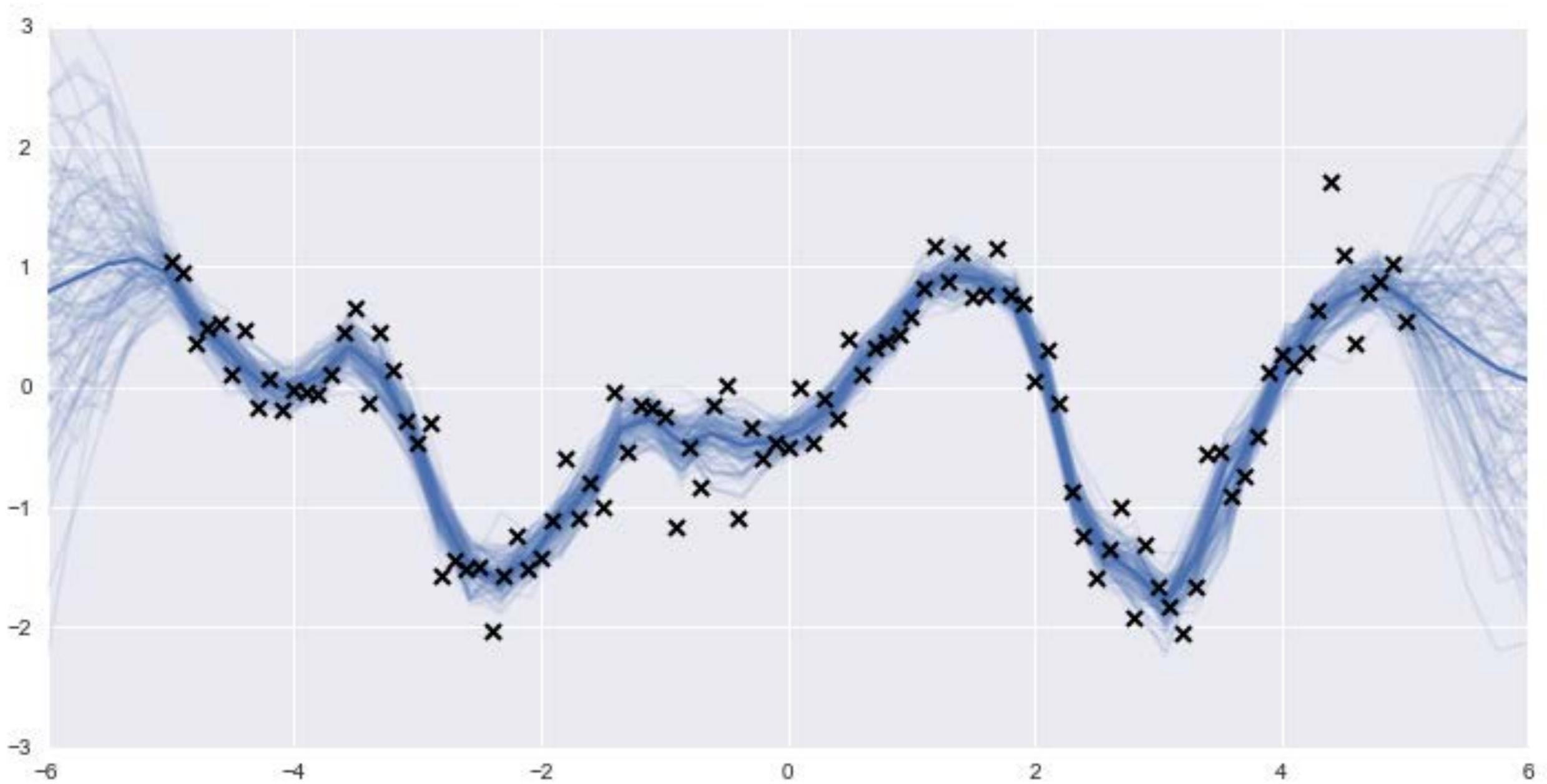


# ENM 540: Data-driven modeling and probabilistic scientific computing

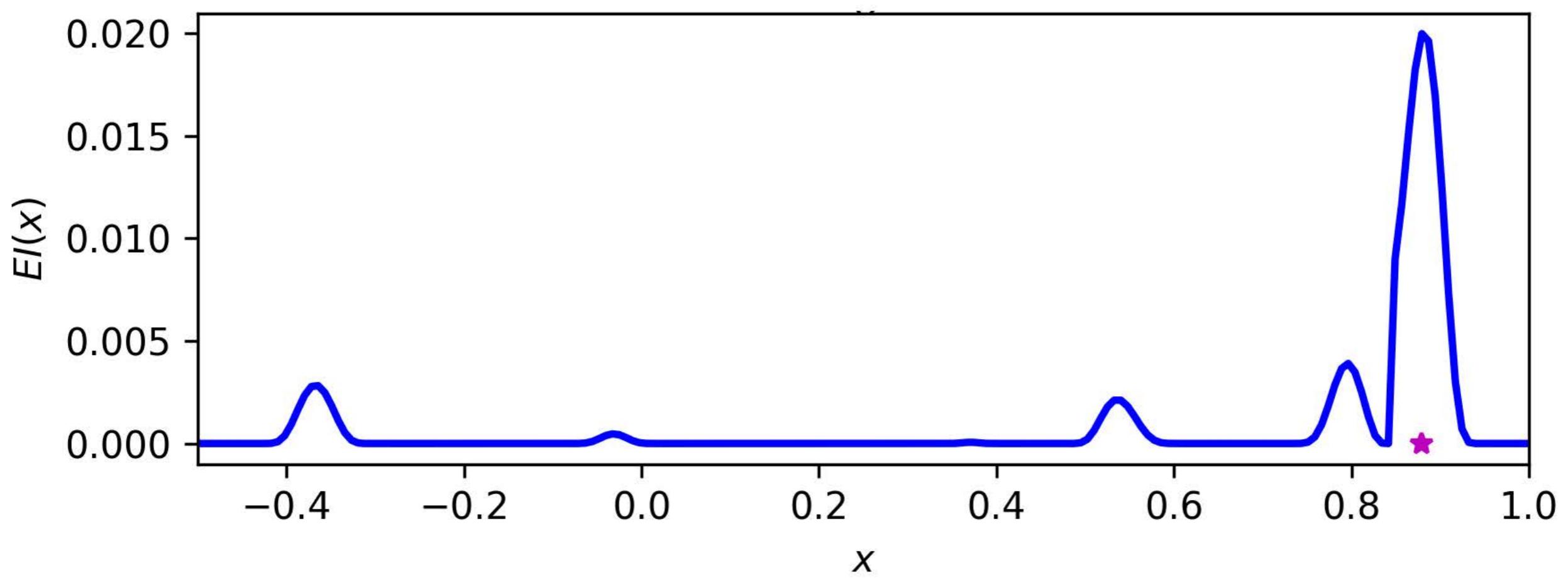
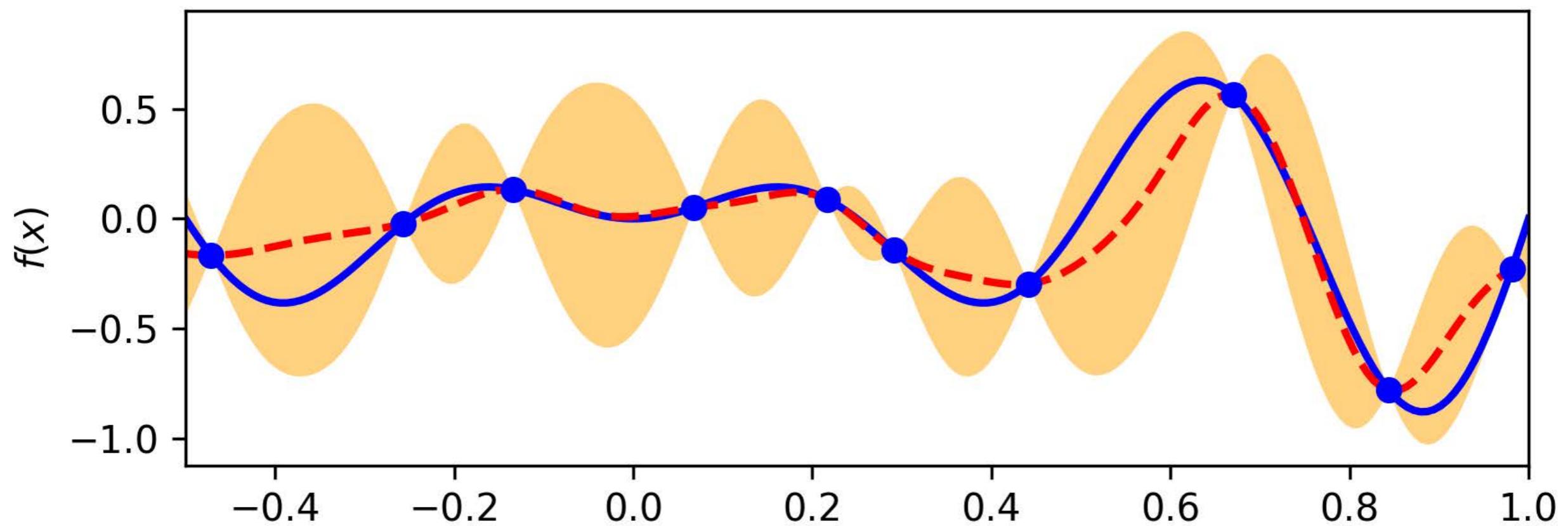
*Active learning & Bayesian optimization  
Applications*

Paris Perdikaris  
March 15, 2018

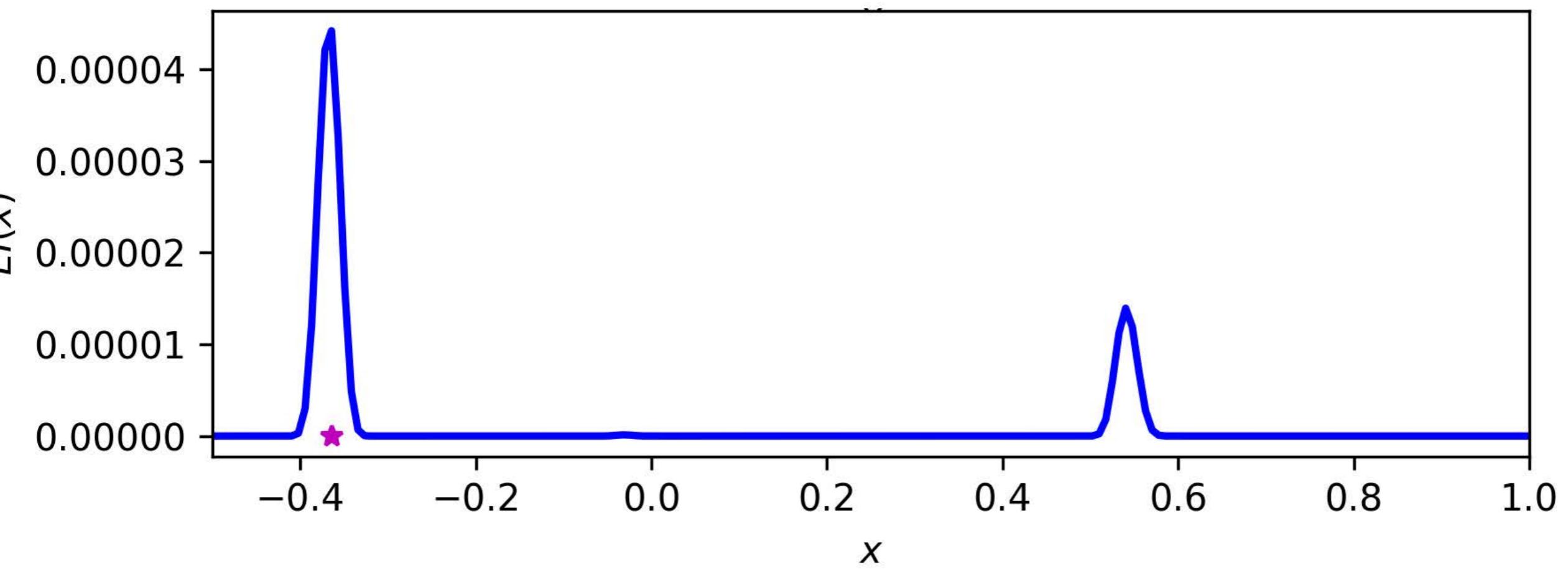
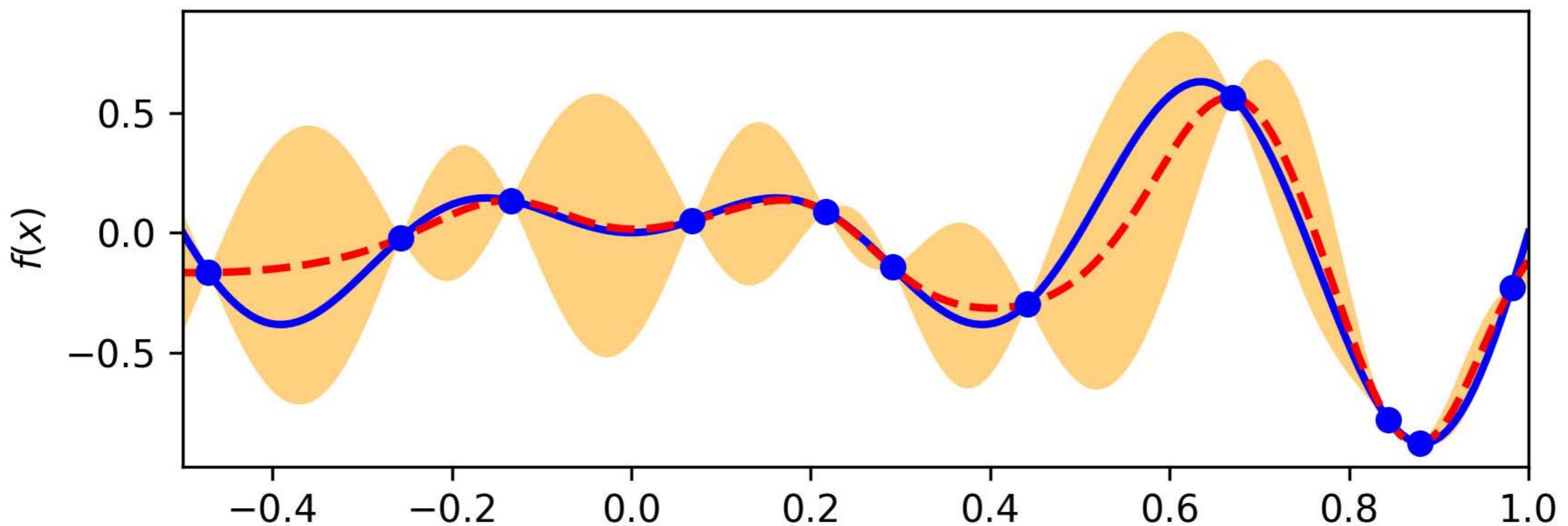




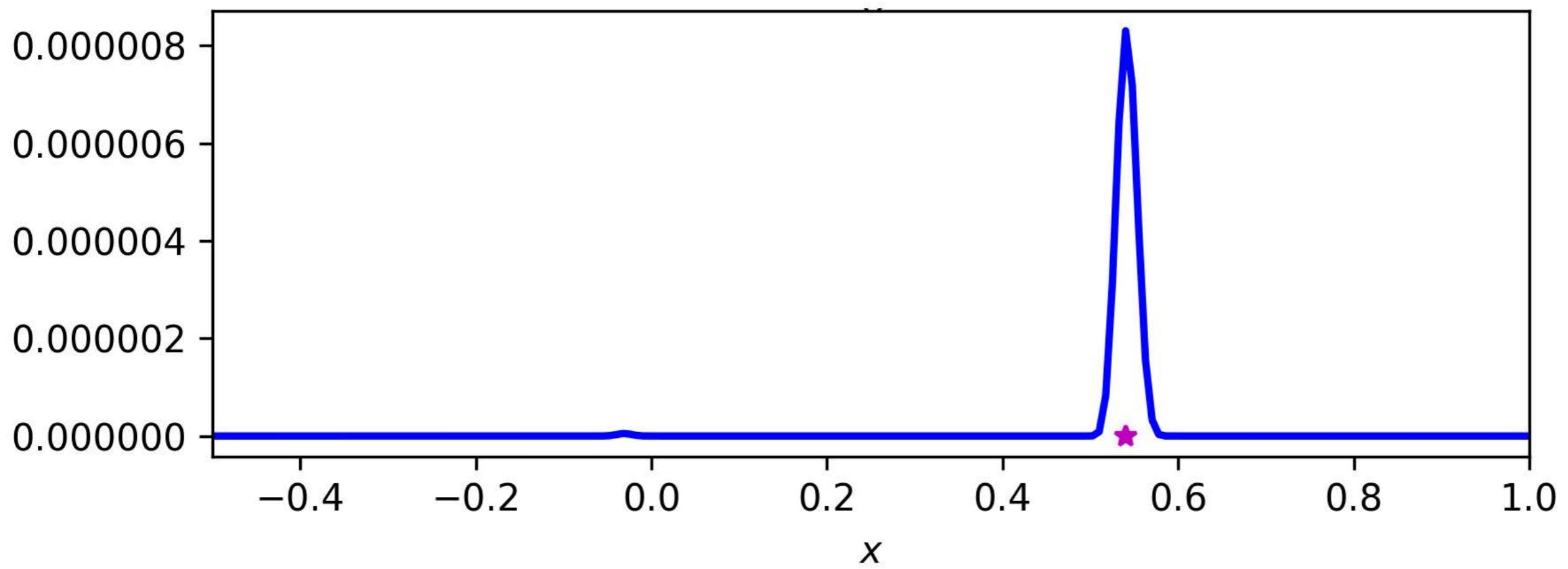
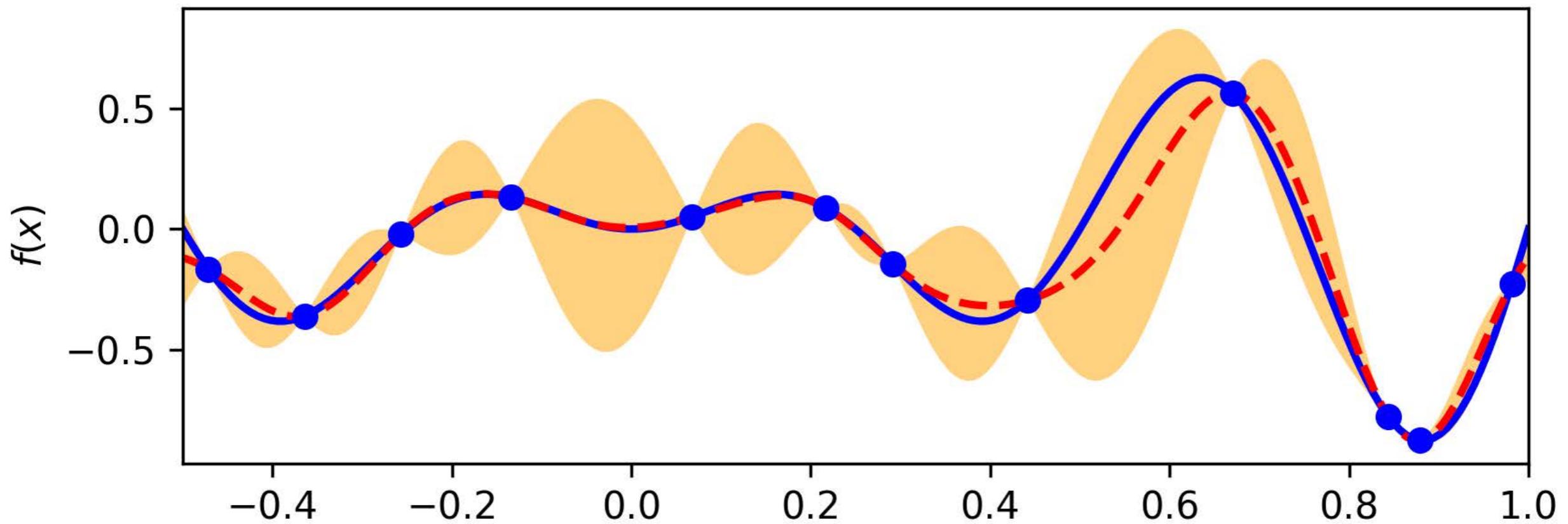
Iteration #1



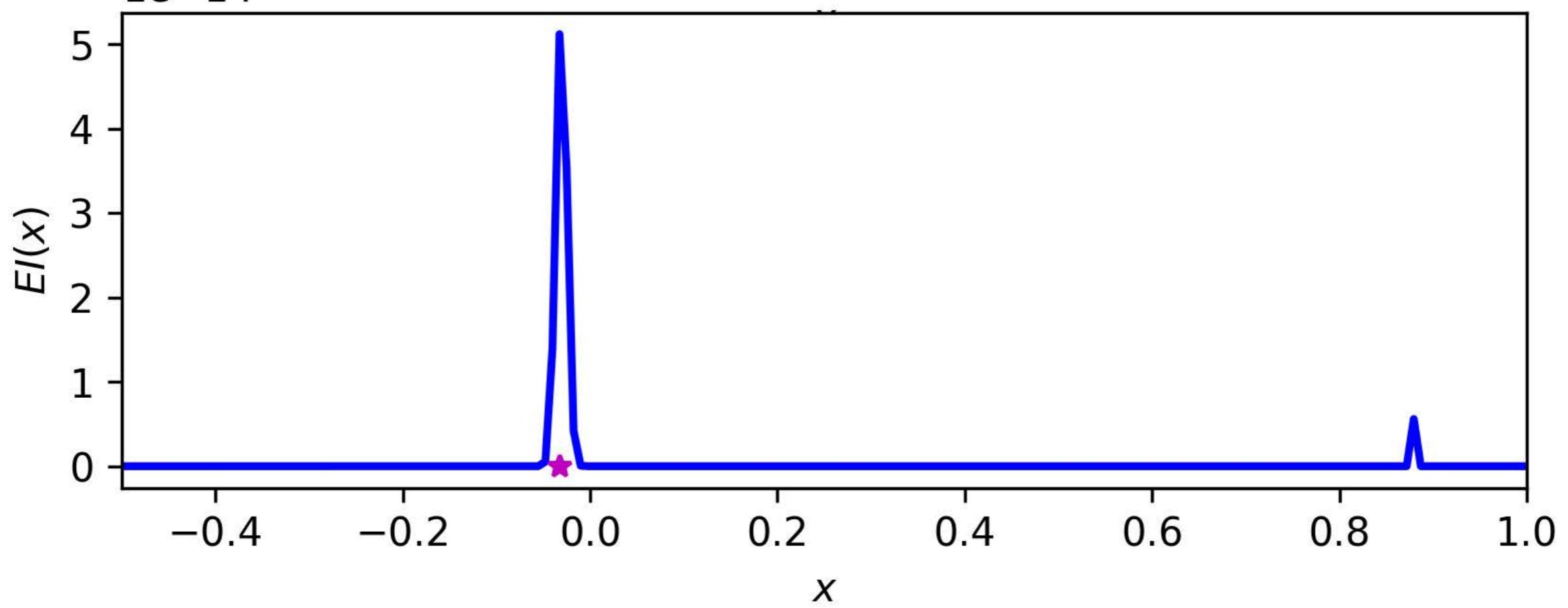
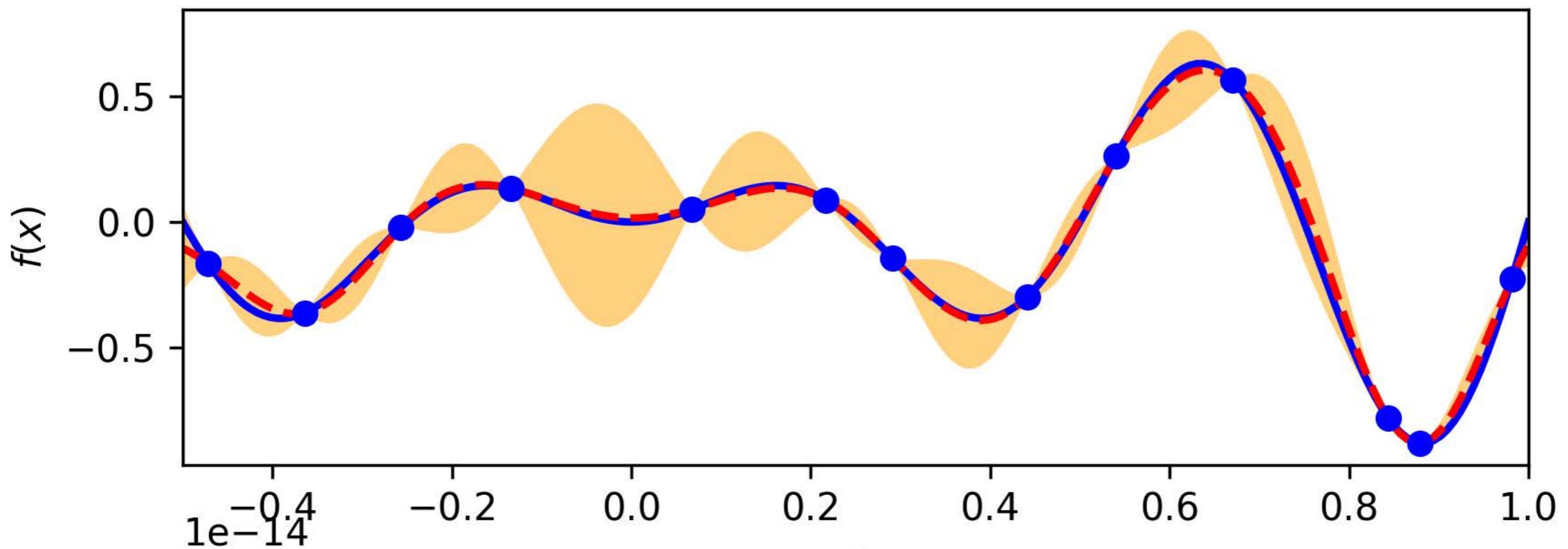
Iteration #2



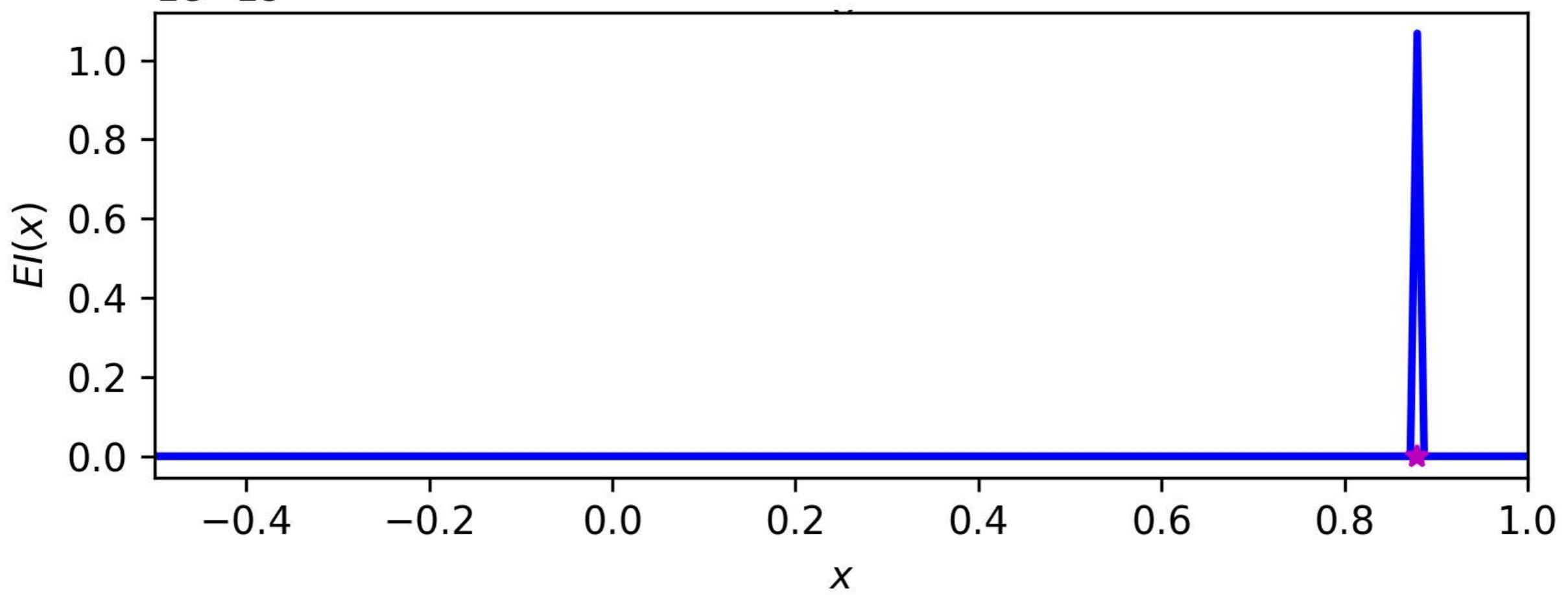
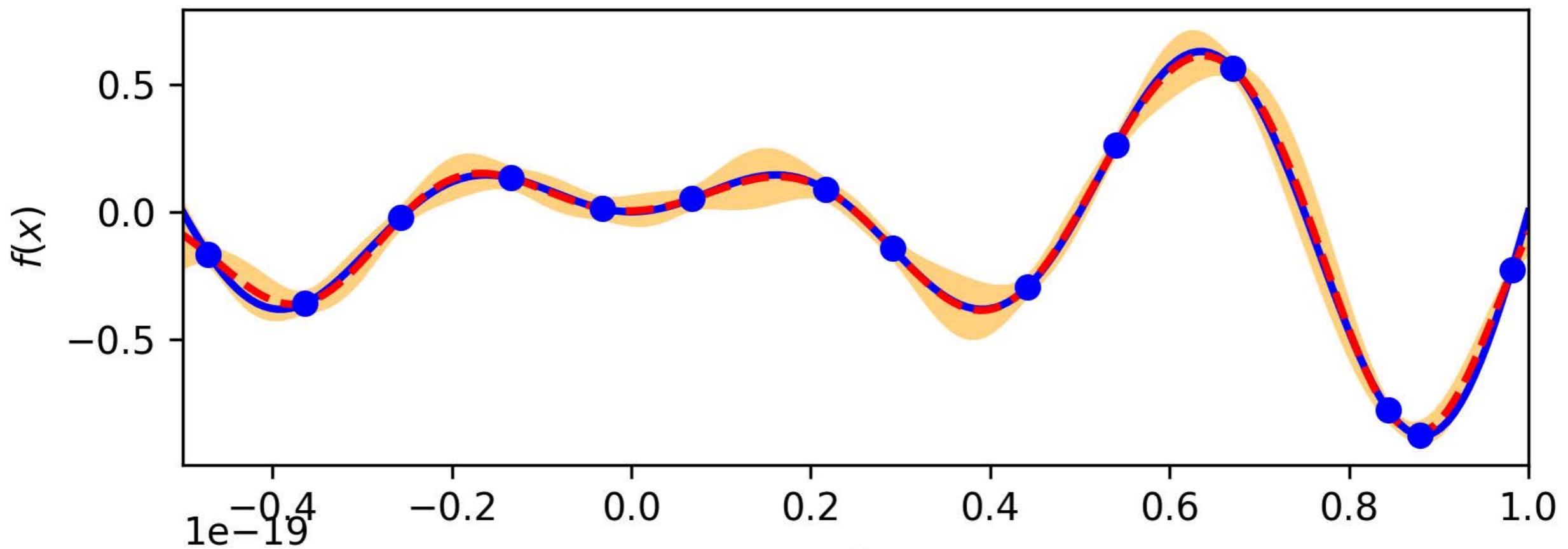
Iteration #3



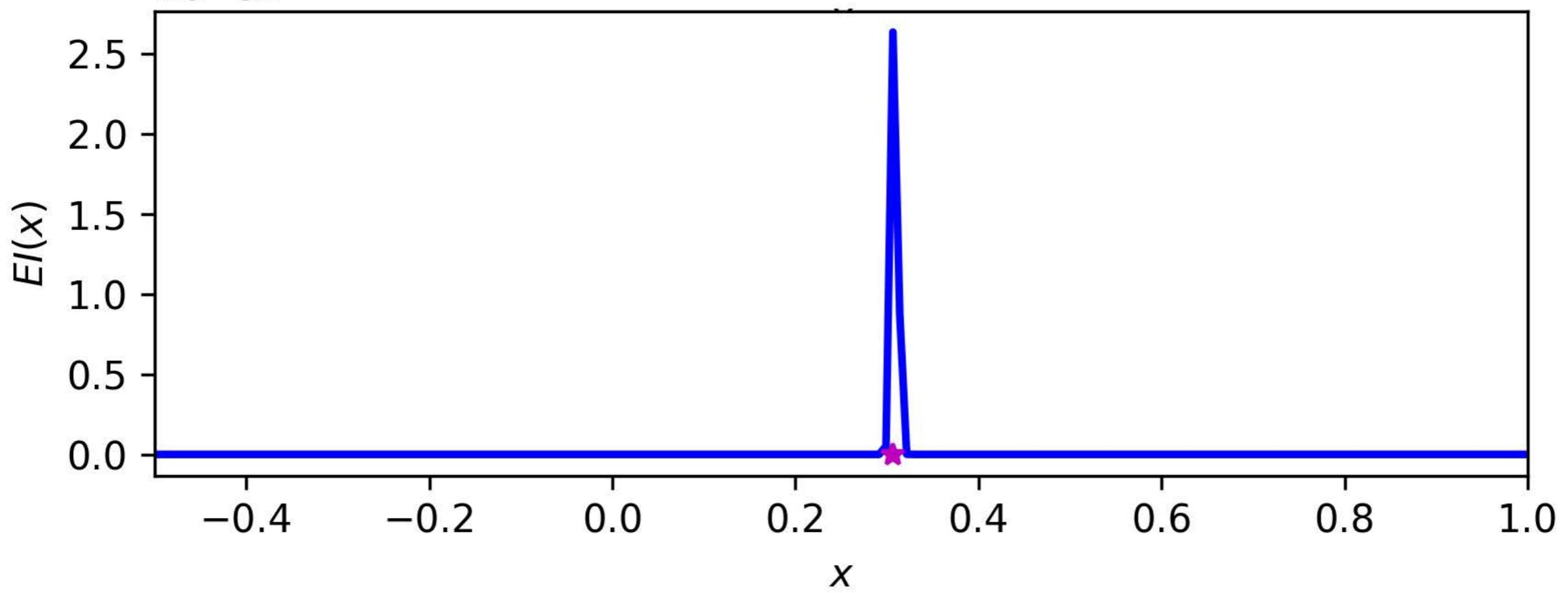
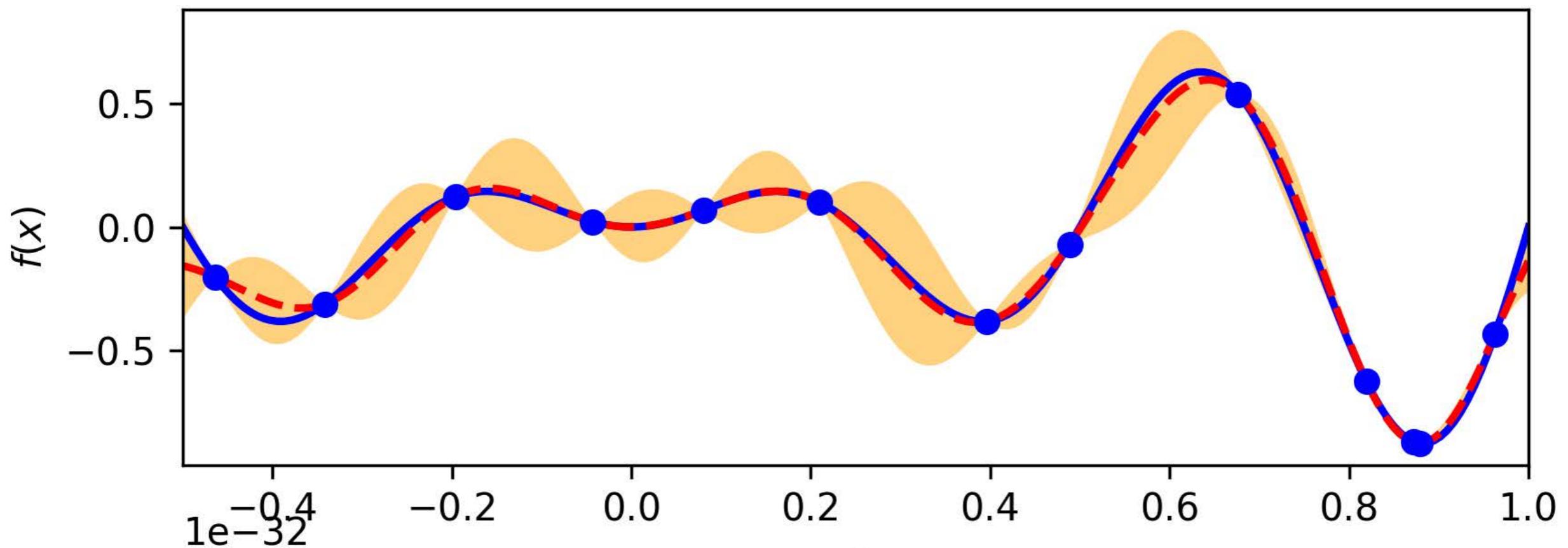
Iteration #4



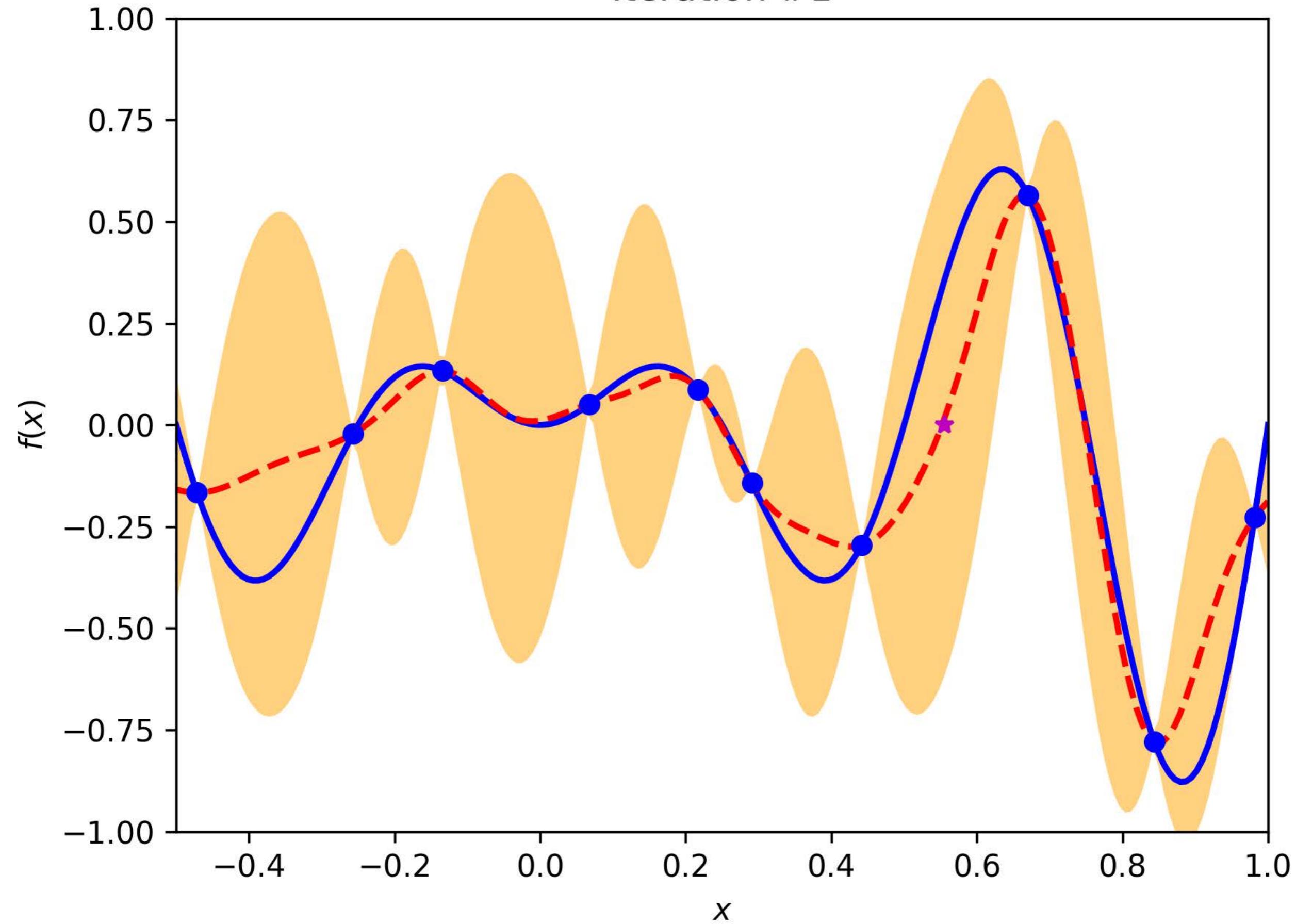
Iteration #5



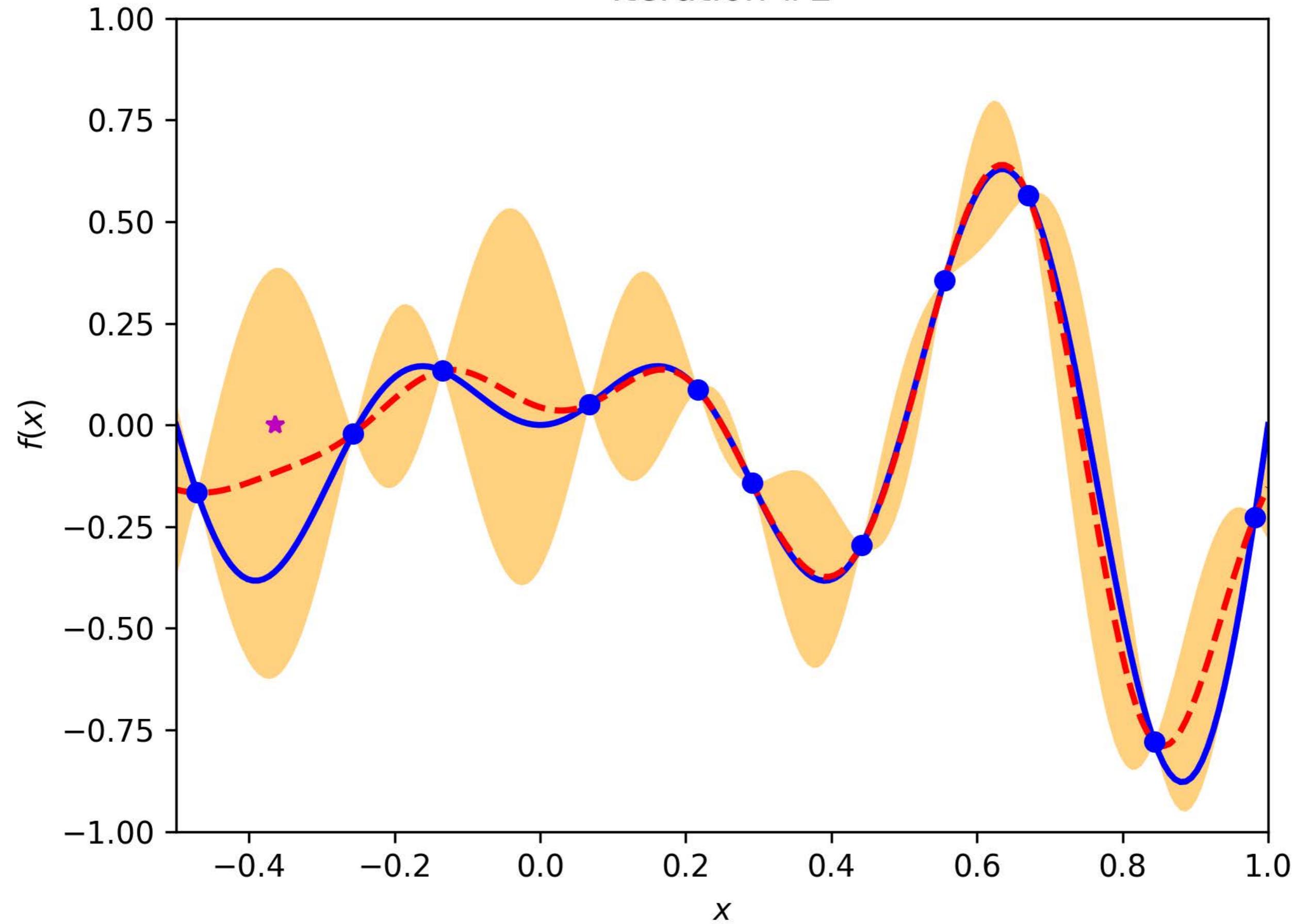
Iteration #6



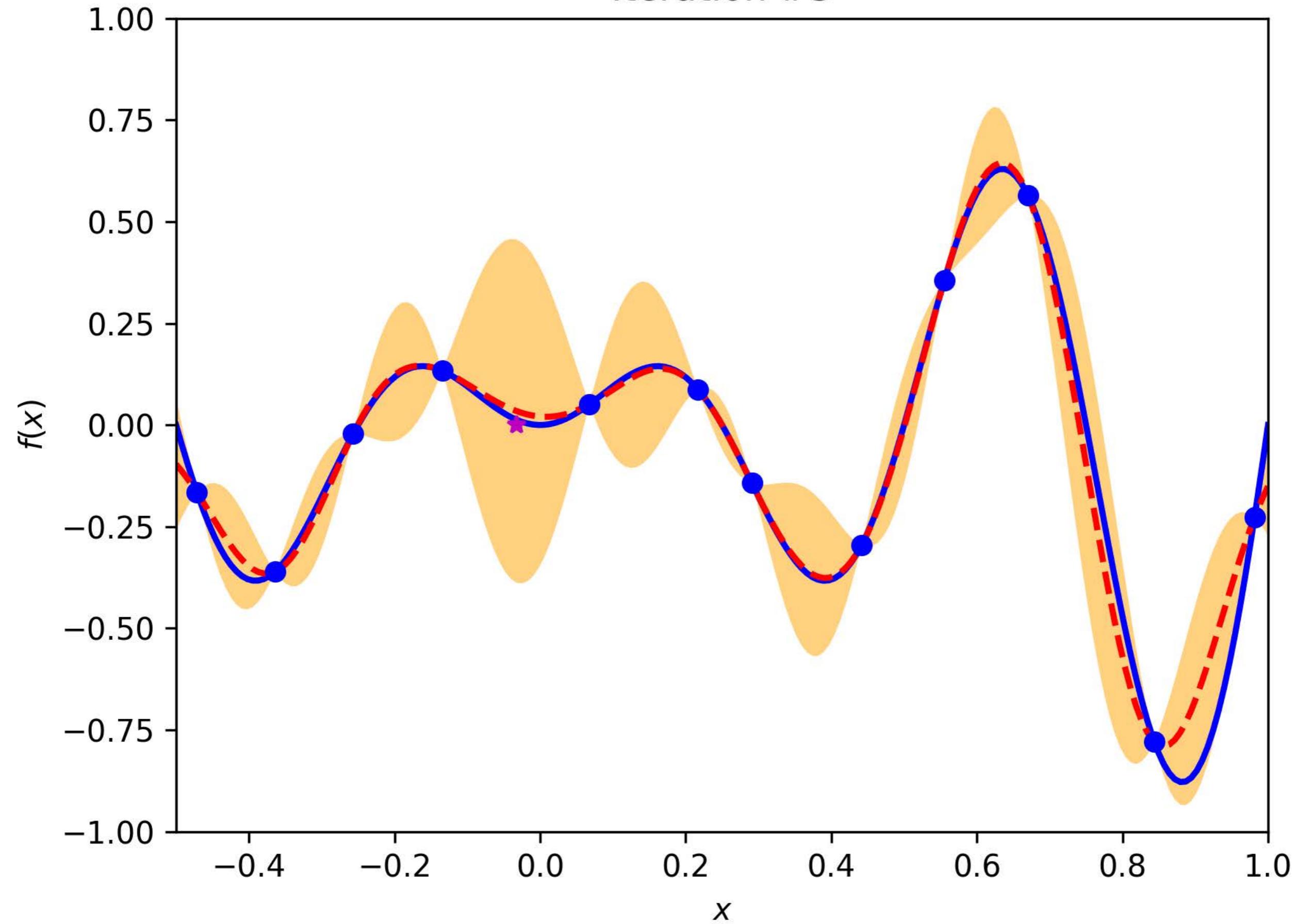
Iteration #1



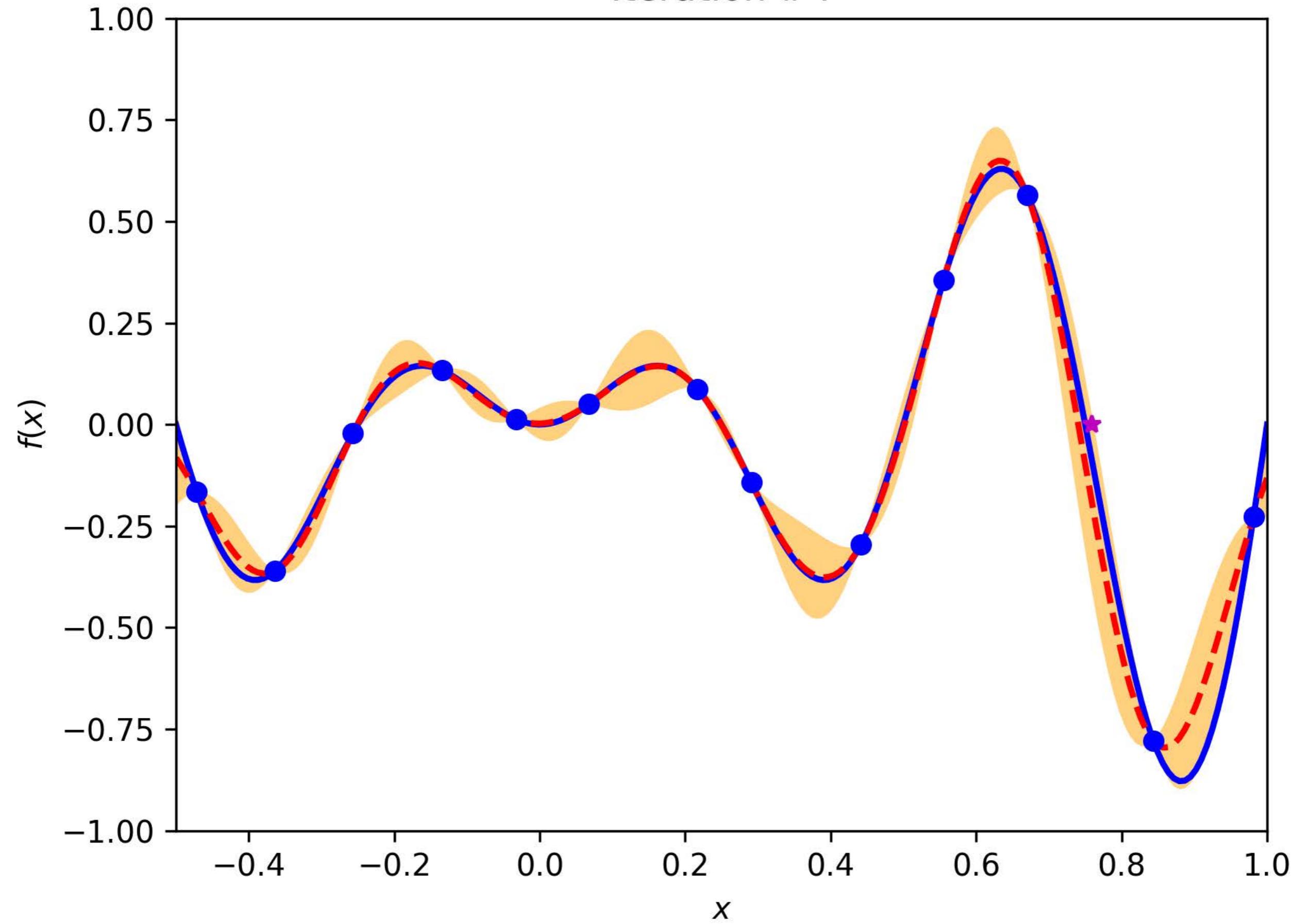
## Iteration #2



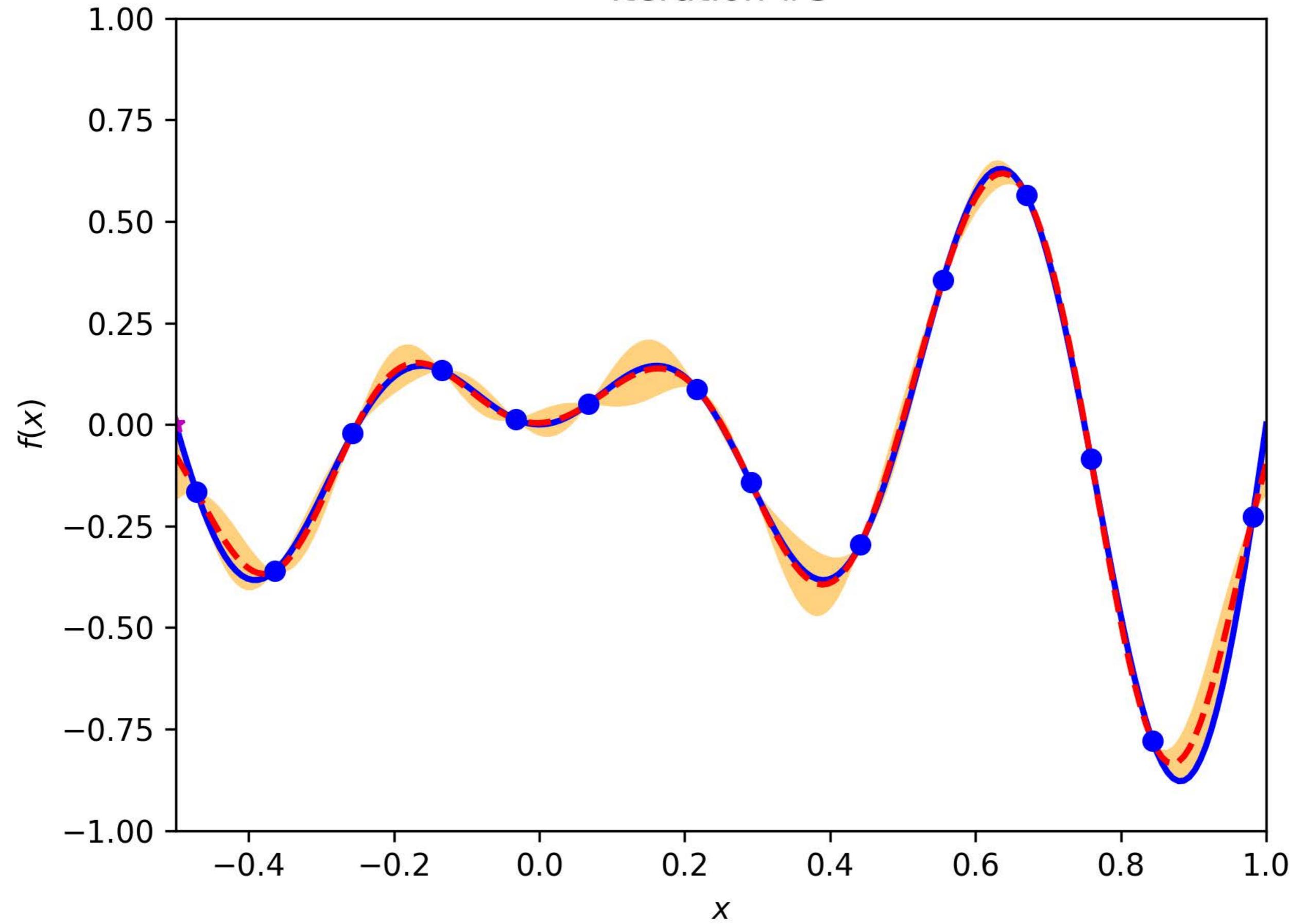
Iteration #3



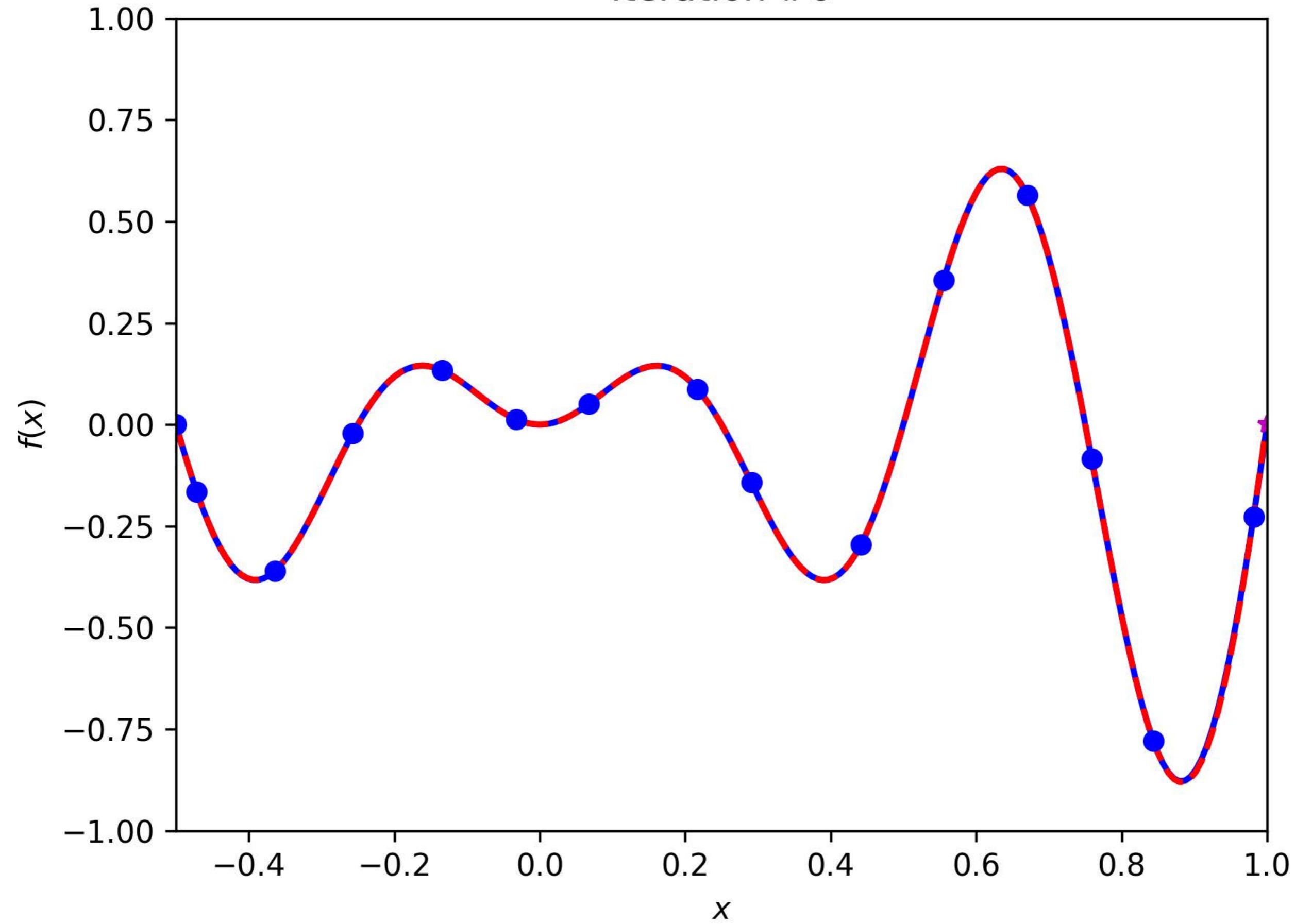
## Iteration #4



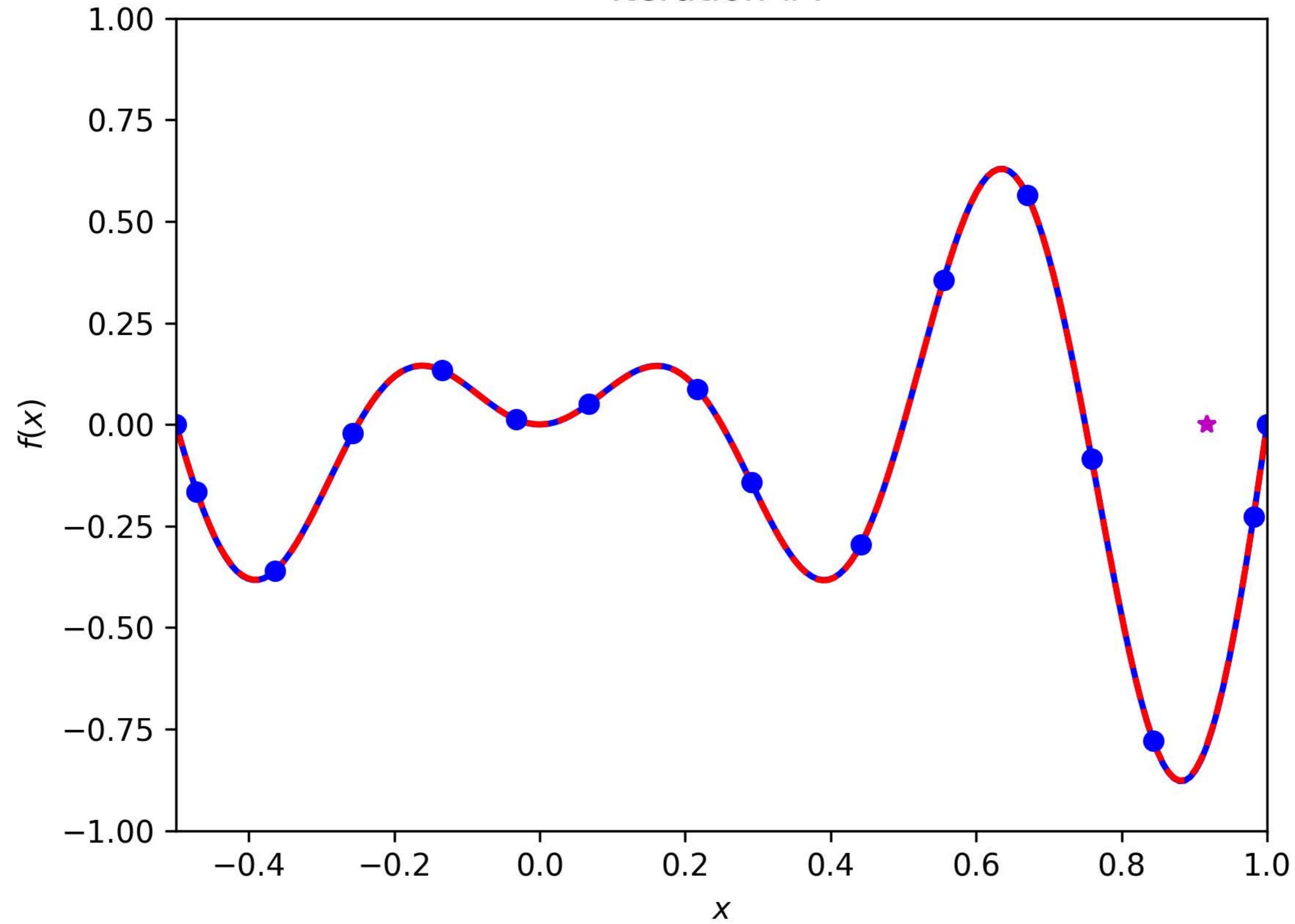
Iteration #5



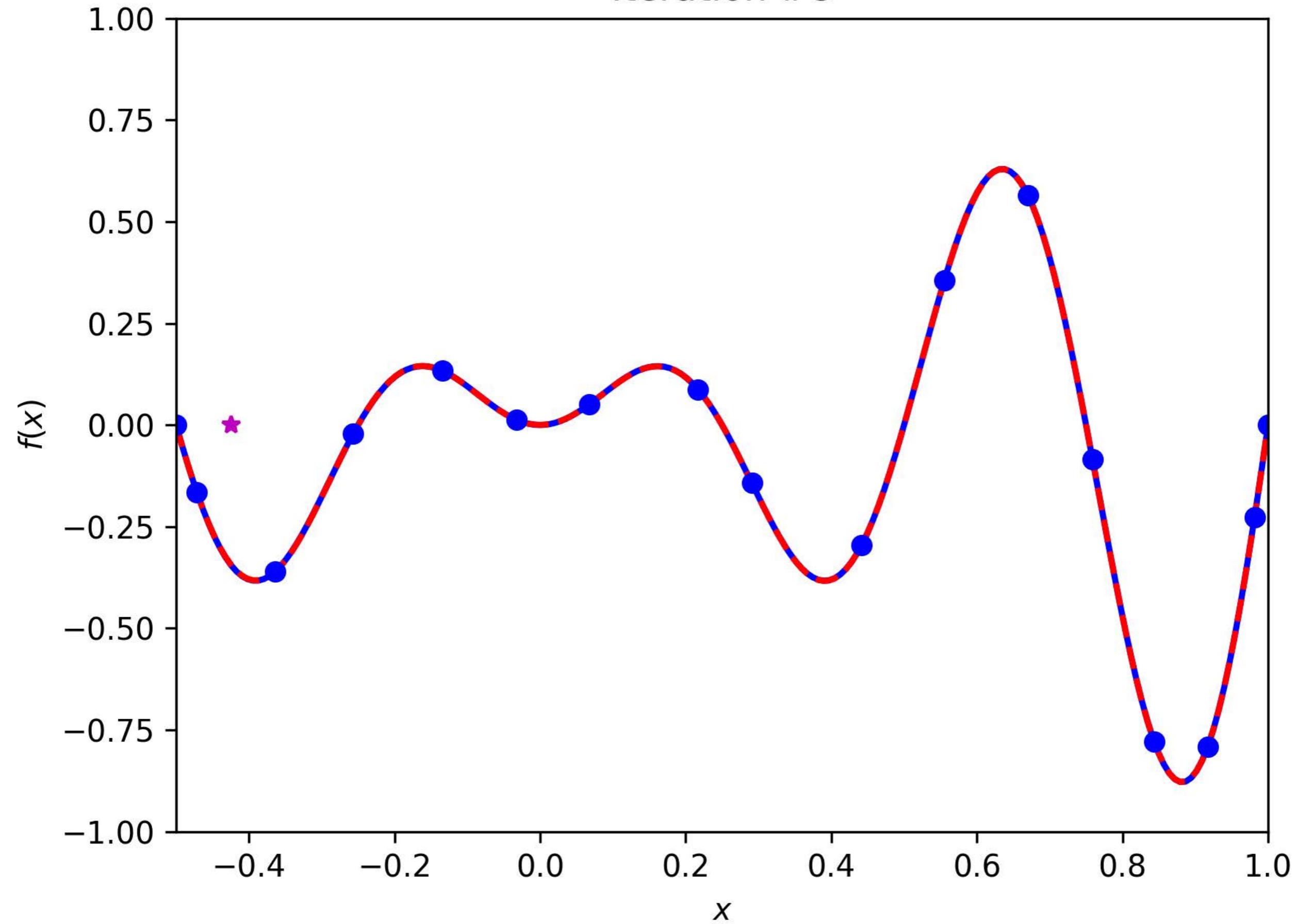
Iteration #6



Iteration #7



Iteration #8

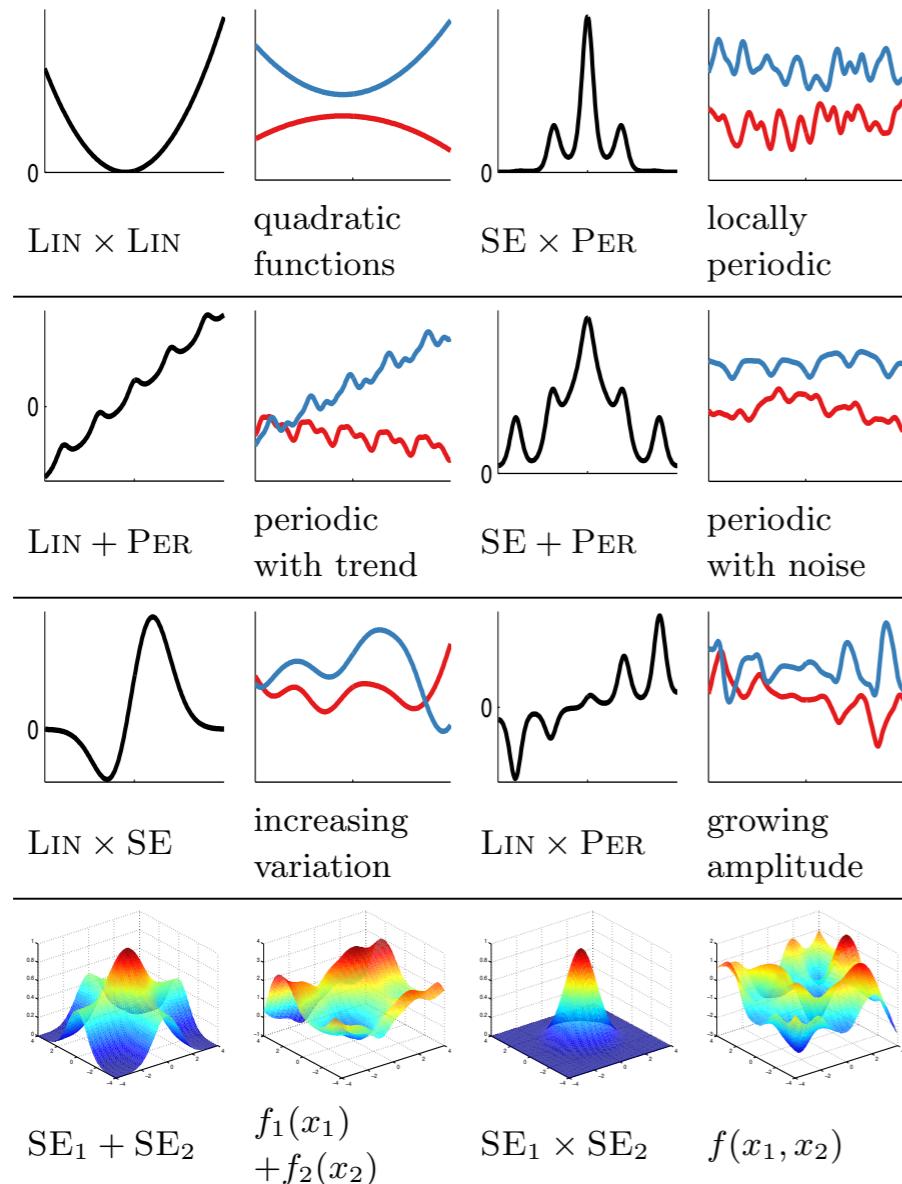


# Applications to model selection

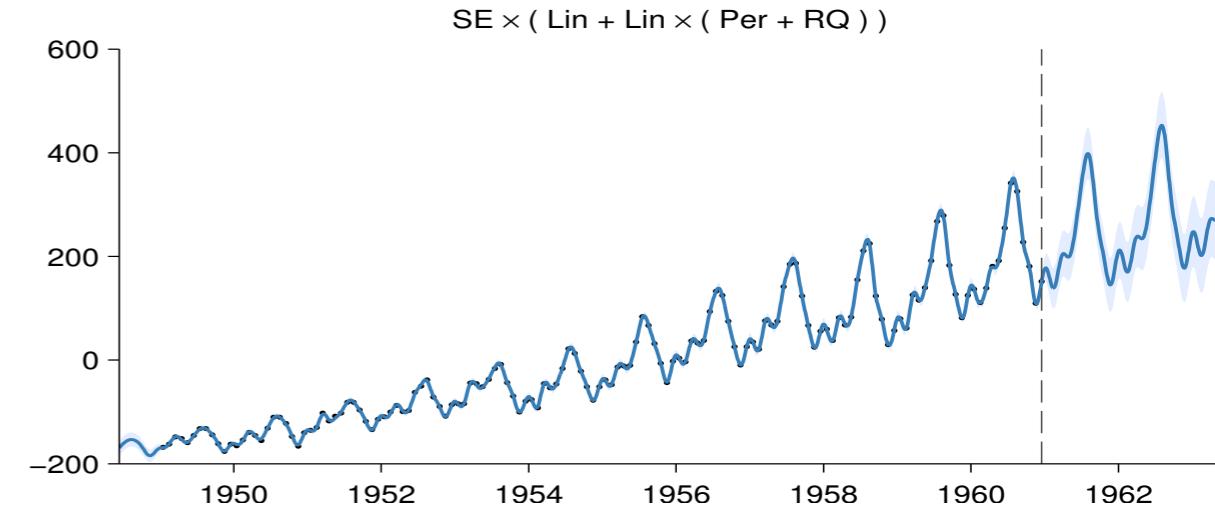
## The Kernel Cookbook: Advice on Covariance functions

by David Duvenaud

<https://www.cs.toronto.edu/~duvenaud/cookbook/>



<https://automaticstatistician.com/index/>



$$K_g(\mathcal{M}, \mathcal{M}'; \theta_g, \mathbf{X}) = \sigma^2 \exp\left(-\frac{1}{2} \frac{\bar{d}_{\text{H}}^2(\mathcal{M}, \mathcal{M}'; \mathbf{X})}{\ell^2}\right)$$

Malkomes, G., Schaff, C., & Garnett, R. (2016). Bayesian optimization for automated model selection. In *Advances in Neural Information Processing Systems* (pp. 2900-2908).

# Applications to tuning ML algorithms

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## Practical Bayesian Optimization of Machine Learning Algorithms

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**Ryan P. Adams**

School of Engineering and Applied Sciences  
Harvard University  
[rpa@seas.harvard.edu](mailto:rpa@seas.harvard.edu)

# Applications to control

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## PILCO: A Model-Based and Data-Efficient Approach to Policy Search

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Department of Computer Science & Engineering, University of Washington, USA

**Carl Edward Rasmussen**

CER54@CAM.AC.UK

Department of Engineering, University of Cambridge, UK

## Gaussian Processes for Data-Efficient Learning in Robotics and Control

Marc Peter Deisenroth, Dieter Fox, and Carl Edward Rasmussen



# Applications to control

## Bayesian Optimization with Safety Constraints: Safe and Automatic Parameter Tuning in Robotics

Felix Berkenkamp\*, Andreas Krause\*, and Angela P. Schoellig†

\*Learning & Adaptive Systems Group, Department of Computer Science, ETH Zurich, Switzerland

†Dynamic Systems Lab, Institute for Aerospace Studies, University of Toronto, Canada

Email: \*{befelix, krausea}@ethz.ch, †schoellig@utias.utoronto.ca

### Safe Controller Optimization for Quadrotors with Gaussian Processes

Felix Berkenkamp, Angela P. Schoellig, and Andreas Krause

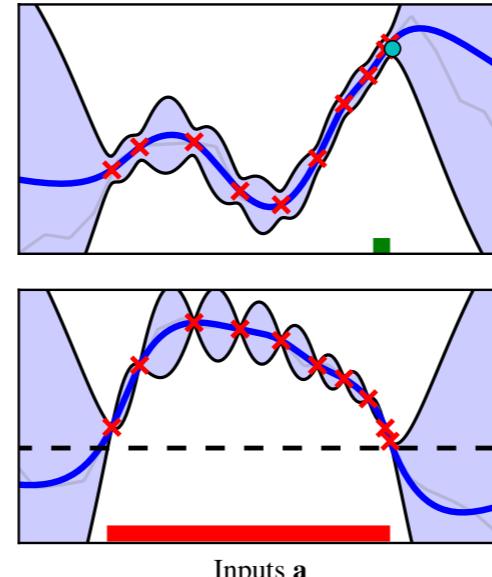
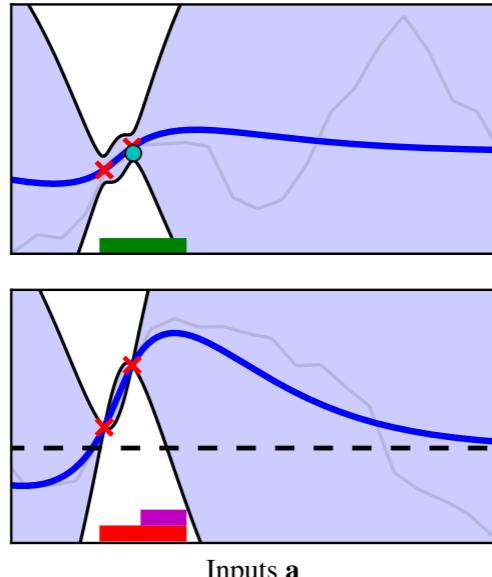
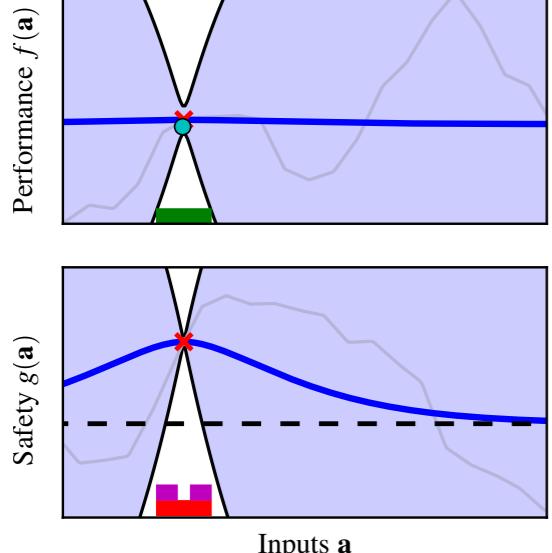
SAFE OPT-MC

Safe  
Bayesian  
Optimization

Parameters  $\mathbf{a}_n$   
 $\hat{f}(\mathbf{a}_n), \hat{g}_i(\mathbf{a}_n)$

Algorithm with Parameters  $\mathbf{a}$

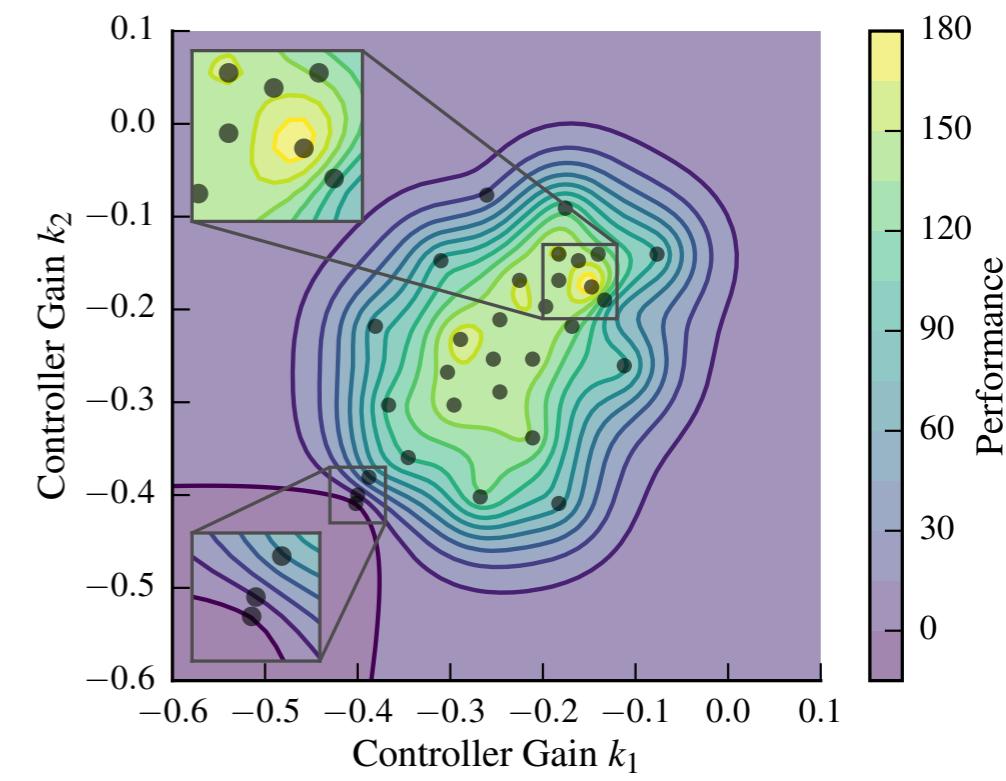
Evaluate on Real System  
Performance:  $f(\mathbf{a}_n)$   
Safety Constraints:  $g_i(\mathbf{a}_n)$



(d) Initial, safe parameters.

(e) Safe exploration.

(f) After 10 evaluations: safe maximum found.



# Example application: Calibration of blood flow simulations

## Goal:

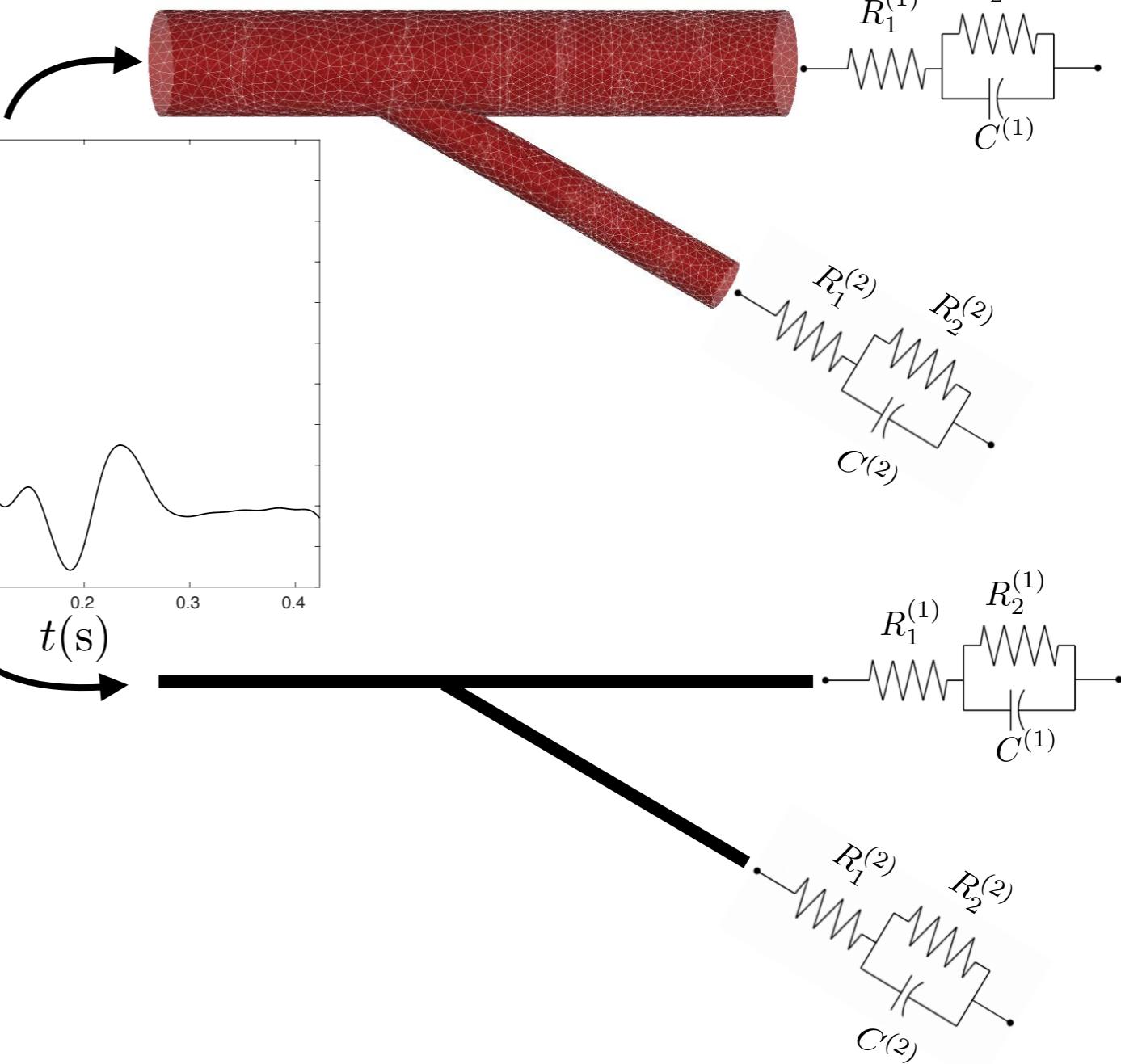
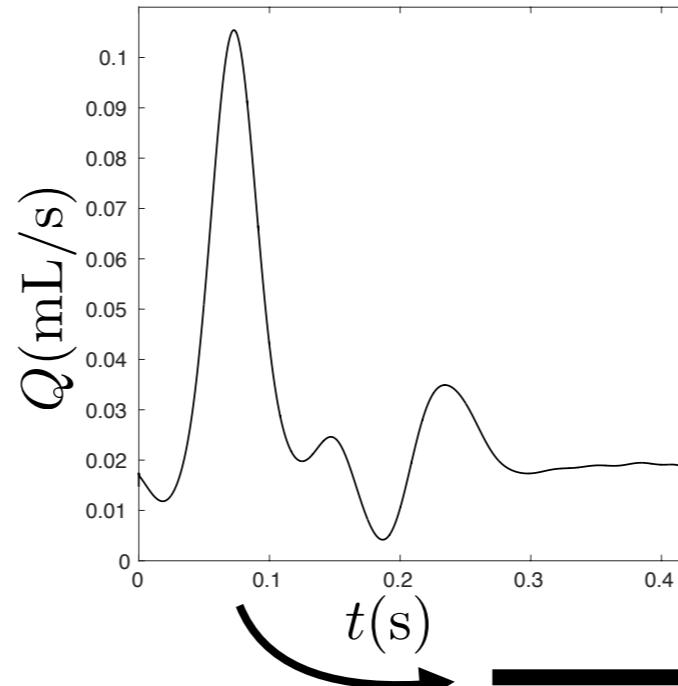
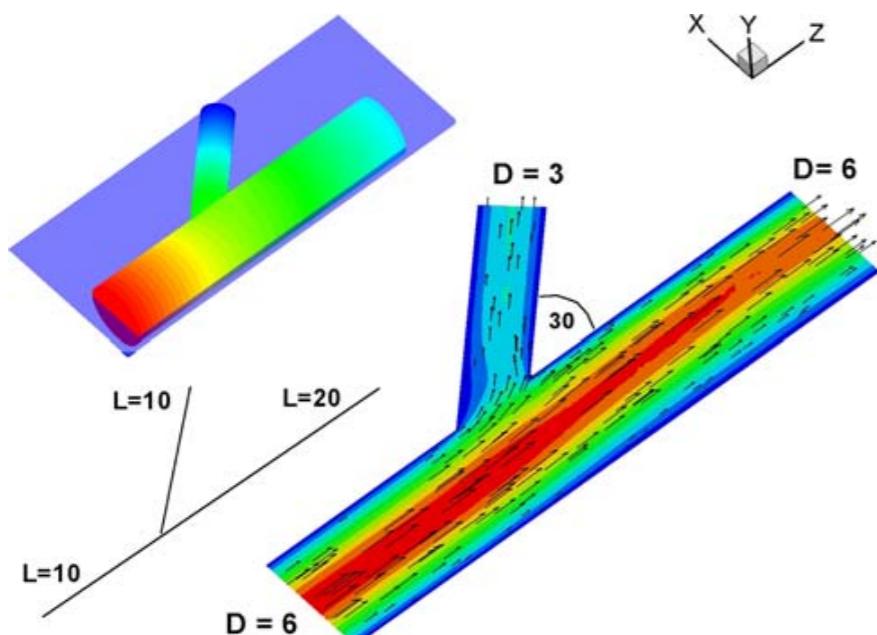
Calibrate the outflow boundary condition parameters to match a target inlet systolic pressure, i.e.,

$$\mathbf{x}^* = \operatorname{argmin}_{\mathbf{x} \in \mathcal{X}} |p_s^* - p_s(\mathbf{x})|^2,$$

$$\mathbf{x} = [R_T^{(1)}, R_T^{(2)}]$$

$$\mathcal{X} = [10^{10}, 10^{11}] \times [10^{11}, 10^{12}]$$

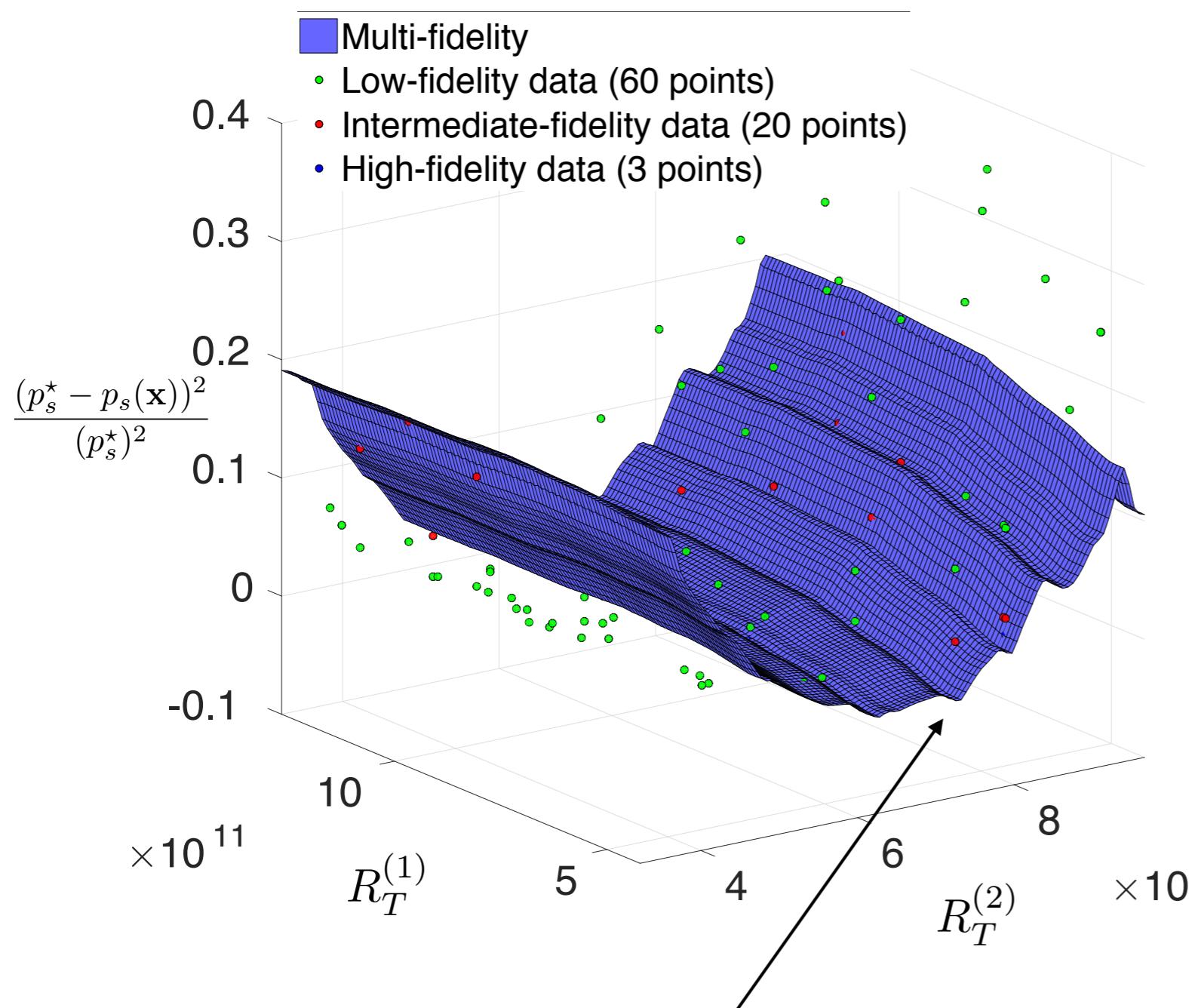
$$p_s^* = 47 \text{ mmHg}$$



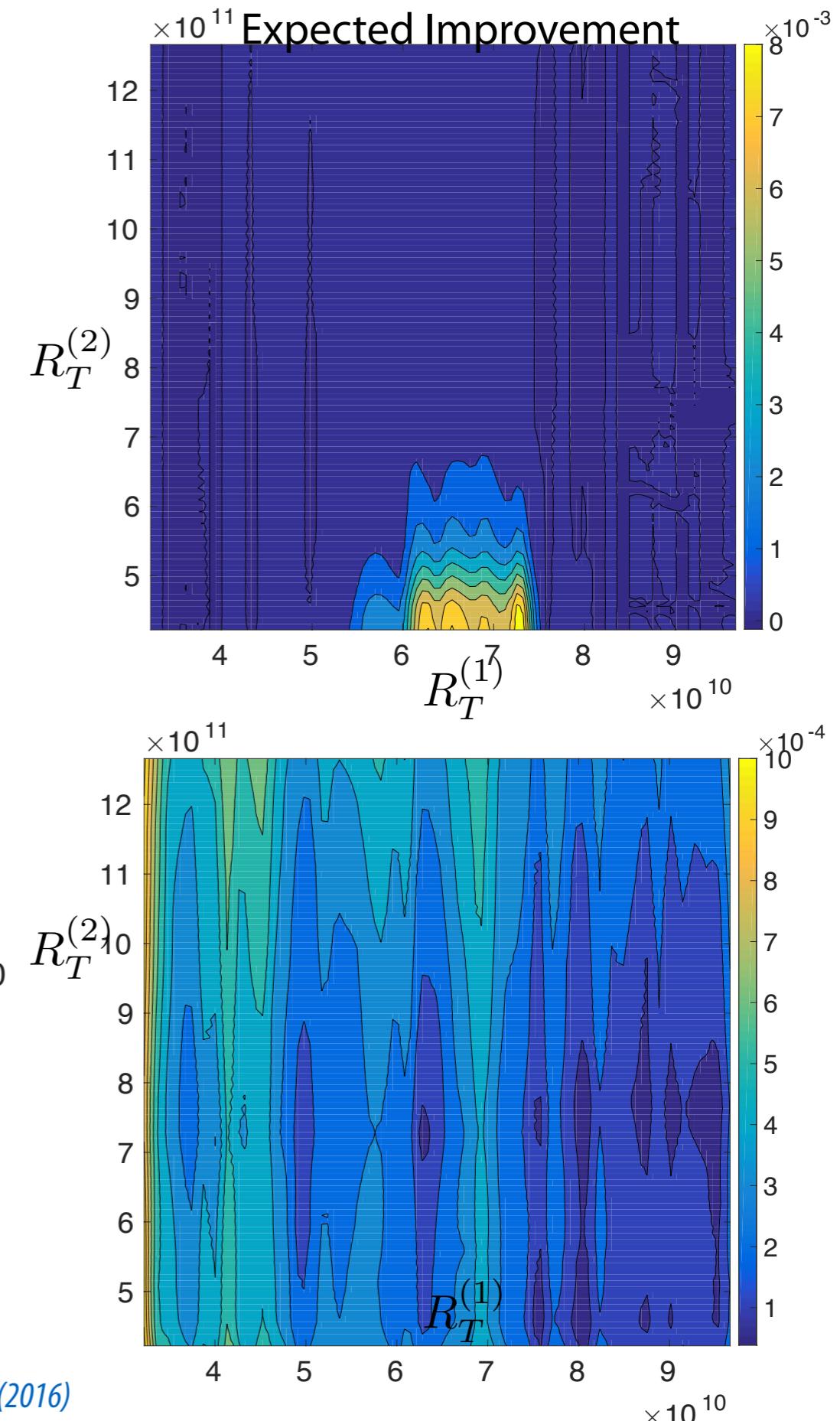
## Multi-fidelity approach:

- 1.) 3D Navier-Stokes (spectral/hp elements, rigid artery) - **high fidelity 0(hrs)**
- 2.) Non-linear 1D-FSI (DG, compliant artery) - **intermediate fidelity 0(mins)**
- 3.) Linearized 1D-FSI solver around an inaccurate reference state - **low fidelity 0(s)**

# Example application: Calibration of blood flow simulations



Decreased the relative error to  $\mathcal{O}(10^{-3})$  after 3 iterations of BO, mainly sampling the lowest fidelity (cheapest) solver.



## Things we didn't cover

- Non-Gaussian likelihoods/noise models
  - Approximate inference techniques (Variational inference, MCMC)
  - Classification
  - Open source software:
    - [GPy](#)
    - [GPflow](#)
    - [GPML](#)
    - [GPyOpt](#)
    - [GPflowOpt](#)
- See the course website for links:*
- <https://www.seas.upenn.edu/~enm540/syllabus/>