AIFA: Reasoning Under Uncertainty - Inference

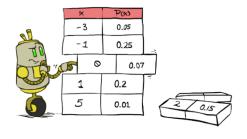
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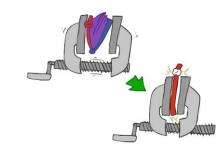
Inference by Enumeration

- General Case:
 - Evidence variables: $E_1, E_2, \dots E_k = e_1, e_2, \dots, e_k$
 - Query Variable: Q
 - Hidden variables: $H_1, H_2, ... H_r$
 - $X_1, X_2, ... X_n$ all variables
- We want: $P(Q|e_1, e_2, ..., e_k)$

Step 1: Select the entries consistent with the evidence



Step 2: Sum out H to get joint of Query and evidence



Step 3: Normalize

$$\times \frac{1}{Z}$$

$$Z = \sum_{q} P(Q, e_1, e_2, \dots, e_k)$$

$$P(Q|e_1, e_2, ..., e_k) = \frac{1}{Z}P(Q, e_1, e_2, ..., e_k)$$

$$P(Q, e_1, e_2, \dots, e_k) = \sum_{h_1, h_2, \dots, h_r} P(Q, h_1, h_2, \dots, h_r, e_1, e_2, \dots, e_k)$$

Inference using Belief Networks

$$P(B|J) = \frac{P(BJ)}{P(J)}$$

$$P(BJ) = P(BJA) + P(BJA')$$

$$P(BJA) = P(J|AB)P(AB) + P(J|A'B)P(A'B)$$

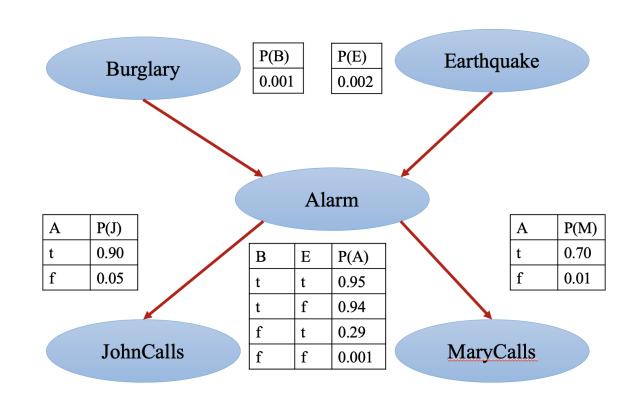
$$P(AB) = P(ABE) + P(ABE')$$

$$P(AB) = P(A|BE)P(BE) + P(A|BE')P(BE')$$

$$P(AB) = 0.00095$$

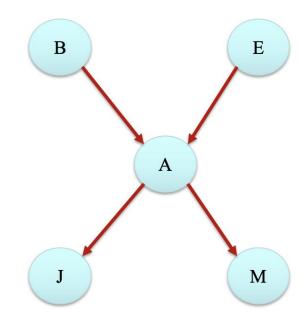
$$P(A'B) = 0.00005$$





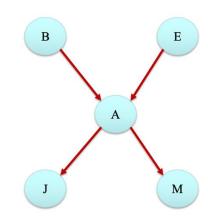
Bayesian Network: Inference

- Compute posterior probability distribution of a set of query variables
 - Given some observed event [evidence variables]
 - Some unobserved events [Hidden variables]
- P(B|J=True, M=True)
- Hidden variables:
 - Earthquake
 - Alarm



• P(B|J=True, M=True)

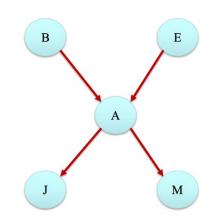
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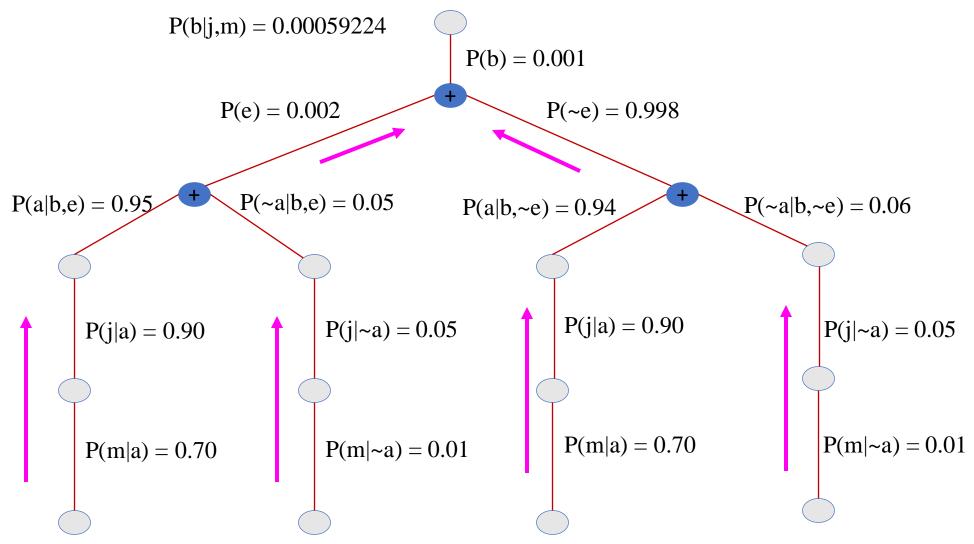
- $P(b|j,m) = \sum_{e} \sum_{a} P(b)P(e)P(a|b,e)P(j|a)P(m|a)$
- Add four terms each computed by multiplying five numbers
- If network contains n variables, complexity $O(n2^n)$

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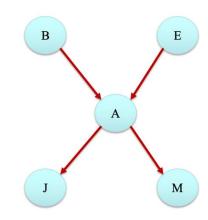


- $P(b|j,m) = \sum_{e} \sum_{a} P(b)P(e)P(a|b,e)P(j|a)P(m|a)$
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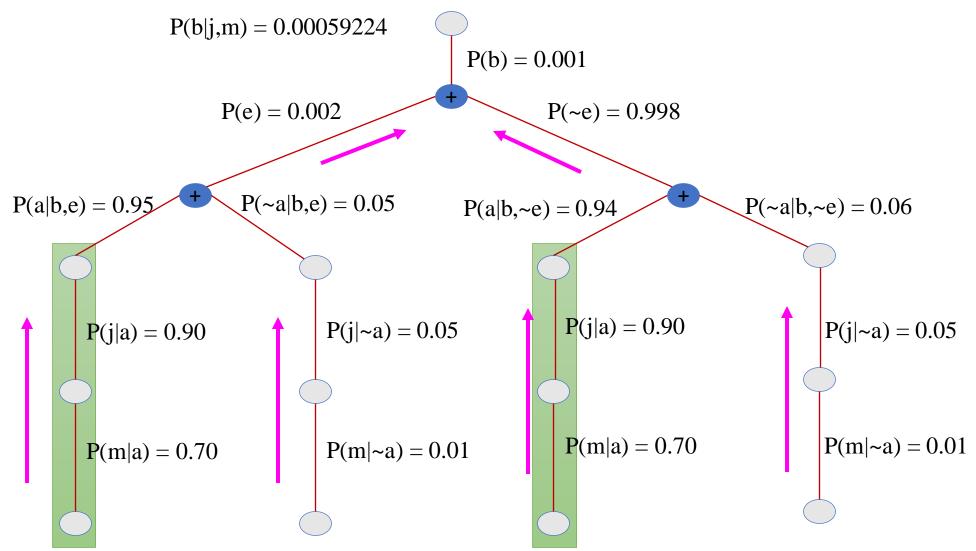


• P(B|J=True, M=True)

- Hidden variables:
 - Earthquake
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- $P(b|j,m) = P(b) \sum_{e} P(e) \sum_{a} P(a|b,e) P(j|a) P(m|a)$
- P(b|j,m) = <0.00059224,0.0014919> = <0.284,0.716>
- Chance of a burglary given calls from both neighbours is 28%
- Complexity: $O(2^n)$



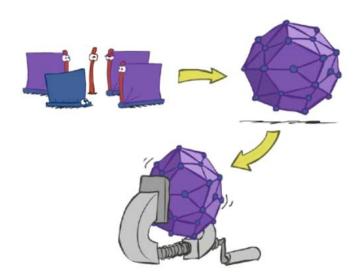
Inference by Variable Elimination

Problem of Inference: Example

- Consider a chain Bayesian network
 - $p(y = 1, x_1, x_2, ..., x_n) = p(x_1) \prod_{i=1}^n p(x_i | x_{i-1})$
- We are interested in computing the marginal probability $p(x_n)$
- Enumeration:
 - $p(x_n) = \sum_{x_1} \sum_{x_2} ... \sum_{x_{n-1}} p(x_1, x_2, ..., x_n)$
 - Complexity:
 - Sum the probability over all assignments of $x_1, x_2, ..., x_{n-1}$
 - k^{n-1}
- Can we do better?

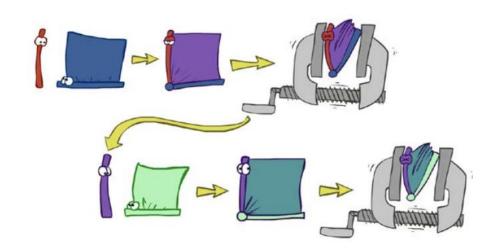
Inference by Elimination

- Why is inference by enumeration so slow?
- We join up the whole joint distribution before you sum out the hidden variables



Variable Elimination

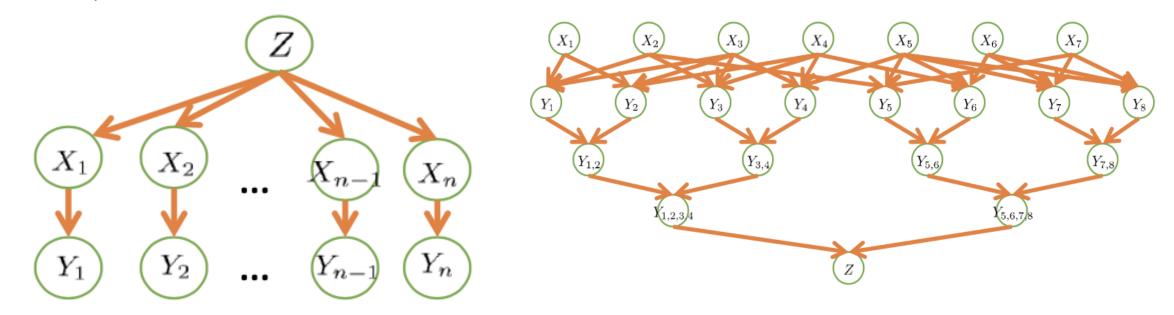
- Idea: interleave joining and marginalizing
- Called "Variable Elimination"
- Still NP-hard, but usually much faster than inference by enumeration



Variable Elimination

- Interleave joining and marginalizing
- d^k entries computed for a factor over k variables with domain sizes d
- Ordering of elimination of hidden variables can affect size of factors generated
- Worst case: running time exponential in the size of the Bayes' net

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Problem of Inference: Example

- We may rewrite the sum in a way that "pushes in" certain variables deeper into the product
- $p(x_n) = \sum_{x_1} \sum_{x_2} \dots \sum_{x_{n-1}} p(x_1) \prod_{i=2}^n p(x_i | x_{i-1})$
- $p(x_n) = \sum_{x_{n-1}} p(x_n|x_{n-1}) \sum_{x_{n-2}} p(x_{n-1}|x_{n-2}) \dots \sum_{x_1} p(x_2|x_1) p(x_1)$
- We sum the inner terms first, starting from x_1 and ending with x_{n-1}
- We start by computing an intermediary factor
 - $\tau(x_2) = \sum_{x_1} p(x_2|x_1) p(x_1)$ by summing out x_1
 - This takes $O(k^2)$ time because we must sum over x_1 for each assignment to x_2
 - The resulting factor $\tau(x_2)$ can be thought of as a table of k values
 - with one entry for each assignment to x₂
 - Not necessarily probability values

•
$$p(x_n) = \sum_{x_{n-1}} p(x_n | x_{n-1}) \sum_{x_{n-2}} p(x_{n-1} | x_{n-2}) \dots \sum_{x_2} p(x_3 | x_2) \tau(x_2)$$

Problem of Inference: Example

- $p(x_n) = \sum_{x_{n-1}} p(x_n | x_{n-1}) \sum_{x_{n-2}} p(x_{n-1} | x_{n-2}) \dots \sum_{x_1} p(x_2 | x_1) p(x_1)$
- $p(x_n) = \sum_{x_{n-1}} p(x_n | x_{n-1}) \sum_{x_{n-2}} p(x_{n-1} | x_{n-2}) \dots \sum_{x_2} p(x_3 | x_2) \tau(x_2)$
- This has the same form as the initial expression, except that we are summing over one fewer variable
- Compute another factor: $\tau(x_3) = \sum_{x_2} p(x_3|x_2)\tau(x_2)$
- Repeat the process until we are only left with x_n
- Each step takes $O(k^2)$ time
- Time Complexity: $O(nk^2)$

Eliminating Variables

- Factors
 - $p(x_1, \dots, x_n) = \prod_{c \in C} \varphi_c(x_c)$
 - Factor as a multi-dimensional table assigning a value to each assignment of a set of variables x_c
 - In a Bayesian network, the factors correspond to conditional probability distributions
- Factor Operations
 - The variable elimination algorithm repeatedly performs two factor operations:
 - product and
 - marginalization
 - We have been implicitly performing these operations in our chain example

Factor Product

- The factor product operation simply defines the product $\phi 3:=\phi 1\times\phi 2$ of two factors $\phi 1,\phi 2$ as
 - $\varphi_3(x_c) = \varphi_1(x_c^{(1)}) \times \varphi_2(x_c^{(2)})$
 - The scope of $\phi 3$ is defined as the union of the variables in the scopes of $\phi 1, \phi 2$;
 - Also $x_c^{(i)}$ denotes an assignment to the variables in the scope of ϕ i defined by the restriction of x_c to that scope
 - $\varphi_3(a,b,c) = \varphi_1(a,b) \times \varphi_2(b,c)$

Factor Product & Marginalization

- Next, the **marginalization** operation "locally" eliminates a set of variables from a factor
- If we have a factor $\phi(X,Y)$ over two sets of variables X,Y, marginalizing Y produces a new factor
 - $\tau(x) = \sum_{y} \varphi(x, y)$
 - where the sum is over all joint assignments to the set of variables Y
- We use τ to refer to the marginalized factor
- It is important to understand that this factor does not necessarily correspond to a probability distribution, even if ϕ was a CPD

Orderings

- Finally, the variable elimination algorithm requires an ordering over the variables according to which variables will be "eliminated."
- In our chain example, we took the ordering implied by the DAG

• Notes:

- Different orderings may dramatically alter the running time of the variable elimination algorithm.
- It is NP-hard to find the best ordering.

Variable Elimination Algorithm

- Essentially, we loop over the variables as ordered by O
- Eliminate them in that ordering
- Intuitively, this corresponds to choosing a sum and "pushing it in" as far as possible inside the product of the factors
- For each variable X_i (ordered according to O)
 - Multiply all factors Φ_i containing X_i
 - Marginalize out X_i to obtain a new factor τ
 - Replace the factors Φ_i with τ

VE: Example

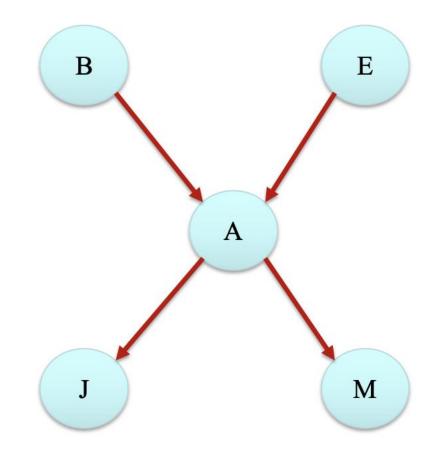
$$p(j,m,a,b,e) = p(j|a)p(m|a)p(a|b,e)p(b)p(e)$$

$$\tau_1(a,e) = \sum_b p(a|b,e)p(b)$$

$$\tau_2(a) = \sum_e \tau_1(a, e) p(e)$$

$$\tau_3(j,m) = \sum_a \tau_2(a) p(j|a) p(m|a)$$

...



Variable Elimination Algorithm

- Evaluate expressions from right to left
- Summations over each variable are done only for those portions of the expression that depend on the variable

•
$$P(B|j,m) = \alpha P(B) \sum_{e} P(e) \sum_{a} P(a|B,e) P(j|a) P(m|a)$$

- Each part of the expression is annotated with the name of the associated variable
 - These parts are called factors

•
$$f_M(A) = \binom{P(m|a)}{P(m|\sim a)}$$

•
$$f_J(A) = \begin{pmatrix} P(j|a) \\ P(j|\sim a) \end{pmatrix}$$

Variable Elimination Algorithm

B E A J M

- $P(B|j,m) = \alpha P(B) \sum_{e} P(e) \sum_{a} P(a|B,e) P(j|a) P(m|a)$
- Sum out A from the product of three factors
- $f_{\bar{A}JM}(B,E) = \sum_{a} f_A(a,B,E) \times f_J(a) \times f_M(a)$
- $f_{\bar{A}JM}(B,E) = f_A(a,B,E) \times f_J(a) \times f_M(a) + f_A(\sim a,B,E) \times f_J(\sim a) \times f_M(\sim a)$
- Pointwise product
- $f_{\bar{E}\bar{A}JM}(B) = f_E(e) \times f_{\bar{A}JM}(B,e) + f_E(\sim e) \times f_{\bar{A}JM}(B,\sim e)$
- $P(B|j,m) = \alpha f_B(B) \times f_{\bar{E}\bar{A}IM}(B)$

VE: Running Time

- Clearly some orderings are more efficient than others
- In fact, the running time of Variable Elimination is $O(nk^{M+1})$
 - where M is the maximum size of any factor τ formed during the elimination process and
 - n is the number of variables

Choosing variable elimination orderings

- Choosing the optimal VE ordering is an NP-hard problem
- Heuristics:
 - *Min-neighbors*: Choose a variable with the fewest dependent variables.
 - *Min-weight*: Choose variables to minimize the product of the cardinalities of its dependent variables
 - *Min-fill*: Choose vertices to minimize the size of the factor that will be added to the graph.

Variable Elimination Algorithm

- function ELIMINATION-ASK(X,e,bn) returns a distribution over X
 - inputs: X, the query variable
 - e, evidence specified as an event
 - bn, a Bayesian network specifying joint distribution P(X1,X2,...,Xn)
 - factors←[]; vars ←REVERSE(VARS[bn])
 - for each var in vars do
 - factors ←[MAKE-FACTOR(var,e)|factors]
 - if var is a hidden variable then factors ←SUM-OUT(var,factors)
 - return NORMALIZE(POINTWISE-PRODUCT(factors))

Thank You