

MATH 341 - LINEAR ALGEBRA
§3.1 - 3.3

Fall 2019

Everyone should learn something new everyday.
- Joseph F. Smith

§3.1 INTRODUCTION TO DETERMINANTS

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Example: Find the determinant of the 2×2 matrix

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Example: Find the determinants of

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 10 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 1 & 0 & 2 \\ 3 & -2 & 0 \\ -1 & 3 & 2 \end{bmatrix}.$$

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$$C_{11} = 2, \quad C_{12} = 2, \quad \text{and} \quad C_{13} = -3.$$

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So, we can state the determinant of A (from the previous example) in terms of its cofactors:

$$\det A = a_{11}C_{11} + a_{12}C_{12} + a_{13}C_{13}$$

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The sign we multiply each A_{ij} to get C_{ij} is given by the following checkerboard pattern:

$$\begin{bmatrix} + & - & + & \cdots \\ - & + & - & \\ + & - & + & \\ \vdots & & & \ddots \end{bmatrix}$$

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$$B = \begin{bmatrix} 6 & -1 & -3 & 2 \\ 0 & 3 & 9 & -11 \\ 0 & 0 & 6 & 0 \\ 0 & 0 & 0 & -2 \end{bmatrix}.$$

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THEOREM

If A is a triangular matrix, then $\det A$ is the product of the entries on the main diagonal of A .

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3. If one row of A is multiplied by k to produce B , then

$$\det B = k \cdot \det A.$$

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Example: Find the determinant of

$$\begin{bmatrix} 0 & 2 & 1 & -2 \\ 3 & 6 & -3 & 0 \\ -1 & -2 & 2 & 11 \\ 1 & -2 & -5 & -2 \end{bmatrix}$$

using row reduction operations.

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$$\det A = \begin{cases} (-1)^r \cdot \left(\begin{array}{c} \text{product of} \\ \text{pivots in } U \end{array} \right) & \text{when } A \text{ is invertible} \end{cases}$$

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Example: Compute

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Example: Compute

$$\begin{vmatrix} 1 & 3 & -1 \\ 2 & 2 & 2 \\ 3 & 5 & 1 \end{vmatrix} = 0$$

because $R_3 = R_1 + R_2$, and hence the rows are not linearly independent (and A is not invertible).

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$$\det \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \det \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} = 1 + 4 \neq 9 = \det \left(\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \right).$$

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For any $n \times n$ matrix A and any \mathbf{b} in \mathbb{R}^n , let $A_i(\mathbf{b})$ be the matrix obtained from A by replacing column i with the vector \mathbf{b} .

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$$x_i = \frac{\det A_i(\mathbf{b})}{\det A}, \quad i = 1, 2, \dots, n.$$

§3.3 CRAMER'S RULE, VOLUME & LINEAR TRANSF.

PROOF.

Let $A = [\mathbf{a}_1 \quad \cdots \quad \mathbf{a}_n]$ and $I = [\mathbf{e}_1 \quad \cdots \quad \mathbf{e}_n]$, and suppose $A\mathbf{x} = \mathbf{b}$.

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Then $I_j(\mathbf{x}) = [\mathbf{e}_1 \ \cdots \ \mathbf{x} \ \cdots \ \mathbf{e}_n]$,

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$$\begin{aligned} A \cdot I_j(\mathbf{x}) &= [A\mathbf{e}_1 \ \cdots \ A\mathbf{x} \ \cdots \ A\mathbf{e}_n] \\ &= [\mathbf{a}_1 \ \cdots \ \mathbf{b} \ \cdots \ \mathbf{a}_n] \\ &= A_j(\mathbf{b}). \end{aligned}$$

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Thus

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Let $A = [\mathbf{a}_1 \ \cdots \ \mathbf{a}_n]$ and $I = [\mathbf{e}_1 \ \cdots \ \mathbf{e}_n]$, and suppose $A\mathbf{x} = \mathbf{b}$.

Then $I_j(\mathbf{x}) = [\mathbf{e}_1 \ \cdots \ \mathbf{x} \ \cdots \ \mathbf{e}_n]$, and $\det I_j(\mathbf{x}) = x_j$.

$$\begin{aligned} A \cdot I_j(\mathbf{x}) &= [A\mathbf{e}_1 \ \cdots \ A\mathbf{x} \ \cdots \ A\mathbf{e}_n] \\ &= [\mathbf{a}_1 \ \cdots \ \mathbf{b} \ \cdots \ \mathbf{a}_n] \\ &= A_j(\mathbf{b}). \end{aligned}$$

Thus

$$\det A_j(\mathbf{b}) = \det(A \cdot I_j(\mathbf{x})) = \det A \cdot \det I_j(\mathbf{x}) = \det A \cdot x_j,$$

$$\text{and } x_j = \frac{\det A_j(\mathbf{b})}{\det A}.$$



§3.3 CRAMER'S RULE, VOLUME & LINEAR TRANSF.

Example: Find the solutions x and y to the following system:

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§3.3 CRAMER'S RULE, VOLUME & LINEAR TRANSF.

Example: Find the solutions x, y and z to the following system:

$$x + 3y - 2z = 0$$

$$4x + y + 3z = 1$$

$$6x + 7y - 2z = 2.$$

§3.3 CRAMER'S RULE, VOLUME & LINEAR TRANSF.

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THEOREM

Let A be an invertible $n \times n$ matrix.

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Let A be an invertible $n \times n$ matrix. Then

$$A^{-1} = \frac{1}{\det A} \text{adj } A.$$

§3.3 CRAMER'S RULE, VOLUME & LINEAR TRANSF.

Example: Find the adjugate of

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 10 \end{bmatrix},$$

and use it to find A^{-1} .

§3.3 CRAMER'S RULE, VOLUME & LINEAR TRANSF.

THEOREM

Let $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$, with standard matrix A , and let $S \subset \mathbb{R}^2$ be a region with finite area.

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i.e. the size of the determinant tells us how much area/volume are scaled under a linear transformation.

§3.3 CRAMER'S RULE, VOLUME & LINEAR TRANSF.

Example: Find the area of a parallelogram P with corners at $(0, 0)$, $(2, 3)$, $(1, -2)$, and $(3, 1)$.

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Example: Find the volume of the ellipsoid E given by the equation

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} \leq 1.$$

