

AIFA: APPROXIMATE INFERENCE

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Sampling

- Sampling from given distribution
 - **Step 1:** Get sample u from uniform distribution over $[0, 1)$
 - e.g. `random()` in python
 - **Step 2:** Convert this sample u into an outcome for the given distribution
 - by having each outcome associated with a sub-interval of $[0,1)$
 - with sub-interval size equal to probability of the outcome

C	P(C)
red	0.6
green	0.1
blue	0.3

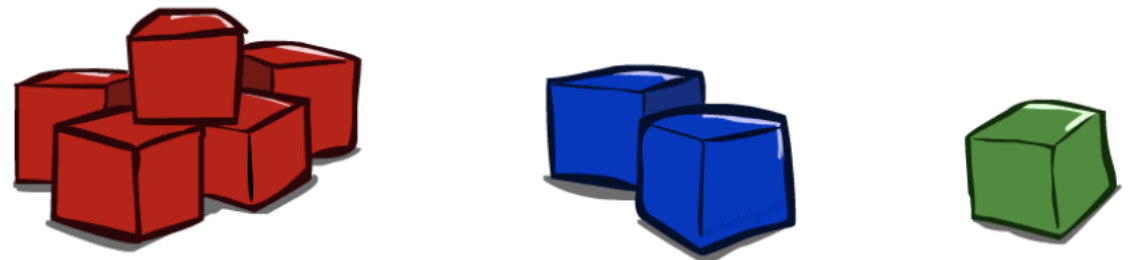
$0 \leq u < 0.6 \rightarrow C = \text{red}$

$0.6 \leq u < 0.7 \rightarrow C = \text{blue}$

$0.7 \leq u < 1 \rightarrow C = \text{red}$

If `random()` returns $u=0.83$
Our sample is $C = \text{blue}$

- E.g, after sampling 8 times:

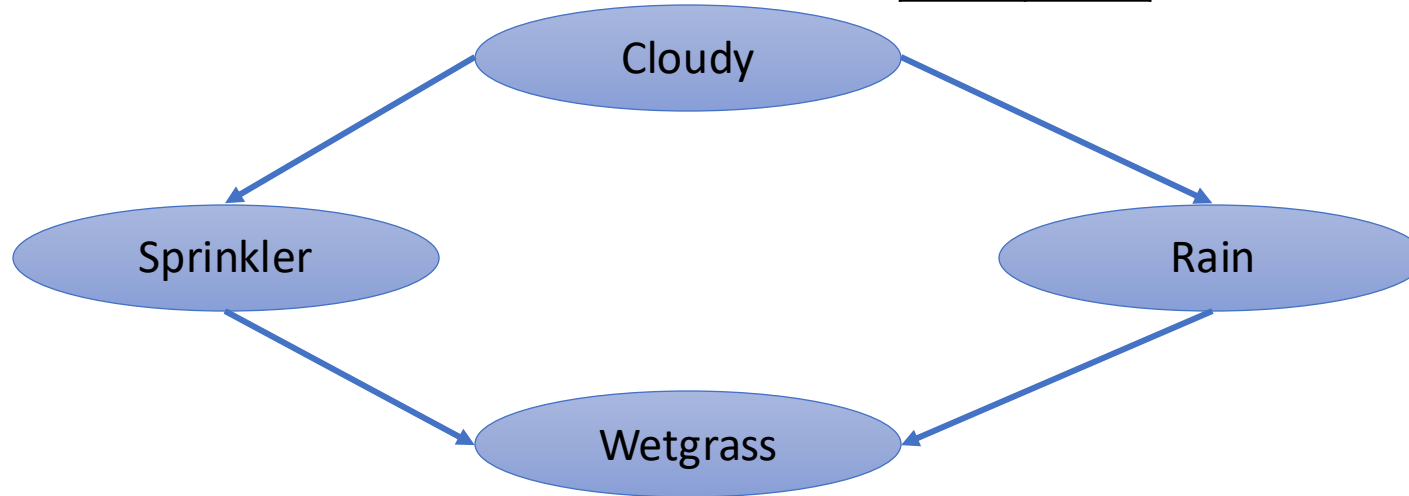


Sampling strategies

- Prior sampling
- Rejection sampling
- Likelihood weighting
- Gibbs sampling

Prior Sampling

$P(S C)$	
+c	0.1
-c	0.5



$P(C)$	
+c	0.5

$P(R C)$	
+c	0.8
-c	0.2

$P(W S,R)$		
+s	+r	0.99
+s	-r	0.90
-s	+r	0.90
-s	-r	0.01

Samples:

+c, -s, +r, +w

-c, +s, -r, +w

...

Prior Sampling

- For $i=1,2,\dots,n$
 - Sample x_i from $P(X_i \mid \text{Parents}(X_i))$
- Return (x_1, x_2, \dots, x_n)

Prior Sampling

- This process generates samples with probability:

$$S_{PS}(x_1 \dots x_n) = \prod_{i=1}^n P(x_i | \text{Parents}(X_i)) = P(x_1 \dots x_n)$$

- ...i.e. the BN's joint probability

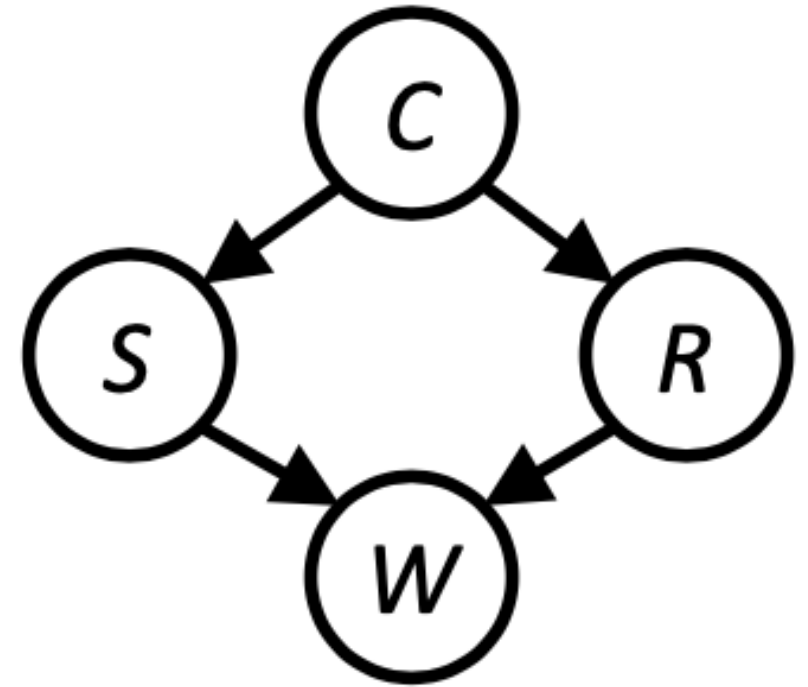
- Let the number of samples of an event be $N_{PS}(x_1, x_2, \dots, x_n)$

- Then
$$\begin{aligned} \lim_{N \rightarrow \infty} \hat{P}(x_1, \dots, x_n) &= \lim_{N \rightarrow \infty} N_{PS}(x_1, \dots, x_n) / N \\ &= S_{PS}(x_1, \dots, x_n) \\ &= P(x_1 \dots x_n) \end{aligned}$$

- the sampling procedure is **consistent**

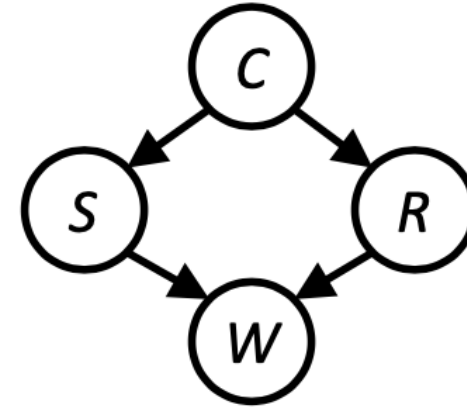
Prior Sampling

- We'll get a bunch of samples from the BN:
- $+c, -s, +r, +w$
- $+c, +s, +r, +w$
- $-c, +s, +r, -w$
- $+c, -s, +r, +w$
- $-c, -s, -r, +w$
- If we want to know $P(W)$
- We have counts $\langle +w:4, -w:1 \rangle$
- Normalize to get $P(W) = \langle +w:0.8, -w:0.2 \rangle$
- This will get closer to the true distribution with more samples
- Can estimate anything else, too
- What about $P(C \mid +w)$? $P(C \mid +r, +w)$? $P(C \mid -r, -w)$?
- Fast: can use fewer samples if less time (what's the drawback?)



Rejection Sampling

- Let's say we want $P(C)$
 - No point keeping all samples around
 - Just tally counts of C as we go
- Let's say we want $P(C \mid +s)$
 - Same thing: tally C outcomes, but ignore (reject) samples which don't have $S=+s$
 - This is called rejection sampling
- It is also consistent for conditional probabilities (i.e., correct in the limit)



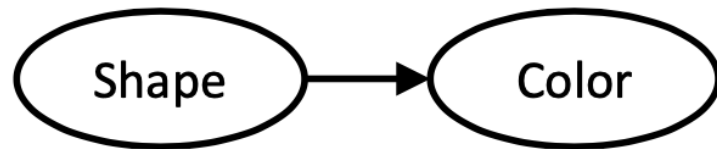
+c, -s, +r, +w
+c, +s, +r, +w
-c, +s, +r, -w
+c, -s, +r, +w
-c, -s, -r, +w

Rejection Sampling

- IN: evidence instantiation
- For $i=1, 2, \dots, n$
 - Sample x_i from $P(X_i \mid \text{Parents}(X_i))$
 - If x_i not consistent with evidence
 - Reject: Return, and no sample is generated in this cycle
- Return (x_1, x_2, \dots, x_n)

Likelihood Weighting

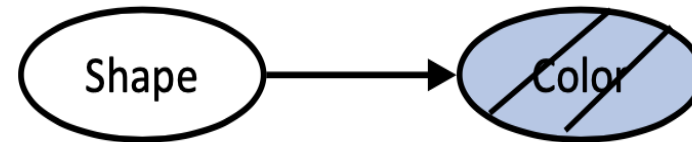
- Problem with rejection sampling:
 - If evidence is unlikely, rejects lots of samples
 - Evidence not exploited as you sample
 - Consider $P(\text{Shape} | \text{blue})$



~~pyramid, green~~
~~pyramid, red~~
sphere, blue
~~cube, red~~
~~sphere, green~~

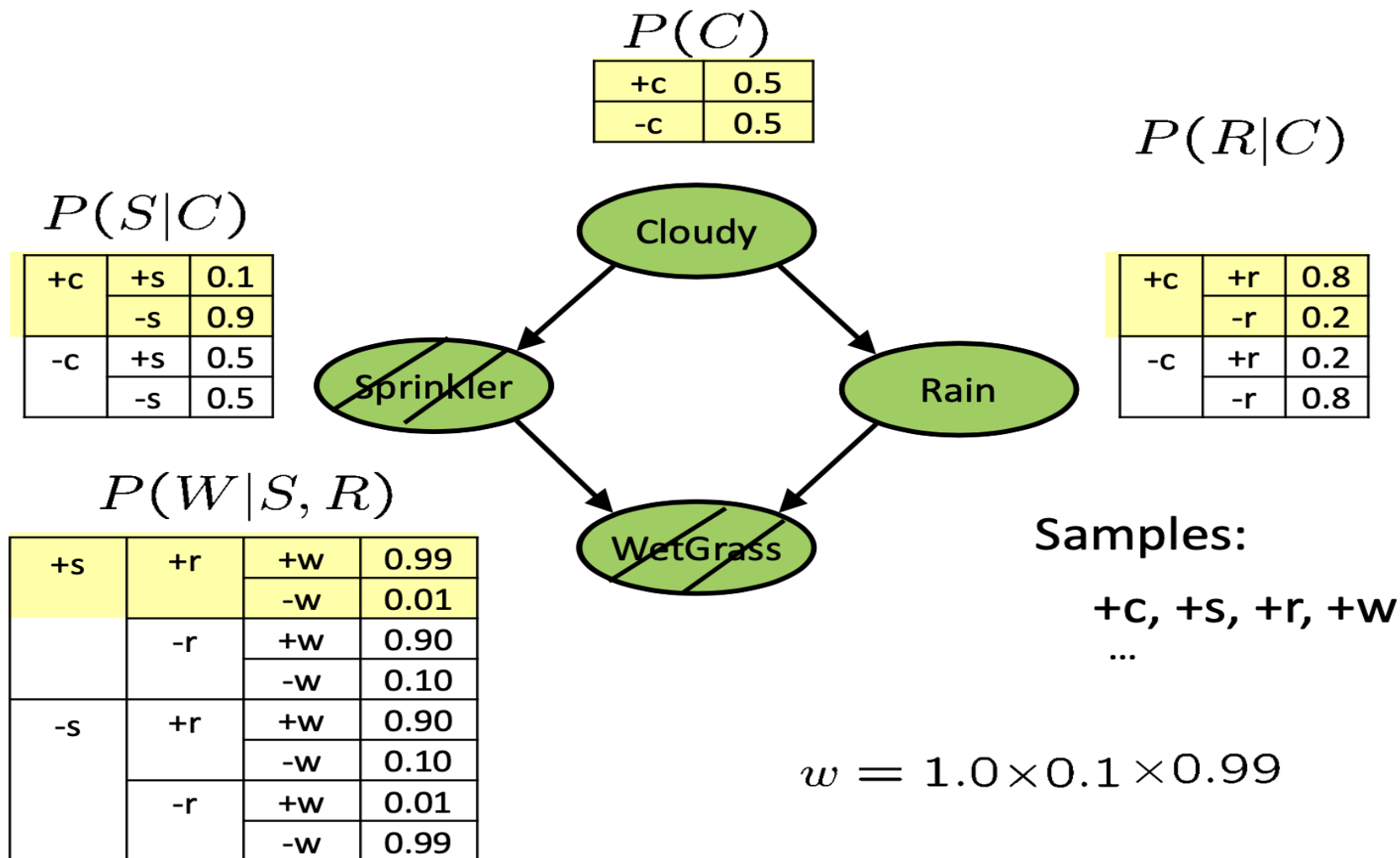
Idea: fix evidence variables and sample the rest

- Problem: sample distribution not consistent!
- Solution: weight by probability of evidence given parents



pyramid, blue
pyramid, blue
sphere, blue
cube, blue
sphere, blue

Likelihood Weighting



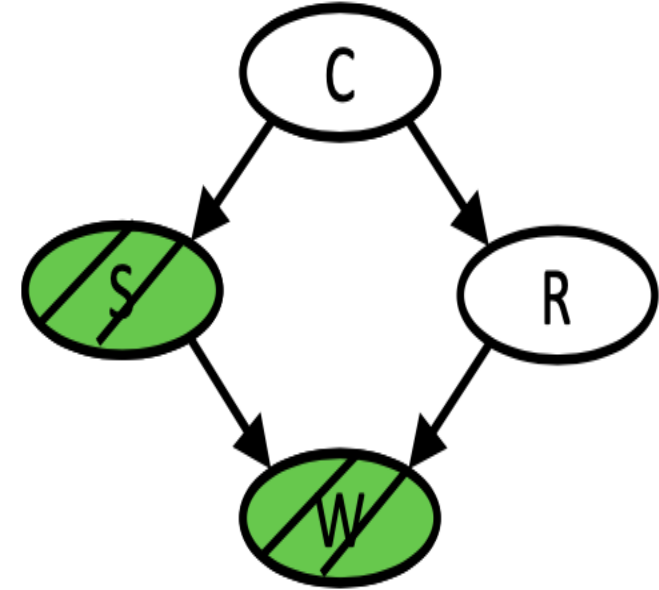
$P(\text{Rain} | \text{Sprinkler}=\text{True}, \text{WetGrass}=\text{True})$

Likelihood Weighting

- IN: evidence instantiation
- $w = 1.0$
- for $i=1, 2, \dots, n$
 - if X_i is an evidence variable
 - $X_i = \text{observation } x_i \text{ for } X_i$
 - Set $w = w * P(x_i \mid \text{Parents}(X_i))$
 - else
 - Sample x_i from $P(X_i \mid \text{Parents}(X_i))$
- return $(x_1, x_2, \dots, x_n), w$

Likelihood Weighting

- Sampling distribution if z sampled and e fixed evidence
 - $S_{WS}(z, e) = \prod_{i=1}^l P(z_i | Parents(z_i))$
- Now, samples have weights
 - $w(z, e) = \prod_{i=1}^m P(e_i | Parents(e_i))$
- Together, weighted sampling distribution is consistent
 - $S_{WS}(z, e)w(z, e) = \prod_{i=1}^l P(z_i | Parents(z_i)) \prod_{i=1}^m P(e_i | Parents(e_i))$
 - $S_{WS}(z, e)w(z, e) = P(z, e)$



Likelihood Weighting

- Likelihood weighting is good
 - We have taken evidence into account as we generate the sample
 - E.g. here, W's value will get picked based on the evidence values of S, R
 - More of our samples will reflect the state of the world suggested by the evidence

Likelihood weighting doesn't solve all our problems

- Evidence influences the choice of downstream variables, but not upstream ones (C isn't more likely to get a value matching the evidence)
- We would like to consider evidence when we sample every variable
 - Gibbs sampling

Gibbs Sampling

- Procedure:
 - keep track of a full instantiation x_1, x_2, \dots, x_n
 - Start with an arbitrary instantiation consistent with the evidence
 - Sample one variable at a time, conditioned on all the rest, but keep evidence fixed
 - Keep repeating this for a long time
- Property:
 - In the limit of repeating this infinitely many times the resulting sample is coming from the correct distribution

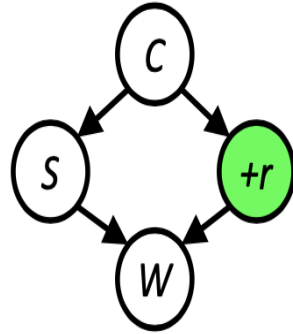
Gibbs Sampling

- Rationale:
 - Both upstream and downstream variables condition on evidence
- In contrast:
 - likelihood weighting only conditions on upstream evidence, and hence weights obtained in likelihood weighting can sometimes be very small
 - Sum of weights over all samples is indicative of how many “effective” samples were obtained, so want high weight

Gibbs Sampling: $P(s|+r)$

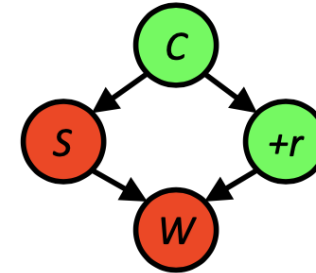
- Step 1: Fix evidence

- $R = +r$



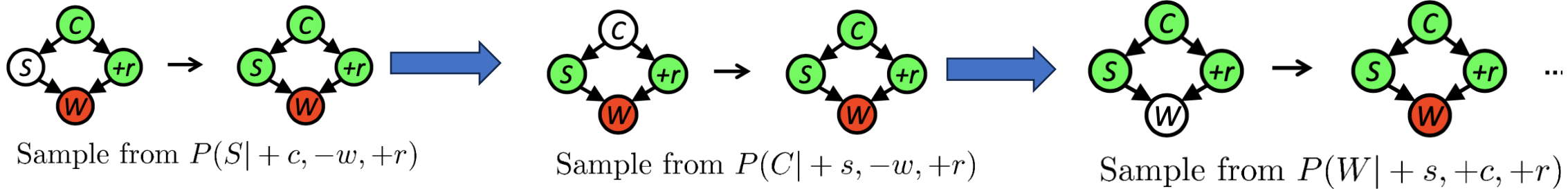
- Step 2: Initialize other variables

- Randomly



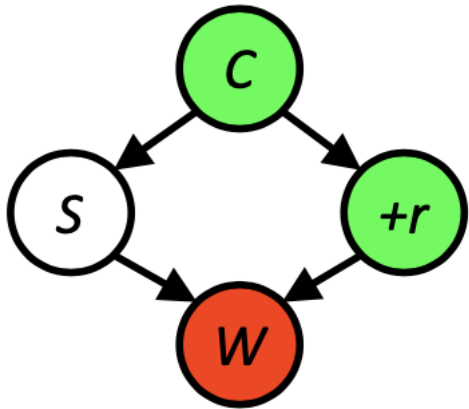
- Steps 3: Repeat

- Choose a non-evidence variable X
- Resample X from $P(X \mid \text{all other variables})$



Efficient Resampling of One Variable

- Sample from $P(S \mid +c, +r, -w)$



- $P(S \mid +c, +r, -w) = \frac{P(S, +c, +r, -w)}{P(+c, +r, -w)}$
- $P(S \mid +c, +r, -w) = \frac{P(S, +c, +r, -w)}{\sum_S P(S, +c, +r, -w)}$
- $P(S \mid +c, +r, -w) = \frac{P(+c)P(S \mid +c)P(+r \mid +c)P(-w \mid S, +r)}{\sum_S P(+c)P(S \mid +c)P(+r \mid +c)P(-w \mid S, +r)}$
- $P(S \mid +c, +r, -w) = \frac{P(+c)P(S \mid +c)P(+r \mid +c)P(-w \mid S, +r)}{P(+c)P(+r \mid +c) \sum_S P(S \mid +c)P(-w \mid S, +r)}$
- $P(S \mid +c, +r, -w) = \frac{P(S \mid +c)P(-w \mid S, +r)}{\sum_S P(S \mid +c)P(-w \mid S, +r)}$

- Many things cancel out – only CPTs with S remain!
- More generally: only CPTs that have resampled variable need to be considered, and joined together

Gibbs Sampling

- Gibbs sampling produces sample from the query distribution $P(Q | e)$ in limit of re-sampling infinitely often
- Gibbs sampling is a special case of more general methods called Markov chain Monte Carlo (MCMC) methods
 - Metropolis-Hastings is one of the more famous MCMC methods (in fact, Gibbs sampling is a special case of Metropolis-Hastings)

Approximate Inference

- Basic idea
 - If we had access to a set of examples from the joint distribution, we could just count
 - $E[f(x)] \approx \frac{1}{N} \sum_{i=1}^N f(x^{(i)})$
 - For inference, we generate instances from the joint and count
 - How do we generate instances?

Generating Instances

- Sampling from the Bayesian Network
 - Conditional probabilities i.e., $P(X|E)$
 - Only generate instances that are consistent with E
- Problems?
 - How many samples? [Law of large numbers]
 - What if the evidence EE is a very low probability event?

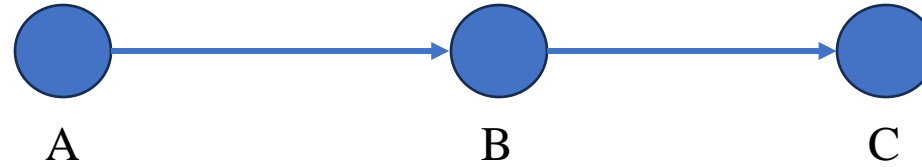
Markov Chain Monte Carlo

- Our goal: To sample from $P(X|e)$
- Overall idea:
 - The next sample is a function of the current sample
 - The samples can be thought of as coming from a Markov Chain whose stationary distribution is the distribution we want
- Can approximate any distribution

Gibbs Sampling

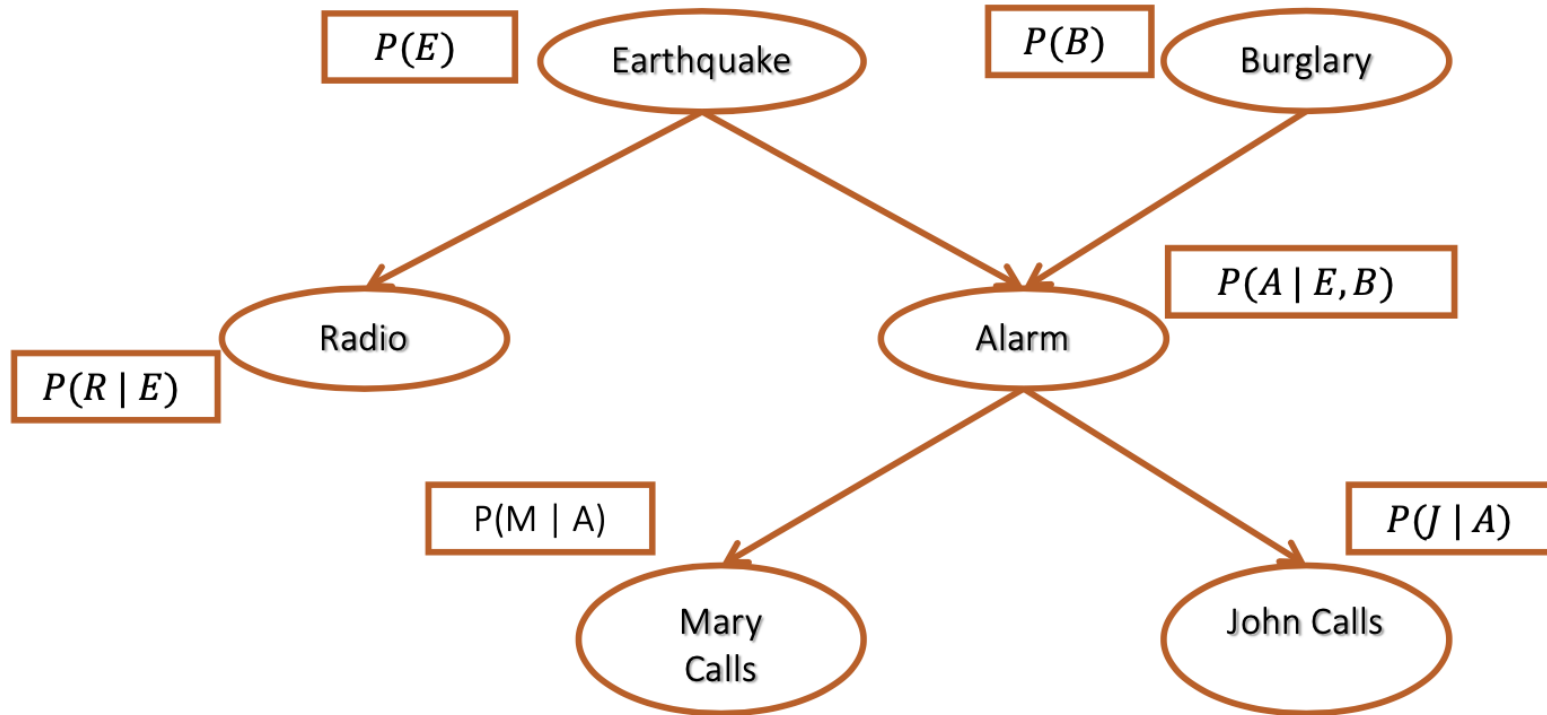
- Algorithm:
 - Initialize X randomly
 - Iterate:
 - Pick a variable X_i uniformly at random
 - Sample $x_i^{(t+1)}$ from $P(x_i | x_1^{(t)}, \dots, x_{i-1}^{(t)}, x_{i+1}^{(t)}, \dots, x_n^{(t)}, e)$
 - $X_k^{(t+1)} = x_k^{(t+1)}$ for all other k
 - This is the next sample
- Using the samples, we approximate the posterior by counting.

Gibbs Sampling: Example 1



- We want to compute $P(C)$:
 - Suppose, after burn in, the Markov Chain is at $A=\text{true}$, $B = \text{false}$, $C= \text{false}$
1. Pick a *variable* $\rightarrow B$
 2. Draw the new value of B from
 1. $P(B|A=\text{true}, C=\text{false}) = P(B|A=\text{true})$
 2. Suppose $B^{\text{new}} = \text{true}$
 3. Our new sample is $A = \text{true}$, $B=\text{true}$, $C=\text{false}$
 4. Repeat

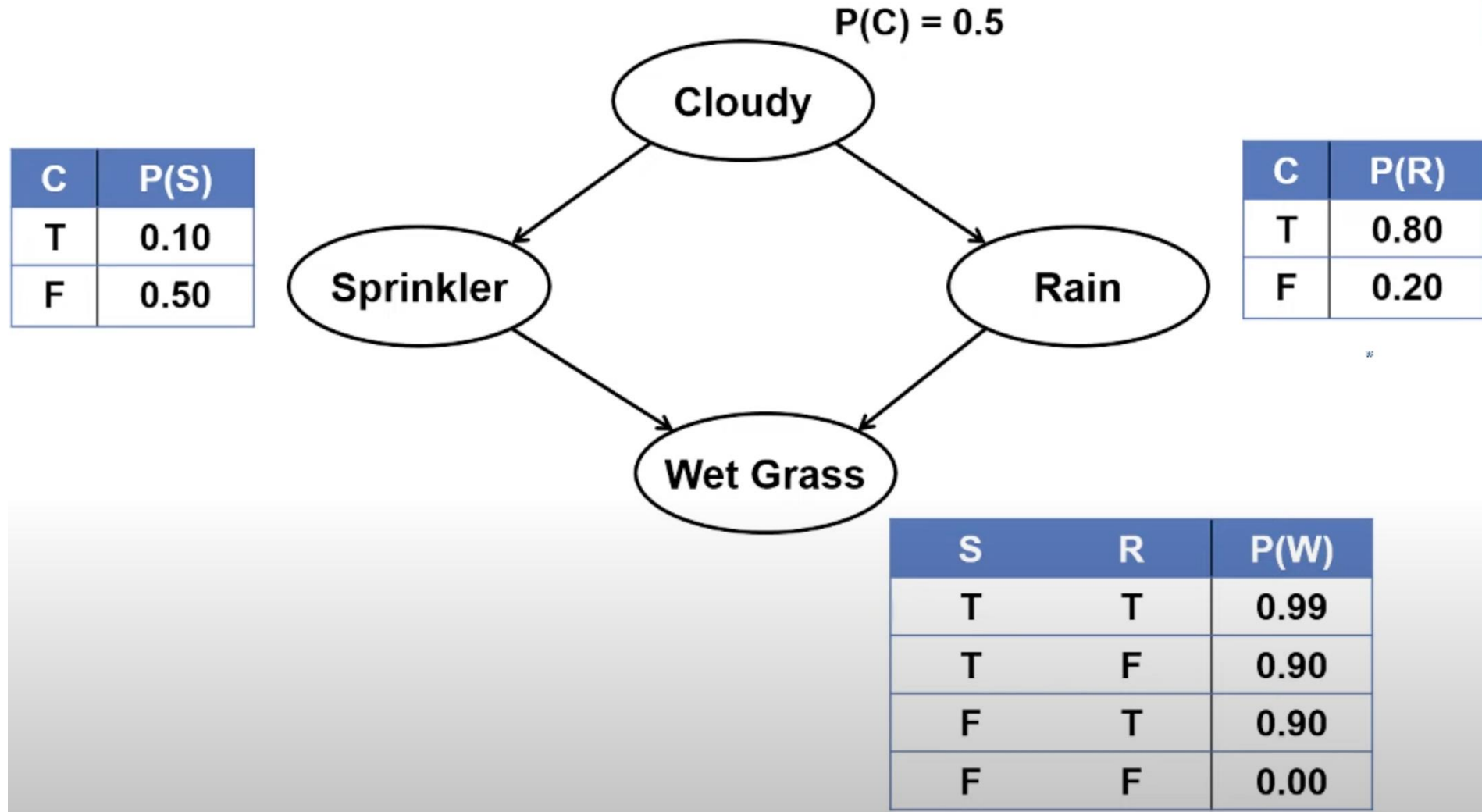
Gibbs Sampling: Example 2



Exercise: $P(M, J | B)$?

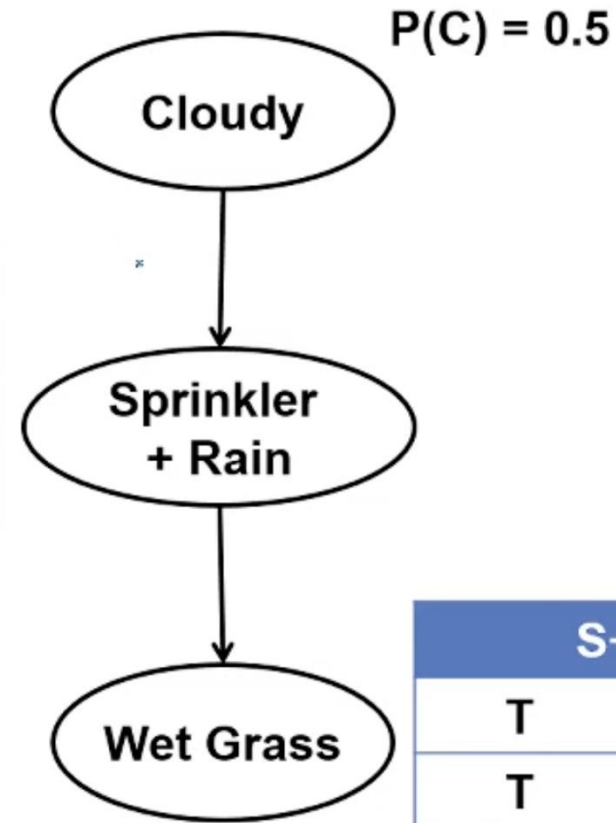
Challenges in Inference

Inference in multiply connected Belief Networks



Clustering Methods

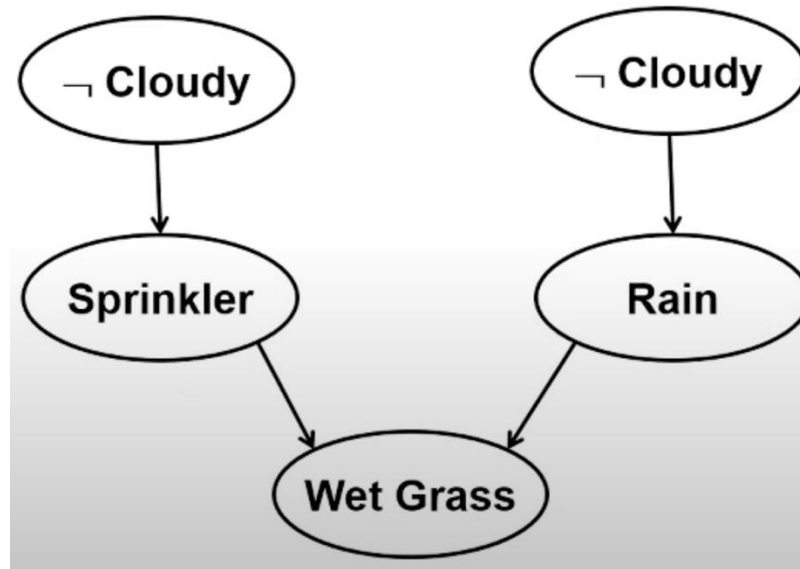
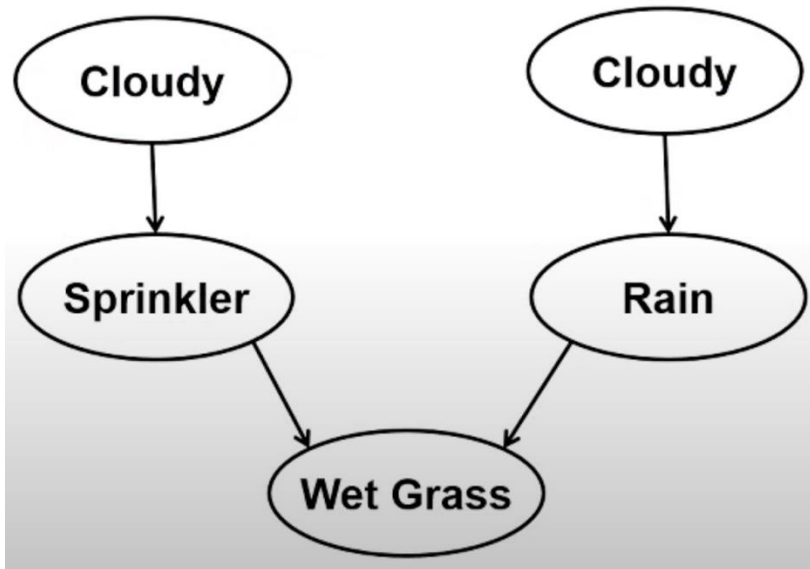
C		P(S+R = x)			
		TT	TF	FT	FF
T		0.08	0.02	0.72	0.18
F		0.40	0.10	0.40	0.10



S+R		P(W)
T	T	0.99
T	F	0.90
F	T	0.90
F	F	0.00

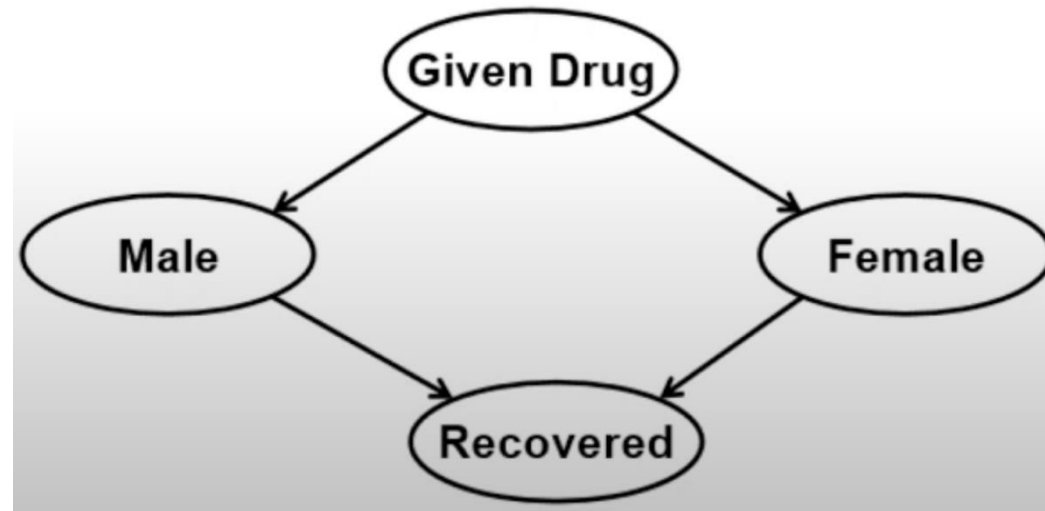
Cutset Conditioning Method

- A set of variables that can be instantiated to yield a poly-tree is called a cutset
- Instantiate the cutset variables to definite values
 - Then evaluate a poly-tree for each possible instantiation



Stochastic Simulation Methods

- Use the network to generate a large number of concrete models of the domain that are consistent with the network distribution
- They give an approximation of the exact evaluation
- Statistical bias can lead to misleading results – Simpson's Paradox



Simpson's Paradox

Males	Recovered	Not Recovered	Rec. Rate
Given drug	18	12	60%
Not given drug	7	3	70%

Females	Recovered	Not Recovered	Rec. Rate
Given drug	2	8	20%
Not given drug	9	21	30%

Combined	Recovered	Not Recovered	Rec. Rate
Given drug	20	20	50%
Not given drug	16	24	40%

- Should the drug be administered or not?

Drug is administered on too few females

Simpson's Paradox

Males	Recovered	Not Recovered	Rec. Rate
Given drug	18	12	60%
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Combined	Recovered	Not Recovered	Rec. Rate
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Females	Recovered	Not Recovered	Rec. Rate
Given drug	2	8	20%
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$$P(\text{recovery}|\text{male} \wedge \text{given_drug}) = 0.6$$

$$P(\text{recovery}|\text{given_drug}) = P(\text{recovery}|\text{male} \wedge \text{given_drug})P(\text{given_drug}|\text{male}) + P(\text{recovery}|\text{female} \wedge \text{given_drug})P(\text{given_drug}|\text{female})$$

$$P(\text{recovery}|\text{given_drug}) = \left(0.6 \times \frac{30}{40}\right) + \left(0.20 \times \frac{10}{40}\right) = 0.5$$

- Should the drug be administered or not?

Default Reasoning

- Some conclusions are made by default unless a counter-evidence is obtained
 - Non-monotonic reasoning
- Points to think:
 - What is the semantic status of default rules?
 - What happens when the evidence matches the premises of two default rules with conflicting conclusions?
 - If a belief is retracted later, how can a system keep track of which conclusions need to be retracted as a consequence?

Issues in Rule-based methods for Uncertain Reasoning

- Locality

- In logical reasoning systems, if we have $A \Rightarrow B$, then we can conclude B given evidence A, **without worrying about any other rules**
- In probabilistic systems, we have to consider all available evidence

- Detachment

- Once a logical proof is found for proposition B, we can use it regardless of how it is derived (it can be detached from its justification)
- **In probabilistic reasoning, the source of the evidence is important for subsequent reasoning**

Issues in Rule-based methods for Uncertain Reasoning

- Truth functionality
 - In logic, the truth of the complex sentences can be computed from the truth of the components
 - Probability combination does not work this way, except under strong independence assumptions
- A famous example of a truth functional system for uncertain reasoning is the [certainly factors model](#), developed for Mycin medical diagnostic problem

Dempster-Shafer Theory

- Designed to deal with the distinction between uncertainty and ignorance
- We use a belief function $\text{Bel}(X)$ – probability that the evidence supports the proposition
- When we do not have any evidence about X , we assign $\text{Bel}(X)=0$ as well as $\text{Bel}(\sim X)=0$
- For example, if we do not know whether a coin is fair, then:
 - $\text{Bel}(\text{heads}) = \text{Bel}(\sim\text{heads}) = 0$
- If we are given that coin is fair with 90% certainty, then:
 - $\text{Bel}(\text{heads}) = 0.9 \times 0.5 = 0.45$
 - $\text{Bel}(\sim\text{heads}) = 0.9 \times 0.5 = 0.45$
 - We still have a gap of 0.10 that is not accounted for by the evidence

Thank You