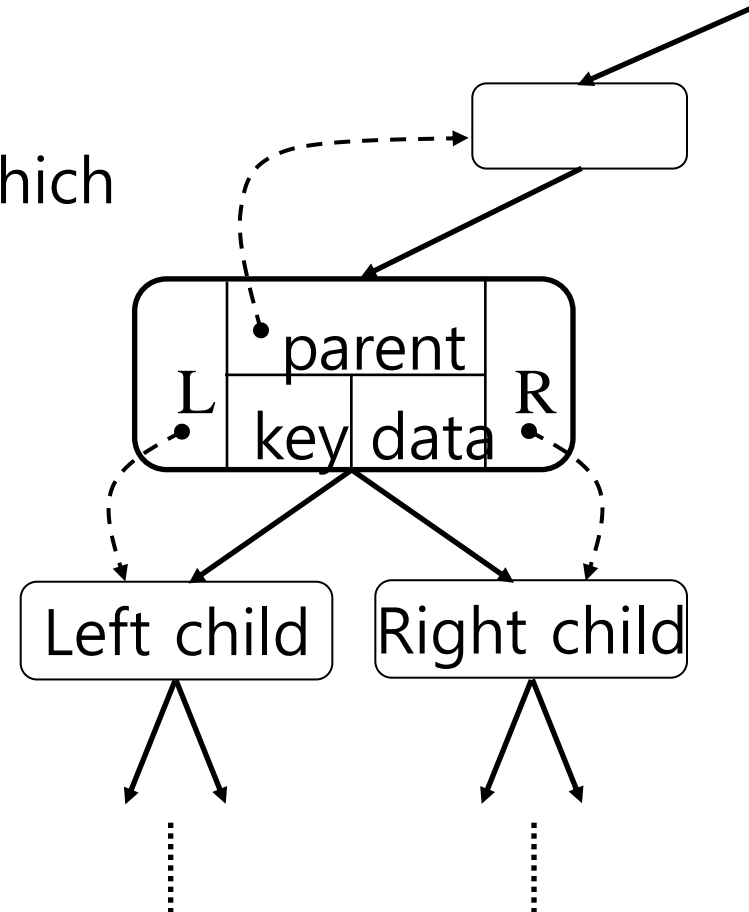


Chapter12. Binary Search Tree

- Binary Search Tree Representation
- Binary Search Tree Property
- Operations on binary search trees

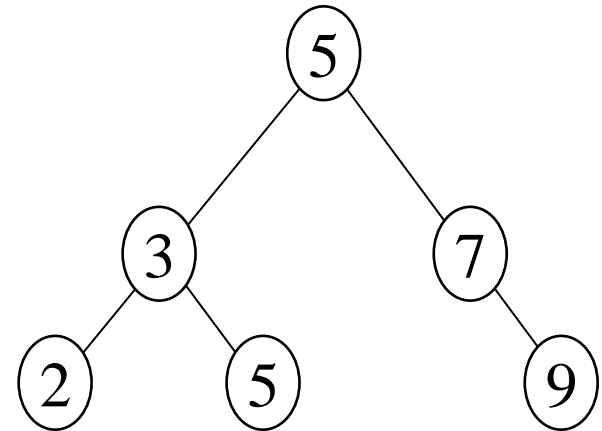
Binary Search Tree Representation

- Tree representation:
 - A linked data structure in which each node is an object
- Node representation:
 - Key field
 - Satellite data
 - Left: pointer to left child
 - Right: pointer to right child
 - p: pointer to parent
(p [root [T]] = NIL)



Binary Search Tree Property

- Binary search tree property:
 - If y is in left subtree of x ,
then $\text{key}[y] \leq \text{key}[x]$
 - If y is in right subtree of x ,
then $\text{key}[y] \geq \text{key}[x]$

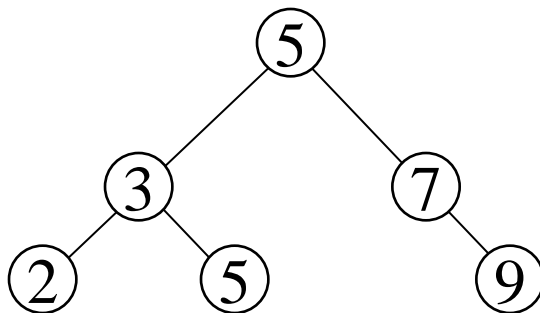


Binary Search Tree

- Support many dynamic set operations
 - SEARCH, MINIMUM, MAXIMUM, PREDECESSOR, SUCCESSOR, INSERT, DELETE
- Running time of basic operations on binary search trees
 - On average: $\Theta(\log n)$
 - The expected height of the tree is $\log n$
 - In the worst case: $\Theta(n)$
 - The tree is a linear chain of n nodes

Traversing a Binary Search Tree

- **Inorder** tree walk:
 - Root is printed between the values of its left and right subtrees: left, root, right
- **Preorder** tree walk:
 - root printed first: root, left, right
- **Postorder** tree walk:
 - root printed last: left, right, root



Inorder: 2 3 5 5 7 9

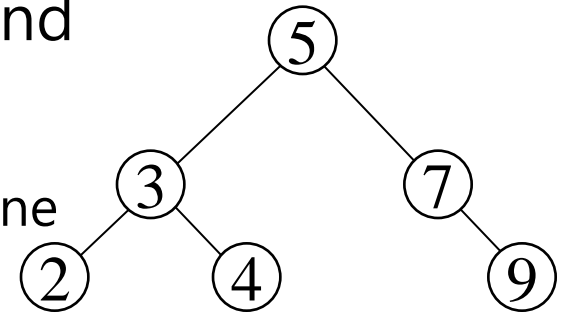
Preorder: 5 3 2 5 7 9

Postorder: 2 5 3 9 7 5

Searching for a Key

- Given a pointer to the root of a tree and a key k :

- Return a pointer to a node with key k if one exists
- Otherwise return NIL



- Idea

- Starting at the root: trace down a path by comparing k with the key of the current node:
 - If the keys are equal: we have found the key
 - If $k < \text{key}[x]$ search in the left subtree of x
 - If $k > \text{key}[x]$ search in the right subtree of x

Searching for a Key

TREE-SEARCH(x, k)

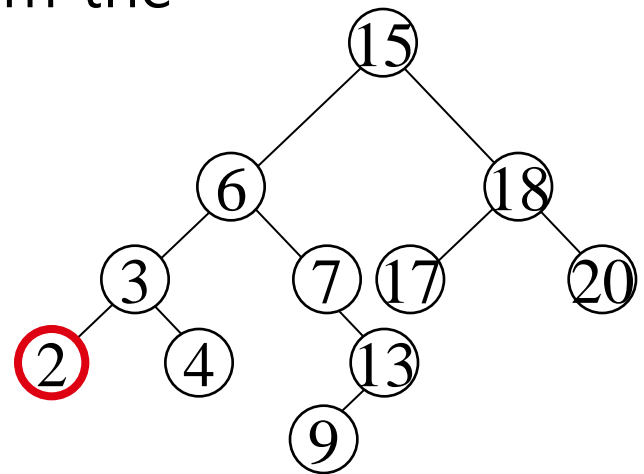
1. **if** $x = \text{NIL}$ or $k = \text{key}[x]$
 2. **then return** x
 3. **if** $k < \text{key}[x]$
 4. **then return** TREE-SEARCH(left $[x], k$)
 5. **else return** TREE-SEARCH(right $[x], k$)
- Running Time: $O(h)$, where h is the height of the tree

Finding the Minimum

- Goal: find the minimum value in a BST
 - Following left child pointers from the root, until a NIL is encountered

TREE-MINIMUM(x)

1. **while** left [x] \neq NIL
2. **do** x \leftarrow left [x]
3. **return** x



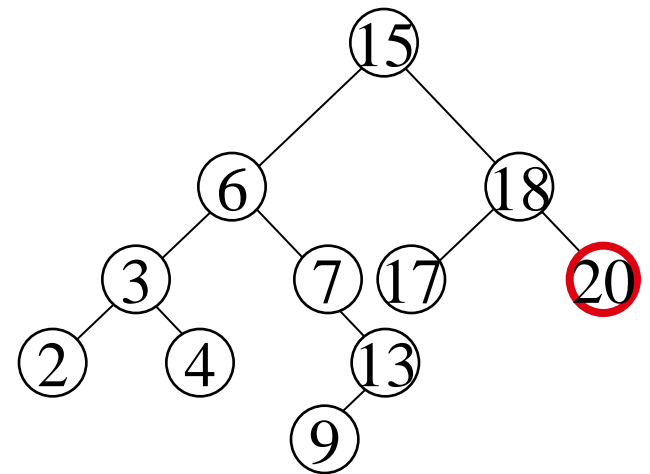
Running time: $O(h)$, where h is the height of tree

Find the Maximum

- Goal: find the maximum value in a BST
 - Following right child pointers from the root, until a NIL is encountered

TREE-MAXIMUM(x)

1. **while** right [x] \neq NIL
2. **do** $x \leftarrow$ right [x]
3. **return** x



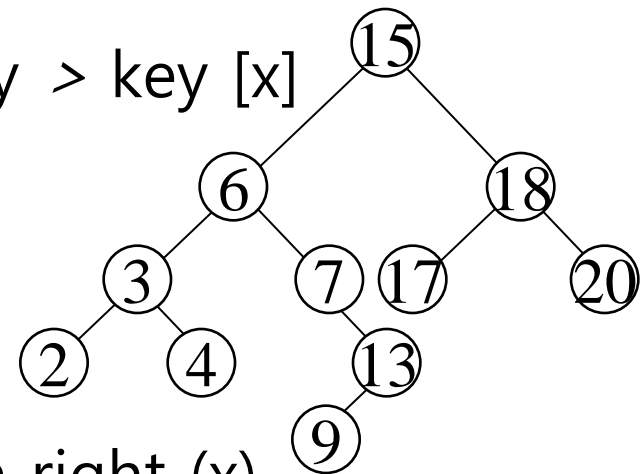
- Running time: $O(h)$, where h is the height of tree

Find the Successor

Def: $\text{successor}(x) = y$,
such that key $[y]$ is the smallest key $>$ key $[x]$

- E.g.: $\text{successor}(15) = 17$
 $\text{successor}(13) = 15$
 $\text{successor}(9) = 13$

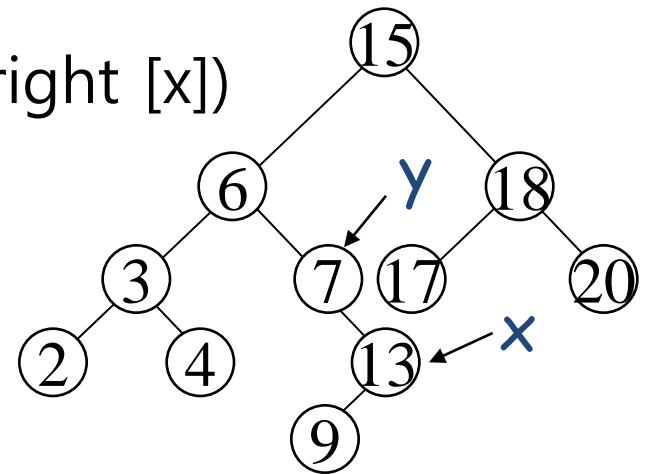
- Case 1: right (x) is non empty
 - $\text{successor}(x) =$ the minimum in right (x)
- Case 2: right (x) is empty
 - go up the tree until the current node is a left child: $\text{successor}(x)$ is the parent of the current node
 - if you cannot go further (and you reached the root): x is the largest element



Find the Successor

TREE-SUCCESSOR(x)

1. **if** right [x] \neq NIL
2. **then return** TREE-MINIMUM(right [x])
3. $y \leftarrow p[x]$
4. **while** $y \neq$ NIL and $x =$ right [y]
5. **do** $x \leftarrow y$
6. $y \leftarrow p[y]$
7. **return** y

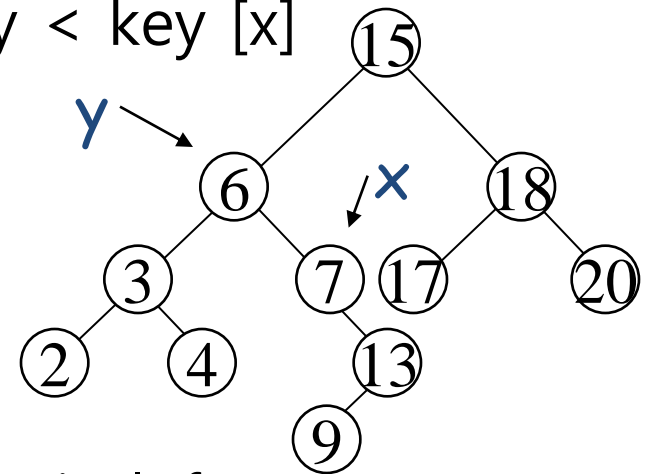


Running time: $O(h)$, where h is the height of the tree

Find the Predecessor

Def: predecessor (x) = y,
such that key [y] is the biggest key < key [x]

- E.g.: predecessor (15) = 13
predecessor (9) = 7
predecessor (7) = 6



- Case 1: left (x) is non empty
 - predecessor (x) = the maximum in left (x)
- Case 2: left (x) is empty
 - go up the tree until the current node is a right child: predecessor (x) is the parent of the current node
 - if you cannot go further (and you reached the root): x is the smallest element

Insertion

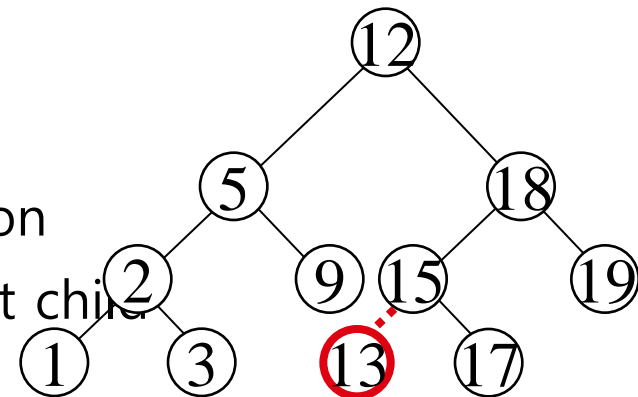
- Goal:

- Insert value v into a binary search tree

- Idea:

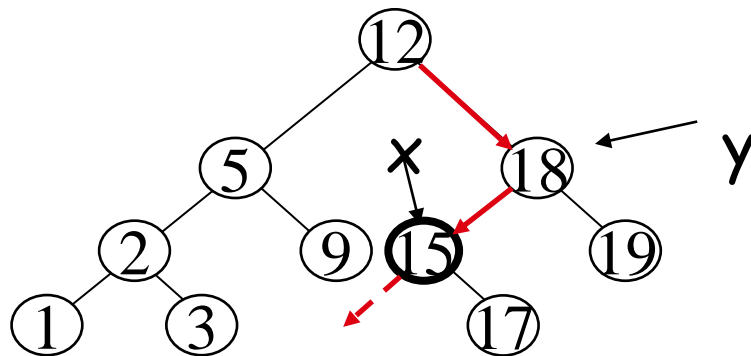
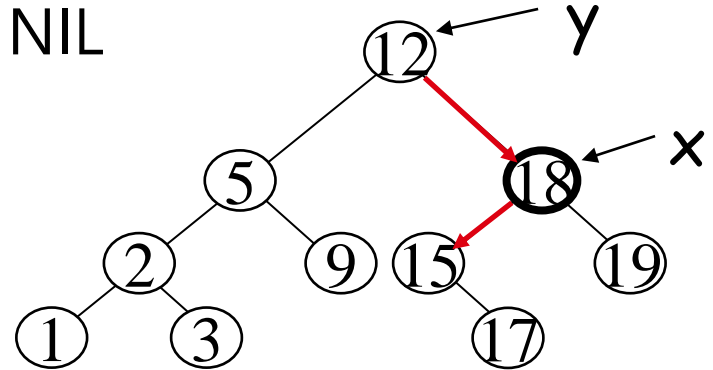
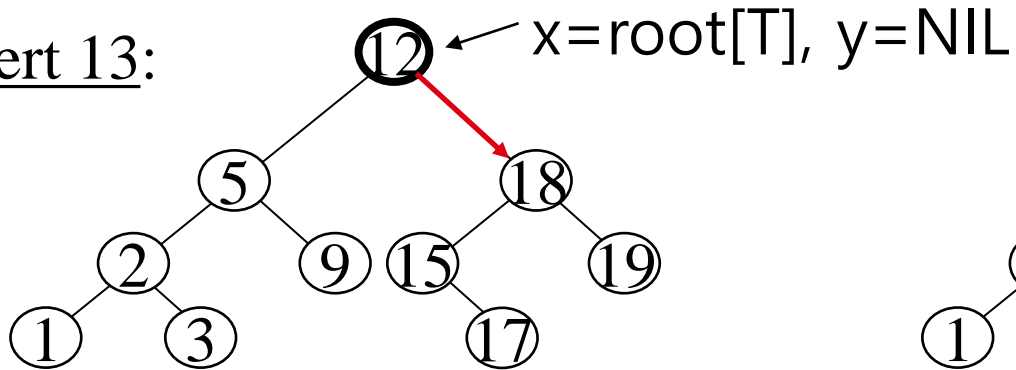
- If $\text{key}[x] < v$ move to the right child of x ,
else move to the left child of x
- When x is NIL, we found the correct position
- If $v < \text{key}[y]$ insert the new node as y 's left child
else insert it as y 's right child
- Beginning at the root, go down the tree and maintain:
 - Pointer x : traces the downward path (current node)
 - Pointer y : parent of x ("trailing pointer")

Insert value 13

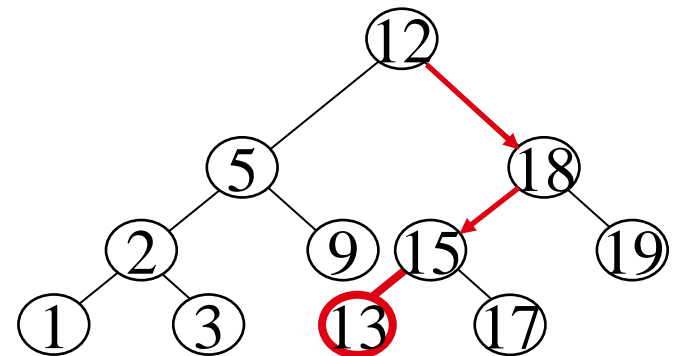


Example: TREE-INSERT

Insert 13:

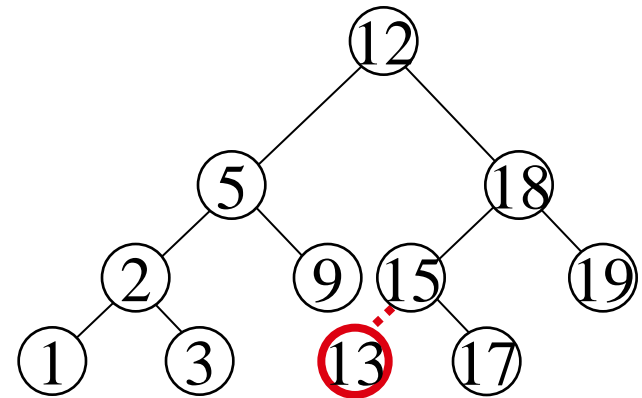


$x = \text{NIL}$
 $y = 15$



TREE-INSERT (T, z)

1. $y \leftarrow \text{NIL}$
2. $x \leftarrow \text{root}[T]$
3. **while** $x \neq \text{NIL}$
4. **do** $y \leftarrow x$
5. **if** $\text{key}[z] < \text{key}[x]$
6. **then** $x \leftarrow \text{left}[x]$
7. **else** $x \leftarrow \text{right}[x]$
8. $p[z] \leftarrow y$
9. **if** $y = \text{NIL}$
10. **then** $\text{root}[T] \leftarrow z$
11. **else if** $\text{key}[z] < \text{key}[y]$
12. **then** $\text{left}[y] \leftarrow z$
13. **else** $\text{right}[y] \leftarrow z$

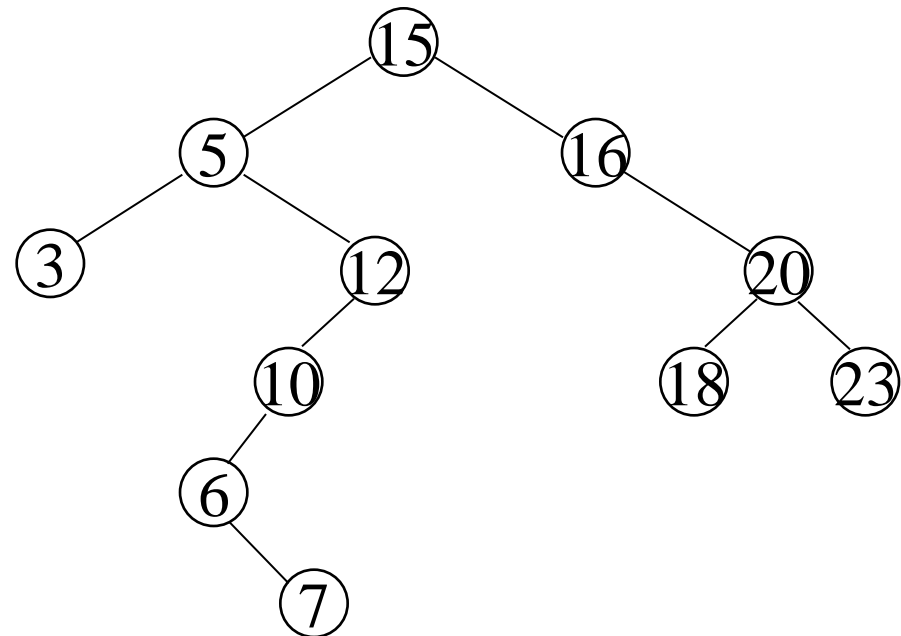
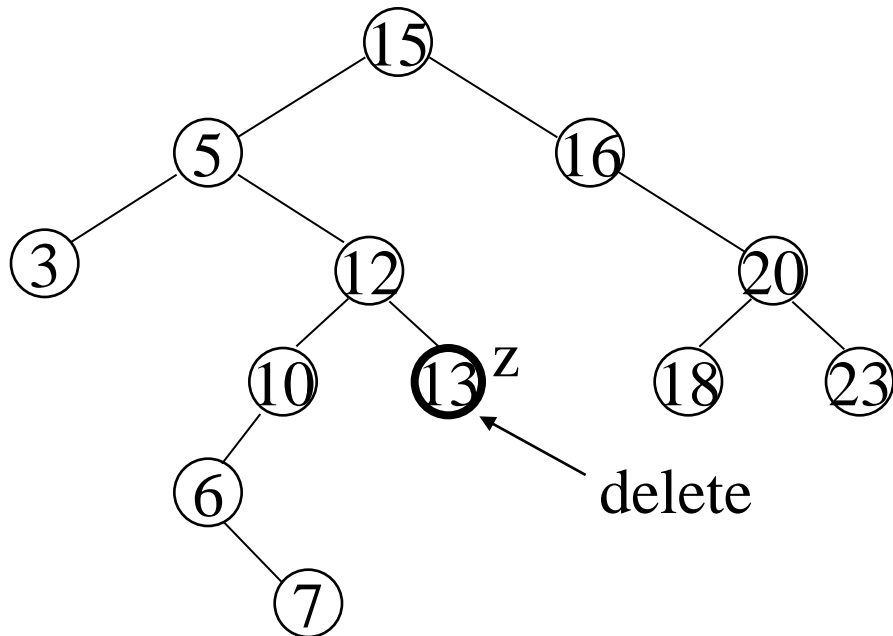


Tree T was empty

Running time: $O(h)$

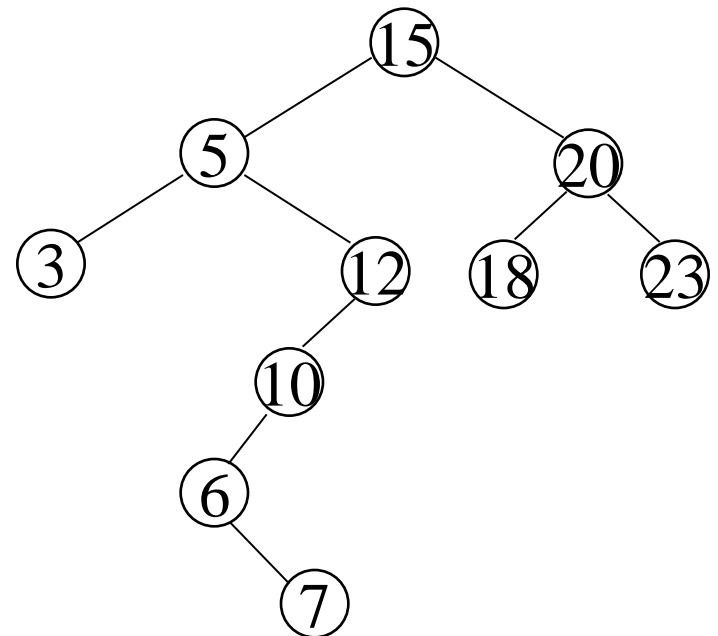
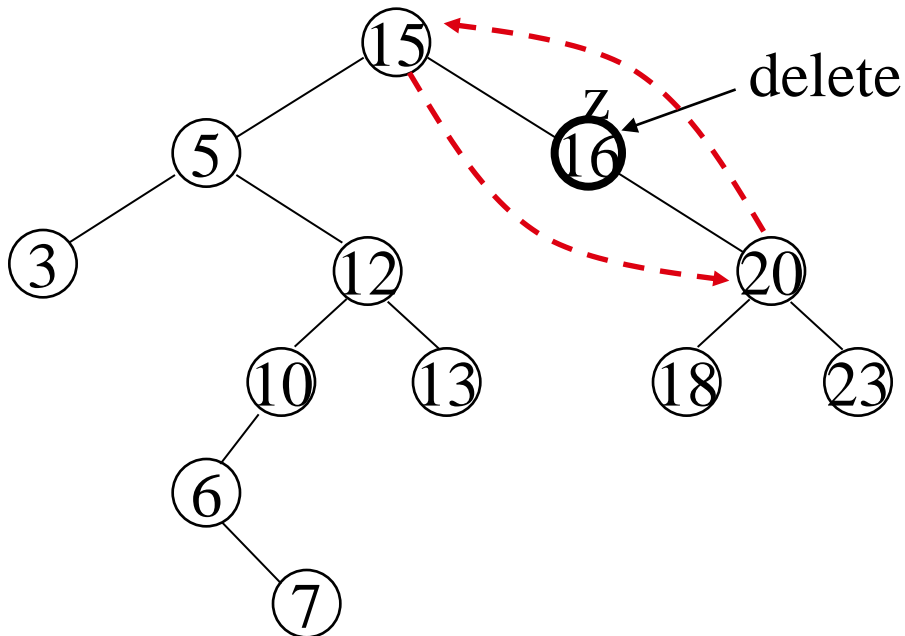
Deletion

- Goal:
 - Delete a given node **z** from a binary search tree
- Idea:
 - **Case 1**: **z** has no children
 - Delete **z** by making the parent of **z** point to NIL



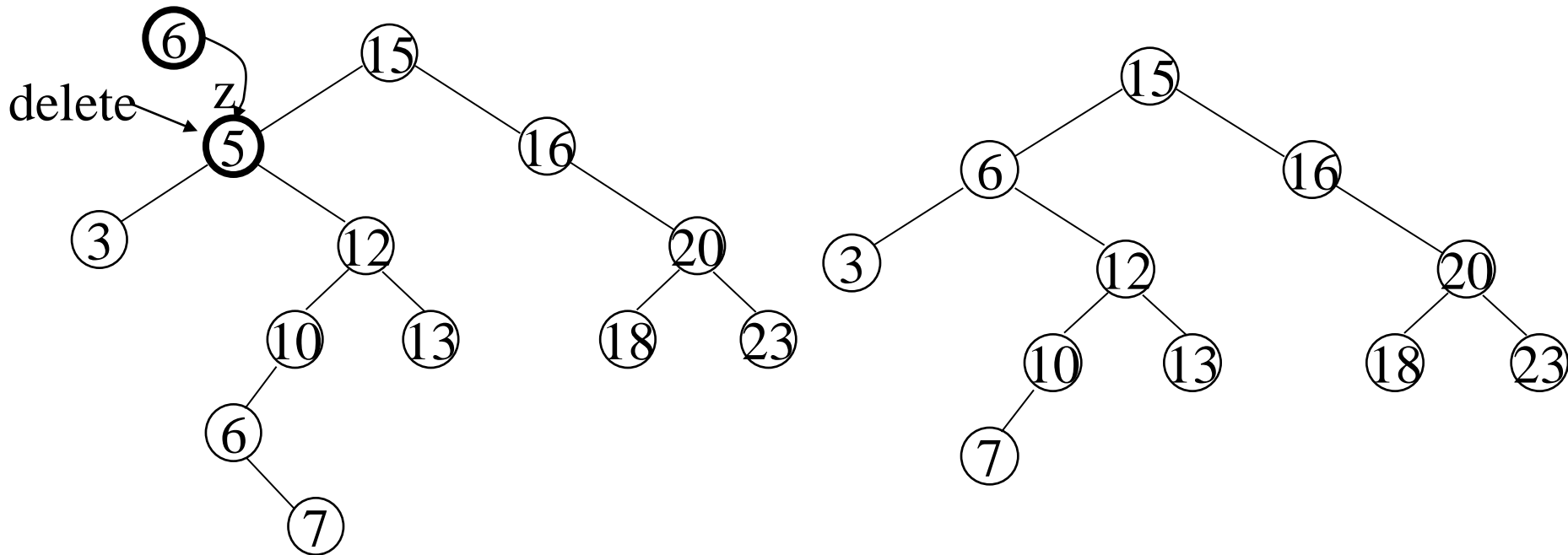
Deletion

- **Case 2:** z has one child
 - Delete z by making the parent of z point to z's child, instead of to z



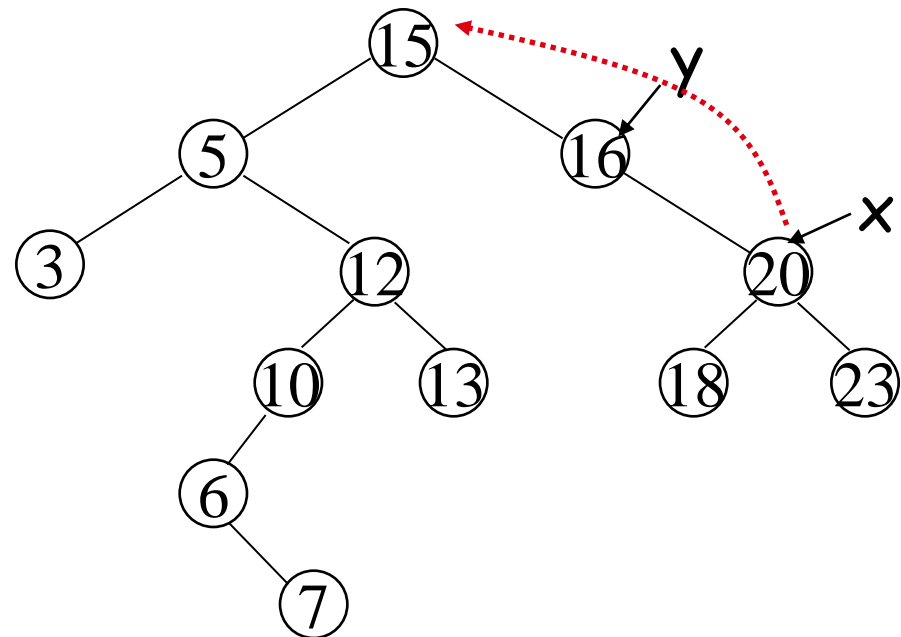
Deletion

- **Case 3:** z has two children
 - z's successor (y) is the minimum node in z's right subtree
 - y has either no children or one right child (but no left child)
 - Delete y from the tree (via Case 1 or 2)
 - Replace z's key and satellite data with y's.



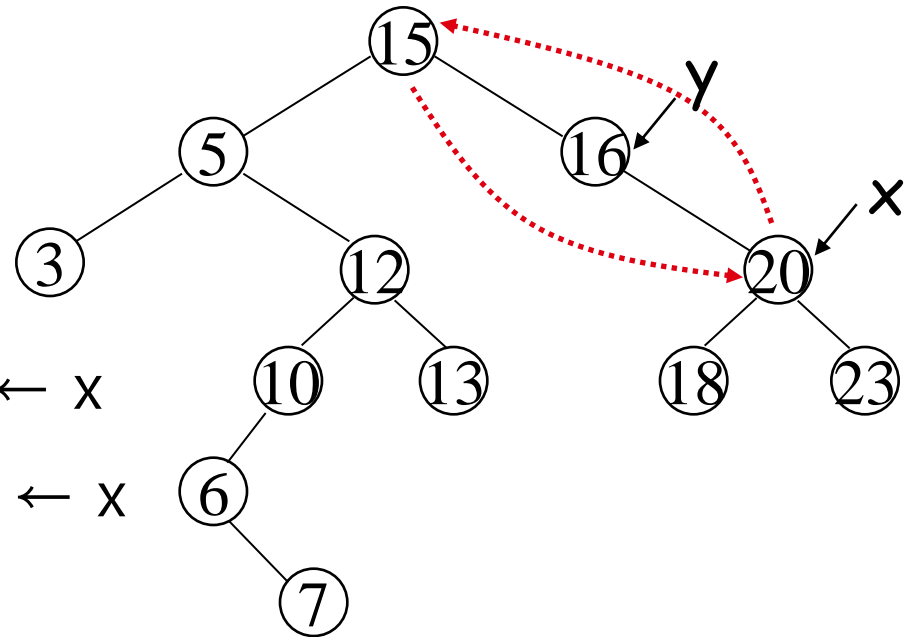
TREE-DELETE(T, z)

1. **if** $\text{left}[z] = \text{NIL}$ or $\text{right}[z] = \text{NIL}$
2. **then** $y \leftarrow z$ z has one child
3. **else** $y \leftarrow \text{TREE-SUCCESSOR}(z)$ z has 2 children
4. **if** $\text{left}[y] \neq \text{NIL}$
5. **then** $x \leftarrow \text{left}[y]$
6. **else** $x \leftarrow \text{right}[y]$
7. **if** $x \neq \text{NIL}$
8. **then** $p[x] \leftarrow p[y]$



TREE-DELETE(T, z)

9. **if** $p[y] = \text{NIL}$
10. **then** $\text{root}[T] \leftarrow x$
11. **else if** $y = \text{left}[p[y]]$
12. **then** $\text{left}[p[y]] \leftarrow x$
13. **else** $\text{right}[p[y]] \leftarrow x$
14. **if** $y \neq z$
15. **then** $\text{key}[z] \leftarrow \text{key}[y]$
16. copy y 's satellite data into z
17. **return** y



Running time: **$O(h)$**

Binary Search Trees: Summary

- Operations on binary search trees:
 - SEARCH $O(h)$
 - PREDECESSOR $O(h)$
 - SUCCESSION $O(h)$
 - MINIMUM $O(h)$
 - MAXIMUM $O(h)$
 - INSERT $O(h)$
 - DELETE $O(h)$
- These operations are fast if the height of the tree is small, otherwise their performance is similar to that of a linked list