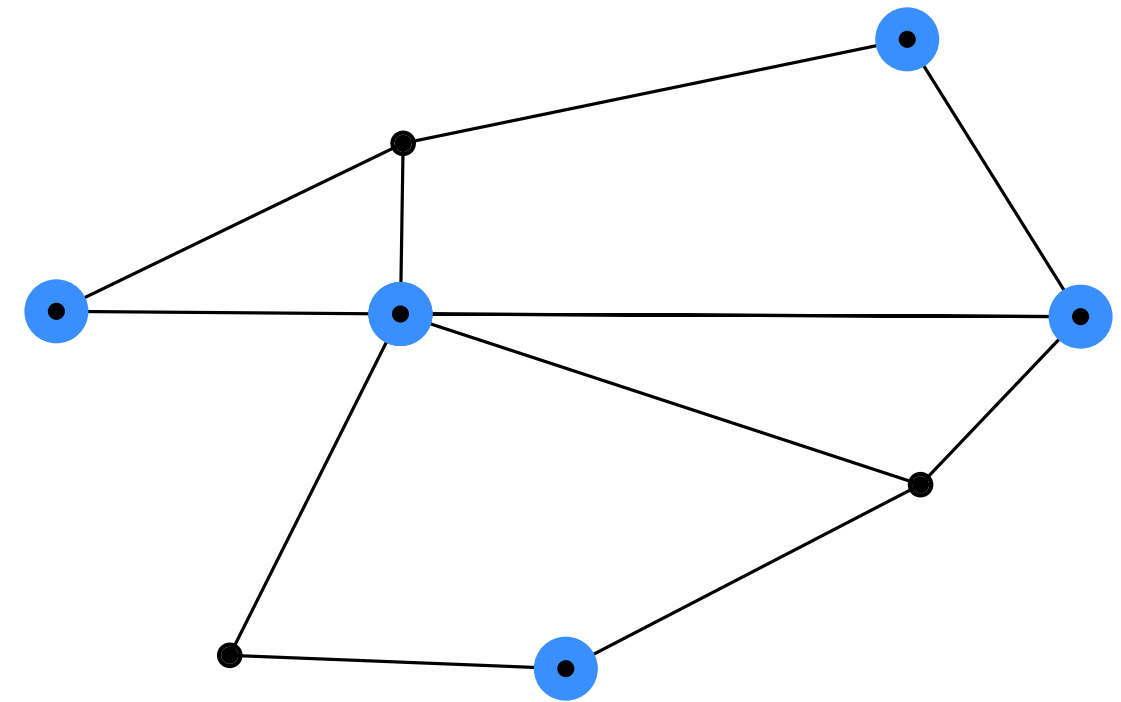
Proof: \Rightarrow is clear.

\Leftarrow will follow from König's Theorem.

Vertex Cover and König's Theorem

König's Theorem: In a bipartite graph the size of a minimum vertex cover equals the size of a maximum matching.

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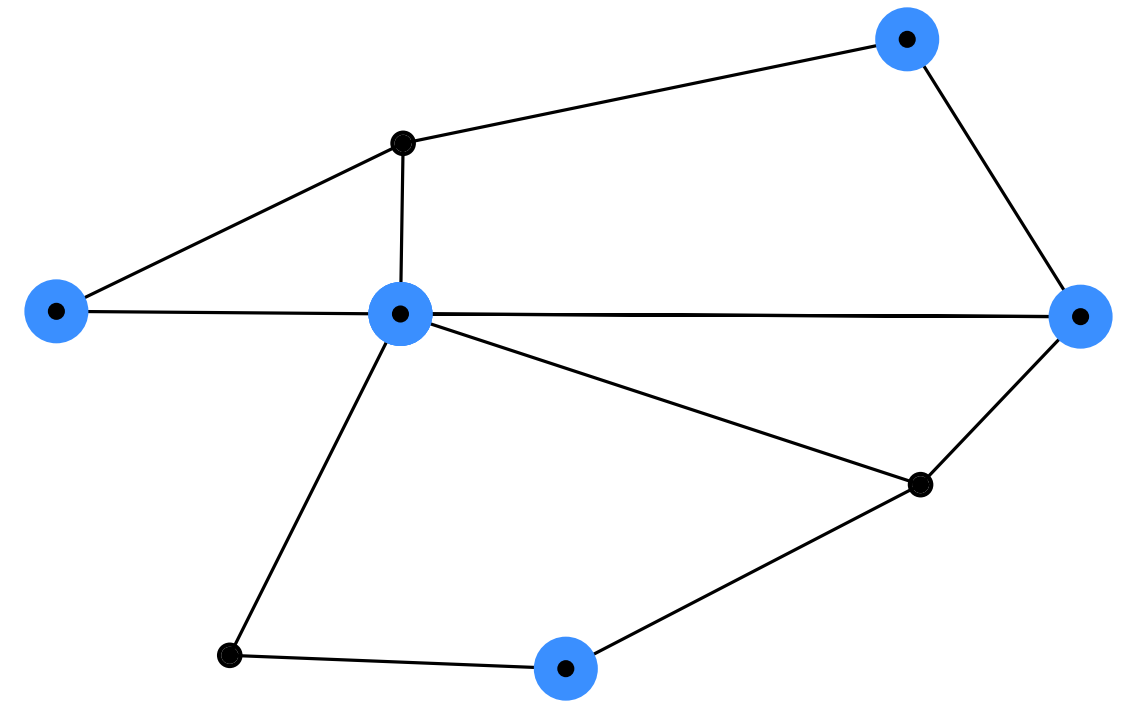


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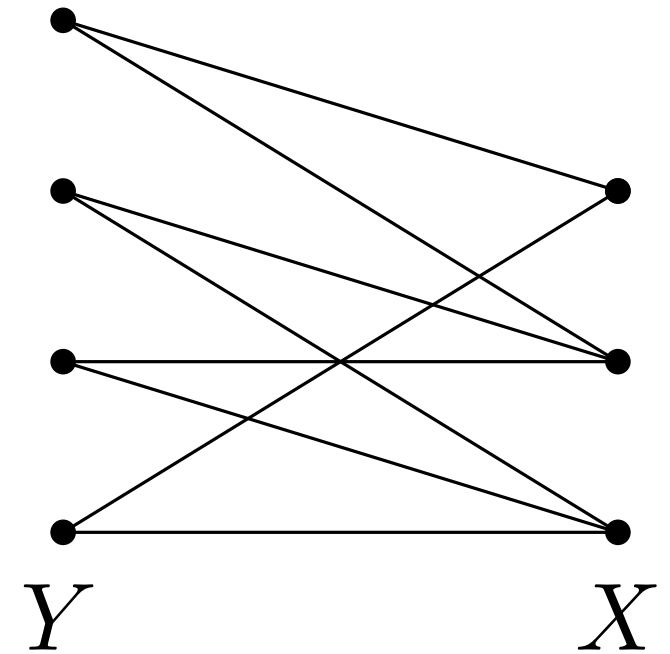
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We will prove this using duality!



Proof of Hall's Theorem from König's Theorem

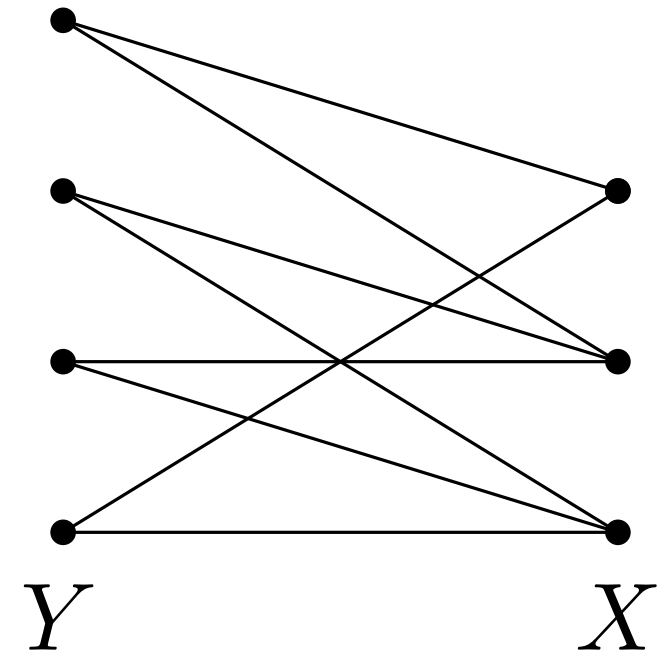
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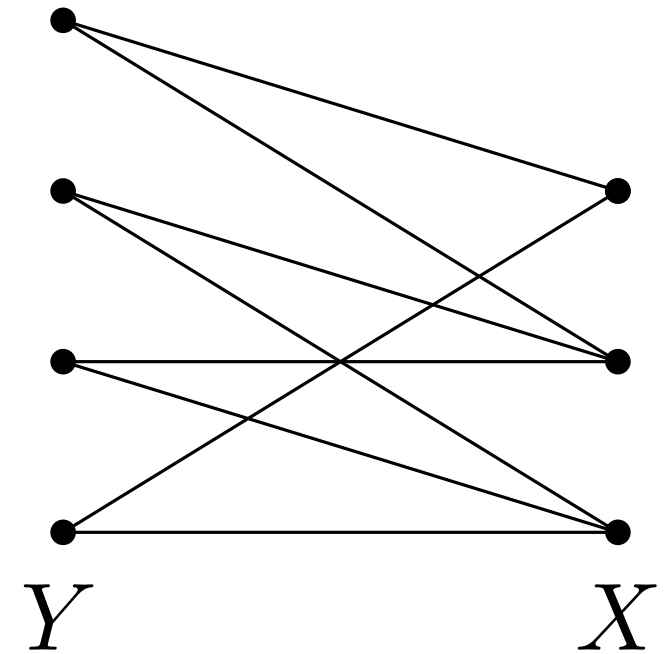
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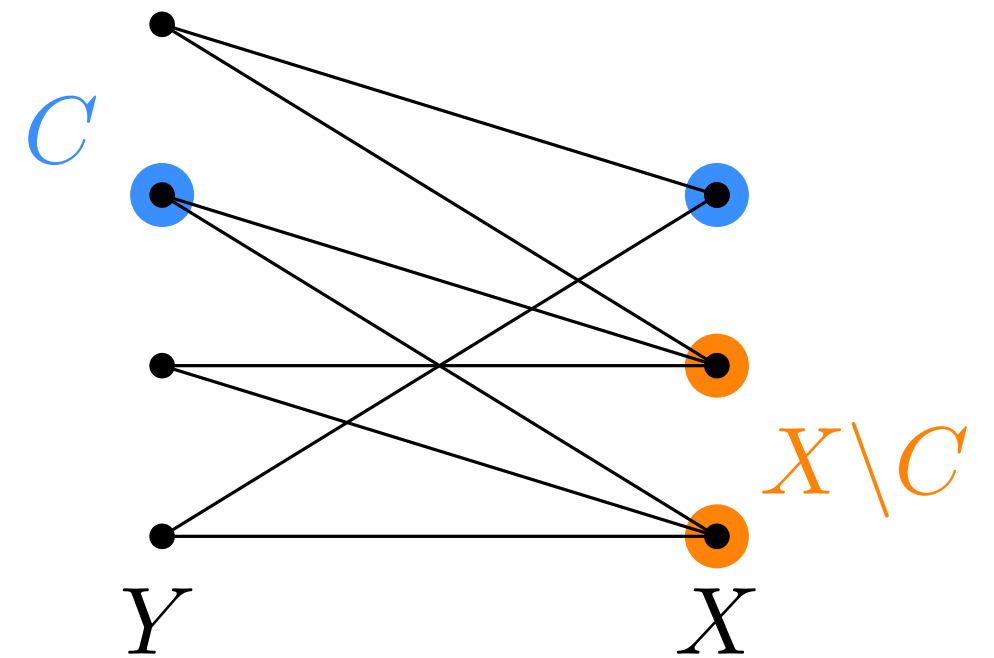
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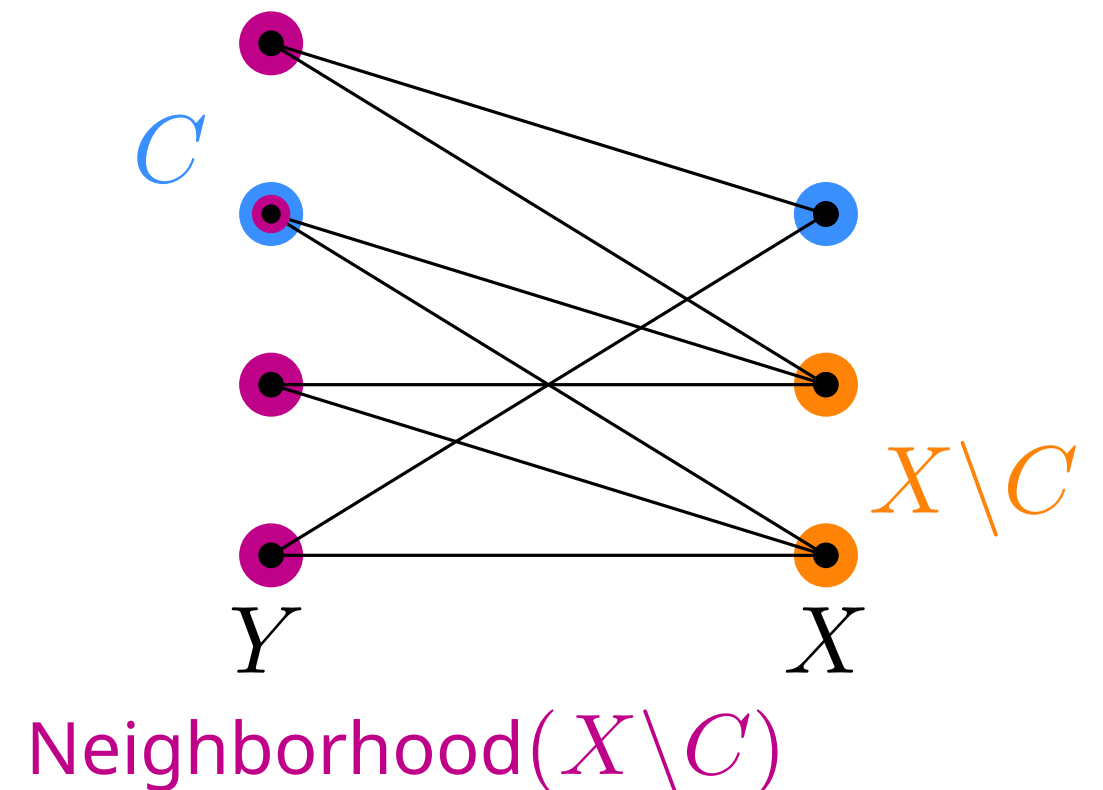
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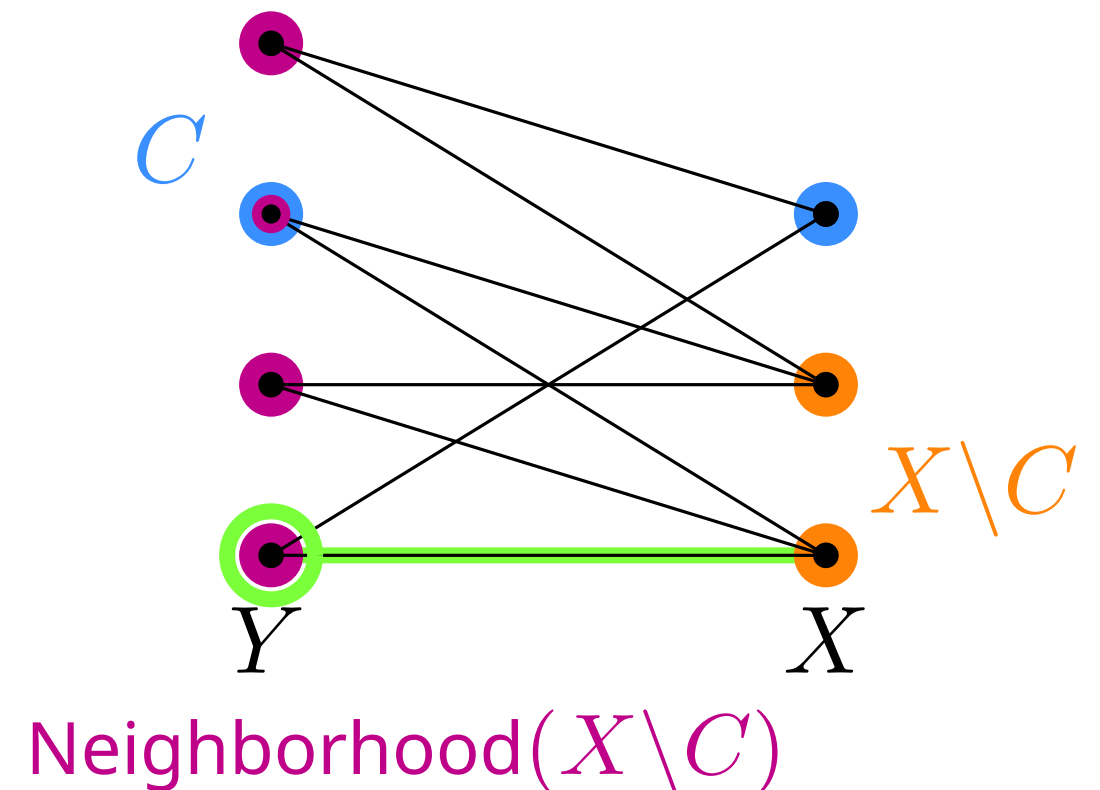
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This gives a **vertex** in $\text{Neighborhood}(X \setminus C)$ that is not in $C \cap Y$ – showing C is not a cover.



Total Unimodular Matrices

A matrix is **totally unimodular** if every square submatrix has determinant 0, 1, or -1 .

Example

$$\begin{bmatrix} -1 & -1 & 0 & 0 & 0 & 1 \\ 1 & 0 & -1 & -1 & 0 & 0 \\ 0 & 1 & 1 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 & 1 & -1 \end{bmatrix}$$

What does this matrix represent?

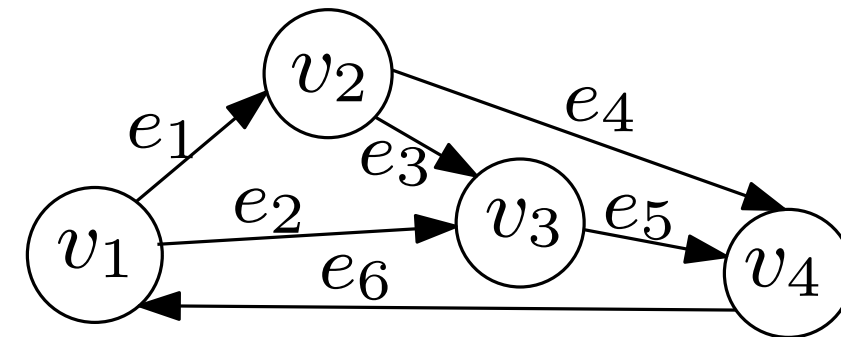
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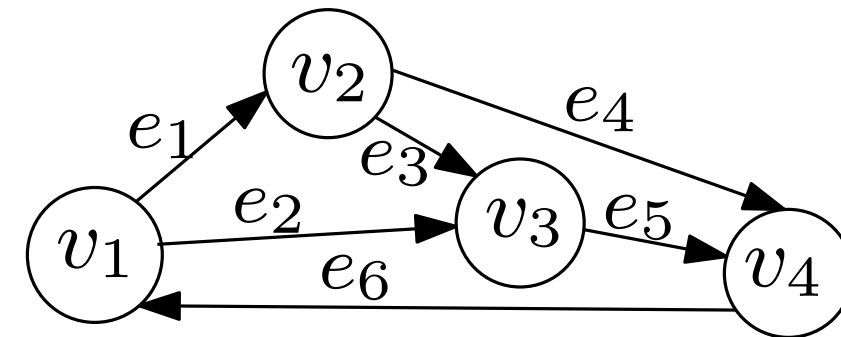
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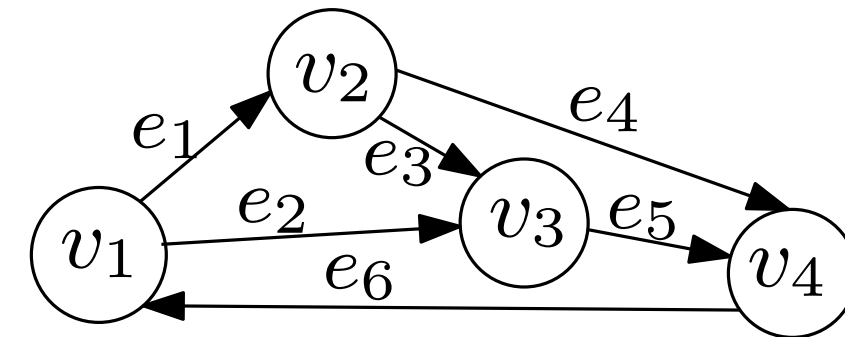
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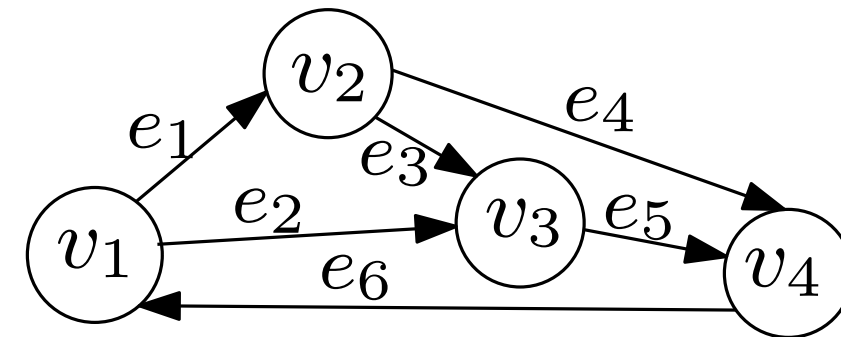
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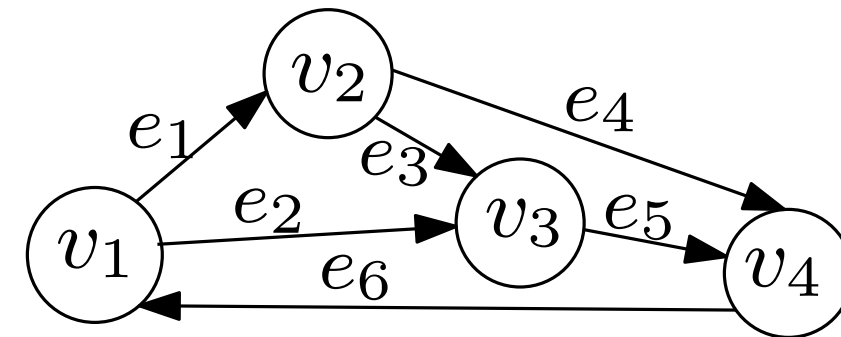
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If matrix A is totally unimodular, then so is

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Total Unimodular Matrices

Theorem: Consider the linear program $\max c^T x$ subject to $Ax \leq b, x \geq 0$. If A is totally unimodular, if $b \in \mathbb{Z}^m$, and if there is an optimal solution, then there is an optimal **integral** solution $x^* \in \mathbb{Z}^n$.

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\bar{A} totally unimodular

\bar{A} nonsingular

What do we know about $\det(\bar{A})$?

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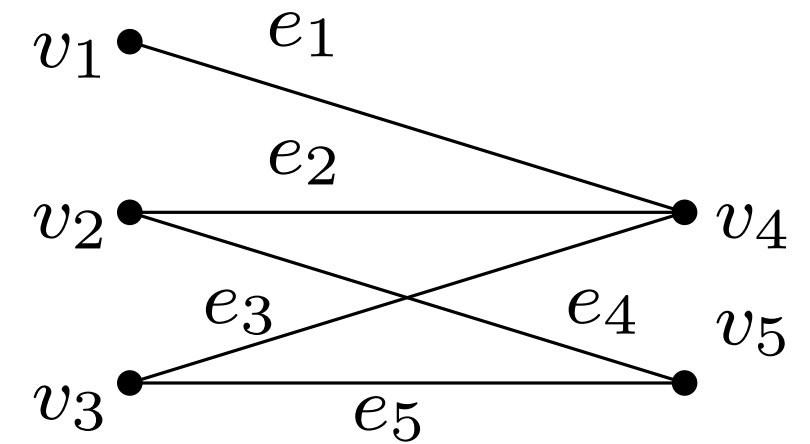
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By Cramer's rule the coefficients of \bar{x}^* are rational numbers with denominator $\det(\bar{A}_B)$, i.e., integer numbers! That is $\bar{x}^* \in \mathbb{Z}^{n+m}$ and hence $x^* \in \mathbb{Z}^n$.

Total Unimodularity and König's Theorem

Lemma: The incidence matrix A of a bipartite graph $G = (X \cup Y, E)$ is totally unimodular.

Example



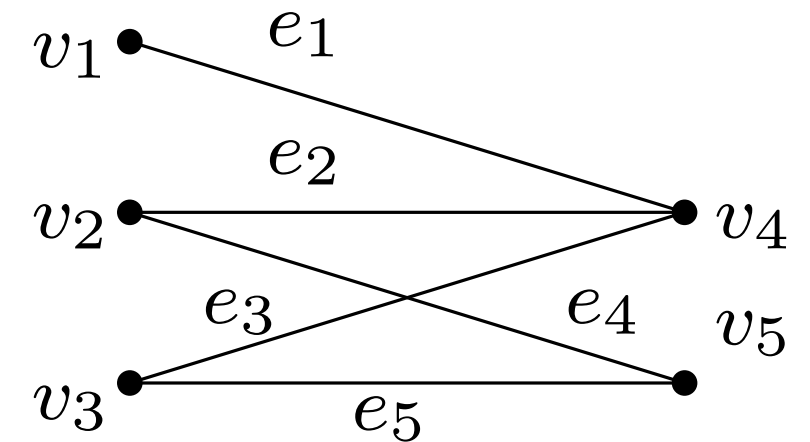
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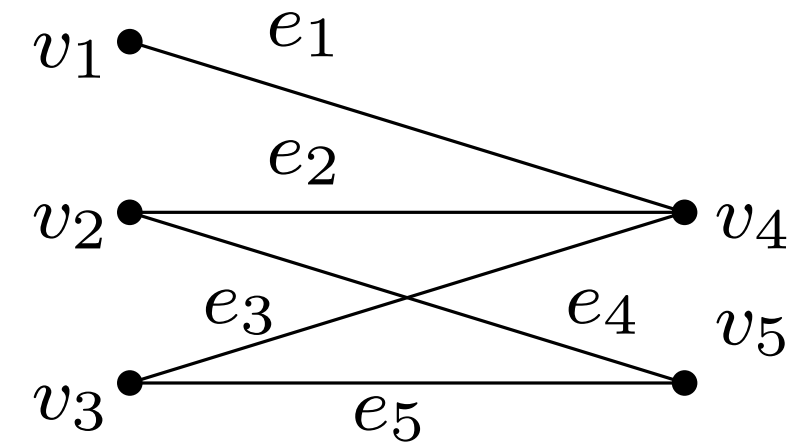
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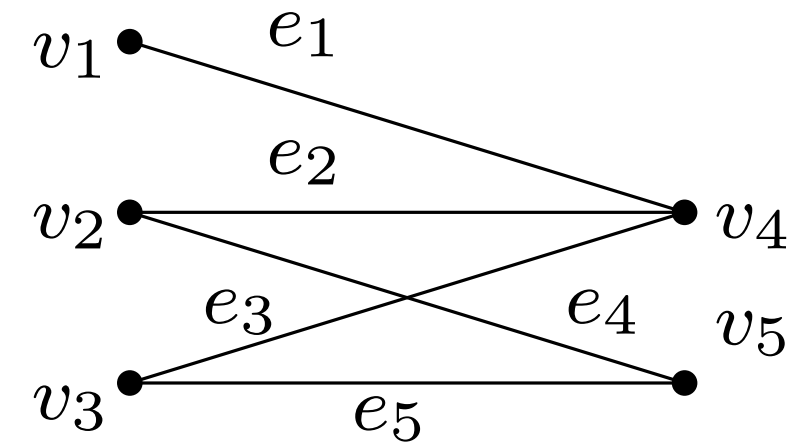
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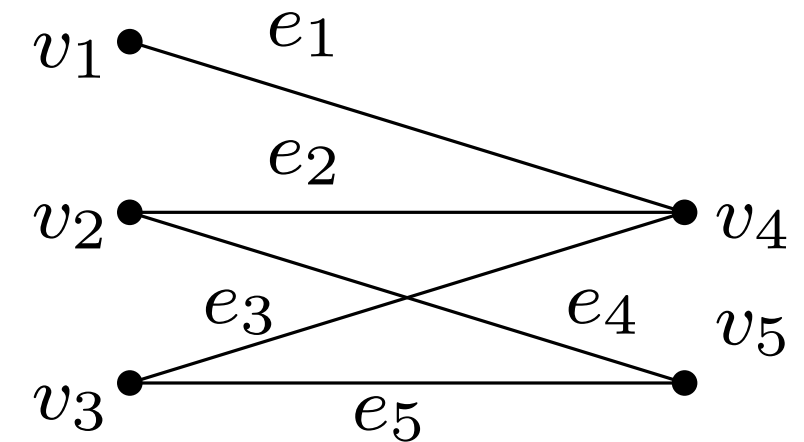
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The sum of all rows for vertices in X gives $(1, 1, \dots, 1)$.

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Hence the rows of Q are linearly dep. and so $\det(Q) = 0$.

Example



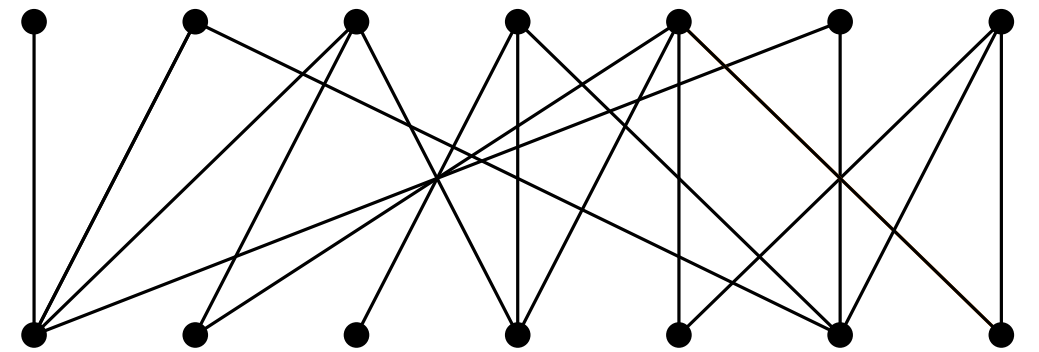
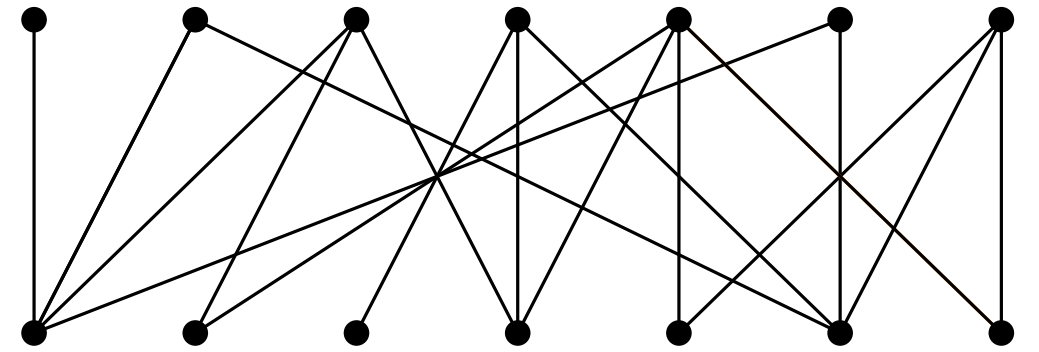
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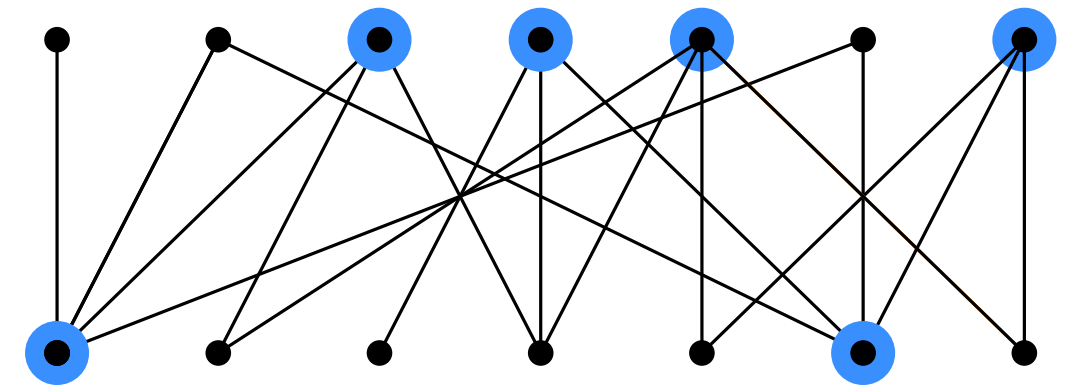
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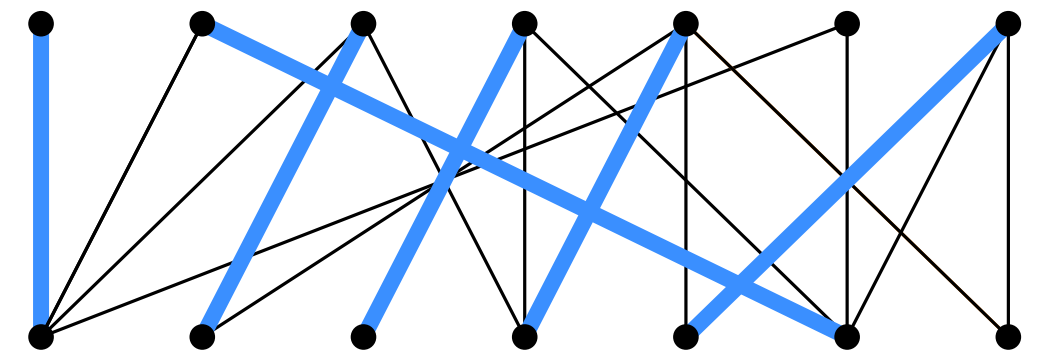


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minimum vertex cover



maximum matching

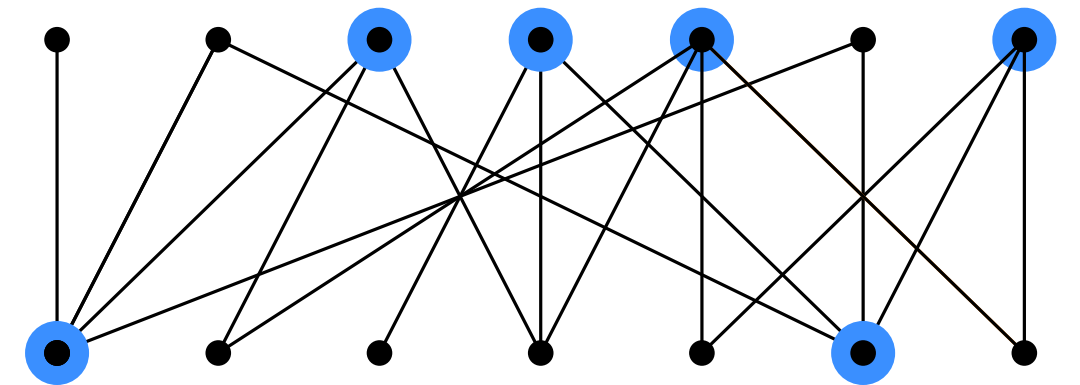
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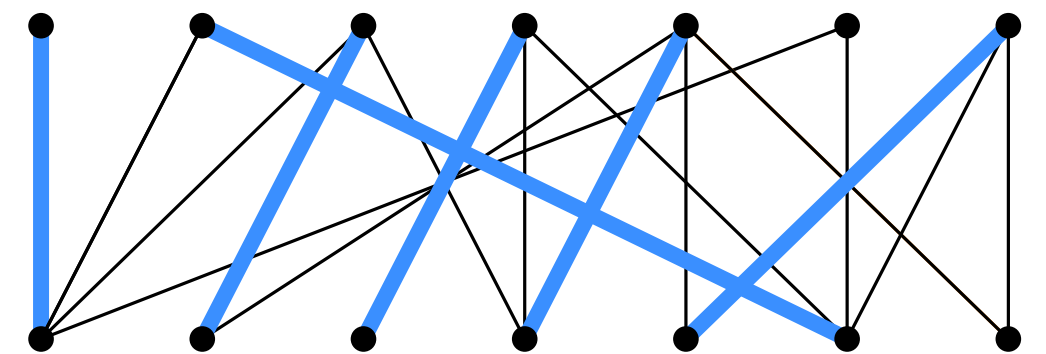
Proof:

Let A be the incidence matrix of the bipartite graph.

What are their LP's?



minimum vertex cover



maximum matching

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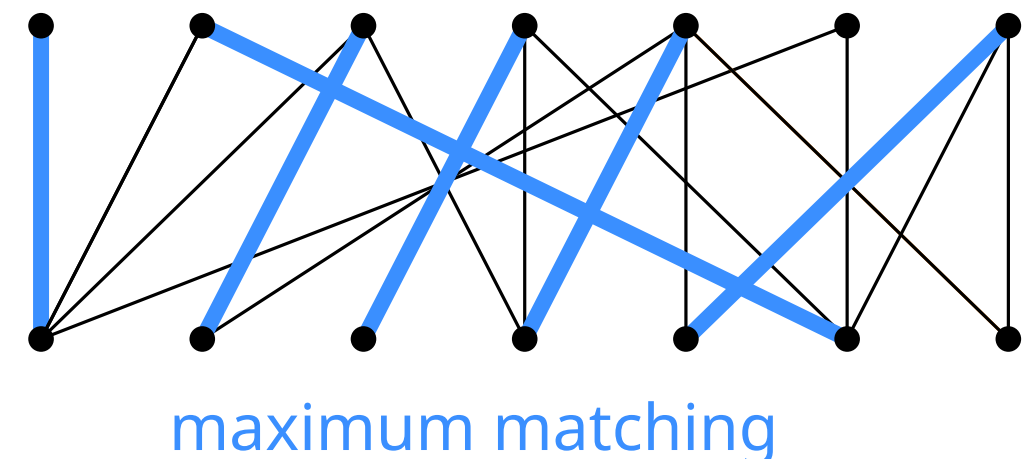
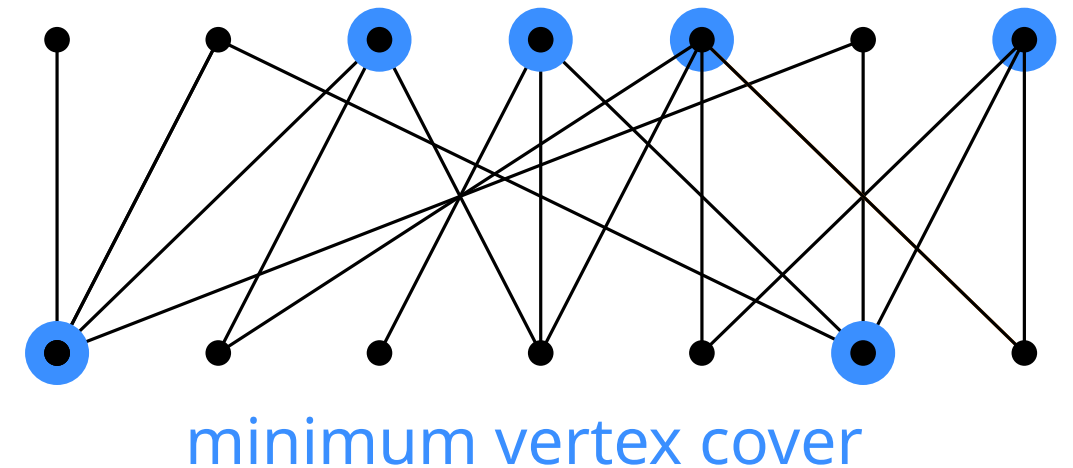
Cover

$$\begin{array}{ll} \min & \sum y_i \\ \text{subject to} & A^T y \geq 1 \\ & y \geq 0 \end{array}$$

Matching

$$\begin{array}{ll} \max & \sum x_j \\ \text{subject to} & Ax \leq 1 \\ & x \geq 0 \end{array}$$

optionally: $y_i, x_j \in \{0, 1\}$



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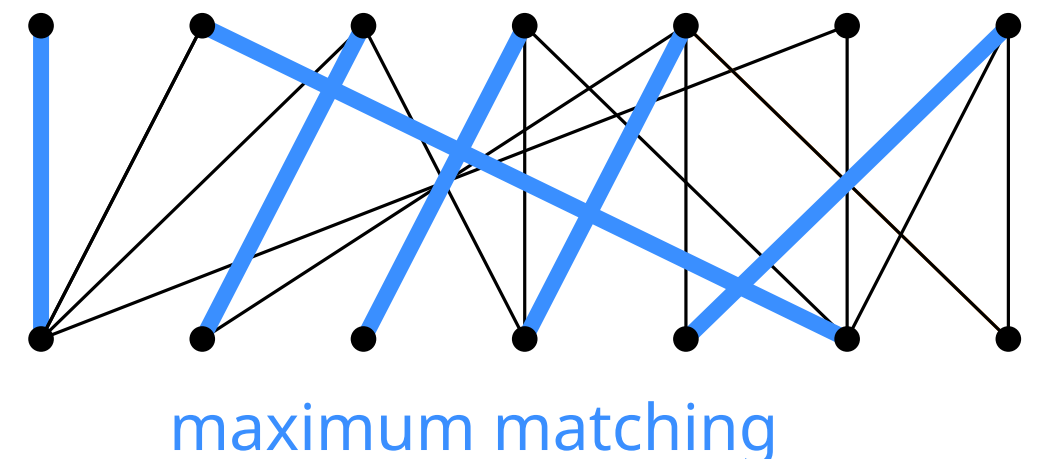
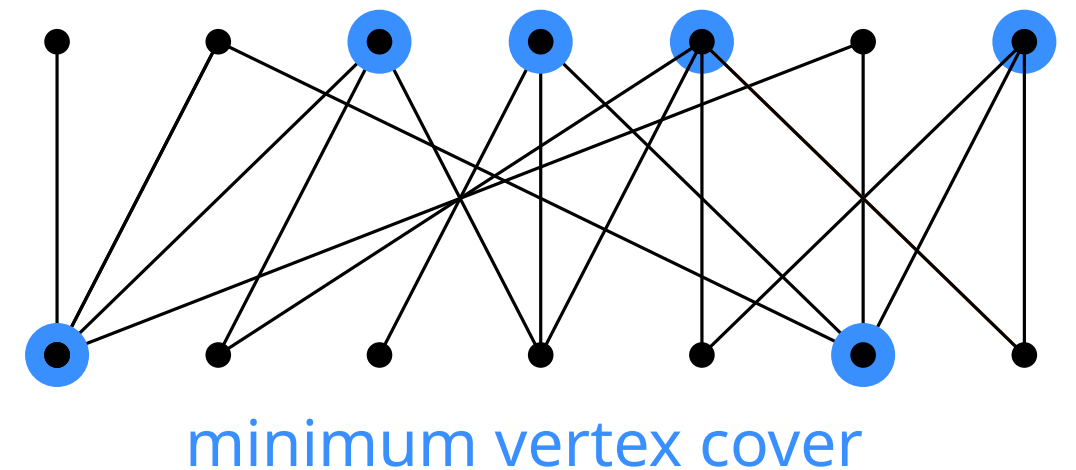
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We can drop the integrality constraints since A is totally unimodular.



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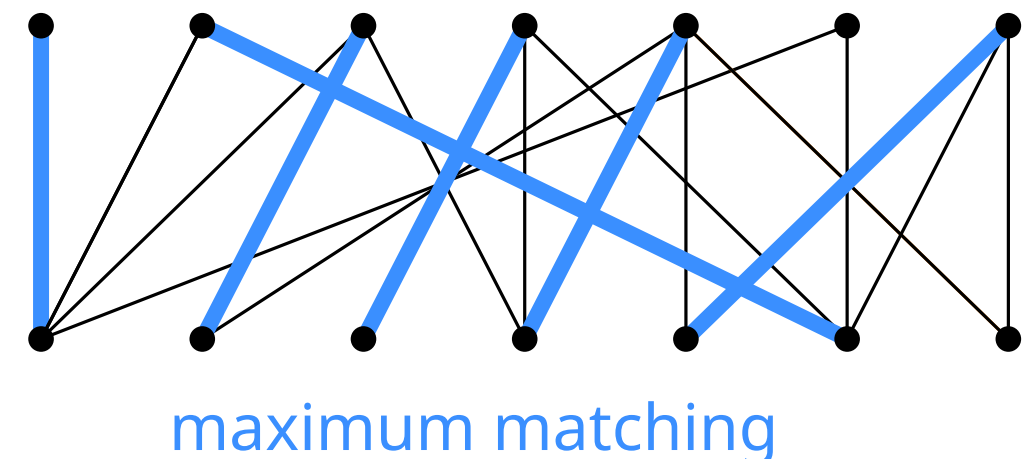
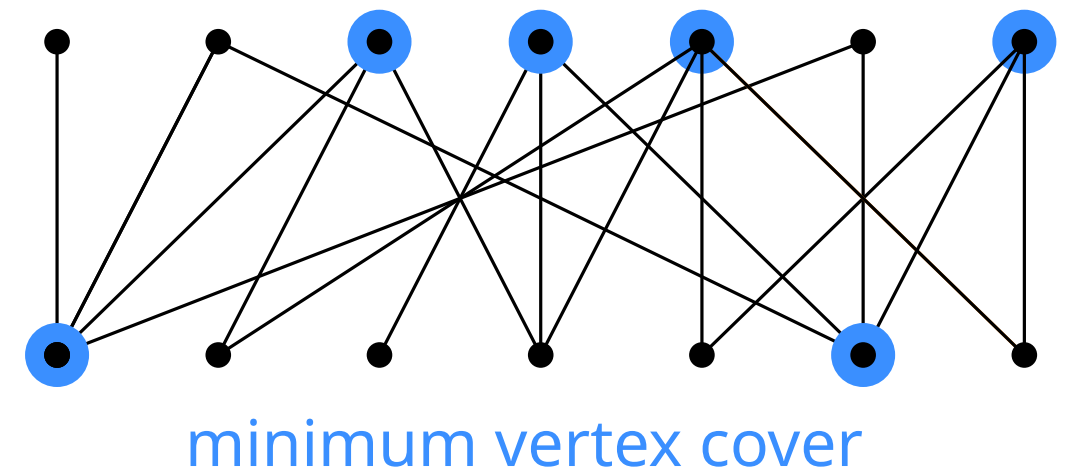
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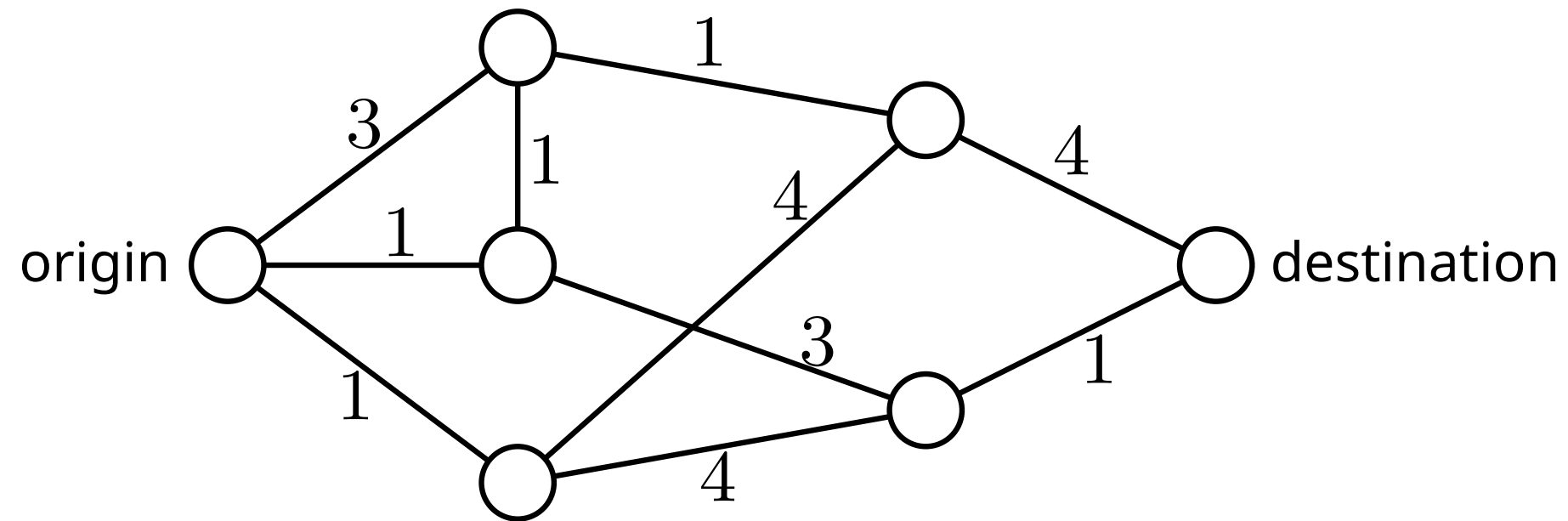
The duality of these linear programs then proves the theorem.



Duality shows $\text{Max Flow} = \text{Min Cut}$

Recall: Flow in a Network

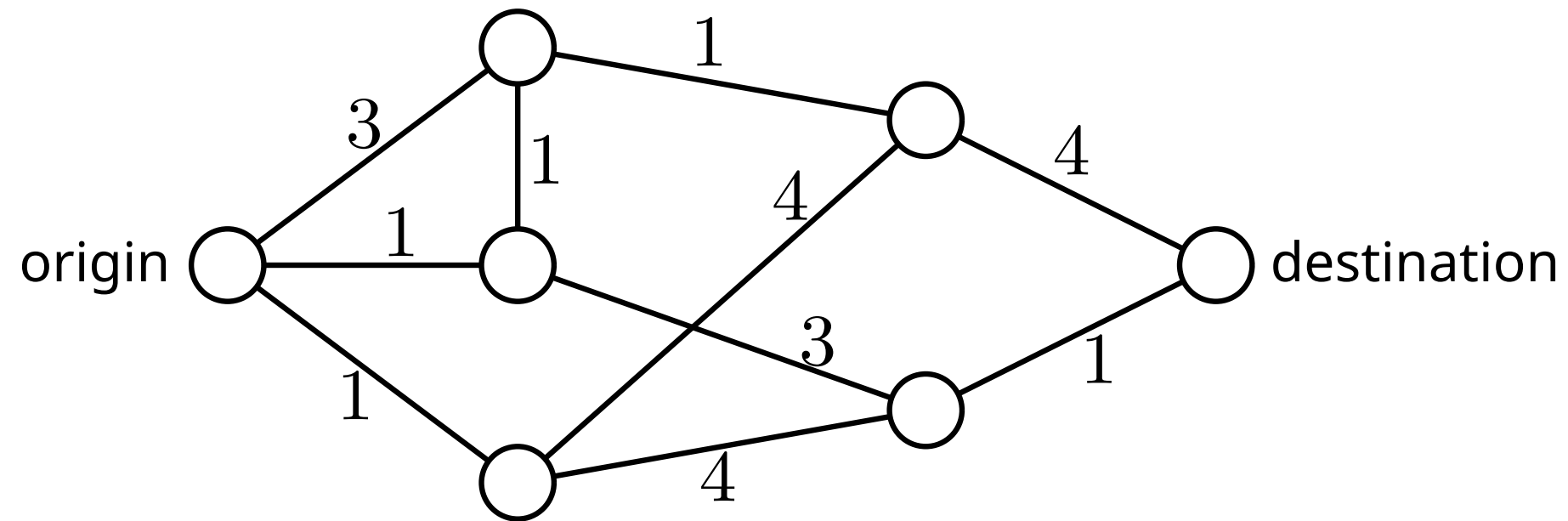
How to send as much data as possible over a local network?



nodes cannot store data and links can transport in only one direction

Recall: Flow in a Network

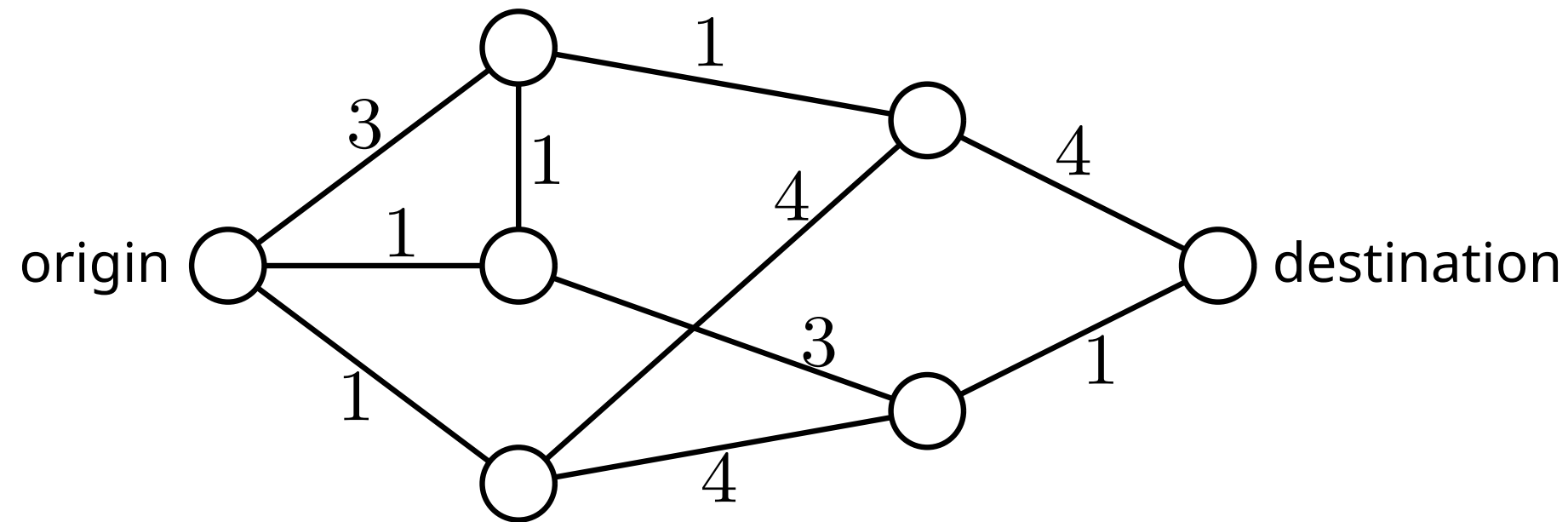
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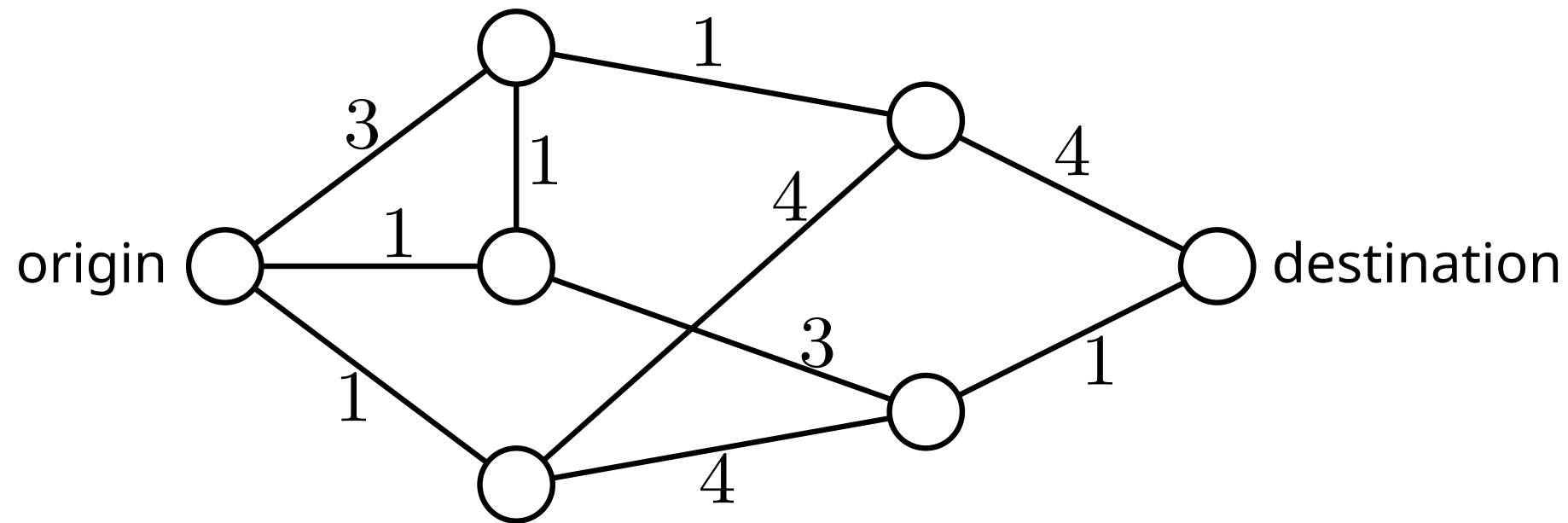


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LP formulation?

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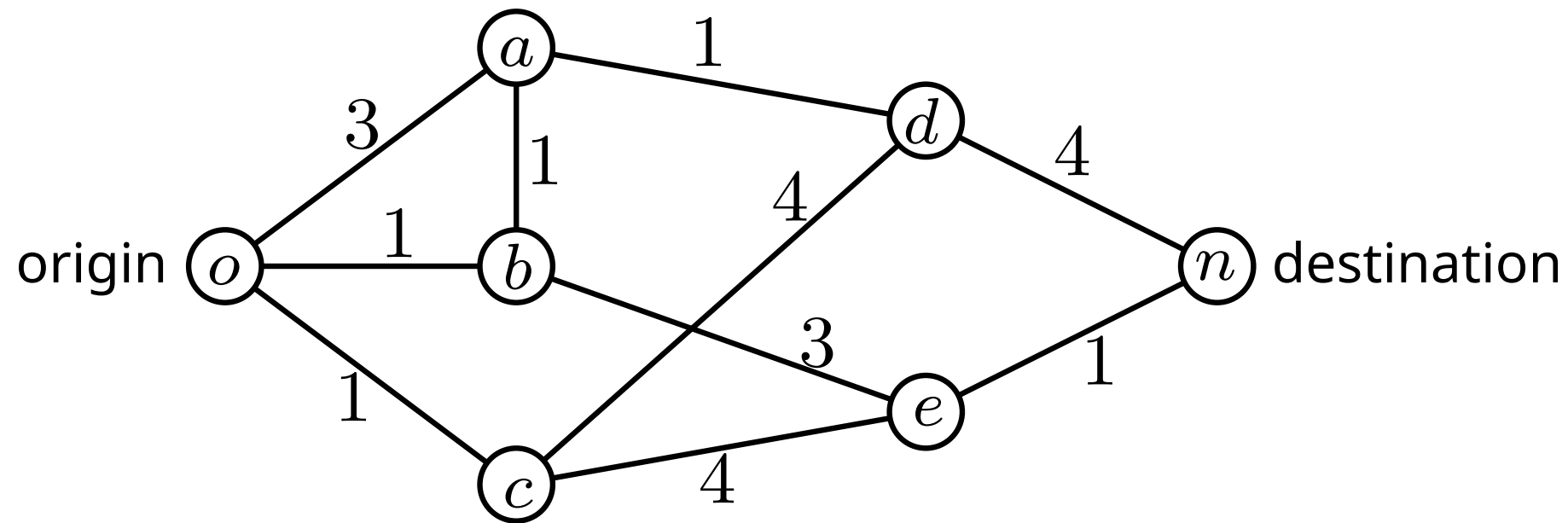
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LP formulation?

- introduce variable x_{uv} for each edge (u, v) and require
1. flow \leq capacities on edges
 2. inflow = outflow on all nodes (except origin, destination)

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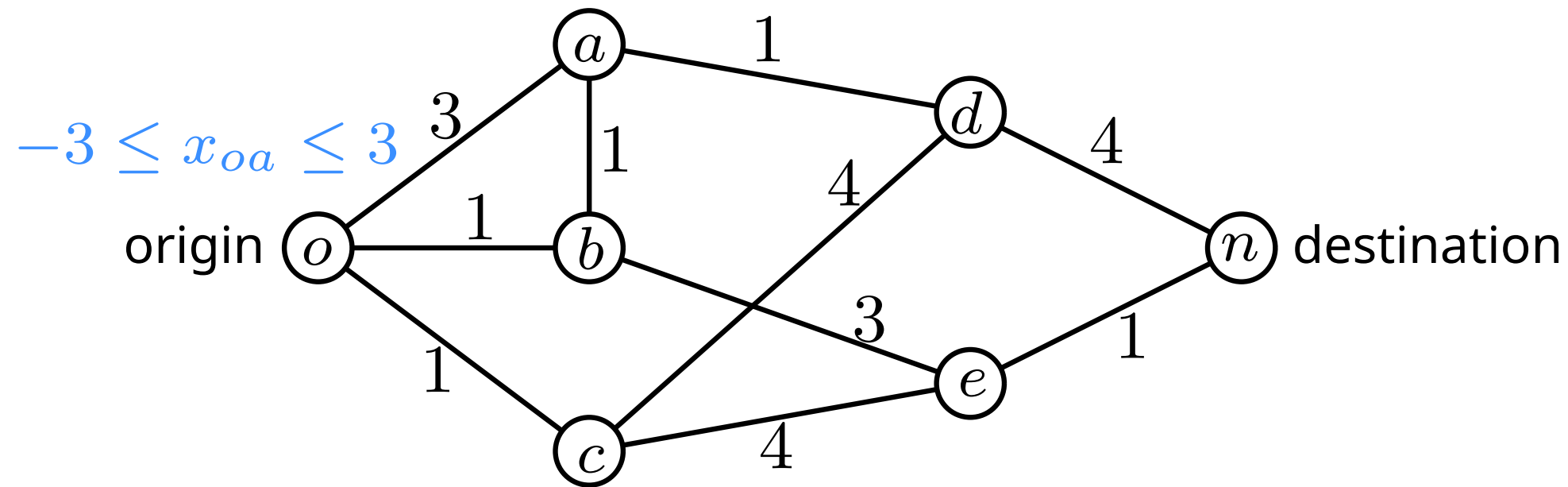
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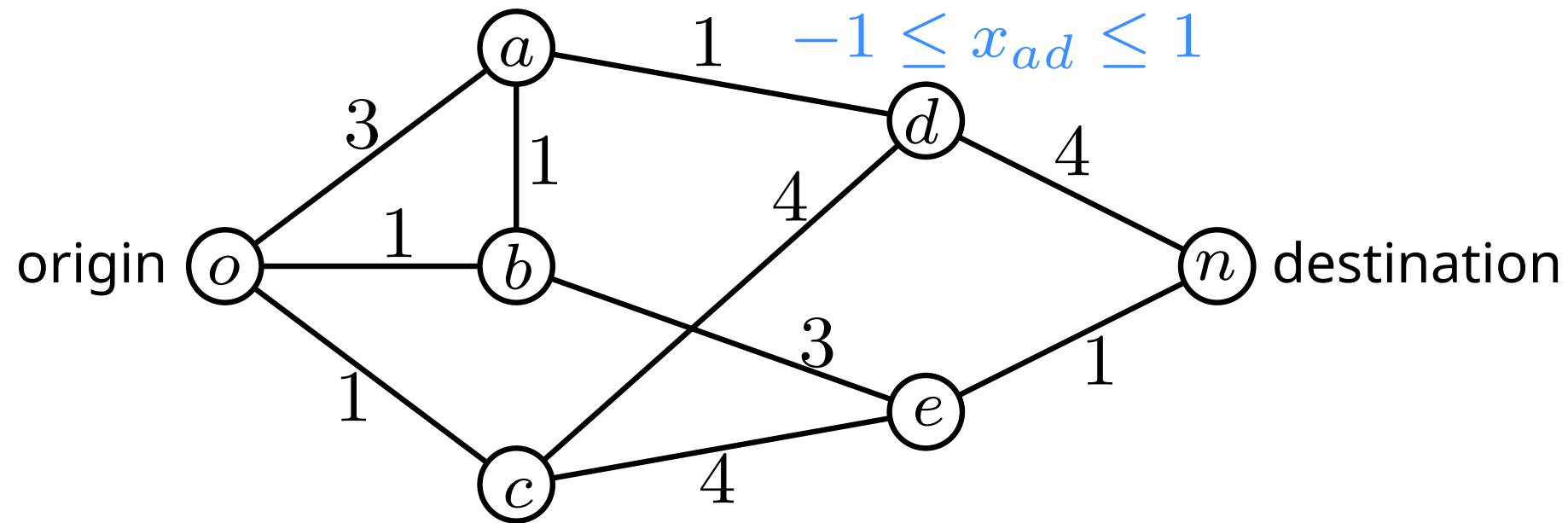
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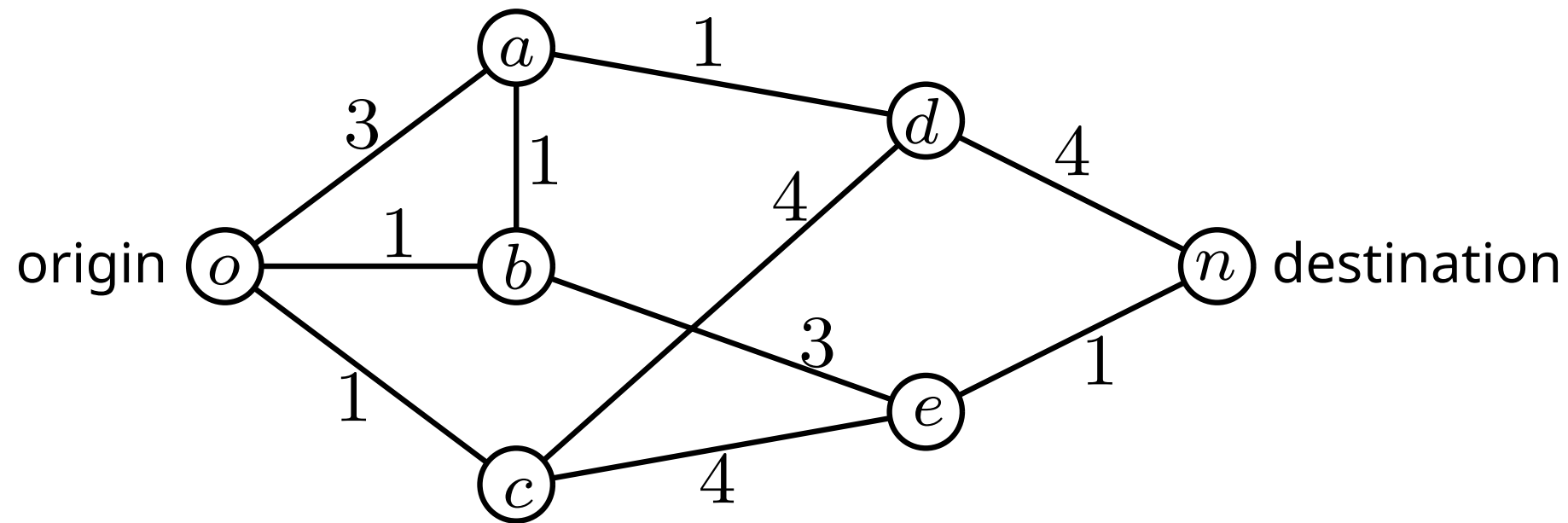
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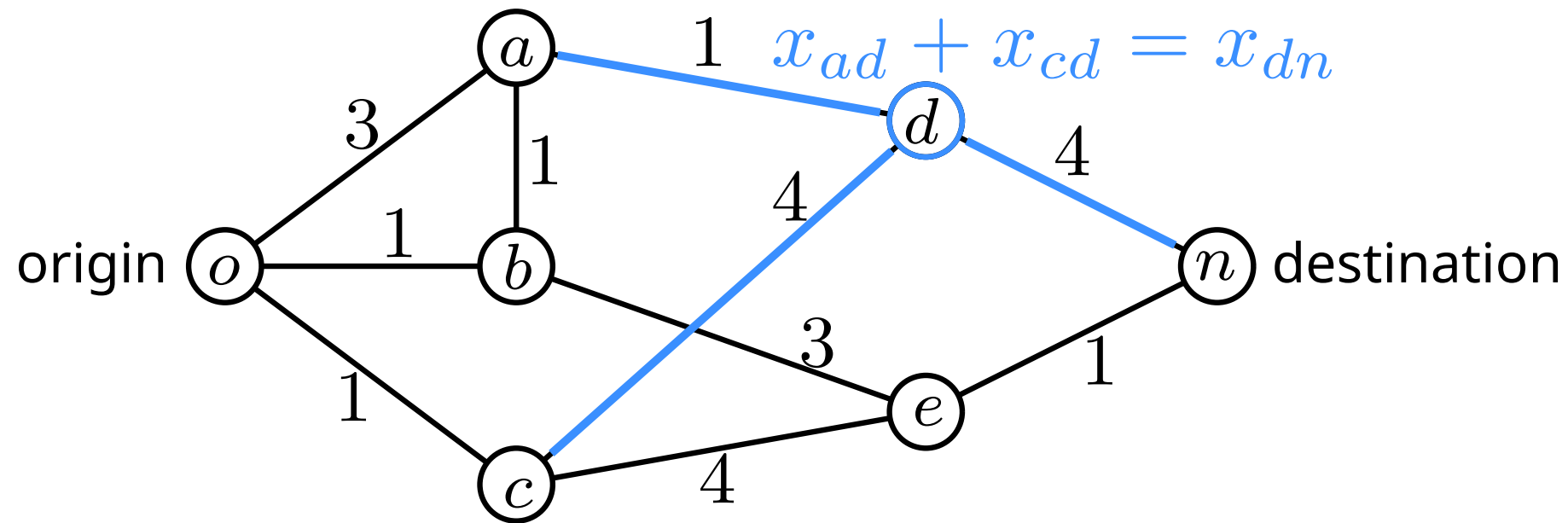
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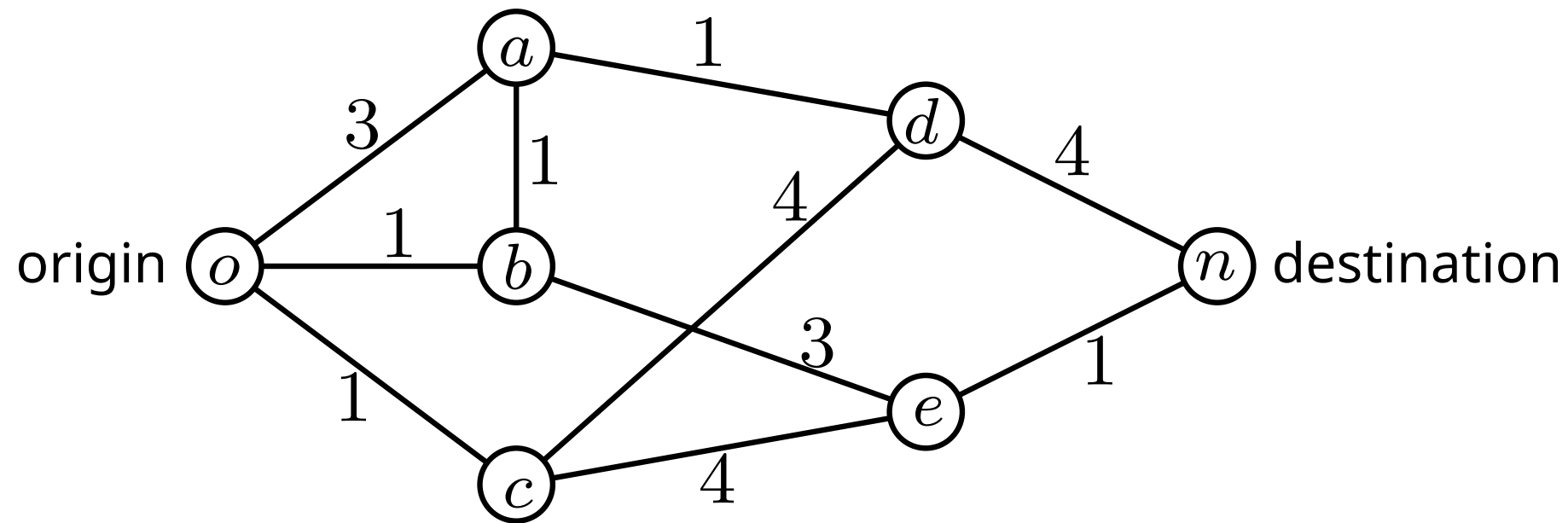
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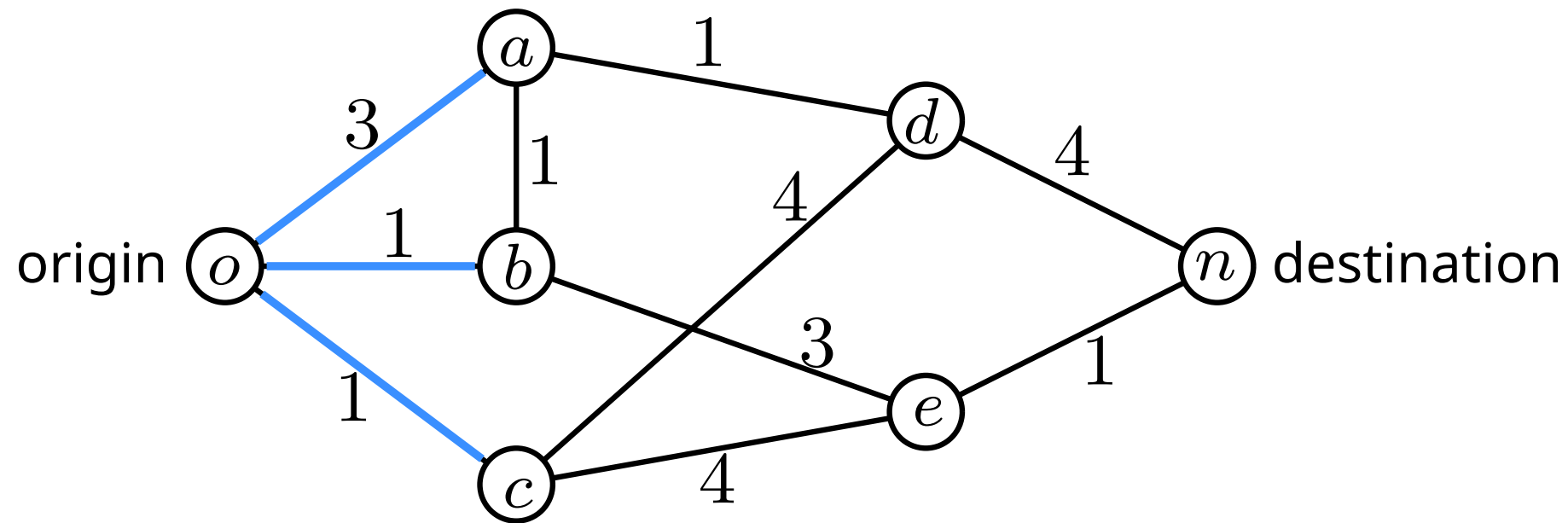
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$$x_{oa} + x_{ob} + x_{oc}$$

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Recall: Flow in a Network

Linear Program Formulation

maximize $x_{oa} + x_{ob} + x_{oc}$

subject to $-3 \leq x_{oa} \leq 3, -1 \leq x_{ob} \leq 1, -1 \leq x_{oc} \leq 1$

$-1 \leq x_{ab} \leq 1, -1 \leq x_{ad} \leq 1, -3 \leq x_{be} \leq 3$

$-4 \leq x_{cd} \leq 4, -4 \leq x_{ce} \leq 4, -4 \leq x_{dn} \leq 4$

$-1 \leq x_{en} \leq 1$

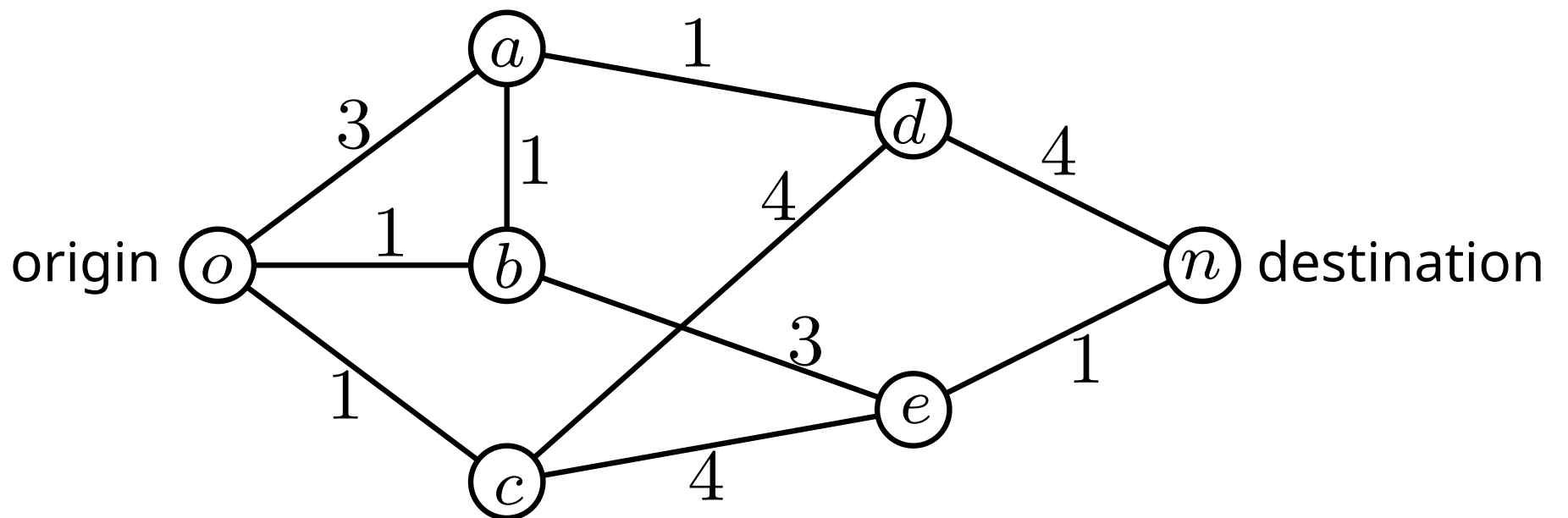
$x_{oa} = x_{ab} + x_{ad}$

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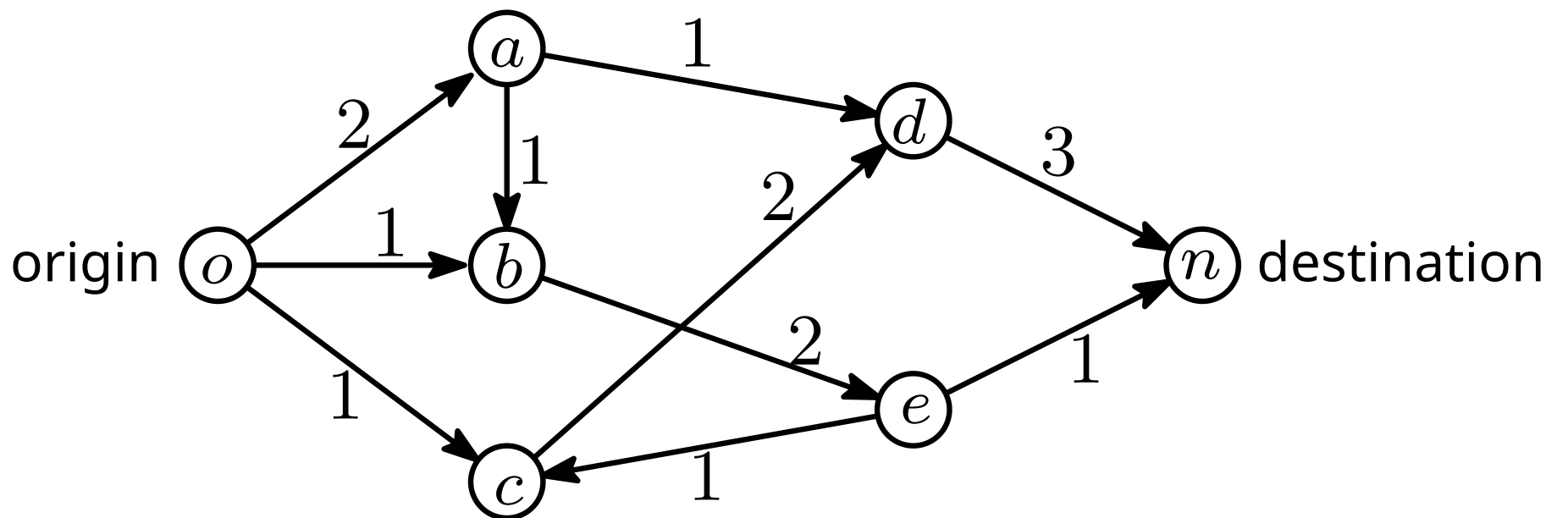
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Optimal
solution: 4



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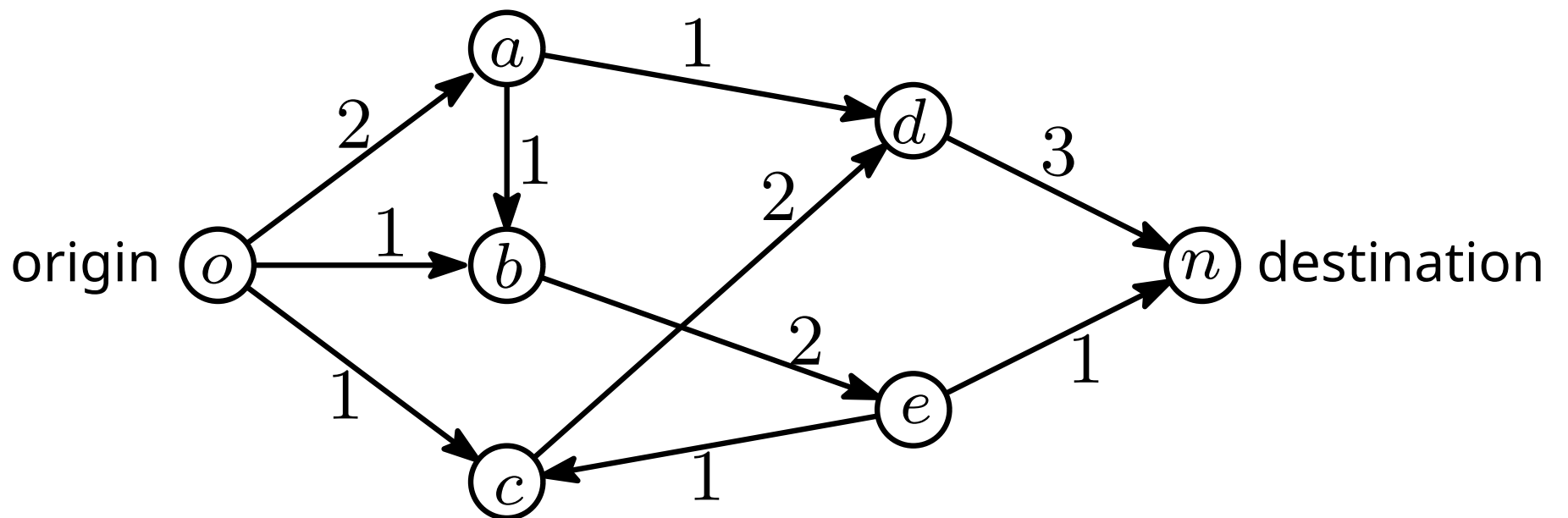
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well-known “max flow = min cut” → now via LP-duality!

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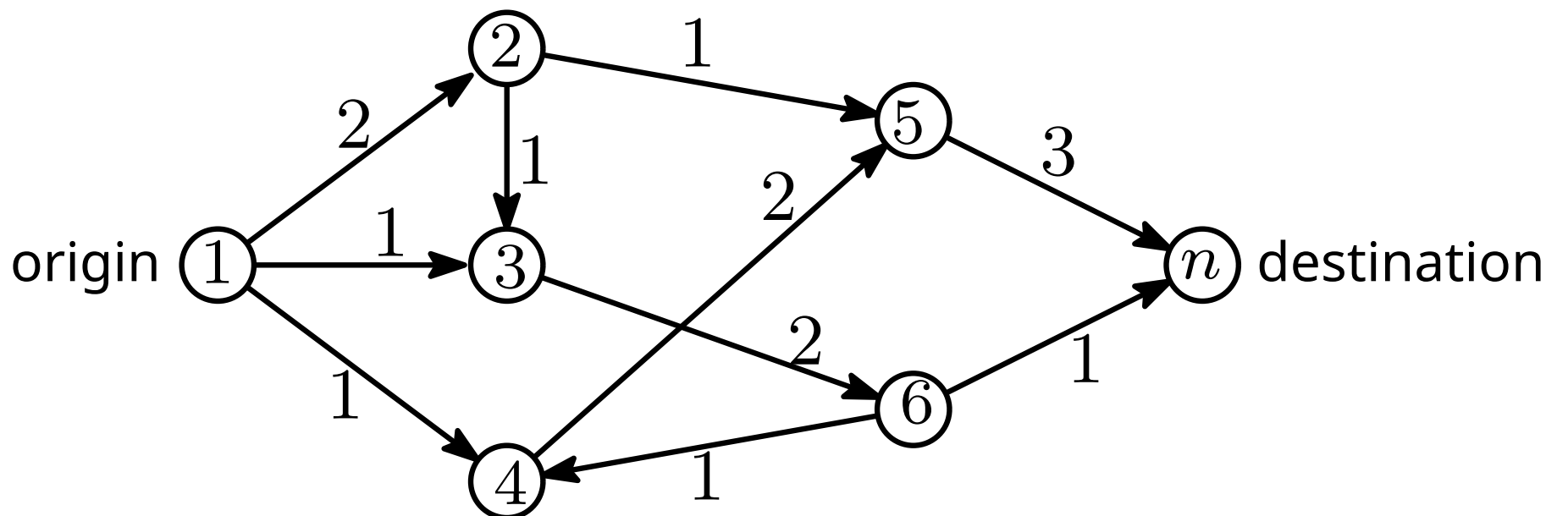
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first we formulate the LP more concisely:

let the vertices be numbered $1, \dots, n$, let c_{ij} the capacity and x_{ij} the flow on directed edge (i, j) , and let f be the max flow.

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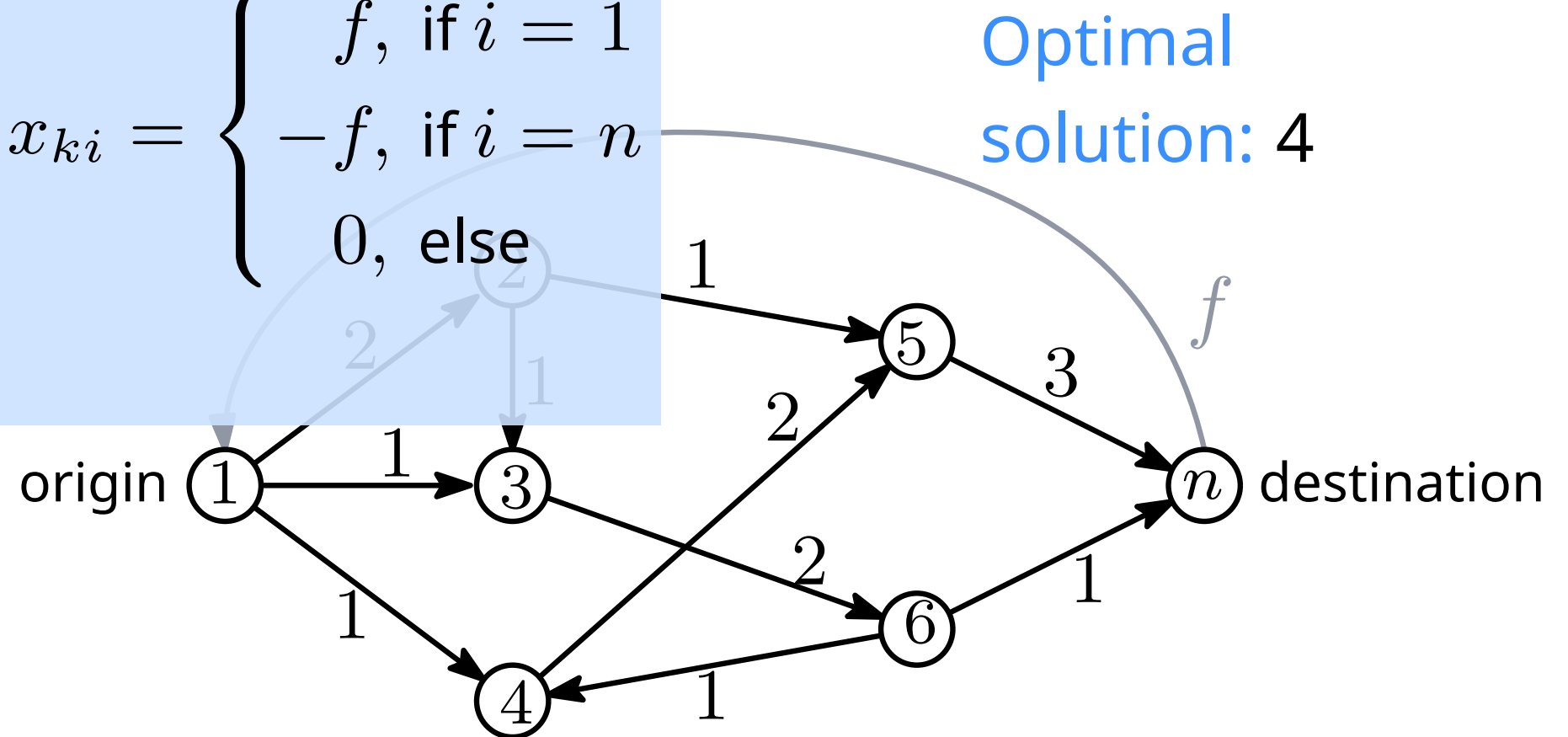
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maximize f

subject to $\sum_{(i,j) \in E} x_{ij} - \sum_{(k,i) \in E} x_{ki} = \begin{cases} f, & \text{if } i = 1 \\ -f, & \text{if } i = n \\ 0, & \text{else} \end{cases}$

$$0 \leq x_{ij} \leq c_{ij}$$



Recall: Flow in a Network

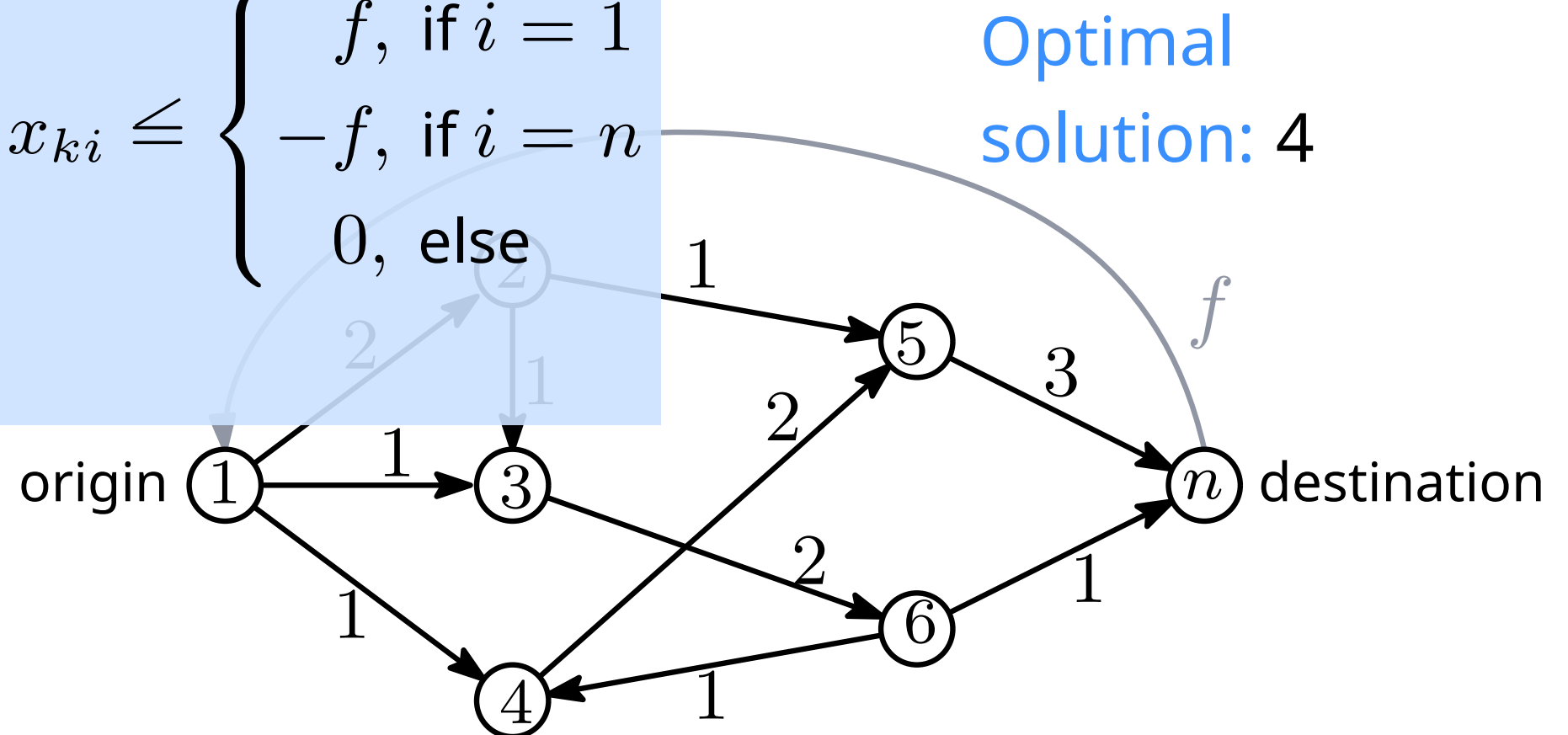
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actually we can relax the constraint without changing the optimum

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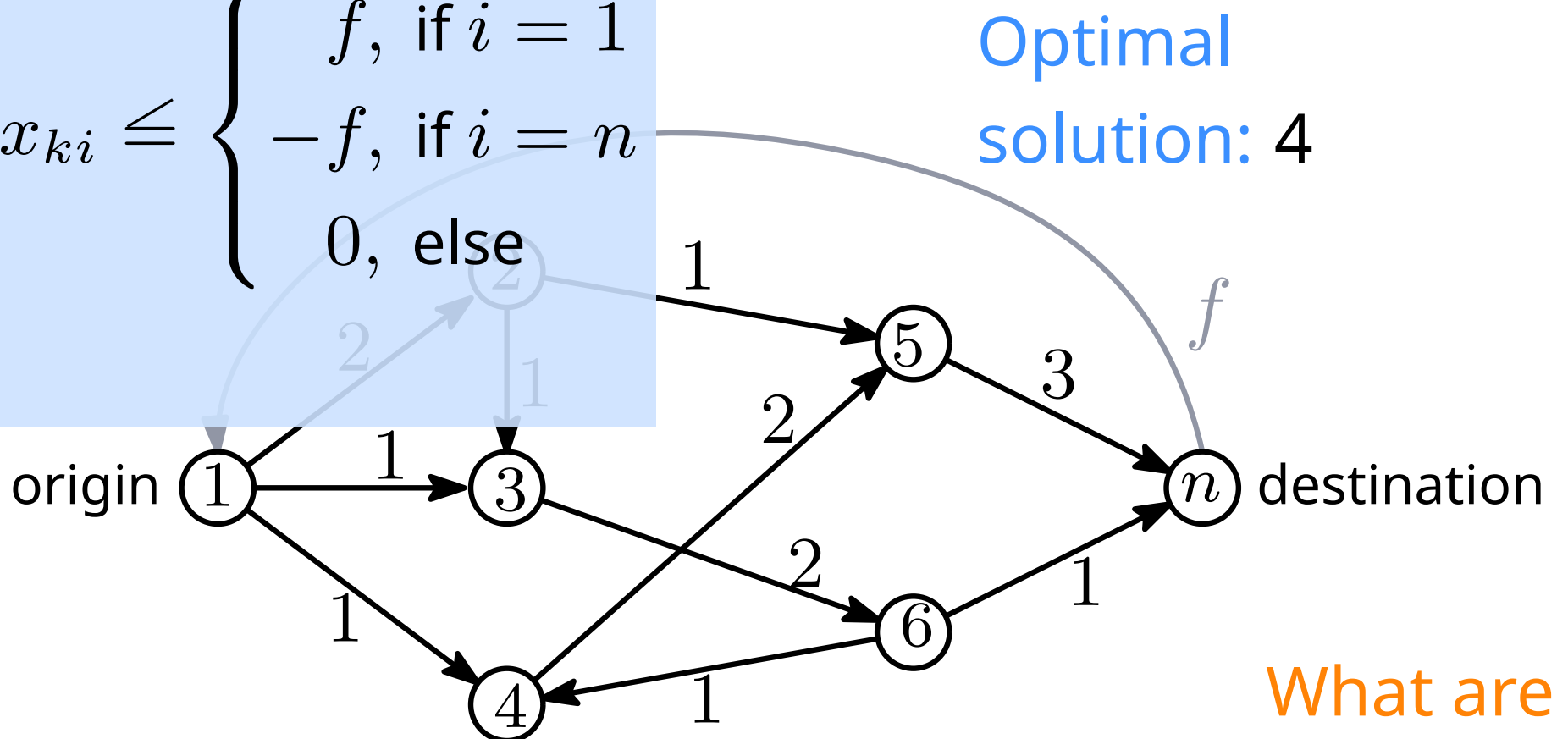
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Let's write this in **Matrix form** $\max f$ subject to $Ax \leq b, x \geq 0$.

What are
 A, x, b, c ?

Recall: Flow in a Network

Linear Program Formulation

in **Matrix form** $\max f$ subject to $Ax \leq b, x \geq 0$ where

$$x = \begin{bmatrix} f \\ x_{ij} \\ \dots \\ \dots \end{bmatrix} \quad c = \begin{bmatrix} 1 \\ 0 \\ \dots \\ \dots \end{bmatrix} \quad A = \left[\begin{array}{c|ccccc} -1 & \dots & \dots & \dots & \dots \\ 0 & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \\ 1 & \dots & \dots & \dots & \dots \\ \hline 0 & 1 & 0 & \dots & \dots \\ \dots & 0 & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & 0 \\ 0 & \dots & \dots & 0 & 1 \end{array} \right] \quad b = \left[\begin{array}{c} 0 \\ \dots \\ \dots \\ 0 \\ \hline c_{ij} \\ \dots \\ \dots \\ \dots \end{array} \right]$$

Recall: Flow in a Network

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every column
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Recall: Flow in a Network

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What is the dual?

Dual of the Max Flow LP

Linear Program Formulation

in **Matrix form** $\min \sum c_{ij} y_{ij}$ subject to $A^T y \geq c, x \geq 0$ where

$$y = \begin{bmatrix} u_1 \\ \vdots \\ \vdots \\ u_n \\ y_{ij} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \quad b = \begin{bmatrix} 0 \\ \vdots \\ \vdots \\ 0 \\ c_{ij} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \quad A^T = \left[\begin{array}{cccc|cccc} -1 & 0 & \dots & 1 & 0 & \dots & \dots & 0 \\ \hline \vdots & \vdots & \vdots & \vdots & 1 & 0 & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & 0 & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & 0 & 1 \end{array} \right] \quad c = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ \vdots \end{bmatrix}$$

every row contains exactly one -1 and one 1

Dual of the Max Flow LP

Linear Program Formulation

in constraint form

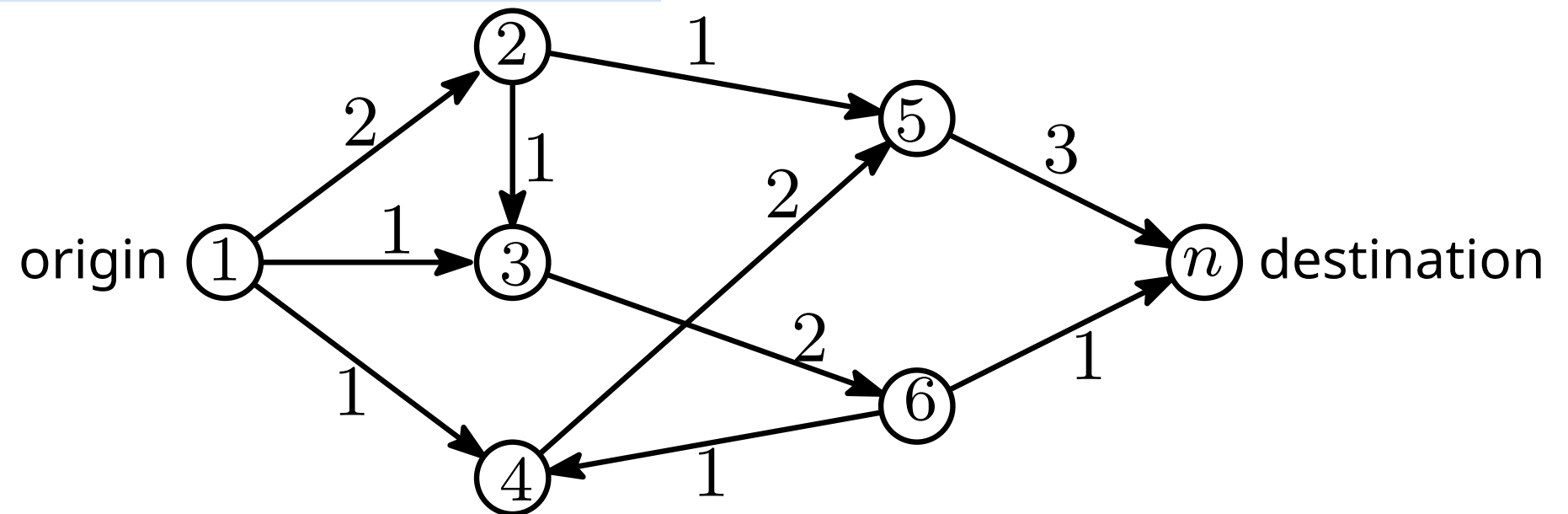
$$\text{minimize } \sum c_{ij} y_{ij}$$

$$\text{subject to } -u_1 + u_n \geq 1$$

$$u_i - u_j + y_{ij} \geq 0$$

$$u_i \geq 0$$

$$y_{ij} \geq 0$$



Dual of the Max Flow LP

Linear Program Formulation

in constraint form

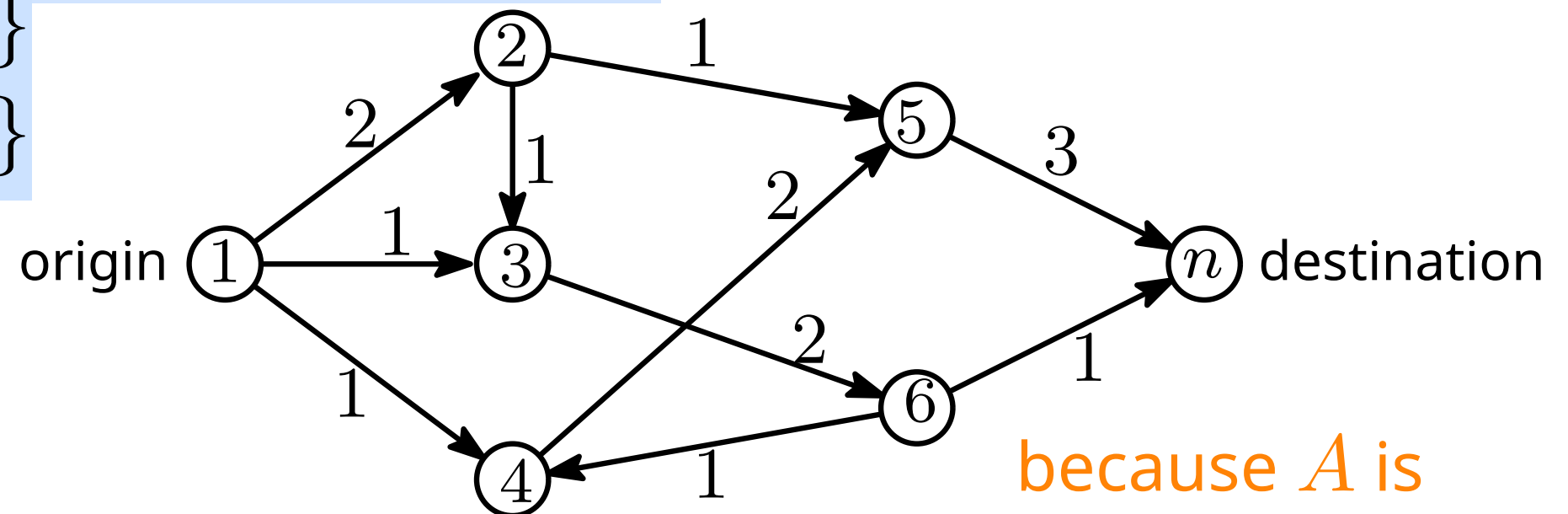
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$$u_i \in \{0, 1\}$$

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actually, we can restrict all variables to be integer, even 0-1

because A is
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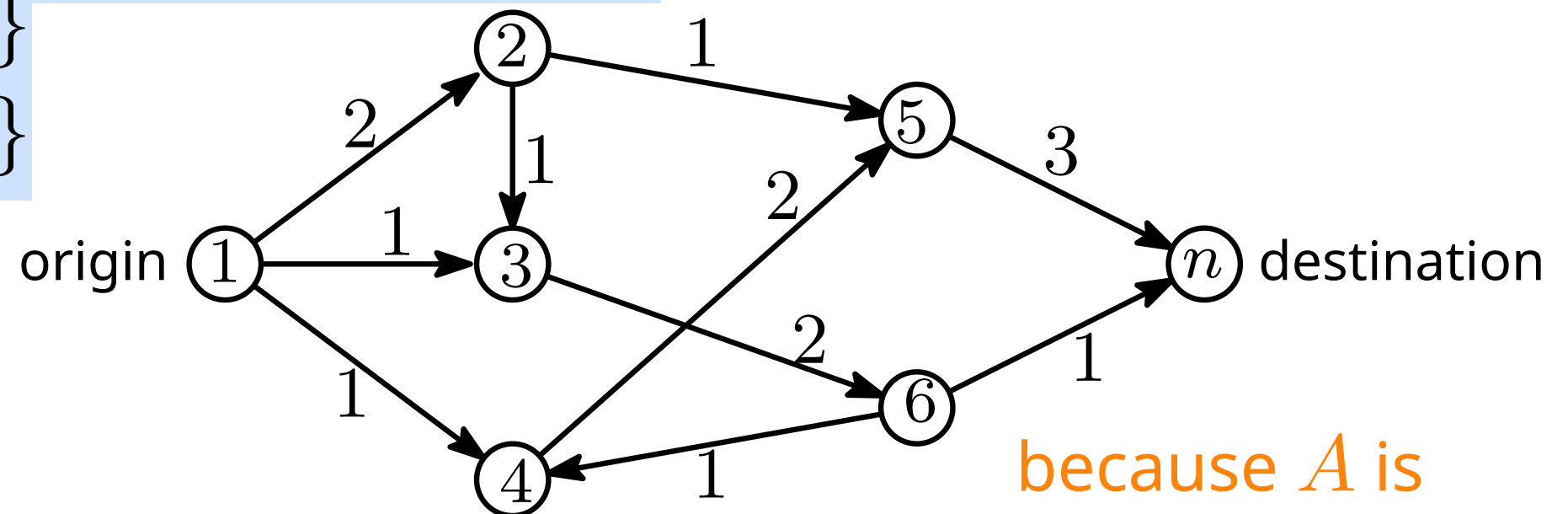
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→ Min Cut



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Flows and Cuts in a Network

Alternative LP

Let P be the set of all paths $q \rightsquigarrow s$
use variables x_p , for all $p \in P$

$$\max \sum_{p \in P} x_p$$

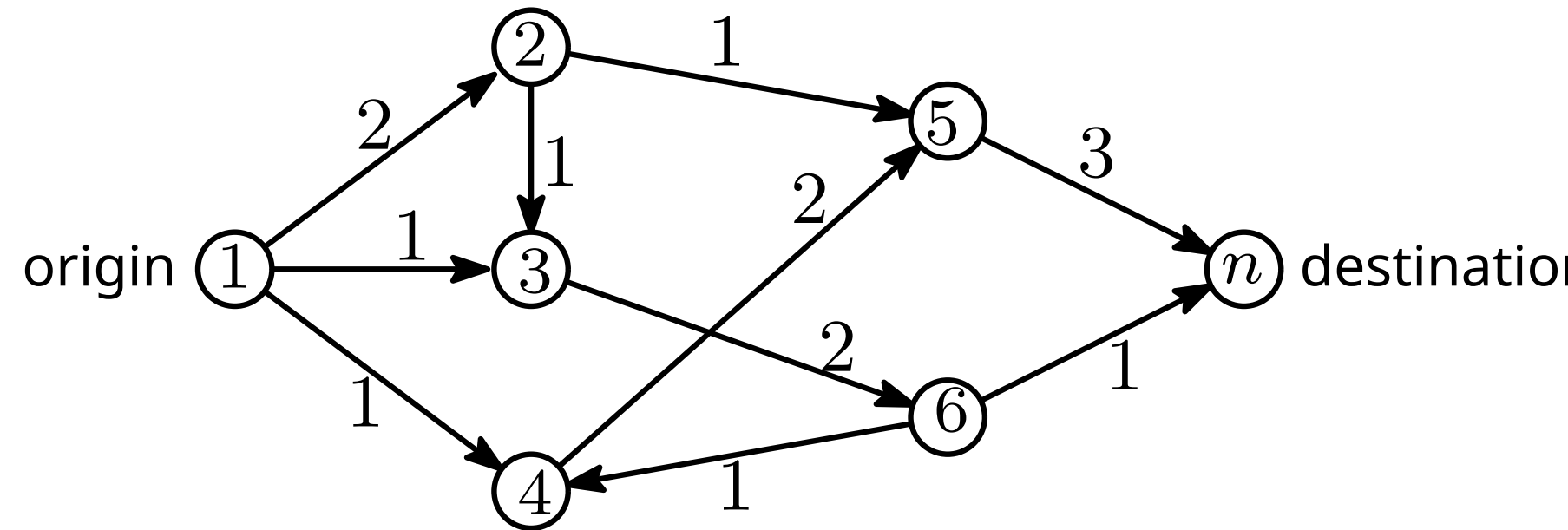
subject to

$$\sum_{p \ni e} x_p \leq c(e) \quad \forall e \in E$$

$$0 \leq x_p \quad \forall p \in P$$

primal

Max Flow



Flows and Cuts in a Network

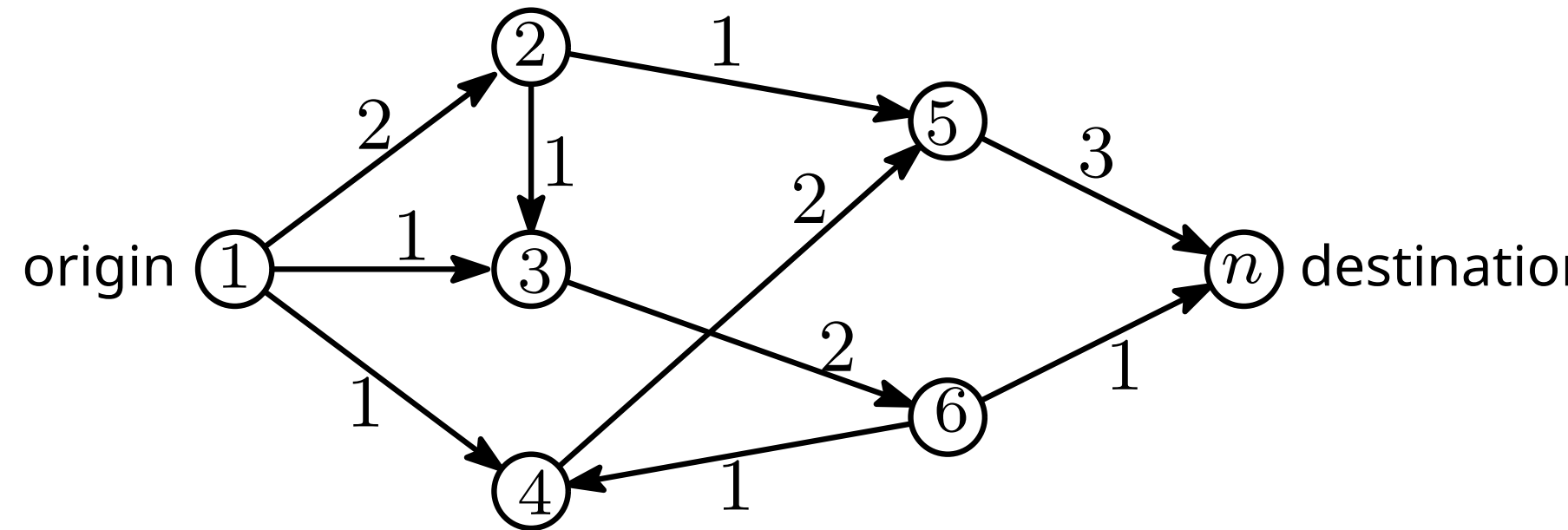
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primal

Max Flow



What is the dual?

Flows and Cuts in a Network

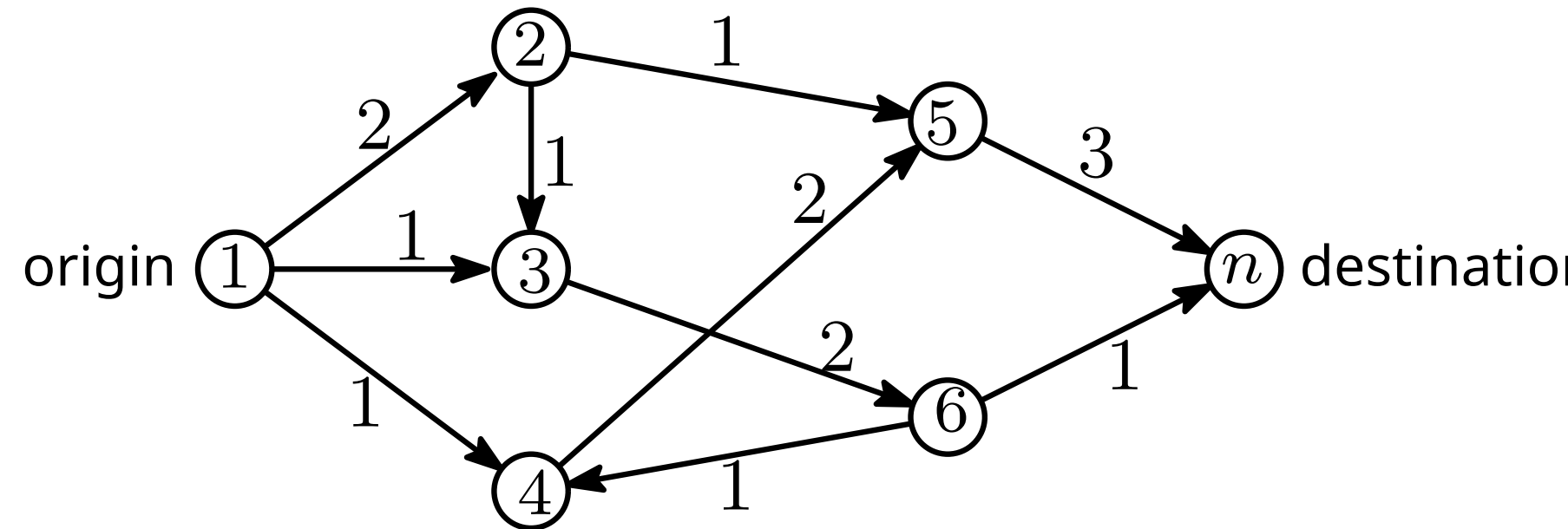
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primal

Max Flow



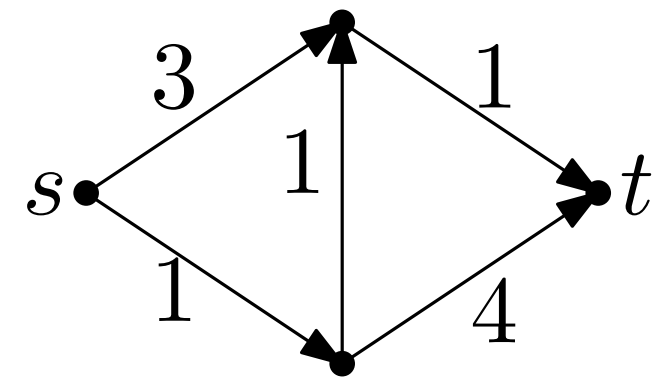
$$\begin{aligned} \min \quad & \sum_{e \in E} c(e)y_e \\ \text{subject to} \quad & \sum_{e \in p} y_e \geq 1 \quad \forall p \in P \\ & y_e \geq 0 \quad \forall e \in E \end{aligned}$$

dual

Min Cut

Shortest Path Problem

Given a directed graph $G = (V, E)$ with edge weights w , we are looking for a shortest path from s to t .



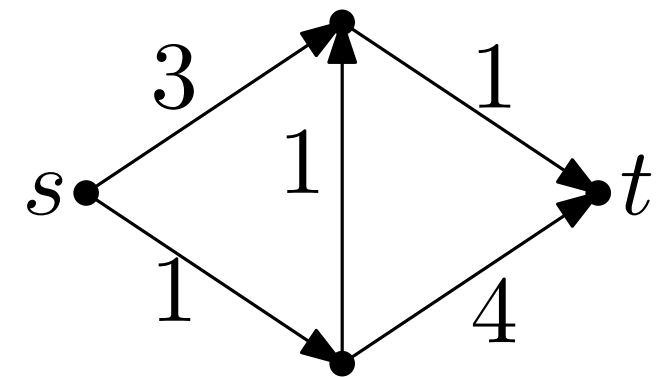
Can we also model this as ILP? Yes! How?

Idea 1: use variable x_{uv} for whether edge (u, v) is used.

$$\begin{aligned} &\text{minimize} && \sum_{(u,v) \in E} w(u,v)x_{uv} \\ &\text{subject to} && \sum_{(u,v) \in E} x_{uv} = \sum_{(v,w) \in E} x_{vw} \text{ for each vertex } v \in V \setminus \{s, t\}, \text{ and} \\ &&& \sum_{(u,t) \in E} x_{ut} = 1. \\ &&& x_{uv} \in \{0, 1\} \text{ for each edge } (u, v) \in E. \end{aligned}$$

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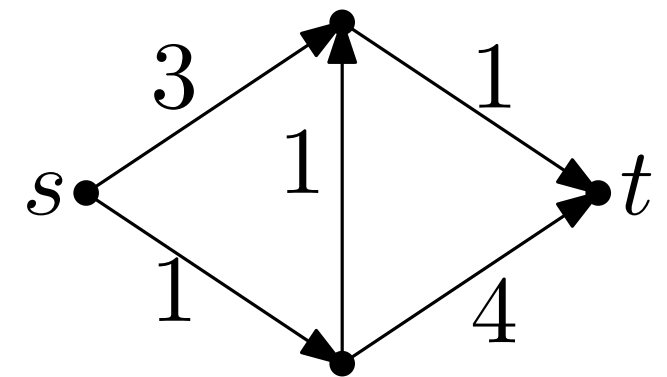
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LP-relaxation has $\{0, 1\}$ -solution,
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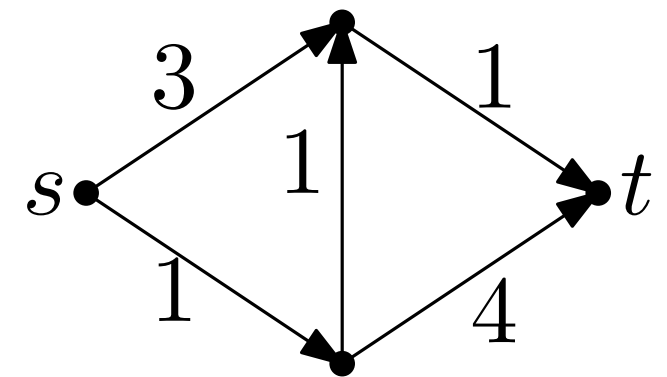
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A is total
unimodular

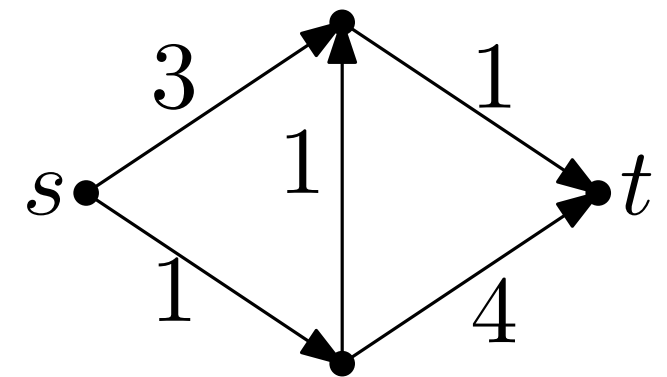
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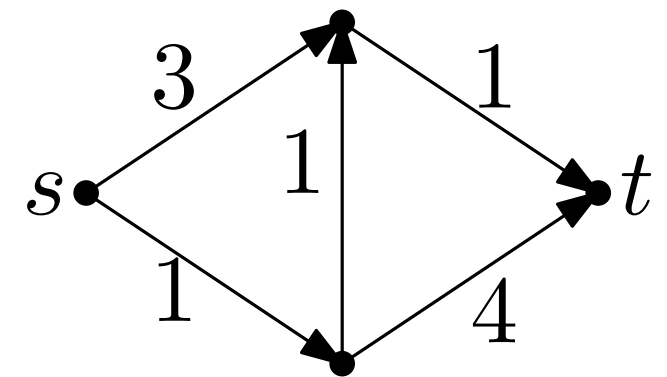
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Then we want that $d_v \leq d_u + w(u, v)$ for all edges (u, v) .



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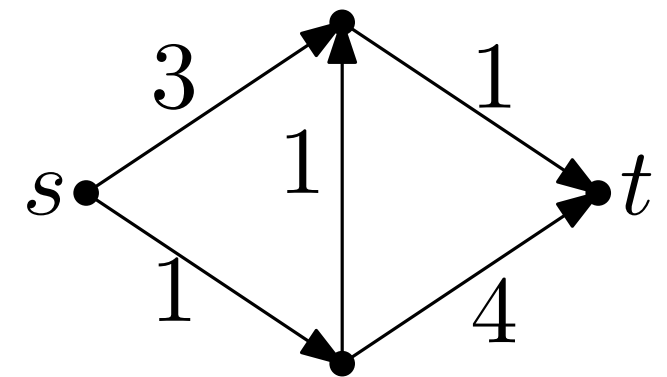
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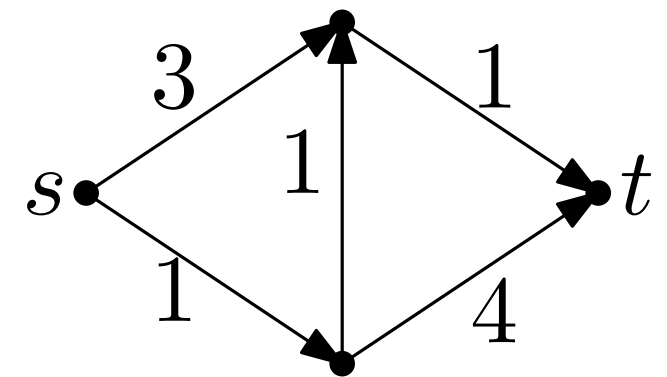
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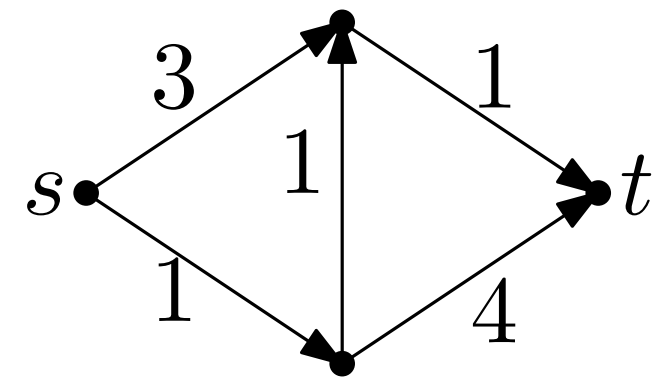
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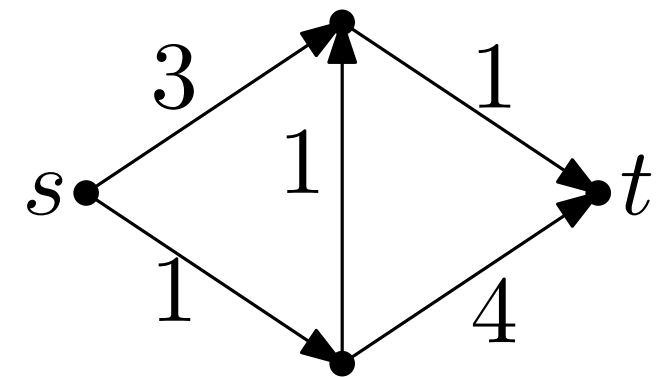
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Is there a connection between the two LPs? They are dual to each other!