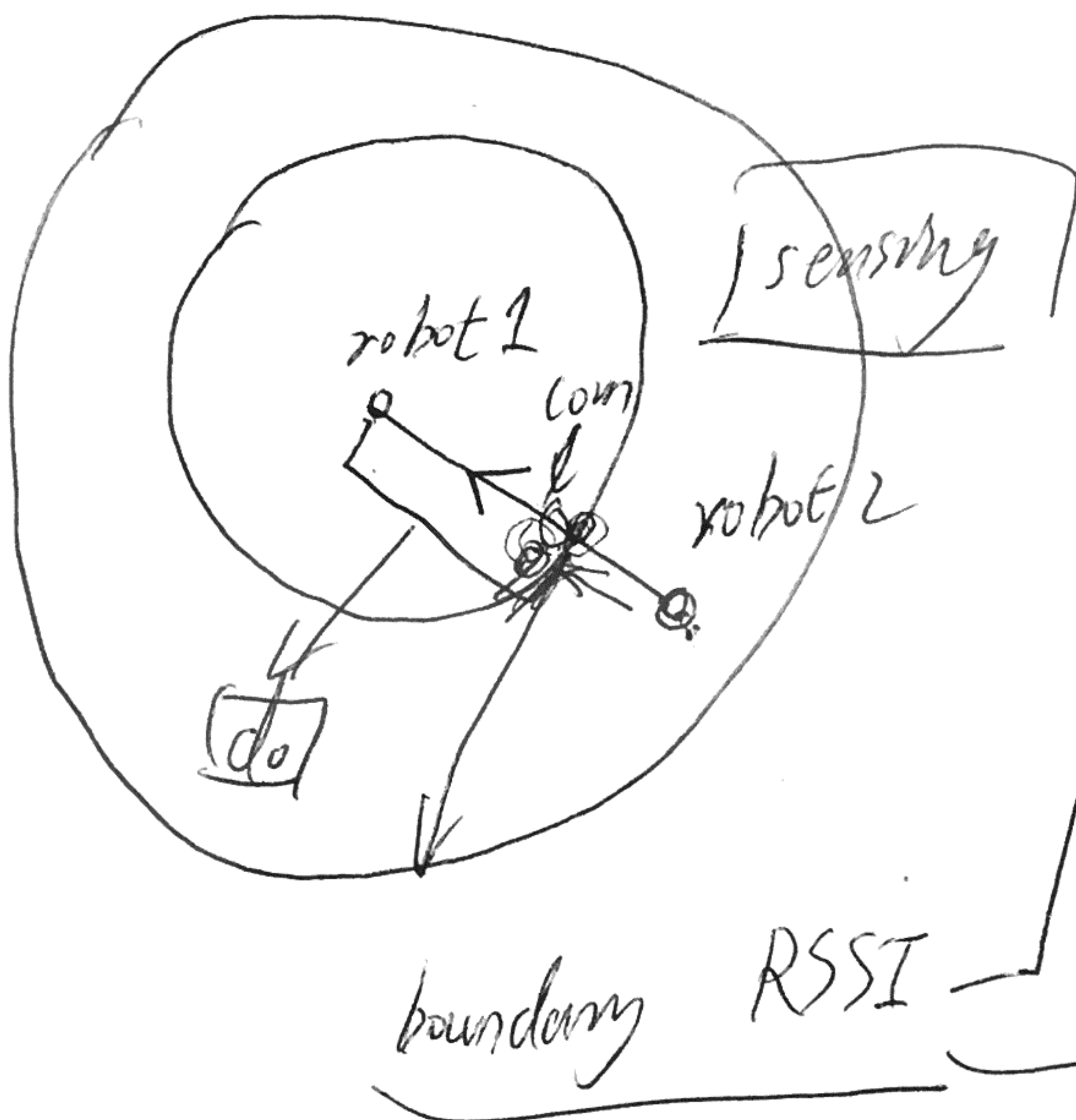


1. drive robot



velocity

direction  $\leftarrow$  Dolt

scalar  $\leftarrow$  RID

boundary RSSI

2. ~~do~~ SNR = 30

white

+

fading

+

Path loss

$\rightarrow$

distance

do

(85%)

~~Rayleigh~~ Rayleigh (90%)

RSSI

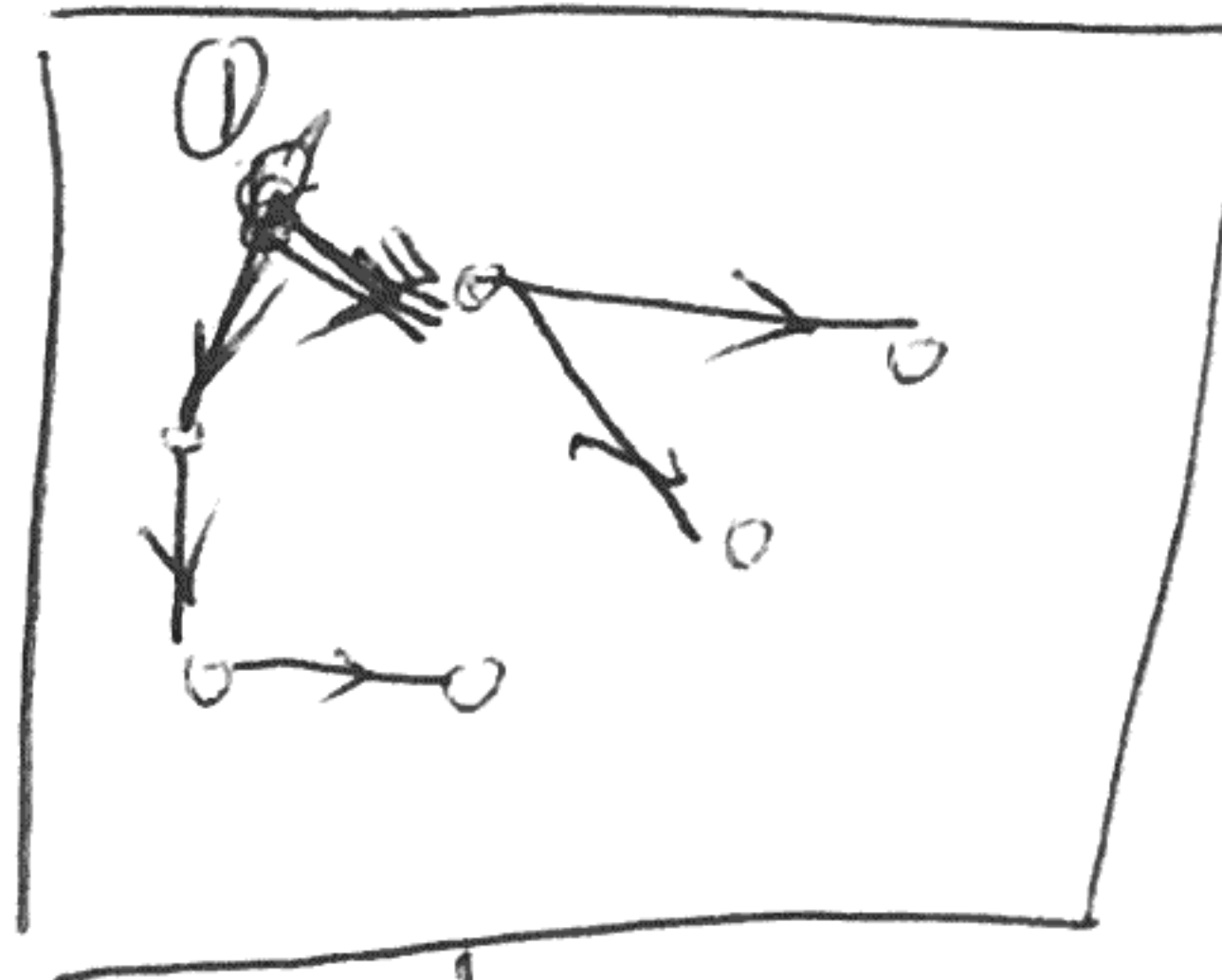
3. function → 8 robot

8

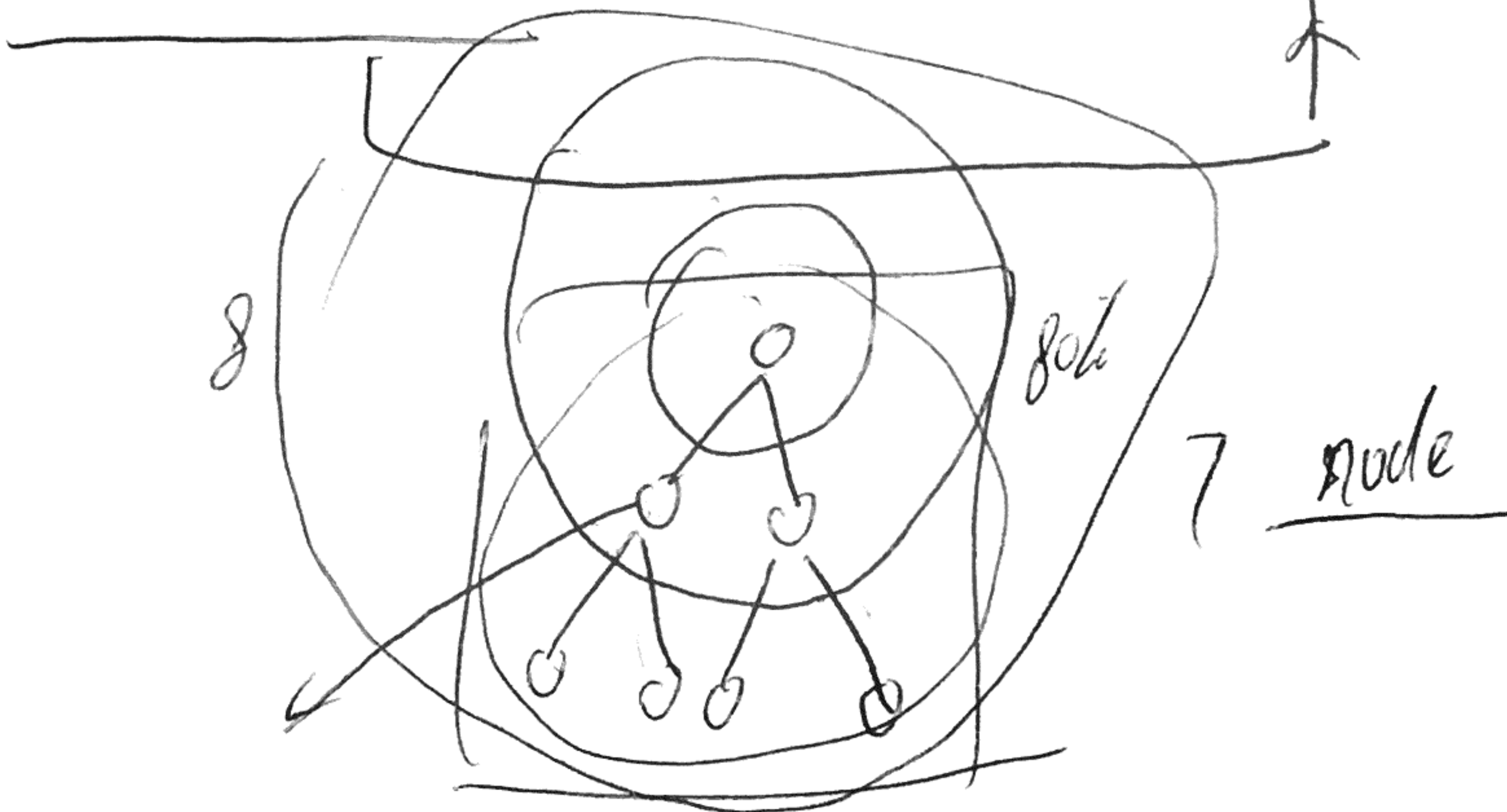
7

7x8

56



detection



RSSI

boundary RSSI

10%

or

2%

90% boundary RSSI

how many node