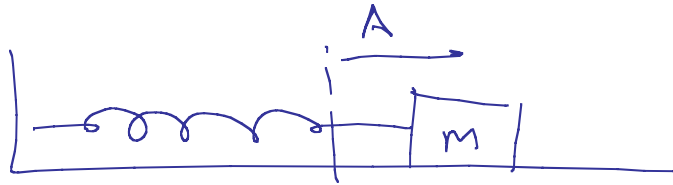


Mass - spring system

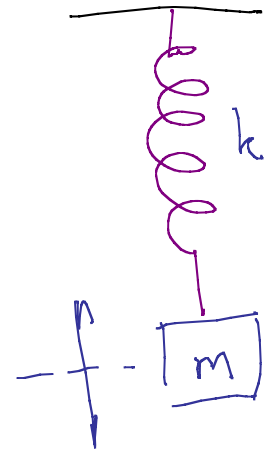
$$\omega = \sqrt{\frac{k}{m}}$$

$$f = \frac{\omega}{2\pi}$$

$$T = \frac{1}{f}$$



Same period for any A (!?)

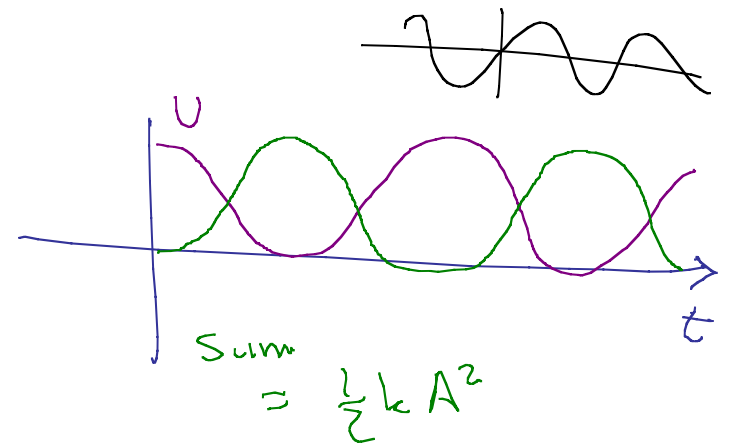


Energy Conservation:

$$U = \frac{1}{2} k x^2 = \frac{1}{2} k A^2 \cos^2(\omega t) \quad \phi=0$$

$$K = \frac{1}{2} m v^2 = \frac{1}{2} k A^2 \sin^2(\omega t)$$

$$x(t) = A \cos(\omega t + \phi)$$



$$\frac{d^2 x}{dt^2} = - \underbrace{\left( \frac{k}{m} \right)}_{\omega^2} x$$

$$x = A \cos(\omega t)$$

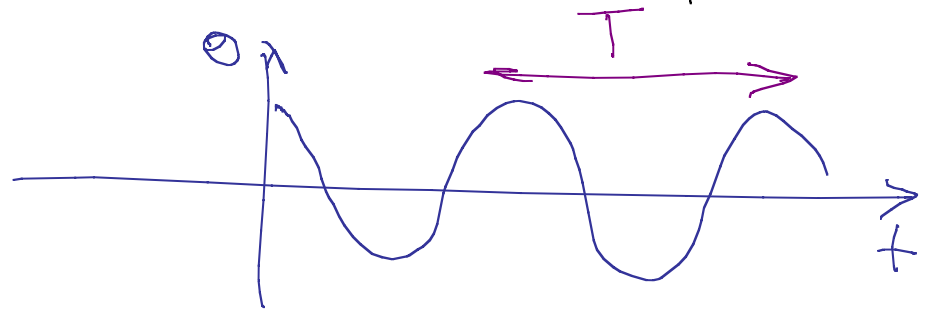
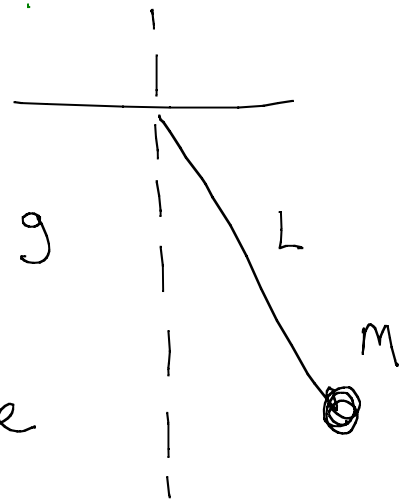
$$\omega = \sqrt{\frac{k}{m}}$$

Sqrt of thing in front of  $x$  is  $\omega$ !

## Simple pendulum

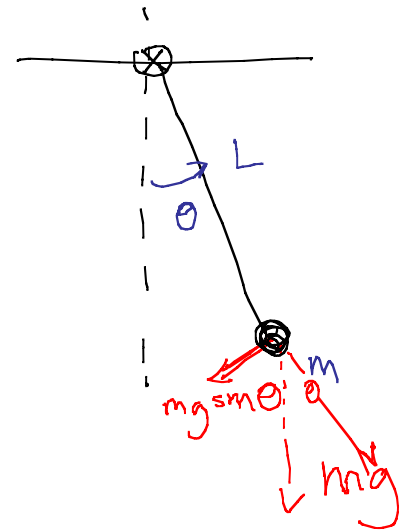
Point mass  $m$  on end of string  
of length  $L$ . Pull back to some angle  
⊙, let it go.

Find period.



Do it with rotations.

$$\begin{aligned}\tau &= -(mg \sin \theta) L \\ &= -mgL \sin \theta \\ &= I \alpha = (mL^2) \frac{d^2 \theta}{dt^2}\end{aligned}$$



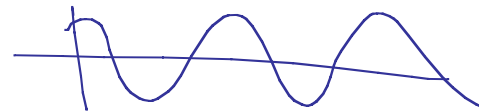
$$\frac{d^2 \theta}{dt^2} = -\frac{g}{L} \sin \theta$$

$$\frac{d^2 x}{dt^2} = -\left(\frac{k}{m}\right)_{\omega^2} x$$

Problem: Don't have  $\theta$  on rhs.

Cheat:

① is in radians

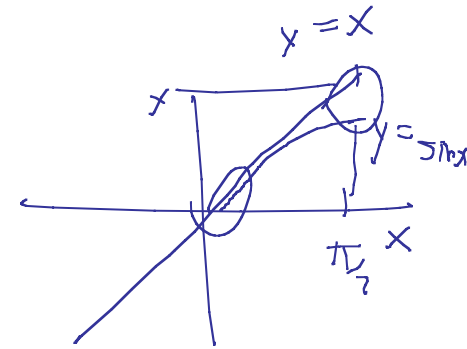


$$\sin \theta \approx \theta$$

when  $\theta$  is small.

$x, \text{deg}$	$X$	$\sin X$
5.73°	0.1	0.09983
11.4°	0.2	0.19866
0.573°	0.01	0.0099998

Promise (hehe heh.)  
 ①  $\text{deg} < 10^\circ$




Did you know this?

$$\sin X = X - \frac{X^3}{3!} + \frac{X^5}{5!} - \frac{X^7}{7!} \dots$$

useful when  $X \ll 1$

$$\sin X \approx X$$

$$\frac{d^2\theta}{dt^2} = -\frac{g}{L} \sin\theta = -\frac{g}{L} \theta$$


 $\omega$

$$\omega = \sqrt{\frac{g}{L}} \quad f = \frac{\omega}{2\pi} = \frac{1}{2\pi} \sqrt{\frac{g}{L}}$$

$$T = \frac{1}{f} = 2\pi \sqrt{\frac{L}{g}}$$

Period of simple pend. 1 m long.

$$T = 2\pi \sqrt{\frac{(1.0 \text{ m})}{(9.8 \frac{\text{m}}{\text{s}^2})}} = 2.01 \text{ s}$$

Recall: Approx.  $\rightarrow \theta(t) = \theta_0 \cos(\omega t)$

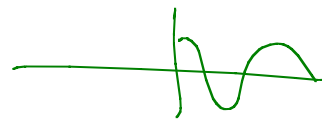
Depends on  $L, g$

$$T \propto \sqrt{L}$$

Not on  $m$

and not on  $\theta_0$

as long as  
it's small.



More general pendulum:

$$\tau = -mgL \sin \theta$$

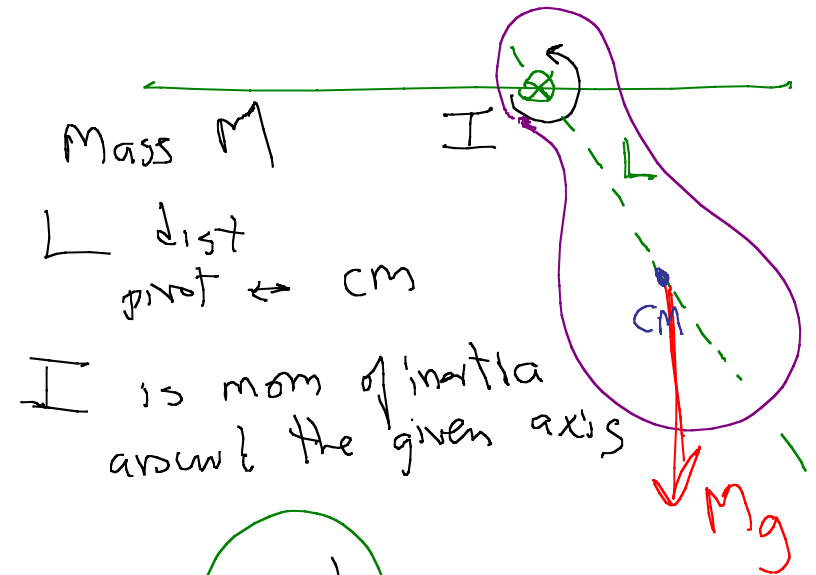
$$= I \frac{d^2 \theta}{dt^2}$$

$$\frac{d^2 \theta}{dt^2} = - \frac{mgL}{I} \sin \theta \approx - \left( \frac{mgL}{I} \right) \theta$$

$\rightarrow \omega^2$

$$\omega = \sqrt{\frac{mgL}{I}}$$

$$T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{I}{mgL}}$$



Make pendulum out of meter stick;  
axis is at one end.

$$l = 1 \text{ m}$$

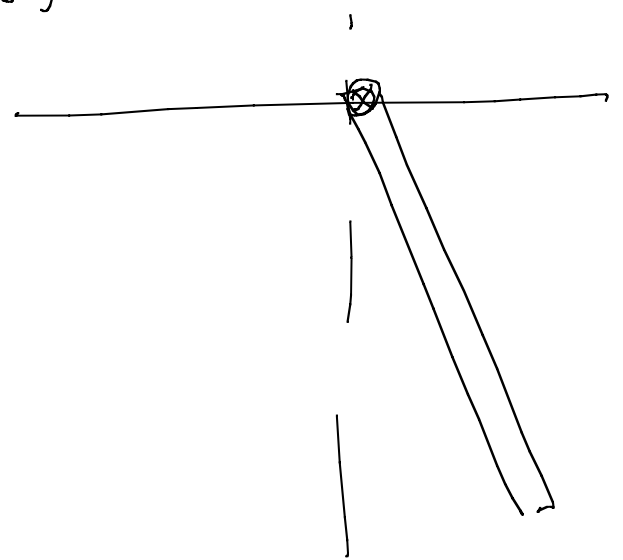
$$L = \frac{l}{2} = 0.50 \text{ m}$$

$$I = \frac{1}{3} M l^2$$

Then

$$T = 2\pi \sqrt{\frac{I}{Mg L}} = 2\pi \sqrt{\frac{\frac{1}{3} M l^2}{Mg \frac{l}{2}}}$$
$$= 2\pi \sqrt{\frac{2}{3} \frac{l}{g}}$$

"physical  
pendulum"



Another kind of pendulum

Torsion fibers

Fiber gives resisting torque.

$$\tau = -K\theta$$

↑ torsional constant,  $\frac{N \cdot m}{rad.}$



Torsional pendulum

$$\tau = -K\theta$$
$$= I \frac{d^2\theta}{dt^2}$$

$$\frac{d^2\theta}{dt^2} = - \frac{K}{I} \theta$$

→  $\omega^2$   
T, f fall out

