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### TODO title

 $TODO\ subtitle$ 

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### Abstract

THIS IS MY ABSTRACT

## Preface

Please write all your preface text here. If you do so, don't forget to thank your supervisor, other committee members, your family, colleagues etc. etc.

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# Chapter 1

# Introduction

Nothing here...

### Chapter 2

### Checkpoint Consensus

### 2.1 Preliminaries

#### 2.1.1 Requirements

- Permissionless
- Byzantine fault tolerant
- No PoW
- Works under churn
- Underlying data structure is TrustChain
- $\bullet\,$  Detects forks or double-spends
- No step in the protocol blocks transactions
- Application independent

#### 2.1.2 Assumptions

- Asynchronous network
- Private and authenticated channel
- We elect N consensus promoters in every round, we assume the number of faulty promoters is f and N = 3f + 1.
- Promoters have the complete history of the previously agreed set of transactions (TX).

#### 2.1.3 Notations

- y = H(x) is a cryptographically secure hash function (random oracle), the domain x is infinite and the range is  $y \in \{0, 2^{256} 1\}$ .
- $\bullet$  Every node in the system has an identifier i and a blockchain

$$B_i = \{b_{i,j} : j \in \{1 \dots h\}\},\$$

where h is the height of the chain. Note that  $h = |B_i|$ 

• Each block  $b_{i,j}$  has a type  $t \in \{\tau, \gamma\}$ , denoted by  $b_{i,j}^t$ . Blocks without the superscript can be of any type.

- $T(b_{i,j}) = \{\tau, \gamma\}$  is the type function, where its domain is a block and outputs the corresponding type of the block.
- A block of type  $\tau$  is a transaction block or TX block. It is a six-tuple, i.e.

$$b_{i,j}^{\tau} = (H(b_{i,j-1}), h_s, h_r, s_s, s_r, m).$$

 $h_s$  and  $h_r$  denote the height (the sequence number for when the TX is made) of the sender and receiver respectively.  $s_s$  and  $s_r$  denote the signature of the sender and the receiver respectively.  $i = \{s, r\}$  and  $j = \{h_s, h_r\}$  and we call the block a sender block or a receiver block respectively.

- Given two TX blocks  $b_{i,j}^{\tau}$  and  $b_{i',j'}^{\tau}$ , but  $i \neq i'$ . If  $h_s = h'_s$ ,  $h_r = h'_r$ , m = m' and the signatures are valid, then we call them a pair.
- If there exist two TX blocks  $b_{i,j}^{\tau}$  and  $b_{i',j'}^{\tau}$ , where  $s_s$  and  $s'_s$  is created by the same public key and  $h_s = h'_s$  but  $i \neq i'$ , then we call this a *fork*.
- A TX block has two *inputs* blocks, to retrieve the input we define the *get-tx-input function*  $I^{\tau}$ . Let the pair of  $b_{i,j}^{\tau}$  be  $b_{i',j'}^{\tau}$ , then

$$I^{\tau}(b_{i,j}^{\tau}) = (b_{i,j-1}, b_{i',j'-1}).$$

• A block of type  $\gamma$  is a *checkpoint block* or *CP block*. It is a three-tuple, i.e.

$$b_{i,j}^{\gamma} = (H(b_{i,j}), H(\mathcal{C}_r), p)$$

where  $C_r$  is the consensus result in round r and  $p \in 0, 1$  which indicates whether i wish to become a promoter in the following consensus round.

• A CP block has one input, we define the get-cp-input function

$$I^{\gamma}(b_{i,j}^{\gamma}) = b_{i,j-1}.$$

• Given the input  $b_{i,j}^{\tau}$ , we define the get-nearest-cp function

$$C(b_{i,j}^{\tau}) = (b_{i,q}^{\gamma}, b_{i,b}^{\gamma})$$

where  $a = \arg\min_{k,k < j, T(b_{i,k}) = \gamma} (j-k)$  and  $b = \arg\min_{k,k > j, T(b_{i,k}) = \gamma} (k-j)$ .

• Given two  $\gamma$  blocks, we define get-piece function

$$P(b_{i,a}^{\gamma}, b_{i,b}^{\gamma}) = \{b_{i,j} : b_{i,j} \in B_i, a \le j \le b\}.$$

• Given two blockchains and a message, we define the do-tx-function

$$X_{\tau}(B_s, B_r, m) = (B'_s, B'_r)$$

where  $B_s' = \{(H(b_{s,h_s}), h_s+1, h_r+1, s_s, s_r, m)\} \cup B_s, B_r' = \{(H(b_{r,h_r}), h_s+1, h_r+1, s_s, s_r, m)\} \cup B_r, h_s = |B_s| \text{ and } h_r = |B_r|.$ 

• Given a blockchain, we define the do-cp function

$$X_{\gamma}(B_i, r, p) = \{ (H(b_{i,h}), H(\mathcal{C}_r), p) \} \cup B_i$$

where  $h = |B_i|$ , and  $C_r$  is the latest consensus result

- Note that  $X_{\tau}$  and  $X_{\gamma}$  perform a state transition.
- The result of a consensus in round r is a set of two-tuple of CP. Namely,  $C_r = \{(b_{i,a}^{\gamma}, b_{i,b}^{\gamma}) : a < b, \text{ agreed by the promoters}\}.$

### 2.2 Checkpoint consensus

#### 2.2.1 Promoter registration

Node i can register as a promoter when the latest consensus result is announced (suppose after the completion of round r-1), then it generates a new block using  $b=T_{\gamma}(B_i,r-1,1)$ . The current promoters (in round r) may decide to include b in the new consensus result. If b is in it, then i becomes one of the promoter of round r+1.

We can fix the number of promotors to N by sorting the promotors by their "luck value" and taking the first N.

#### 2.2.2 Setup phase

We begin in the state where  $C_{r-1}$  has just been agreed but has not been disseminated yet. The promoters

**Lemma 1.** If a node sees a valid  $C_r$  and another node sees a valid  $C'_r$ , then  $C_r = C'_r$ .

Proof.

**Lemma 2.** The new set of promoter for the next consensus round is consistent with respect to all the nodes in the network.

**Lemma 3.** Promoters waiting for a some time  $\Delta$  to collect transactions does not violate the asynchronous assumption.

Corollary 1. The setup phase satisfies the validity, correctness and termination properties.

#### 2.2.3 Consensus phase

We need an atomic broadcast algorithm for the consensus phase. We use a similar but simplified construction as [3], where atomic broadcast is constructed from the reliable broadcast<sup>1</sup> [1] and asynchronous common subset (ACS). The ACS protocol requires a binary Byzantine agreement protocol, and for that it needs a trusted dealer to distributed the secret shares. Promoters can check whether the secret shares are valid, but they cannot prevent the dealer from disclosing the secrets.

There techniques that uses no dealers. First is to use PBFT [2], but we must change our asynchronous assumption into the weak synchrony assumption. Second is to use an inefficient binary Byzantine agreement protocol where its message complexity is  $O(N^3)$  rather than  $O(N^2)$  and becomes a bottleneck.

Suppose we use a dealer, what is the effect to the algorithm if the dealer is malicious?

#### 2.3 Fraud detection

Here we provide two techniques for fraud detection. The first guarantees fraud detection but is not practical. The second is a randomised solution that detects fraud with a high probability.

#### 2.3.1 Depth first search

```
bs = \emptyset

procedure REVERSE-DFS(G, b)

bs \leftarrow b \cup bs

if t = \text{genesis then}

return 1
```

<sup>&</sup>lt;sup>1</sup>Reliable broadcast solves the Byzantine generals problem.

```
end if
    for all d \in I(b) do
        if VALID(d) = 0 then
            return 0
        end if
    end for
   return 1
end procedure
procedure VALID(b,bs)
    (b_a^{\gamma}, b_b^{\gamma}) = C(b)
   p = P(b_a^{\gamma}, b_b^{\gamma})
   if (b_a^{\gamma}, b_b^{\gamma}) is in a consensus result then
        if p is a valid chain then
           if b does not have a fork in bs then
                return 1
            end if
        end if
    end if
   return 0
end procedure
```

**Lemma 4.** The reverse-dfs algorithm traverses all nodes that may have an effect on block b.

*Proof.* Recall that the TrustChain is a DAG, which always has a topological ordering. That is, for every edge (b',b), b' comes before b in the ordering, and nodes before b are its ancestors. If we reverse all the edges, then b' comes after b in the ordering, and nodes before b are its descendents. reverse-dfs is essentially running DFS with all the edges reversed. If the DFS outputs the visited nodes in reverse postordering, then the output is in topological order and contains all of b's original ancestors. Due to the hash pointers, only the ancestors can have an effect on b.

### 2.3.2 Random sampling

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