

Deep Reinforcement Learning in a Handful of Trials with Probabilistic Dynamics Models

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University of California, Berkeley



What is Reinforcement Learning?

What is Reinforcement Learning?



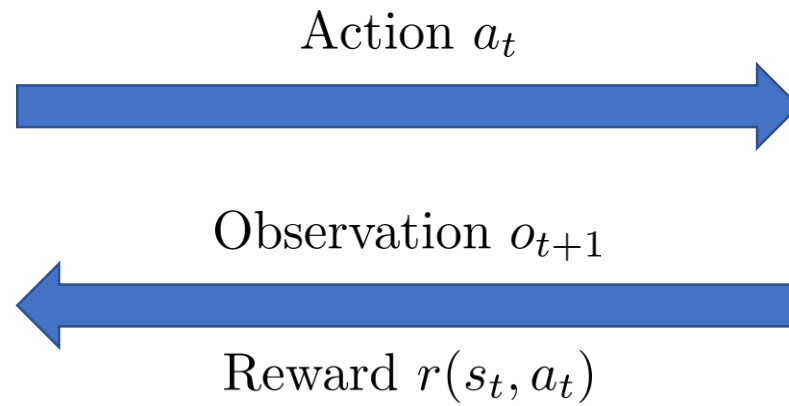
What is Reinforcement Learning?



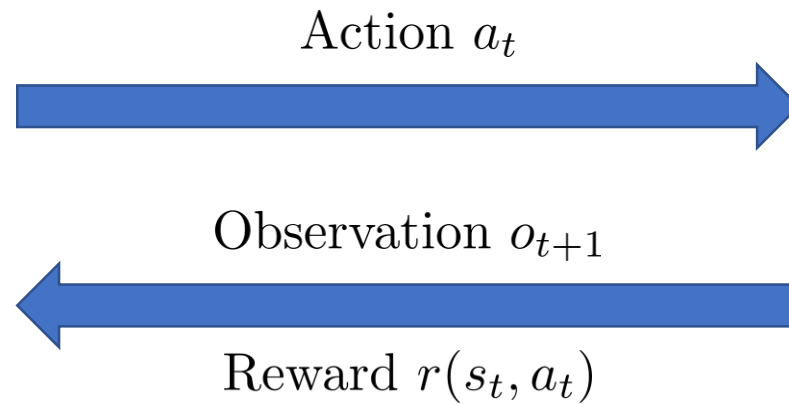
Action a_t



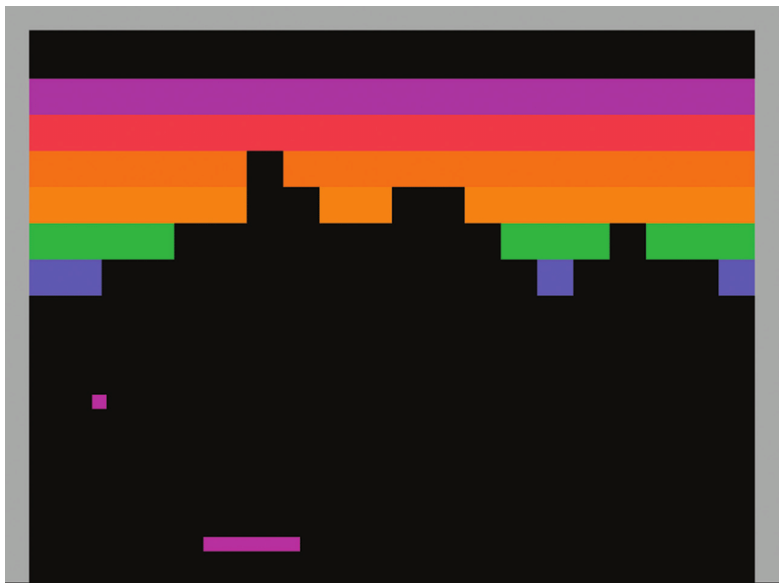
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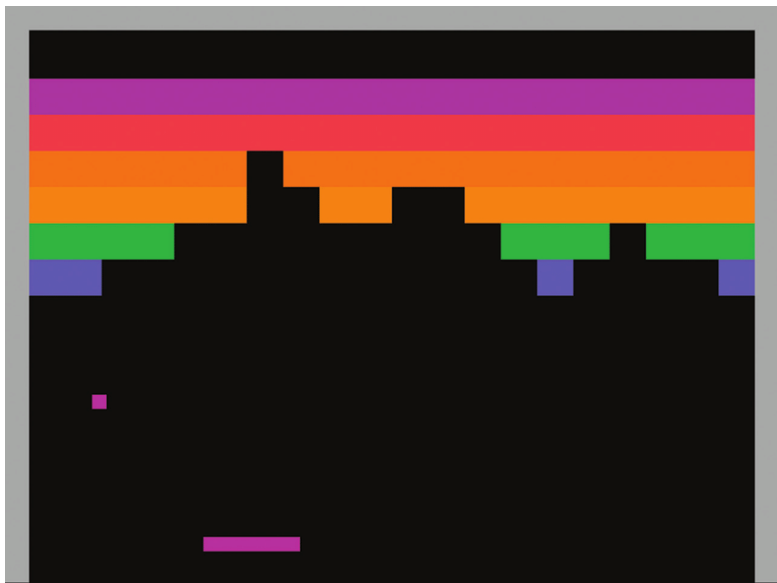


What is Reinforcement Learning?



$$\max_{a_1, \dots, a_{T-1}} \sum_{i=1}^{T-1} r(s_i, a_i)$$



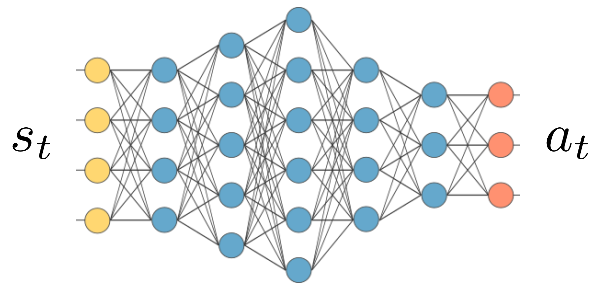




Current Approaches to Reinforcement Learning

Current Approaches to Reinforcement Learning

Policy Gradients

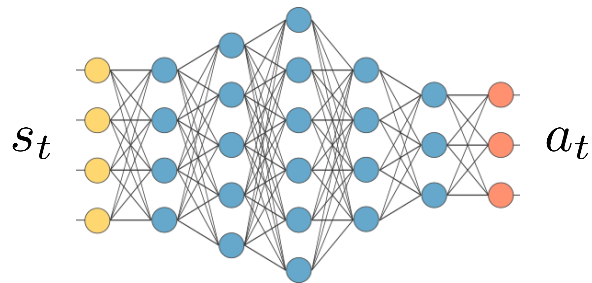


PPO, TRPO

(Schulman et al. '15, Schulman et al. '17)

Current Approaches to Reinforcement Learning

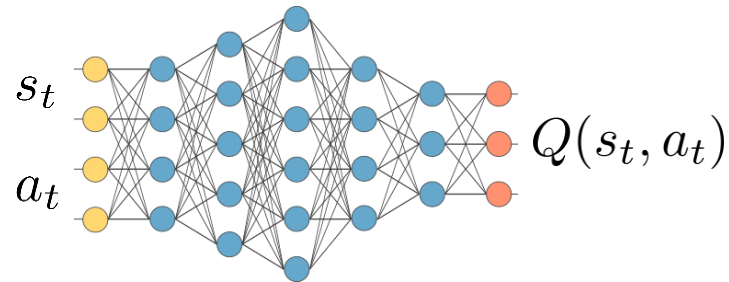
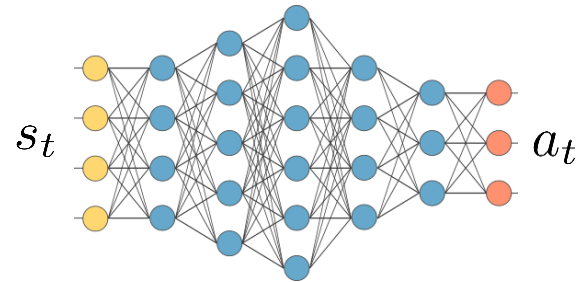
Policy Gradients



PPO, TRPO

(Schulman et al. '15, Schulman et al. '17)

Actor-Critic

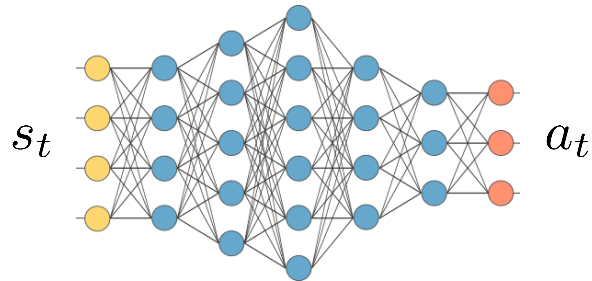


SAC, DDPG

(Haarnoja et al., Lillicrap et al.)

Current Approaches to Reinforcement Learning

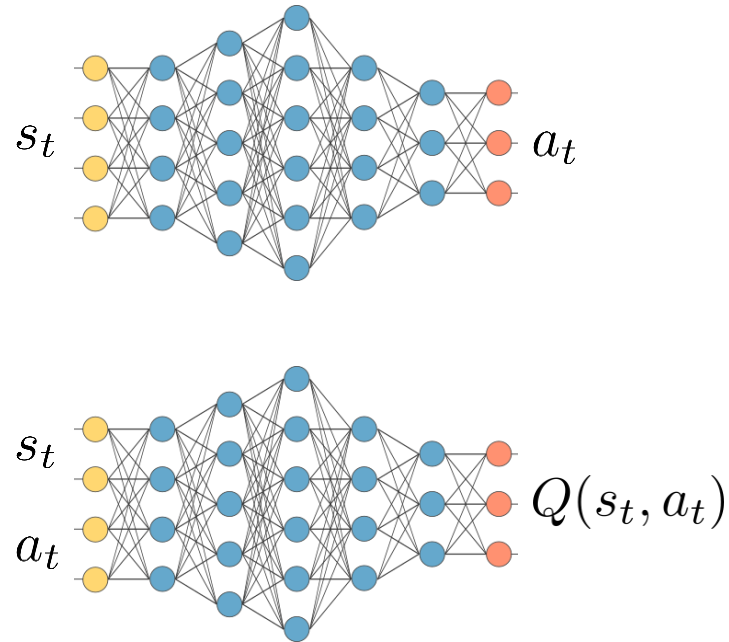
Policy Gradients



PPO, TRPO

(Schulman et al. '15, Schulman et al. '17)

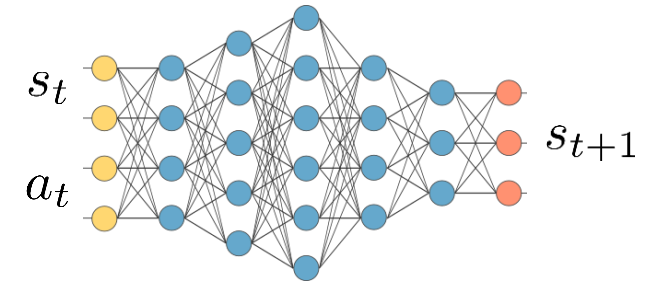
Actor-Critic



SAC, DDPG

(Haarnoja et al., Lillicrap et al.)

Model-based RL

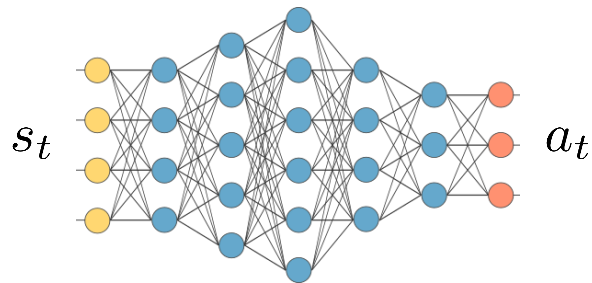


MBMF

(Nagabandi et al.)

Current Approaches to Reinforcement Learning

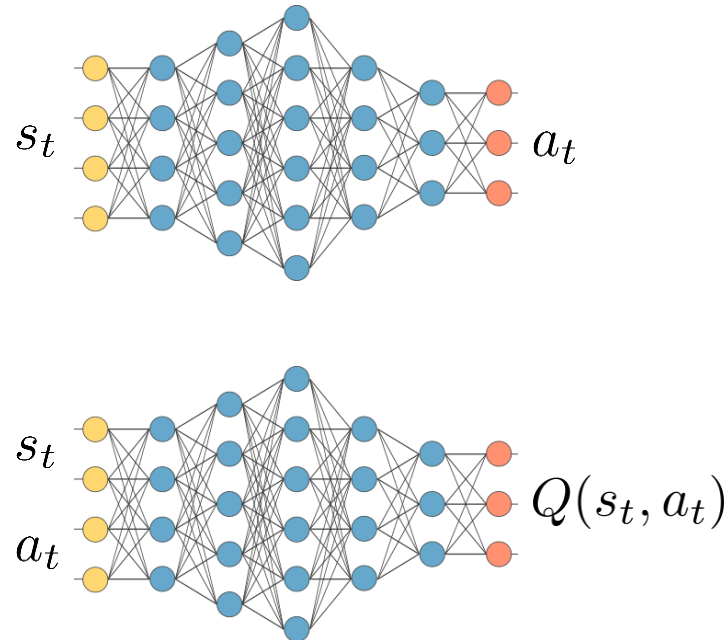
Policy Gradients



PPO, TRPO

(Schulman et al. '15, Schulman et al. '17)

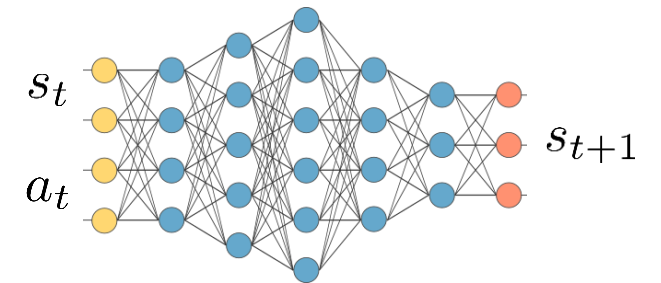
Actor-Critic



SAC, DDPG

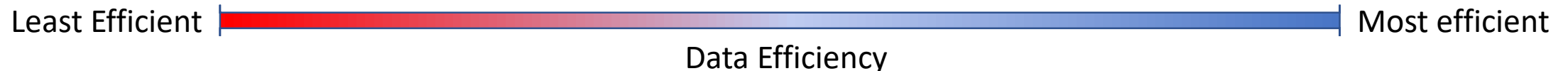
(Haarnoja et al., Lillicrap et al.)

Model-based RL



MBMF

(Nagabandi et al.)



Comparative Performance on HalfCheetah

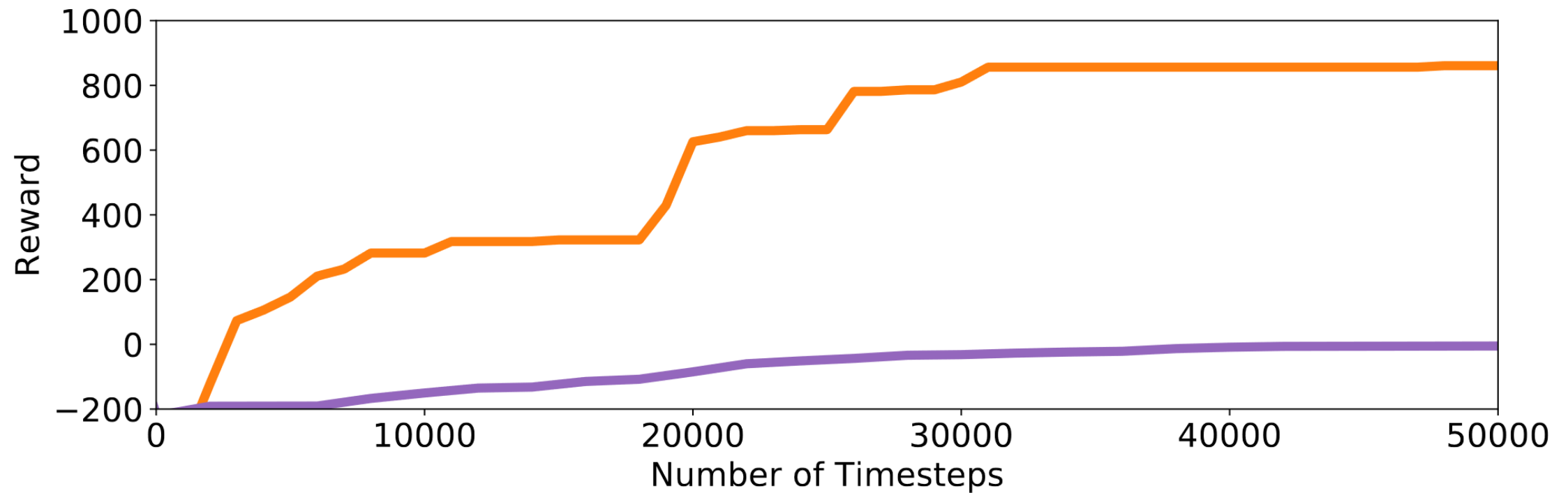
Comparative Performance on HalfCheetah



PPO



[Nagabandi et al. 2017]



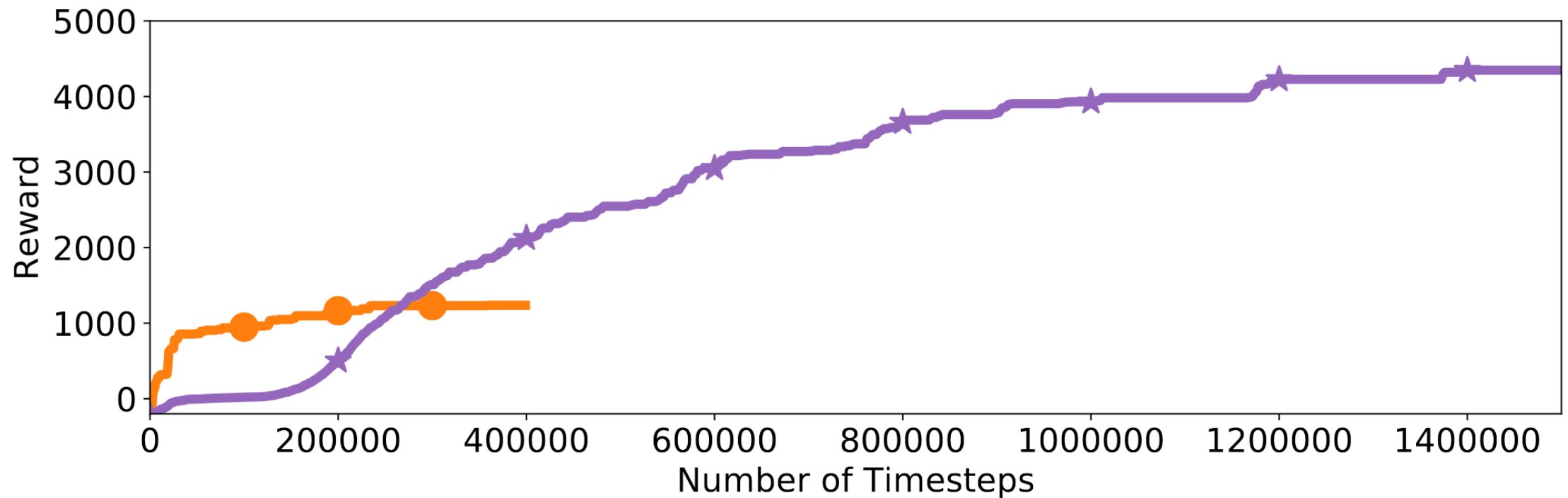
Comparative Performance on HalfCheetah



PPO



[Nagabandi et al. 2017]



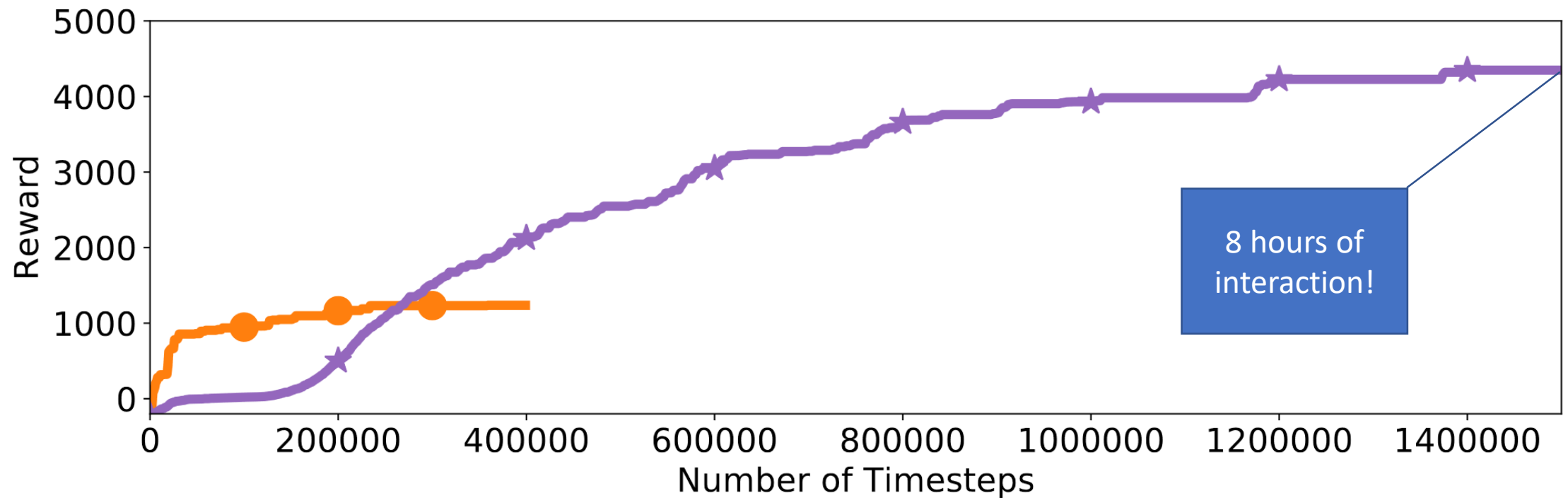
Comparative Performance on HalfCheetah



PPO



[Nagabandi et al. 2017]

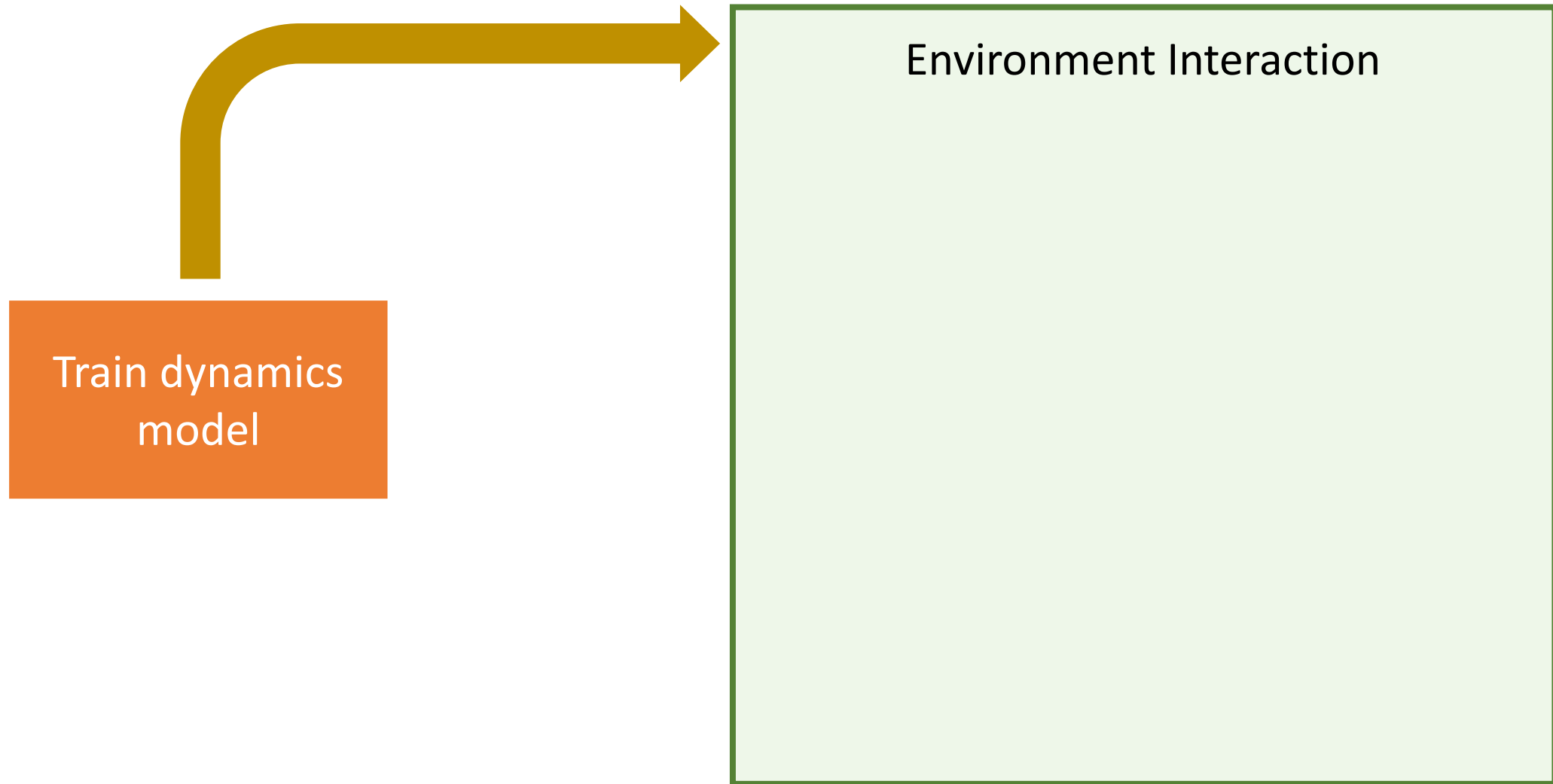


Model-based Reinforcement Learning

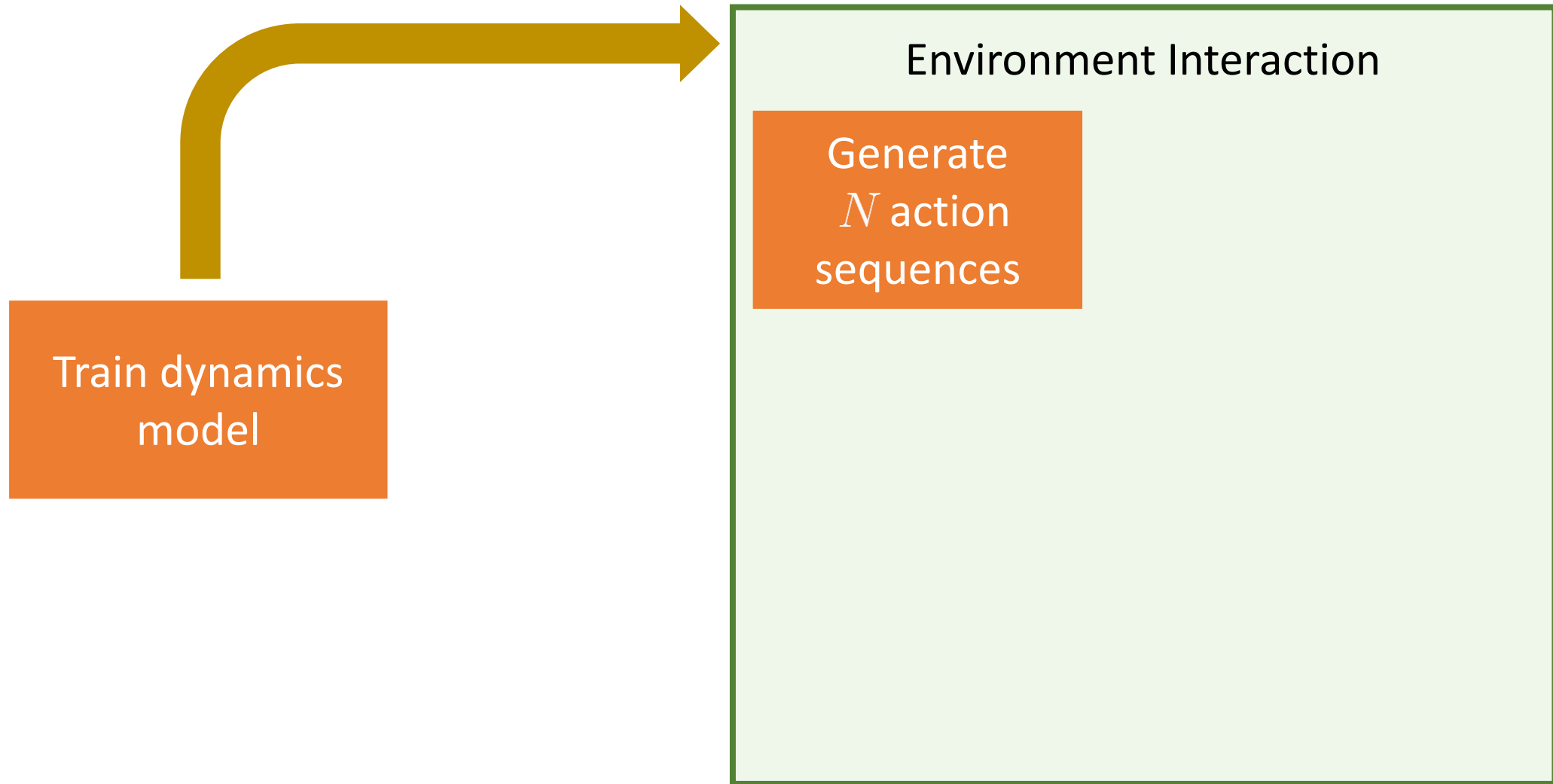
Model-based Reinforcement Learning

Train dynamics
model

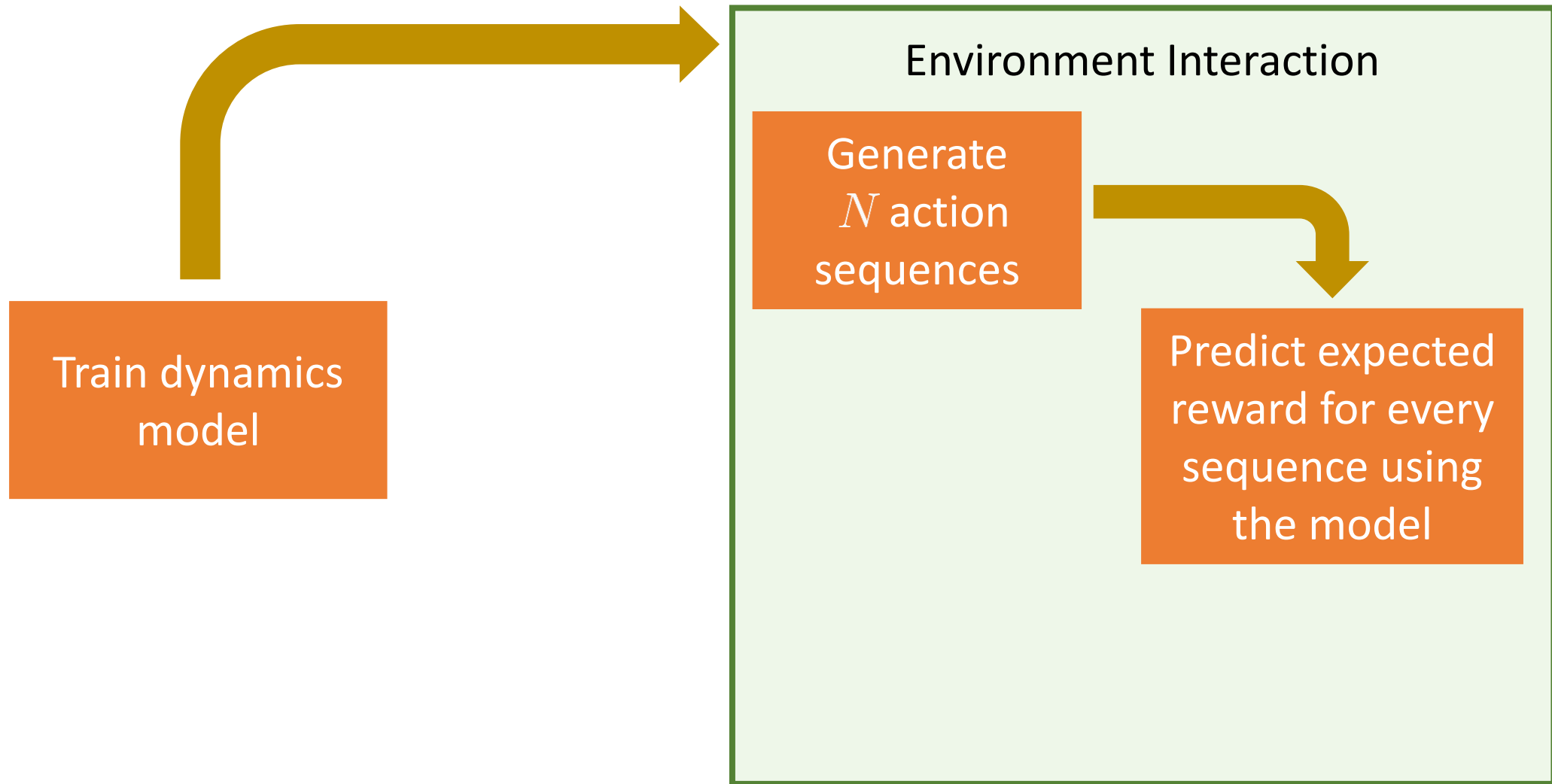
Model-based Reinforcement Learning



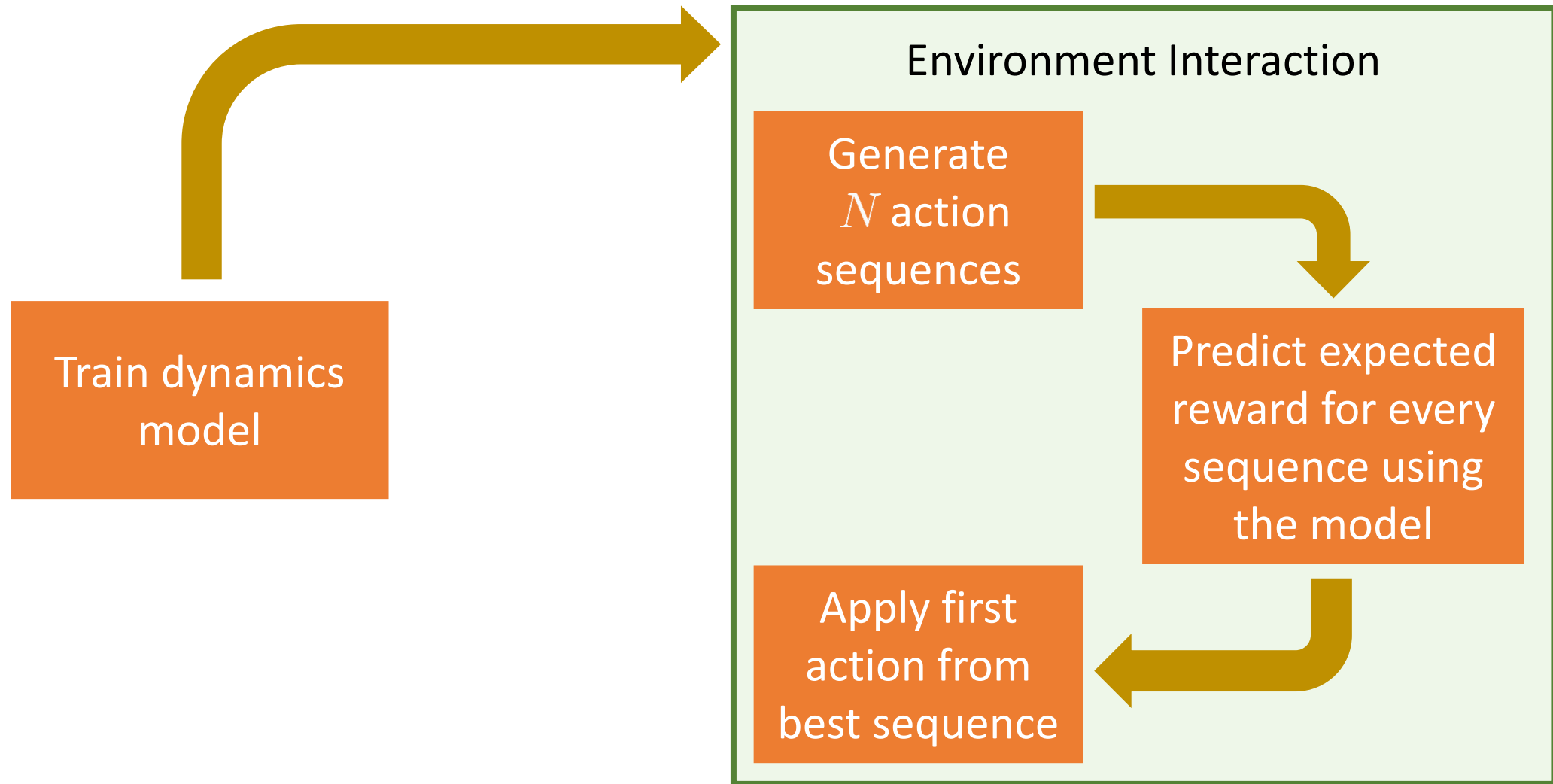
Model-based Reinforcement Learning



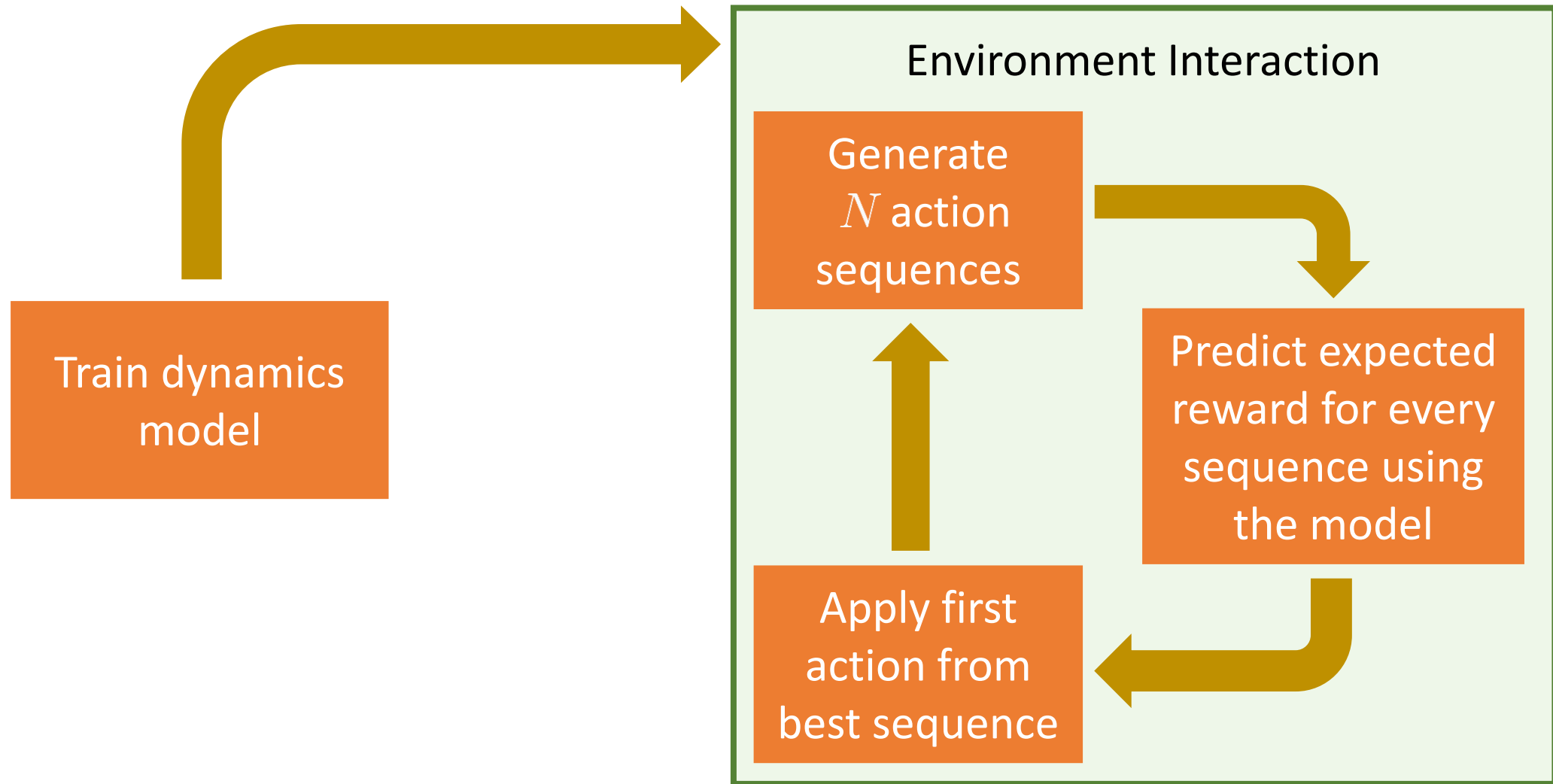
Model-based Reinforcement Learning



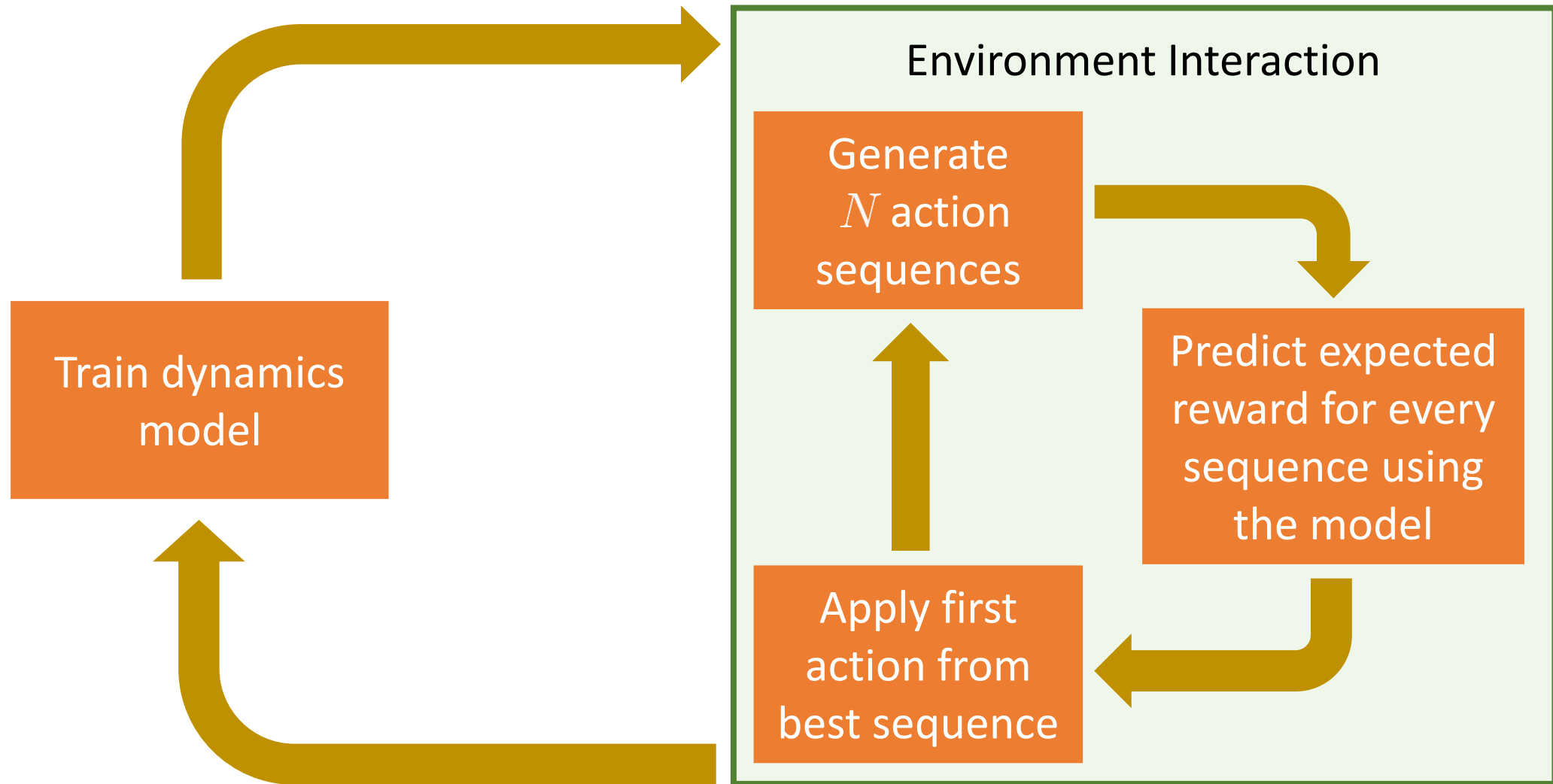
Model-based Reinforcement Learning



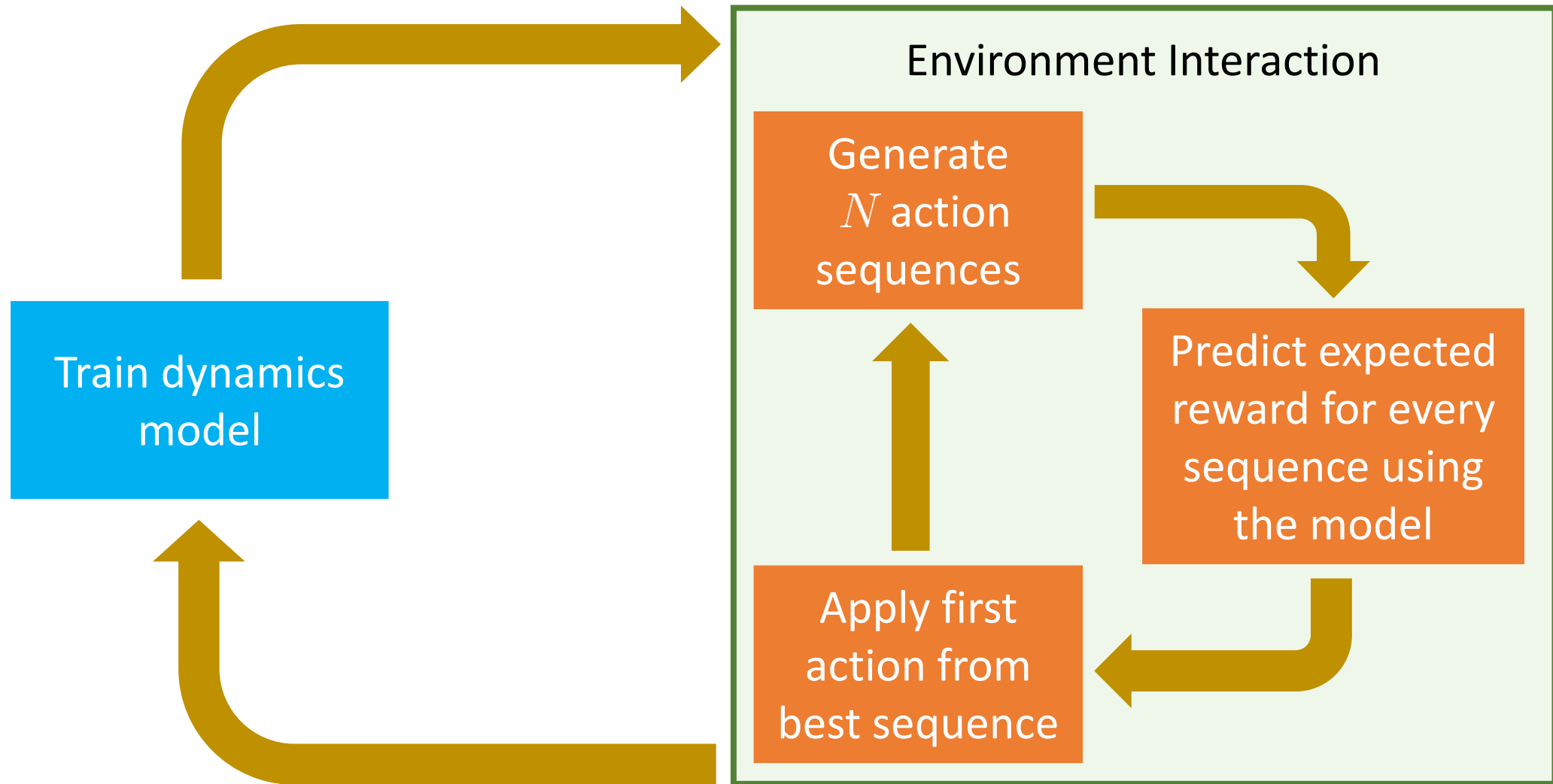
Model-based Reinforcement Learning



Model-based Reinforcement Learning

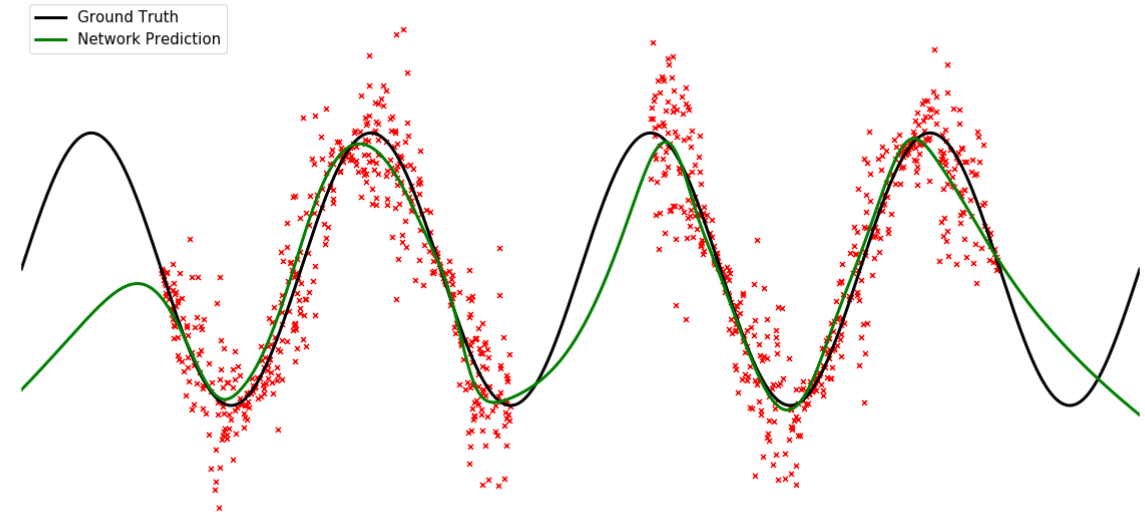
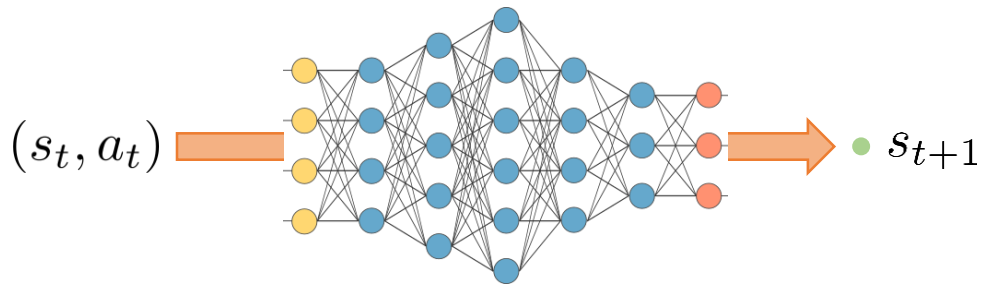


Model-based Reinforcement Learning

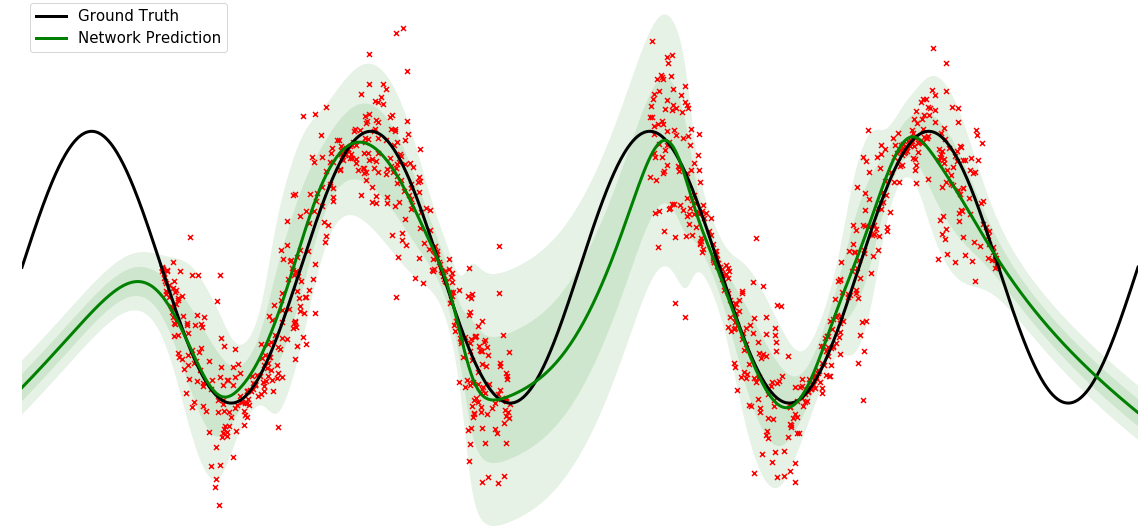
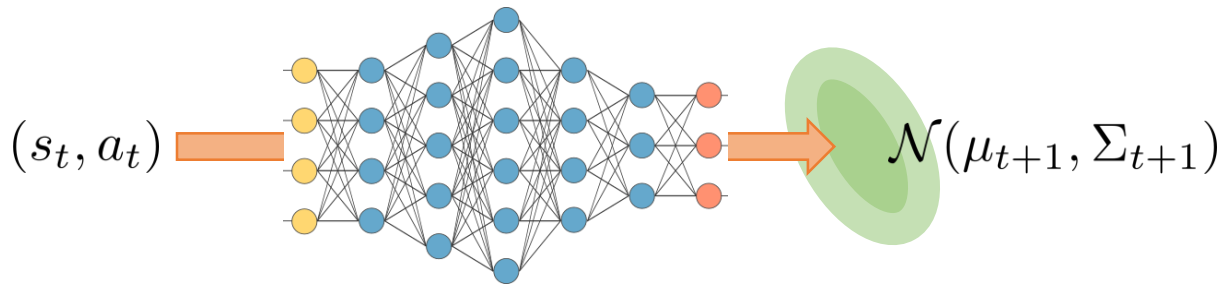


Deterministic Neural Nets as Models

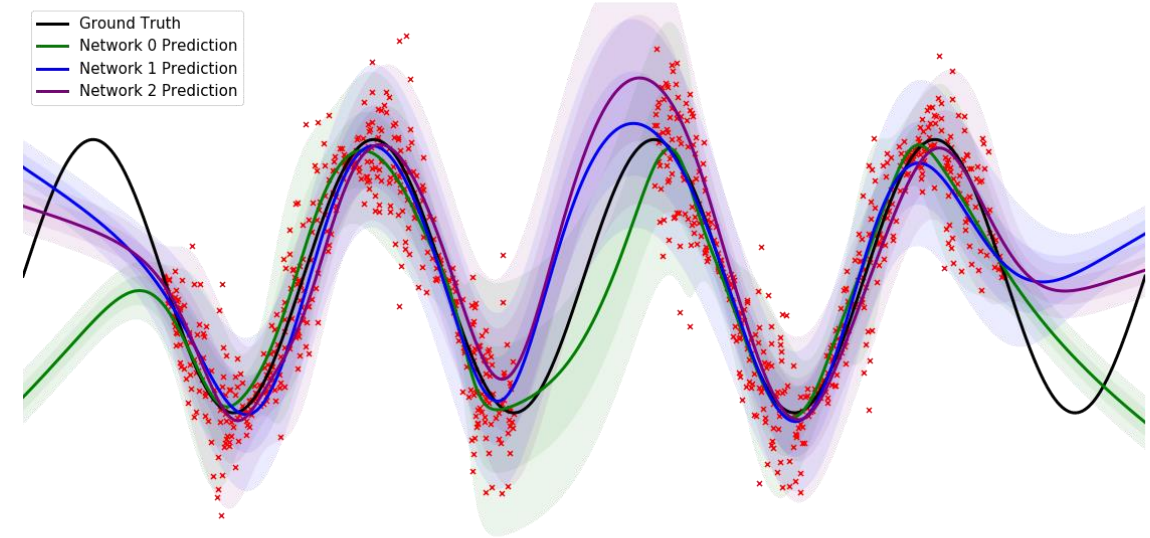
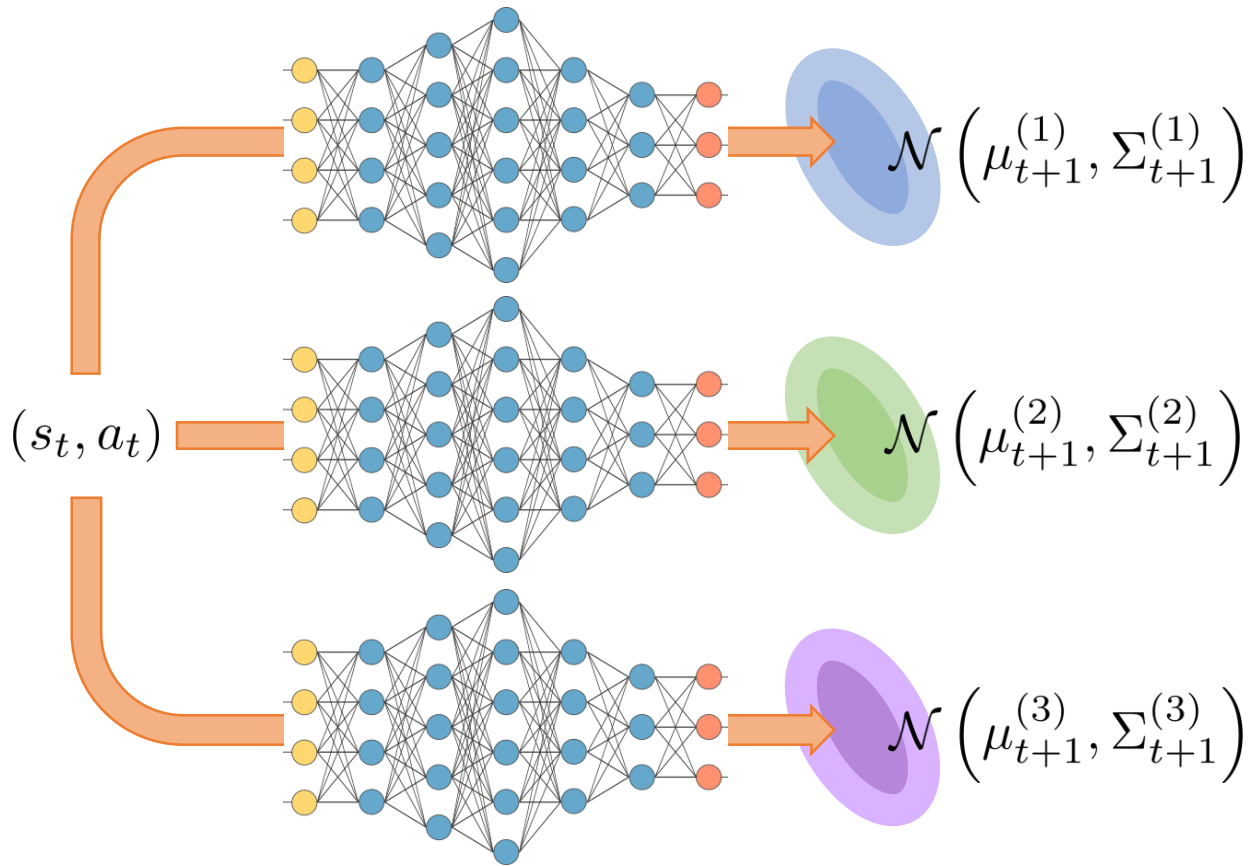
Deterministic Neural Nets as Models



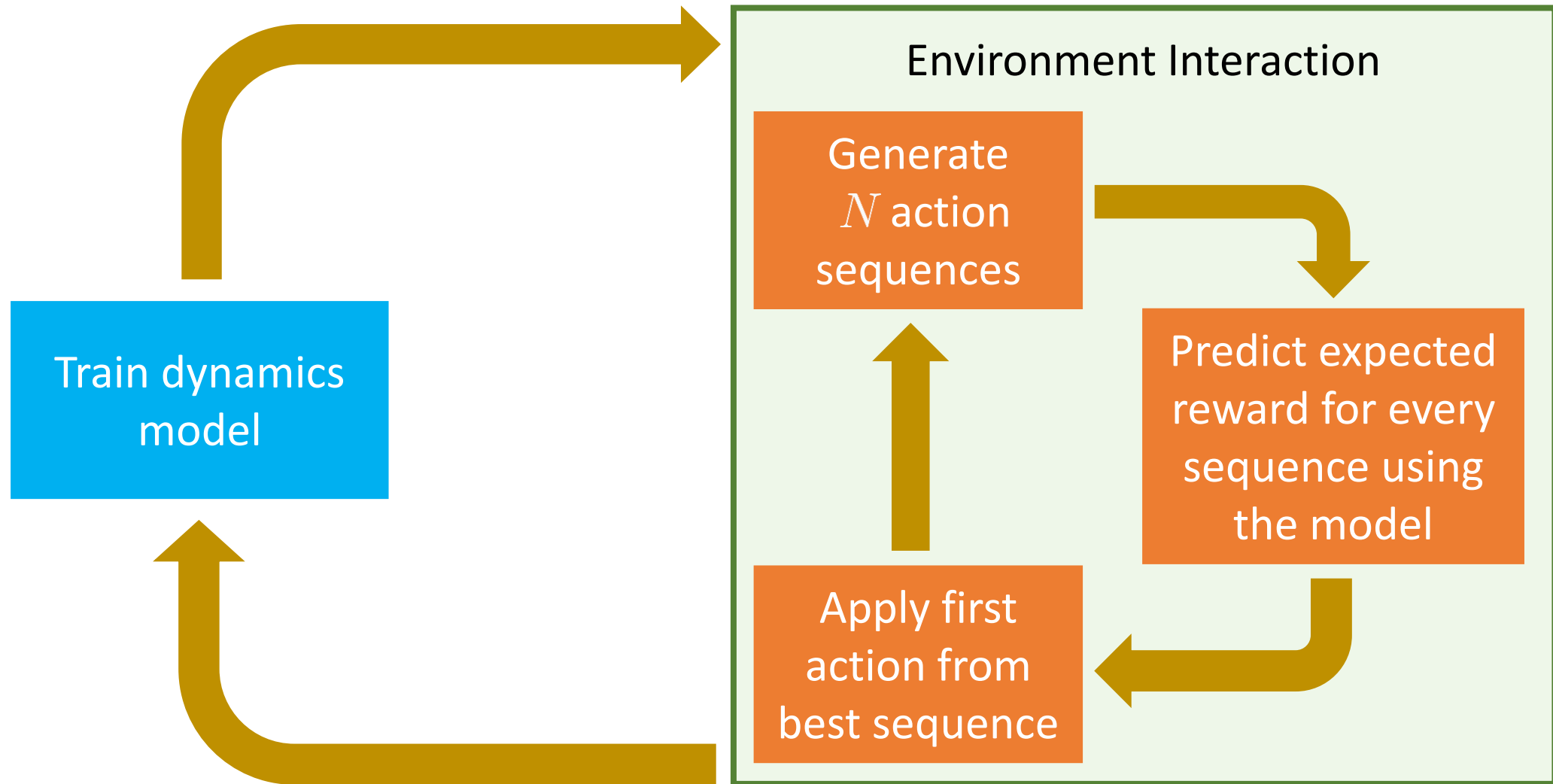
Probabilistic Neural Nets as Models



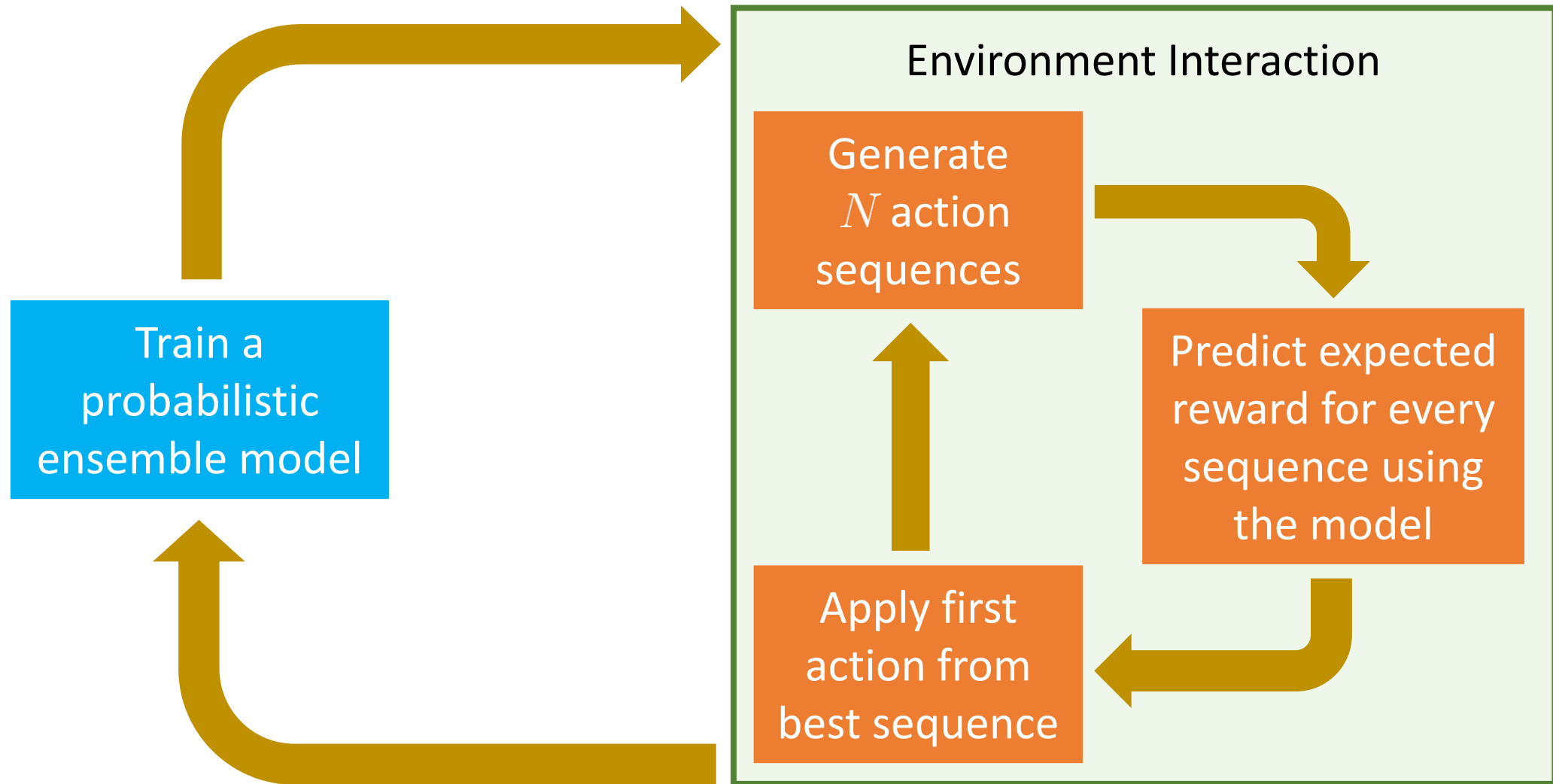
Probabilistic Ensembles as Models



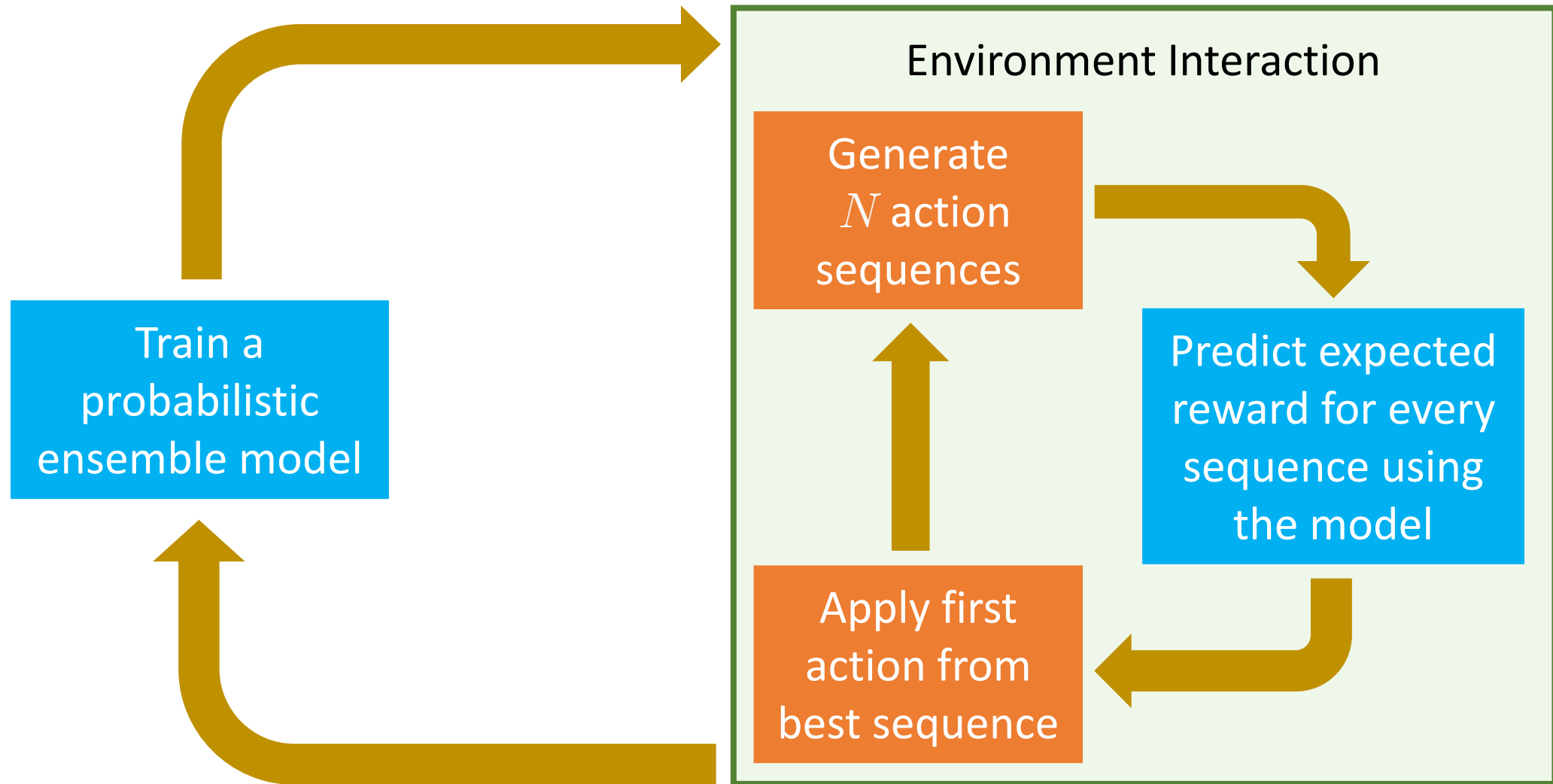
Model-based Reinforcement Learning



Model-based Reinforcement Learning



Model-based Reinforcement Learning



Trajectory Sampling for State Propagation

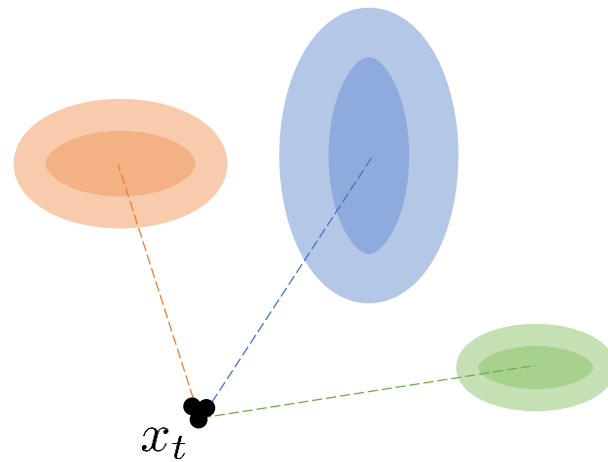
Trajectory Sampling for State Propagation

x_t^\bullet

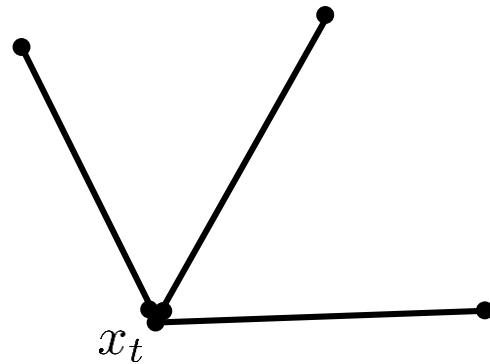
Trajectory Sampling for State Propagation

x_t 

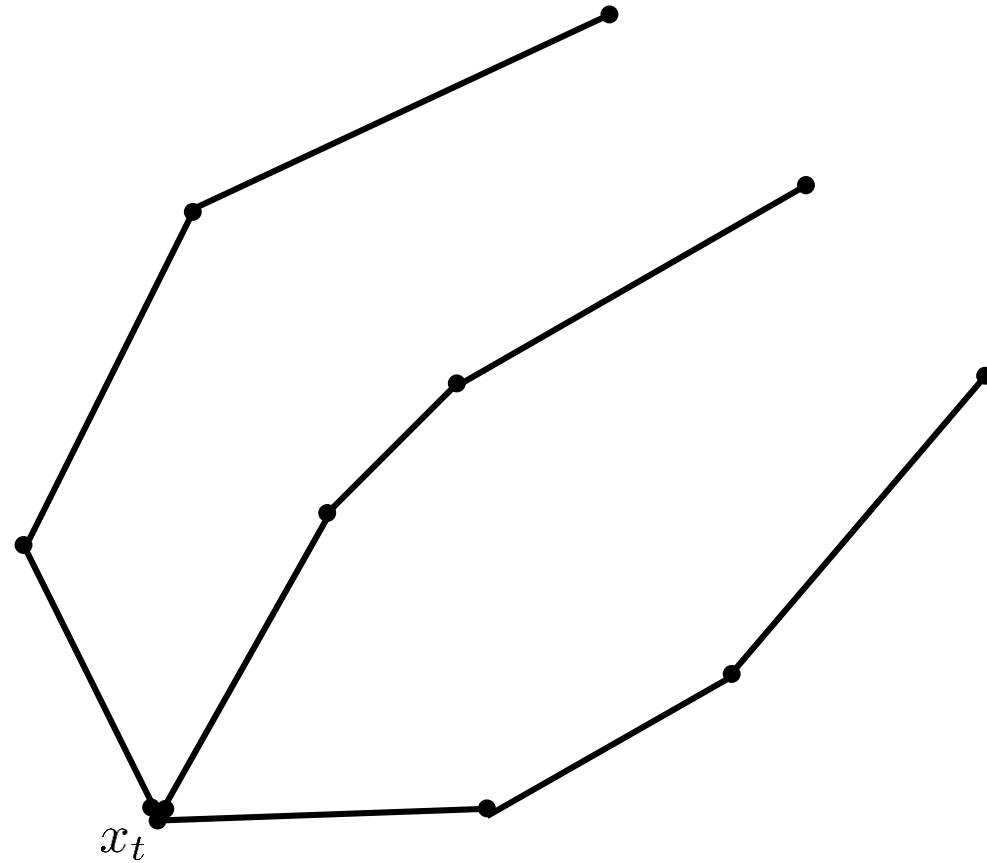
Trajectory Sampling for State Propagation



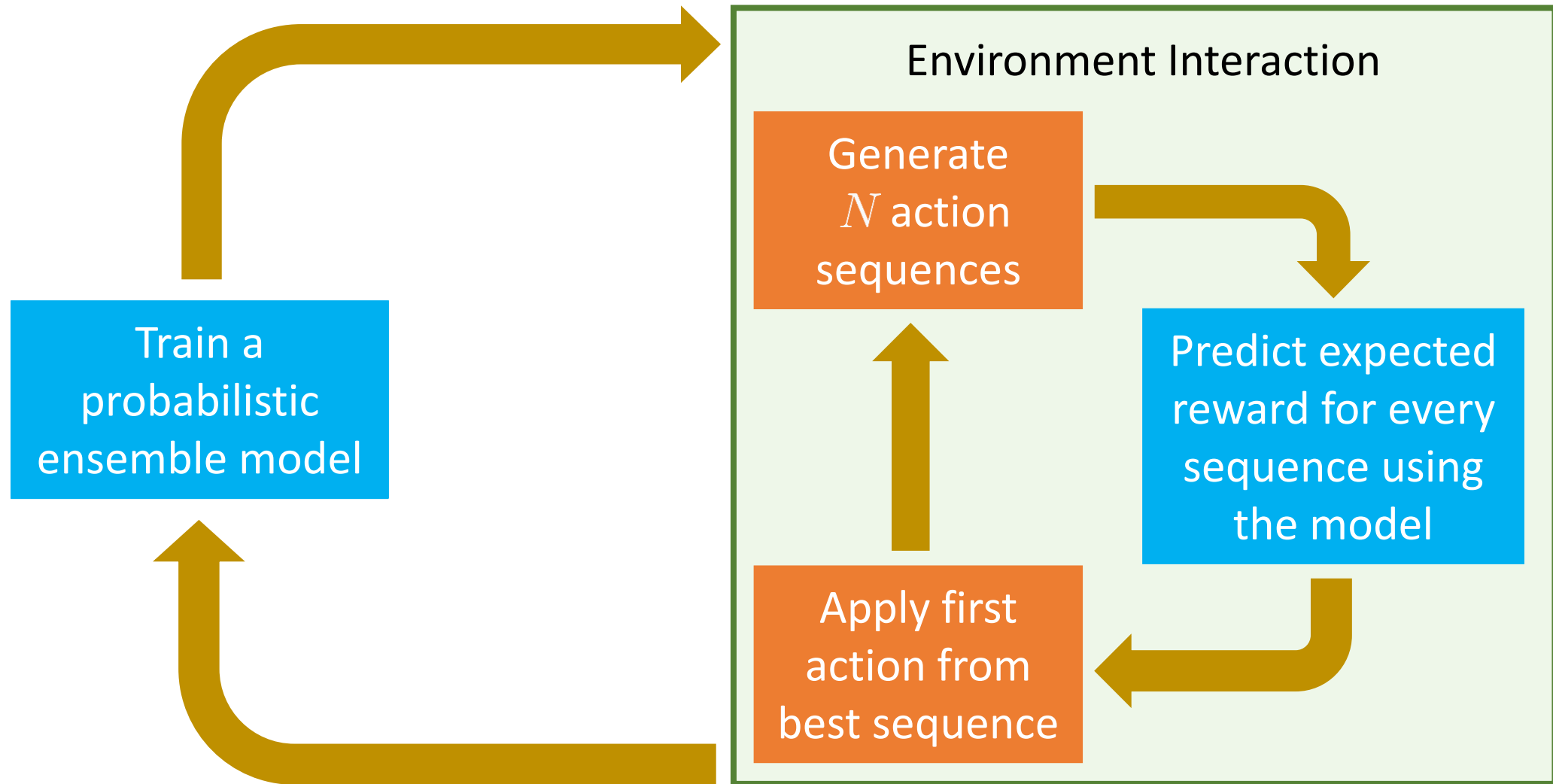
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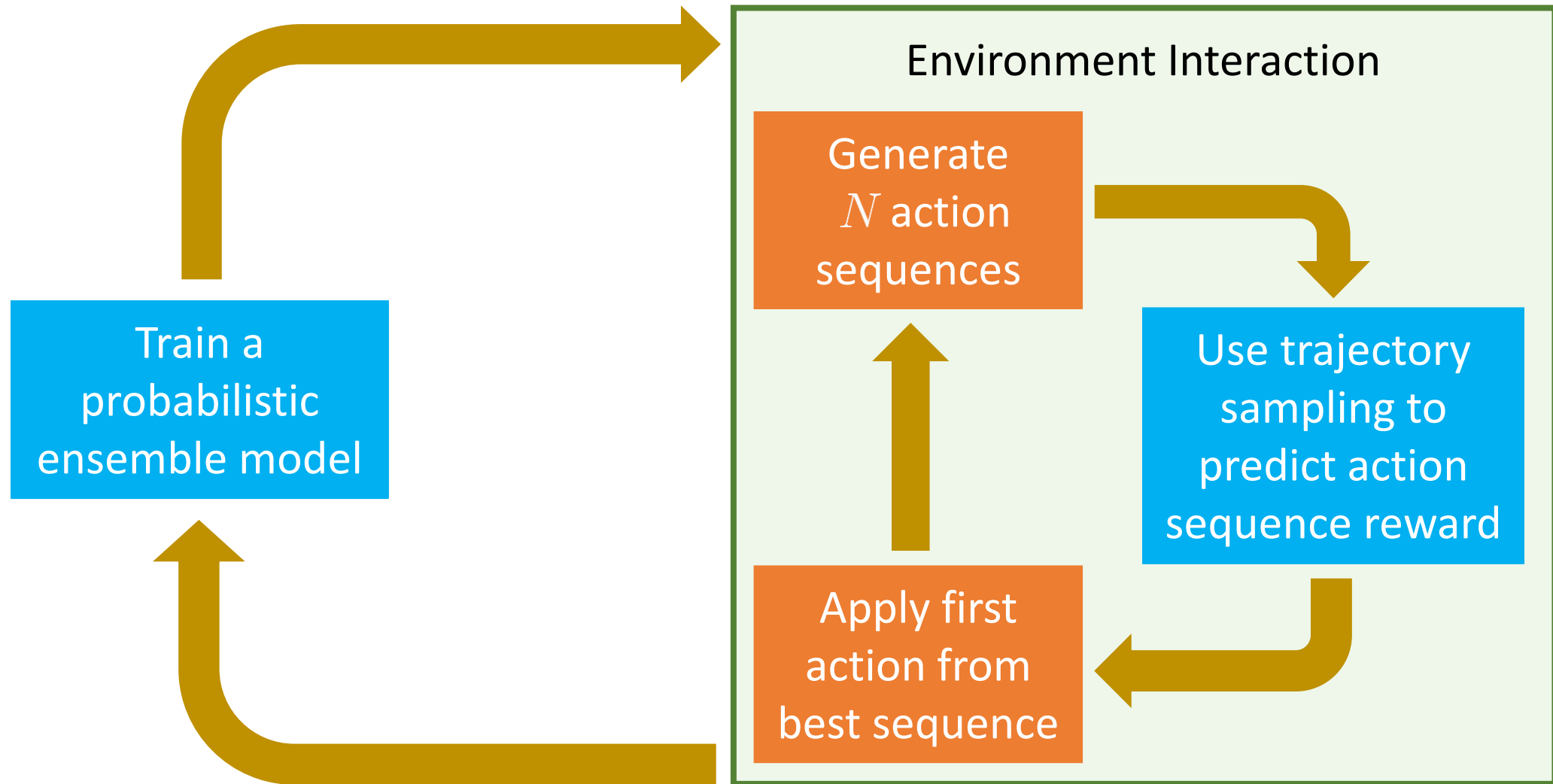
Trajectory Sampling for State Propagation



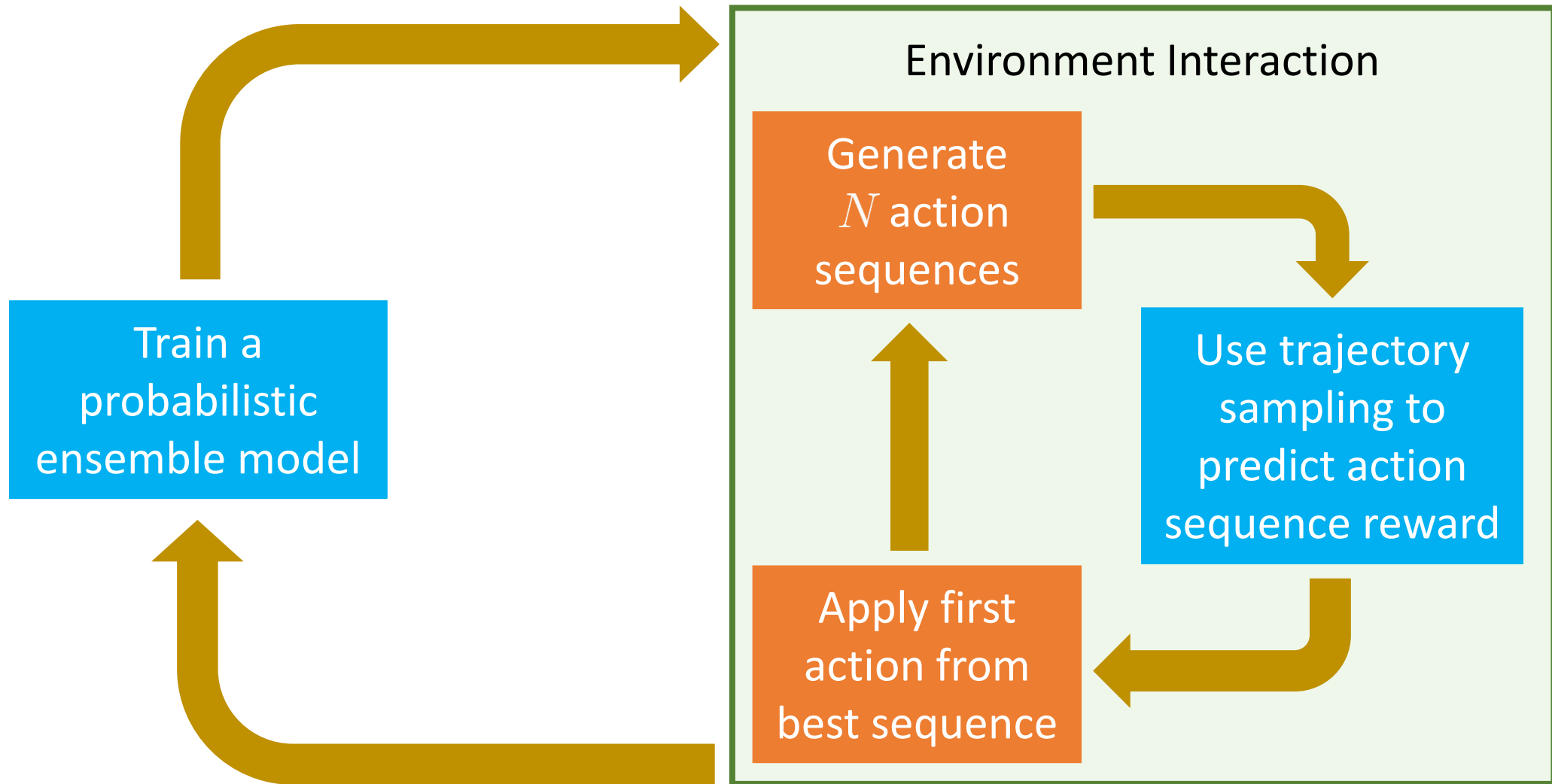
Model-based Reinforcement Learning



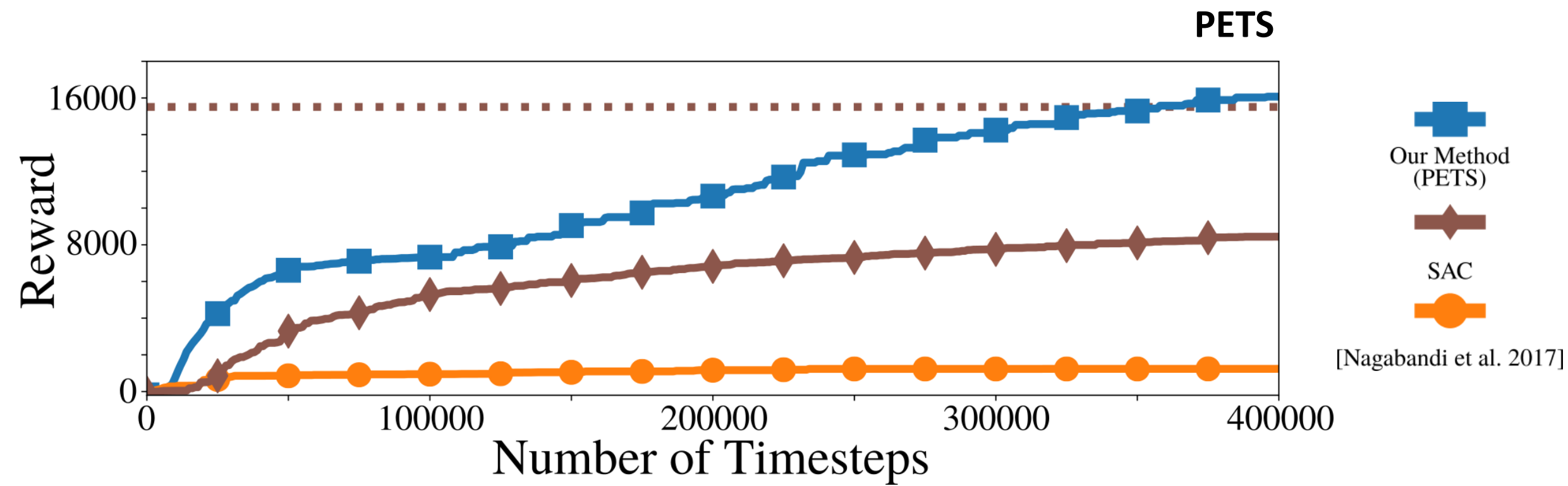
Model-based Reinforcement Learning



Our Method: Probabilistic Ensembles with Trajectory Sampling (PETS)



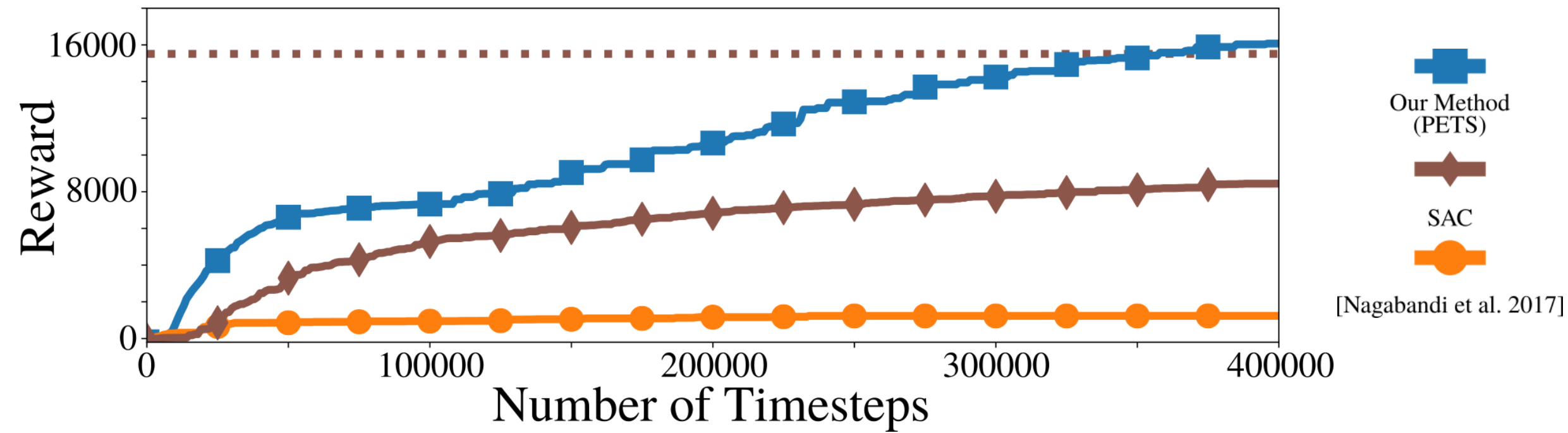
Experimental Results



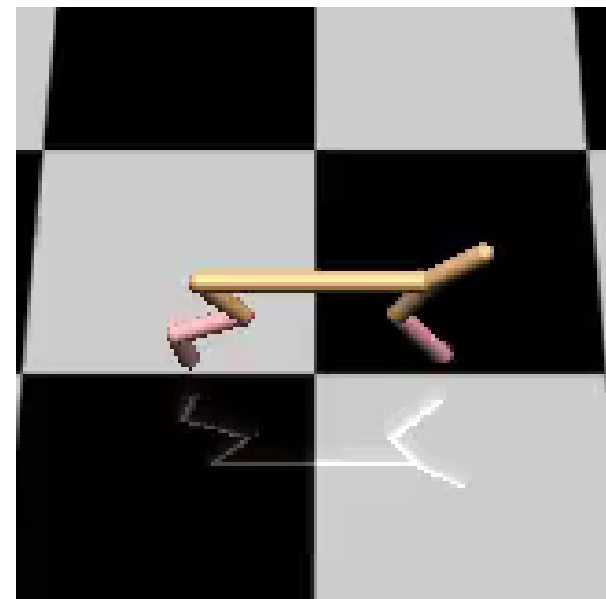
Experimental Results



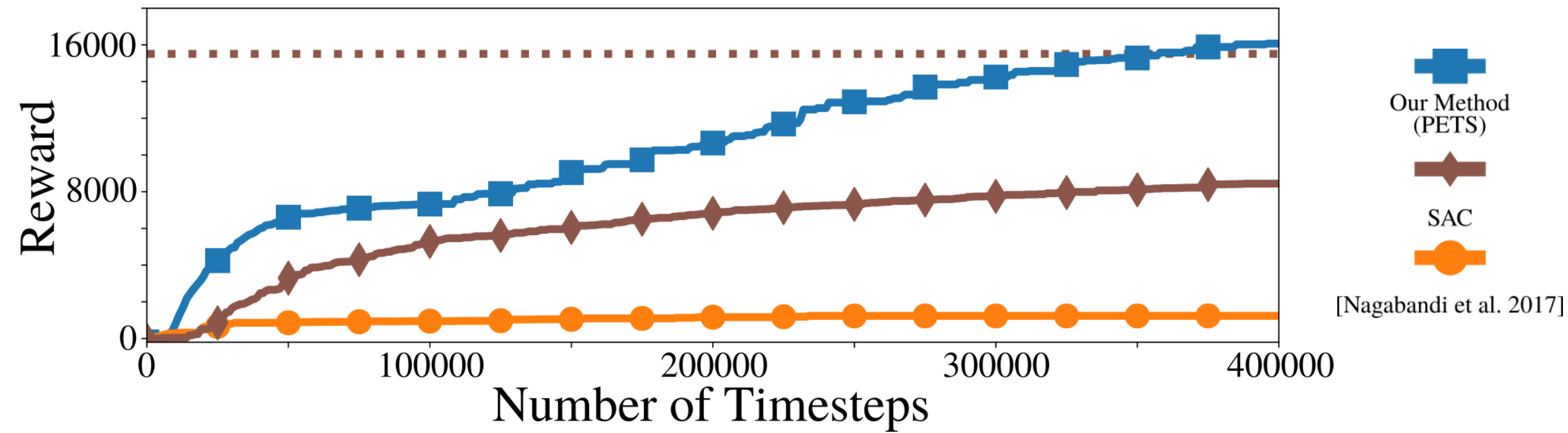
PETS



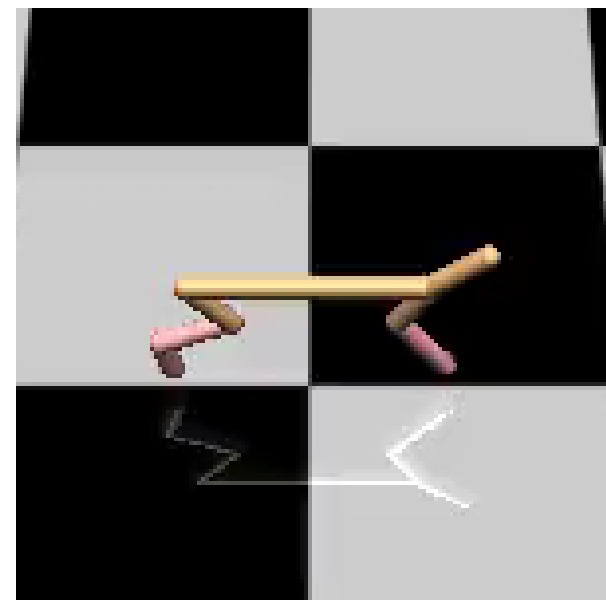
Experimental Results



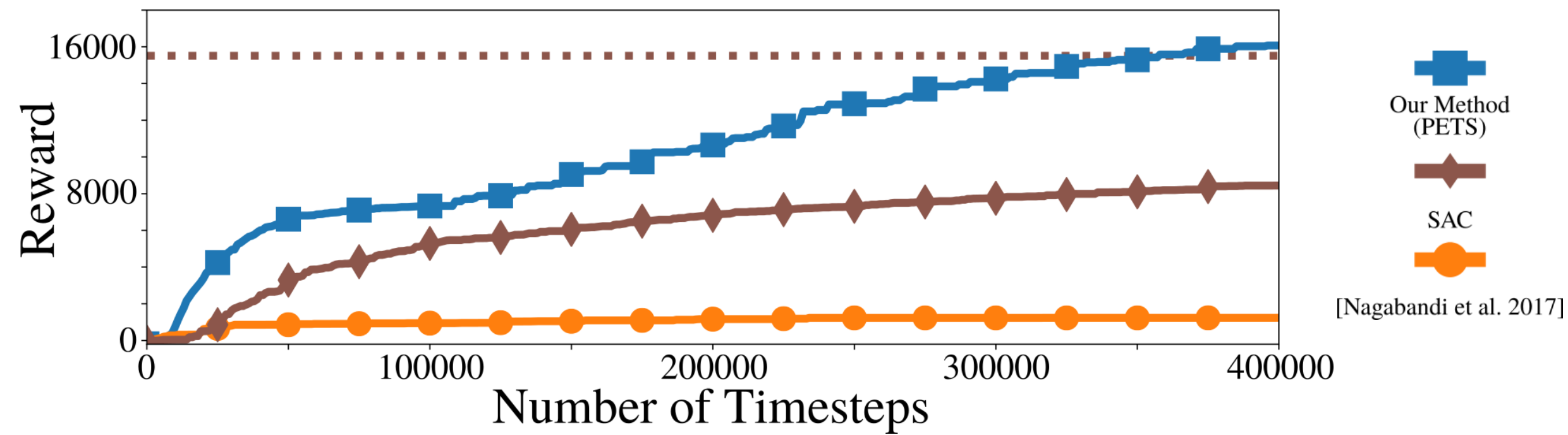
PETS



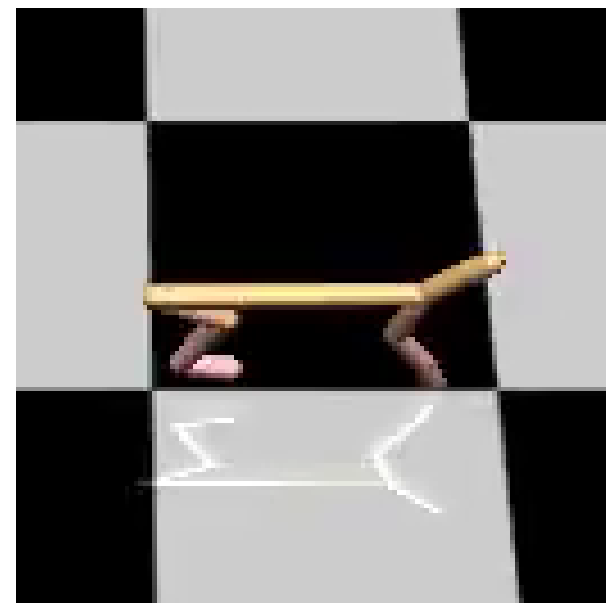
Experimental Results



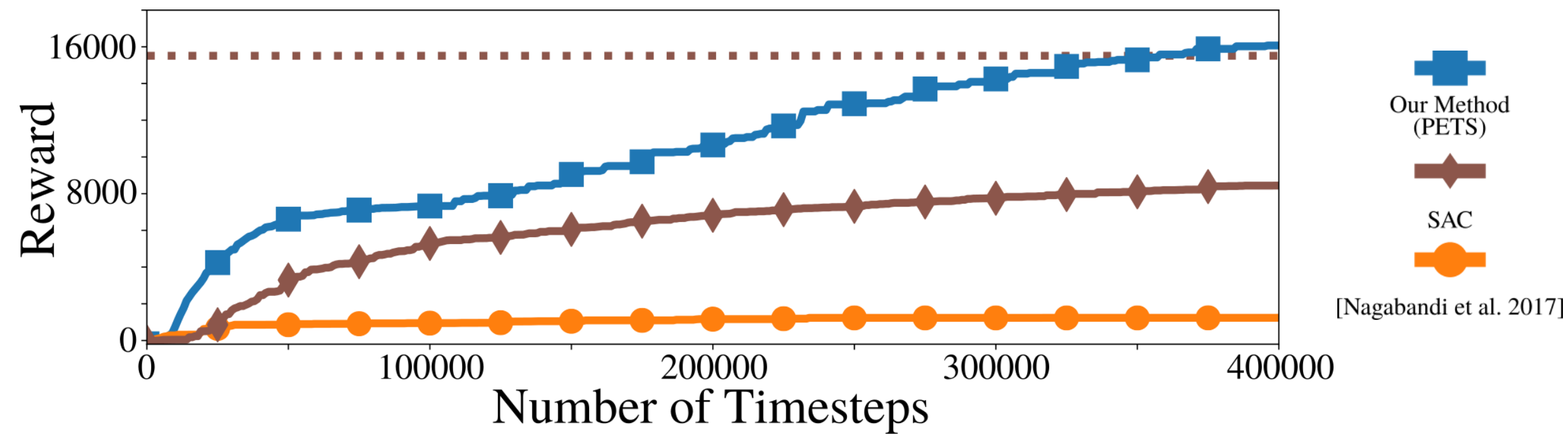
PETS



Experimental Results



PETS



Why use PETS?

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- ✓ Data efficiency

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- ✓ Data efficiency
- ✓ Competitive asymptotic performance

Why use PETS?

- ✓ Data efficiency
- ✓ Competitive asymptotic performance
- ✓ Ease of implementation

Deep Reinforcement Learning in a Handful of Trials with Probabilistic Dynamics Models

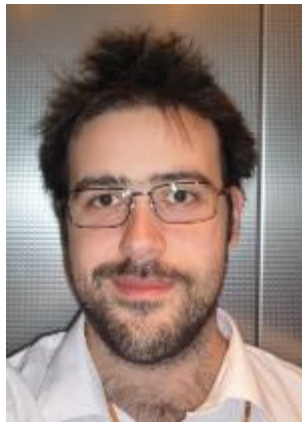
Code: <https://github.com/kchua/handful-of-trials>

Website: <https://sites.google.com/view/drl-in-a-handful-of-trials>

Paper: <https://arxiv.org/abs/1805.12114>



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