

**Phys 2920, Fall 2008**  
**Maple Pointers**

**Using vectors:**

Define vectors **a** and **b** and find their dot and cross products,

$$r = \mathbf{a} \cdot \mathbf{b} \quad \text{and} \quad \mathbf{s} = \mathbf{a} \times \mathbf{b}$$

```
with(LinearAlgebra);  
a:= <1., 2., 3.>;  
b:= <-2., 5., 6.>;  
r=a.b;  
s=a &x b;
```

**Matrices:**

Setting up a matrix: Set up matrix *z*; find its inverse; multiply a vector.

```
z := Matrix([[1., 2., 3.], [-5., -3., 4.], [-1., 0., -3.]));  
w := MatrixInverse(z);  
or  
w := z^ (-1);  
c = z.a;
```

Getting eigenvalues and eigenvectors:

```
Eigenvectors(a);
```

gives both eigenvalues and the eigenvectors, or

```
Eigenvalues(a);
```

just gives the eigenvalues.