
자료구조

Chap 8. Search

2018년 1학기

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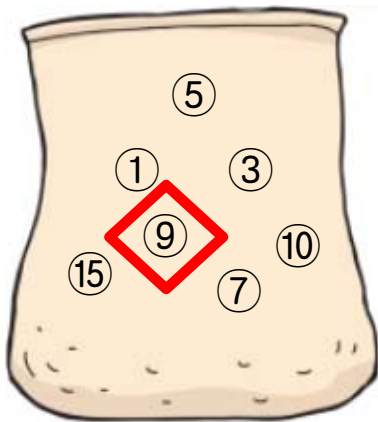
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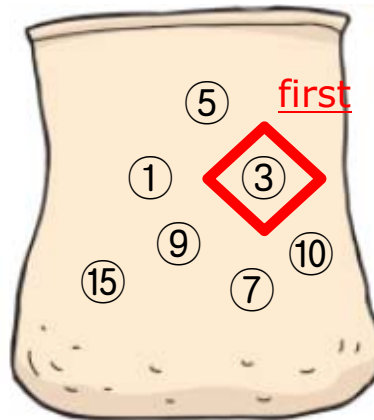
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7.0 Introduction

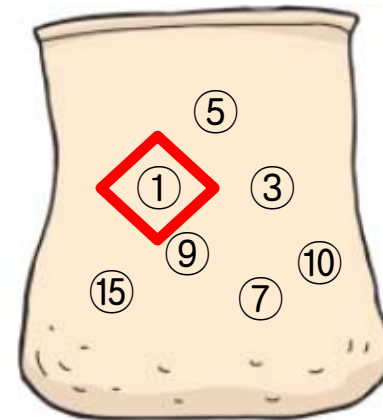
- 3 types of search
 - Find an **arbitrary** element in a given set
 - Find the **first/last** element in a give set
 - Find the **top** (maximum/minimum) element in a given set



Find **arbitrary**



Find **first/last**



Find **top**

7.0 Introduction

- Traversal
 - Find all the elements **reachable** from an element in a given set
 - Used in tree and graph
 - Depth first **search** = depth first **traversal**
 - Breadth first **search** = breadth first **traversal**
 - Inorder **search** = inorder **traversal**
 - Preorder **search** = preorder **traversal**
 - Postorder **search** = postorder **traversal**
-

7.0 Introduction

- All about search (1)

search	operation	Data structure	algorithm	Time complexity		
				search	insert	delete
Arbitrary	Find x	Unsorted array	Linear search	O(n)	O(1)	O(n)
		Sorted array	Linear search	O(n)	O(n)	
			Binary search	O(log n)		
			Interpolation search	O(log n)		
		Binary search tree	Search	O(log n) / O(n)	O(log n) / O(n)	O(log n) / O(n)
		Hash	Hashing	O(1)	O(1)	O(1)
Top	Find max/min	Unsorted array	Find max/min	O(n)	O(1)	O(n)
		Sorted array	Find max/min	O(1)	O(n)	
		Heap	Find max/min	O(1)	O(log n)	O(log n)
Arrival	Find first/ last	Stack	Pop	O(1)	O(1)	O(1)
		Queue	DeleteQ			

7.0 Introduction

- All about search (2)

Type	Data structure	Type of search	Algorithm	Time complexity		
				search	insert	delete
Linear	Unsorted array	Arbitrary	Linear search	O(n)	O(1)	O(n)
		Top	Find max/min			
	Sorted array	Arbitrary	Linear search	O(n)	O(n)	
			Binary search	O(log n)		
			Interpolation search	O(log n)		
		Top	Find max/min	O(1)		
	Stack	Arrival	Pop	O(1)	O(1)	O(1)
	Queue		Push			
Hiearchical	Binary search tree	Arbitrary	Search	O(log n) / O(n)	O(log n) / O(n)	O(log n) / O(n)
	Heap	Top	Find max/min	O(1)	O(log n)	O(log n)
Hash	Hash	Arbitrary	Hashing	O(1)	O(1)	O(1)

7.1 Search on linear data structure

- Linear data structure
 - data structure
 - A data structure whose elements are mapped by indices

index	1	2	3	4	5	6	7	8	9	10	11	12
element	20	42	55	62	78	92	112	132	140	145	150	170

- List
 - Implementation
 - Consecutive VS separate
 - Array VS linked list
 - Index VS pointer
-

7.1 Search on linear data structure

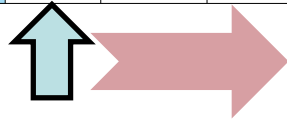
(1) Linear search

- Definition:

- Search an element by visiting the elements from the first one to the last one

- Next element to visit: $(i+1)$

index	1	2	3	4	5	6	7	8	9	10	11	12
element	20	42	55	62	78	92	112	132	140	145	150	170



- Working on unsorted list

- $O(n)$

7.1 Search on linear data structure

(2) Binary search

– Definition:

- Search an element by visiting the element in the center index (mid)

$$\text{mid} = \frac{(\text{high} + \text{low})}{2} = \text{low} + \frac{(\text{high} - \text{low})}{2}$$

index	1	2	3	4	5	6	7	8	9	10	11	12
element	20	42	55	62	78	92	112	132	140	145	150	170



low



mid



high

low: 1
high: 12

$$\text{mid} = 1 + (12-1)/2 = 6.5 \approx 6$$

7.1 Search on linear data structure

(2) Binary search

– Example:

- Search 150 from List[1..12]

index	1	2	3	4	5	6	7	8	9	10	11	12
element	20	42	55	62	78	92	112	132	140	145	150	170



- Step 1. Search 150 from List[1..12]
 - $\text{mid} = 1 + (12-1)/2 = 6.5 = 6$
 - Compare List[6] & 150
 - If $150 > \text{List}[6] \rightarrow$ Search 150 from List[7..12]
 - Else \rightarrow Search 150 from List[1..5]
-

7.1 Search on linear data structure

(2) Binary search

– Example:

- Search 150 from List[1..12]

index	1	2	3	4	5	6	7	8	9	10	11	12
element	20	42	55	62	78	92	112	132	140	145	150	170



- Step 2. Search 150 from List[7..12]
 - $\text{mid} = 7 + (12-7)/2 = 9.5 = 9$
 - Compare List[9] & 150
 - If $150 > \text{List}[9] \rightarrow$ Search 150 from List[10..12]
 - Else \rightarrow Search 150 from List[7..8]

7.1 Search on linear data structure

- Binary search

- Example:

- Search 150 from List[1..12]

index	1	2	3	4	5	6	7	8	9	10	11	12
element	20	42	55	62	78	92	112	132	140	145	150	170



- Step 3. Search 150 from List[10..12]

- $\text{mid} = 10 + (12-10)/2 = 11$
 - Compare List[11] & 150
 - If $150 > \text{List}[11] \rightarrow$ Search 150 from List[12]
 - Else \rightarrow Search 150 from List[10]
 - If $\text{List}[11] == 150 \rightarrow$ Bingo!!
-

7.1 Search on linear data structure

(2) Binary search

– Example:

- Search 150 from List[1..12]

index	1	2	3	4	5	6	7	8	9	10	11	12
element	20	42	55	62	78	92	112	132	140	145	150	170


(1)


(2)


(3)


– Problem of binary search?


7.1 Search on linear data structure


(2) Binary search

– Example: Search 150 from List[1..12]

index	1	2	3	4	5	6	7	8	9	10	11	12
element	20	42	55	62	78	92	112	132	140	145	150	170


(1)


(2)


(3)

– Problem of binary search?

- 150 (key to find) is closer to 170 (high) than to 20 (low)
($|150 - 170| < |150 - 20|$)
 - Searching from high is more efficient than searching from mid or low
-

7.1 Search on linear data structure

(3) Interpolation search

- Search an element by visiting the element in the center index (mid)

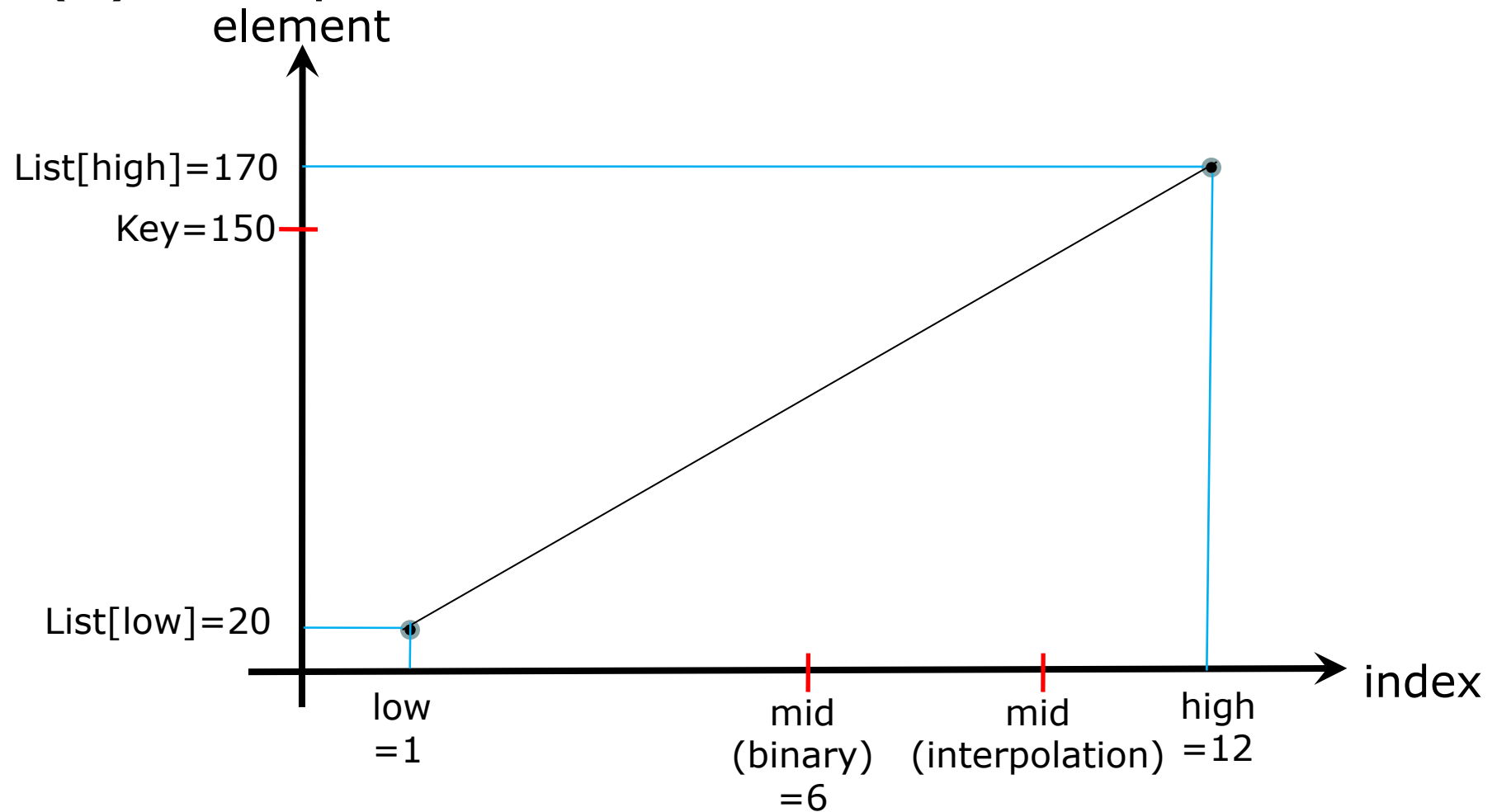
$$\text{mid} = \text{low} + \frac{(\text{Key} - \text{List}[\text{low}])}{(\text{List}[\text{high}] - \text{List}[\text{low}])} (\text{high} - \text{low})$$

- In binary search,

$$\text{mid} = \text{low} + \frac{1}{2} (\text{high} - \text{low})$$

7.1 Search on linear data structure

(3) Interpolation search



7.1 Search on linear data structure

(3) Interpolation search

– Example: Search 150 from List[1..12]

index	1	2	3	4	5	6	7	8	9	10	11	12
element	20	42	55	62	78	92	112	132	140	145	150	170



$$\text{mid} = \text{low} + \frac{(\text{Key} - \text{List}[\text{low}])}{(\text{List}[\text{high}] - \text{List}[\text{low}])} (\text{high} - \text{low})$$

- Step 1. Search 150 from List[1..12]
 - $\text{mid} = 1 + ((150 - 20) / (170 - 20)) * (12 - 1) = 10.5 = 10$
 - Compare List[10] & 150
 - If $150 > \text{List}[10] \rightarrow$ Search 150 from List[11..12]
 - Else \rightarrow Search 150 from List[1..9]
-

7.1 Search on linear data structure

(3) Interpolation search

– Example: Search 150 from List[1..12]

index	1	2	3	4	5	6	7	8	9	10	11	12
element	20	42	55	62	78	92	112	132	140	145	150	170



$$\text{mid} = \text{low} + \frac{(\text{Key} - \text{List}[\text{low}])}{(\text{List}[\text{high}] - \text{List}[\text{low}])} (\text{high} - \text{low})$$

- Step 2. Search 150 from List[11..12]
 - $\text{mid} = 11 + ((150 - 150) / (170 - 150)) * (12 - 11) = 11$
 - Compare List[11] & 150
 - If $150 > \text{List}[11] \rightarrow$ Search 150 from List[12]
 - Else \rightarrow None
 - If $150 == \text{List}[11] \rightarrow$ Bingo!!

7.1 Search on linear data structure

- Summary

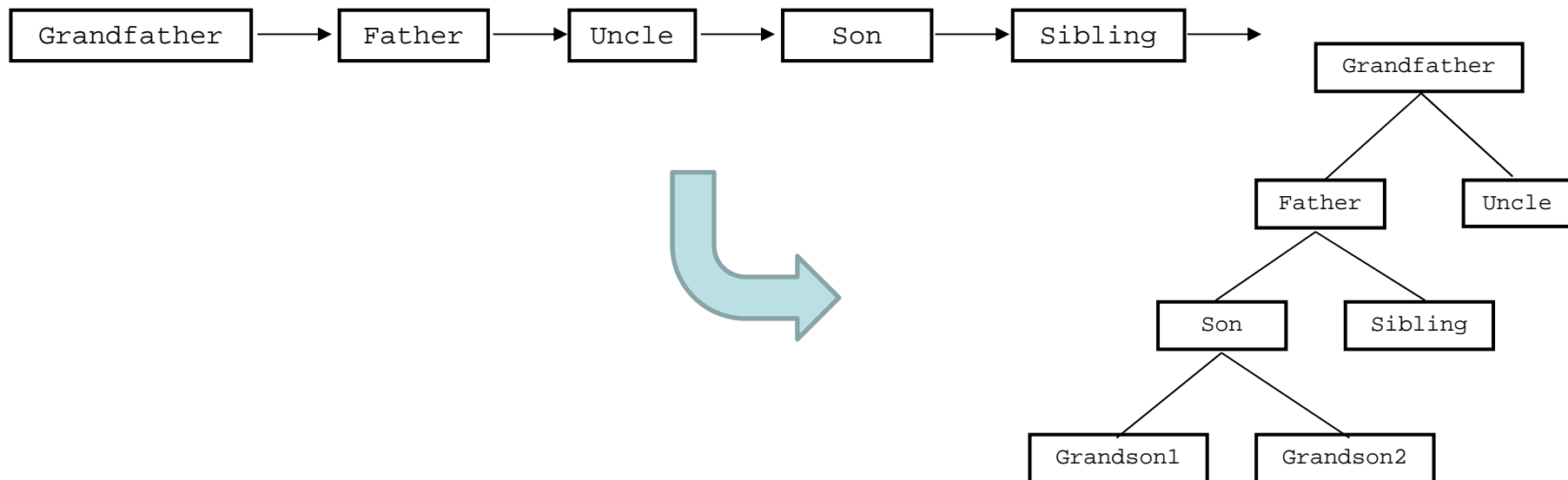
	Linear search	Binary search	Interpolation search
Next one to visit	$i + 1$	$low + \frac{1}{2}(high - low)$	$low + \frac{(Key - List[low])}{(List[high] - List[low])}(high - low)$
Time complexity	$O(n)$	$O(\log n)$	Improved $O(\log n)$
On sorted list?	No	Yes	Yes
Depends on implementation?	No	Yes	Yes

7.2 Search on hierarchical data structure

- Hierarchical data structure
 - Binary search tree
 - Heap
 - AVL tree
 - B+ tree
-

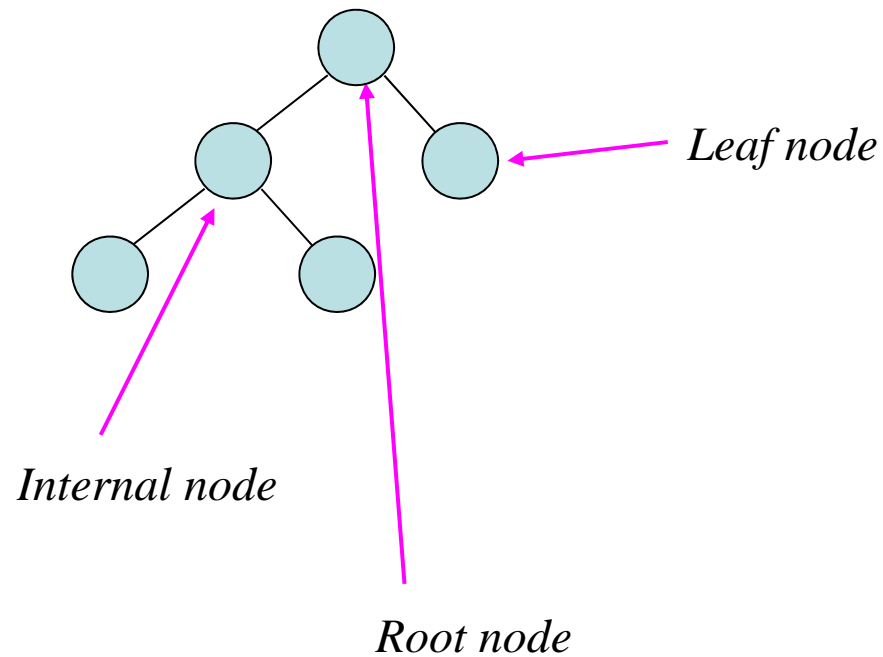
7.2 Search on hierarchical data structure

- Hierarchical data structure
 - Limitations of linear data structure?
 - Representation of “family record”
 - grandfather
 - father, uncle
 - son, sibling
 - grandson1, grandson2



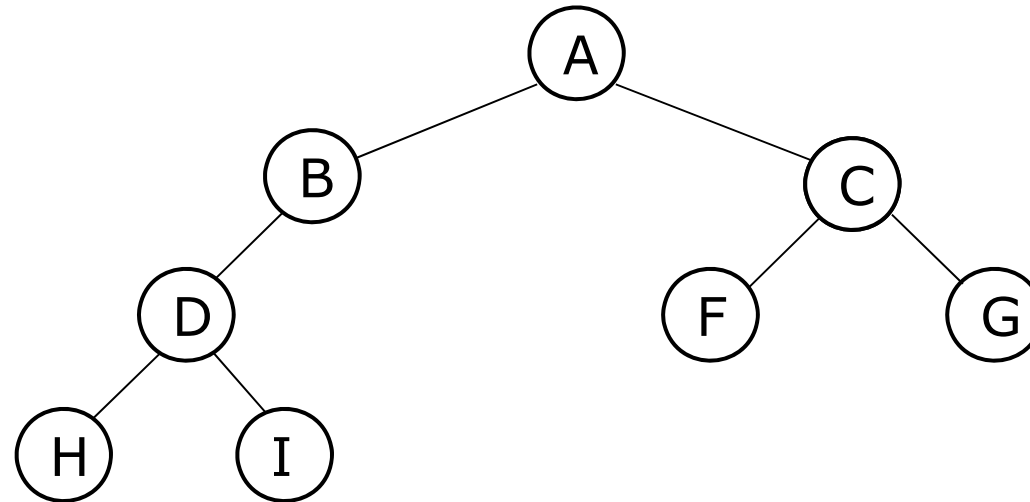
7.2 Search on hierarchical data structure

- Hierarchical data structure
 - Tree



7.2 Search on hierarchical data structure

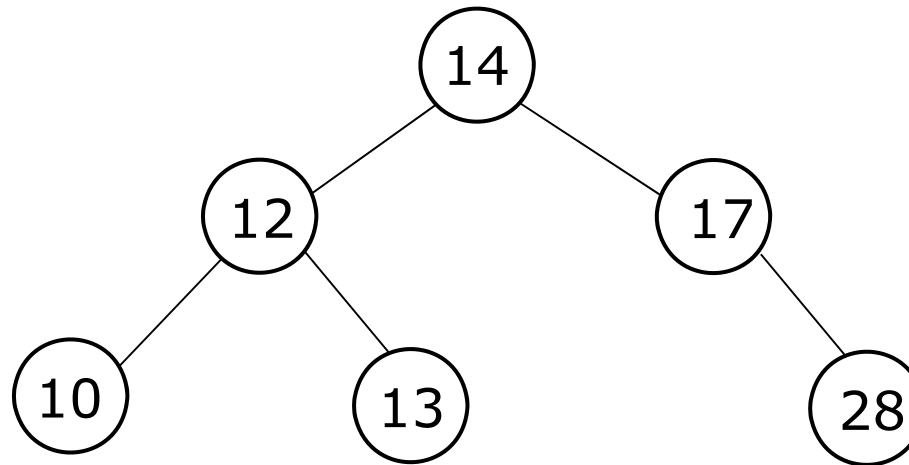
- Hierarchical data structure
 - Binary tree
 - A tree whose nodes have at most two child nodes



- Tree traversal algorithm: $O(n)$
 - Pre-order search
 - In-order search
 - Post-order search
-

7.2 Search on hierarchical data structure

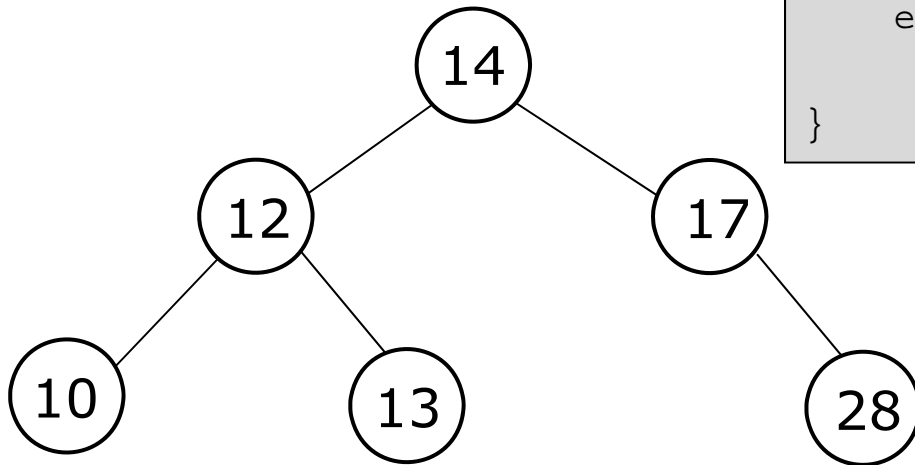
- Binary search tree (BST)
 - A binary tree (may be empty)
 - Satisfies the following properties
 - Each node has exactly one key, which is distinct
 - The keys in the left subtree $<$ the key in root
 - The keys in the right subtree $>$ the key in root
 - The left and right subtrees are also binary search tree



7.2 Search on hierarchical data structure

- Binary search tree (BST)
 - Search algorithm

```
element search ( BST root, KEY key )  
{  
    if ( !root )  
        return NULL;  
    if ( key == root->key )  
        return root->data;  
    if ( key < root->key )  
        return search ( root->lchild, key );  
    else  
        return search ( root->rchild, key );  
}
```



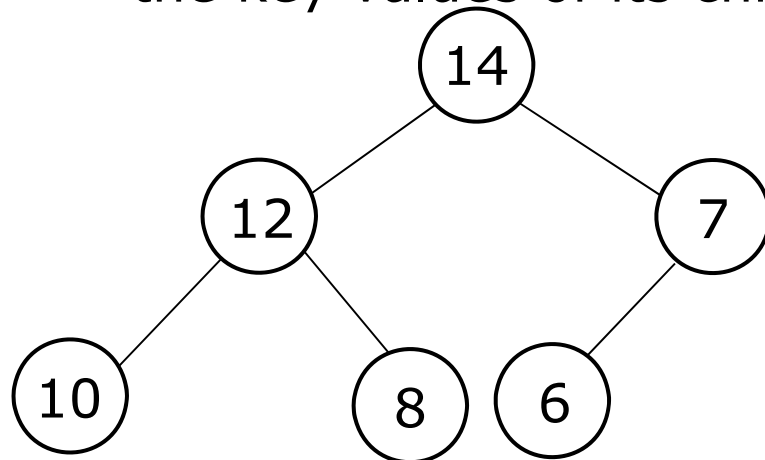
7.2 Search on hierarchical data structure

- Binary search tree (BST)
 - Time complexity?
 - $O(\log_2 n)$
 - Is it better than binary search on list?
 - Why binary search tree is better than sorted list?

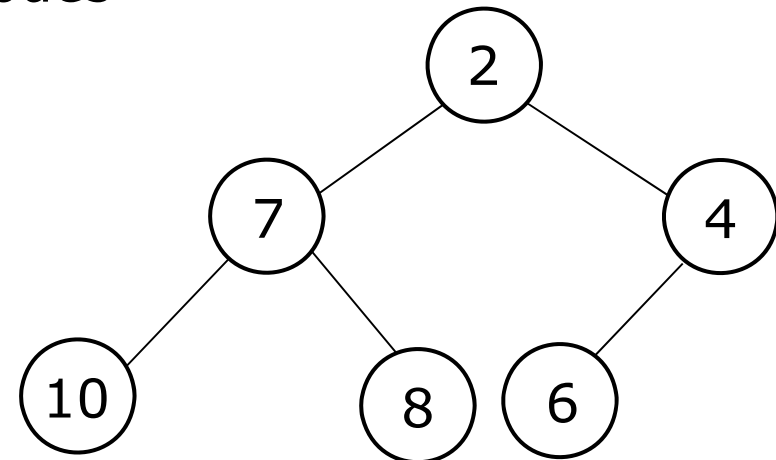
```
element search ( BST root, KEY key )
{
    if ( !root )
        return NULL;
    if ( key == root->key )
        return root->data;
    if ( key < root->key )
        return search ( root->lchild, key );
    else
        return search ( root->rchild, key );
}
```

7.2 Search on hierarchical data structure

- Heap
 - Priority queue
 - The element to be deleted is the one with the highest (or lowest) priority
 - A complete binary tree
 - Max heap (**Min heap**)
 - The key value in each node is no *smaller* (**greater**) than the key values of its child nodes



Max heap



Min heap

7.2 Search on hierarchical data structure

- Comparison of the data structures

	Sorted list	BST	Heap
What is it?	A list whose elements are sorted (array VS linked list)	A binary tree...	A complete binary tree...
Arbitrary	Sorted array: $O(\log n)$ Linked list: $O(n)$	$O(\log n)/O(n)$	-
Top	Sorted array: $O(1)$ Linked list: $O(1)$	$O(\log n)/O(n)$	$O(1)$
Insert/Delete	Array: $O(n)$ Linked list: $O(n)$	$O(\log n)/O(n)$	$O(\log n)$

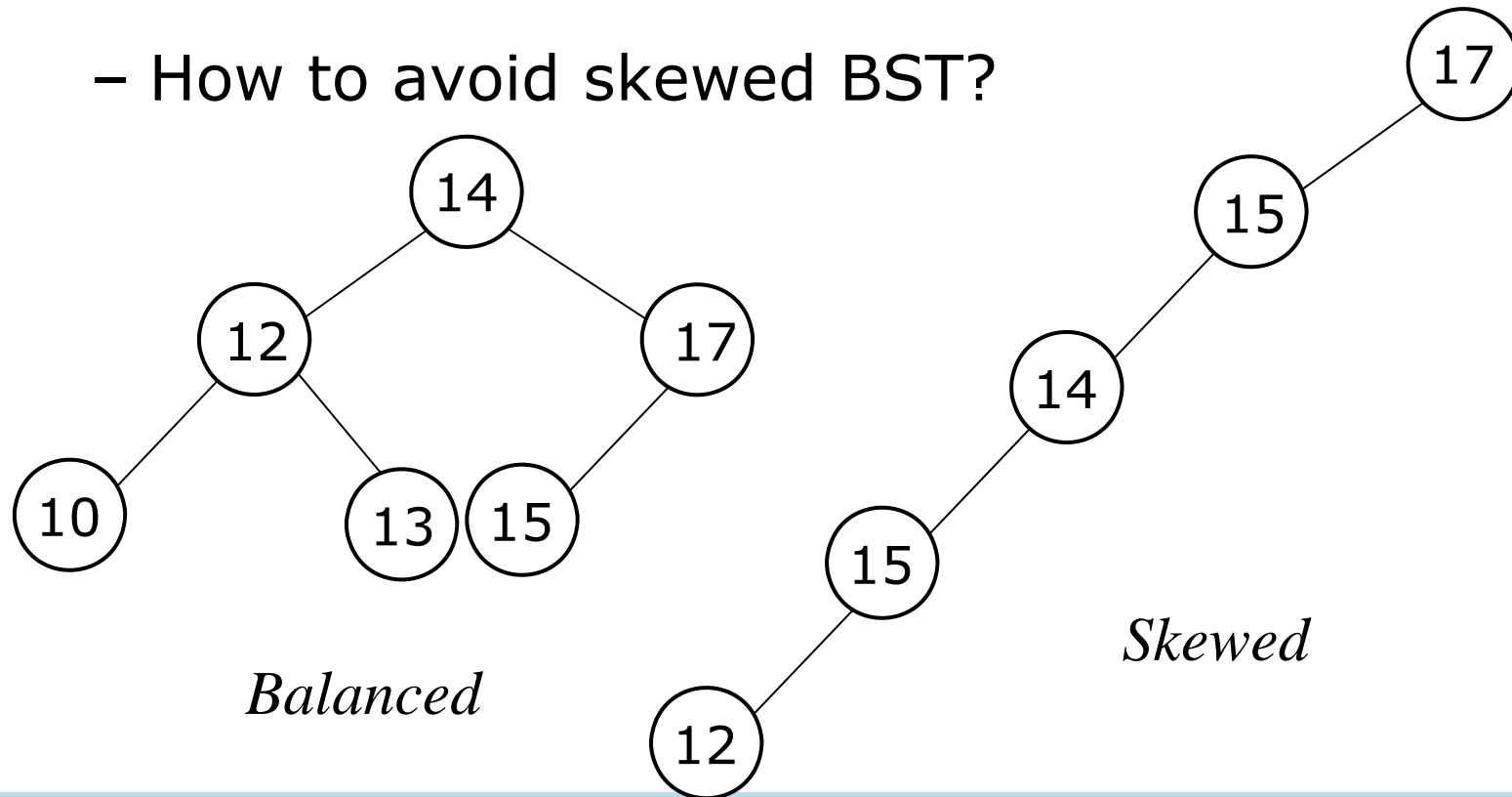
7.2 Search on hierarchical data structure

- Balanced Binary Search Tree (BBST)
 - Self-balancing search tree
 - Height-balanced search tree
 - a search tree that attempts to keep its *height* as small as possible at all times, automatically
 - (1) AVL tree
 - (2) Red-black tree
 - (3) 2-3 tree
 - (4) B+ tree
-

7.2 Search on hierarchical data structure

(1) AVL tree

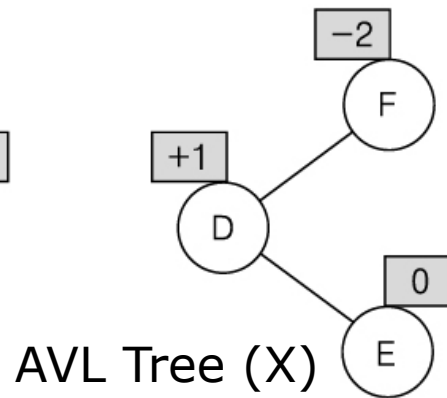
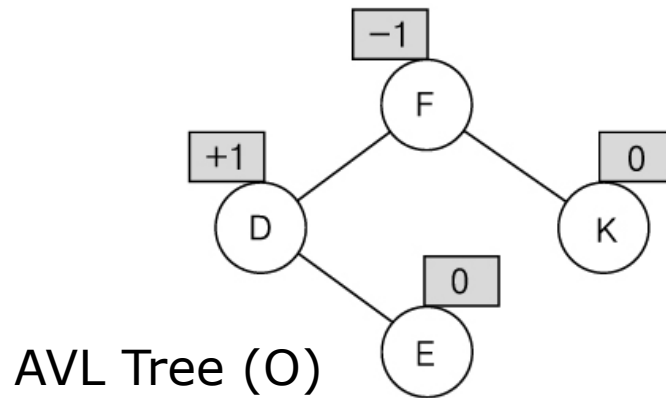
- Weakness of binary search tree
 - On a skewed BST, all operations take $O(n)$
- How to avoid skewed BST?



7.2 Search on hierarchical data structure

(1) AVL tree

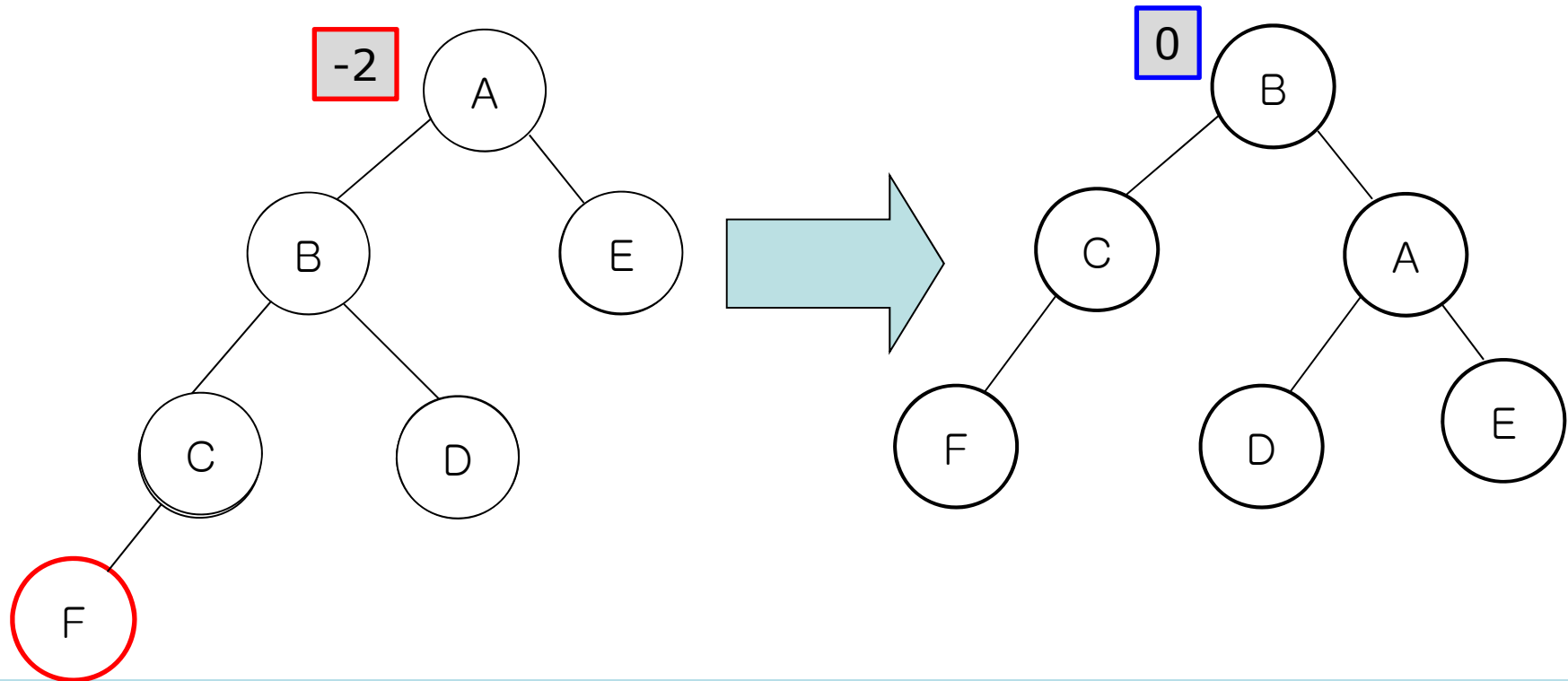
- G. M. Adelson-Velskii & E. M. Landis
- the heights of the two child subtrees of any node differ by at most one
- Balance factor
= Height of right subtree – Height of left subtree



7.2 Search on hierarchical data structure

(1) AVL tree

- After insertion/deletion, balance can be broken
- Using balancing operations, the tree is modified to keep the balance



7.2 Search on hierarchical data structure

(1) AVL tree

- Balancing operations

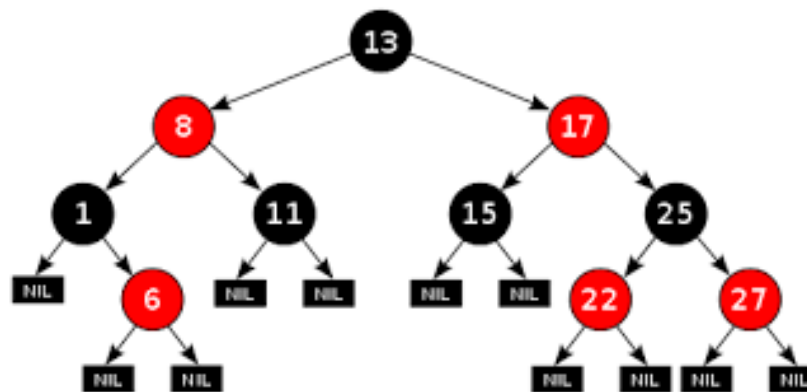
- Single left rotate
- Single right rotate

- Double left rotate
- Double right rotate

7.2 Search on hierarchical data structure

(2) Red-black tree

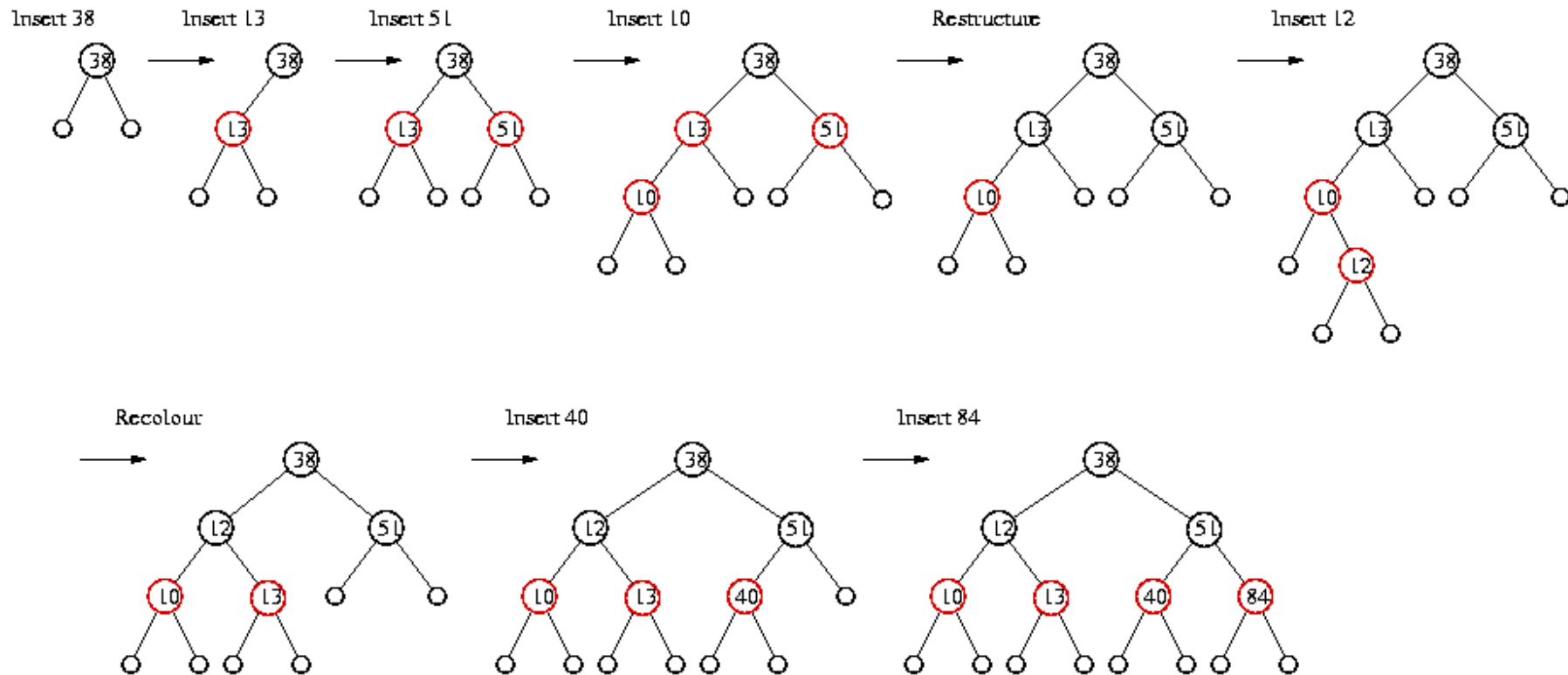
- L. J. Guibas and R. Sedgwick (1978)
- Five properties
 - Each node is either red or black
 - The root is black
 - All leaf nodes (NIL node) are black
 - If a node is red, then its both child nodes are black
 - Every path from a given node to all of its descendent NIL nodes contain the same number of black nodes



7.2 Search on hierarchical data structure

(2) Red-black tree

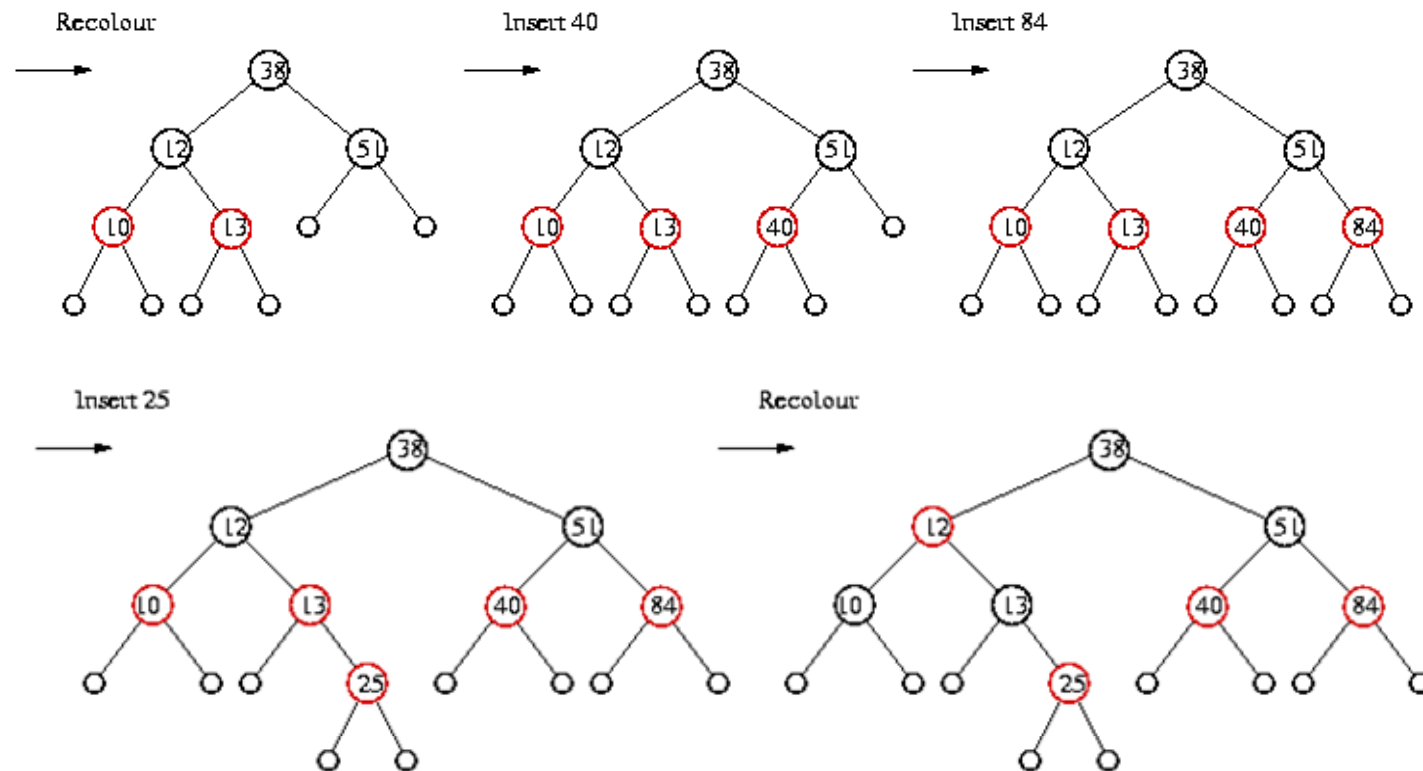
Insertions: 38, 13, 51, 10, 12, 40, 84, 25



7.2 Search on hierarchical data structure

(2) Red-black tree

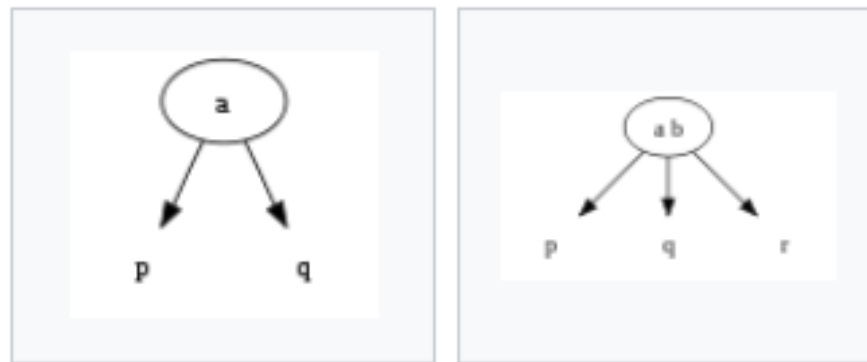
Insertions: 38, 13, 51, 10, 12, 40, 84, 25



7.2 Search on hierarchical data structure

(3) 2-3 tree

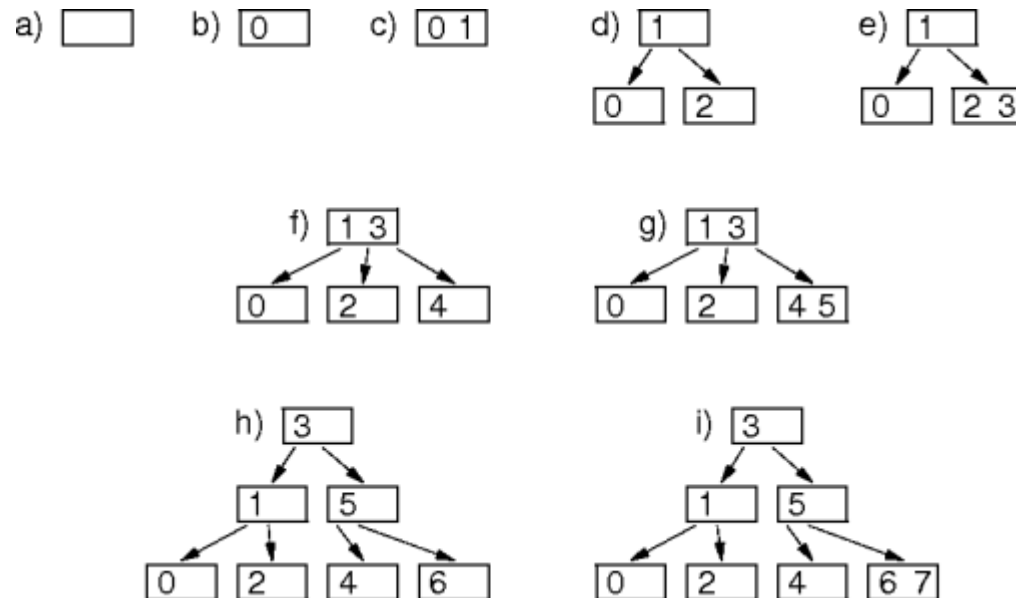
- J. Hopcroft (1970)
- A search tree whose nodes are either 2-node or 3-node.
 - 2-node
 - One key value with two child nodes
 - 3-node
 - Two key values with three child nodes



7.2 Search on hierarchical data structure

(3) 2-3 tree

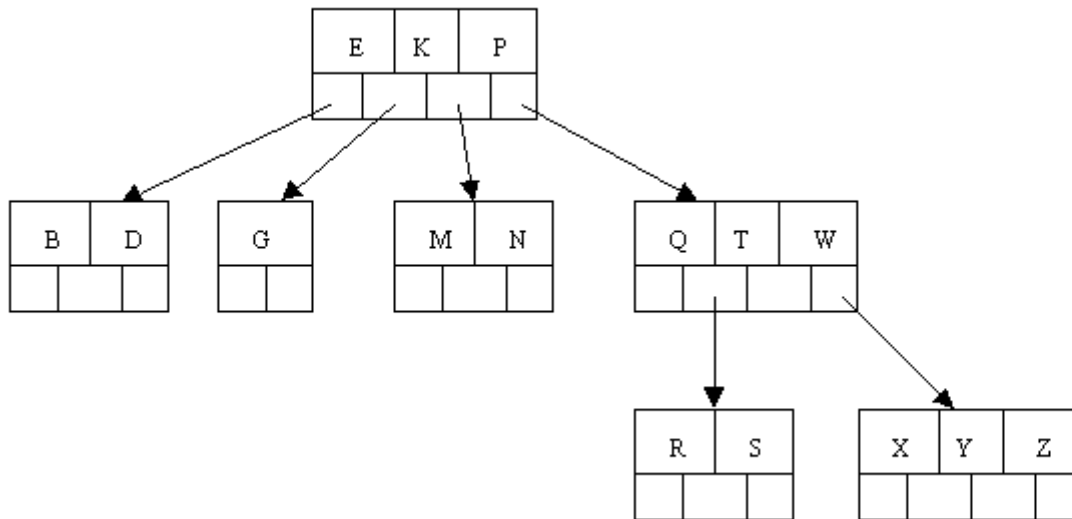
– Insert 0, 1, 2, 3, 4, 5, 6, 7



7.2 Search on hierarchical data structure

(4) B+ tree

- A multi-way tree
 - Each node stores
 - k keys
 - (k+1) subtrees
- Time complexity: $O(\log_k n)$



7.3 Search on graph

- Travesal
 - Find a vertex of a graph that contains the key element
 - Depth-first traversal
 - Breadth-first traversal
-

7.4 Hashing

- Why hashing?
 - 이진 탐색
 - $O(\log n)$ 의 탐색 시간
 - 자료의 크기에 따라서 검색 시간이 결정됨
 - 자료의 크기에 상관없이 실시간에 탐색이 수행되어야 하는 경우가 있음
 - $O(1)$ 의 탐색 시간을 보장하는 탐색 알고리즘
-

7.4 Hashing

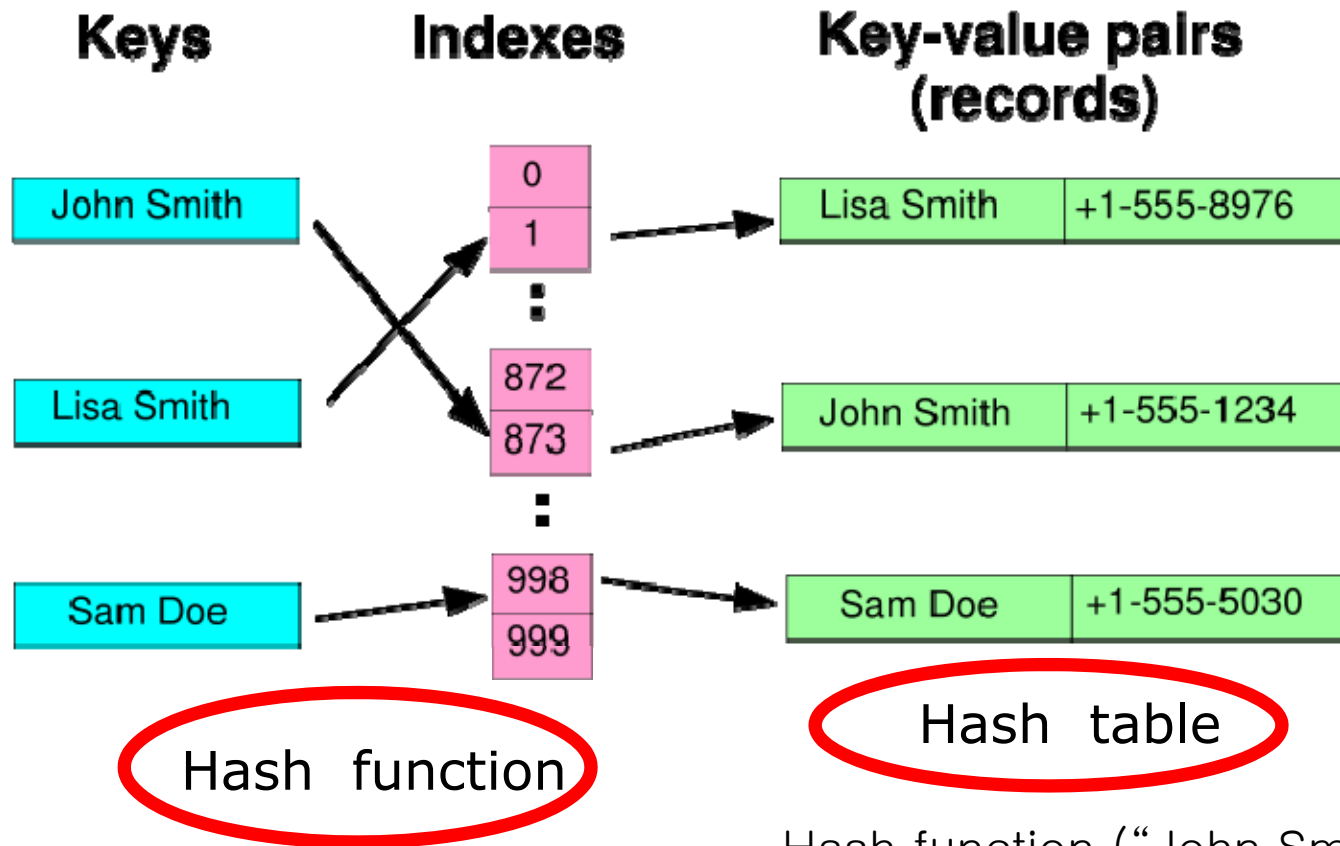
- Definition

“모든 키의 레코드를 산술 연산에 의해 한 번에 바로 접근할 수 있는 기법”

- Hash function
 - Hash index
 - Hash table
 - Collision & collision resolution
-

7.4 Hashing

- Key concept of hashing



Hash function ("John Smith") = 873

Hash function ("Sam Doe") = 998

7.4 Hashing

- Hash function (1)

- ① 자릿수 선택 (digit selection)

- 키의 값 중에서 일부 자릿수만 골라내서 인덱스를 생성하는 함수
 - 예
 - 13자리 주민등록번호 중 홀수 자릿수만 선택

$$h(8812152051218) = 8112528$$

- 충돌이 발생하는 경우는?

$$h(8812152051218) = 8112528$$

$$h(8711142152238) = 8112528$$

7.4 Hashing

- Hash function (2)

- ② 자릿수 접기 (digit folding)

- 키의 각각의 자릿수를 더해서 인덱스를 생성하는 함수
 - 예

$$h(8812152051218) = 8 + 8 + 1 + \dots + 8 = 44$$

- 충돌이 발생하는 경우는?

$$\begin{aligned} h(8812152051218) &= \\ 8+8+1+2+1+5+2+0+5+1+2+1+8 &= 44 \end{aligned}$$

$$\begin{aligned} h(8713142152208) &= \\ 8+7+1+3+1+4+2+1+5+2+2+0+8 &= 44 \end{aligned}$$

7.4 Hashing

- Hash function (3)

- ③ 모듈로 연산 (modulo function)

- 키를 해쉬 테이블의 크기로 나눈 나머지를 인덱스로 생성하는 함수

- $h(\text{KEY}) = \text{KEY} \bmod \text{TableSize}$

- 충돌이 발생하는 경우는?

- $h(8812152051218) = 8812152051218 \% 100 = 18$

- $h(8713142152218) = 8713142152218 \% 100 = 18$



7.4 Hashing

- 충돌 (collision)

- 서로 다른 키를 가진 레코드가 해쉬 함수에 의해서 동일한 인덱스로 대응되는 현상

- 예

- Hash function:

- $$H(K) = K \bmod m, \text{ where } m = 17$$

- For $K_1 = 18$ & $K_2 = 171$,

- $H(K_1) = 18 \bmod 17 = 1$

- $H(K_2) = 171 \bmod 17 = 1$

- Collision !!!

7.4 Hashing

- 충돌

- 예

- $K_1 = 18$ & $K_2 = 171$,
 - $H(K_1) = 18 \bmod 17 = 1$
 - $H(K_2) = 171 \bmod 17 = 1$

0	1	2	3	4	5	6	7	8	9
	18								

...

18 171

7.4 Hashing

- 충돌 해소
 - 충돌이 발생한 레코드를 다른 주소에 저장하는 기법
 - 열린 어드레싱 (open addressing)
 - 충돌이 발생한 레코드를 저장할 다른 주소를 찾는 방법
 - 레코드의 주소 (address)가 변경될 수 있기 때문에 열린 (open) 어드레싱이라고 함
 - 선형 탐사 (linear probing)
 - 제곱 탐사 (quadratic probing)
 - 이중 해시 (double hash)
 - 닫힌 어드레싱 (closed addressing)
 - 충돌이 발생한 레코드를 동일한 주소에 저장하는 방법
 - 주소가 변경되지 않으므로 닫힌 (closed) 어드레싱이라고 함
 - 버킷 (bucket)
 - 별도 체인 (separate chain)
-

7.4 Hashing

- 열린 어드레싱 (1)

- ① 선형 탐사 (linear probing)

- 충돌이 일어나면 그 다음 빈 곳에 원소를 저장함
 - $T[h(KEY)]$ 가 점유되어 있을 때,
 - $T[h(KEY) + 1]$
 - $T[h(KEY) + 2]$
 - ...
 - 배열의 끝을 만나면 다시 처음으로 되돌아와서 거기서부터 빈자리를 찾음
 - $T[n-1]$
 - $T[0]$

7.4 Hashing

- 열린 어드레싱 (1)
 - ① 선형 탐사 (linear probing)
 - 예: $h(x) = x \% 31$

0	1	2	3	4	5	6	7	8	9	...
			65							

↑
65

7.4 Hashing

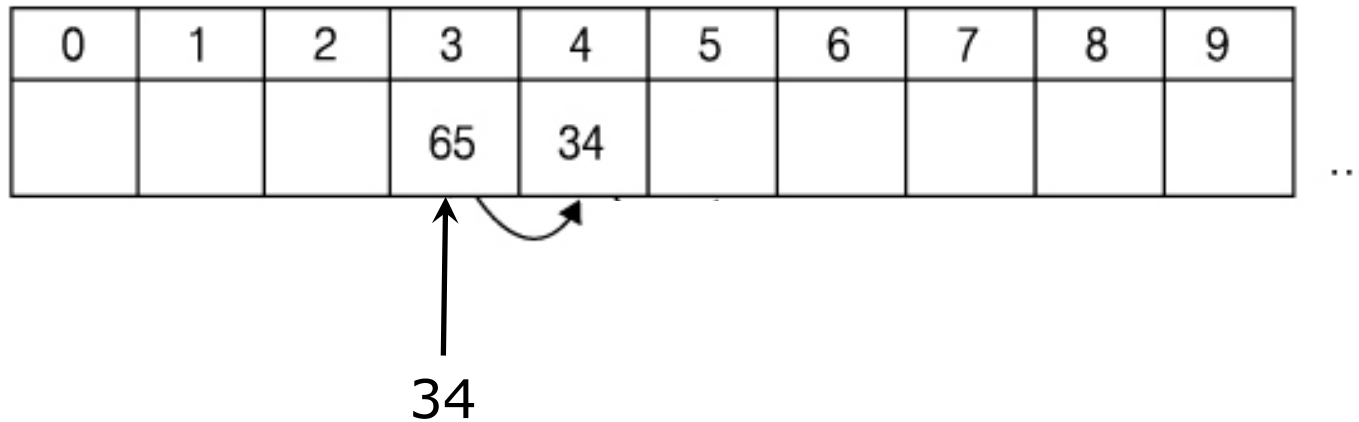
- 열린 어드레싱 (1)
 - ① 선형 탐사 (linear probing)
 - 예: $h(x) = x \% 31$
 - 65를 삽입 $\rightarrow 65 \% 31 = 3$
 - 34를 삽입 $\rightarrow 34 \% 31 = 3$

0	1	2	3	4	5	6	7	8	9	...
			65							

↑
34

7.4 Hashing

- 열린 어드레싱 (1)
 - ① 선형 탐사 (linear probing)
 - 예: $h(x) = x \% 31$
 - 65를 삽입 $\rightarrow 65 \% 31 = 3$
 - 34를 삽입 $\rightarrow 34 \% 31 = 3$

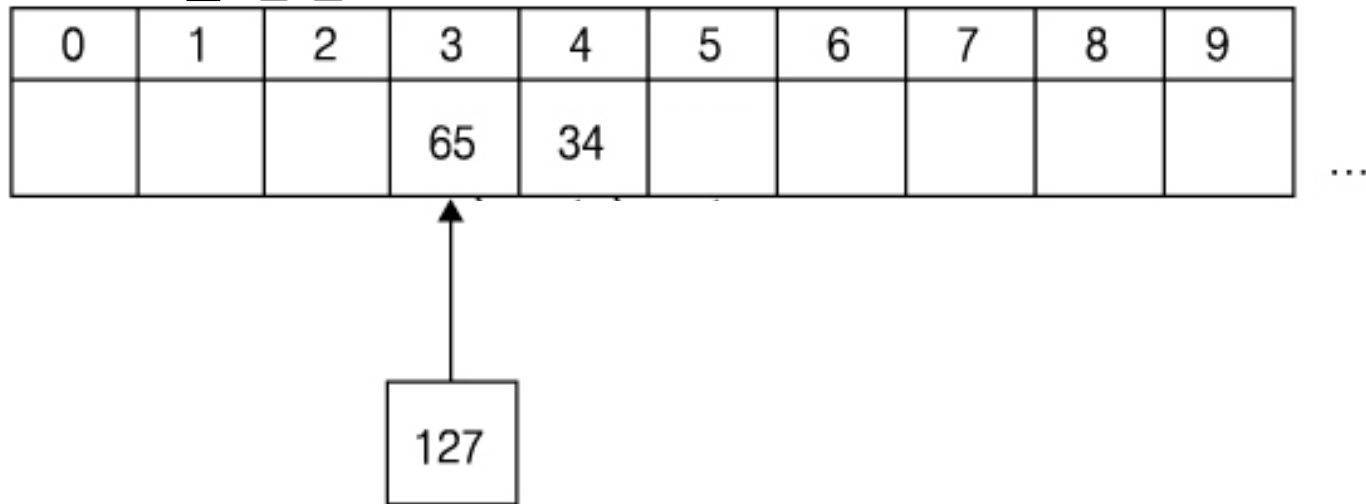


7.4 Hashing

- 열린 어드레싱 (1)

- ① 선형 탐사 (linear probing)

- 예: $h(x) = x \% 31$
 - 65를 삽입 $\rightarrow 65 \% 31 = 3$
 - 34를 삽입 $\rightarrow 34 \% 31 = 3$
 - 127을 삽입 $\rightarrow 127 \% 31 = 3$

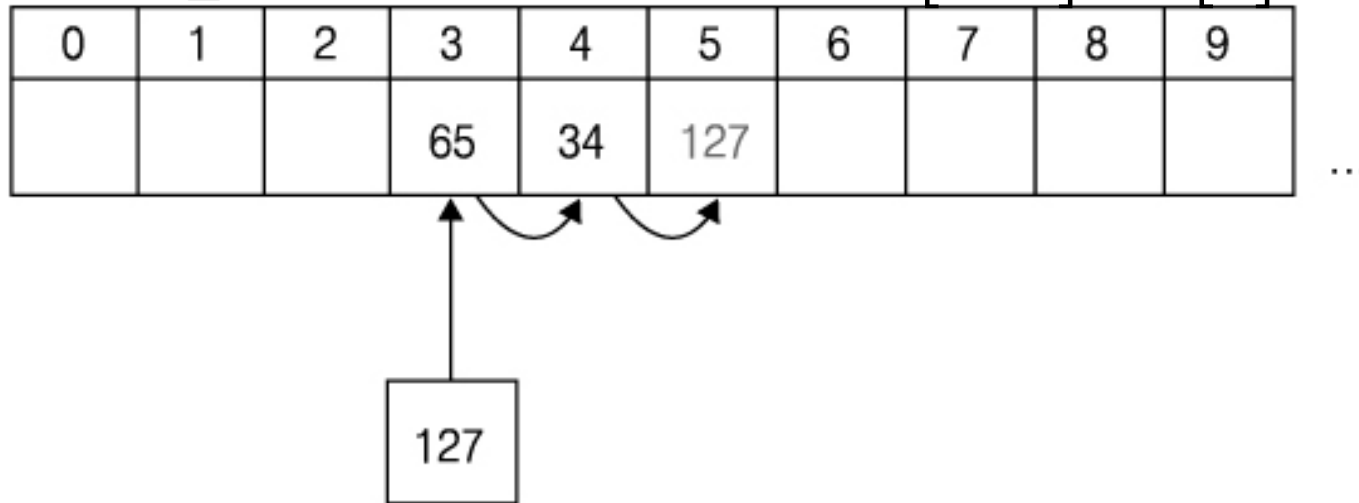


7.4 Hashing

- 열린 어드레싱 (1)

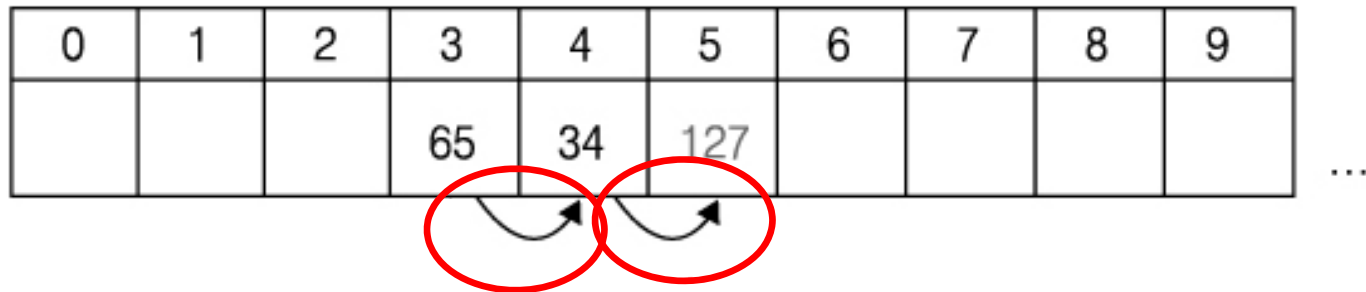
- ① 선형 탐사 (linear probing)

- 예: $h(x) = x \% 31$
 - 65를 삽입 $\rightarrow 65 \% 31 = 3$
 - 34를 삽입 $\rightarrow 34 \% 31 = 3 \rightarrow T[3+1] = T[4]$
 - 127을 삽입 $\rightarrow 127 \% 31 = 3 \rightarrow T[3+2] = T[5]$



7.4 Hashing

- 열린 어드레싱 (1)
 - ① 선형 탐사 (linear probing)
 - 태그 (tag)
 - 선형 탐사에서 다음 원소를 가리키는 포인터



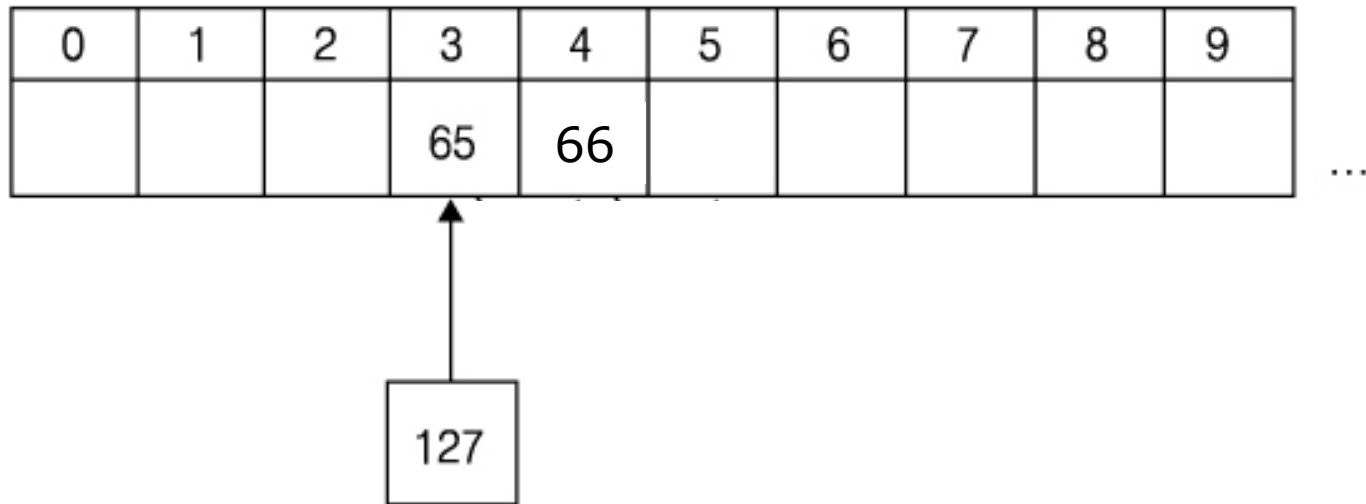
7.4 Hashing

- 열린 어드레싱 (1)

- ① 선형 탐사 (linear probing)

- 태그 (tag)의 필요성 (1)

- 다음 자리 ($h(\text{key})+1$)에 이미 다른 원소가 존재할 때



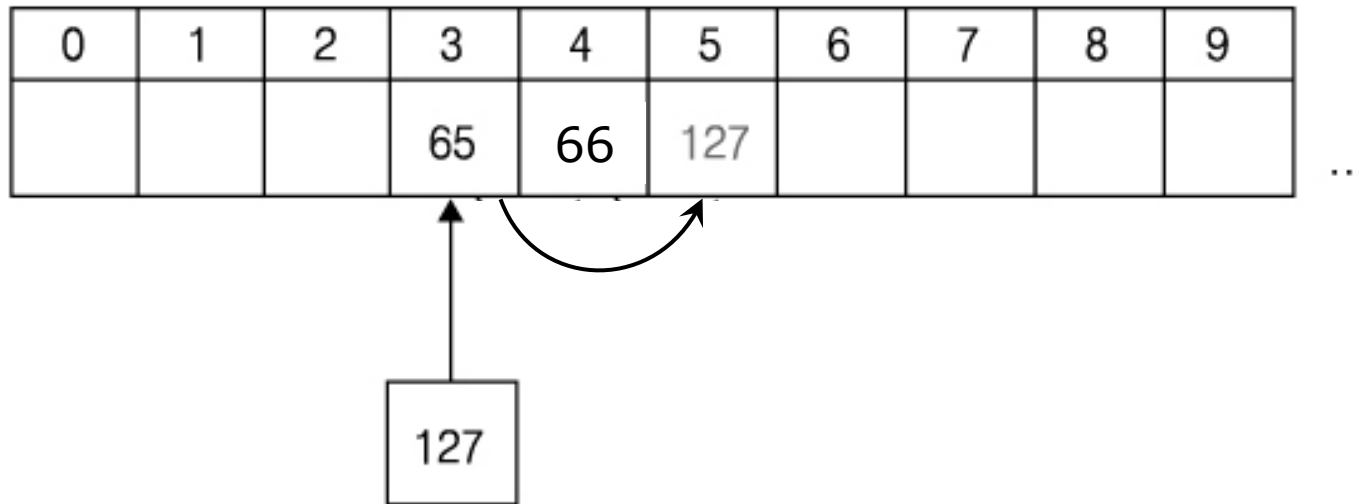
7.4 Hashing

- 열린 어드레싱 (1)

- ① 선형 탐사 (linear probing)

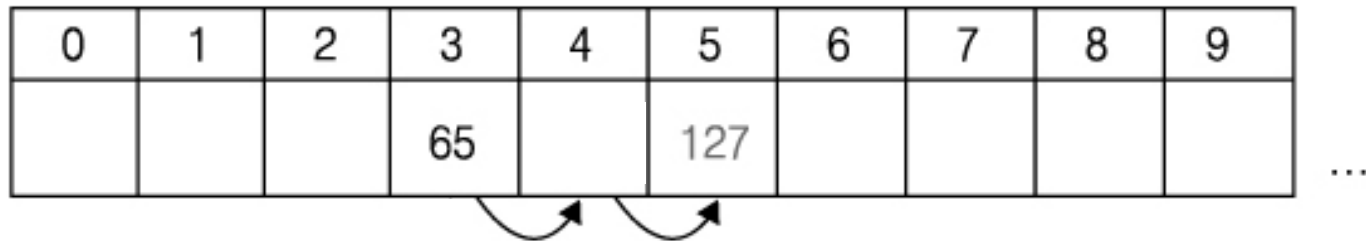
- 태그 (tag)의 필요성 (1)

- 다음 자리 ($h(\text{key})+1$)에 이미 다른 원소가 존재할 때
 - 다음 원소의 위치를 가리킴



7.4 Hashing


- 열린 어드레싱 (1)
 - ① 선형 탐사 (linear probing)
 - 태그 (tag)의 필요성 (2)
 - 중간의 원소를 삭제할 때



7.4 Hashing

- 열린 어드레싱 (1)
 - ① 선형 탐사 (linear probing)
 - 태그 (tag)의 필요성 (2)
 - 중간의 원소를 삭제할 때
 - 태그를 수정함

0	1	2	3	4	5	6	7	8	9	
			65		127					...



7.4 Hashing

- 열린 어드레싱 (1)
 - ① 선형 탐사 (linear probing)
 - 단점: 클러스터링 (clustering)
 - 레코드가 분산되지 않고 군집되는 현상

0	1	2	3	4	5	6	7	8	9
			65	34	127				

...

7.4 Hashing

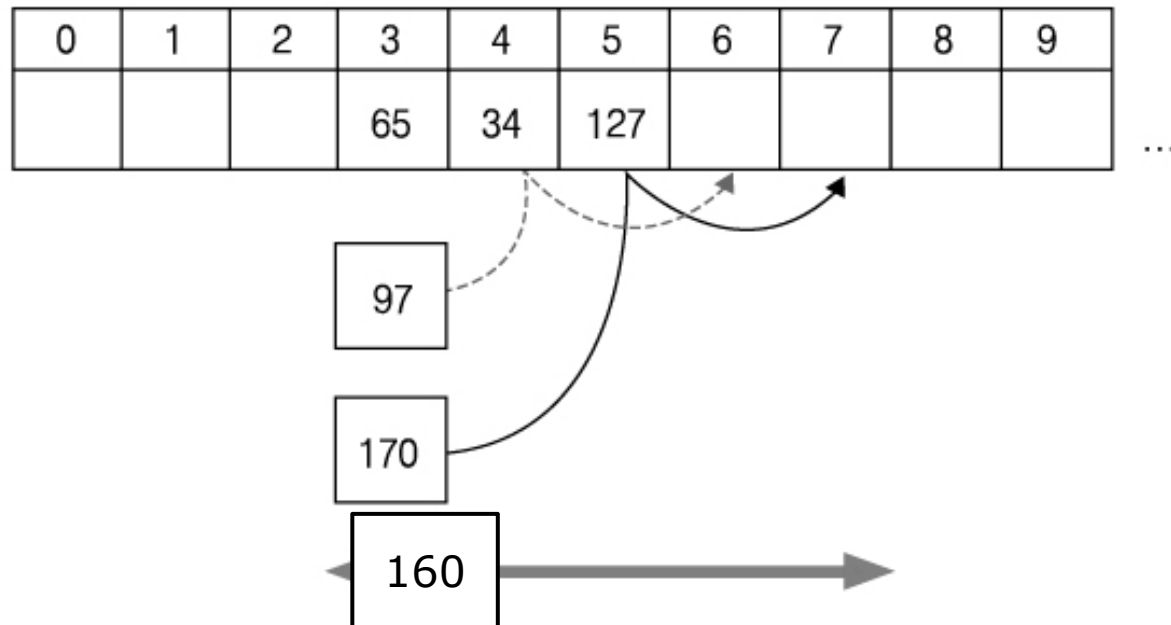
- 열린 어드레싱 (1)

- ① 선형 탐사 (linear probing)

- 단점: 클러스터링 (clustering)

- 예: 97을 삽입: $97 \% 31 = 4$

- 예: 160을 삽입: $160 \% 31 = 5$



7.4 Hashing

- 열린 어드레싱 (2)

- ② 제곱 탐사 (quadratic probing)

- 충돌이 일어날 때 바로 그 뒤에 넣지 않고 조금 간격을 두고 삽입
 - $T[h(KEY)]$ 가 점유되어 있을 때,
 - $T[h(KEY) + 1]$
 - $T[h(KEY) + 2^2]$
 - ...

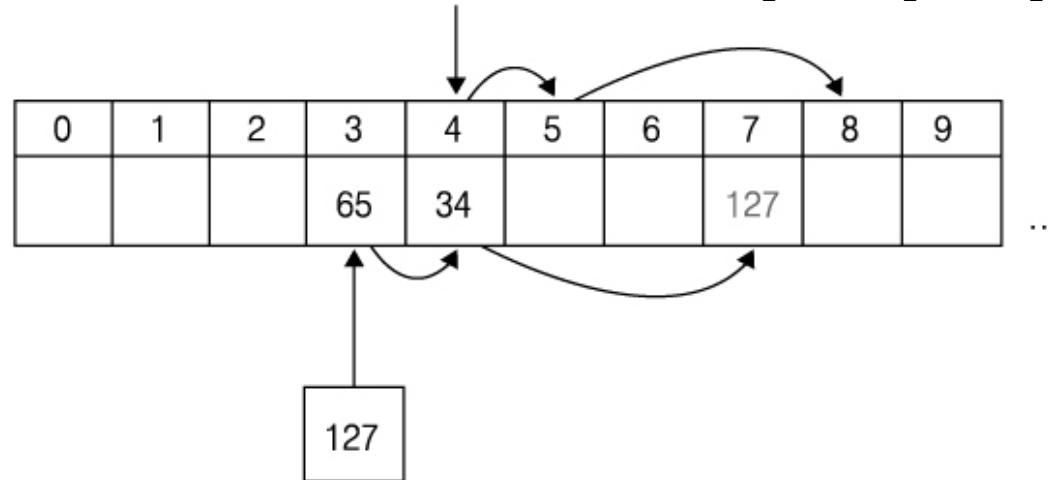
7.4 Hashing

- 열린 어드레싱 (2)

- ② 제곱 탐사 (quadratic probing)

- 충돌이 일어날 때 바로 그 뒤에 넣지 않고 조금 간격을 두고 삽입

- 예: $h(x) = x \% 31$
- 65를 삽입 $\rightarrow 65\%31 = 3$
- 34를 삽입 $\rightarrow 34\%31 = 3 \rightarrow T[3+1] = T[4]$
- 127을 삽입 $\rightarrow 127\%31 = 3 \rightarrow T[3+2^2] = T[7]$

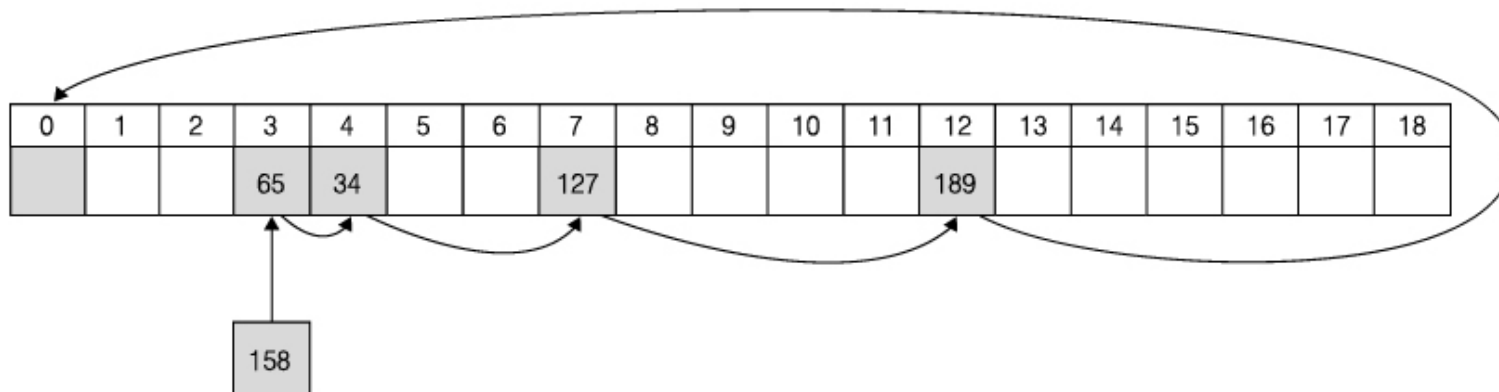


7.4 Hashing

- 열린 어드레싱 (2)

- ② 제곱 탐사 (quadratic probing)

- 클러스터링을 피할 수 있는가?
 - 연속적인 배열을 피할 수 있음
 - 동일한 키를 가진 레코드는 동일한 자리에 삽입됨
 - 예: 158의 경우, 65, 34, 127, 189 다음의 자리에 삽입
 - 궁극적으로는 클러스터링을 피할 수 없음
- ➔ 2차 클러스터링



7.4 Hashing

- 열린 어드레싱 (3)
 - ③ 이중 해쉬 (double hash)
 - 제곱탐사의 단점인 2차 클러스터를 방지
 - 두 개의 해쉬 함수 h_1 , h_2 를 사용
 - h_1 은 주어진 키로부터 인덱스를 계산하는 해쉬 함수
 - h_2 는 충돌 시 탐색할 인덱스의 간격(Step Size)을 의미
-

7.4 Hashing

- 열린 어드레싱 (3)
 - ③ 이중 해쉬 (double hash)
 - 예
 - $h_1 = \text{KEY} \% 13$
 - $h_2 = 1 + \text{KEY} \% 11$
 - 14를 삽입 (KEY = 14)
 - $h_1 = 14 \% 13 = 1 \rightarrow \text{Collision}$

0	1	2	3	4	5	6	7	8	9	10	11	12
	79			69	98		72		15		50	

↑

14

7.4 Hashing

- 열린 어드레싱 (3)

- ③ 이중 해쉬 (double hash)

- 예

- $h_1 = \text{KEY} \% 13$

- $h_2 = 1 + \text{KEY} \% 11$

- 14를 삽입 (KEY = 14)

- $h_1 = 14 \% 13 = 1 \rightarrow \text{Collision}$

- $h_2 = 1 + 14 \% 11 = 4 \rightarrow 4\text{칸씩 건너뛰면서 삽입}$

0	1	2	3	4	5	6	7	8	9	10	11	12
	79			69	98		72		15		50	

14

7.4 Hashing

- 열린 어드레싱 (3)

- ③ 이중 해쉬 (double hash)

- 예

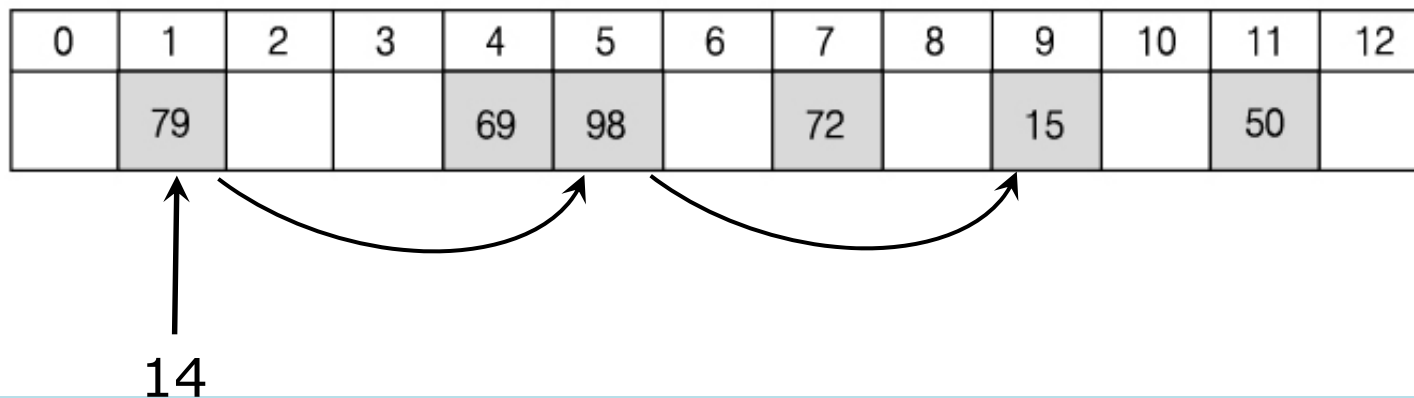
- $h_1 = \text{KEY} \% 13$

- $h_2 = 1 + \text{KEY} \% 11$

- 14를 삽입 (KEY = 14)

- $h_1 = 14 \% 13 = 1 \rightarrow \text{Collision}$

- $h_2 = 1 + 14 \% 11 = 4 \rightarrow 4\text{칸씩 건너뛰면서 삽입}$



7.4 Hashing

- 열린 어드레싱 (3)

- ③ 이중 해쉬 (double hash)

- 예

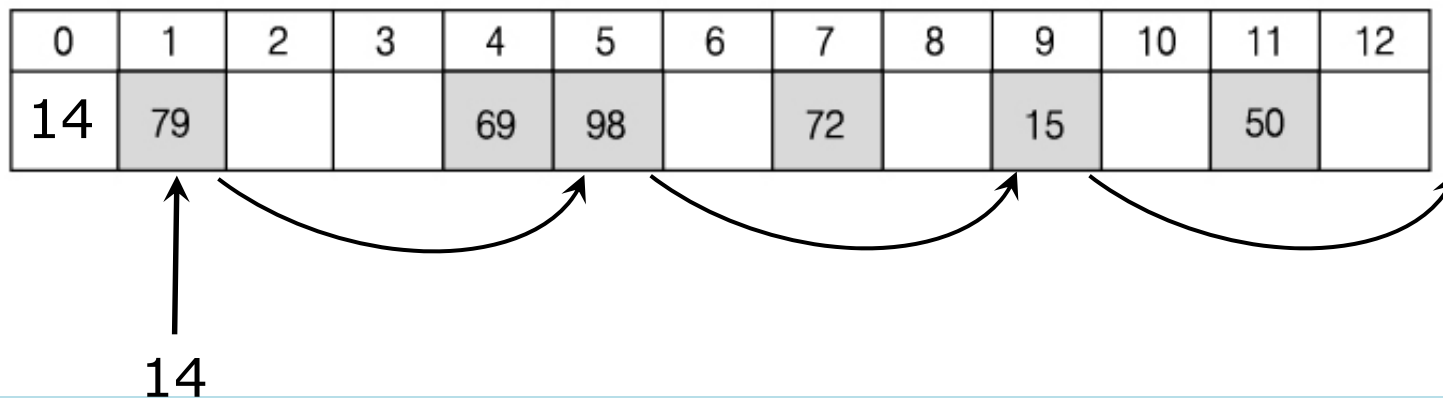
- $h_1 = \text{KEY} \% 13$

- $h_2 = 1 + \text{KEY} \% 11$

- 14를 삽입 (KEY = 14)

- $h_1 = 14 \% 13 = 1 \rightarrow \text{Collision}$

- $h_2 = 1 + 14 \% 11 = 4 \rightarrow 4\text{칸씩 건너뛰면서 삽입}$



7.4 Hashing

- 닫힌 어드레싱 (1)

- ① 버킷 (bucket)

- 해쉬 테이블의 각 원소들이 다시 여러 개의 원소로 이루어짐
 - 2차원 배열
 - 충돌되는 레코드를 하나의 인덱스에 둠
 - 사용되지 않는 배열 공간이 낭비됨

3					4				
65	34	127	189						

...

7.4 Hashing

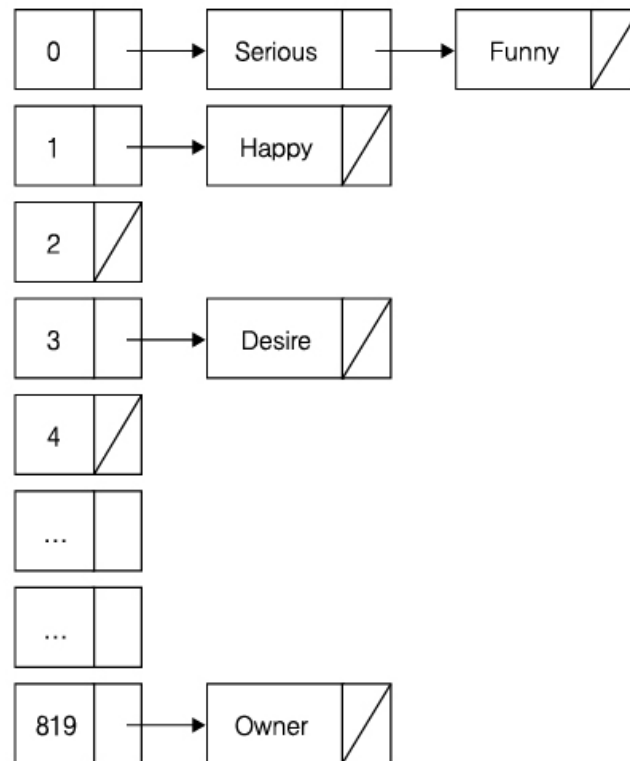
- 닫힌 어드레싱 (2)

- ② 별도 체인 (separate chain)

- 해쉬 테이블의 각 원소들이 연결 리스트를 가리키는 헤드
 - 충돌이 일어날 때마다 해당 레코드를 연결 리스트의 첫 위치에 삽입
 - 동적 구조(Dynamic Structure)

7.4 Hashing

- 닫힌 어드레싱 (2)
 - ② 별도 체인 (separate chain)



키	해시 값
Funny	0
Happy	1
Serious	0
Owner	819
Desire	3
...	...

7.5 Heuristic search

- Graph search algorithm
 - Find a path from a source node to a target node by estimating the best route
 - Depends on the heuristic
 - Find the best path according to the heuristic
 - After a failure, it searches an alternative
 - An evaluation function quantifies the heuristic to find the best path
 - A* search
 - $f(n) = g(n) + h(n)$
 - Game programming
-

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