

# Chapter15. Dynamic Programming

# Dynamic Programming

- Dynamic Programming is an algorithm design technique for optimization problems: minimizing or maximizing.
- Like divide and conquer, Dynamic Programming solves problems by combining solutions to subproblems.
- Unlike divide and conquer, subproblems are not independent.
  - Subproblems may share subsubproblems,
- Dynamic Programming reduces computation by
  - Solving subproblems in a bottom-up fashion.
  - Storing solution to a subproblem the first time it is solved.
  - Looking up the solution when subproblem is encountered again.
- Key: determine structure of optimal solutions

# Dynamic Programming

- Dynamic programming is a way of improving on inefficient divide-and-conquer algorithms.
- By “*inefficient*”, we mean that *the same recursive call is made over and over*.
- If same subproblem is solved several times, we can use table to store result of a subproblem the first time it is computed and thus never have to recompute it again.
- Dynamic programming is applicable when the subproblems are dependent, that is, when subproblems share subproblems.
- “Programming” refers to a tabular method

# Difference between Dynamic Programming and Divide-and-Conquer

- Using Divide-and-Conquer to solve these problems is inefficient because the same common subproblems have to be solved many times.
- Dynamic Programming will solve each of them once and their answers are stored in a table for future use.

# Elements of Dynamic Programming

DP is used to solve problems with the following characteristics:

- Simple subproblems
  - We should be able to break the original problem to smaller subproblems that have the same structure
- Optimal substructure of the problems
  - The optimal solution to the problem contains within optimal solutions to its subproblems.
- Overlapping subproblems
  - there exist some places where we solve the same subproblem more than once.

# Steps in Dynamic Programming

1. **Characterize** structure of an optimal solution.
2. **Define** value of optimal solution recursively.
3. **Compute** optimal solution values either top-down with caching or bottom-up in a table.
4. **Construct** an optimal solution from computed values. (not always necessary)

# Dynamic Programming Example

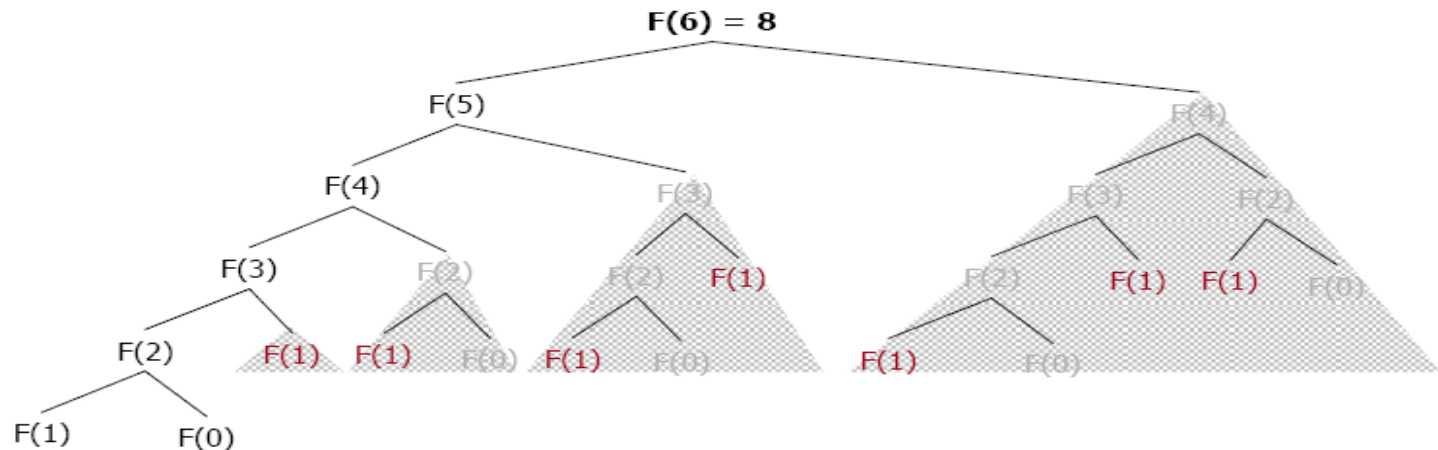
- Fibonacci Numbers

- $F_n = F_{n-1} + F_{n-2} \quad n \geq 2$

- $F_0 = 0, F_1 = 1$

- 0, 1, 1, 2, 3, 5, 8, 13, 21, 34, 55, ...

- Straightforward recursive procedure is slow!



○ We keep calculating the same value over and over!

# Dynamic Programming Example

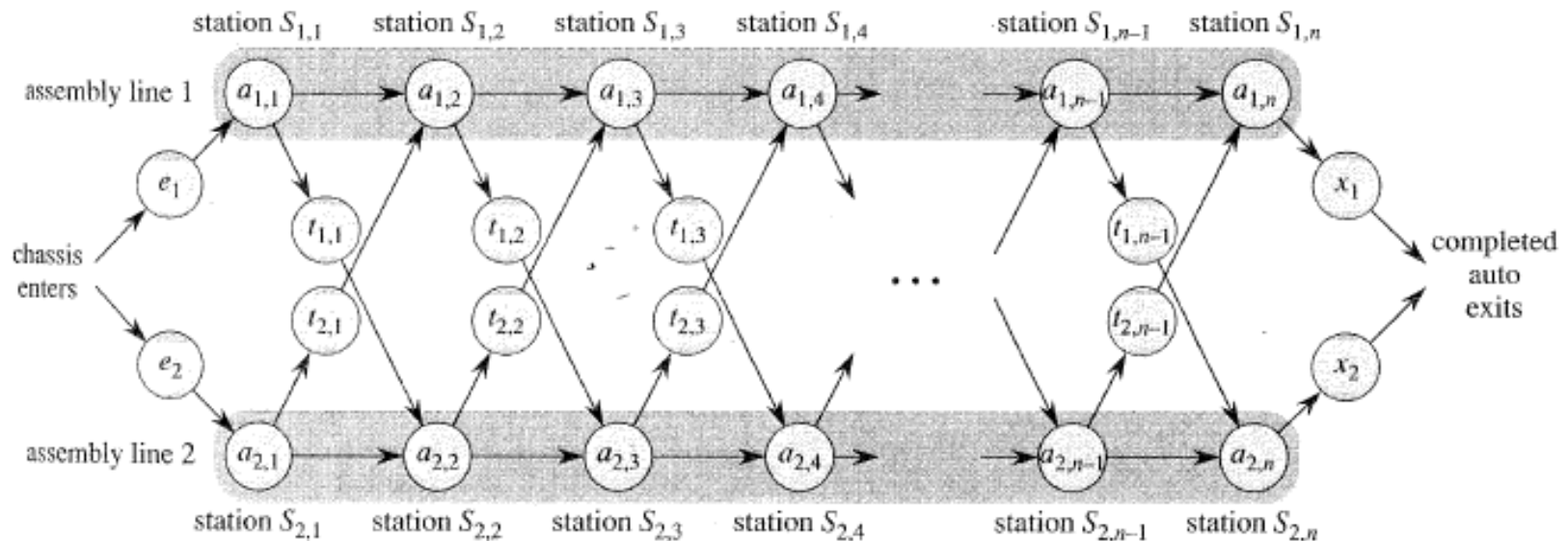
- We can calculate  $F_n$  in **linear time** by remembering solutions to the solved subproblems : *dynamic programming*
- Compute solution in a bottom-up fashion
- In this case, only two values need to be remembered at any time

```
Fibonacci (n)  
   $F_0 \leftarrow 0$   
   $F_1 \leftarrow 1$   
  for  $i \leftarrow 2$  to  $n$  do  
     $F_i \leftarrow F_{i-1} + F_{i-2}$ 
```



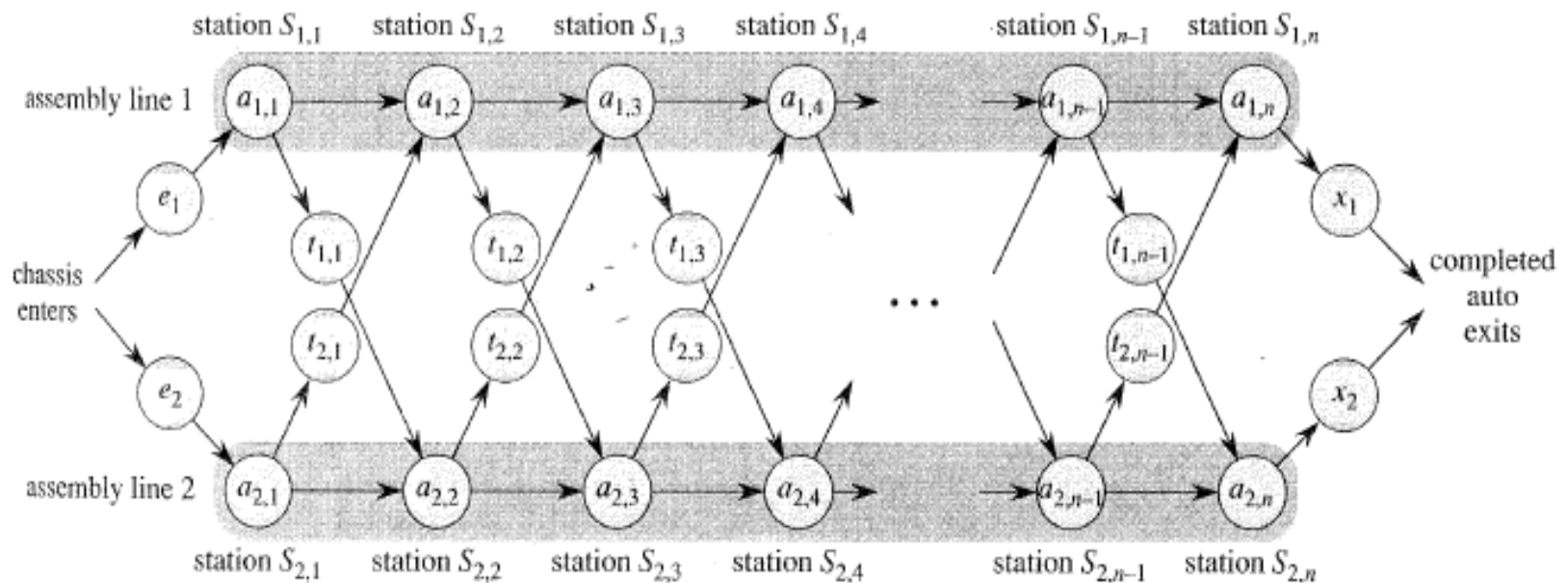
# Assembly Line Scheduling

- Automobile factory with two assembly lines
  - Each line has  $n$  stations:  $S_{1,1}, \dots, S_{1,n}$  and  $S_{2,1}, \dots, S_{2,n}$
  - Corresponding stations  $S_{1,j}$  and  $S_{2,j}$  perform the same function but can take different amounts of time  $a_{1,j}$  and  $a_{2,j}$
  - Entry times are:  $e_1$  and  $e_2$ ; exit times are:  $x_1$  and  $x_2$



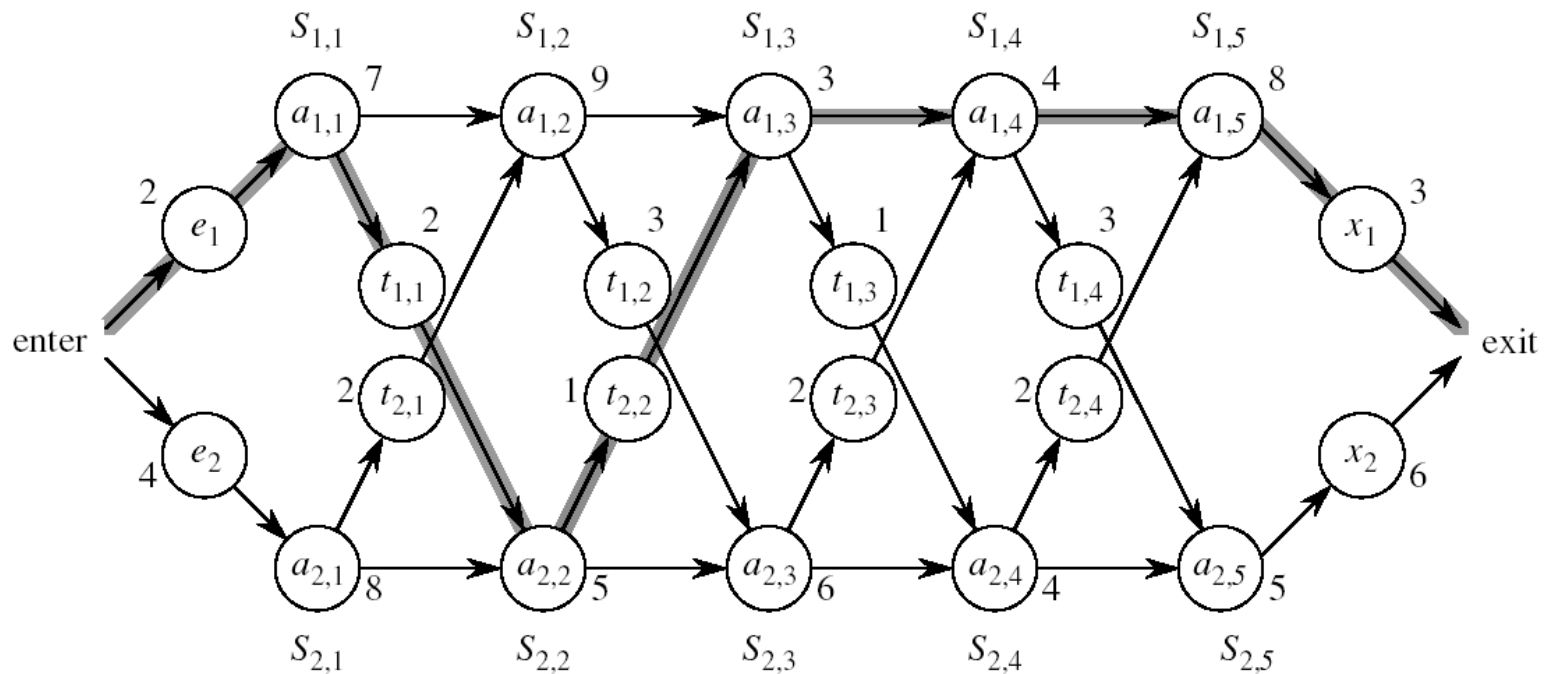
# Assembly Line Scheduling

- After going through a station, can either:
  - stay on same line at no cost, or
  - transfer to other line: cost after  $S_{i,j}$  is  $t_{i,j}$ ,  $j = 1, \dots, n - 1$



# Assembly Line Scheduling

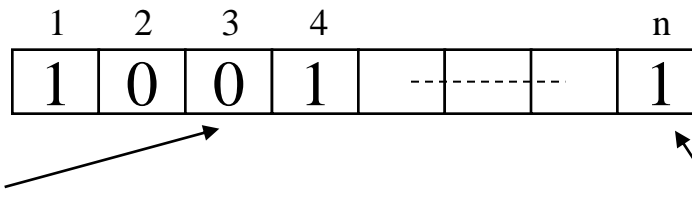
- Problem:  
what stations should be chosen from line 1 and which from line 2  
in order to **minimize the total time through the factory for one car?**



# One Solution

- Brute force
  - Enumerate all possibilities of selecting stations
  - Compute how long it takes in each case and choose the best one

- Solution:



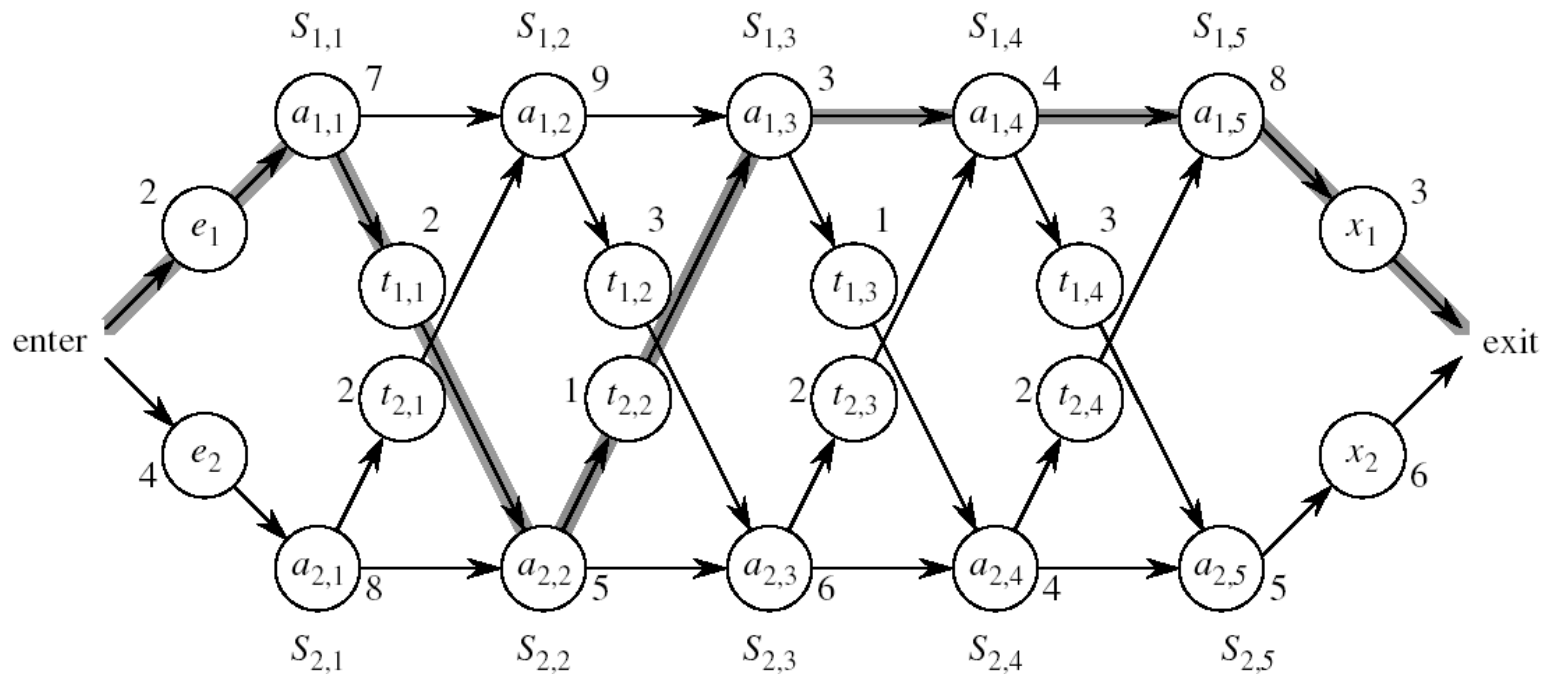
0 if choosing line 2  
at step  $j$  ( $= 3$ )

1 if choosing line 1  
at step  $j$  ( $= n$ )

- There are  $2^n$  possible ways to choose stations
- Infeasible when  $n$  is large!!

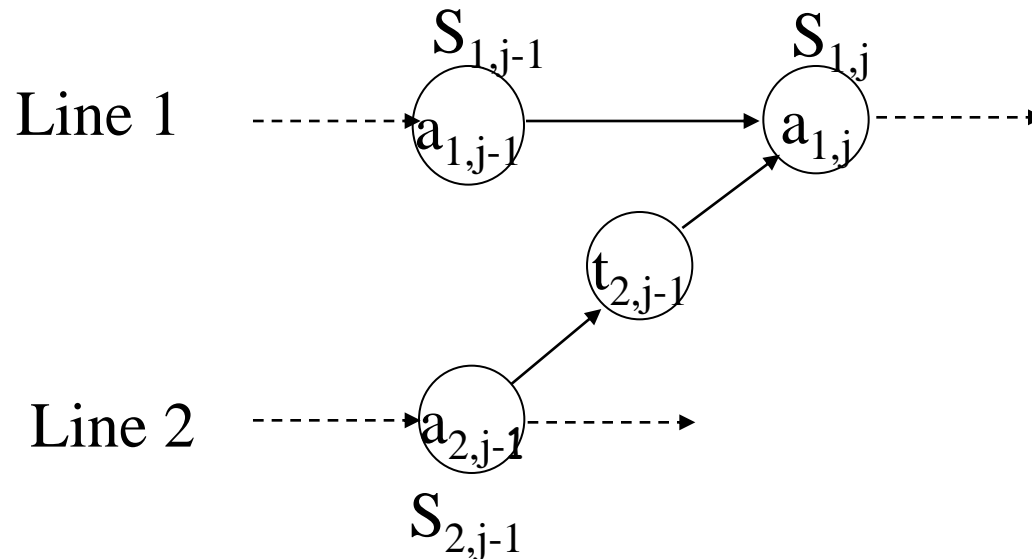
# 1. Structure of the Optimal Solution

- How do we compute the minimum time of going through a station?



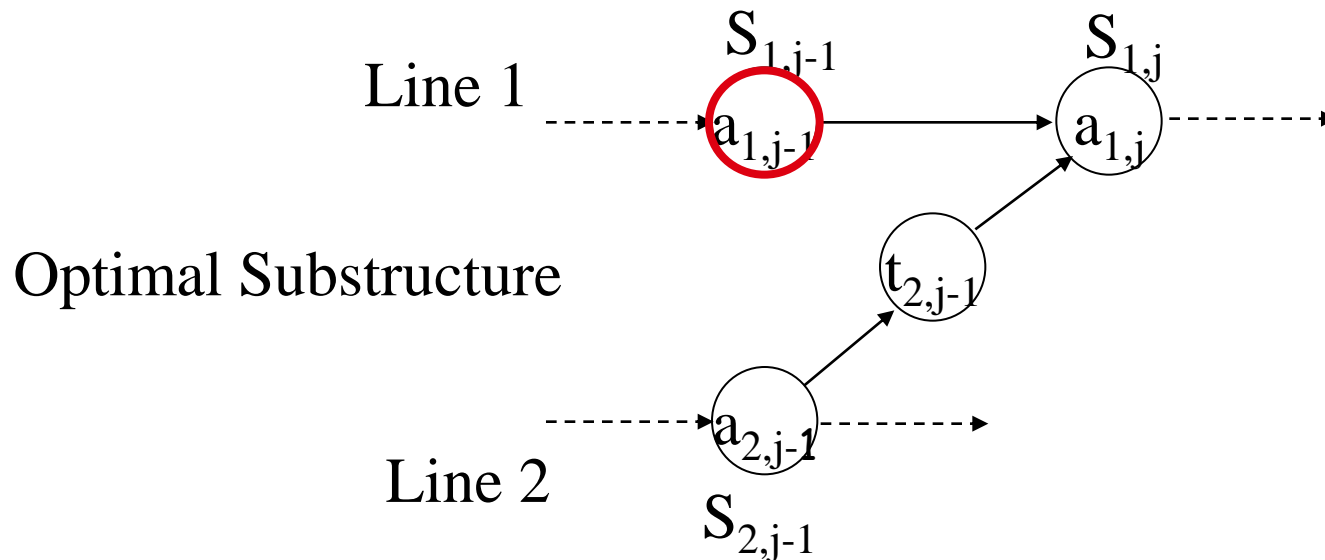
# 1. Structure of the Optimal Solution

- Let's consider all possible ways to get from the starting point through station  $S_{1,j}$ 
  - We have two choices of how to get to  $S_{1,j}$ :
    - Through  $S_{1,j-1}$ , then directly to  $S_{1,j}$
    - Through  $S_{2,j-1}$ , then transfer over to  $S_{1,j}$



# 1. Structure of the Optimal Solution

- Suppose that the fastest way through  $S_{1,j}$  is through  $S_{1,j-1}$ 
  - We must have taken a fastest way from entry through  $S_{1,j-1}$
  - If there were a faster way through  $S_{1,j-1}$ , we would use it instead
- Similarly for  $S_{2,j-1}$



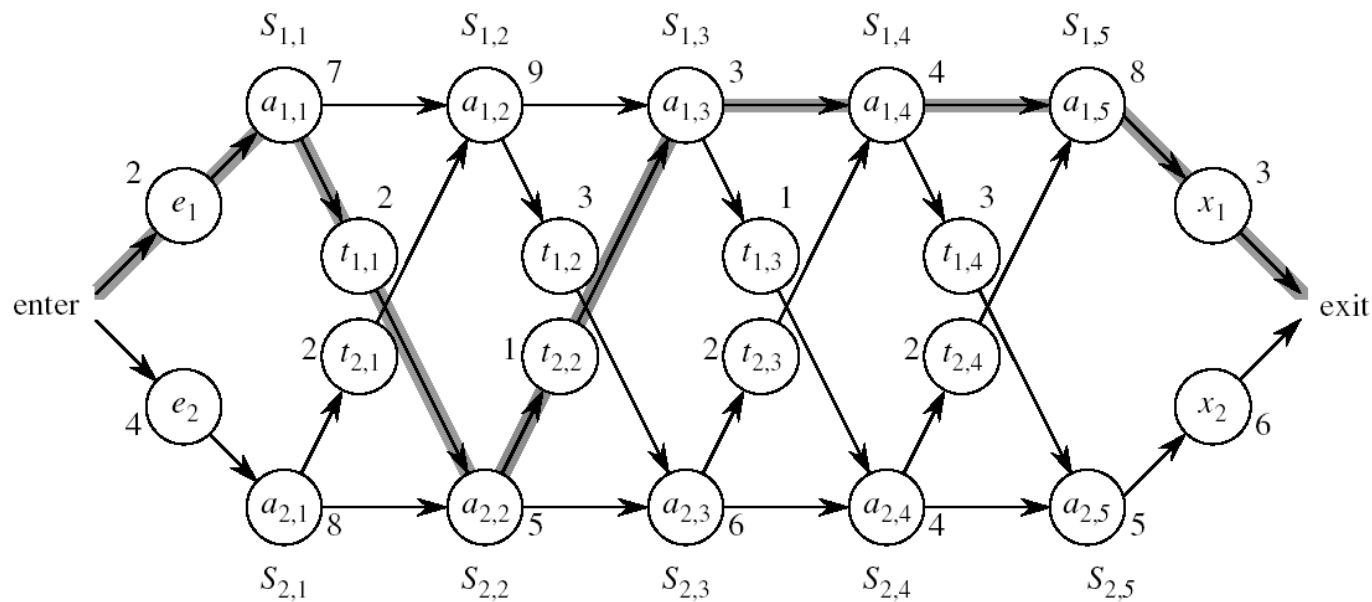
# Optimal Substructure

- **Generalization:** an optimal solution to the problem “*find the fastest way through  $S_{1,j}$* ” contains within it an optimal solution to subproblems: “*find the fastest way through  $S_{1,j-1}$  or  $S_{2,j-1}$* ”.
- This is referred to as the optimal substructure property
- We use this property to construct an optimal solution to a problem from optimal solutions to subproblems



## 2. A Recursive Solution

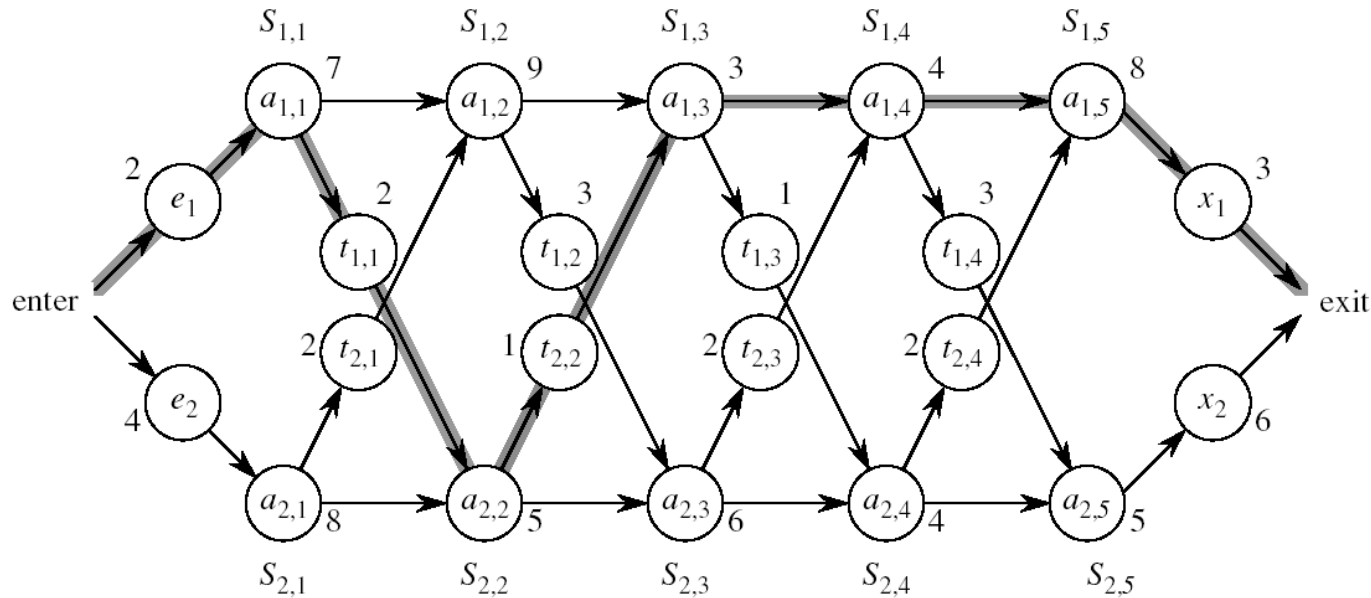
- Define the value of an optimal solution in terms of the optimal solution to subproblems



## 2. A Recursive Solution (cont.)

- Definitions:
  - $f^*$  : the fastest time to get through the entire factory
  - $f_i[j]$  : the fastest time to get from the starting point through station  $S_{i,j}$

$$f^* = \min (f_1[n] + x_1, f_2[n] + x_2)$$

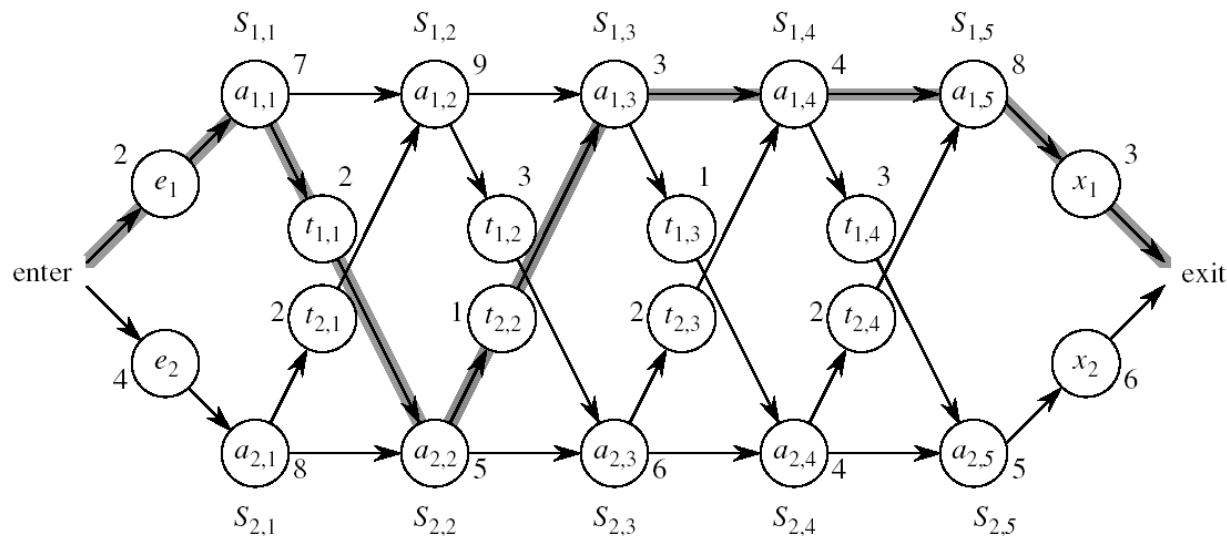


## 2. A Recursive Solution (cont.)

- Base case:  $j = 1$ ,  $i=1,2$  (getting through station 1)

$$f_1[1] = e_1 + a_{1,1}$$

$$f_2[1] = e_2 + a_{2,1}$$

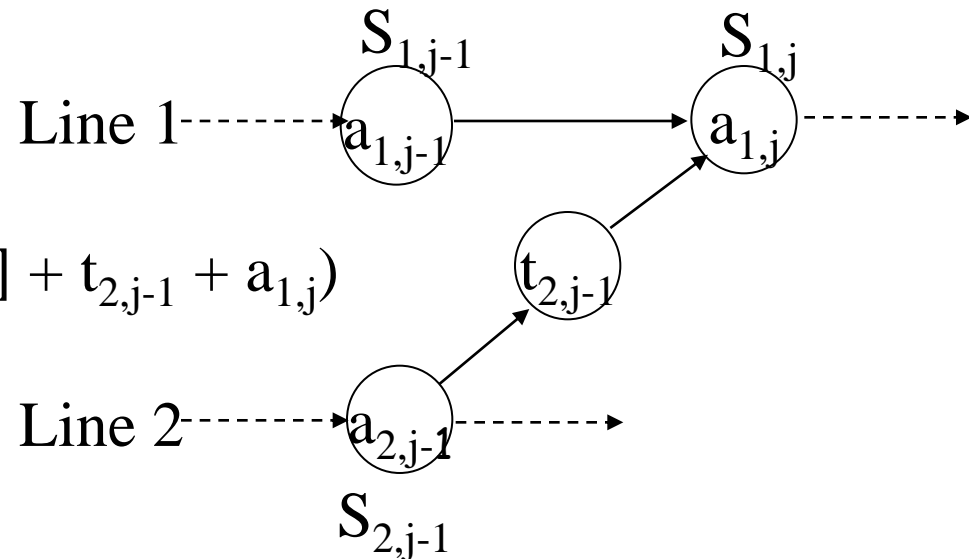


## 2. A Recursive Solution (cont.)

- General Case:  $j = 2, 3, \dots, n$ , and  $i = 1, 2$
- Fastest way through  $S_{1,j}$  is either:
  - the way through  $S_{1,j-1}$  then directly through  $S_{1,j}$ , or
  - the way through  $S_{2,j-1}$ , transfer from line 2 to line 1, then through  $S_{1,j}$

$$f_1[j-1] + a_{1,j}$$

$$f_2[j-1] + t_{2,j-1} + a_{1,j}$$



$$f_1[j] = \min(f_1[j-1] + a_{1,j}, f_2[j-1] + t_{2,j-1} + a_{1,j})$$

## 2. A Recursive Solution (cont.)

$$f_1[j] = \begin{cases} e_1 + a_{1,1} & \text{if } j = 1 \\ \min(f_1[j-1] + a_{1,j}, f_2[j-1] + t_{2,j-1} + a_{1,j}) & \text{if } j \geq 2 \end{cases}$$

$$f_2[j] = \begin{cases} e_2 + a_{2,1} & \text{if } j = 1 \\ \min(f_2[j-1] + a_{2,j}, f_1[j-1] + t_{1,j-1} + a_{2,j}) & \text{if } j \geq 2 \end{cases}$$

# 3. Computing the Optimal Solution

$$\mathbf{f}^* = \min (\mathbf{f}_1[\mathbf{n}] + \mathbf{x}_1, \mathbf{f}_2[\mathbf{n}] + \mathbf{x}_2)$$

$$f_1[j] = \min(f_1[j - 1] + a_{1,j}, f_2[j - 1] + t_{2,j-1} + a_{1,j})$$

$$f_2[j] = \min(f_2[j - 1] + a_{2,j}, f_1[j - 1] + t_{1,j-1} + a_{2,j})$$

	1	2	3	4	5
$f_1[j]$	$f_1(1)$	$f_1(2)$	$f_1(3)$	$f_1(4)$	$f_1(5)$
$f_2[j]$	$f_2(1)$	$f_2(2)$	$f_2(3)$	$f_2(4)$	$f_2(5)$


4 times
2 times

- Solving top-down would result in exponential running time

### 3. Computing the Optimal Solution

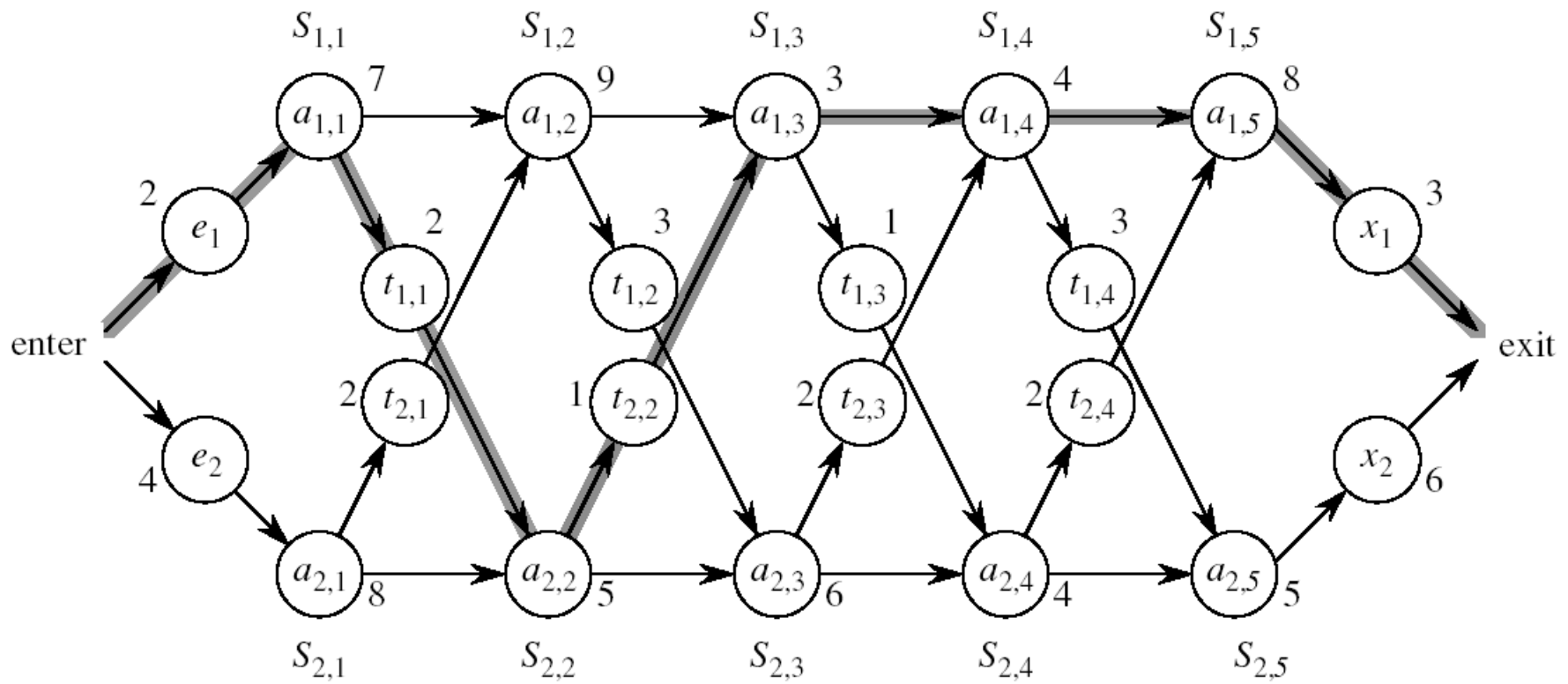
- For  $j \geq 2$ , each value  $f_i[j]$  depends only on the values of  $f_1[j - 1]$  and  $f_2[j - 1]$
- Idea: compute the values of  $f_i[j]$  as follows:

in increasing order of  $j$



	1	2	3	4	5
$f_1[j]$					
$f_2[j]$					

- Bottom-up approach
  - First find optimal solutions to subproblems
  - Find an optimal solution to the problem from the subproblems



$$f_1[j] = \begin{cases} e_1 + a_{1,1}, & \text{if } j = 1 \\ \min(f_1[j-1] + a_{1,j}, f_2[j-1] + t_{2,j-1} + a_{1,j}) & \text{if } j \geq 2 \end{cases}$$

	1	2	3	4	5
$f_1[j]$	9	18 <sup>[1]</sup>	20 <sup>[2]</sup>	24 <sup>[1]</sup>	32 <sup>[1]</sup>
$f_2[j]$	12	16 <sup>[1]</sup>	22 <sup>[2]</sup>	25 <sup>[1]</sup>	30 <sup>[2]</sup>

$$f^* = 35^{[1]}$$



# FASTEST-WAY(a, t, e, x, n)

1.  $f_1[1] \leftarrow e_1 + a_{1,1}$   
2.  $f_2[1] \leftarrow e_2 + a_{2,1}$  } Compute initial values of  $f_1$  and  $f_2$   
3. **for**  $j \leftarrow 2$  **to**  $n$  **O(N)**

4.     **do if**  $f_1[j - 1] + a_{1,j} \leq f_2[j - 1] + t_{2,j-1} + a_{1,j}$   
5.         **then**  $f_1[j] \leftarrow f_1[j - 1] + a_{1,j}$   
6.              $l_1[j] \leftarrow 1$   
7.         **else**  $f_1[j] \leftarrow f_2[j - 1] + t_{2,j-1} + a_{1,j}$   
8.              $l_1[j] \leftarrow 2$  } Compute the values of  $f_1[j]$  and  $l_1[j]$   
9.     **if**  $f_2[j - 1] + a_{2,j} \leq f_1[j - 1] + t_{1,j-1} + a_{2,j}$   
10.         **then**  $f_2[j] \leftarrow f_2[j - 1] + a_{2,j}$   
11.              $l_2[j] \leftarrow 2$   
12.         **else**  $f_2[j] \leftarrow f_1[j - 1] + t_{1,j-1} + a_{2,j}$   
13.              $l_2[j] \leftarrow 1$  } Compute the values of  $f_2[j]$  and  $l_2[j]$

# FASTEST-WAY(a, t, e, x, n)

14. **if**  $f_1[n] + x_1 \leq f_2[n] + x_2$

15.     **then**  $f^* = f_1[n] + x_1$

16.          $l^* = 1$

17.     **else**  $f^* = f_2[n] + x_2$

18.          $l^* = 2$

} Compute the values of  
the fastest time through the  
entire factory

# 4. Construct an Optimal Solution

Alg.: PRINT-STATIONS( $l, n$ )

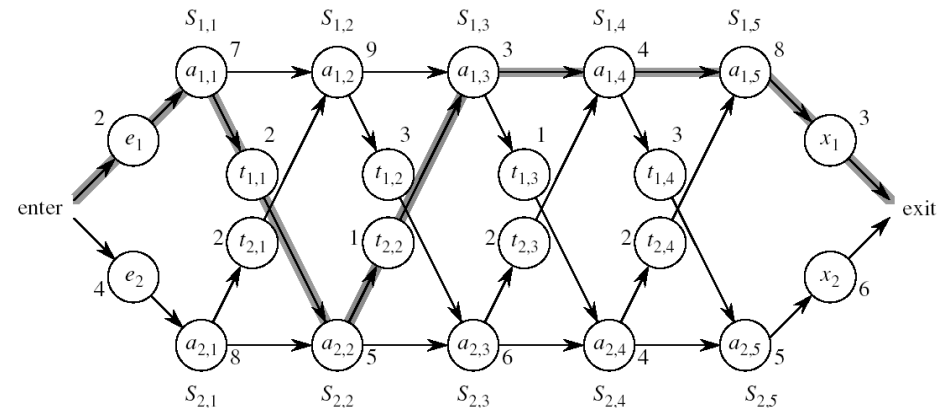
$i \leftarrow l^*$

print “line ”  $i$  “, station ”  $n$

**for**  $j \leftarrow n$  **downto** 2

**do**  $i \leftarrow l_i[j]$

print “line ”  $i$  “, station ”  $j - 1$



	1	2	3	4	5
$f_1[j]/l_1[j]$	9	18 <sup>[1]</sup>	20 <sup>[2]</sup>	24 <sup>[1]</sup>	32 <sup>[1]</sup>
$f_2[j]/l_2[j]$	12	16 <sup>[1]</sup>	22 <sup>[2]</sup>	25 <sup>[1]</sup>	30 <sup>[2]</sup>

$l^* = 1$