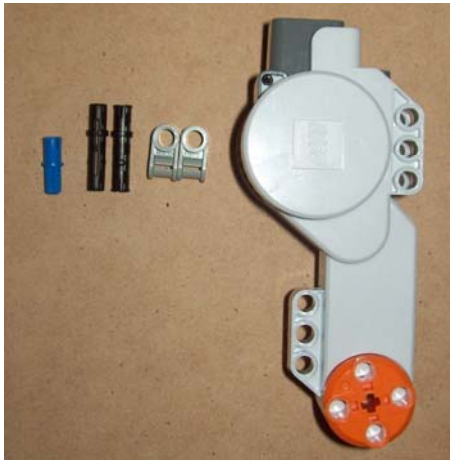


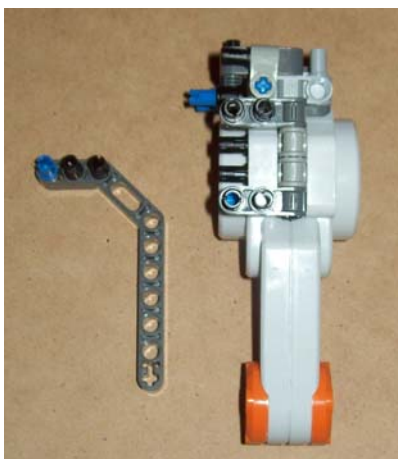
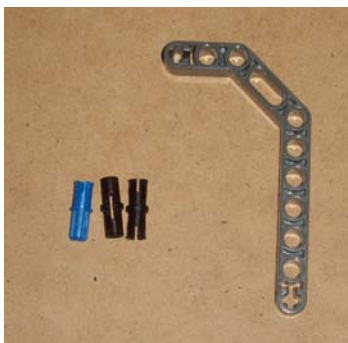
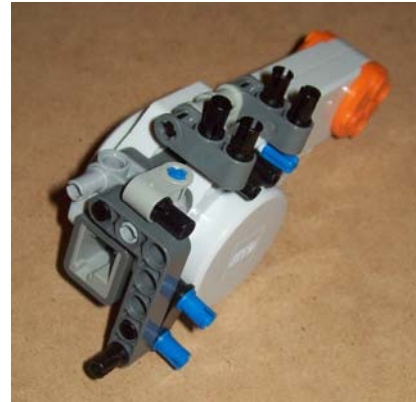
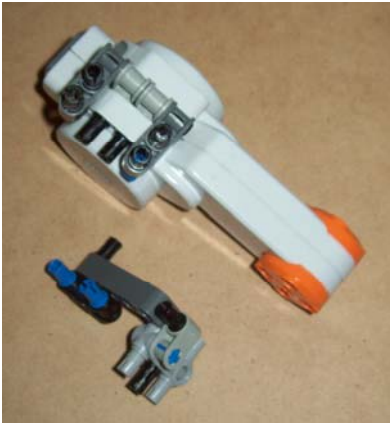
GELway Building Instructions

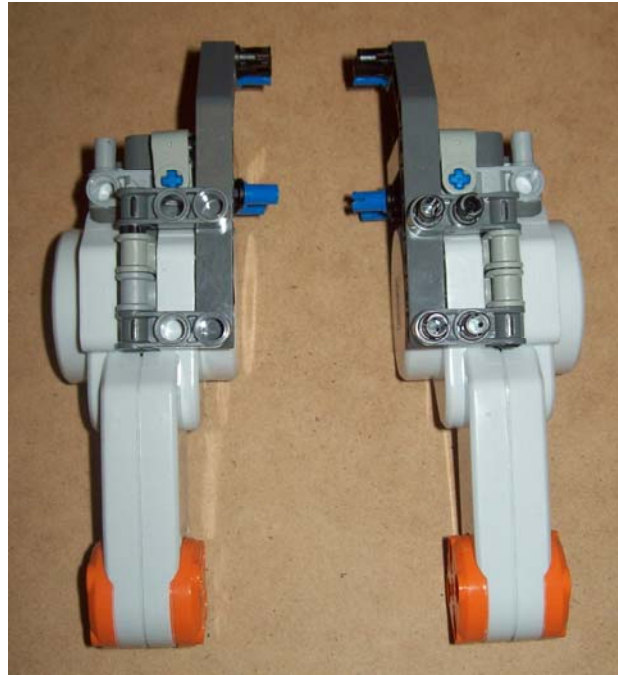
Modified version of the NXTway-GS building instructions



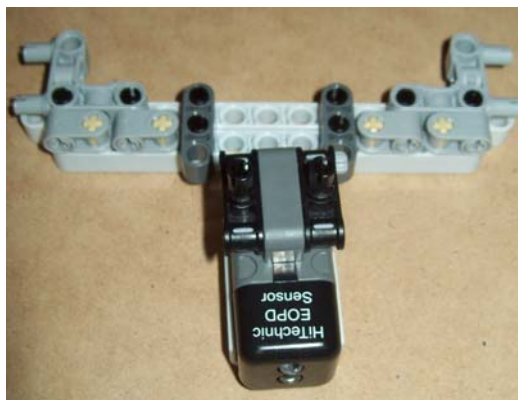
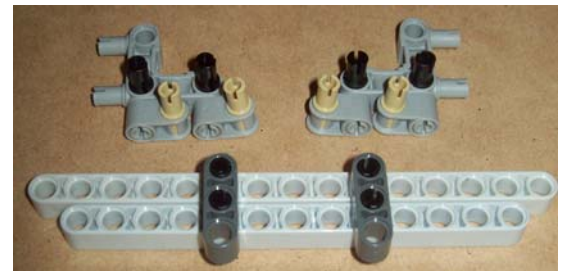
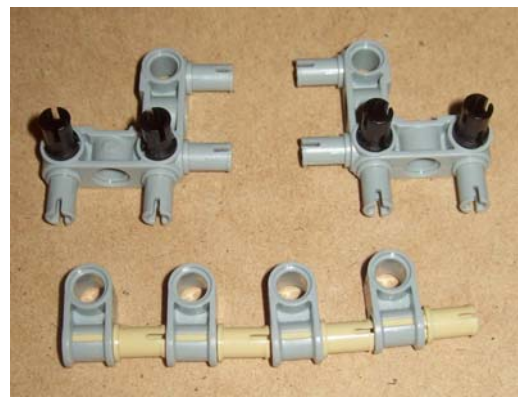
Step 1—Building the Motor Connection







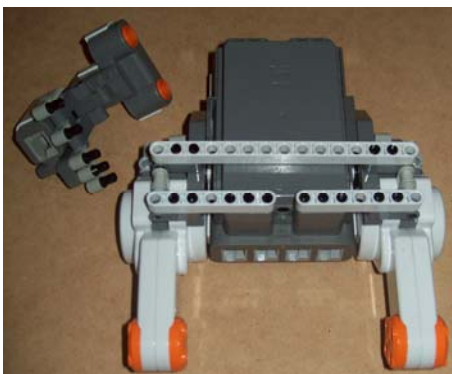
Step 3—Building the Upright Detector Frame



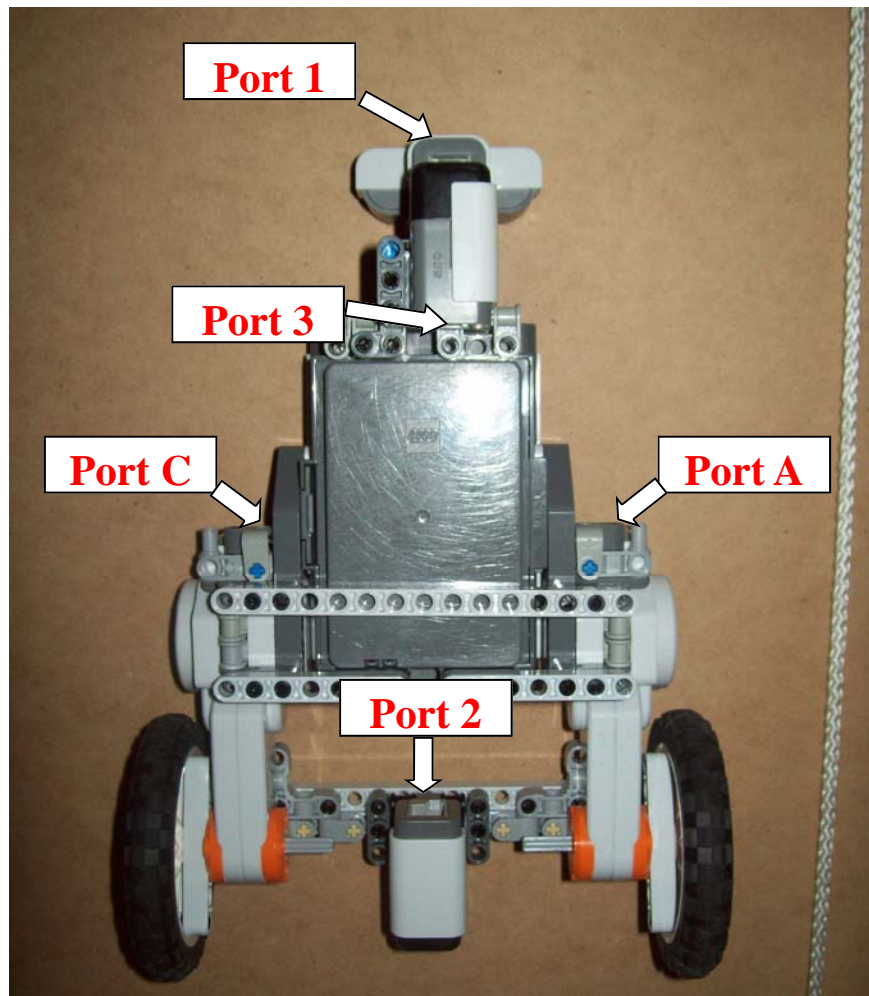
Step 3—Connecting the Motors



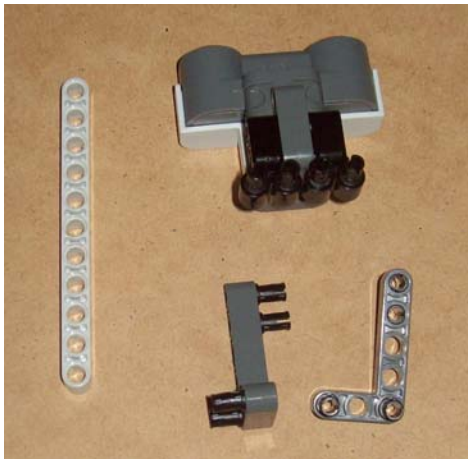
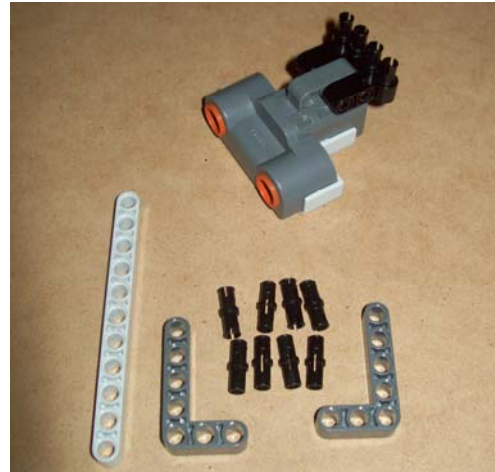
Leading Robot—Head Connection



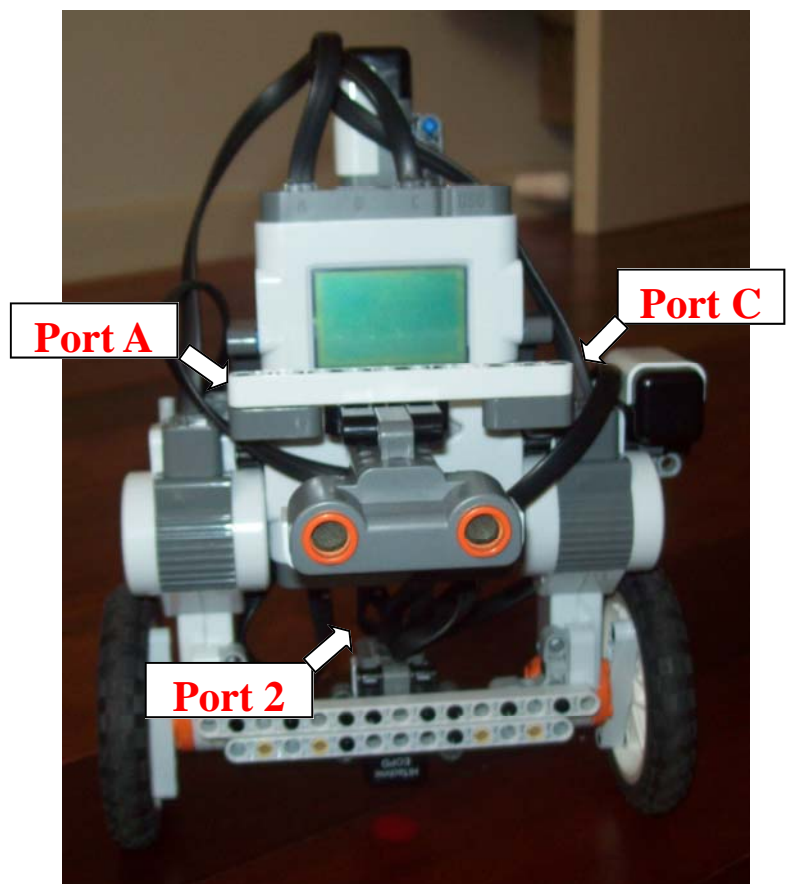
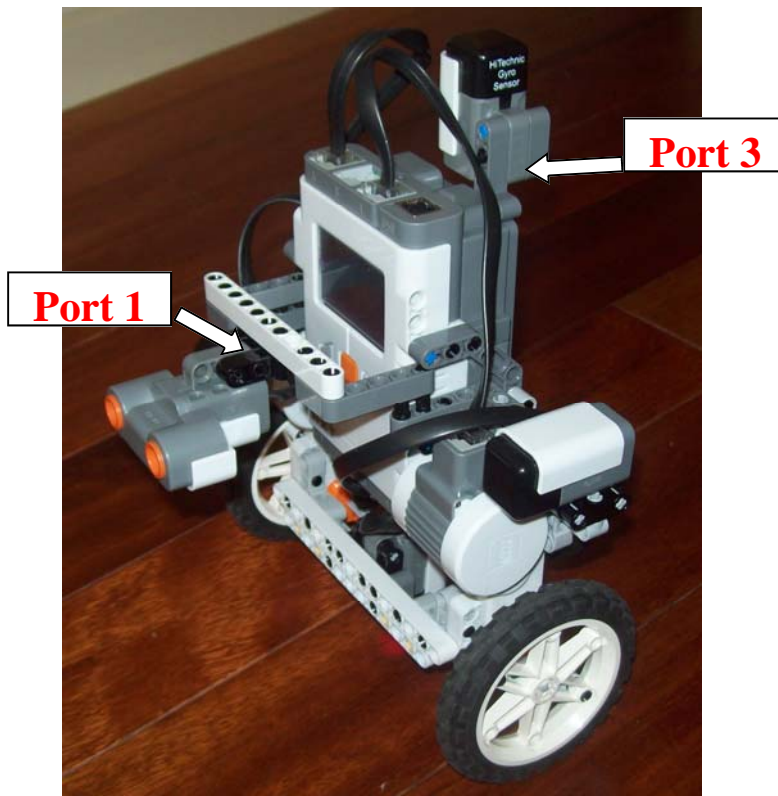
Leading Robot—Complete with Port Connections



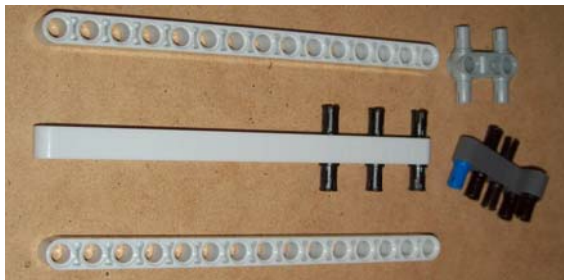
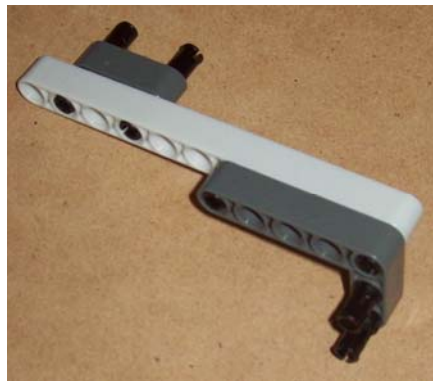
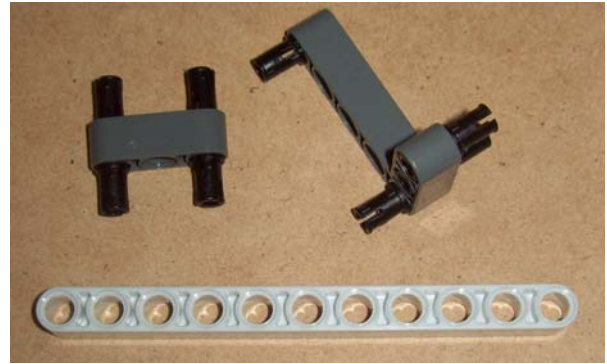
Follower Robot—Head Connection

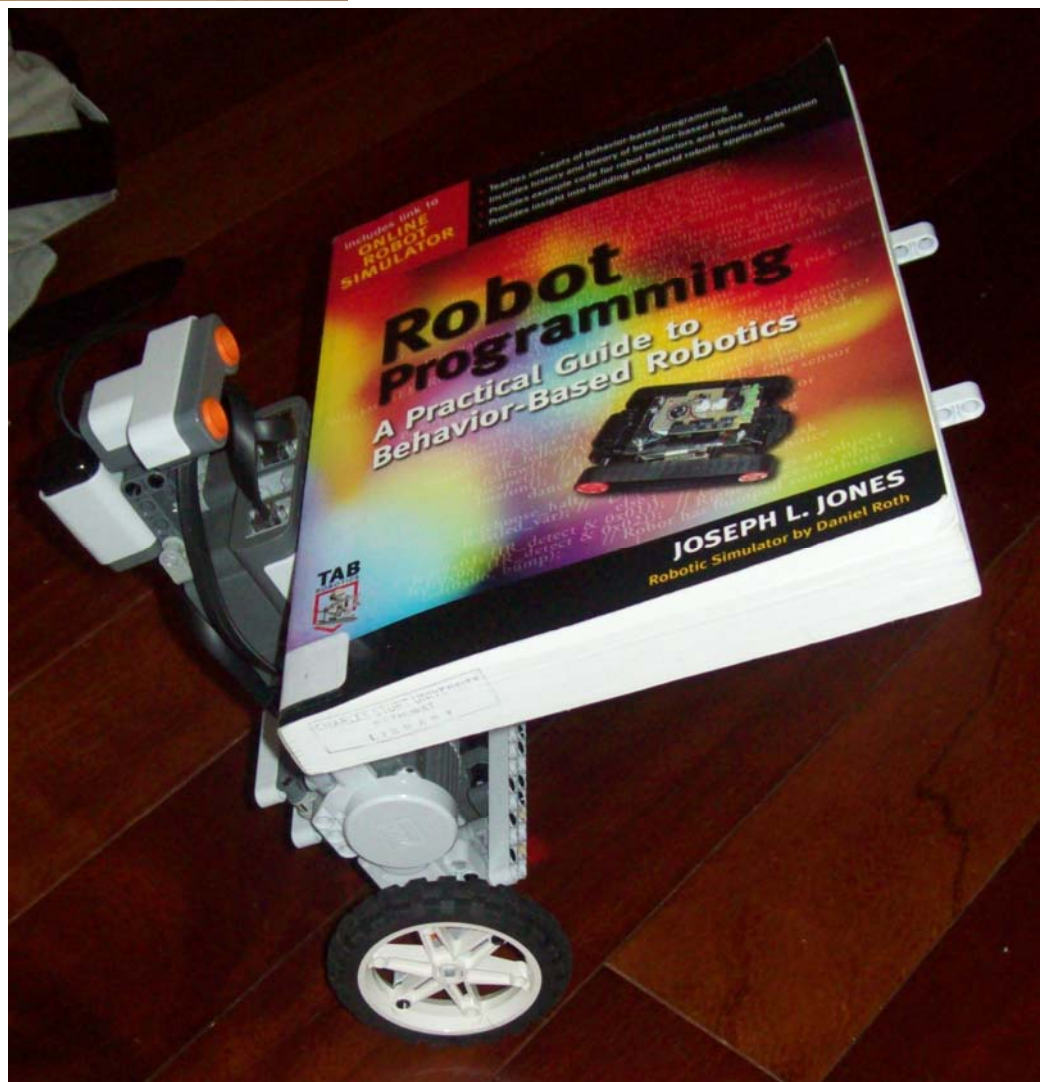


Follower Robot—Complete with Port Connections



Weight Carrying Attachment—Sturdy Arms





Additional Sensor Attachments

