

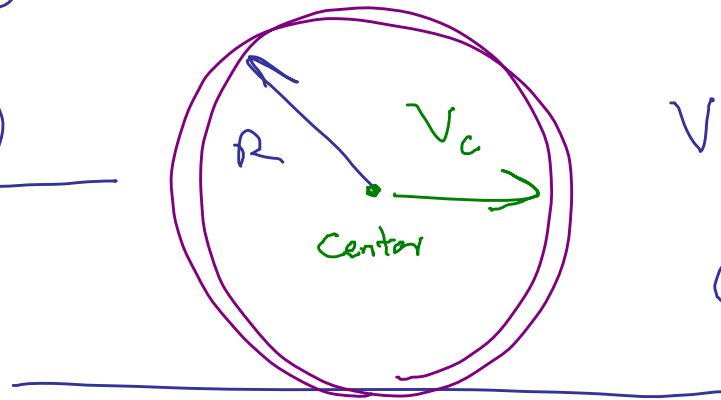
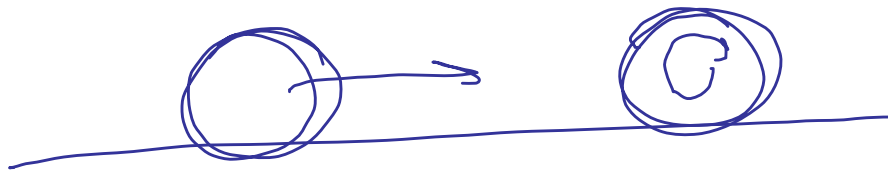
Rotations



$$\tau_{\text{net}} = I\alpha$$

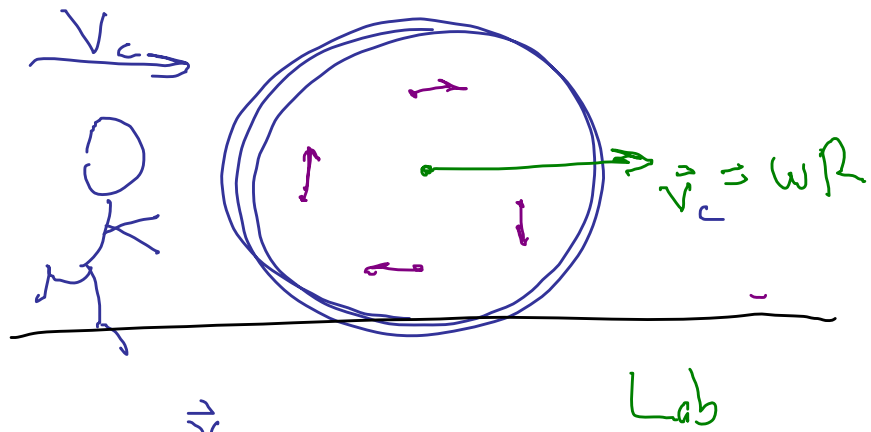
$$K = \frac{1}{2} I \omega^2$$

Rolling w/o slipping

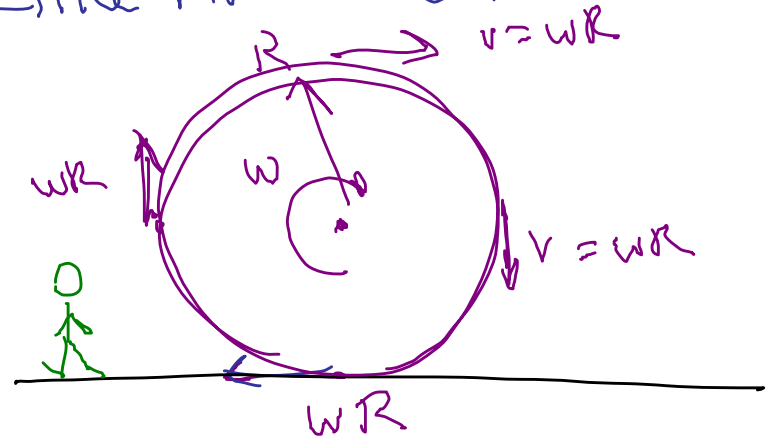


$$v_c = \omega R$$

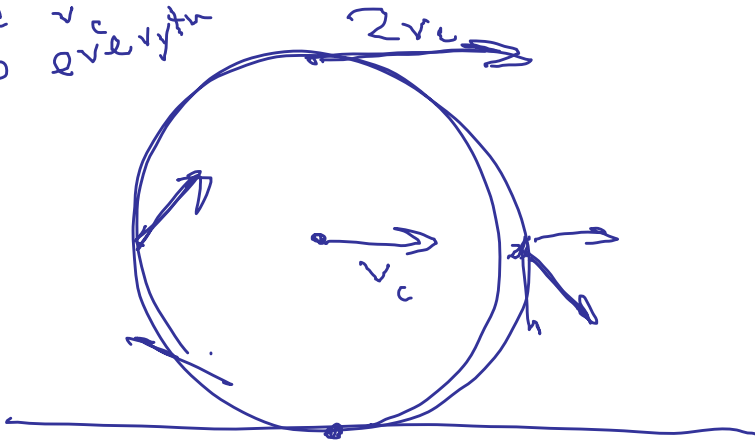
$$a_c = \alpha R$$



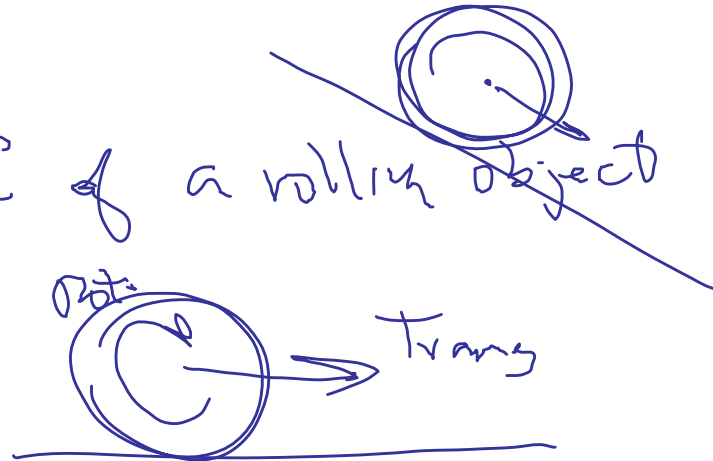
Little man: sees:



Add \vec{v}_c onto everything

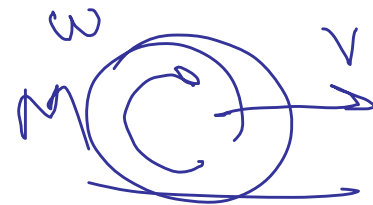


KE of a rolling object



KE of rolling object

Translational Rotational.



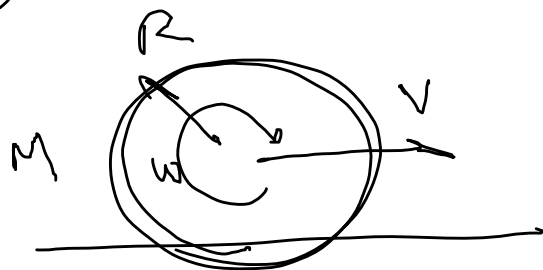
$$KE = \frac{1}{2} M v^2 + \frac{1}{2} I \omega^2 = K_{tra} + K_{rot} \quad v = \omega R$$

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10.39 What fraction of a solid disk's kinetic energy is rotational if it rolls w/o slipping.

$$I = \frac{1}{2} M R^2$$



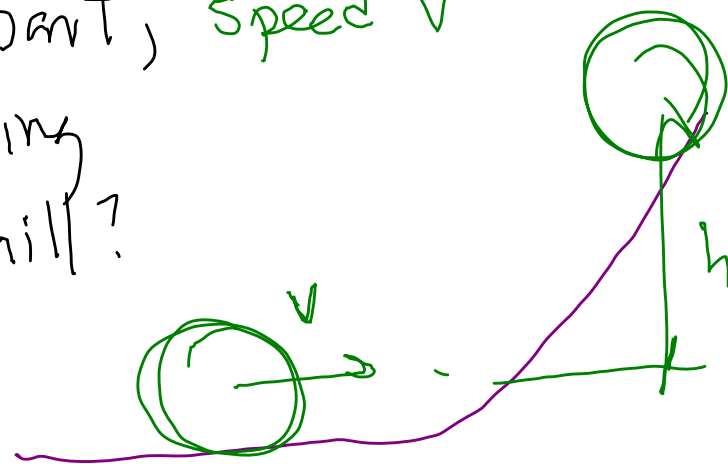
$$\begin{aligned} KE &= K_{tra} + K_{rot} \\ &= \frac{1}{2} M v^2 + \frac{1}{2} I \omega^2 \\ &= \frac{1}{2} M v^2 + \frac{1}{2} \left(\frac{1}{2} M R^2 \right) \left(\frac{v}{R} \right)^2 \\ &= \frac{1}{2} M v^2 + \frac{1}{4} M v^2 \end{aligned}$$

$$\omega = \frac{v}{R}$$

$$K_{\text{Tot}} = \underbrace{\frac{1}{2} M v^2}_{\text{trans}} + \underbrace{\frac{1}{4} M v^2}_{\text{rot}} = \frac{3}{4} M v^2$$

$$\frac{K_{\text{rot}}}{K_{\text{Tot}}} = \frac{\frac{1}{4} M v^2}{\frac{3}{4} M v^2} = \frac{1}{3}$$

Example ^{solid sphere} Ball rolls on flat part, speed v
 rolls up hill, w/o slipping
 how high does it go up hill?





$$v = 0$$

$$K = 0$$

$$U =$$

Cons of Energy

$K_{\text{trans}} + K_{\text{rot}} = U$

Solve for h

$$h = \frac{7}{10} \frac{v^2}{g}$$



$$K_{\text{trans}} + K_{\text{rot}} = \frac{1}{2} M v^2 + \frac{1}{2} I \omega^2$$

$$= \frac{1}{2} M v^2 + \frac{1}{2} \left(\frac{2}{5} M R^2 \right) \left(\frac{v}{R} \right)^2$$

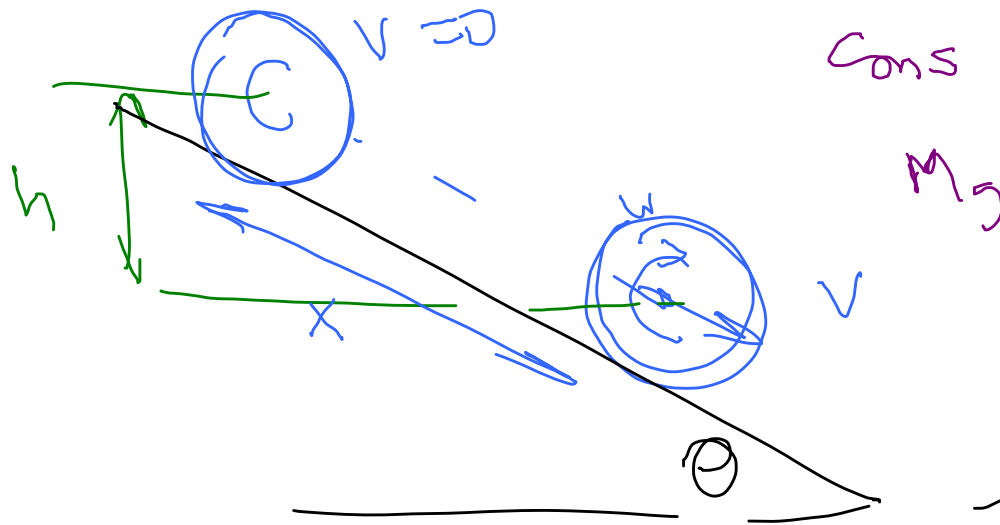
$$= \frac{1}{2} M v^2 + \frac{1}{5} M v^2$$

$$= \frac{7}{10} M v^2 = M g h$$

Hollow sphere $I = \frac{2}{3}MR^2$. -

Ball rolls down hill, what's its acceleration.

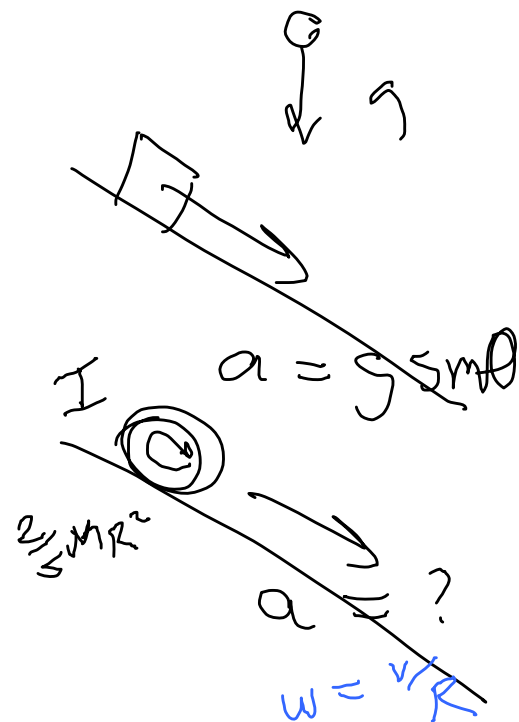
First, do it by cons of energy



Cons of E

$$Mgh = K$$

$$\begin{aligned} &= \frac{1}{2}Mv^2 + \frac{1}{2}I\omega^2 \\ &= \frac{1}{2}Mv^2 + \frac{1}{2}\left(\frac{2}{3}MR^2\right)\left(\frac{v}{R}\right)^2 \\ &= \frac{1}{2}Mv^2 + \frac{1}{5}Mv^2 \\ &= \frac{7}{10}Mv^2 \end{aligned}$$



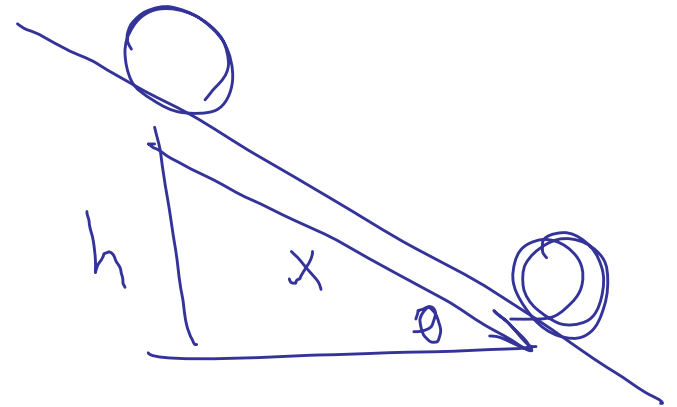
$$\cancel{1}gh = \cancel{\frac{2}{10}}Mv^2$$

$$v^2 = \frac{10}{7}gh$$

$$= \frac{10}{7}g x \sin \theta$$

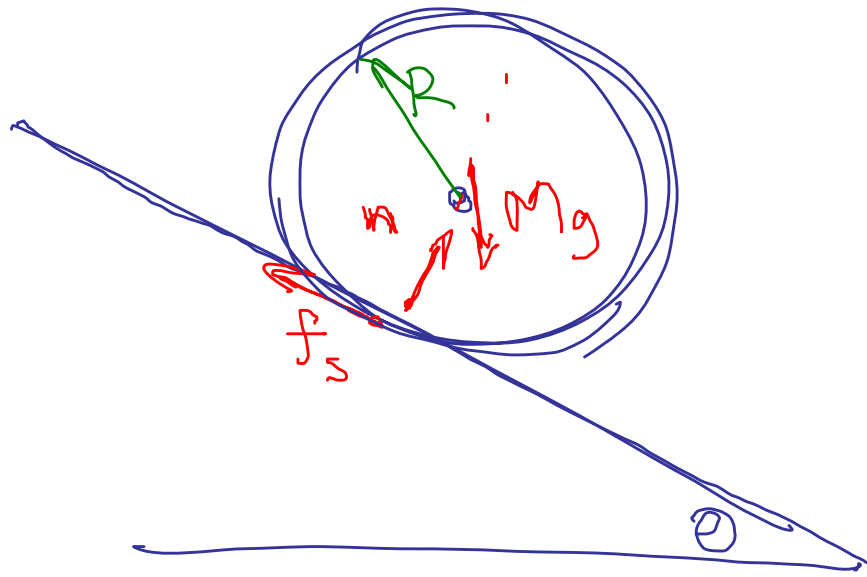
$$= (2x) \left(\frac{5g}{7} \sin \theta \right)$$

$$\underline{a = \frac{5}{7}g \sin \theta}$$



$$h = x \sin \theta$$

$$\boxed{\begin{aligned} v^2 &= 2ax \\ &= \cancel{2x} \cancel{a} \end{aligned}}$$



Net force down slope

$$F_{\alpha \text{ to-}} = Mg \sin \theta - f_s = Ma$$

Torque about center
 Mg , n no torque

$$\tau_{\text{net}} = f_s R = I \alpha = I a / R$$

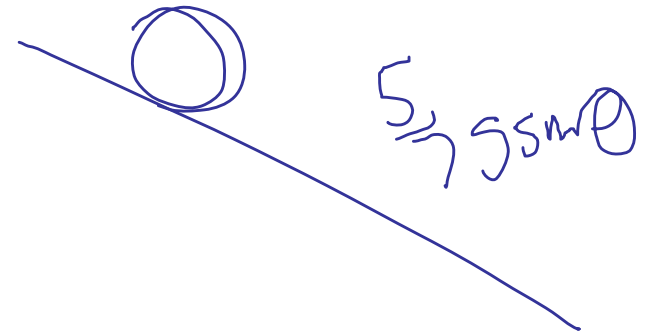
$$f_s = \frac{I a}{R^2} = \frac{2}{5} M R^2 \frac{a}{R^2} = \frac{2}{5} Ma$$

$\alpha = a/R$

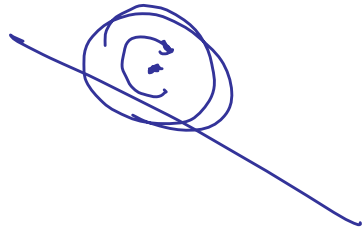
$$Mg \sin \theta - \frac{2}{3}Ma = Ma$$

~~$$Mg \sin \theta = Ma \left(\frac{1}{3} \right)$$~~

$$a = \frac{5}{7}g \sin \theta$$



Technique



ctr of ball is accel.

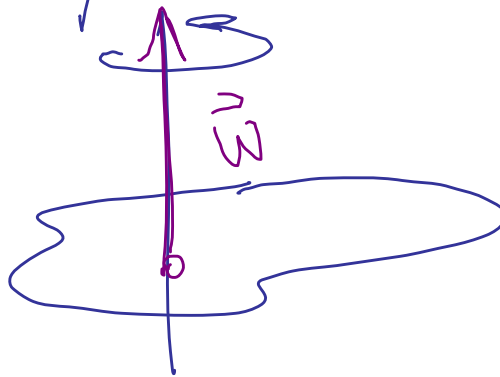
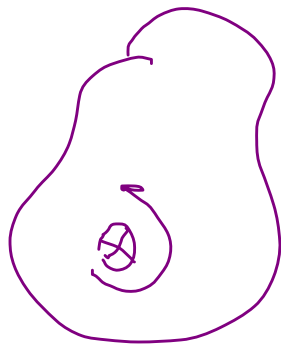
It's ok

Ch 11

More on rotations

Vector nature of our quantities.

Angular velocity



Essential: Cross product

\vec{a}, \vec{b}
 $\rightarrow \vec{c}$