

Putting the Magnetic Field into the Lagrangian and QM

1 Fixing up the Lagrangian

We will consider a particle of mass m and charge q moving in *static* electric and magnetic fields; we will work in the non-relativistic regime.

With the possibility of both electric *and* magnetic forces, we want to set up the Lagrangian L for the problem so that the equations of motion will follow from the Euler–Lagrange equations. How do we do this?

The electric potential energy is $U_{\text{elec}} = qV$, where $\mathbf{E} = -\nabla V$. In elementary discussions of the Lagrangian, we are told to form

$$L(\mathbf{r}, \dot{\mathbf{r}}) = T - U = \frac{1}{2}mv^2 + U(\mathbf{r}) \quad (1)$$

where $v = |\dot{\mathbf{r}}|$.

Obviously the electric potential energy U_{elec} just adds on to the other kinds of potential energy in 1 that might be in the problem; if there is *only* electric potential energy, then the Lagrangian is

$$L(\mathbf{r}, \dot{\mathbf{r}}) = \frac{1}{2}mv^2 - qV(\mathbf{r}) \quad (2)$$

But there is no potential energy associated with the magnetic field (it does no work!) so how can it possibly be included in the Lagrangian? The answer is that for a force like that of magnetism which arises from a vector potential \mathbf{A} , the thing we write down (instead of 2) is

$$L(\mathbf{r}, \dot{\mathbf{r}}) = \frac{1}{2}mv^2 - qV(\mathbf{r}) + q\mathbf{v} \cdot \mathbf{A} \quad (3)$$

Note the functional dependence of the parts of L : v contains the components of $\dot{\mathbf{r}}$; V depends only on the components of \mathbf{r} ; \mathbf{A} depends only on the components of \mathbf{r} but it appears dotted with $\mathbf{v} = \dot{\mathbf{r}}$. The latter fact will give some interesting results.

With 3 as the Lagrangian, we *do* get the correct equation of motion, but showing this takes some care and that's what we'll do now.

2 Getting the Equations of Motion from L

We want to show that when we apply the Euler–Lagrange equations,

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}_i} \right) = \frac{\partial L}{\partial x_i} \quad \text{where } x_i = x, y, z \quad (4)$$

we get the Lorentz force equation, $\mathbf{F} = q(\mathbf{E} + \mathbf{v} \times \mathbf{B})$. At first glance it may seem impossible, because the latter contains a cross product which mixes up the components, while the Euler–Lagrange equations are written out for *each* degree of freedom separately. But we will get it!

We'll work on the left side of 4 first. We'll form the E-L equation for the degree of freedom x (of course y and z will be similar). First, find $\partial L/\partial \dot{x}$. Eq. 3 gives

$$\frac{\partial L}{\partial \dot{x}} = m\dot{x} + qA_x \quad (5)$$

Now take $\frac{d}{dt}(\partial L/\partial \dot{x})$. The first term in 5 gives $m\ddot{x}$, but the second term requires some care. A_x has an explicit dependence on (x, y, z) and (by our assumption) no *explicit* dependence on t , but each of the three coordinates has a dependence on time; in fact the total time derivative of A_x is

$$\frac{d}{dt}A_x = \frac{\partial A_x}{\partial x} \frac{dx}{dt} + \frac{\partial A_x}{\partial y} \frac{dy}{dt} + \frac{\partial A_x}{\partial z} \frac{dz}{dt} = \frac{\partial A_x}{\partial x} \dot{x} + \frac{\partial A_x}{\partial y} \dot{y} + \frac{\partial A_x}{\partial z} \dot{z} \quad (6)$$

This can be written as $\mathbf{v} \cdot \nabla$ operating on A_x :

$$\frac{d}{dt}A_x = (\mathbf{v} \cdot \nabla)A_x = [(\mathbf{v} \cdot \nabla)\mathbf{A}] \cdot \hat{\mathbf{x}} \quad (7)$$

Using these results in 5, we get:

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}} \right) = m\ddot{x} + q[(\mathbf{v} \cdot \nabla)\mathbf{A}] \cdot \hat{\mathbf{x}} \quad (8)$$

Now work on the right side of 4. We find:

$$\begin{aligned} \frac{\partial L}{\partial x} &= -q \frac{\partial V}{\partial x} + q \left[v_x \frac{\partial A_x}{\partial x} + v_y \frac{\partial A_y}{\partial x} + v_z \frac{\partial A_z}{\partial x} \right] \\ &= -q \frac{\partial V}{\partial x} + q [\nabla(\mathbf{v} \cdot \mathbf{A})] \cdot \hat{\mathbf{x}} \end{aligned} \quad (9)$$

Replace both sides of Eq. 4 (and use $-\partial V/\partial x = E_x$) and get

$$m\ddot{x} + q[(\mathbf{v} \cdot \nabla)\mathbf{A}] \cdot \hat{\mathbf{x}} = qE_x + q[\nabla(\mathbf{v} \cdot \mathbf{A})] \cdot \hat{\mathbf{x}} \quad (10)$$

Combine the two terms with the $\hat{\mathbf{x}}$ and get:

$$m\ddot{x} = qE_x + q[\nabla(\mathbf{v} \cdot \mathbf{A}) - (\mathbf{v} \cdot \nabla)\mathbf{A}] \cdot \hat{\mathbf{x}} \quad (11)$$

Now, using that fact that \mathbf{v} has no dependence on \mathbf{r} , one of the vector product rules from the inside front cover of the book gives:

$$\nabla(\mathbf{v} \cdot \mathbf{A}) = \mathbf{v} \times (\nabla \times \mathbf{A}) + (\mathbf{v} \cdot \nabla)\mathbf{A} \quad (12)$$

Using this in 11 gives

$$m\ddot{x} = qE_x + q[\mathbf{v} \times (\nabla \times \mathbf{A})] \cdot \hat{\mathbf{x}} \quad (13)$$

Use $\nabla \times \mathbf{A} = \mathbf{B}$ and get:

$$m\ddot{x} = qE_x + q[\mathbf{v} \times \mathbf{B}] \cdot \hat{\mathbf{x}} \quad (14)$$

for which we notice that each term is the x -component of a vector. Making a full vector equation out of 14, and using $\mathbf{F} = m\ddot{\mathbf{r}} = m\mathbf{a}$, we get

$$\mathbf{F} = m\mathbf{a} = q\mathbf{E} + q\mathbf{v} \times \mathbf{B} \quad (15)$$

The Lorentz force equation does follow from our Lagrangian in 3...when we do all the steps carefully!

3 Two Kinds of Momentum

In first year physics we learn that the (non-relativistic) momentum of a particle is $m\mathbf{v}$. Later when we first encounter the Lagrangian we get a more general definition of momentum: The momentum corresponding to the coordinate q_i is

$$p_i \equiv \frac{\partial L}{\partial \dot{q}_i}$$

(often called the “generalized momentum”!).

But with our complete Lagrangian in Eq. 3 this definition would seem to give us a problem. Because for p_x it gives:

$$p_x = \frac{\partial L}{\partial \dot{x}} = \frac{\partial L}{\partial v_x} = mv_x + qA_x$$

or, written as a vector,

$$\mathbf{p} = m\mathbf{v} + q\mathbf{A} \quad (16)$$

So which one *is* the momentum... $m\mathbf{v}$ or $m\mathbf{v} + q\mathbf{A}$? Both, actually; we just have *two kinds* of momentum. The momentum given in 16 is the **canonical momentum**, and we will use the symbol \mathbf{p} for this. The quantity $m\mathbf{v}$ is known as the **mechanical** or **kinetic** momentum, so that

$$\mathbf{p}_{\text{mech}} = m\mathbf{v} = \mathbf{p} - q\mathbf{A} \quad (17)$$

Note, one can get very confused about the signs in Eqs. 16 and 17 if we are not careful about the notation for the charge. In these equations, q is the charge; substitute what you want! But in some books, the charge of the particle is represented by e which can get confusing if we are applying it to the electron (as we so often do) whose charge we normally want to write as $-e$. It can be quite aggravating to decide if some equation really means “ e ” or “ $-e$ ” for our application.

4 The Magnetic Field and Quantum Mechanics

In quantum mechanics, some of the familiar quantities from mechanics become *operators* which work on wave functions. The time-independent Schrödinger equation features the total energy operator H_{op} (the sum of the kinetic and potential energy operators) acting on the wavefunction $\Psi(\mathbf{r})$:

$$H_{\text{op}}\Psi = \left(\frac{\mathbf{p}_{\text{op}}^2}{2m} + U(\mathbf{r}) \right) \Psi(\mathbf{r}) = E\Psi(\mathbf{r}) \quad (18)$$

Now we can appreciate the subtleties: *Which* \mathbf{p} are we talking about here, and what operator is it replaced by? The answer is that the momentum operator in 18 should be the one for the *kinetic* momentum, since that’s what gives the kinetic energy. But it the *canonical* momentum \mathbf{p} which goes with the famous “momentum” operator $\frac{\hbar}{i}\nabla$. So the Hamiltonian operator in 18 needs to be written in terms of the canonical momentum. Including an electric potential energy for U , it is:

$$\begin{aligned} H &= \frac{1}{2m}(\mathbf{p} - q\mathbf{A})^2 + qV \\ &= \frac{\mathbf{p}^2}{2m} - \frac{q}{2m}(\mathbf{p} \cdot \mathbf{A} + \mathbf{A} \cdot \mathbf{p}) + \frac{q^2}{2m}\mathbf{A}^2 + qV \end{aligned} \quad (19)$$

where we have been very careful to preserve the order of the operators.

Now we can replace the operator \mathbf{p} by $\frac{\hbar}{i}\nabla$; for most of the terms in 19 it is clear how to do this:

$$\frac{\mathbf{p}^2}{2m} \Rightarrow -\frac{\hbar^2}{2m}\nabla^2 \quad -\frac{q}{2m}\mathbf{A} \cdot \mathbf{p} \Rightarrow \frac{iq\hbar}{2m}\mathbf{A} \cdot \nabla$$

with the functions of \mathbf{r} becoming multiplicative factors, but the term we need to be careful about is the second one, $-\frac{q}{2m}\mathbf{p} \cdot \mathbf{A}$. In this term, the meaning of the \mathbf{p} operator is to operate on *everything* that lies to the right of it, so that when it is applied to the wavefunction Ψ , it works as:

$$\frac{i\hbar q}{2m}(\nabla \cdot \mathbf{A})\Psi = \frac{i\hbar q}{2m} \left(\frac{\partial}{\partial x}[A_x\Psi] + \frac{\partial}{\partial y}[A_y\Psi] + \frac{\partial}{\partial z}[A_z\Psi] \right)$$

The product rule and a little simplifying then gives this as:

$$\frac{i\hbar q}{2m}[(\nabla \cdot \mathbf{A})\Psi + \mathbf{A} \cdot \nabla\Psi] = \frac{i\hbar q}{2m}[(\nabla \cdot \mathbf{A}) + \mathbf{A} \cdot \nabla]\Psi \quad (20)$$

where here $(\nabla \cdot \mathbf{A})$ means to just hit the \mathbf{A} with the ∇ . We can now remove the Ψ from the right hand side to get the *operator* that we want to put back into 19.

Now substitute for all the terms in 19 and get:

$$\begin{aligned} H &= -\frac{\hbar^2}{2m}\nabla^2 + \frac{i\hbar q}{2m}[(\nabla \cdot \mathbf{A}) + \mathbf{A} \cdot \nabla] + \frac{iq\hbar}{2m}\mathbf{A} \cdot \nabla + \frac{q^2}{2m}\mathbf{A}^2 + qV \\ &= -\frac{\hbar^2}{2m}\nabla^2 + \frac{i\hbar q}{2m}(\nabla \cdot \mathbf{A}) + \frac{iq\hbar}{m}\mathbf{A} \cdot \nabla + \frac{q^2}{2m}\mathbf{A}^2 + qV \end{aligned} \quad (21)$$

The meaning of the operators is clearer in this form; if the ∇ is out in front, then clearly it works on the Ψ ; if it is dotted with the \mathbf{A} , it works *only* on the \mathbf{A} .

So we now have a Hamiltonian operator which can handle magnetic fields. We note that it is the *potentials* (both scalar and vector) of the fields that enter into H . In general, the really cool equations of advanced physics deal with the potentials and *not* with the fields.

But we have reason to be bothered by this: Didn't we show that there is some ambiguity in the choice of potentials that go with particular \mathbf{E} and \mathbf{B} fields (called *gauge* choices)? Won't this ambiguity give *different solutions* to the equations for different gauge choices? But the fields (and initial conditions) *determine* the physical solutions, don't they?

The issue of gauge choices is an important one and beyond the scope of this blurb.