

Variational bounds in Variational Inference: how to choose them?

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CoSInES-Bayes4Health VI Masterclass – 09/11/2022

Outline

- ① Introduction
- ② The VR bound
- ③ The VR-IWAE bound
- ④ Study of the VR-IWAE bound
- ⑤ Application to VAEs
- ⑥ Study of the gradient(s) of the VR-IWAE bound
- ⑦ Conclusion

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Introduction

- We consider a **model** with joint distribution $p_\theta(x, z)$ parameterized by θ , where x is an observation and z is a latent variable valued in \mathbb{R}^d
- Posterior density of the latent variable z given the observation x

$$p_\theta(z|x) = \frac{p_\theta(x, z)}{\int p_\theta(x, z) dz}$$

- What we would like : **compute / sample** from the posterior density
- Key example : maximize the **marginal log likelihood** w.r.t. θ

$$\ell(\theta; x) := \log p_\theta(x) = \log \left(\int p_\theta(x, z) dz \right)$$

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- Problem : for many important models, we can only evaluate $p_\theta(z|x)$ **up to the marginal likelihood** $\int p_\theta(x, z) dz$

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Variational bounds

- **Variational bounds** are surrogate objective functions to the marginal log likelihood that are more amenable to optimization.
- They involve a **variational family** of probability densities \mathcal{Q}

$$\text{e.g. } \mathcal{Q} = \{z \mapsto q_\phi(z|x) : \phi \in \mathbb{R}^L\}$$

- Example : **Evidence Lower BOund (ELBO)**

$$\text{ELBO}(\theta, \phi; x) = \int q_\phi(z|x) \log(w_{\theta, \phi}(z; x)) dz \quad \text{where} \quad w_{\theta, \phi}(z; x) = \frac{p_\theta(x, z)}{q_\phi(z|x)}$$

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“Traditional Variational Inference” : θ is constant, the goal is to minimize the exclusive KL divergence \Leftrightarrow maximizing the ELBO

Optimisation w.r.t. (θ, ϕ) : **Variational Auto-Encoder (VAE)** framework

Training with the ELBO

- ➊ Unbiased Monte Carlo (MC) estimator of the ELBO

$$\begin{aligned}\text{ELBO}(\theta, \phi; x) &= \int q_\phi(z|x) \log(w_{\theta,\phi}(z;x)) dz \\ &\approx \frac{1}{N} \sum_{i=1}^N \log(w_{\theta,\phi}(z_i;x)), \quad z_i \sim q_\phi(\cdot|x), \quad i = 1 \dots N\end{aligned}$$

- ➋ Reparameterization trick $z = f(\varepsilon, \phi; x) \sim q_\phi(\cdot|x)$ where $\varepsilon \sim q$
- ➌ Reparameterized gradient of the ELBO:

$$\nabla_{\theta,\phi} \text{ELBO}(\phi; x) = \int q(\varepsilon) \nabla_{\theta,\phi} (\log w_{\theta,\phi}(f(\varepsilon, \phi; x); x)) d\varepsilon$$

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The Variational Rényi (VR) bound

Variational Rényi (VR) bound (Li and Turner, NeurIPS 2016): for all $\alpha > 0$ and $\neq 1$

$$\begin{aligned} \text{VR}^{(\alpha)}(\theta, \phi; x) &:= \frac{1}{1-\alpha} \log \left(\int q_\phi(z|x) w_{\theta, \phi}(z; x)^{1-\alpha} dz \right), \quad w_{\theta, \phi}(z; x) = \frac{p_\theta(z, x)}{q_\phi(z|x)} \\ &= \ell(\theta; x) - D^{(\alpha)}(q_\phi(\cdot|x) || p_\theta(\cdot|x)) \end{aligned}$$

where $D^{(\alpha)}(q_\phi(\cdot|x) || p_\theta(\cdot|x))$ is **Rényi's α -divergence**: for all $\alpha > 0$ and $\neq 1$

$$D^{(\alpha)}(q_\phi(\cdot|x) || p_\theta(\cdot|x)) = \frac{1}{\alpha-1} \log \left(\int q_\phi(z|x) \left(\frac{q_\phi(z|x)}{p_\theta(z|x)} \right)^{\alpha-1} dz \right)$$

- We have that $\lim_{\alpha \rightarrow 1} D^{(\alpha)}(q_\phi(\cdot|x) || p_\theta(\cdot|x)) = D^{(KL)}(q_\phi(\cdot|x) || p_\theta(\cdot|x))$

Proof Set $f(\alpha) = \int q_\phi(z|x) \left(\frac{q_\phi(z|x)}{p_\theta(z|x)} \right)^{\alpha-1} dz$

Then, $f(1) = 1$ and $f'(\alpha) = \int q_\phi(z|x) \log \left(\frac{q_\phi(z|x)}{p_\theta(z|x)} \right) \left(\frac{q_\phi(z|x)}{p_\theta(z|x)} \right)^{\alpha-1} dz$

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$$D^{(\alpha)}(q_\phi(\cdot|x) || p_\theta(\cdot|x)) = \frac{1}{\alpha-1} \log \left(\int q_\phi(z|x) \left(\frac{q_\phi(z|x)}{p_\theta(z|x)} \right)^{\alpha-1} dz \right)$$

- We have that $\lim_{\alpha \rightarrow 1} D^{(\alpha)}(q_\phi(\cdot|x) || p_\theta(\cdot|x)) = D^{(KL)}(q_\phi(\cdot|x) || p_\theta(\cdot|x))$

Proof Set $f(\alpha) = \int q_\phi(z|x) \left(\frac{q_\phi(z|x)}{p_\theta(z|x)} \right)^{\alpha-1} dz$

Then, $f(1) = 1$ and $f'(\alpha) = \int q_\phi(z|x) \log \left(\frac{q_\phi(z|x)}{p_\theta(z|x)} \right) \left(\frac{q_\phi(z|x)}{p_\theta(z|x)} \right)^{\alpha-1} dz$

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The Variational Rényi (VR) bound

Variational Rényi (VR) bound (Li and Turner, NeurIPS 2016): for all $\alpha > 0$ and $\neq 1$

$$\begin{aligned} \text{VR}^{(\alpha)}(\theta, \phi; x) &:= \frac{1}{1-\alpha} \log \left(\int q_\phi(z|x) w_{\theta, \phi}(z; x)^{1-\alpha} dz \right), \quad w_{\theta, \phi}(z; x) = \frac{p_\theta(z, x)}{q_\phi(z|x)} \\ &= \ell(\theta; x) - D^{(\alpha)}(q_\phi(\cdot|x) || p_\theta(\cdot|x)) \end{aligned}$$

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→ The VR bound generalizes the ELBO, interpolates between $\ell(\theta; x)$ and the ELBO

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Impact of α

$$\text{VR}^{(\alpha)}(\theta, \phi; x) = \ell(\theta; x) - D^{(\alpha)}(q_\phi(\cdot|x) || p_\theta(\cdot|x))$$

- Question How does the regularization term behave?

Impact of α

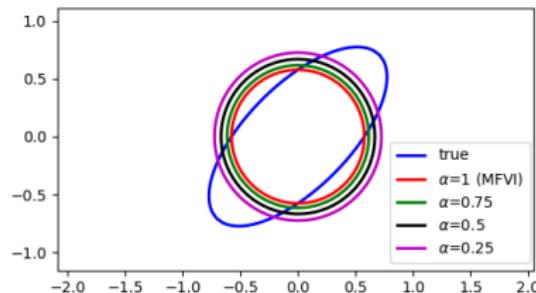
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- Example : $D^{(\alpha)}(q||p)$ with $p(z) = \mathcal{N}(z; [0, 0], [[3, -2], [-2, 3]])$ and $\mathcal{Q} = \{q : z \mapsto \mathcal{N}(z_1; \mu_1, \sigma_1^2) \mathcal{N}(z_2; \mu_2, \sigma_2^2) : \mu_1, \mu_2 \in \mathbb{R}, \sigma_1, \sigma_2 > 0\}$



Adapted from (Li and Turner, NeurIPS 2016)

Training with the VR bound (Li and Turner, NeurIPS 2016)

- ① MC estimator of the VR bound

$$\begin{aligned}\text{VR}^{(\alpha)}(\theta, \phi; x) &= \frac{1}{1-\alpha} \log \left(\int q_\phi(z|x) w_{\theta, \phi}(z; x)^{1-\alpha} dz \right) \\ &\approx \frac{1}{1-\alpha} \log \left(\frac{1}{N} \sum_{i=1}^N w_{\theta, \phi}(z_i; x)^{1-\alpha} \right), \quad z_i \sim q_\phi(\cdot|x), \quad i = 1 \dots N\end{aligned}$$

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Some important comments

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→ Sanity check : $\nabla_{\theta, \phi} \text{VR}^{(1)}(\theta, \phi; x) = \nabla_{\theta, \phi} \text{ELBO}(\theta, \phi; x)$

→ Training with $\alpha < 1$ lead to positive empirical results

→ However,

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- Li and Turner (Theorem 2, NeurIPS 2016) looked into the properties of the biased approximation of the VR bound

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An idea

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💡 Could this expectation be seen as a variational bound?

Daudel, Benton, Shi and Doucet (2022). **Alpha-divergence Variational Inference Meets Importance Weighted Auto-Encoders: Methodology and Asymptotics.**

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Outline

- ① Introduction
- ② The VR bound
- ③ The VR-IWAE bound
- ④ Study of the VR-IWAE bound
- ⑤ Application to VAEs
- ⑥ Study of the gradient(s) of the VR-IWAE bound
- ⑦ Conclusion

The VR-IWAE bound

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The VR-IWAE bound is a **lower bound** on the marginal log likelihood that

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The VR-IWAE bound

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$$\ell_N^{(\alpha)}(\theta, \phi; x) := \frac{1}{1-\alpha} \int \int \prod_{i=1}^N q_\phi(z_i|x) \log \left(\frac{1}{N} \sum_{j=1}^N w_{\theta, \phi}(z_j; x)^{1-\alpha} \right) dz_{1:N}$$

The VR-IWAE bound is a **lower bound** on the marginal log likelihood that

- ① Can be estimated using **unbiased** MC estimators
- ② Leads to the same SGD procedure as the VR bound in the reparameterized case, but this time using **unbiased** estimators

$$\begin{aligned} & \nabla_{\theta, \phi} \ell_N^{(\alpha)}(\theta, \phi; x) \\ &= \int \int \prod_{i=1}^N q(\varepsilon_i) \left(\sum_{j=1}^N \frac{w_{\theta, \phi}(z_j; x)^{1-\alpha}}{\sum_{k=1}^N w_{\theta, \phi}(z_k; x)^{1-\alpha}} \nabla_{\theta, \phi} \log w_{\theta, \phi}(f(\varepsilon_j, \phi; x); x) \right) d\varepsilon_{1:N}. \\ & \approx \sum_{j=1}^N \frac{w_{\theta, \phi}(z_j; x)^{1-\alpha}}{\sum_{k=1}^N w_{\theta, \phi}(z_k; x)^{1-\alpha}} \nabla_{\theta, \phi} \log w_{\theta, \phi}(f(\varepsilon_j, \phi; x); x), \quad \varepsilon_j \sim q, \quad j = 1 \dots N \end{aligned}$$

- 💡 The VR-IWAE bound provides **theoretical guarantees** behind various VR-bound gradient-based schemes previously proposed in the literature

Special cases of the VR-IWAE bound

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- The case $\alpha \rightarrow 1$

$$\lim_{\alpha \rightarrow 1} \ell_N^{(\alpha)}(\theta, \phi; x) = \text{ELBO}(\theta, \phi; x)$$

- The case $\alpha = 0$

$$\ell_N^{(0)}(\theta, \phi; x) = \int \int \prod_{i=1}^N q_\phi(z_i|x) \log \left(\frac{1}{N} \sum_{j=1}^N w_{\theta, \phi}(z_j; x) \right) dz_{1:N}$$

The VR-IWAE bound recovers the **Importance Weighted Auto-encoder (IWAE) bound** (Burda et al., ICLR 2016) when $\alpha = 0$

→ Extension of the ELBO also leading to positive empirical results

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 The VR-IWAE bound **interpolates** between the IWAE bound and the ELBO

It is the **theoretically-sound** extension of the IWAE bound originating from the VR bound methodology

At this stage

- The VR-IWAE bound provides **theoretical guarantees** behind various VR-bound gradient-based schemes previously proposed in the literature
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Questions?

- Question Can we understand the behavior of the VR-IWAE bound as a function of $\alpha \in [0, 1)$ better?

Outline

- ① Introduction
- ② The VR bound
- ③ The VR-IWAE bound
- ④ Study of the VR-IWAE bound
- ⑤ Application to VAEs
- ⑥ Study of the gradient(s) of the VR-IWAE bound
- ⑦ Conclusion

Quantity of interest

Variational gap

For all $\alpha \in [0, 1]$,

$$\begin{aligned}\Delta_N^{(\alpha)}(\theta, \phi; x) &:= \ell_N^{(\alpha)}(\theta, \phi; x) - \ell(\theta; x) \\ &= \frac{1}{1-\alpha} \int \int \prod_{i=1}^N q_\phi(z_i|x) \log \left(\frac{1}{N} \sum_{j=1}^N \bar{w}_{\theta, \phi}(z_j; x)^{1-\alpha} \right) dz_{1:N}\end{aligned}$$

where $\bar{w}_{\theta, \phi}(z_1; x), \dots, \bar{w}_{\theta, \phi}(z_N; x)$ are the **relative weights** : for all $z \in \mathbb{R}^d$,

$$\bar{w}_{\theta, \phi}(z; x) := \frac{w_{\theta, \phi}(z; x)}{\mathbb{E}_{Z \sim q_\phi}(w_{\theta, \phi}(Z; x))} = \frac{w_{\theta, \phi}(z; x)}{p_\theta(x)} = \frac{p_\theta(z|x)}{q_\phi(z|x)},$$

NB : we will drop the dependency in x in $\bar{w}_{\theta, \phi}(z; x)$ for convenience

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Part I

N goes to infinity and d is fixed in the variational gap

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→ Maddison et al. (NeurIPS 2017) followed by Domke and Sheldon (NeurIPS 2018) looked into the variational gap for the IWAE bound ($\alpha = 0$)

Informally, Domke and Sheldon (Theorem 3, NeurIPS 2018) states that

$$\Delta_N^{(0)}(\theta, \phi; x) = -\frac{\gamma_0^2}{2N} + o\left(\frac{1}{N}\right)$$

where γ_0 is the variance of the relative weights, i.e.

$$\gamma_0^2 := \mathbb{V}_{Z \sim q_\phi(\cdot|x)}(\bar{w}_{\theta,\phi}(Z))$$

→ Comments :

- N is very beneficial to reduce $\Delta_N^{(0)}(\theta, \phi; x)$ (goes to 0 at a fast $1/N$ rate)
- Question What about $\Delta_N^{(\alpha)}(\theta, \phi; x)$, $\alpha \in [0, 1]$?

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Main result when $N \rightarrow \infty$ and d is fixed

Theorem 1

Let $\alpha \in [0, 1)$, denote $\bar{w}_{\theta, \phi}^{(\alpha)}(z) = w_{\theta, \phi}(z)^{1-\alpha}/\mathbb{E}_{Z \sim q_\phi(\cdot|x)}(w_{\theta, \phi}(Z)^{1-\alpha})$ for all $z \in \mathbb{R}^d$ and $\gamma_\alpha^2 = (1 - \alpha)^{-1}\mathbb{V}_{Z \sim q_\phi(\cdot|x)}(\bar{w}_{\theta, \phi}^{(\alpha)}(Z))$. Then, under “*some conditions*”, we have:

$$\Delta_N^{(\alpha)}(\theta, \phi; x) = \text{VR}^{(\alpha)}(\theta, \phi; x) - \ell(\theta; x) - \frac{\gamma_\alpha^2}{2N} + o\left(\frac{1}{N}\right).$$

→ Two main terms :

- ① A term going to zero at a fast $1/N$ rate that depends on γ_α^2
- ② An error term $\text{VR}^{(\alpha)}(\theta, \phi; x) - \ell(\theta; x)$ [decreases away from 0 as α increases]

The hyperparameter α balances between these two terms meaning that a proper tuning of α may be beneficial in practice

→ “*some conditions*”

- generalize the conditions from Domke and Sheldon (2018)
- do not get more restrictive as α increases, motivating $\alpha \in (0, 1)$
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- ② An error term $\text{VR}^{(\alpha)}(\theta, \phi; x) - \ell(\theta; x)$ [decreases away from 0 as α increases]

The hyperparameter α balances between these two terms meaning that a **proper tuning of α may be beneficial** in practice

→ “*some conditions*”

- **generalize** the conditions from Domke and Sheldon (2018)
- **do not** get more restrictive as α increases, motivating $\alpha \in (0, 1)$
- one of them **controls** γ_α^2

 To the best of our knowledge, **first result** shedding light on how α may play a

Example

Example 1 : Log-normal distribution of the relative weights

Let $\sigma > 0$, S_1, \dots, S_N be **i.i.d. normal r.v** and assume that the distribution of the relative weights $\bar{w}_{\theta,\phi}(z_1), \dots, \bar{w}_{\theta,\phi}(z_N)$ is log-normal of the form

$$\log \bar{w}_{\theta,\phi}(z_i) = -\frac{\sigma^2 d}{2} - \sigma \sqrt{d} S_i, \quad i = 1 \dots N.$$

Then, for all $\alpha \in [0, 1)$,

$$\Delta_N^{(\alpha)}(\theta, \phi; x) = \text{VR}^{(\alpha)}(\theta, \phi; x) - \ell(\theta; x) - \frac{\gamma_\alpha^2}{2N} + o\left(\frac{1}{N}\right)$$

with

$$\text{VR}^{(\alpha)}(\theta, \phi; x) - \ell(\theta; x) = -\frac{\alpha \sigma^2 d}{2} \quad \text{and} \quad \gamma_\alpha^2 = \frac{\exp[(1-\alpha)^2 \sigma^2 d] - 1}{1-\alpha}.$$

→ Sanity check : $\mathbb{E}(\bar{w}_{\theta,\phi}) = \mathbb{E}(\exp(-\frac{\sigma^2 d}{2} - \sigma \sqrt{d} S_1)) = 1$

→ **Gaussian example** Set $p_\theta(z|x) = \mathcal{N}(z; \theta, I_d)$ and $q_\phi(z|x) = \mathcal{N}(z; \phi, I_d)$, with $\theta = 0 \cdot u_d$ and $\phi = u_d$, where u_d is the d -dimensional vector whose coordinates are all equal to 1. Then $\sigma = 1$.

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Gaussian example and Theorem 1 empirically

- $\Delta_N^{(\alpha)}(\theta, \phi; x)$ is estimated using the unbiased MC estimator

$$\frac{1}{1-\alpha} \log \left(\frac{1}{N} \sum_{j=1}^N \bar{w}_{\theta, \phi}(z_j; x)^{1-\alpha} \right), \quad z_j \sim q_\phi(\cdot | x), \quad j = 1 \dots N$$

- Theorem 1 is represented through functions of the form:

$$c \mapsto -\frac{\alpha d}{2} - \frac{\exp[(1-\alpha)^2 d] - 1}{2(1-\alpha)N} + \frac{c}{N}$$

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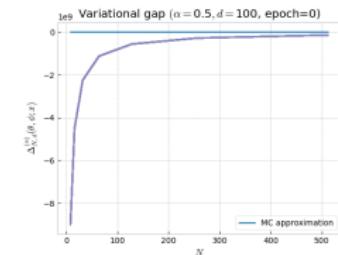
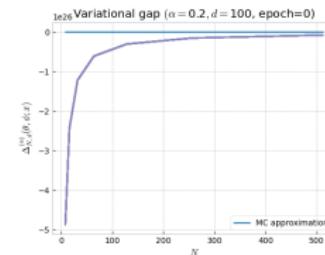
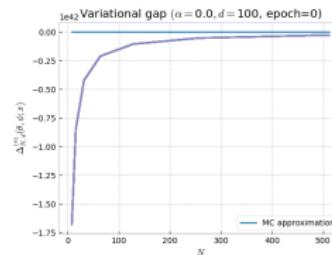
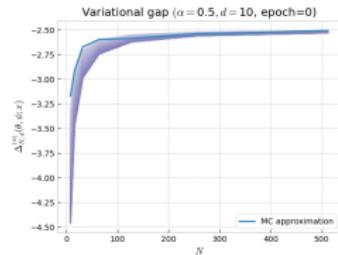
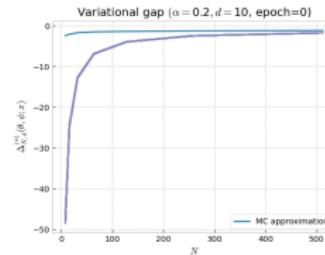
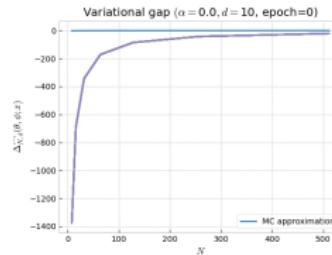
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Part II

N and d go to infinity in the variational gap

$N, d \rightarrow \infty$ in the variational gap

→ Key intuition : it is typically possible to approximate the distribution of the relative weights by a **log-normal distribution** of the form

$$\log \bar{w}_{\theta, \phi}(z_i) = -\frac{\sigma^2 d}{2} - \sigma \sqrt{d} S_i, \quad S_i \sim \mathcal{N}(0, 1), \quad i = 1 \dots N.$$

→ Theoretical study in two steps :

- ① Log-normal case : $d, N \rightarrow \infty$ with $\frac{\log N}{d} \rightarrow 0$
- ② Approximate log-normal case : $d, N \rightarrow \infty$ with $\frac{\log N}{d^{1/3}} \rightarrow 0$

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Part II.1

Log-normal case

Main result in the log-normal case

Theorem 2

Let S_1, \dots, S_N be **i.i.d. normal random variables**. Further assume that

$$\log \bar{w}_{\theta, \phi}(z_i) = -\frac{\sigma^2 d}{2} - \sigma \sqrt{d} S_i, \quad i = 1 \dots N.$$

with $\sigma > 0$. Then, for all $\alpha \in [0, 1)$, we have

$$\lim_{\substack{N, d \rightarrow \infty \\ \log N/d \rightarrow 0}} \Delta_{N, d}^{(\alpha)}(\theta, \phi; x) + \frac{d\sigma^2}{2} \left(1 - 2\sqrt{\frac{2 \log N}{d\sigma^2}} + \frac{1}{1-\alpha} \frac{2 \log N}{d\sigma^2} + O\left(\frac{\log \log N}{\sqrt{d \log N}}\right) \right) = 0.$$

→ Informally

$$\Delta_{N, d}^{(\alpha)}(\theta, \phi; x) \approx -\frac{d\sigma^2}{2} \left(1 - 2\sqrt{\frac{2 \log N}{d\sigma^2}} + \frac{1}{1-\alpha} \frac{2 \log N}{d\sigma^2} + O\left(\frac{\log \log N}{\sqrt{d \log N}}\right) \right)$$

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→ Comparison with Theorem 1

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→ **Weight collapse** phenomenon : for all $\alpha \in [0, 1)$,

$$\Delta_{N, d}^{(\alpha)}(\theta, \phi; x) \approx \text{ELBO}(\theta, \phi; x) - \ell(\theta; x), \quad \text{as } N, d \rightarrow \infty \text{ with } \frac{\log N}{d} \rightarrow 0.$$

Gaussian example revisited

Gaussian example

Set $p_\theta(z|x) = \mathcal{N}(z; \theta, \mathbf{I}_d)$ and $q_\phi(z|x) = \mathcal{N}(z; \phi, \mathbf{I}_d)$, with $\theta = 0 \cdot \mathbf{u}_d$ and $\phi = \mathbf{u}_d$, where \mathbf{u}_d is the d -dimensional vector whose coordinates are all equal to 1. Then

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$$\lim_{\substack{N,d \rightarrow \infty \\ \log N/d \rightarrow 0}} \Delta_{N,d}^{(\alpha)}(\theta, \phi; x) + \frac{d\sigma^2}{2} \left(1 - 2\sqrt{\frac{2 \log N}{d\sigma^2}} + \frac{1}{1-\alpha} \frac{2 \log N}{d\sigma^2} + O\left(\frac{\log \log N}{\sqrt{d \log N}}\right) \right) = 0.$$

Gaussian example revisited

Gaussian example

Set $p_\theta(z|x) = \mathcal{N}(z; \theta, \mathbf{I}_d)$ and $q_\phi(z|x) = \mathcal{N}(z; \phi, \mathbf{I}_d)$, with $\theta = 0 \cdot \mathbf{u}_d$ and $\phi = \mathbf{u}_d$, where \mathbf{u}_d is the d -dimensional vector whose coordinates are all equal to 1. Then

$$\log \bar{w}_{\theta,\phi}(z_i) = -\frac{\sigma^2 d}{2} - \sigma \sqrt{d} S_i, \quad S_i \sim \mathcal{N}(0, 1), \quad i = 1 \dots N$$

with $\sigma = 1$.

- Theorem 1

$$\Delta_{N,d}^{(\alpha)}(\theta, \phi; x) = -\alpha \cdot \frac{\sigma^2 d}{2} - \frac{\exp[(1-\alpha)^2 \sigma^2 d] - 1}{2(1-\alpha)N} + o\left(\frac{1}{N}\right)$$

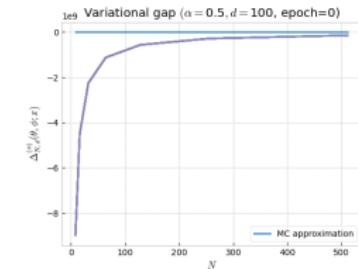
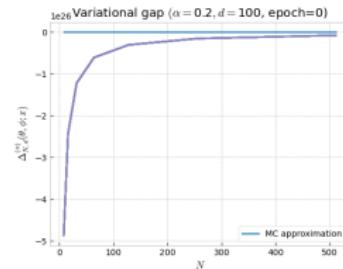
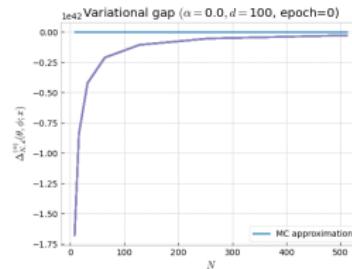
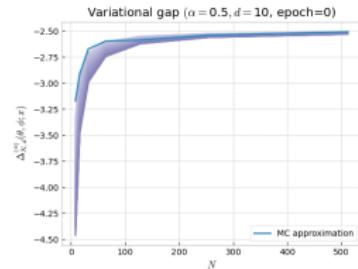
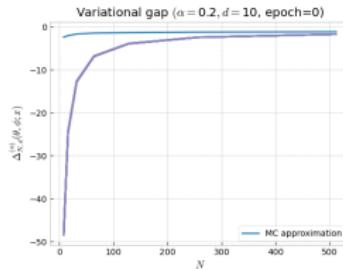
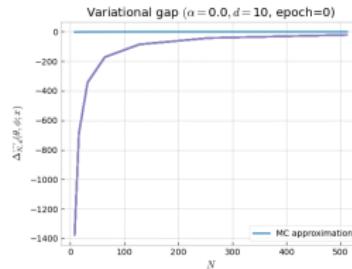
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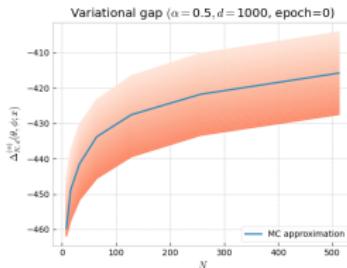
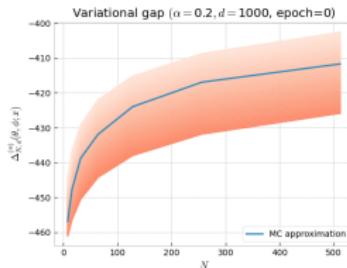
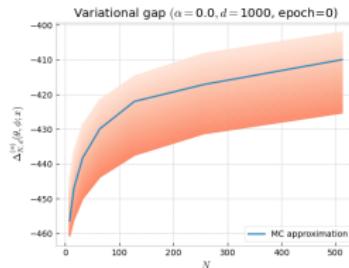
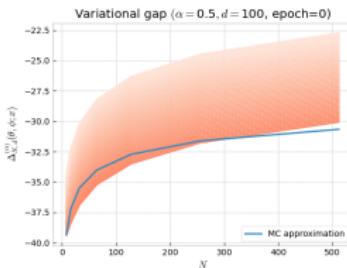
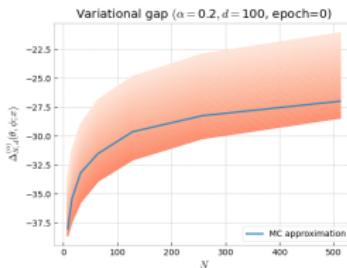
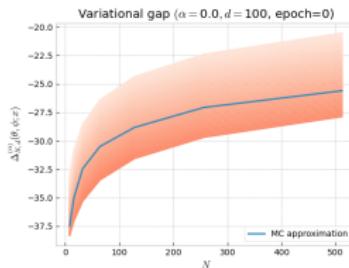
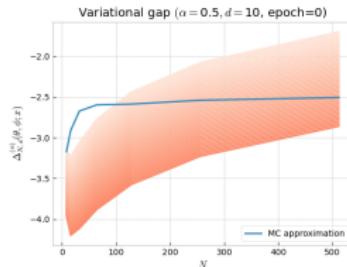
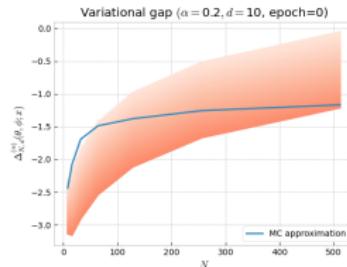
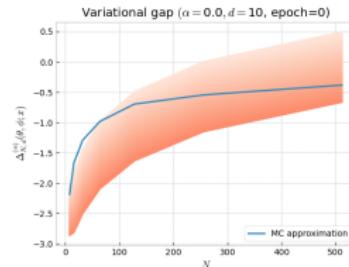


Weight collapse phenomenon might occur even for simple examples!

Gaussian example and Theorem 1 empirically



Gaussian example and Theorem 2 empirically



Part II.2

Approximate log-normal case

Assumptions

Let S_1, \dots, S_N be such that :

$$S_i = \frac{1}{\sigma\sqrt{d}} \sum_{j=1}^d \xi_{i,j}, \quad i = 1 \dots N$$

We will work under (A1) :

(A1) For all $i = 1 \dots N$,

- ① $\xi_{i,1}, \dots, \xi_{i,d}$ are i.i.d. random variables which are absolutely continuous with respect to the Lebesgue measure and satisfy $\mathbb{E}(\xi_{i,1}) = 0$ and $\mathbb{V}(\xi_{i,1}) = \sigma^2 < \infty$.
- ② There exists $K > 0$ such that:

$$|\mathbb{E}(\xi_{i,1}^k)| \leq k!K^{k-2}\sigma^2, \quad k \geq 3.$$

Approximate log-normal weights

$$\begin{aligned} \log \bar{w}_{\theta,\phi}(z_i) &= -\log \mathbb{E}(\exp(-\sigma\sqrt{d}S_1)) - \sigma\sqrt{d}S_i, \quad i = 1 \dots N \\ &= -da - \sigma\sqrt{d}S_i, \quad i = 1 \dots N \end{aligned}$$

with $a := \log \mathbb{E}(\exp(-\xi_{1,1}))$

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Main result in the approximate log-normal case

Theorem 3

Assume (A1) and that

$$\log \bar{w}_{\theta, \phi}(z_i) = -da - \sigma \sqrt{d} S_i, \quad i = 1 \dots N.$$

Then, $a > 0$ and for all $\alpha \in [0, 1)$, we have

$$\lim_{\substack{N, d \rightarrow \infty \\ \log N / d^{1/3} \rightarrow 0}} \Delta_{N, d}^{(\alpha)}(\theta, \phi; x) + da \left(1 - \frac{\sigma}{a} \sqrt{\frac{2 \log N}{d}} + O\left(\frac{\log \log N}{\sqrt{d \log N}}\right) \right) = 0.$$

→ Weight collapse phenomenon : for all $\alpha \in [0, 1)$,

$$\Delta_{N, d}^{(\alpha)}(\theta, \phi; x) \approx \text{ELBO}(\theta, \phi; x) - \ell(\theta; x), \quad \text{as } N, d \rightarrow \infty \text{ with } \frac{\log N}{d^{1/3}} \rightarrow 0.$$

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Linear Gaussian example

Linear Gaussian example (Rainforth et al., ICML 2018)

Set $p_\theta(z) = \mathcal{N}(z; \theta, \mathbf{I}_d)$, $p_\theta(x|z) = \mathcal{N}(x; z, \mathbf{I}_d)$ with $\theta \in \mathbb{R}^d$, and $q_\phi(z|x) = \mathcal{N}(z; Ax + b, 2/3 \mathbf{I}_d)$ with $A = \text{diag}(\tilde{a})$ and $\phi = (\tilde{a}, b) \in \mathbb{R}^d \times \mathbb{R}^d$. Then, we can write

$$\log \bar{w}_{\theta, \phi}(z_i) = -da - \sigma \sqrt{d} S_i, \quad i = 1 \dots N.$$

with $\sigma^2 = \frac{1}{18} + \frac{8}{3}\lambda^2$ and $a = \lambda^2 + \frac{1}{6} + \frac{1}{2}\log(3/4)$, where $\lambda = \frac{\|\frac{\theta+x}{2} - Ax - b\|}{\sqrt{d}}$

→ (A1) holds if we set $(\theta, \phi) = (\theta^*, \phi^*)$!

[$\theta^* = T^{-1} \sum_{t=1}^T x_t$, $\phi^* = (a^*, b^*)$ with $a^* = \frac{1}{2}u_d$, $b^* = \frac{\theta^*}{2}$]

- Theorem 1

$$\Delta_{N,d}^{(\alpha)}(\theta, \phi; x) = \frac{d}{2} \left[\log \left(\frac{4}{3} \right) + \frac{1}{1-\alpha} \log \left(\frac{3}{4-\alpha} \right) \right] - \frac{(4-\alpha)^d (15-6\alpha)^{-\frac{d}{2}} - 1}{2(1-\alpha)N} + o\left(\frac{1}{N}\right)$$

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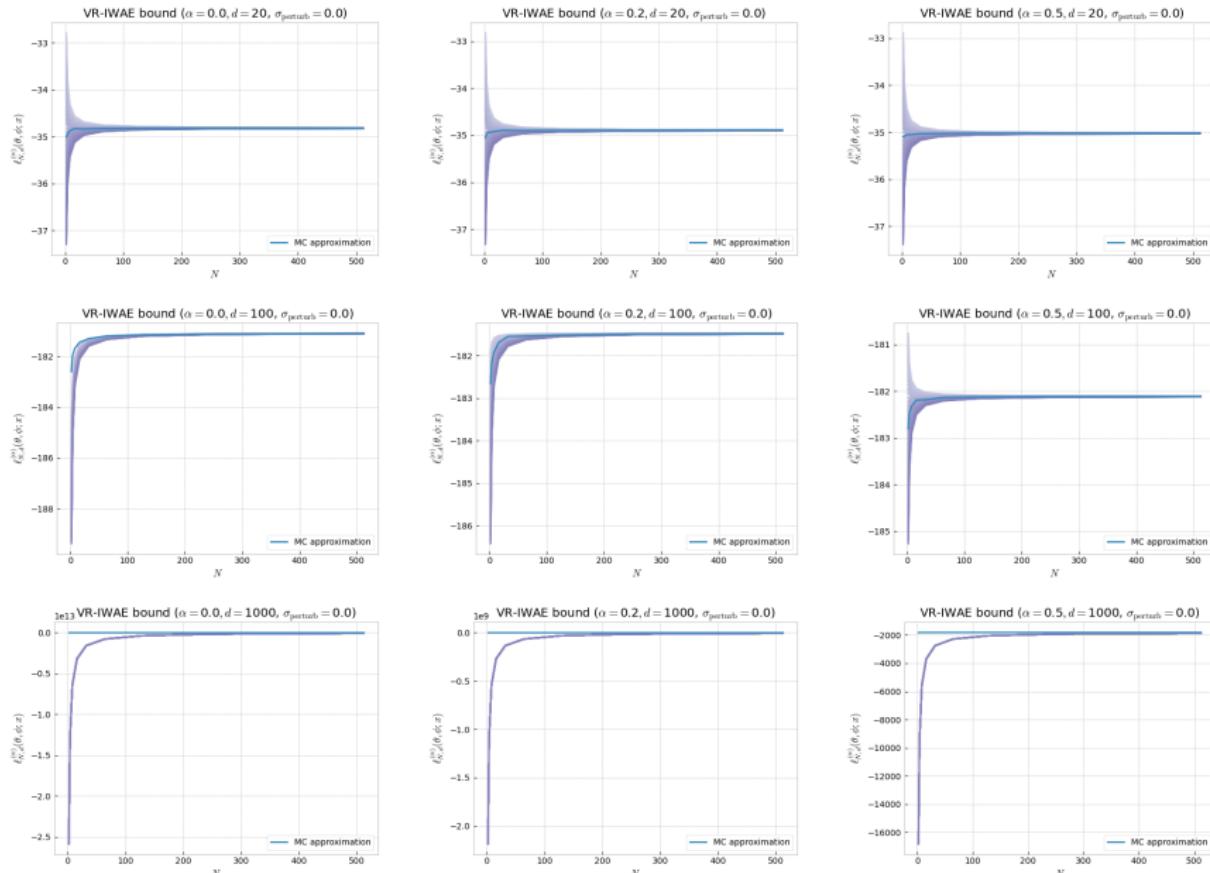
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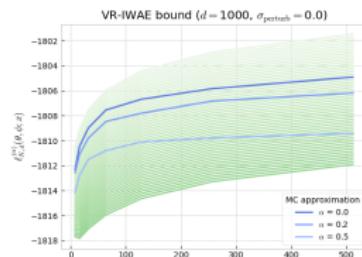
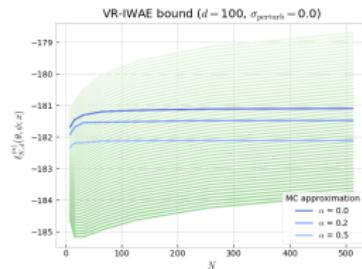
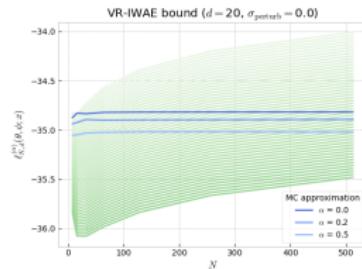


The choice of the variational approximation $q_\phi(\cdot|x)$ matters a lot!

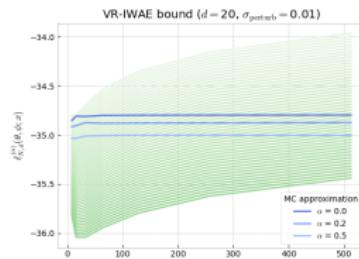
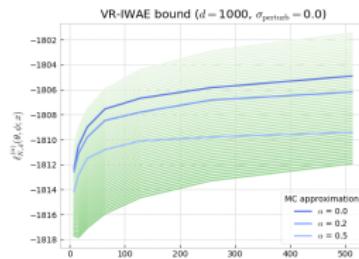
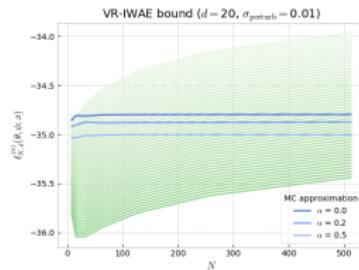
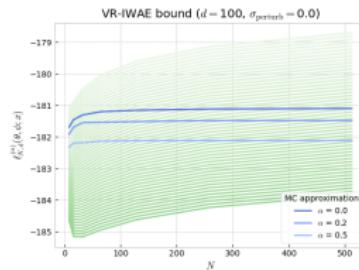
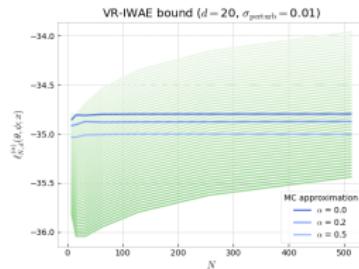
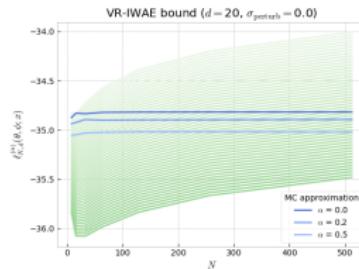
Linear Gaussian example and Theorem 1 empirically



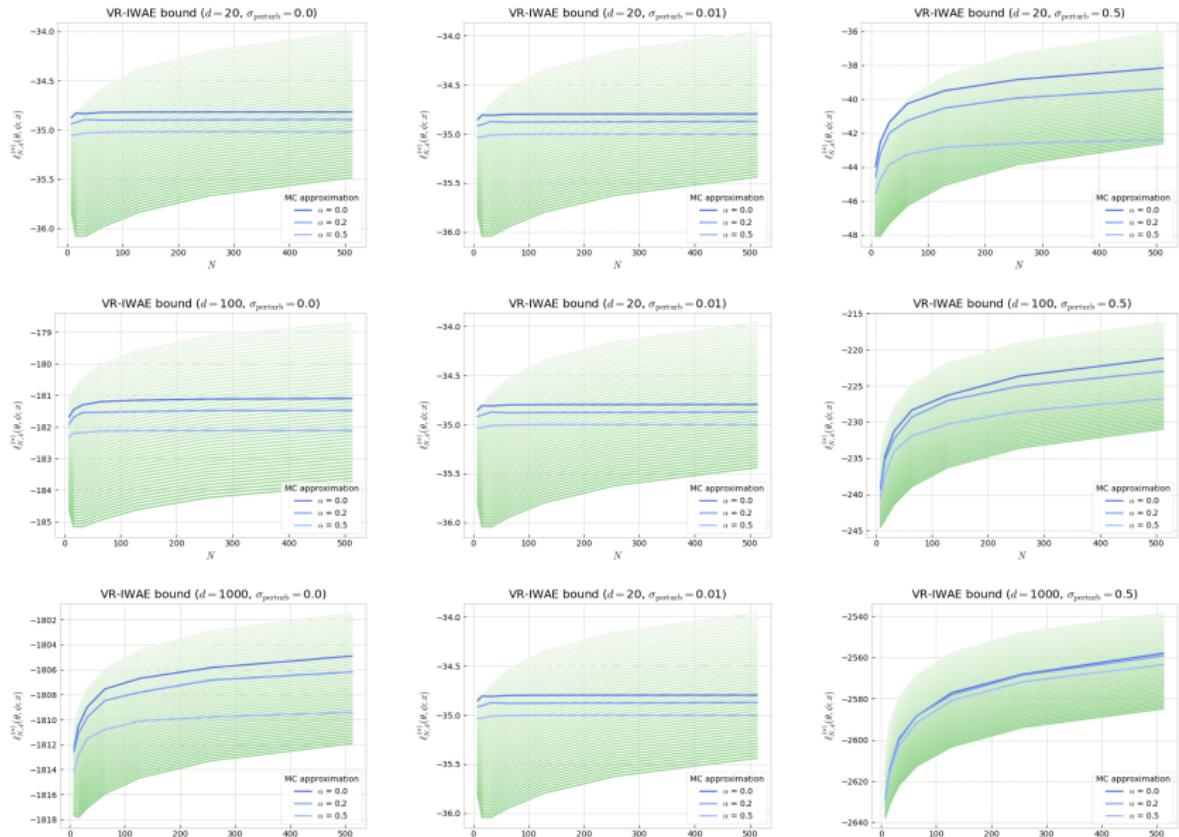
Linear Gaussian example and Theorem 3 empirically



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At this stage

Quantity of interest : **variational gap**

$$\Delta_N^{(\alpha)}(\theta, \phi; x) := \ell_N^{(\alpha)}(\theta, \phi; x) - \ell(\theta; x), \quad \alpha \in [0, 1)$$

→ Two complementary studies

① When $N \rightarrow \infty$ and the dimension of the latent space d is fixed

② When $N, d \rightarrow \infty$ with (i) $\frac{\log N}{d} \rightarrow 0$ or (ii) $\frac{\log N}{d^{1/3}} \rightarrow 0$

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From theory to practice

- $\ell_N^{(\alpha)}(\theta, \phi; x)$ is estimated using the unbiased MC estimator

$$\frac{1}{1-\alpha} \log \left(\frac{1}{N} \sum_{j=1}^N w_{\theta, \phi}(z_j)^{1-\alpha} \right), \quad z_j \sim q_\phi(\cdot | x), \quad j = 1 \dots N$$

- Theorem 1

$$\Delta_N^{(\alpha)}(\theta, \phi; x) = \text{VR}^{(\alpha)}(\theta, \phi; x) - \ell(\theta; x) - \frac{\gamma_\alpha^2}{2N} + o\left(\frac{1}{N}\right)$$

- Theorem 3 Assuming that the weights are approximately log-normal

$$\lim_{\substack{N, d \rightarrow \infty \\ \log N / d^{1/3} \rightarrow 0}} \Delta_{N,d}^{(\alpha)}(\theta, \phi; x) + da \left(1 - \frac{\sigma}{a} \sqrt{\frac{2 \log N}{d}} + O\left(\frac{\log \log N}{\sqrt{d \log N}}\right) \right) = 0$$

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becomes

$$\lim_{\substack{N, d \rightarrow \infty \\ \log N / d^{1/3} \rightarrow 0}} \ell_{N,d}^{(\alpha)}(\theta, \phi; x) - \left[\text{ELBO}(\theta, \phi; x) + \sqrt{d} \sigma \sqrt{2 \log N} + O\left(\frac{\sqrt{d} \log \log N}{\sqrt{\log N}}\right) \right] = 0$$

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VAE on MNIST dataset

- More details about this framework in the afternoon lecture!
- Here, we only want to look at
 - ➊ the behavior of the relative weights
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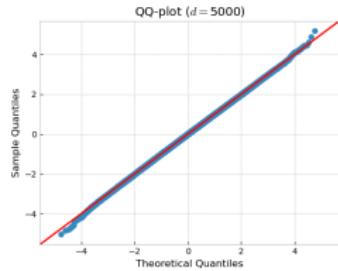
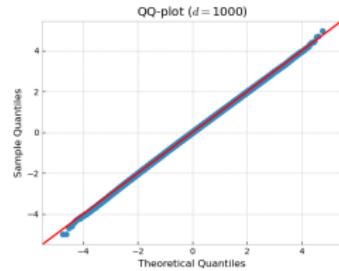
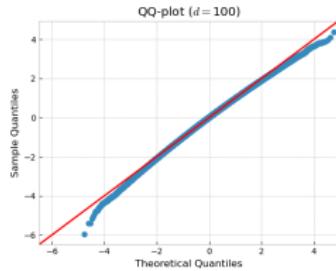
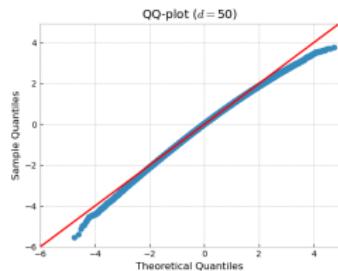
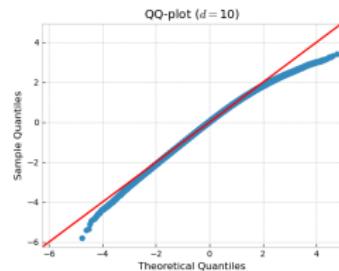
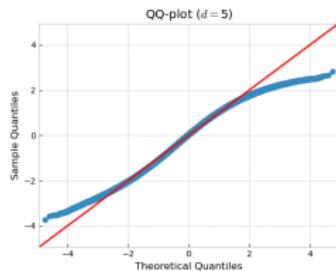
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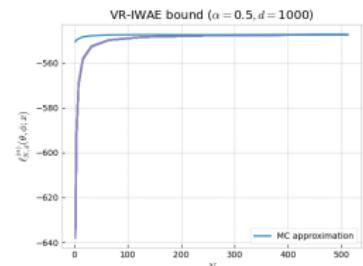
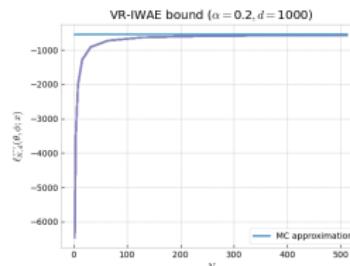
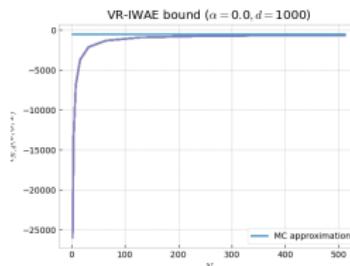
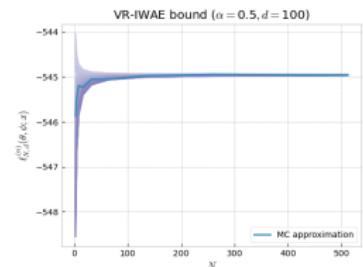
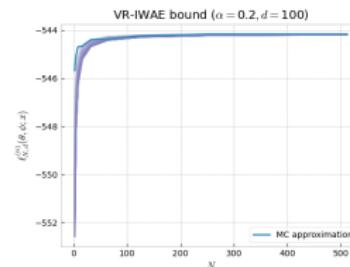
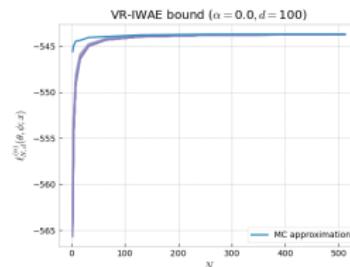
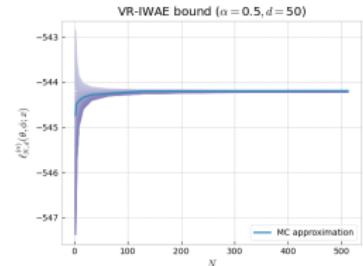
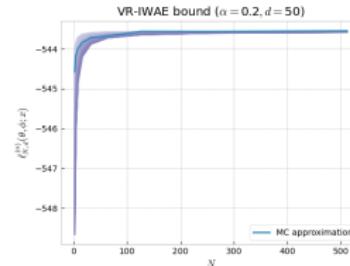
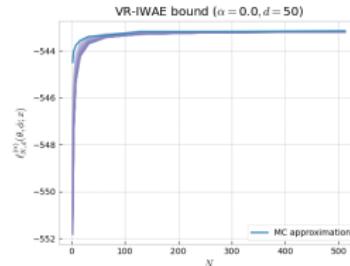
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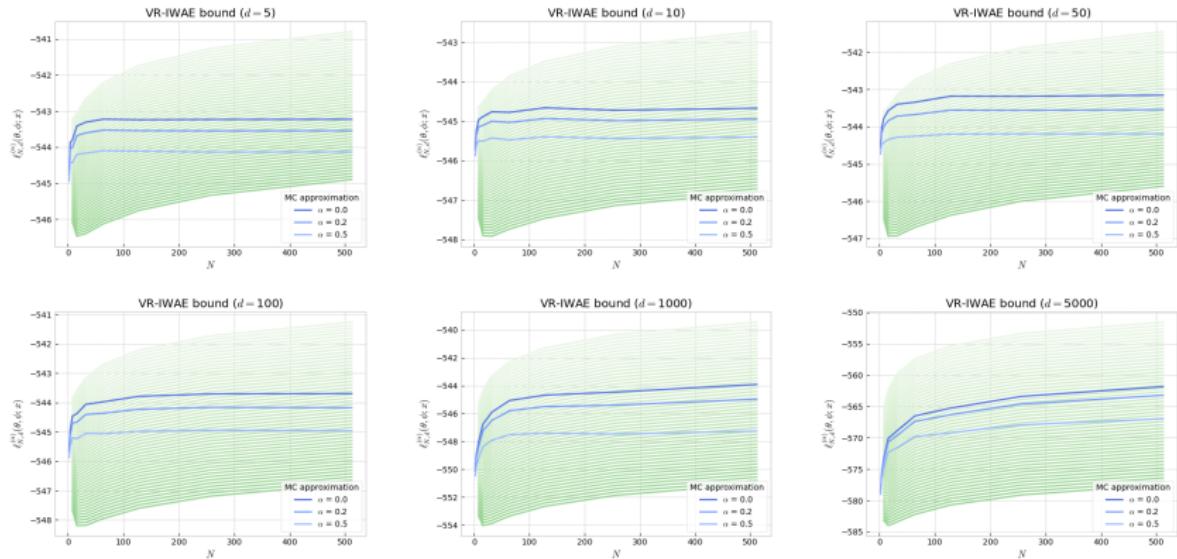
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VAE on MNIST dataset and Theorem 1



VAE on MNIST dataset and Theorem 3



At this stage

→ Two complementary analyses of the VR-IWAE bound that we verified on a real-world scenario

- ① Theorem 1 is tailored for low to medium dimensions settings
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Question Can we say something about the gradient of the VR-IWAE bound as a function of $\alpha \in [0, 1)$?

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Study of the gradient(s) of the VR-IWAE bound

Quantities of interest

- MC estimates of the reparameterized gradients of the VR-IWAE bound

$$\delta_N^{(\alpha)}(\phi_\ell) = \frac{\partial}{\partial \phi_\ell} \log \left(\frac{1}{N} \sum_{j=1}^N w_{\theta, \phi}(f(\varepsilon_j, \phi; x))^{1-\alpha} \right), \quad \ell = 1 \dots L$$
$$\delta_N^{(\alpha)}(\theta_{\ell'}) = \frac{\partial}{\partial \theta_{\ell'}} \log \left(\frac{1}{N} \sum_{j=1}^N w_{\theta, \phi}(f(\varepsilon_j, \phi; x))^{1-\alpha} \right), \quad \ell' = 1 \dots L'$$

with $\phi = (\phi_1, \dots, \phi_L)$, $\theta = (\theta_1, \dots, \theta_{L'})$

- Signal-to-Noise Ratio

Letting $X = (X_1, \dots, X_L)$ be a random vector of dimension L ,

$$\text{SNR}[X] = \left(\frac{|\mathbb{E}(X_1)|}{\sqrt{\mathbb{V}(X_1)}}, \dots, \frac{|\mathbb{E}(X_L)|}{\sqrt{\mathbb{V}(X_L)}} \right).$$

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SNR analysis in the reparameterized case

Theorem 4

Let $\alpha \in [0, 1)$. Define $\tilde{w}_j = w_{\theta, \phi}(f(\varepsilon_j, \phi; x))$ and $\hat{Z}_{N, \alpha} = N^{-1} \sum_{j=1}^N \tilde{w}_j^{1-\alpha}$. Assume that the eighth moments of $\tilde{w}_1^{1-\alpha}$, $\partial \tilde{w}_1^{1-\alpha} / \partial \phi_\ell$ and $\partial \tilde{w}_1^{1-\alpha} / \partial \theta_{\ell'}$ are finite. Furthermore, assume that there exists some $N \in \mathbb{N}^*$ for which $\mathbb{E}((1/\hat{Z}_{N, \alpha})^4) < \infty$. Lastly, assume that

$$\begin{aligned}\partial \mathbb{V}(\tilde{w}_1^{1-\alpha}) / \partial \phi_\ell &> 0, & \text{if } \alpha = 0 \\ \partial \mathbb{E}(\tilde{w}_1^{1-\alpha}) / \partial \phi_\ell &\neq 0, & \text{if } \alpha \in (0, 1)\end{aligned}$$

and that $\partial \mathbb{E}(\tilde{w}_1^{1-\alpha}) / \partial \theta_{\ell'} \neq 0$. Then,

$$\begin{aligned}\text{SNR}[\delta_N^{(\alpha)}(\phi_\ell)] &= \begin{cases} \Theta(\sqrt{1/N}) & \text{if } \alpha = 0, \\ \Theta(\sqrt{N}) & \text{if } \alpha \in (0, 1) \end{cases} \\ \text{SNR}[\delta_N^{(\alpha)}(\theta_{\ell'})] &= \Theta(\sqrt{N}).\end{aligned}$$

- The IWAE case was already known from Rainforth et al. (ICML 2018)
- Motivates $\alpha \in (0, 1)$

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Doubly-reparameterized gradients

→ Introduced in **Tucker (ICLR 2019)** for the IWAE bound

Theorem 5

For all $\alpha \in [0, 1]$,

$$\frac{\partial}{\partial \phi} \ell_N^{(\alpha)}(\theta, \phi; x) = \int \int \prod_{i=1}^N q(\varepsilon_i) \left(\sum_{j=1}^N h_j(\alpha) \frac{\partial}{\partial \phi} \log w_{\theta, \phi'}(f(\varepsilon_j, \phi; x))|_{\phi'=\phi} \right) d\varepsilon_{1:N}$$

with $z_j = f(\varepsilon_j, \phi; x)$ for all $j = 1 \dots J$ and

$$h_j(\alpha) = \alpha \frac{w_{\theta, \phi}(z_j)^{1-\alpha}}{\sum_{k=1}^N w_{\theta, \phi}(z_k)^{1-\alpha}} + (1 - \alpha) \left(\frac{w_{\theta, \phi}(z_j)^{1-\alpha}}{\sum_{k=1}^N w_{\theta, \phi}(z_k)^{1-\alpha}} \right)^2.$$

An unbiased estimator of $\partial \ell_N^{(\alpha)}(\theta, \phi; x) / \partial \phi$ is then given by

$$\sum_{j=1}^N h_j(\alpha) \frac{\partial}{\partial \phi} \log w_{\theta, \phi'}(f(\varepsilon_j, \phi))|_{\phi'=\phi}$$

where $\varepsilon_1, \dots, \varepsilon_N$ are i.i.d. samples generated from q and $z_j = f(\varepsilon_j, \phi; x)$ for all $j = 1 \dots J$.

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At this stage

- Setting $\alpha > 0$ instead of $\alpha = 0$ (IWAE bound) can **improve on the SNR** for the reparameterized estimated gradients of the VR-IWAE bound

$$\text{SNR}_{\phi_\ell} = \begin{cases} \Theta(\sqrt{1/N}) & \text{if } \alpha = 0 \text{ (Rainforth et al., ICML 2018),} \\ \Theta(\sqrt{N}) & \text{if } \alpha \in (0, 1) \end{cases}$$
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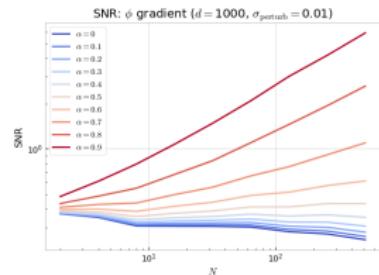
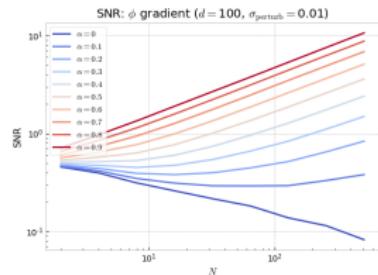
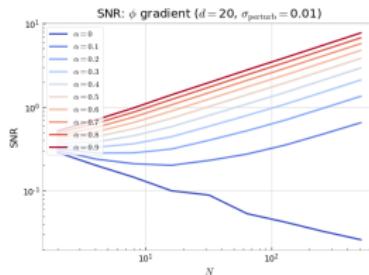
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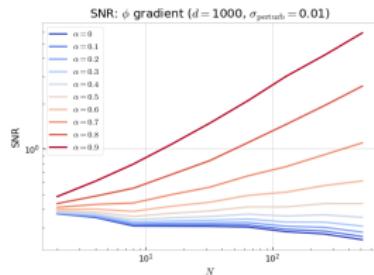
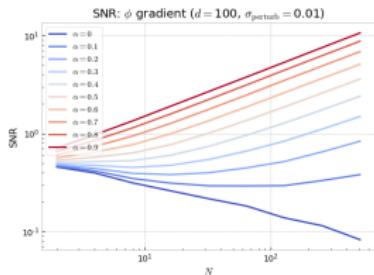
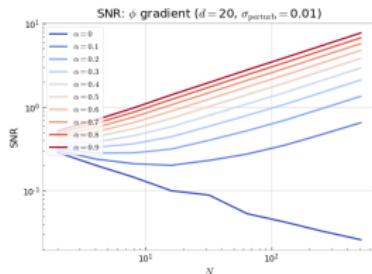
SNR analysis for the Linear Gaussian example : ϕ

Reparameterized

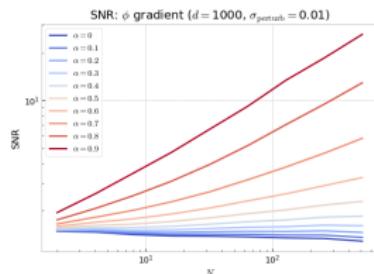
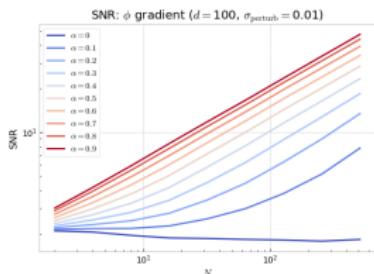
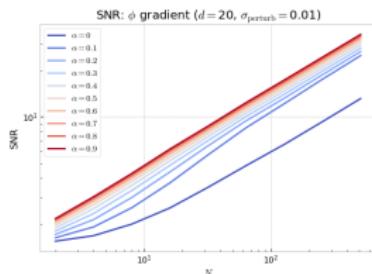


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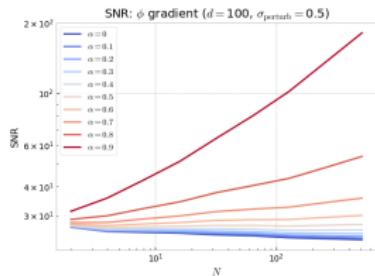
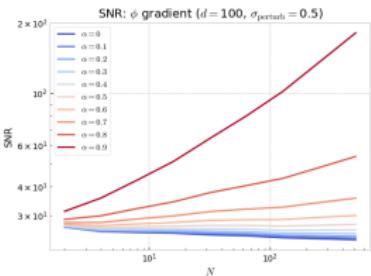
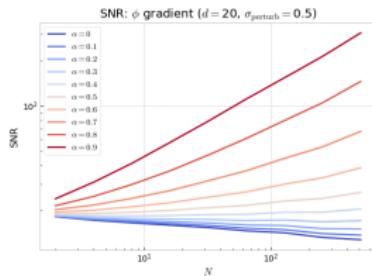


Doubly-reparameterized



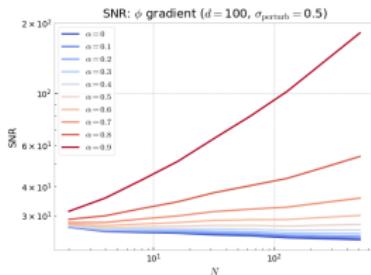
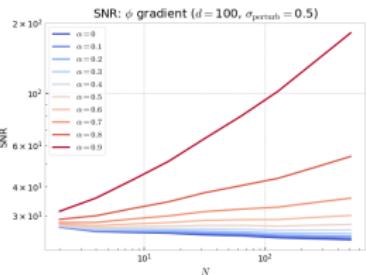
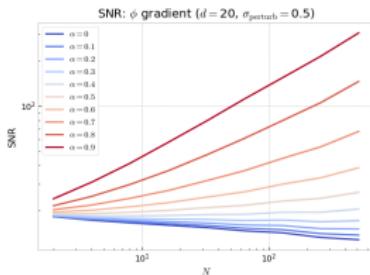
SNR analysis for the Linear Gaussian example : ϕ (cont'd)

Reparameterized

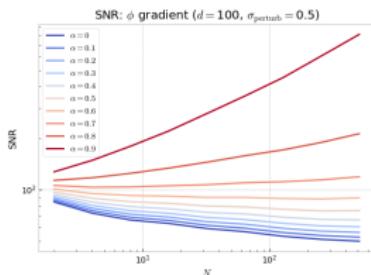
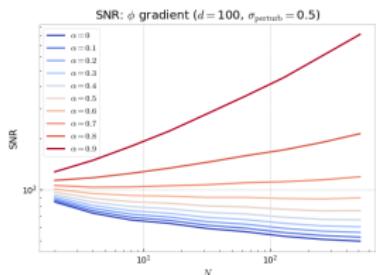
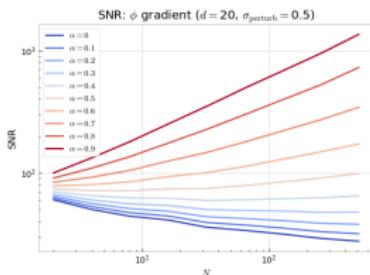


SNR analysis for the Linear Gaussian example : ϕ (cont'd)

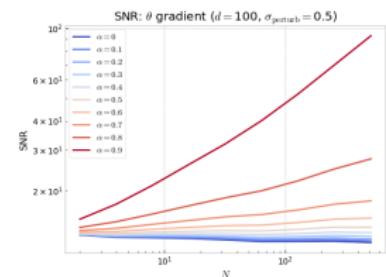
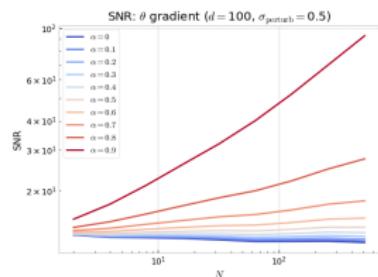
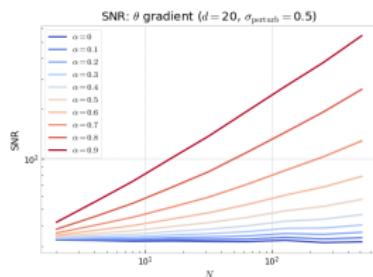
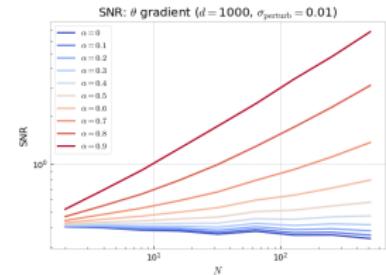
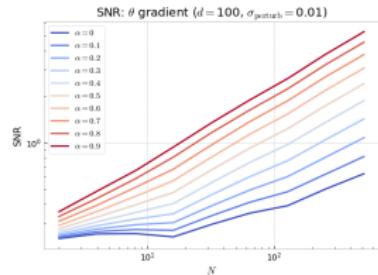
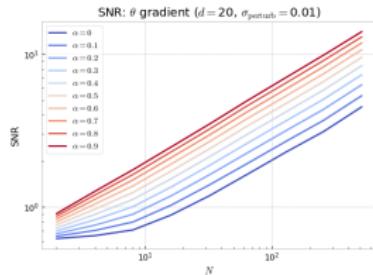
Reparameterized



Doubly-reparameterized

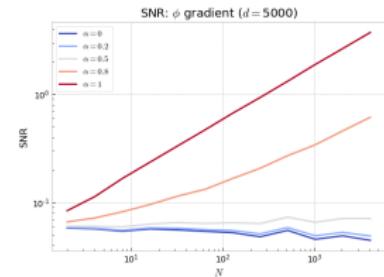
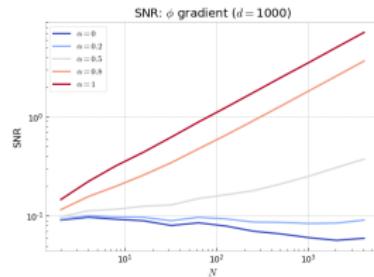
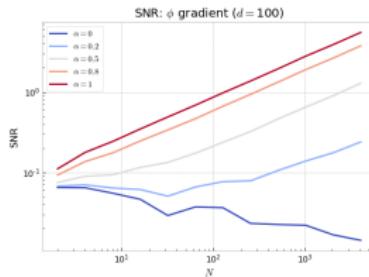


SNR analysis for the Linear Gaussian example : θ



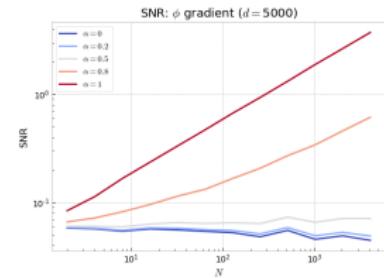
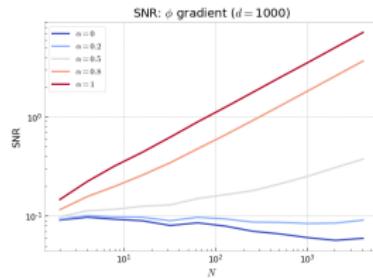
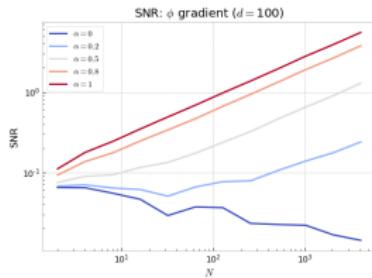
SNR analysis for VAE with MNIST : ϕ

Reparameterized

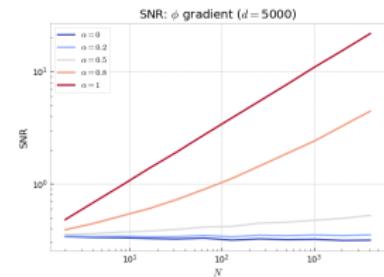
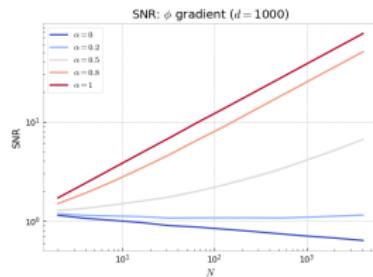
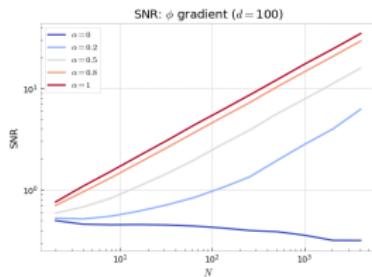


SNR analysis for VAE with MNIST : ϕ

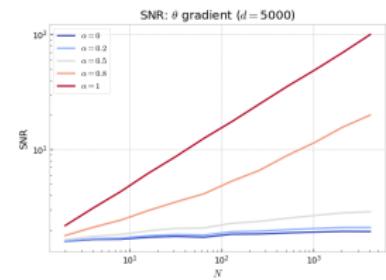
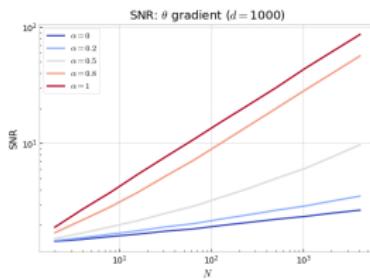
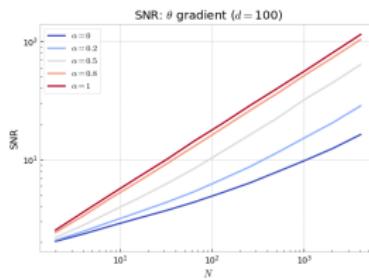
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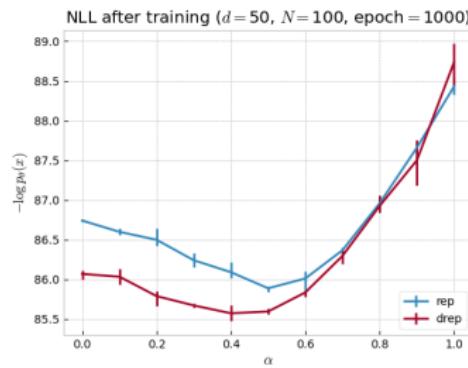
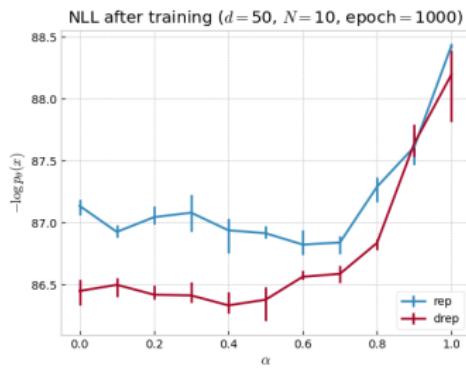
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SNR analysis for VAE with MNIST : θ



Final plots



Outline

- ① Introduction
- ② The VR bound
- ③ The VR-IWAE bound
- ④ Study of the VR-IWAE bound
- ⑤ Application to VAEs
- ⑥ Study of the gradient(s) of the VR-IWAE bound
- ⑦ Conclusion

Conclusion

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- ➊ We formalized and motivated the VR-IWAE bound
 - Theoretically-sound extension of the IWAE bound ($\alpha = 0$)
 - Provides theoretical guarantees behind various VR bound-based schemes proposed in the literature
- ➋ We provided two complementary analyses of the VR-IWAE bound
 - Shed light on the conditions behind the success or failure of the VR-IWAE bound methodology
 - Encompass the case of the IWAE bound
- ➌ We looked into the gradient(s) of the VR-IWAE bound and found desirable properties (SNR, doubly-reparameterized)
- ➍ Empirical verification of our theoretical results

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Perspectives

Some open questions:

- Does the weight collapse behavior apply beyond the cases highlighted here?
- How does the weight collapse affect the gradient descent procedures?
- Can we use the fact that the VR-IWAE bound extends the IWAE bound?
(e.g. to build better gradient estimators / to enrich the variational family \mathcal{Q})

Thank you for your attention !

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