4th April 2012

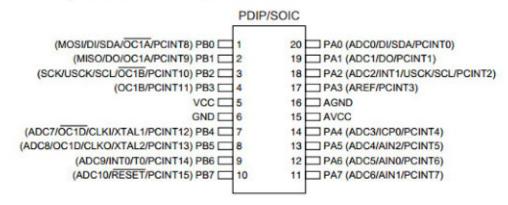
Romotive Hacked with Schematics

Yay- So my Romotive does not work... So lets hack it.

Specs

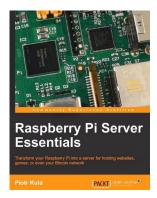
- ATMEL ATiny 861 [http://www.atmel.com/Images/doc2588.pdf] (SOIC)
- 20Mhz Crystal
- 56:1 Micro Geared Motors 100:1 Motor From Pololu [http://www.pololu.com/catalog/product/992]
- R4558 [http://www.kula.org.uk/public/romotive/datasheet/romotive-r4558.pdf] Audio Amplifier (SOIC)
- 2nd Gen Audio Protocol [http://romotive.com/blog/2012/04/hackers-welcomed-second-gen-protocol/] (Posted by Romotive Blog)
- · ATiny861 Official Pin out

Figure 1-1. Pinout ATtiny261/461/861 and ATtiny261V/461V/861V



[http://2.bp.blogspot.com/-czZa69uDylg/T3oHGIPpswl/AAAAAAAAAAXI/lboAUiT2Rfw/s1600/attiny861-pinout.jpg]

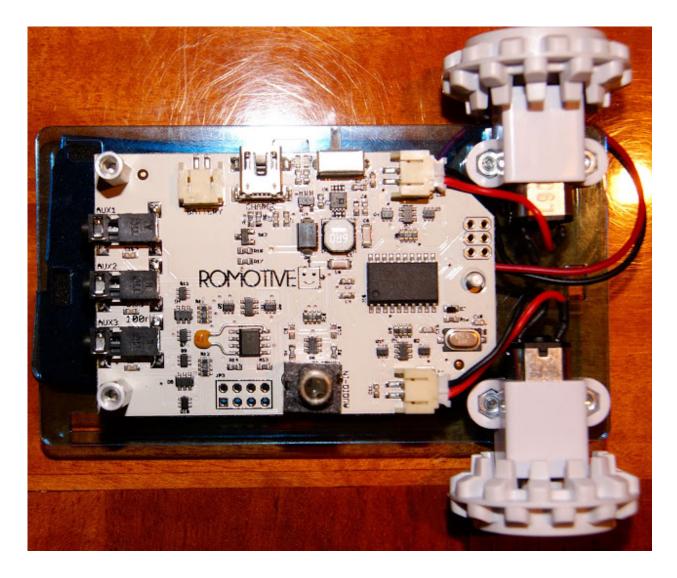
· Romotive PCB- Click for nice 8MP Macro shot.



[http://4.bp.blogspot.com/-

Ps6EMrAYRnQ/UuGGszTeUcl/AAAAAAAAAAAAh6Y/mV07lw0HqP0/s1600/raspberry-pi-server-essentials-cover.jpg] Buy Raspberry Pi Server Essentials [http://raspberrypi-pkula.blogspot.co.uk/2014/01/raspberry-pi-server-essentials-my-book.html] .

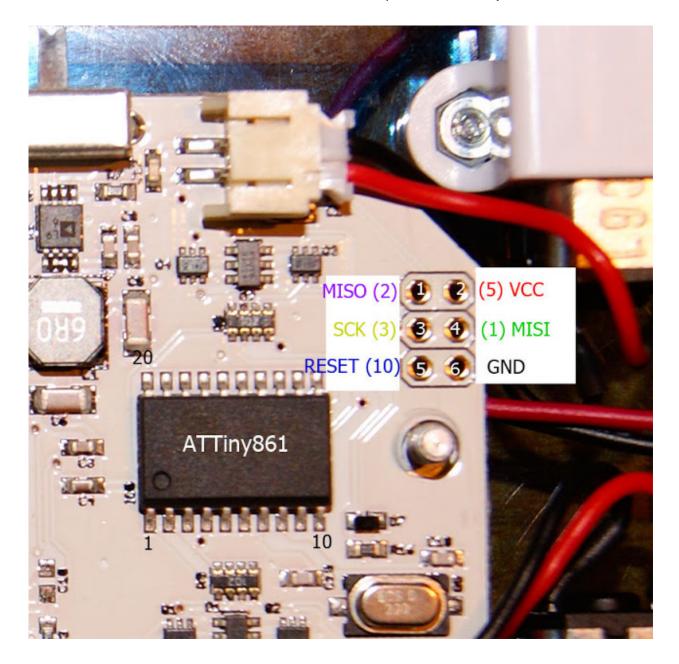
Problems with Romotive? Learn about Raspberry Pi instead and make your own robot!



[http://2.bp.blogspot.com/-9B2cR_v5t1c/T3n6iy7gWII/AAAAAAAAAAAWw/vTcm1av7yx0/s1600/romotive-pcb.jpg]

Bottom Half 8MP @300mm Macro (5.5mb) Incredible CloseUp [http://www.kula.org.uk/public/romotive/pcb/Romotive-Blown-Up.jpg]

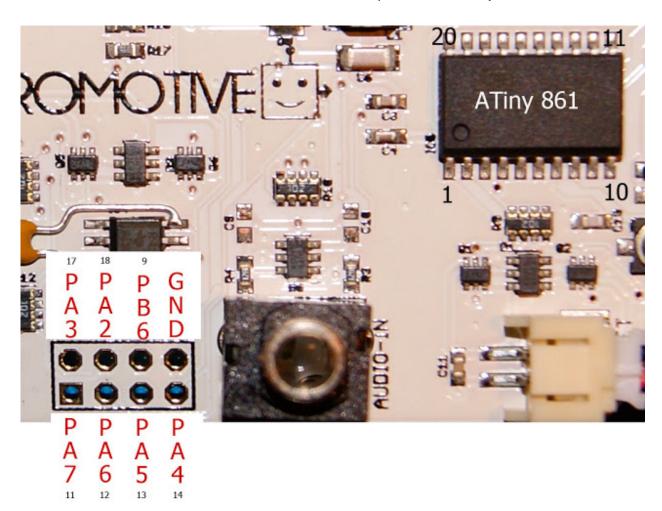
• Romotive Pin-out for Programming and Debugging



[http://4.bp.blogspot.com/-uDT9toEu_Lw/T3ocGrmSSVI/AAAAAAAAAAAAAAAGXg/UP2hM9_E7og/s1600/romotive-pinout.jpg]

Buy a programmer here, includes headers and tutorials [http://goo.gl/WE8d6]

Romotive Extra Pins



These pins make no sense to me yet. Especially that pins 20,19 the ones used for Serial Communication seem to be connected to ... nothing?

Motors

Link to website [http://robotmarketplace.com/products/0-GM11A.html] <-- I thought these were the motors but they are actually 100:1- Still good link to have



[http://4.bp.blogspot.com/-Xr0THuWVjKA/T3oPODjAwTI/AAAAAAAAAAAXY/FFg7S9wMS0M/s1600/images.jpg]

56:1 Micro Geared Motor (100-1 - the rest is the similar) Part# 0-GM11A

Typical operating voltage 1.7-5.0VDC (tested upto 9v & 12v works fine apparently)

No load speed 480 rpm

No load current 300 mA

load current 550 mA +/- 30%

Starting torque 11.1 oz-in (800 g-cm)

True gear ratio 56.8:1

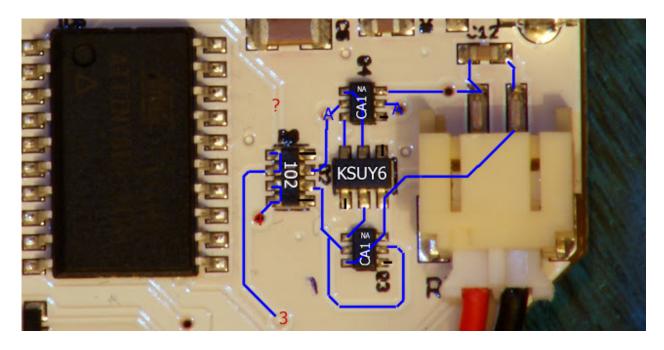
Shaft Size 3mm diameter. 7.4mm (.29") long

Size 0.47" x 0.39" x .94 (12mm x 10mm x 24mm)

Weight 7.8 grams (0.27 oz)

Motor Pin-outs

Right Motor (Pins 3,4)



Left Motor (no pic) (Pins 1,2)

Bottom Half 8MP @300mm Macro 5.5mb [http://www.kula.org.uk/public/romotive/pcb/Romotive-Blown-Up.jpg]

NB! Motor shares some of the same pins for programming the Atmel chip. I am not sure yet if the motors can stay connected while being flashed... Motors can stay connected and the Right motor will turn a bit while programming because it triggers the H-Bridge.

Audio Input

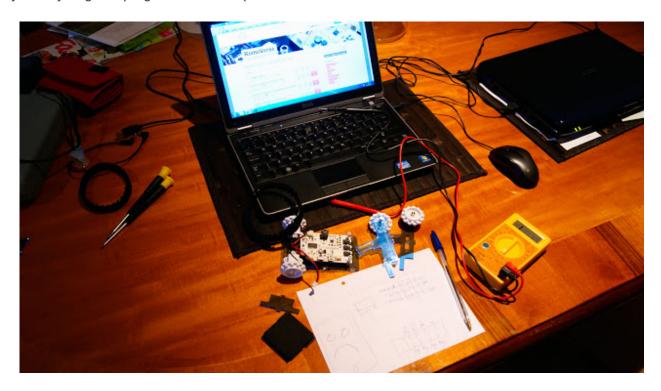
It uses an amplification chip. R4558 [http://www.kula.org.uk/public/romotive/datasheet/romotive-r4558.pdf]
I am not interested in working out how this works- I have tried tracing how it connects but I cannot really make sense of

it yet.

Other

Looks like Electrical Engineering on Stack Exchange [http://electronics.stackexchange.com/q/29283/4160] is giving a shot at reverse engineering Romo too :-)

Hey- Maybe they forgot to programme mine :-(



 $[http://3.bp.blogspot.com/-ltFNgWdJ5xg/T3oMoKBW4il/AAAAAAAAAAAQ/Yf0Wgukuj_U/s1600/romo-is-ded.jpg] \\$

Posted 4th April 2012 by Piotr Kula

