

# Kush Desai

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## EDUCATION

### THE UNIVERSITY OF TEXAS AT AUSTIN

BS IN COMPUTER ENGINEERING  
(DATA SCIENCE AND INFORMATION PROCESSING)

May 2022 | Austin, TX

Cockrell School of Engineering

GPA: 3.68 / 4.0

## LINKS

Github:// [kdesai2018](#)

LinkedIn:// [kushkdesai](#)

Twitter:// [@kdesai2018](#)

## COURSEWORK

### GRADUATE

Neural Computation

Robot Learning

### UNDERGRADUATE

Operating Systems

Algorithms

Digital Image Processing

Data Science Principles

Linear Algebra

Software Implementation and Design  
(Honors)

Probability

Senior Design

## SKILLS

### PROGRAMMING

Rust, Python, Java, C++ ★★★★★★

Javascript, CSS ★★★★★☆

C, Assembly ★★★☆☆

### TECHNOLOGIES

Robot Operating System • AWS • Azure •

Google Cloud • PyTorch • Tensorflow •

OpenCV • Jupyter • sklearn • pandas •

keras • Git • Docker • Bash • Arduino •

\*-nix systems

### VOLUNTEERING

AAAI Volunteer (2021) • HRI Volunteer

(2021) • Freetail Hackers Logistics

Director (2020-21)

## EXPERIENCE

### FACEBOOK | PRODUCTION ENGINEERING INTERN

Summer 2021 | Remote

- Using **Rust** and **Buck** to build an end-to-end load testing system for Facebook Live infrastructure that can handle over 1 million requests at 1000 QPS
- Used **Scuba**, **ODS** and **Unidash** to build a comprehensive monitoring system with detailed real-time visualization

### DILIGENT ROBOTICS | SOFTWARE ENGINEERING INTERN

Feb 2021 - May 2021 | Austin, TX

- Using **Python** and **ROS** to build new features for Moxi, a socially-aware humanoid robot

### SOCIALLY INTELLIGENT MACHINES LAB | RESEARCH INTERN

August 2018 - Present | Austin, TX

- Researching **audio-augmented Imitation Learning** and implemented **object recognition algorithms** under Dr. Andrea Thomaz
- Conducted robotics experiments using **Python**, **TensorFlow**, **ROS**, **AWS**, **Mechanical Turk** and **Javascript**

### BP | SOFTWARE ENGINEERING INTERN

Summer 2020 | Remote

- Designed an **optimal routing algorithm** for shipping to minimize carbon emissions by 30% globally
- My team won **Most Innovative Solution** in the intern hackathon out of 80 interns

## PROJECTS

### BEVO [GITHUB.COM/KDESAI2018/BEVO](#)

Best Use of Google Cloud, Best Accessibility Hack | TAMUHack 2020

Built BEVO (Blind Environment Visualization Objects) a palm and object-recognition pipeline to help visually impaired individuals locate objects using audio cues using **Tensorflow**, **Google Cloud**, **Python** and **OpenCV**

### DROWSY DRIVER [GITHUB.COM/KDESAI2018/DROWSY-DRIVER](#)

1st overall, Best in workplace safety | UT Makeathon 2019

Developed an eye and grip tracking system using **OpenCV**, **Python** and **Arduino**

### 3D RENDERING FROM 2D IMAGES

[KDESAI2018.GITHUB.IO/NBA-PROJECT](#)

Class Competition Winner | Fall 2020

Built an end-to-end pipeline using **Python**, **OpenCV** and **PyTorch** to convert videos from NBA games into 3-dimensional pointclouds with pose and object information

## AWARDS

2021	UT Engineering	Gail and Howard Neal Endowed Scholarship
2019	National	BP Scholar

## PUBLICATIONS

- [1] A. Saran, K. Desai, R. Lioutikov, A. Thomaz, and N. Scott. A case for leveraging human prosody during reward learning. *Workshop, 16th Annual Conference for Basic and Applied Human-Robot Interaction Research*, March 2021.