

Physics 137B Lecture 2

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These are notes taken from lectures on Quantum Mechanics delivered by Professor Raúl A. Briceño for UC Berkeley's Physics 137B class in the Spring 2024 semester.

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1 January 19 - Review (Continuation)

- Dirac Ket $|\psi\rangle$

$$\langle\psi_\alpha|\psi_\beta\rangle = \int dx \psi_\alpha^*(x) \psi_\beta(x)$$

- Observables are associated with Hermitian operators

$$\hat{\Theta}^\dagger = \hat{\Theta}$$

and the experimentally measured values are the expectation values of operators

$$\langle\hat{\Theta}\rangle = b$$

Hermitian operators have real eigenvalues.

- If $\underbrace{\hat{Q}}_{\text{hermitian}} |a\rangle = a|a\rangle$ and $\underbrace{\hat{Q}}_{\text{hermitian}} |b\rangle = b|b\rangle$ with $a \neq b$ then

$$\langle a|b\rangle = 0$$

- Eigenvectors of \hat{Q} form a complete basis.

In this class we will primarily focus of operators that are Hermitian and/or unitary.

- Unitary Operators:

$$\hat{Q}^\dagger = \hat{Q}^{-1}$$

$$\begin{aligned} \implies \hat{Q}^\dagger \hat{Q} &= \hat{Q}^{-1} \hat{Q} = \mathbf{1} \\ &= \hat{Q} \underbrace{\hat{Q}^\dagger}_{\hat{Q}^{-1}} \end{aligned}$$

- Two observables are simultaneously diagonalizable if their operators commute i.e.

$$[\hat{A}, \hat{B}] = 0$$

such that

$$\hat{A}|a, b\rangle = a|a, b\rangle$$

$$\hat{B}|a, b\rangle = b|a, b\rangle$$

- Generalized Uncertainty principle:

$$\sigma_A^2 \sigma_B^2 \geq \left(\frac{\langle [A, B] \rangle}{2i} \right)^2$$

- Ehrenfest Theorem:

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$$\frac{d}{dt} \langle \hat{Q} \rangle = \frac{i}{\hbar} \langle [\hat{H}, \hat{Q}] \rangle + \left\langle \frac{\partial \hat{Q}}{\partial t} \right\rangle$$

- This will be important later when considering symmetries and conservations.

1.1 Review of 3D QM:

- $|\vec{r}\rangle = |x\rangle \otimes |y\rangle \otimes |z\rangle$ where $\langle x|x'\rangle\delta(x-x')$.
- The inner product of general position space kets is just

$$\begin{aligned}\langle \vec{r}|\vec{r}'\rangle &= \langle x|x'\rangle\langle y|y'\rangle\langle z|z'\rangle \\ &= \delta(x-x')\delta(y-y')\delta(z-z').\end{aligned}$$

- $\psi(\vec{r}, t) = \langle \vec{r}|\psi(t)\rangle$.
- The TISE in three dimensions is

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- For a central potential, i.e. $V(\vec{r}) = V(r)$ (no angular dependence) we can get the general solution

$$\psi(\vec{r}) = R(r)Y(\theta, \phi)$$

- $Y_{lm}(\theta, \phi) = \langle \theta, \phi|l, m\rangle$.

1.2 Introduction to Symmetries

This is one of the most fundamental concepts in physics. Three of the four fundamental forces are heavily based on symmetry arguments. A theorem of great importance is **Noether's Theorem**.

Noether's Theorem

There is a correspondence between Symmetries and Conservation laws.

For instance, the facts that charge and energy are conserved in nuclear reactions are due to this theorem. Rather than being postulates, as they were in our earlier studies of Classical Mechanics, these conservations are the results of symmetries.

In 137B

We will encounter many situations where the Hamiltonian is of the form

$$\hat{H}(\lambda) = \underbrace{\hat{H}_0}_{\text{known sol.}} + \lambda\delta\hat{H}$$

and generally there will be some **degeneracies** i.e. spaces of Eigenvectors such that $|n_1\rangle, |n_2\rangle$ have the same energy $E_{n_1} = E_{n_2}$.

Then, we will usually introduce a **Perturbation**. [Insert graph]

What is a symmetry in Physics?

- A symmetry in Physics is an action/transformation that leaves a system unchanged or invariant.
- There can be **continuous** or **discrete** symmetries.
- Draw images and give example of continuous \rightarrow circle and discrete \rightarrow square.

Some more examples of continuous symmetries that we will be considering are

- Translations in space-time.

- momentum, energy.
- Rotations in space.
 - orbital angular momentum (\vec{L}).
 - spin.

and some discrete ones are

- Parity.
- Time reversal.

Active vs. Passive Transformations

Transformations can be thought of as acting on the state $|\psi\rangle$ or on the operator $\hat{\Theta}$, but physically both are **equivalent**.

$$\implies \langle \psi' | \hat{\Theta} | \psi' \rangle = \langle \psi | \hat{\Theta}' | \psi \rangle$$

[Draw images from lecture of function on graph example.]

- Let's define the transformation operator as \hat{U} such that

$$\begin{aligned} |\psi'\rangle &= \hat{U}|\psi\rangle \\ \implies \langle \psi' | &= \langle \psi | \hat{U}^\dagger \end{aligned}$$

- This tells us that \hat{U} is unitary. Why?

$$\begin{aligned} 1 &= \langle \psi | \psi \rangle \\ &= \langle \psi' | \psi' \rangle \\ &= \langle \psi | \underbrace{\hat{U}^\dagger \hat{U}}_{\mathbf{1}} | \psi \rangle \end{aligned}$$

and

$$\begin{aligned} \langle \psi | \hat{U}^\dagger \hat{\Theta} \hat{U} | \psi \rangle &= \langle \psi | \hat{\Theta}' | \psi \rangle \\ \implies \hat{\Theta}' &= \hat{U}^\dagger \hat{\Theta} \hat{U} \end{aligned}$$

which tells us that \hat{U} is a unitary operator.

- Now, the system is **invariant** under the transformation $|\psi\rangle \rightarrow \hat{U}|\psi\rangle$.