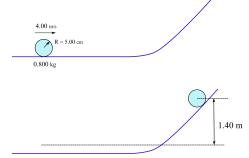
Name____

Apr. 19, 2013

- 1. A round object of mass 0.800 kg and radius 5.00 cm rolls without slipping on a flat surface so that the speed of its center is $4.00\frac{\rm m}{\rm s}$. It continues to roll (smoothly) up a ramp so that it reaches a maximum height of 1.40 m.
- **a)** What is the *translational* kinetic energy of the object as it is rolling on the flat part?



$$K_{\text{trans}} = \frac{1}{2}mv_{\text{c}}^2 = \frac{1}{2}(0.800 \text{ kg})(4.00\frac{\text{m}}{\text{s}})^2 = \boxed{6.40 \text{ J}}$$

b) What is the angular velocity (speed) of the object is it rolls on the flat part?

$$\omega = \frac{v_{\rm c}}{R} = \frac{(4.00\frac{\rm m}{\rm s})}{(0.0500\ \rm m)} = 80.0\frac{\rm rad}{\rm s}$$

c) What is the total energy of the object as it rolls on the flat part?

By conservation of energy (no friction forces doing any work) it must be equal to the potential energy of the object in the final position, thus

$$K_{\text{roll}} = mgh = (0.800 \text{ kg})(9.80 \frac{\text{m}}{\text{s}^2})(1.40 \text{ m}) = 11.0 \text{ J}$$

d) What is the *rotational* kinetic energy of the object as it rolls on the flat part?

The sum of translational and rotational KE's gives the total KE, so

$$K_{\rm rot} = K_{\rm roll} - K_{\rm trans} = 4.60 \text{ J}$$

e) What is the moment of inertia of the object (for an axis thru its center)?

Since $K_{
m rot}=rac{1}{2}I\omega^2$ we get

$$I = \frac{2K_{\text{rot}}}{\omega^2} = \frac{2(4.60 \text{ J})}{(80.0\frac{\text{rad}}{\text{s}})^2} = \boxed{1.44 \times 10^{-3} \text{ kg} \cdot \text{m}^2}$$

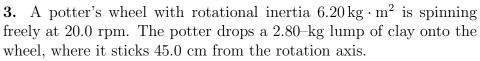
2. Find the length of a simple pendulum which has a period of 5.00 s.

Use

$$T = 2\pi\sqrt{\frac{L}{g}} \implies T^2 = 4\pi^2 \frac{L}{g} \implies L = \frac{gT^2}{4\pi^2}$$

Plug in numbers

$$L = \frac{(9.80 \frac{\text{m}}{\text{s}^2})(5.00 \text{ s})^2}{4\pi^2} = 6.20 \text{ m}$$



What's the wheel's subsequent angular speed?

[Hint: Before the collision, the lump has no angular momentum about the rotation axis.]



$$\omega_i = (20.0 \text{ rpm}) = 2.09 \frac{\text{rad}}{\text{s}}$$

With the moment of inertia of the wheel being $I_{\rm wh}$, the initial angular momentum of the system was

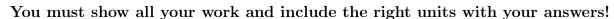
$$L_i = I_{\rm wh}\omega_i$$

After the collision the system rotates as one unit with moment of inertia

$$I = I_{\rm wh} + mr^2 = 6.20 \,\mathrm{kg} \cdot \mathrm{m}^2 + (2.80 \,\mathrm{kg})(0.450 \,\mathrm{m})^2 = 6.77 \,\mathrm{kg} \cdot \mathrm{m}^2$$

No net external torque; L is conserved; this gives

$$L_f = I\omega_f = L_i = I_{\text{wh}}\omega_i \implies \omega_f = \frac{I_{\text{wh}}}{I}\omega_i = \boxed{1.91\frac{\text{rad}}{\text{s}} = 18.3 \text{ rpm}}$$



$$\tau = rF \sin \theta \quad \tau_{\rm net} = I\alpha \quad I = \sum m_i r_i^2 \quad I_{\rm cyl} = \frac{1}{2}MR^2 \quad I_{\rm sph, \, sol} = \frac{2}{5}MR^2 \quad I_{\rm sph, \, hol} = \frac{2}{3}MR^2$$

$$K_{\rm rot} = \frac{1}{2}I\omega^2 \quad W_{\rm rot} = \int \tau d\theta \quad v_c = \omega r \quad a_c = \alpha r \quad K = \frac{1}{2}mv^2 + \frac{1}{2}I\omega^2 = K_{\rm trans} + K_{\rm rot}$$

$$I_{\rm rod, \, end} = \frac{1}{3}ML^2 \quad I_{\rm rod, \, ctr} = \frac{1}{12}ML^2 \quad L = I\omega \quad L_{\rm str \, line} = mvb \quad \text{No net ext torque} \Rightarrow L \text{ cons'd}$$

$$\frac{d^2x}{dt^2} = -\frac{k}{m}x = -\omega^2 x \quad \omega = \sqrt{\frac{k}{m}} \quad T = \frac{2\pi}{\omega} \quad f = \frac{1}{T} \quad v_{\rm max} = A\omega \quad a_{\rm max} = A\omega^2$$

$$\frac{a^2x}{dt^2} = -\frac{\kappa}{m}x = -\omega^2 x \qquad \omega = \sqrt{\frac{\kappa}{m}} \qquad T = \frac{2\pi}{\omega} \qquad f = \frac{1}{T} \qquad v_{\text{max}} = A\omega \qquad a_{\text{max}} = A\omega$$

$$\omega = \sqrt{\frac{g}{L}} \qquad T = \frac{2\pi}{\omega} = 2\pi\sqrt{\frac{L}{g}} \qquad \omega = \sqrt{\frac{mgL}{I}} \qquad T = 2\pi\sqrt{\frac{I}{mgL}} \qquad \omega = \sqrt{\frac{\kappa}{I}}$$

