자료구조

Chap 09. Graph

2018년 1학기

컴퓨터과학과 민경하

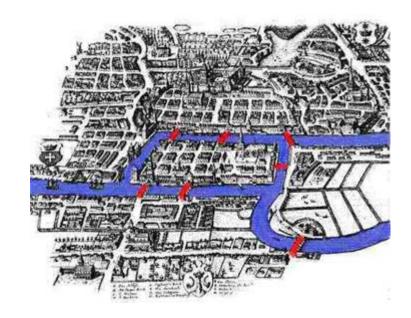
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9.1 Introduction

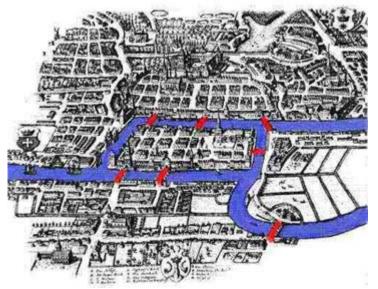
- Konigsberg bridge problem
 - To determine whether, starting at one land area, it is possible to walk across all the bridges exactly once in returning to starting land area

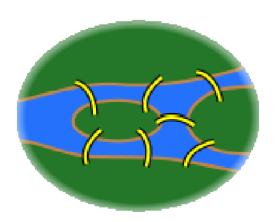


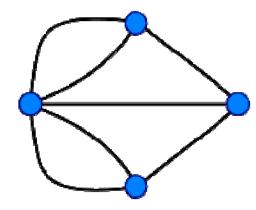


9.1 Introduction

- Konigsberg bridge problem
 - Euler introduced "Graph"
 - Abstraction
 - Land & island → node (vertex)
 - Bridge → edge (link)







(1) Graph

 A mathematical (abstracted) model that represents the one-to-one (binary) relationship between objects visually

```
-G = (V, E)
```

- V
 - Vertex represents objects
- E
 - Edge represents relationship
 - Edge is a pair of vertices

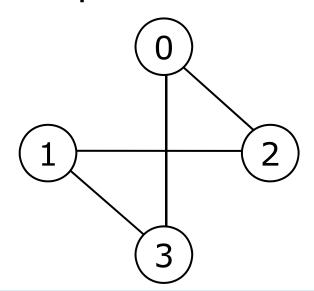
(1) Graph

- Mathematical representation

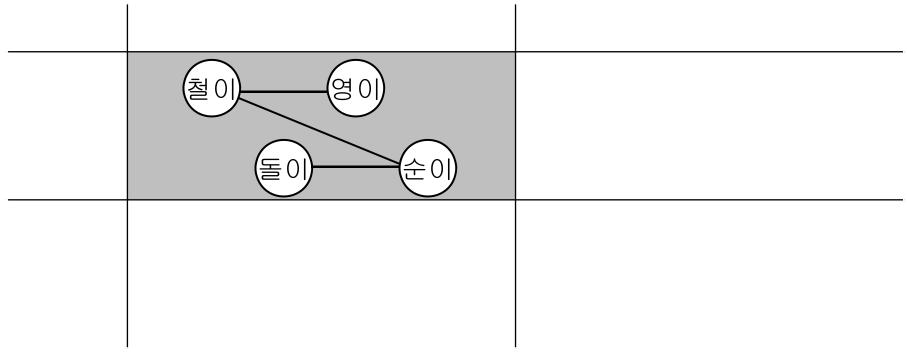
-
$$V = \{0, 1, 2, 3\}$$

- $E = \{(0, 2), (0, 3), (1, 2), (1, 3)\}$

- Geometrical representation



(2) Types of graph



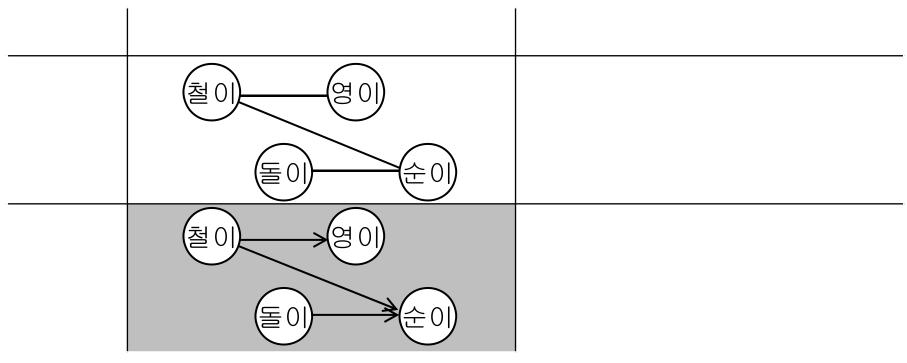
개체: 철이, 영이, 돌이, 순이

관계: 철이, 영이는 페친임.

철이, 순이는 페친임.

돌이, 순이는 페친임.

(2) Types of graph

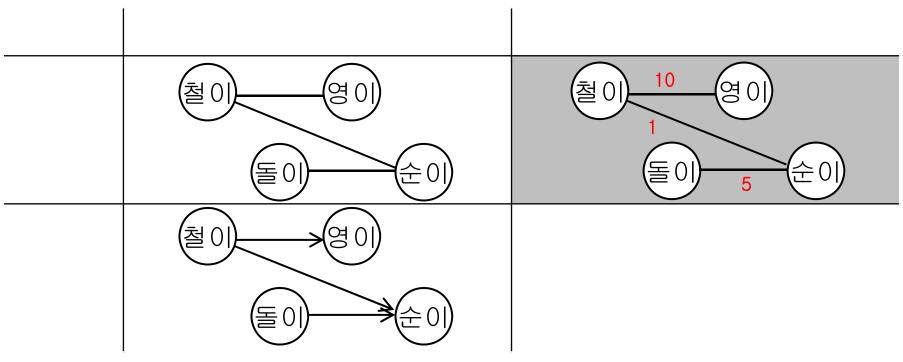


개체: 철이, 영이, 돌이, 순이

관계: 철이는 영이를 follow함.

철이는 순이를 follow함. 돌이는 순이를 follow함.

(2) Types of graph

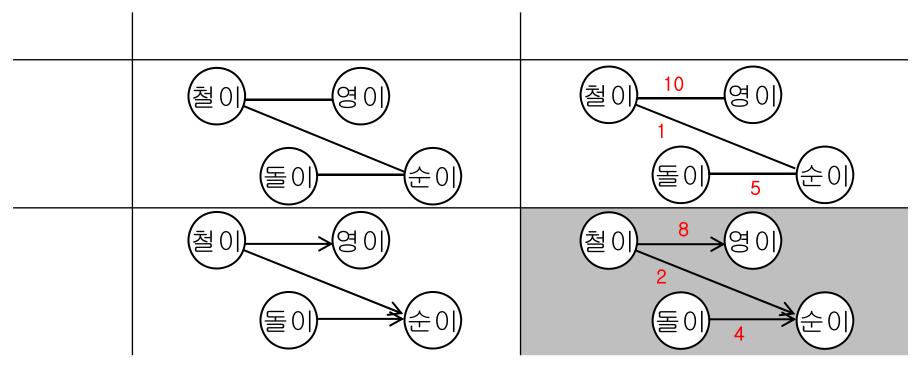


개체: 철이, 영이, 돌이, 순이

관계: 철이, 영이는 심각한 페친임.

철이, 순이는 썰렁한 페친임. 돌이, 순이는 평범한 페친임.

(2) Types of graph

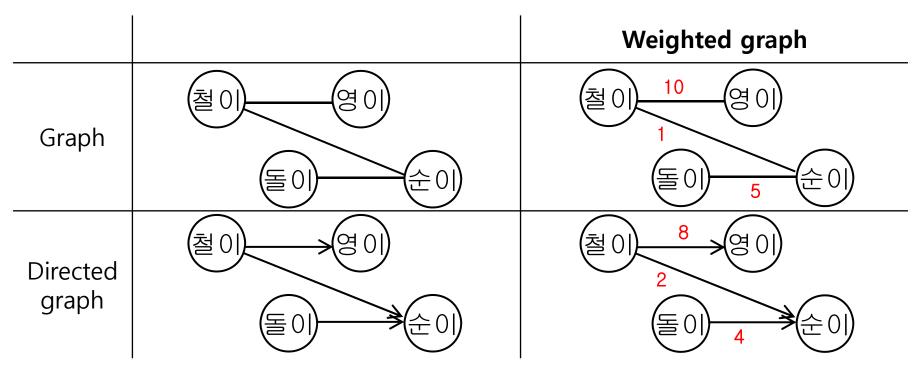


개체: 철이, 영이, 돌이, 순이

관계: 철이는 영이를 많이 follow함.

철이는 순이를 조금 follow함. 돌이는 순이를 보통 follow함

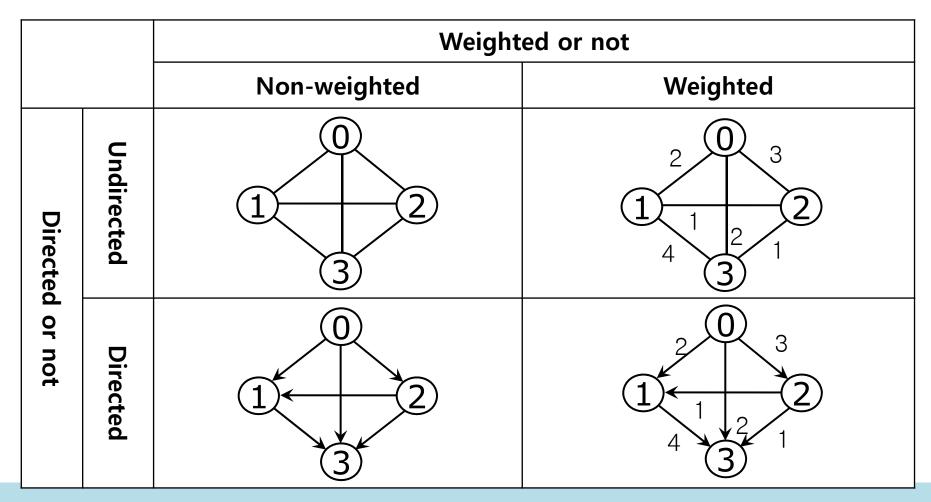
(2) Types of graph



(Undirected) Graph: (u, v) = (v, u)

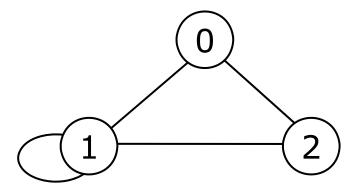
Directed graph: $(u, v) \neq (v, u)$

(2) Types of graph

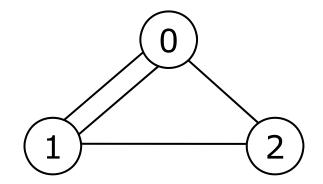


(2) Types of graph

- Extraordinary case: Graph with self edge
 - self edge: (u, u)



- (2) Types of graph
 - Extraordinary case: Multigraph
 - A graph with a set of multiple edges



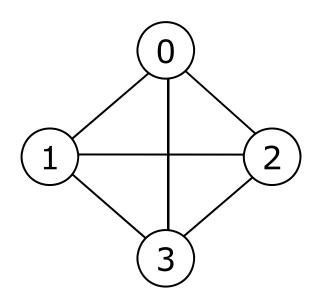
(3) Complexity of graph

- Complete graph
 - Maximum number of edges of a graph with n vertices → n(n-1)/2
 - Ex)

$$-V = \{0, 1, 2, 3\}$$

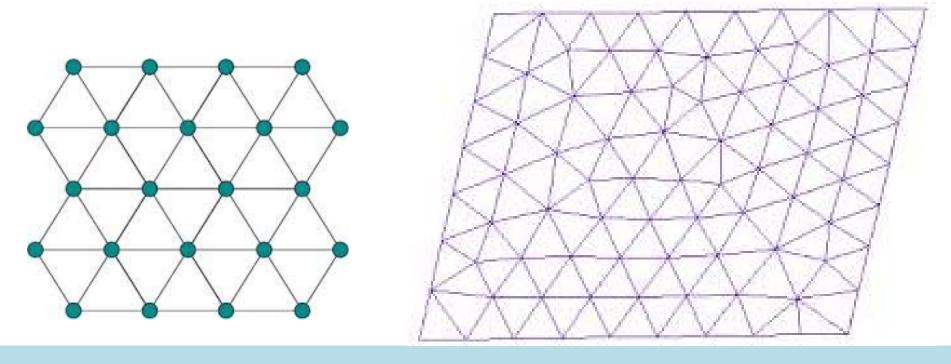
 $-n(E) = 4*3/2 = 6$

- Complete graph
 - A graph whose no. of edges is n(n-1)/2
- Dense graph



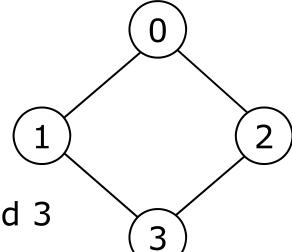
(3) Complexity of graph

- Sparse graph
 - A graph whose vertices are connected to a constant number of edges.



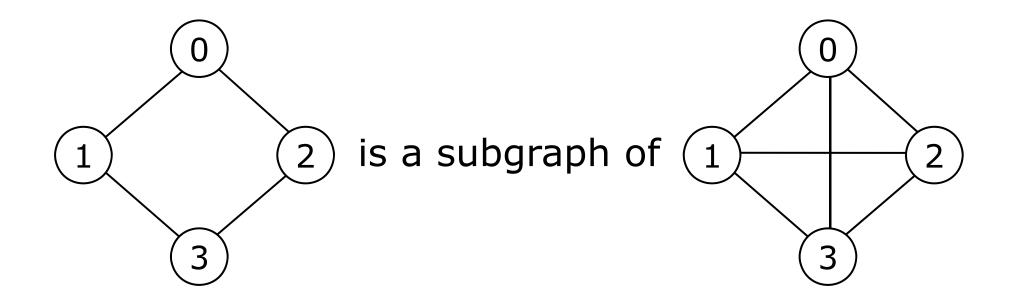
(4) Adjacency & Incidency

- If $(u, v) \in E$, then
 - u and v are adjacent
 - (u, v) is incident to u and v
- Ex)
 - 0 and 1 are adjacent
 - 0 and 3 are not adjacent
 - (0, 1) is incident to 0 and 1
 - (0, 1) is not incident to 2 and 3

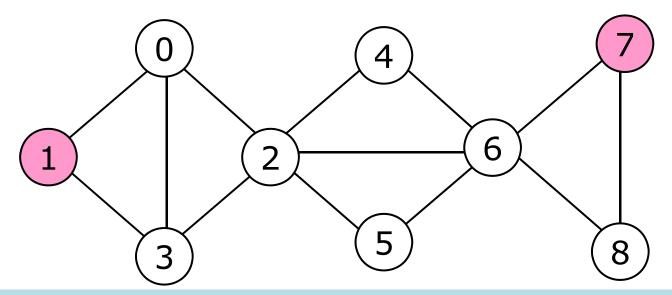


(5) Subgraph

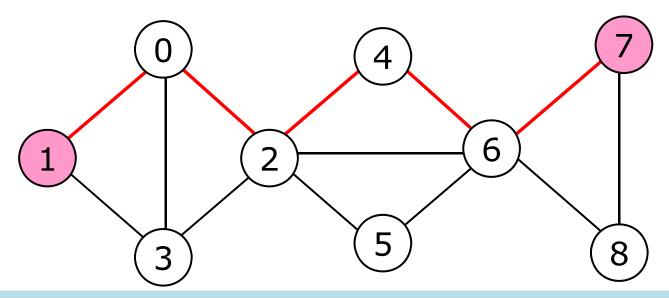
- Graph G' = (V', E') is a subgraph of G = (V, E), if $V' \subseteq V$ and $E' \subseteq E$



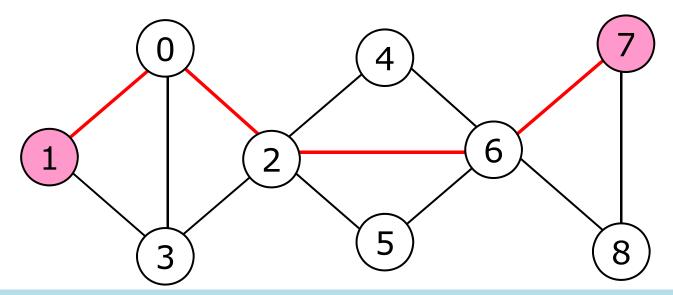
- A path from a vertex u to a vertex v is a sequence of vertices u, i_1 , i_2 , ..., i_k , v such that (u, i_1) , (i_1, i_2) , ..., $(i_k, v) \in E$
- Path from 1 to 7: 1, 0, 2, 4, 6, 7



- A path from a vertex u to a vertex v is a sequence of vertices u, i_1 , i_2 , ..., i_k , v such that (u, i_1) , (i_1, i_2) , ..., $(i_k, v) \in E$
- Path from 1 to 7: 1, 0, 2, 4, 6, 7



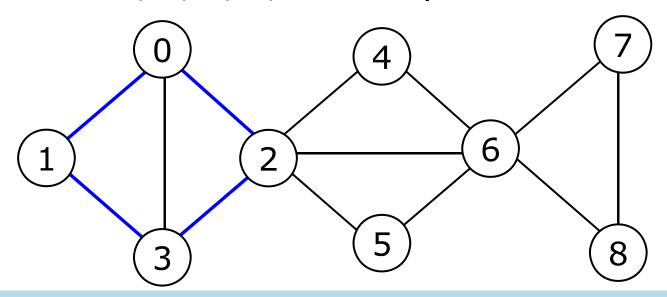
- A path from a vertex u to a vertex v is a sequence of vertices u, i_1 , i_2 , ..., i_k , v such that (u, i_1) , (i_1, i_2) , ..., $(i_k, v) \in E$
- Another Path: 1, 0, 2, 6, 7



- A path from a vertex u to a vertex v is a sequence of vertices u, i_1 , i_2 , ..., i_k , v such that (u, i_1) , (i_1, i_2) , ..., $(i_k, v) \in E$
- Multiple paths can exist
- The length of a path
 - The number of edges on it
 - The number of vertices on it
- Simple path
 - A path in which all vertices except possibly the first and last are distinct

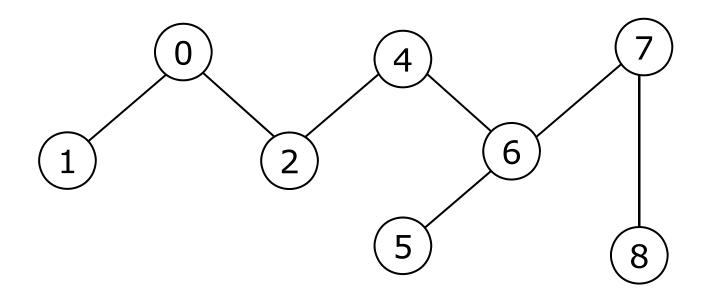
(7) Cycle

- A simple path in which the first and last vertices are the same
- -Ex)
 - Path "0, 1, 3, 2, 0" is a cycle



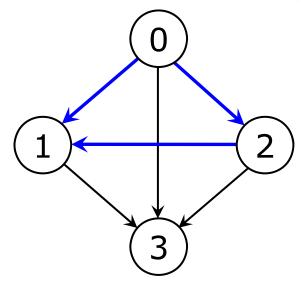
(7) Cycle

- Acyclic graph
 - A graph that does not contain a cycle

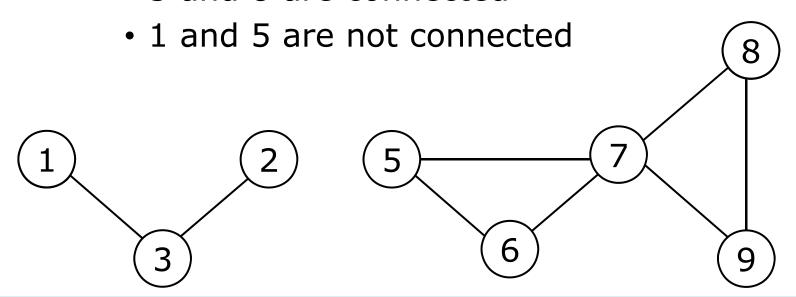


(7) Cycle

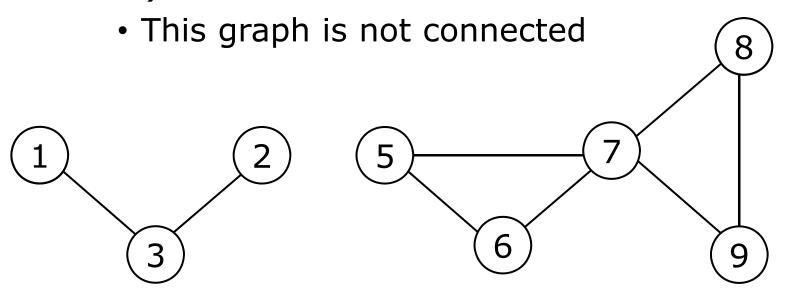
- A simple path in which the first and last vertices are the same
- -Ex)
 - Path "0, 2, 1, 0" is not a cycle



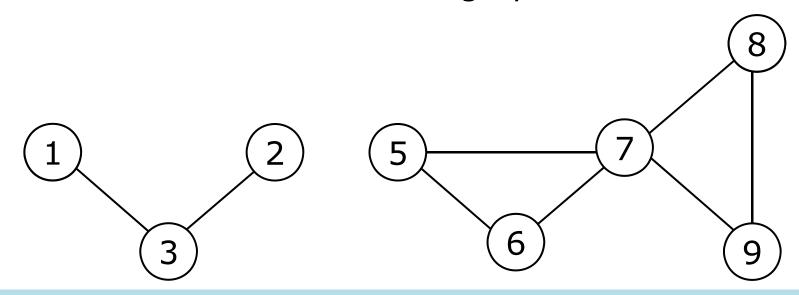
- Two vertices u and v are connected if there is a path from u to v
- Ex)
 - 5 and 8 are connected



- A graph is connected if for every pair of distinct vertices u and v, there is a path from u to v
- Ex)

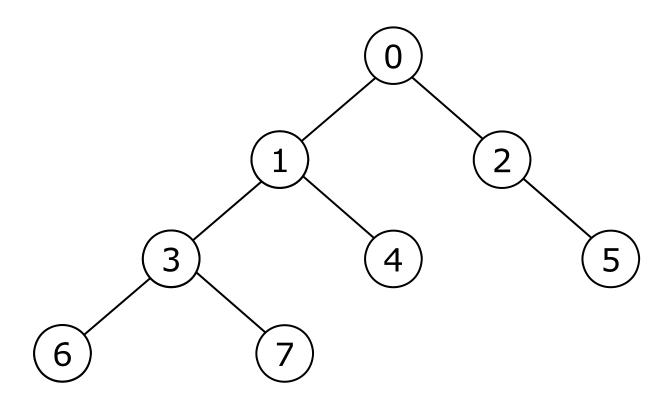


- Connected component
 - A maximal connected subgraph
- Ex)
 - Two connected subgraphs



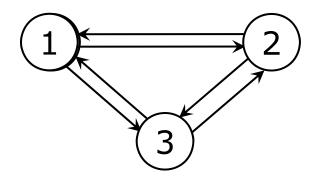
(8) Connected

- Tree is a connected acyclic graph

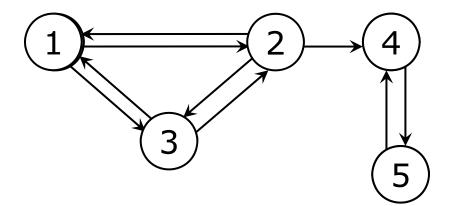


(8) Connected

A directed graph is strongly connected,
 if for every pair of distinct vertices u and
 v, there is a directed path from u to v
 and also from v to u



- A strongly connected component is a maximal subgraph that is strongly connected
- -Ex)
 - {1, 2, 3} is a strongly connected component
 - {4, 5} is a strongly connected component

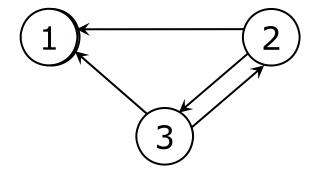


(9) Degree of a vertex

- The number of edges incident to a vertex
- In-degree of a vertex v
 - The number of edges for which v is the head
- Out-degree of a vertex v
 - The number of edges for which v is the tail

(10) Degree of a vertex

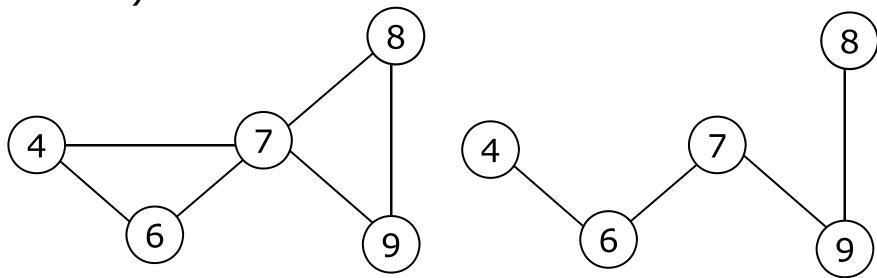
- Ex)
 - Degree of vertex 2 = 3
 - In-degree of vertex 3: 1
 - Out-degree of vertex 3: 2



(11) Spanning tree

T = (V', E') is a spanning tree of a graph
 G = (V, E), if V' = V and E' ⊆ E and E'
 does not contain a cycle

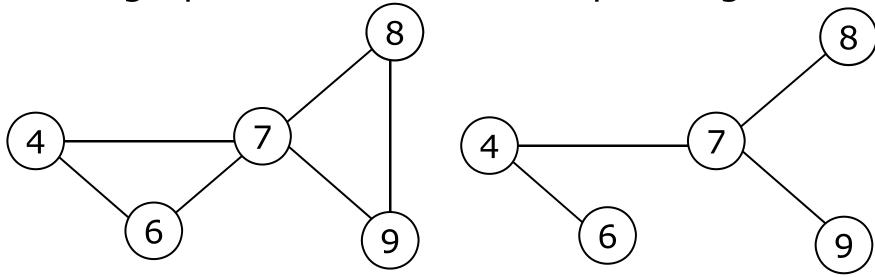
- Ex)



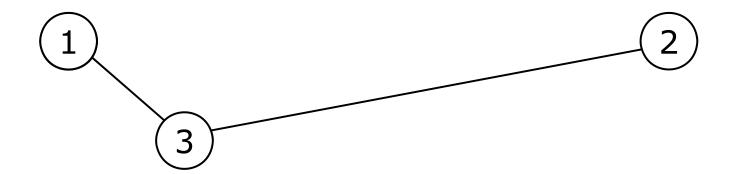
(11) Spanning tree

-T = (V', E') is a spanning tree of a graph G = (V, E), if V' = V and $E' \subseteq E$ and E' does not contain a cycle

A graph can have several spanning trees

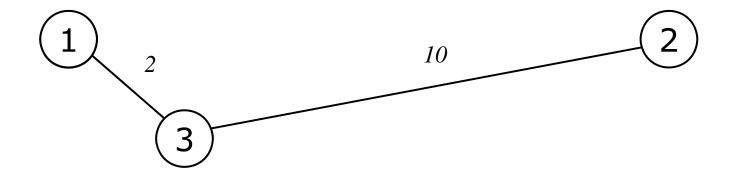


- (12) Weighted graph
 - A graph whose edges have some weights



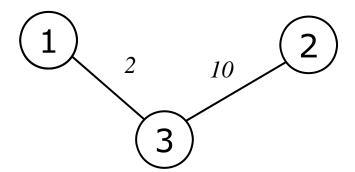
9.2 Basic concepts

- (12) Weighted graph
 - A graph whose edges have some weights



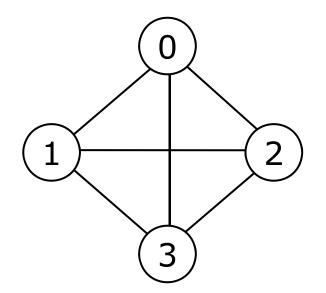
9.2 Basic concepts

- (12) Weighted graph
 - A graph whose edges have some weights



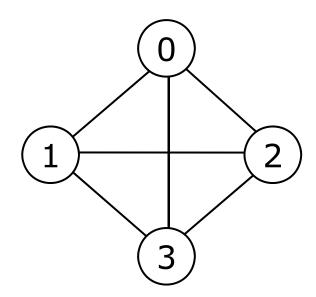
(1) Edge list

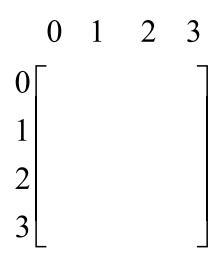
- A list of edges
- Available on many coding problems



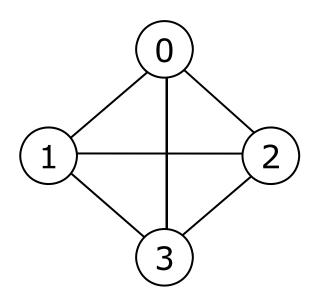
4, 6 0, 1 0, 2 0, 3 1, 2 1, 3 2, 3

- (2) Adjacency matrix of G = (V, E)
 - A two-dimensional n X n array: a[n][n]
 - -a[i][j] = 1, if $(v_i, v_j) \in E$
 - a[i][j] = 0, if $(v_i, v_j) ! \in E$





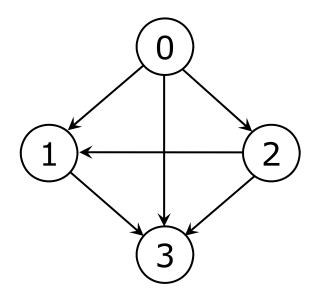
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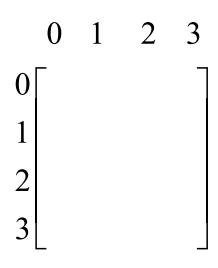


	0	1	2	3
0	0	1	1	1
1	1 1 1	0	1	1
2	1	1	0	1
3	1	1	1	0

(2) Adjacency matrix of G = (V, E)

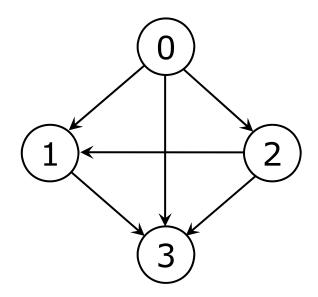
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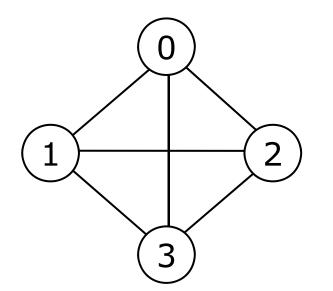
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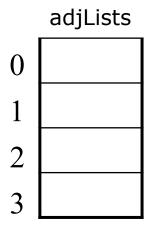
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- a[i][j] = 0, if $< v_i, v_j > ! \in E$



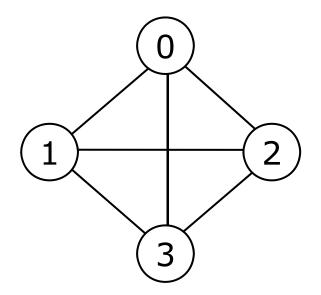
	0	1	2	3
0	0	1	1	1
1	$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$	0	0	1
2	0	1	0	1
3	0	0	0	0

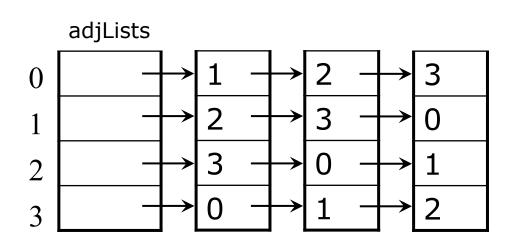
- (3) Adjacency list of G = (V, E)
 - adjLists[n]
 - adjLists[i] is a pointer to the first node in the adjacency list for vertex i



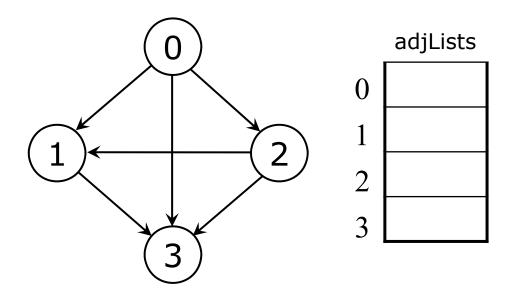


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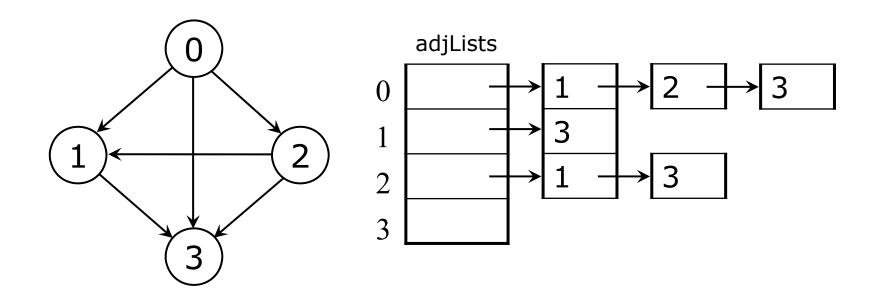




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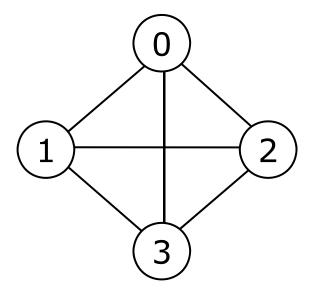
- (3) Adjacency list of G = (V, E)
 - adjLists[n]
 - adjLists[i] is a pointer to the first node in the adjacency list for vertex i



- Comparison of performance
 - Ex) At all vertices, list all the incident vertices

```
for all vertices v in G
for all vertices w adjacent to v
report (v, w);
```

- Expected output:
 - 0: 1, 2, 3
 - 1: 0, 2, 3
 - 2: 0, 1, 3
 - 3: 0, 1, 2

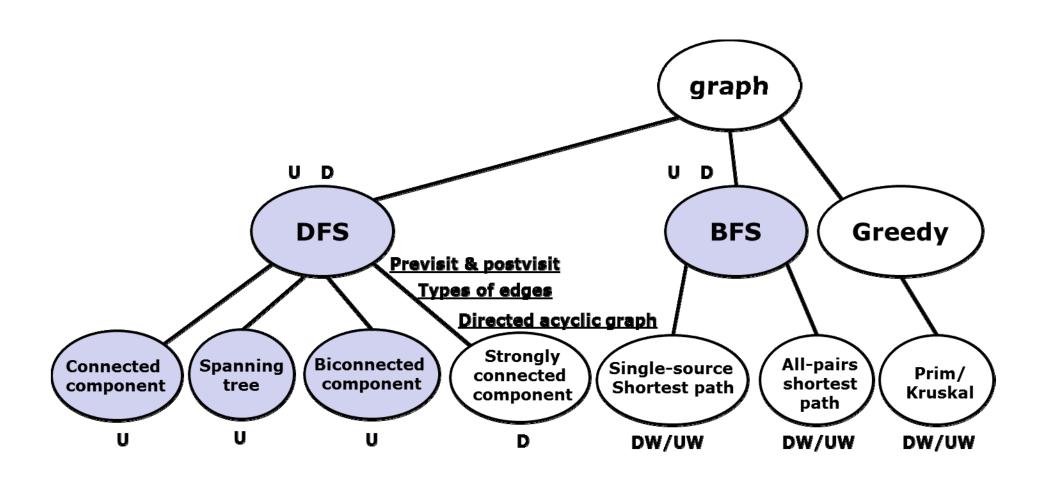


- Comparison of performance
 - Ex) At all vertices, list all the incident vertices

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for all vertices v in G
for all vertices w adjacent to v
report (v, w);
```

	Adjacency matrix	Adjacency list
Complete graph	O(n ²)	O(n ²)
Sparse graph	O(n ²)	O(n)

9.4 Search



9.4 Search

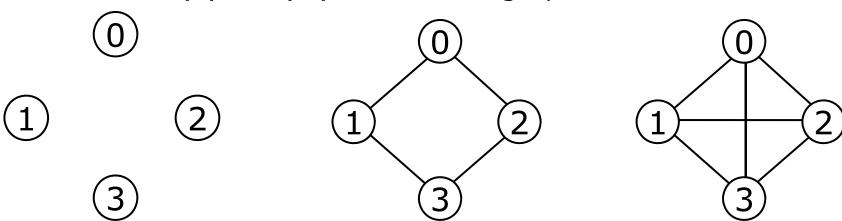
- Problem of search on a graph
 - Given a graph G = (V, E) and a vertex v
 ∈ V, find all the vertices that are reachable from v.
 - Depth-first search
 - Breadth-first search

- Depth-first search
 - In visiting a node v,
 - Mark node v as VISITED
 - Select an unvisited node w, which is adjacent to v
 - Push w to a stack
 - Find the next node to visit among the adjacent vertices of v
 - If cannot find, v ← pop a stack

- Required data structure
 - visit[n]
 - visit[i] == 1, if node i is visited,
 == 0, if node i is unvisited
 - Stack → recursive call → function stack

```
void dfs ( int v )
    nodePointer w;
    visit[v] = TRUE;
     for ( w = graph[v]; w; w = w->link ) {
         if ( !visit[w->vertex] )
                                           Adjacency matrix \rightarrow O(n)
              dfs ( w->vertex );
                                            for ( int i = 0; i < n; i++ )
                                               if ( adjacency_matrix[v][i] != 0 )
                                            Adjacency list \rightarrow O(1) \sim O(n)
                                            for ( t = v; t != NULL; t = t->next)
     for all v in G
          if ( visit[v] == FALSE )
               dfs ( v );
```

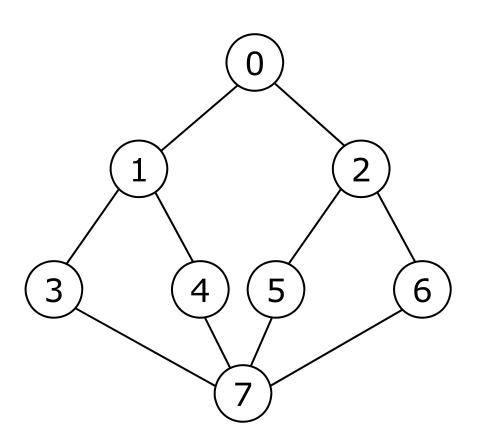
- Time complexity?
 - -O(n + m)
 - O(m) for visiting all edges
 - O(n) for visiting all vertices
 - O(n) > O(m) for a disconnected graph
 - -O(n) == O(m) for a sparse graph
 - O(n) < O(m) for a dense graph

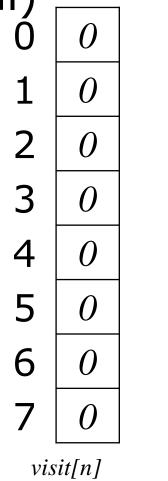


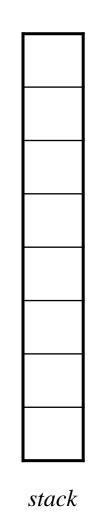
- Time complexity?
 - -O(n + m)
 - It depends on the representation
 - A sparse graph on a adjacency matrix ?
 - A sparse graph on a adjacency list?

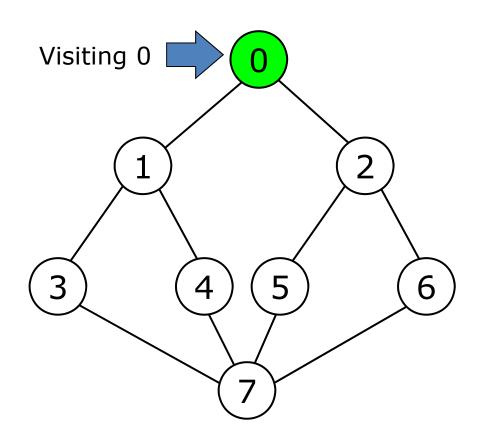
	Adjacency matrix	Adjacency list
Disconnected	O(n)	O(n)
Sparse	O(n ²)	O(n)
Dense	O(n ²)	O(n)

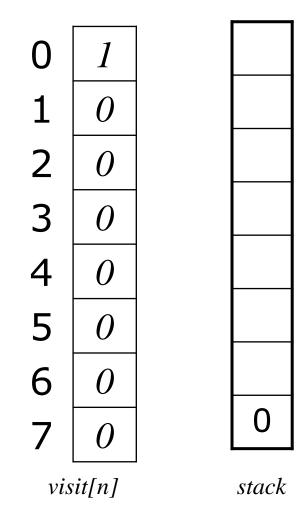
Depth-first search (Initial)

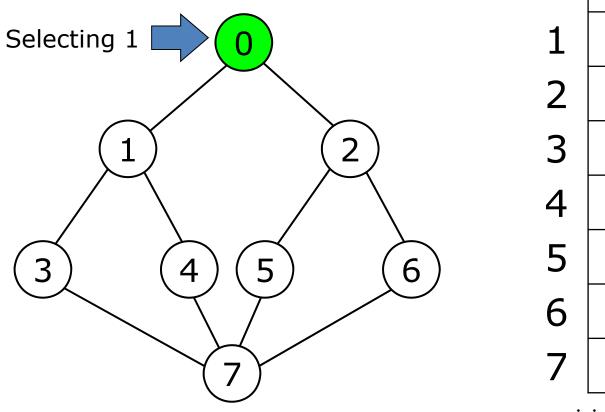


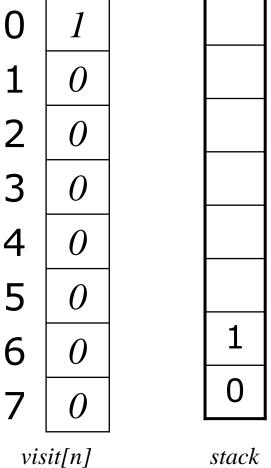


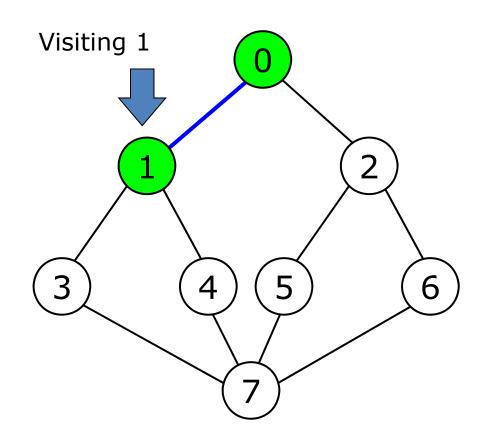


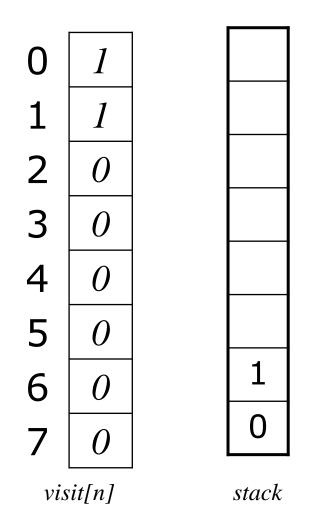


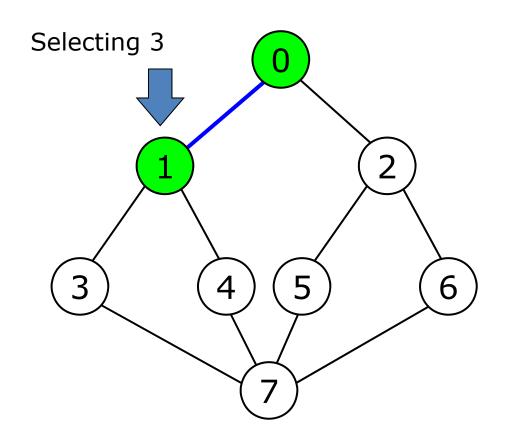


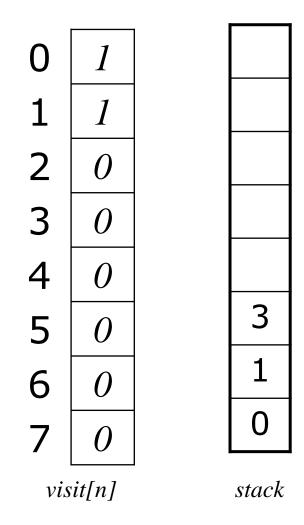


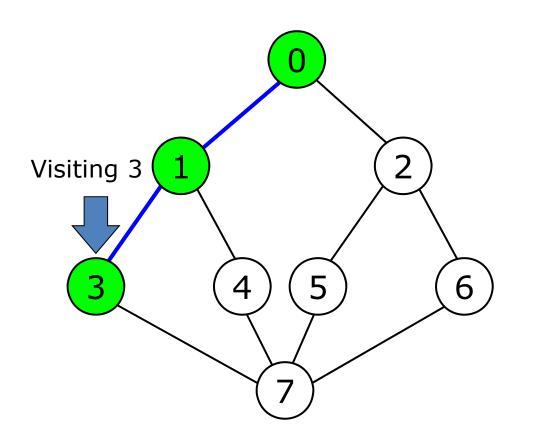


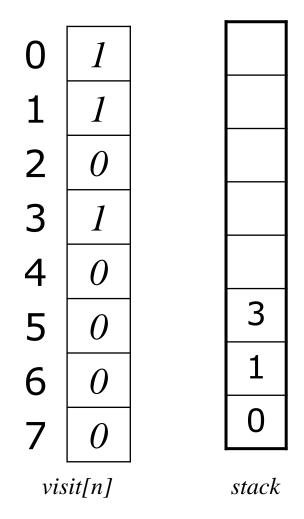


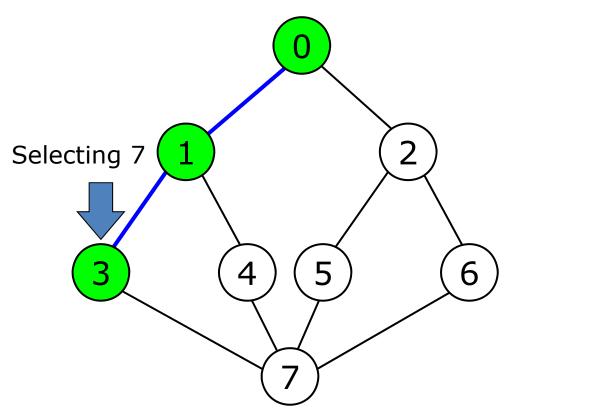


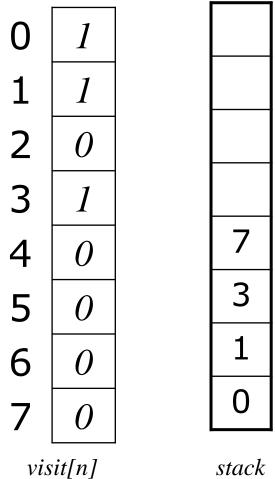


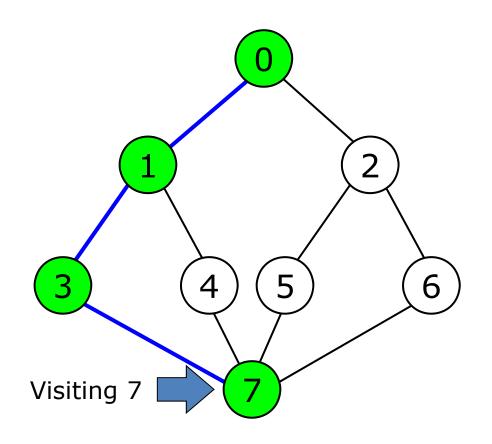


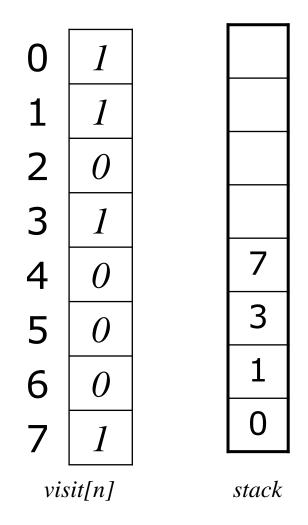


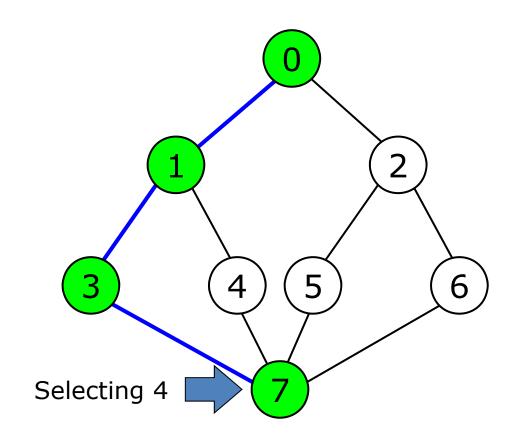


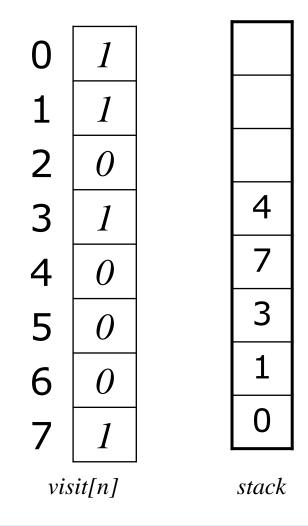


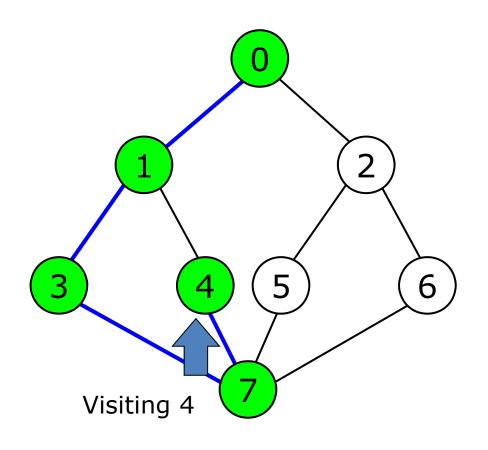


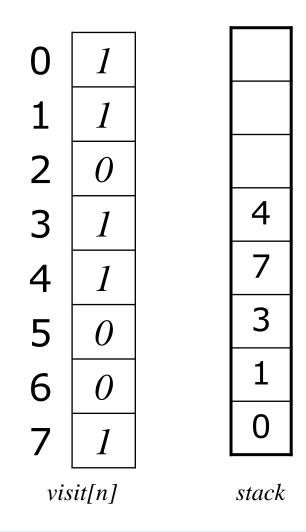


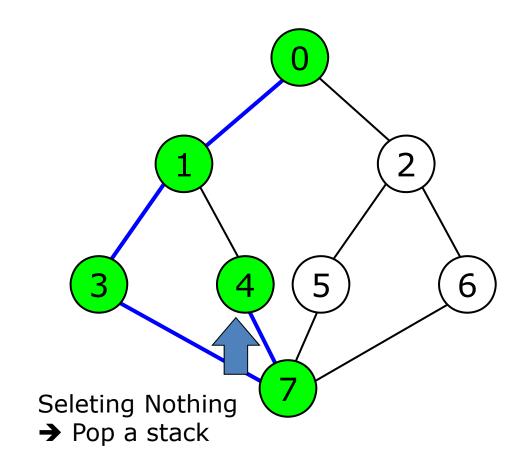


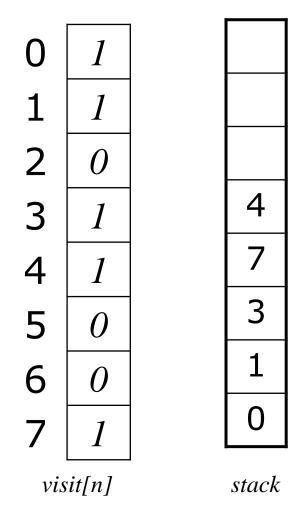


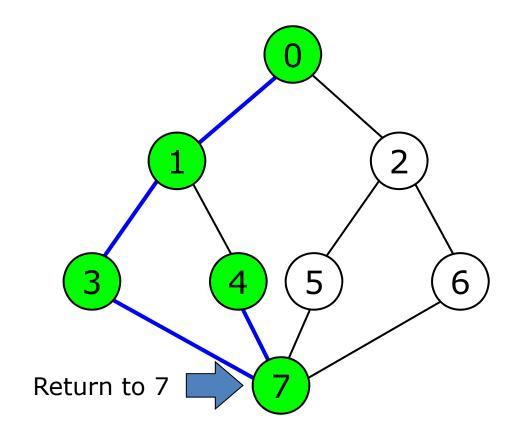


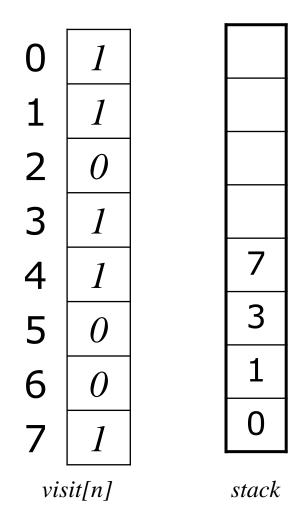


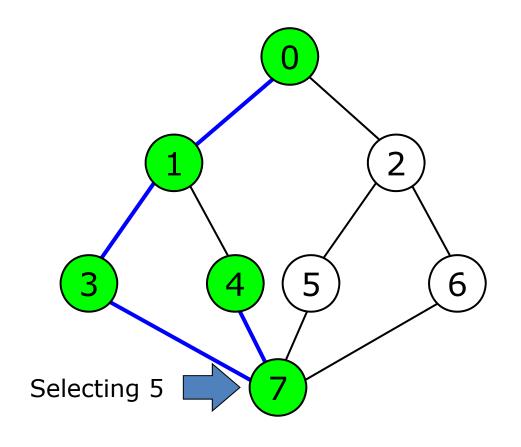


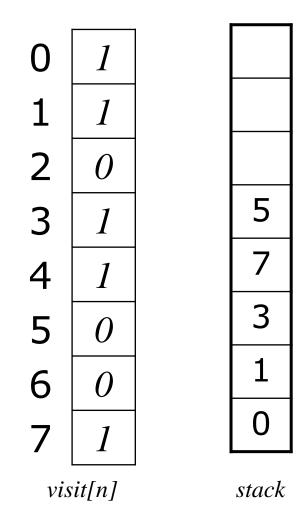


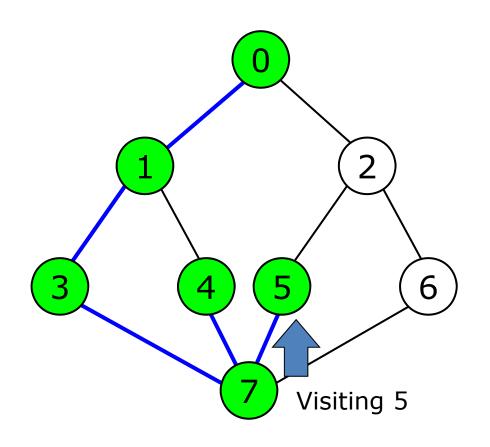


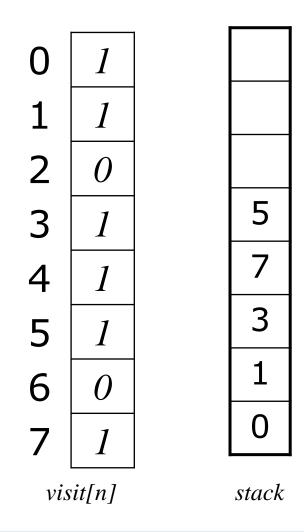


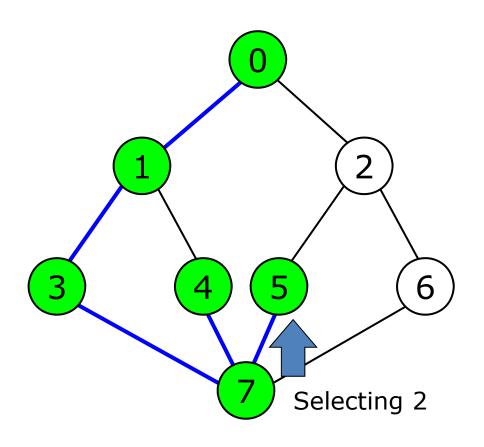


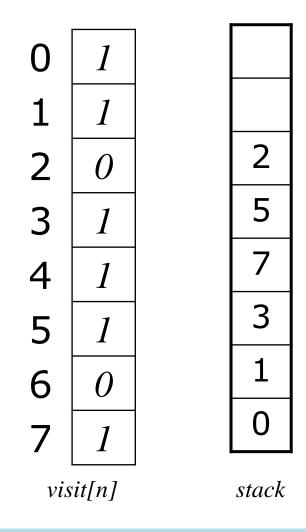


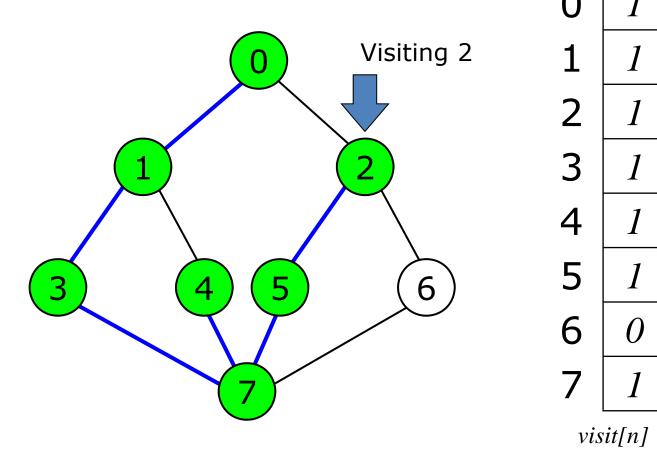


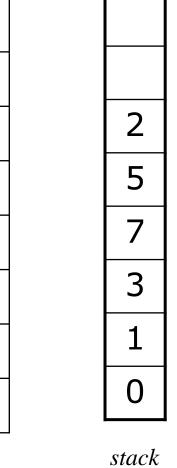




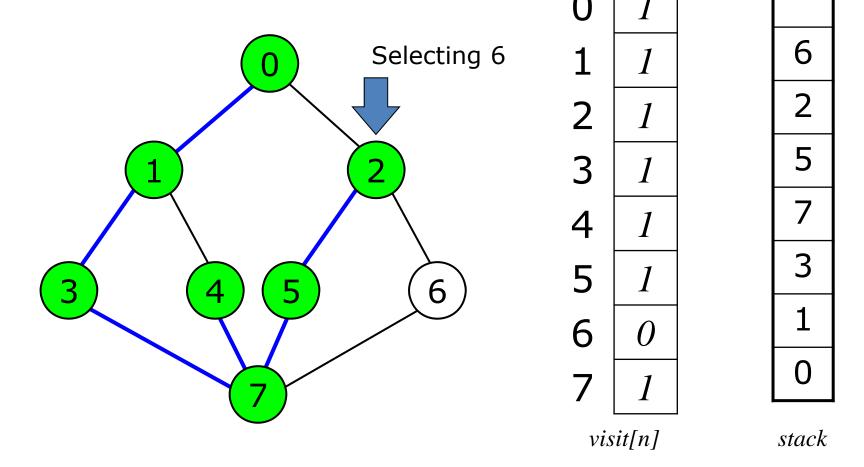




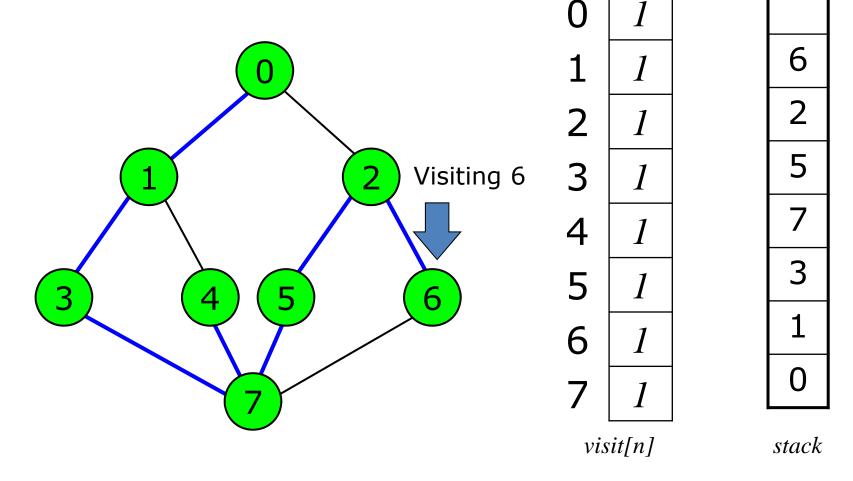




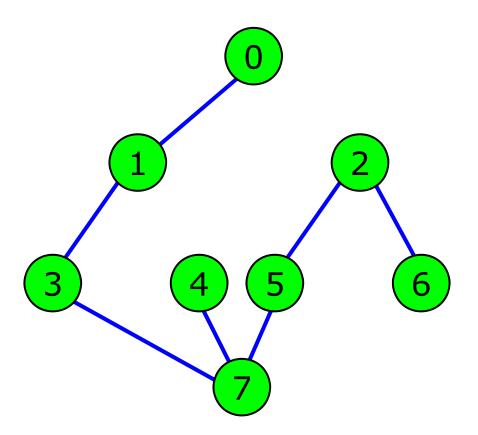
Depth-first search



Depth-first search

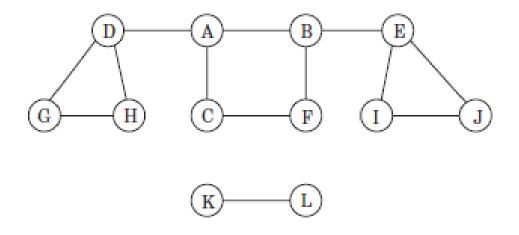


Depth-first spanning tree



 Depth-first spanning tree 9.4 Search

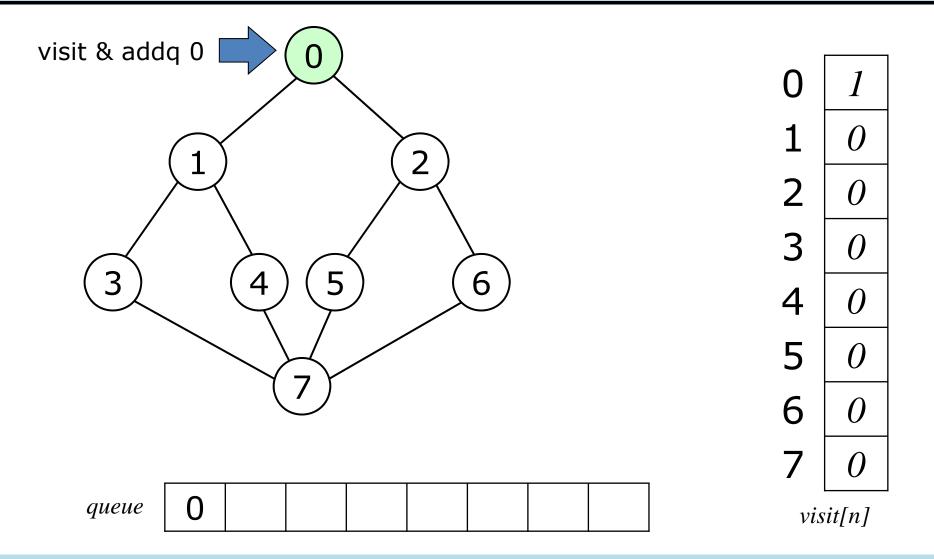
Exercise

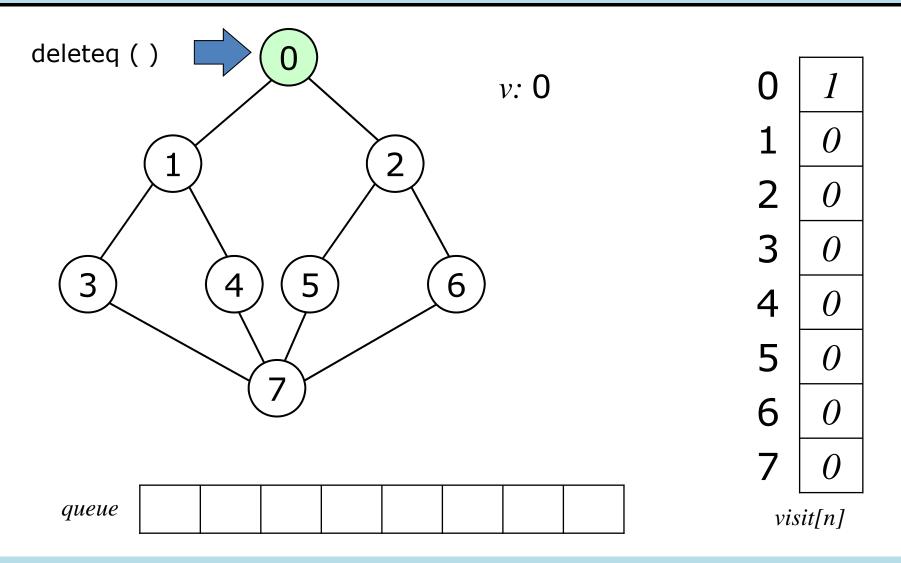


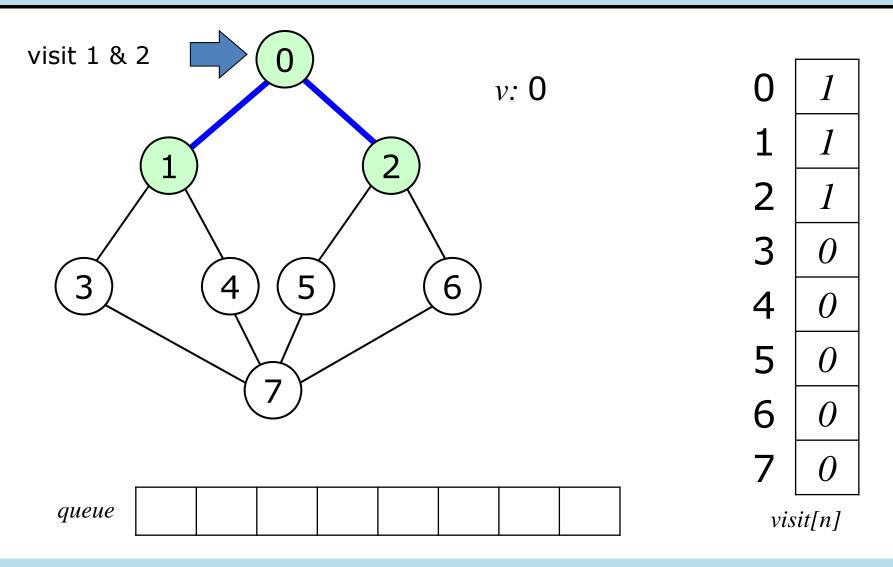
- Breadth-first search
 - Use a queue
 - In visiting a vertex v,
 - mark all the adjacent vertices as visited
 - add the vertices to the queue

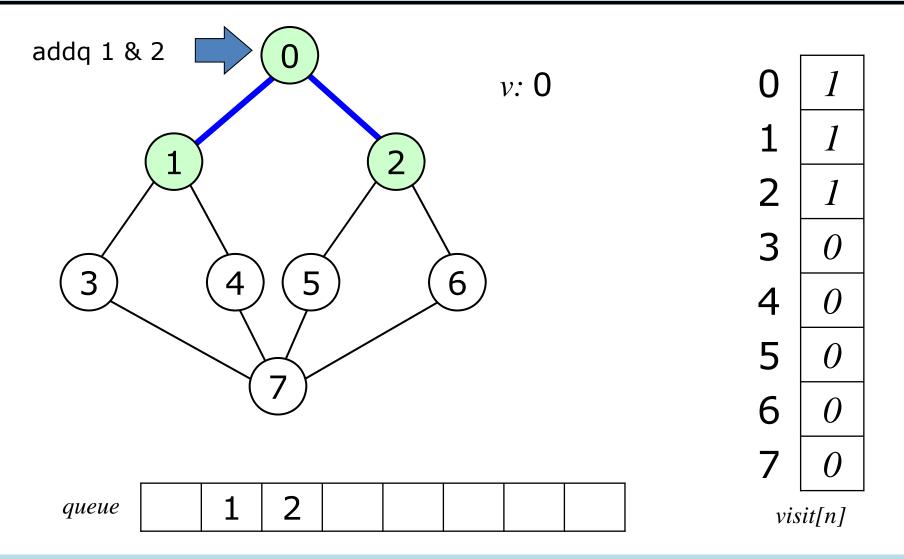
```
void bfs ( int v )
    nodePointer w;
    front = rear = NULL;
    visit[v] = TRUE;
    addq ( v );
    while ( front ) {
      v = deleteq ();
      for ( w = graph[v]; w; w = w -> link )
           if ( !visit[w->vertex] ) {
             visit[w->vertex] = TRUE;
             addq ( w->vertex );
```

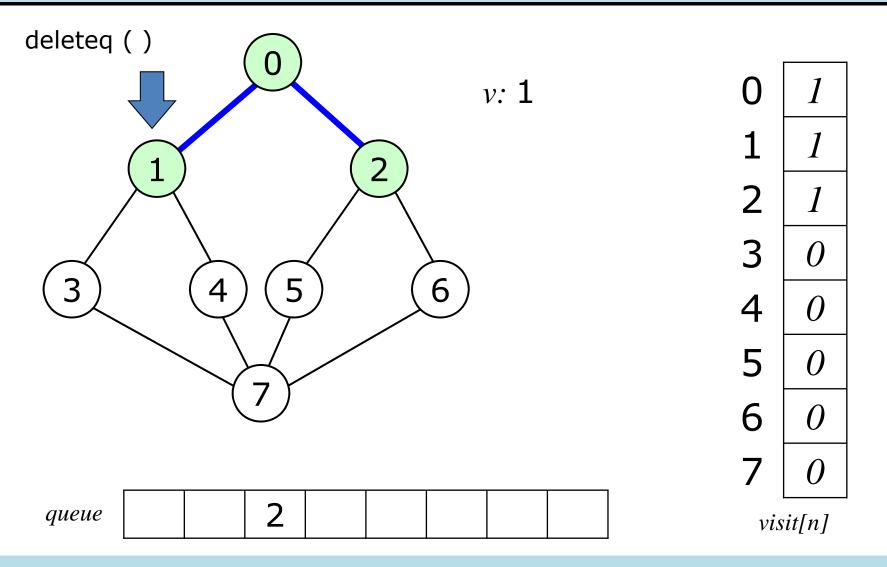
- Time complexity?
 - -O(n + m)
 - O(m) for visiting all edges
 - O(n) for visiting all vertices
 - O(n) > O(m) for a disconnected graph
 - O(n) == O(m) for a sparse graph
 - O(n) < O(m) for a dense graph
 - It depends on the representation
 - A sparse graph on a adjacency matrix ?
 - A sparse graph on a adjacency list?

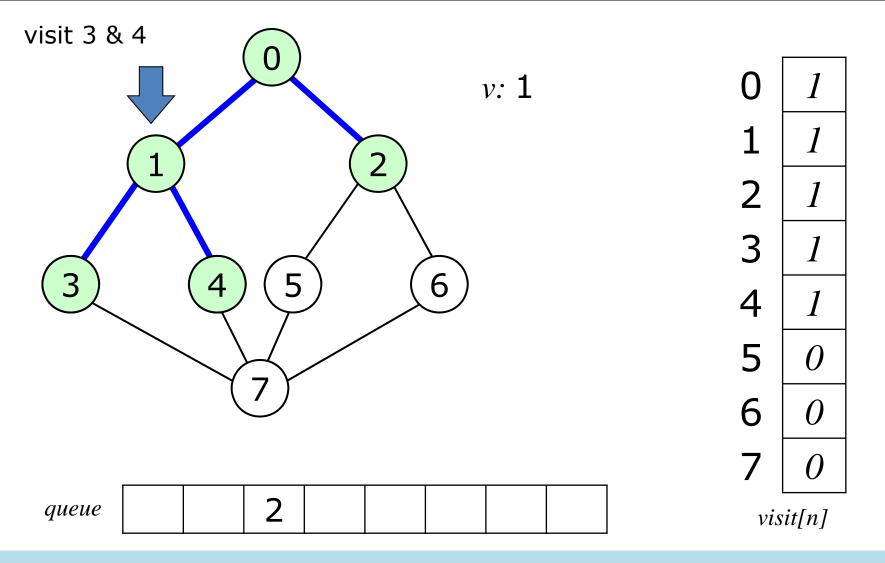


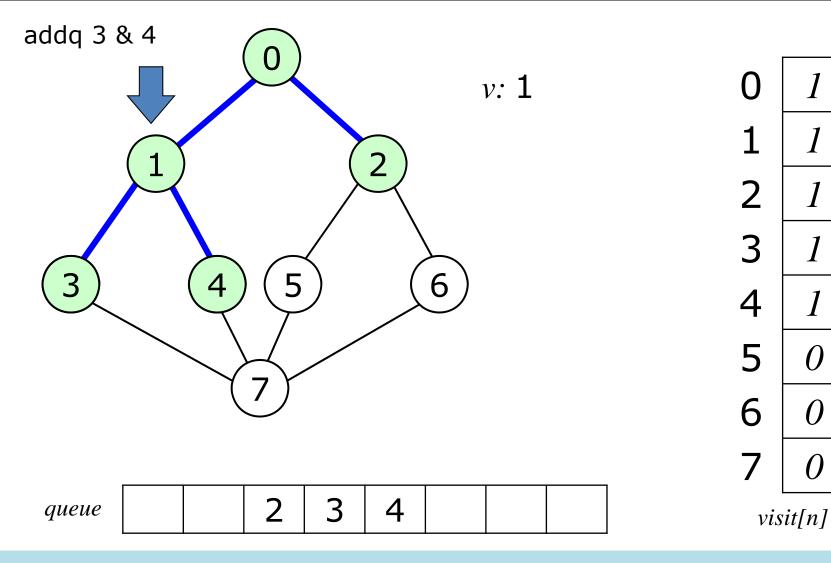


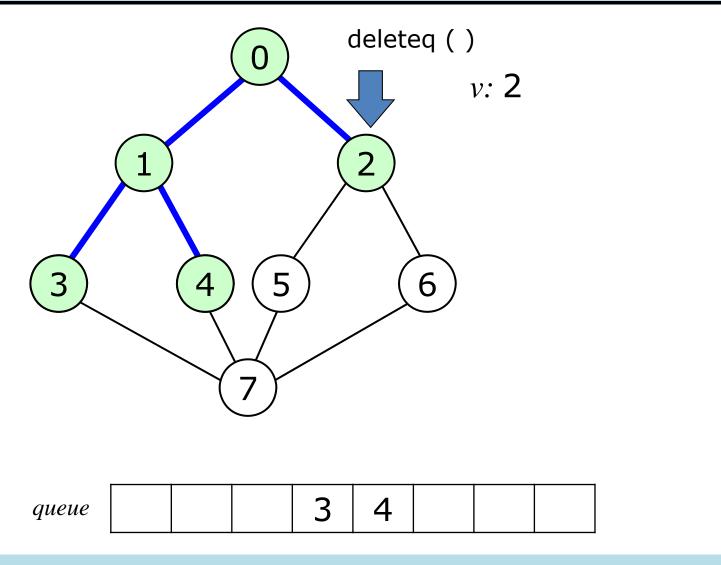


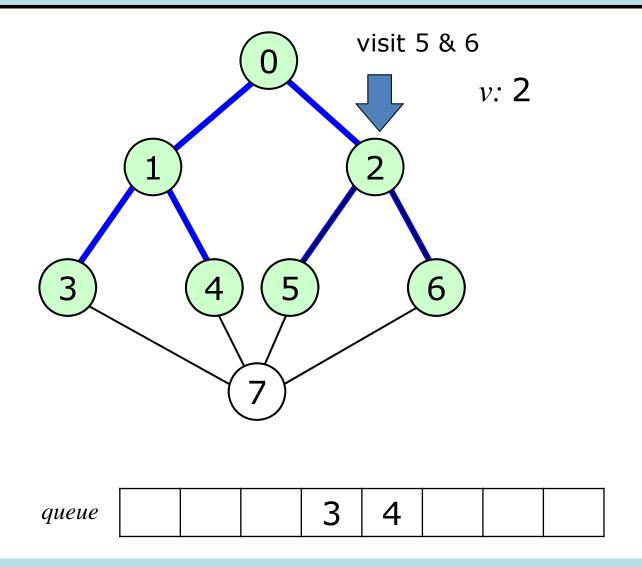


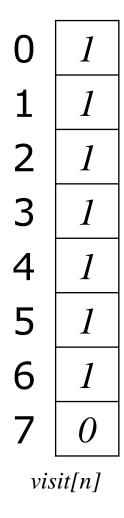


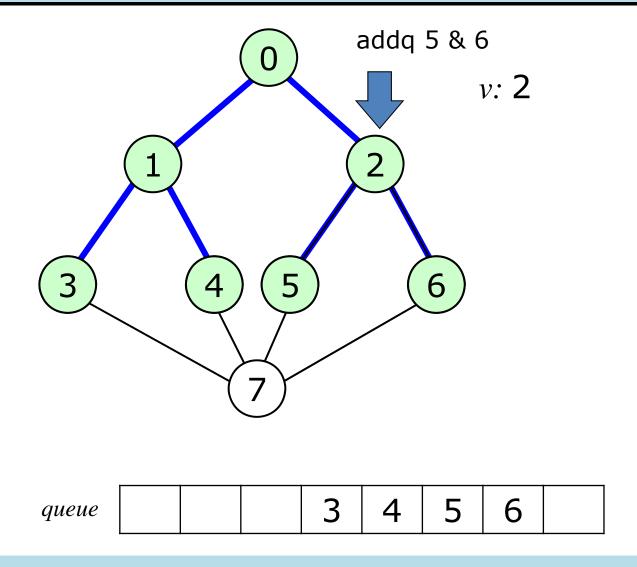


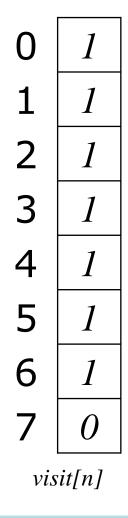


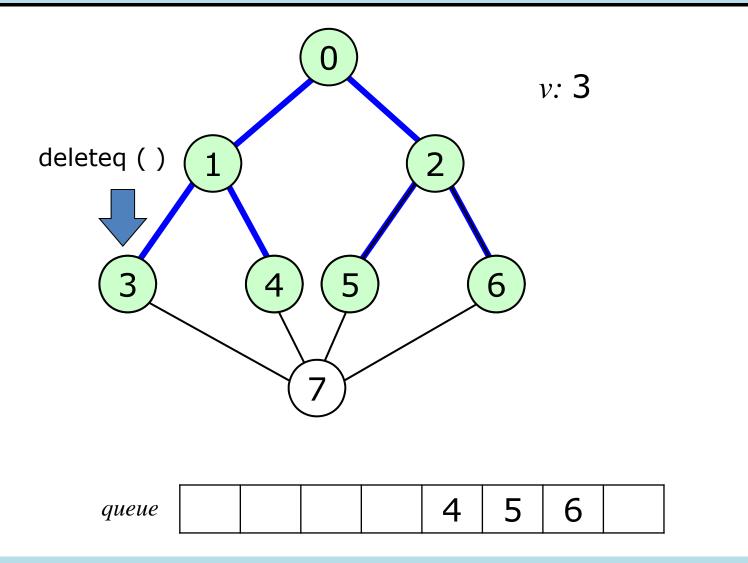


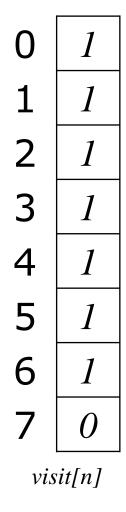


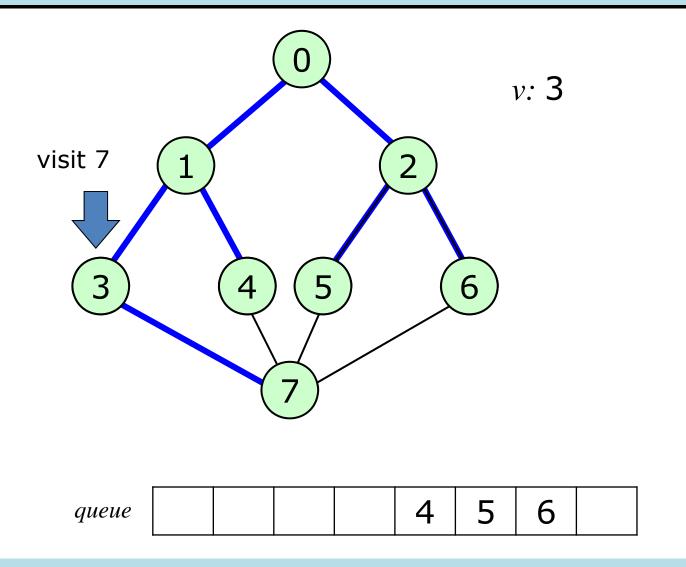


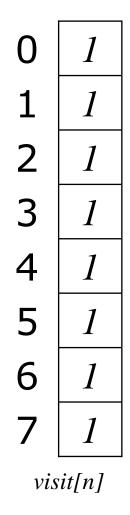


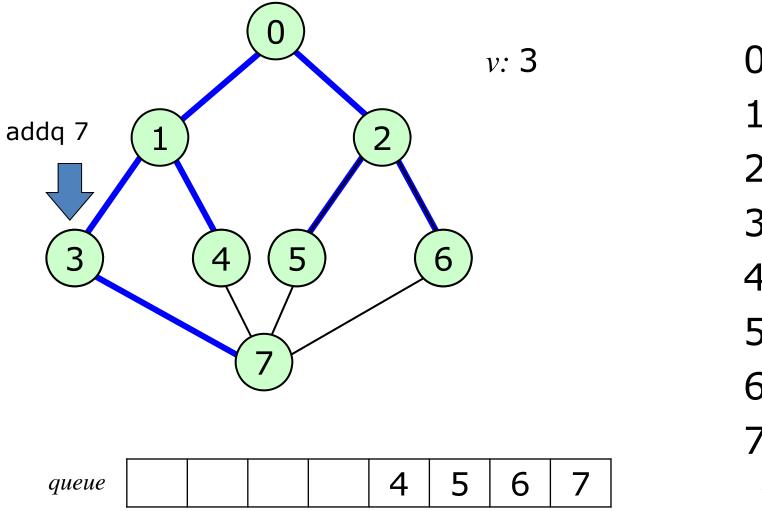




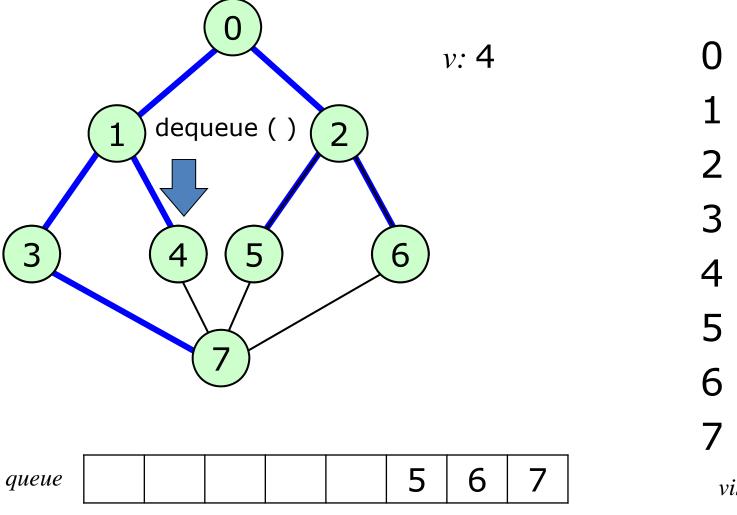




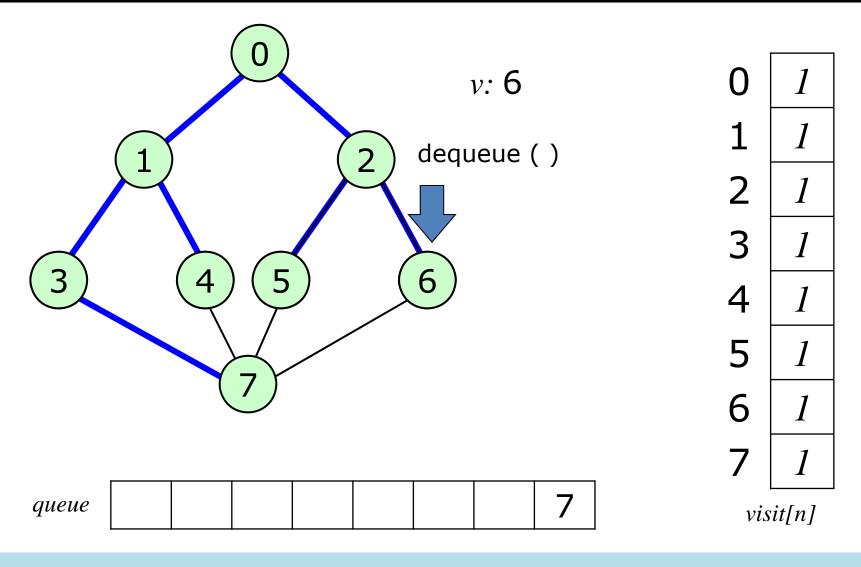


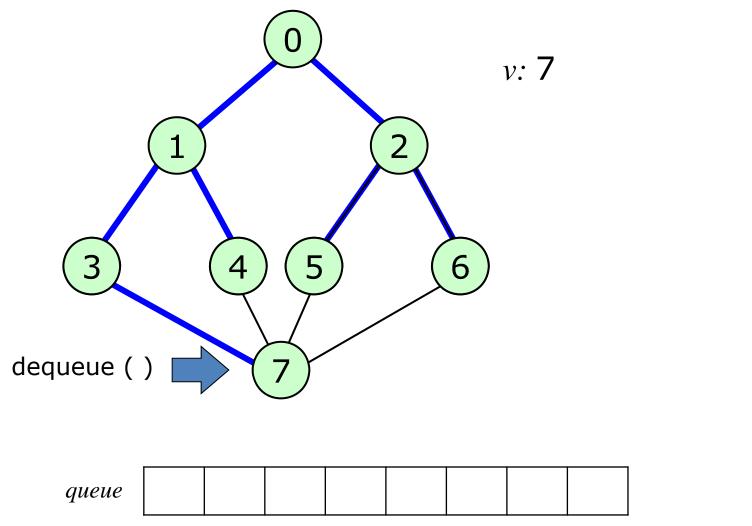


3 6 visit[n]



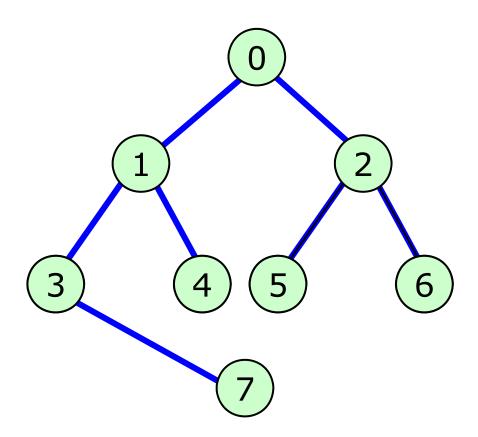
visit[n]



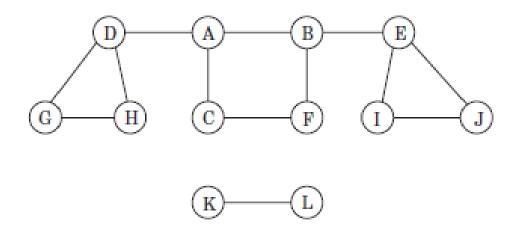




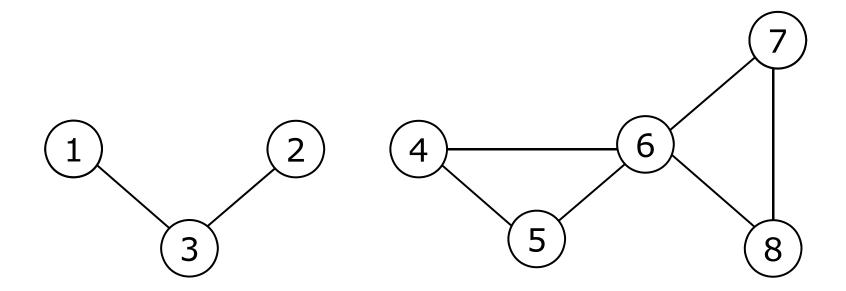
Breadth-first spanning tree



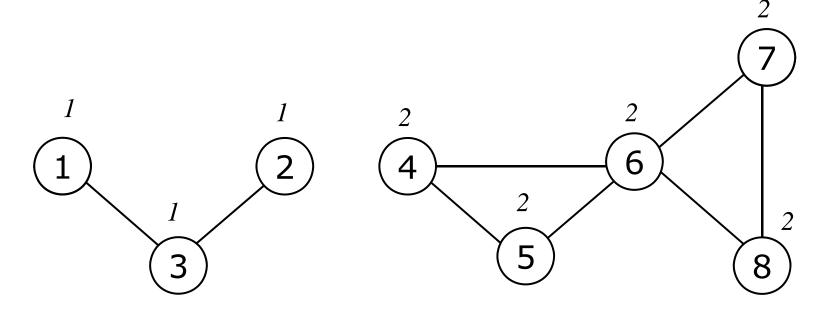
Exercise



- Mark the connected components of a graph
- Ex)



- Mark the connected components of a graph
- Ex)



- Use a search algorithm to explore all the vertices in a connected component
- In calling dfs () or bfs (), add an index for a connected component

```
void connected ( )
{
    int i;
    int idx = 1;
    for ( i = 0; i < n; i++ ) {
        if ( !visit[i] ) {
            dfs ( i, idx );
            idx++;
        }
    }
}</pre>
```

```
void dfs ( int v, int idx )
{
   nodePointer w;
   visit[v] = TRUE;
   v->label = idx;

   for ( w = graph[v]; w; w = w->link ) {
      if ( !visit[w->vertex] )
           dfs ( w->visit, idx );
    }
}
```

9.4.4 Spanning Trees

- Spanning tree
 - No. of vertices of G = n
 - No. of edges of the spanning tree of G → (n-1)
 - Use dfs () to create depth-first spanning tree

9.4.4 Spanning Trees

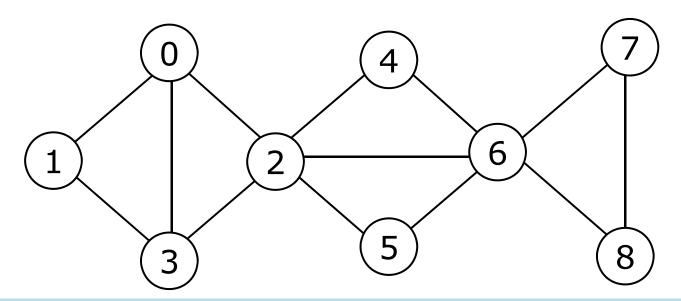
Depth-first spanning tree

```
void dfst ( int v )
{
    nodePointer w;
    visit[v] = TRUE;

    for ( w = graph[v]; w; w = w->link ) {
        if ( !visit[w->vertex] ) {
            add (v, w) to the depth-first spanning tree;
            dfst ( w->visit );
        }
    }
}
```

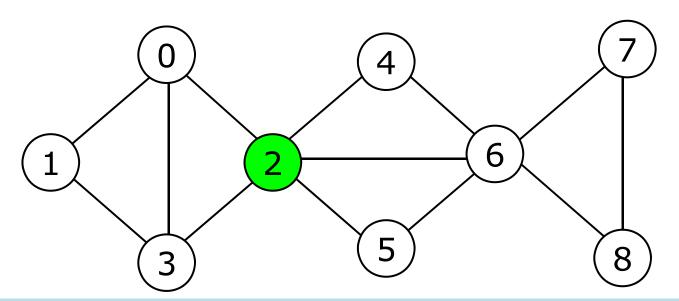
9.5 Biconnected Components

- Articulation point
 - A vertex v of G such that the deletion of v, together with all edges incident to v, produces a graph G' that has at least two connected components



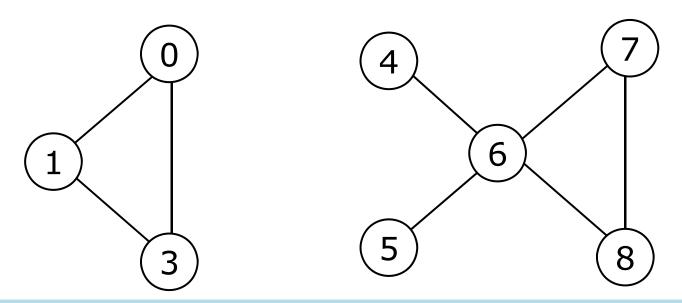
9.5 Biconnected Components

- Articulation point
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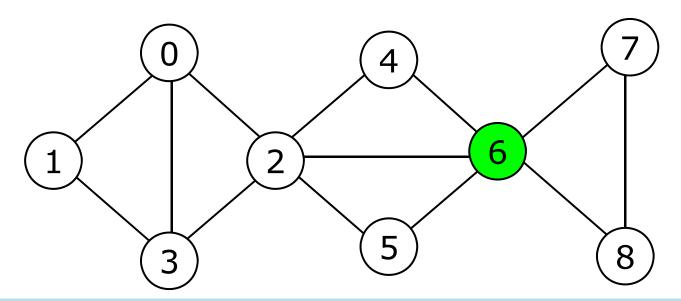


9.5 Biconnected Components

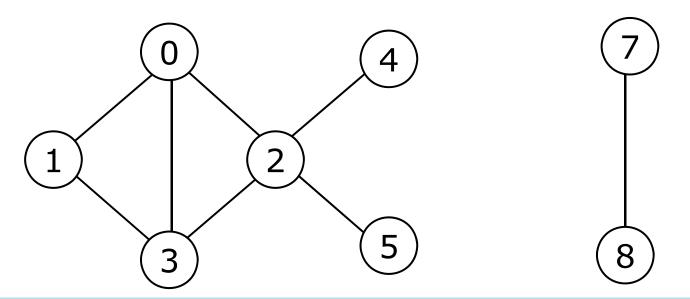
- Articulation point
 - A vertex v of G such that the deletion of v, together with all edges incident to v, produces a graph G' that has at least two connected components



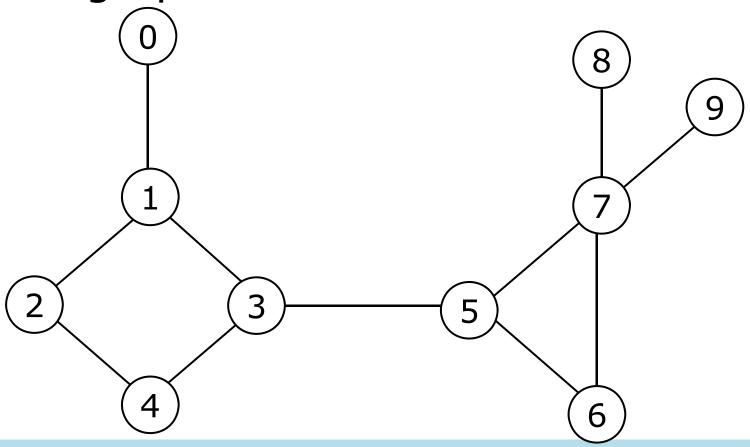
- Articulation point
 - A vertex v of G such that the deletion of v, together with all edges incident to v, produces a graph G' that has at least two connected components



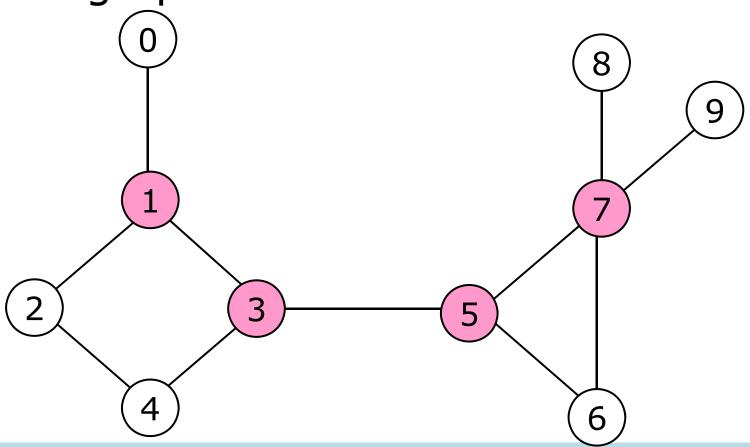
- Articulation point
 - A vertex v of G such that the deletion of v, together with all edges incident to v, produces a graph G' that has at least two connected components



 Ex) What is the articulation point on this graph?

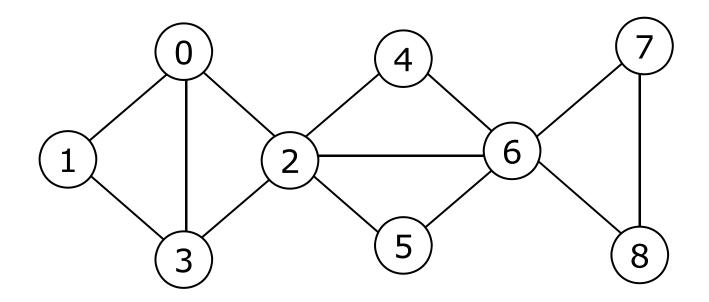


 Ex) What is the articulation point on this graph?

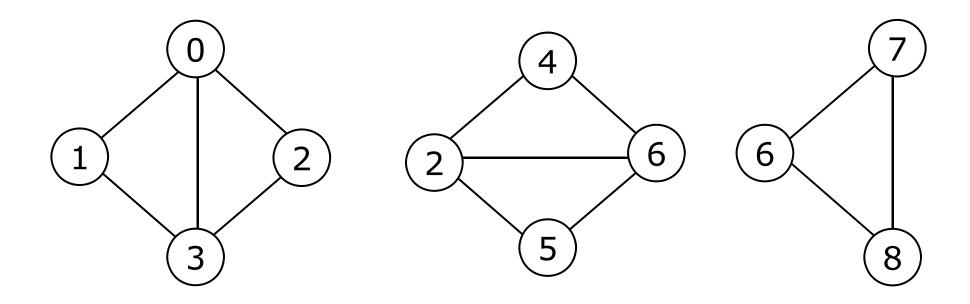


- Biconnected graph
 - A connected graph that has no articulation points

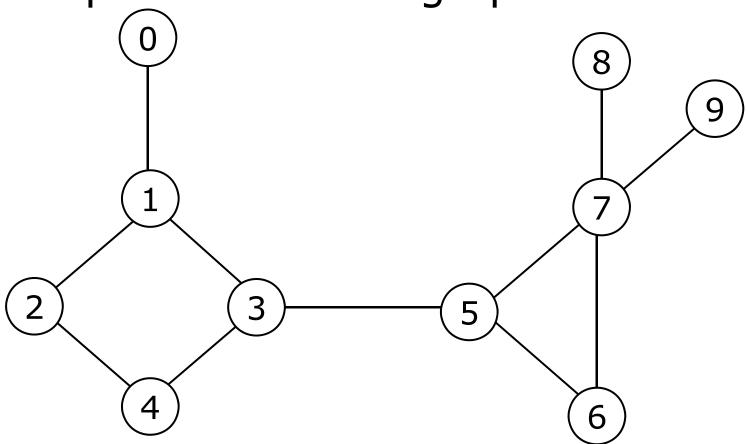
- Biconnected component
 - A maximal biconnected subgraph



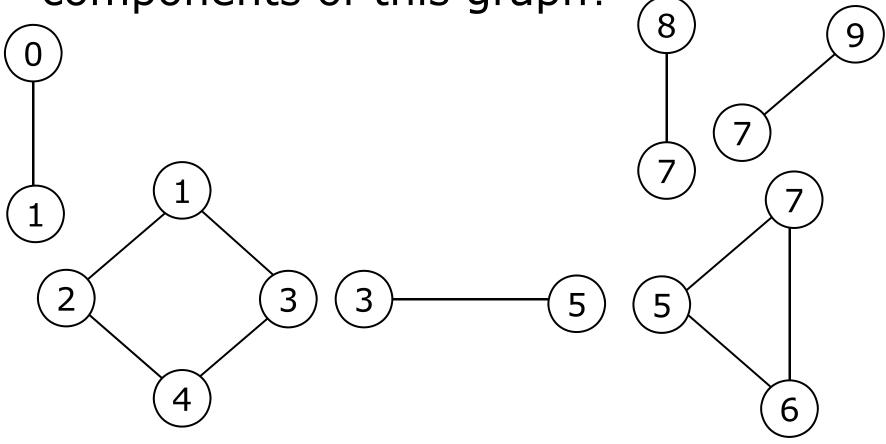
- Biconnected component
 - A maximal biconnected subgraph



 Ex) What are the biconnected components of this graph?

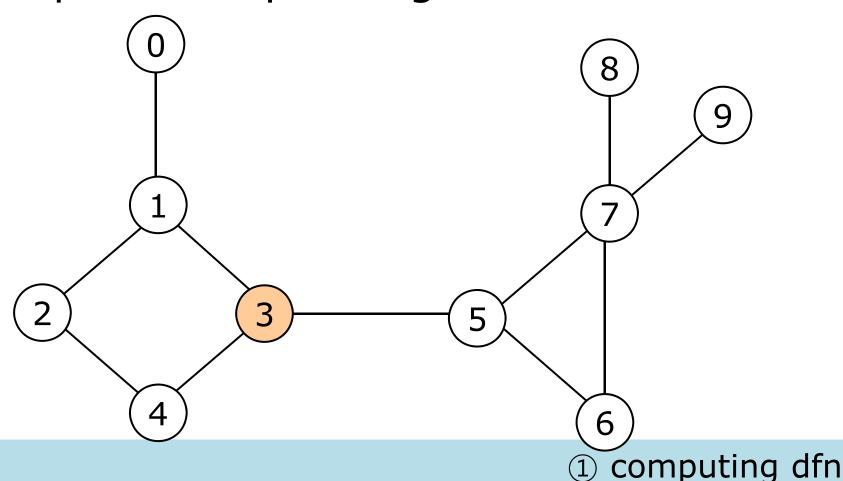


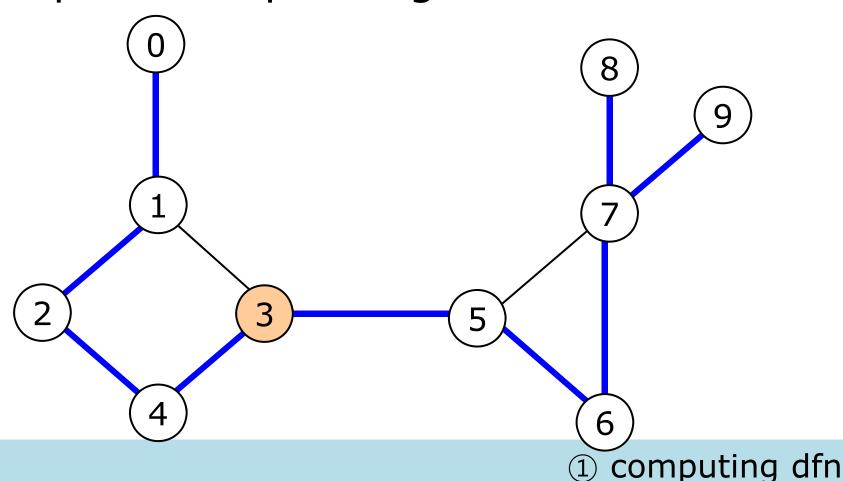
 Ex) What are the biconnected components of this graph?

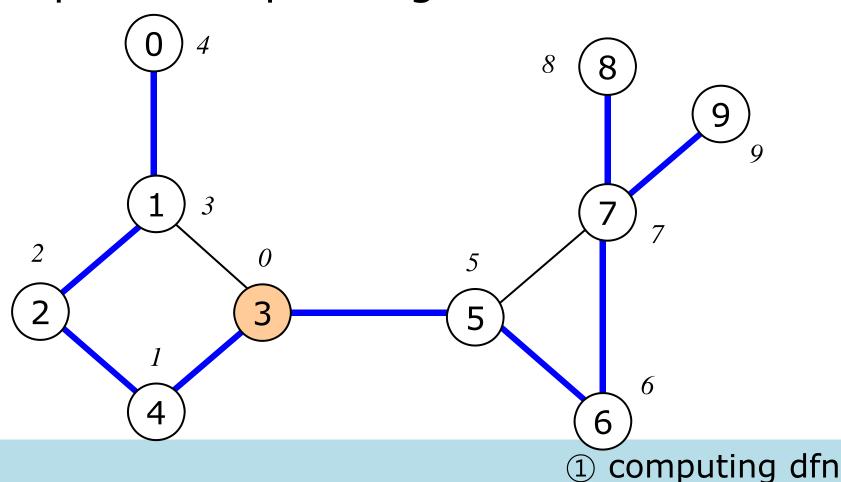


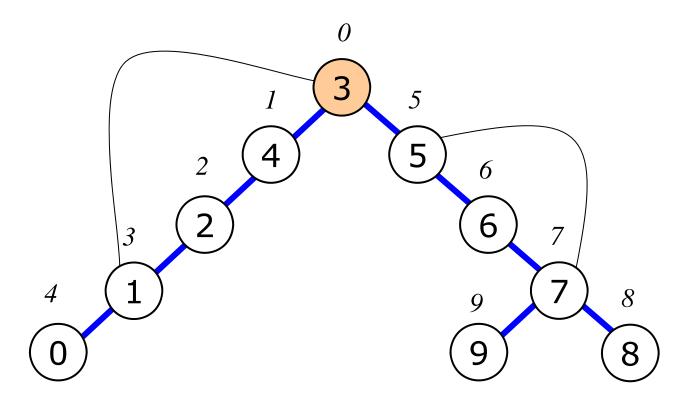
- Steps to compute biconnected components
- (1) Computing articulation points
 - 1 computing dfn
 - 2 finding back edge
 - 3 definition of articulation point
 - 4 computing articulation points
- (2) Decomposition of a graph into biconnected components using articulation points

- 1 computing dfn
 - dfn: depth-first number
 - computed by depth-first search
 - dfn of a vertex
 - The sequence in which the vertices are visited during depth-first search





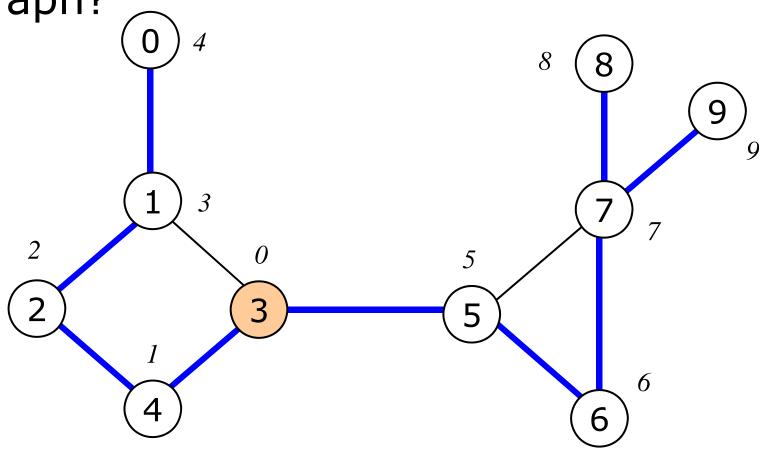




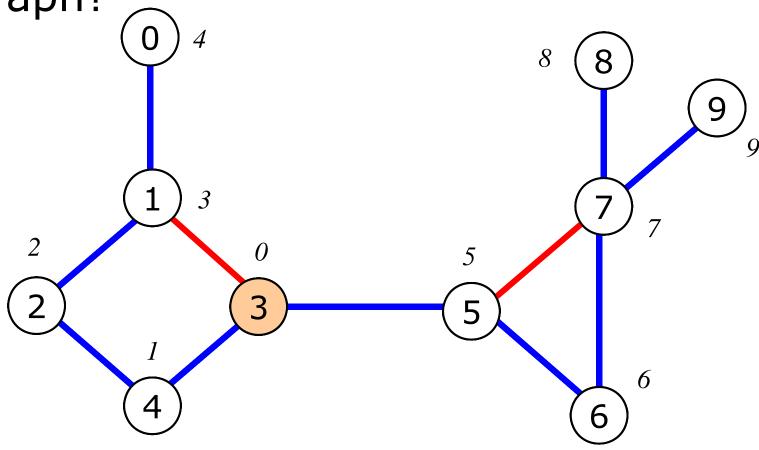
- Property of dfn
 - u is an ancestor of v in the depth-first spanning tree \rightarrow dfn(u) < dfn(v)
 - -Ex) Vertex 4 is the ancestor of vertex 1 \rightarrow dfn(4) = 1 < dfn(1) = 3

- ② Back edge
 - Edges in G = edges in the spanning tree+ nontree edges
 - Back edge:
 - A nontree edge (u, v), if u is an ancestor of v or vice versa
 - In depth-first spanning tree, all the nontree edges are back edges

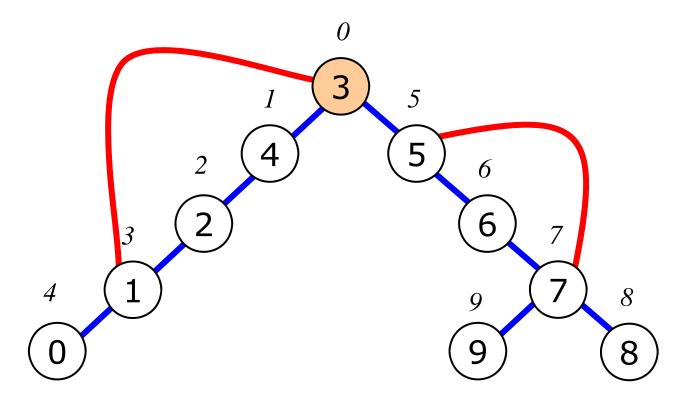
Ex) What are the back edges of this graph?



Ex) What are the back edges of this graph?

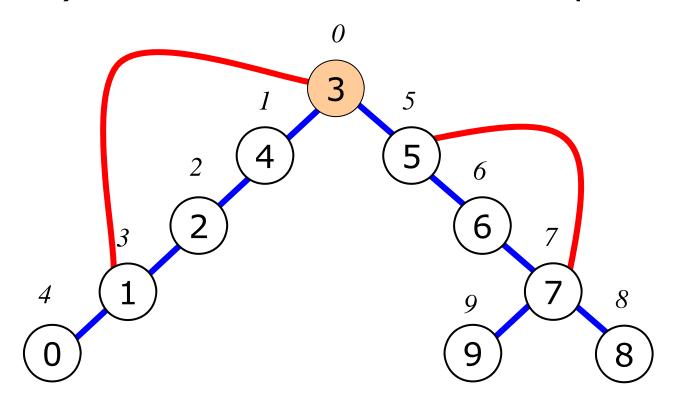


Ex) What are the back edges of this graph?

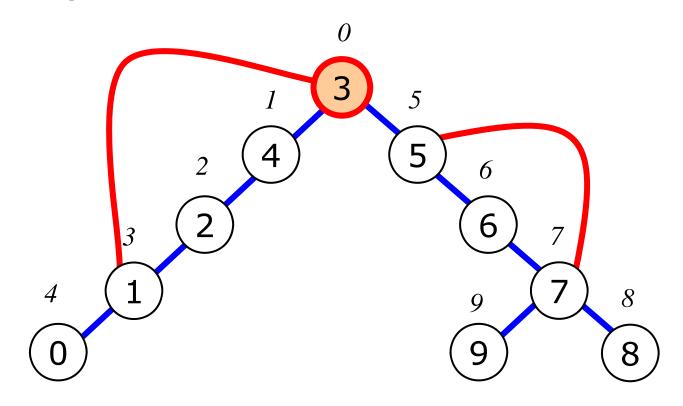


- 3 Definition of articulation point (1)
 - A root of a depth-first spanning tree is an articulation point, if it has at least two childs

- Articulation points
 - Ex) What are the articulation points?

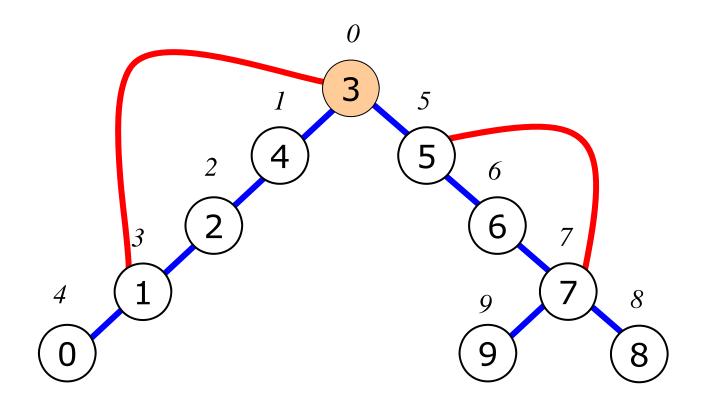


Articulation points

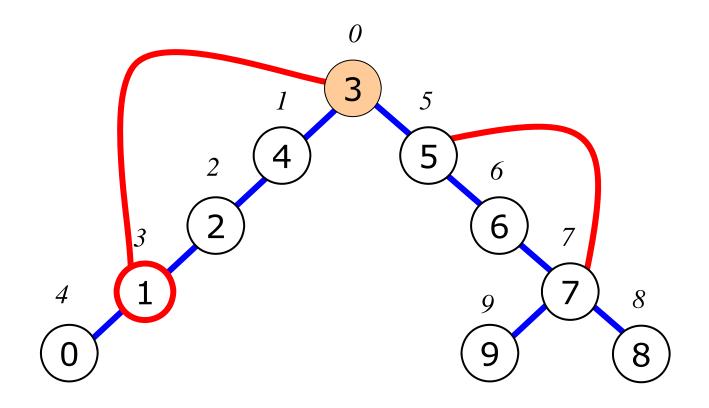


- 3 Definition of articulation point (2)
 - A vertex u, if it has at least one child w such that a path (w, descendants of w, and a single back edge, ancestor of u) does not exist

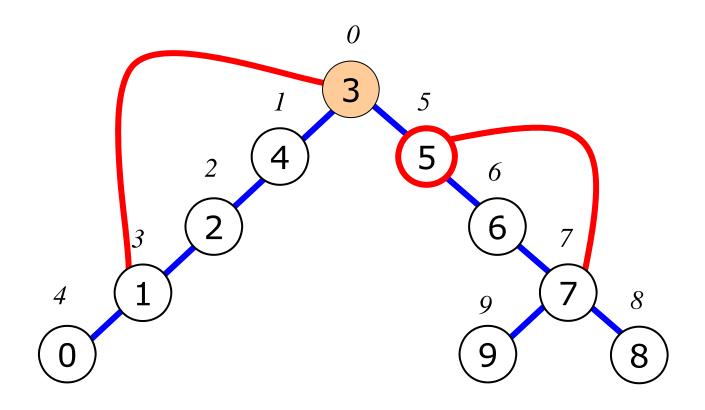
Ex) Is vertex 4 an articulation point?



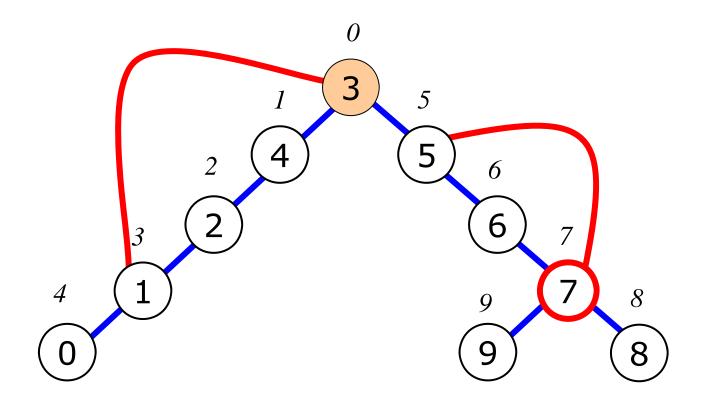
Ex) Is vertex 1 an articulation point?



Ex) Is vertex 5 an articulation point?



Ex) Is vertex 7 an articulation point?

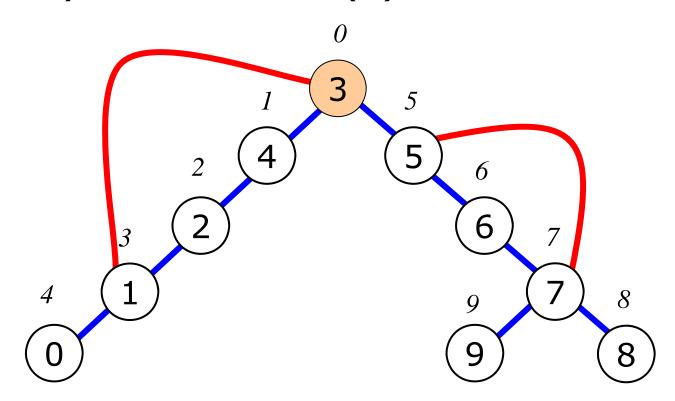


- 4 computing articulation points
 - Define a new value low for each vertex u, such as low(u)
 - low(u)
 - The lowest depth first number that we can reach from u using a path of descendants followed by at most one back edge

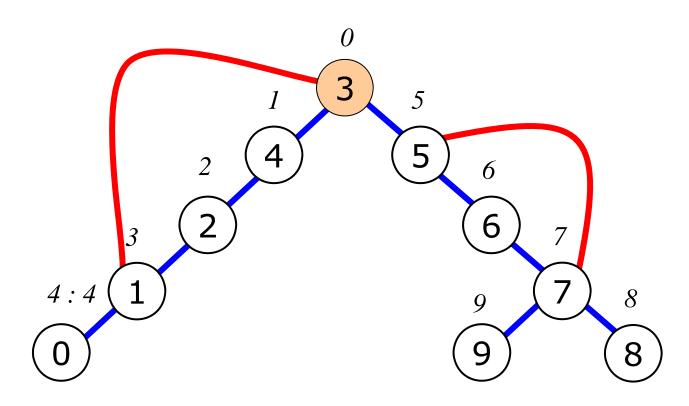
```
low(u) = min\{dfn(u),
min\{low(w) \mid w \text{ is a child of } u\},
min\{dfn(v) \mid (u,v) \text{ is a back edge}\}\}
```

4 computing articulation points

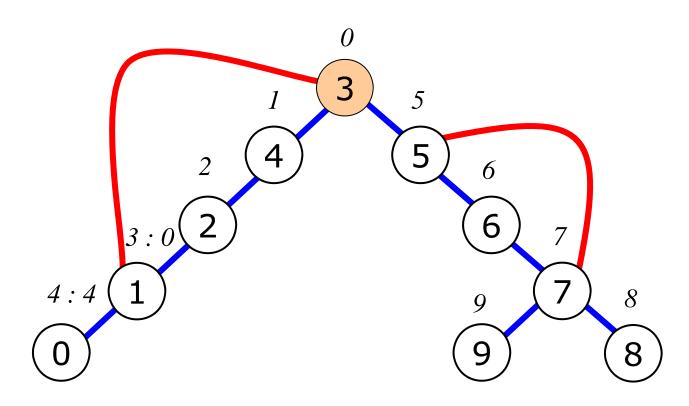
- low(u)
 - Ex) What are low(u)?



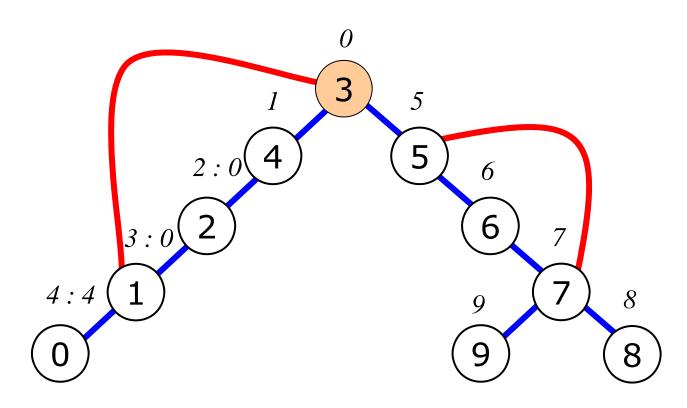
- low(u)
 - -Ex) What are low(0)?



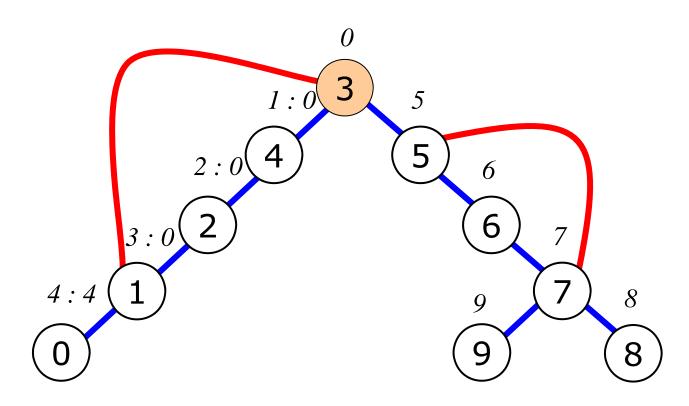
- low(u)
 - -Ex) What are low(1)?



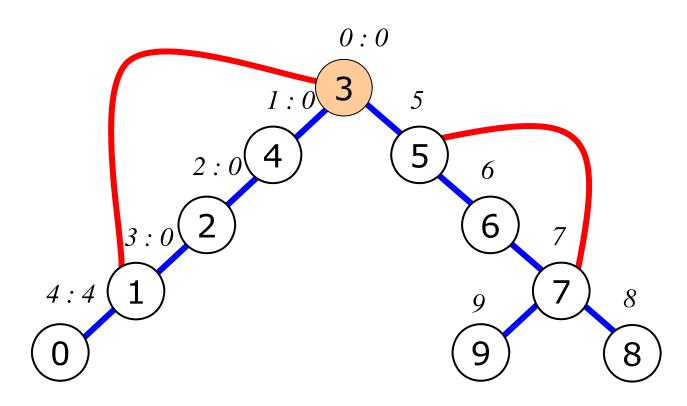
- low(u)
 - -Ex) What are low(2)?



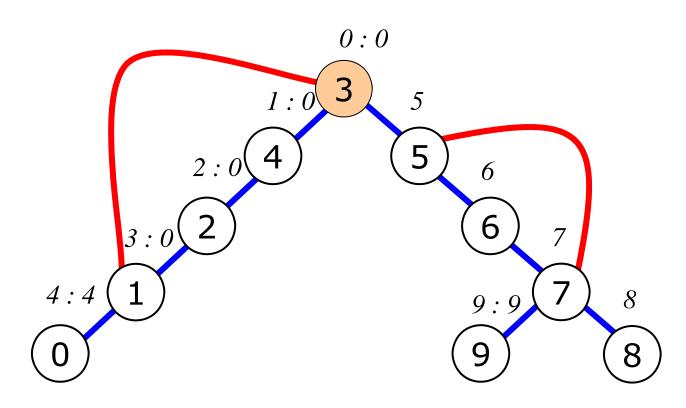
- low(u)
 - -Ex) What are low(4)?



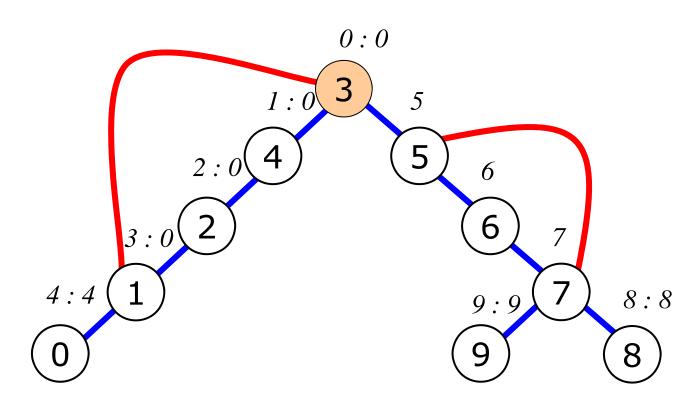
- low(u)
 - -Ex) What are low(3)?



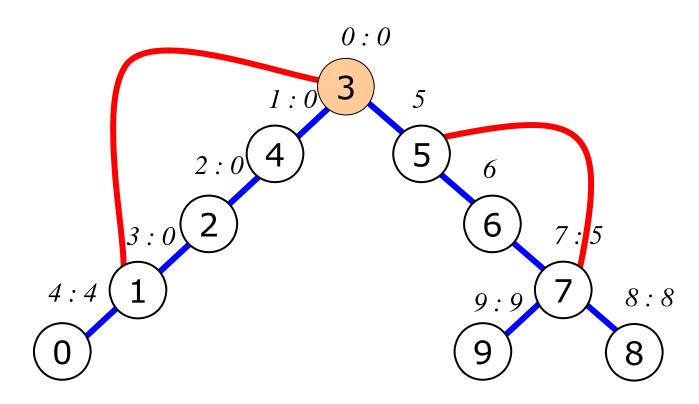
- low(u)
 - -Ex) What are low(9)?



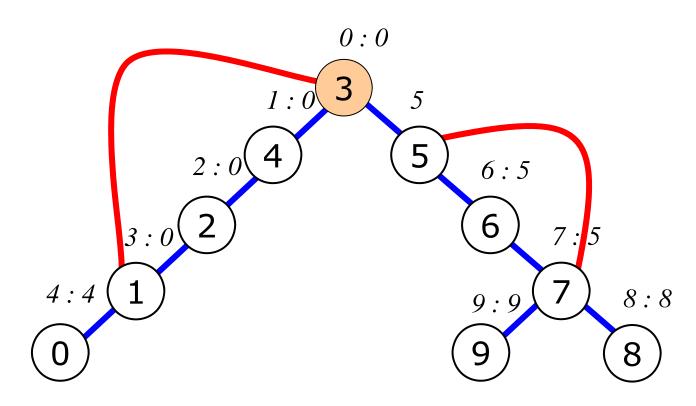
- low(u)
 - -Ex) What are low(8)?



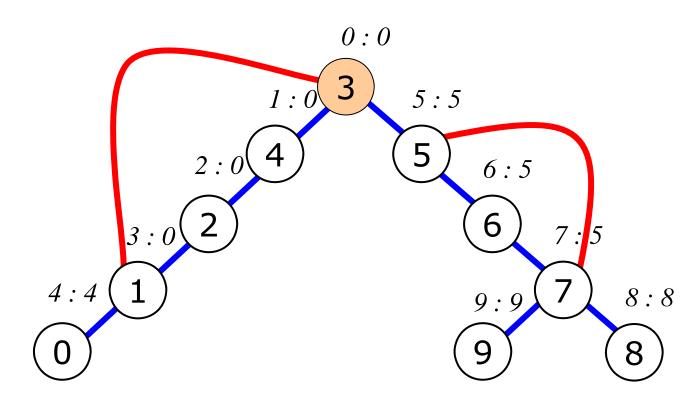
- low(u)
 - -Ex) What are low(7)?



- low(u)
 - -Ex) What are low(6)?



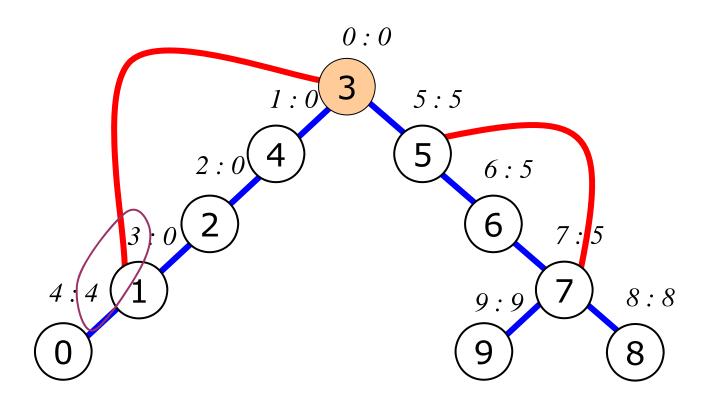
- low(u)
 - -Ex) What are low(5)?



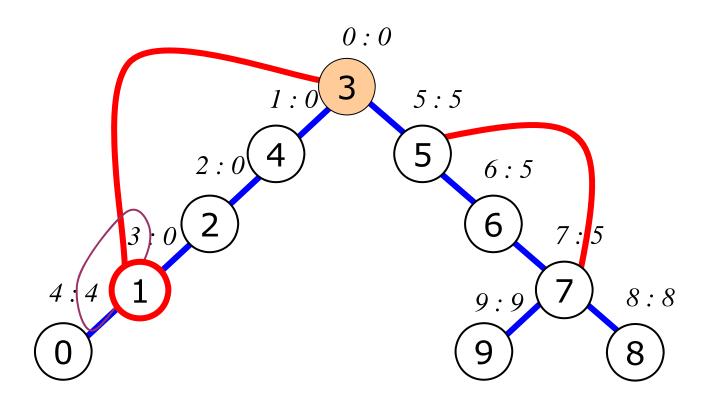
- Articulation points
 - u is an articulation point,
 - if u is either the root of the spanning tree with two or more childs,
 - or u is not a root and has a child w such that $low(w) \ge dfn(u)$

	0	1	2	3	4	5	6	7	8	9
		3								
low	4	0	0	0	0	5	5	5	8	9

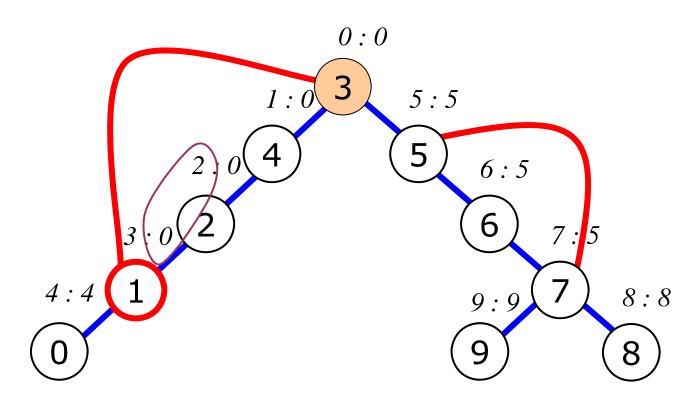
- Determine articulation points
 - At 1, low(w) \geq dfn(u)?



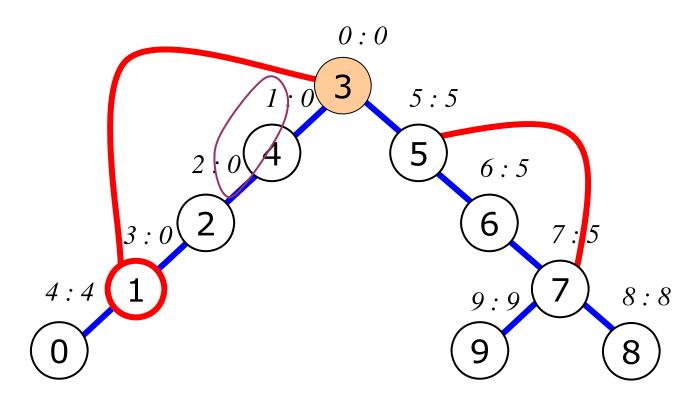
- Determine articulation points
 - At 1, low(w) \geq dfn(u)?



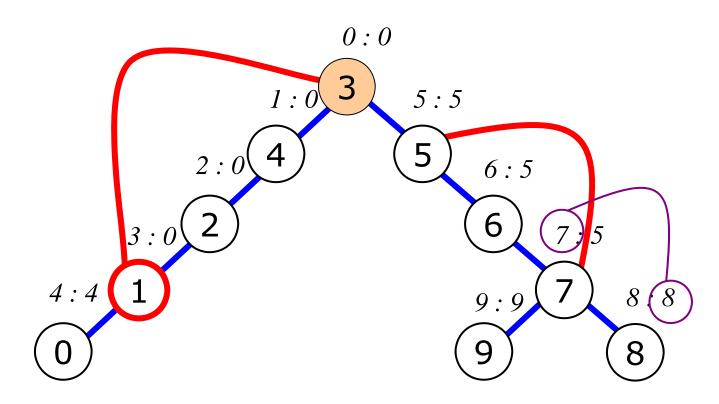
- Determine articulation points
 - -At 2, $low(w) \ge dfn(u)$?



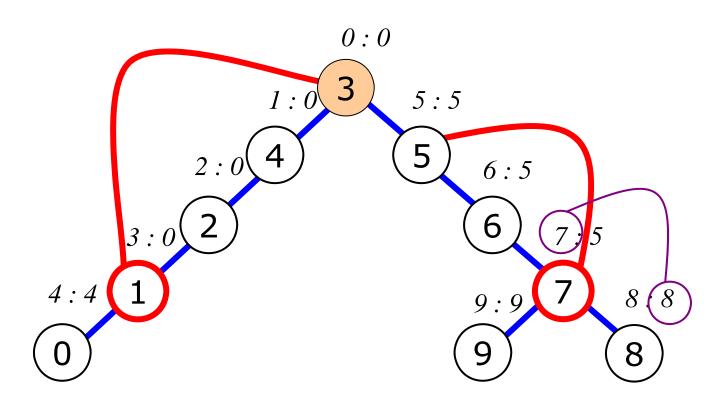
- Determine articulation points
 - -At 4, $low(w) \ge dfn(u)$?



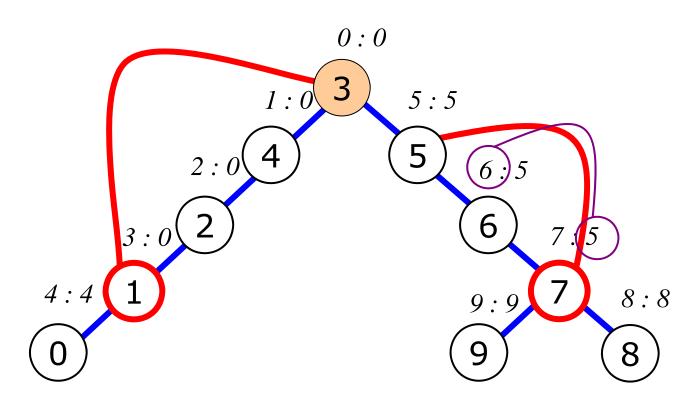
- Determine articulation points
 - -At 7, $low(w) \ge dfn(u)$?



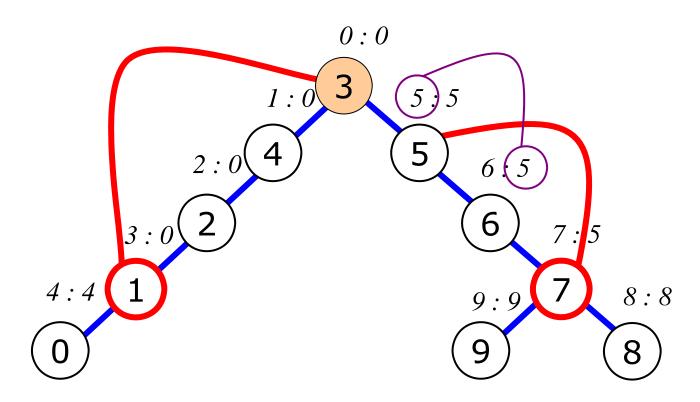
- Determine articulation points
 - -At 7, $low(w) \ge dfn(u)$?



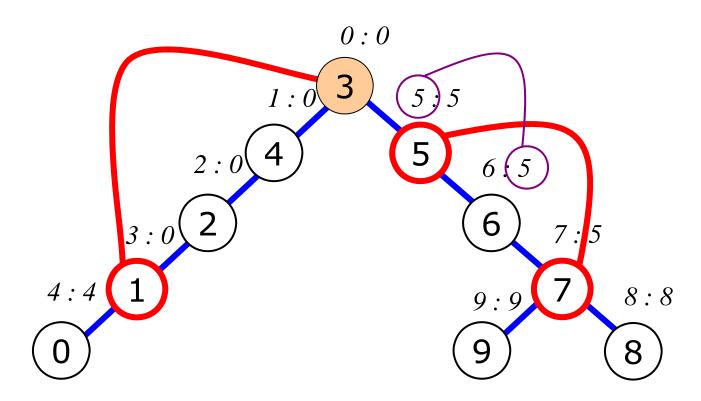
- Determine articulation points
 - -At 6, $low(w) \ge dfn(u)$?



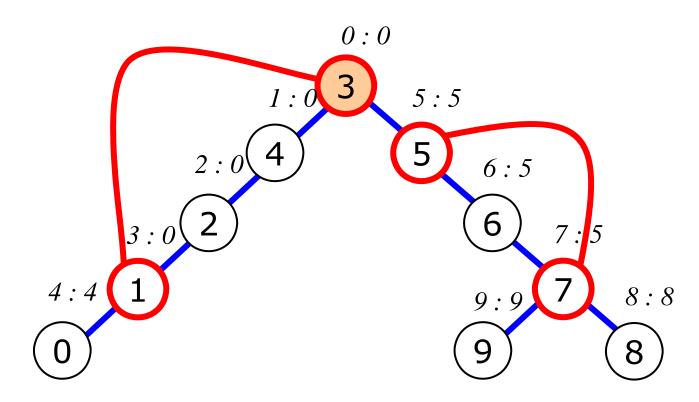
- Determine articulation points
 - At 5, $low(w) \ge dfn(u)$?



- Determine articulation points
 - At 5, $low(w) \ge dfn(u)$?

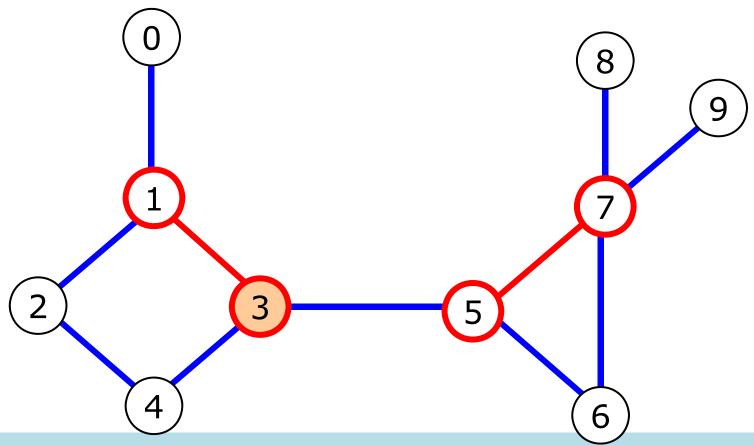


- Total articulation points
 - $-\{u \mid low(w) \ge dfn(u)\} + root$



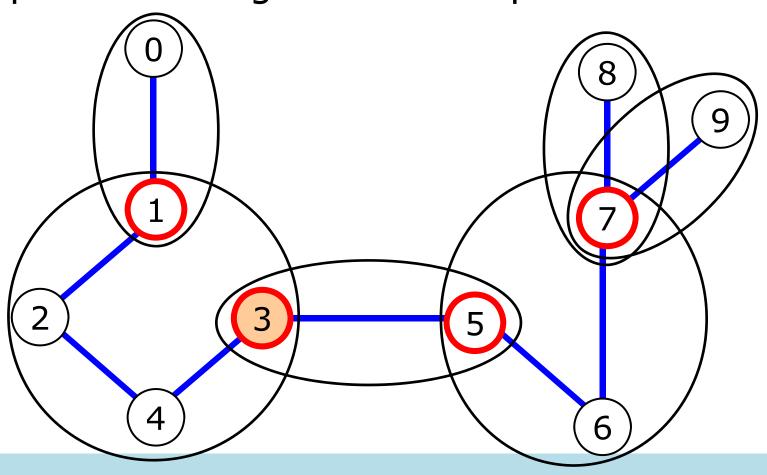
Total articulation points

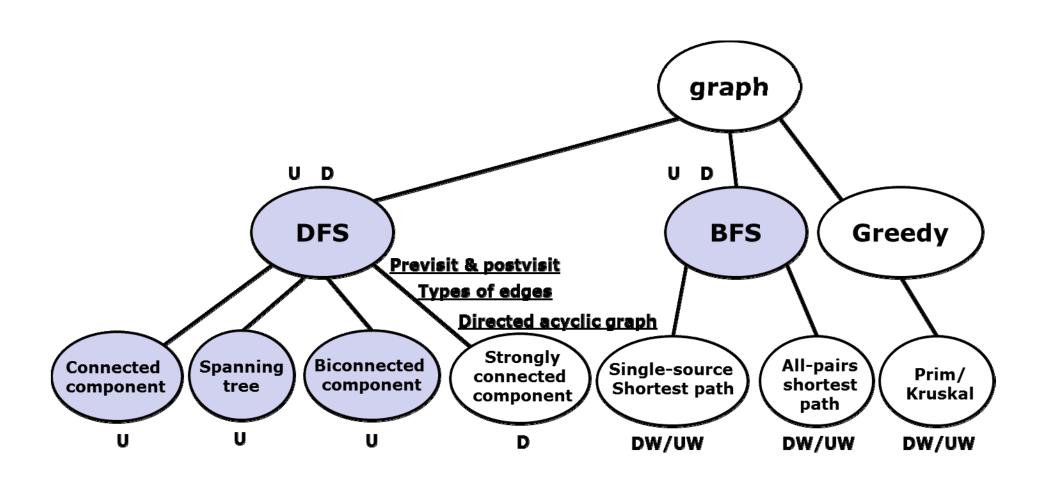
 $-\{u \mid low(w) \ge dfn(u)\} + root$



4 computing articulation points

(2) Decomposition of a graph into biconnected components using articulation points





Contents

- 9.1 Introduction
- 9.2 Basic concepts
- 9.3 Representation of graph
- 9.4 Search
- 9.5 Biconnected component