Physics 198: Differential Geometry and Lie Groups

Notes

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These are a compilation of notes for the UC Berkeley DeCal 'Physics 198: Differential Geometry and Lie Groups for Physics Students'. These notes are largely based on the primary reference to the class, namely "Differential Geometry and Lie Groups for Physicists" by Marián Fecko, and cover topics in roughly the same order as in the book.

This template is based heavily off of the one produced by Kevin Zhou.

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1 Lie Groups

In physics, we can learn a great deal from studying the symmetries of *continuous* systems.

2 Representations of Lie Groups and Lie Algebras

2.1 What is a Representation?

- To understand what a group really is, it can be very enlightening to study what the group does i.e. to study group actions. It's particularly easy to extract information about a group from its linear actions on linear spaces.
- How exactly do we do this? We can use some sort of map to assign a *linear operator* over that vector space to each group element to describe (or represent) the action of each group element on the vector space elements. The map that we use is a **representation** of the group.

Recall that the space of all linear operators $\rho: V \to V$ is denoted End (V). The subset of these operators which are invertible (isomorphisms on V) is denoted Aut (V).

Notably, Aut (V) has a group structure! (Check this!) On the other hand, End (V) becomes an (Associative, and later Lie) Algebra if we define the commutator for $A, B \in \text{End}(V)$ as

$$[A, B] = AB - BA$$

Now the formal definition.

Group Representation

Given a group G and vector space V, a group homomorphism

$$\rho: G \to \operatorname{Aut}(V)$$

is called a **representation** of G in V.

Example. Complete this later

We can use the same idea to define the representation of an algebra, but this time with $\operatorname{End}(V)$.

Lie Algebra Representation

Given a Lie algebra \mathcal{G} and vector space V, an algebra homomorphism

$$\rho': \mathcal{G} \to \operatorname{End}(V)$$

is called a representation of the Lie algebra \mathcal{G} over V.

Note. The representations ρ and ρ' of a lie group and its lie algebra are related! so ρ' is called the derived representation.

Fecko, Exercise 12.1.4

Consider a Lie algebra \mathcal{G} whose basis elements $\{E_i\}$ satisfy the commutation relations

$$[E_i, E_j] = c_{ij}^k E_k$$

and a representation $f: \mathcal{G} \to \text{End}(V)$. Then, define $\mathcal{E}_i \equiv f(E_i)$. Since f is a homomorphisms between algebra, it is linear and respects the commutator i.e. for $A, B \in \mathcal{G}$

$$f([A,B]) = [f(A), f(B)]$$

Thus,

$$\begin{aligned} [\mathcal{E}_i, \mathcal{E}_j] &= [f(E_i), f(E_j)] \\ &= f([E_i, E_j]) \\ &= f\left(c_{ij}^k E_k\right) \\ &= c_{ij}^k f(E_k) \\ &= c_{ij}^k \mathcal{E}_k \end{aligned}$$

(The basis elements of the representation satisfy the same commutation relation as those of the Lie Algebra!)

Fecko, Exercise 12.1.5

Do this one later

- The assignment from Lie Group to Lie Algebra $G \mapsto \mathcal{G}$ is nice and unique, but the other way around can get messy.
- Similarly, given a Lie group representation ρ there is a unique Lie algebra representation ρ' , but not necessarily the other way around.

Fecko, Exercise 12.1.6

(i) Consider the Lie Group $H = \text{Aut}(V) \equiv \text{GL}(V)$. Recall that the Lie Algebra of H is

Write about ρ -invariant inner products.