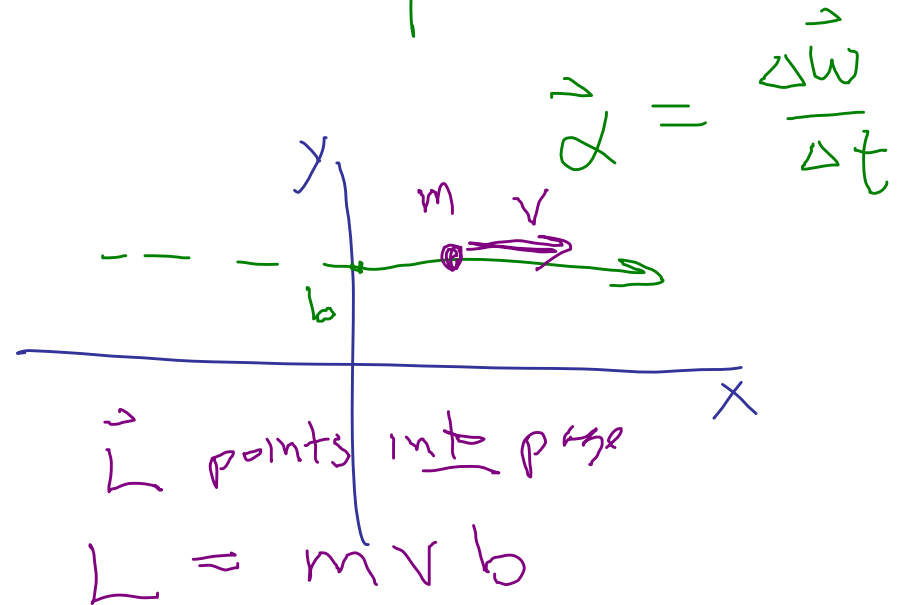
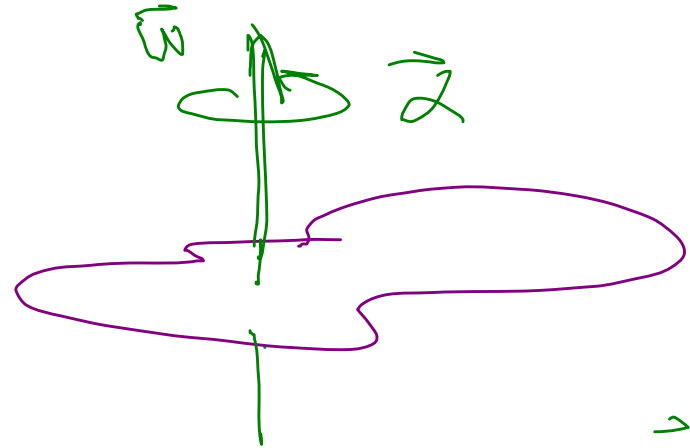


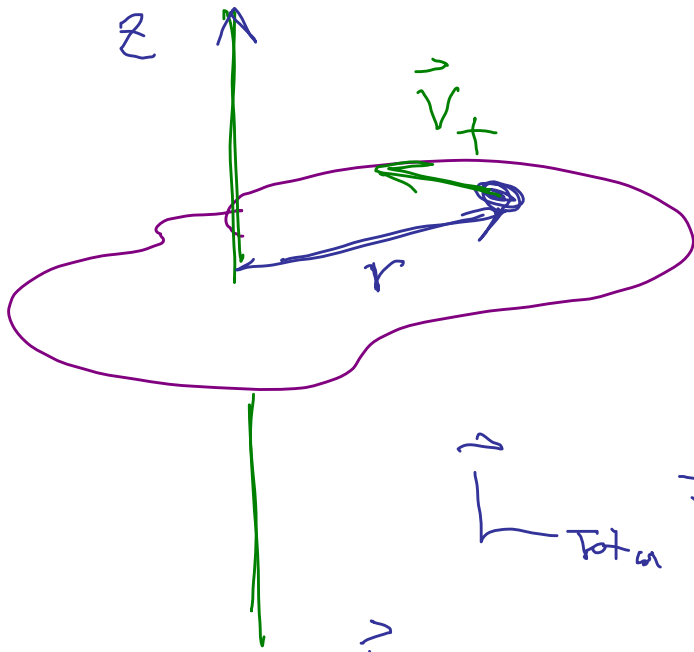
Rotations (Ch11)

$$\vec{\tau} = \vec{r} \times \vec{F}$$

Angular momentum

$$\vec{L} = \vec{r} \times \vec{p}$$





$$\vec{L} = r(mv) \hat{k} \\ = r(m\omega r) \hat{k}$$

$$\vec{L}_{\text{Total}} = \sum \vec{L}_i = \omega \left(\sum m_i r_i^2 \right) \hat{k}$$

$$\vec{L}_{\text{Total}} = \omega I \hat{k} = \tau \omega \hat{k} \rightarrow \tau$$

$$p_x = m v_x$$

$$\vec{L} = I \omega$$

\vec{L} (huh!) what is it good for?

$$\vec{F} = \frac{d\vec{p}}{dt}$$

Isolated system

→ total P stays.

$$\vec{\tau} = \frac{d\vec{L}}{dt}$$

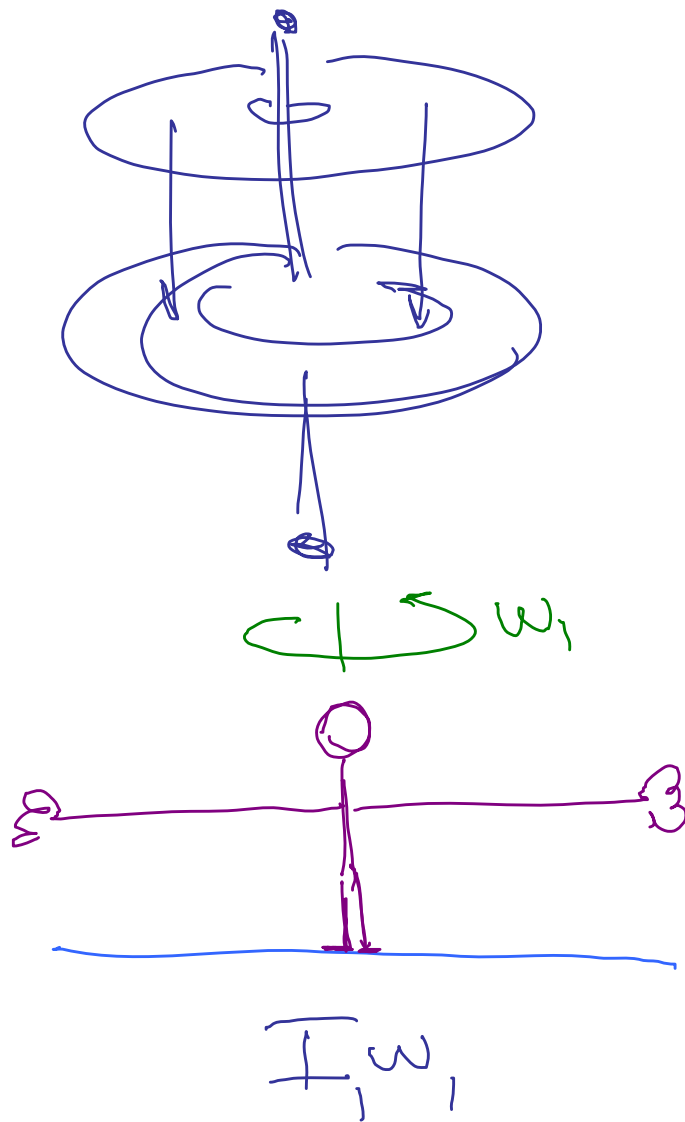
Rotationally isolated system

→ Total L stays same.

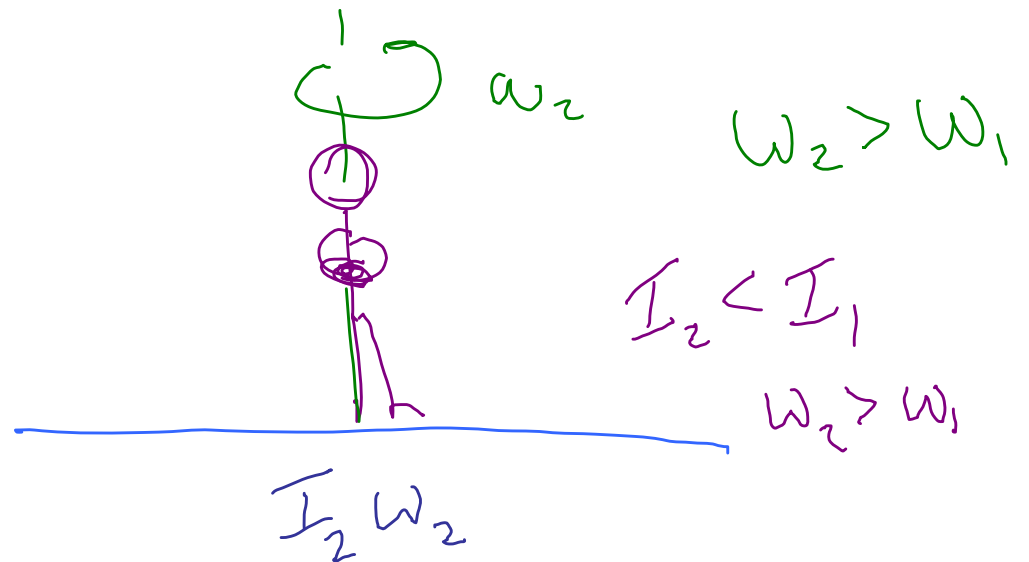
No (net) external torques.

$\sum L$ stays
same.

$$L = I\omega$$

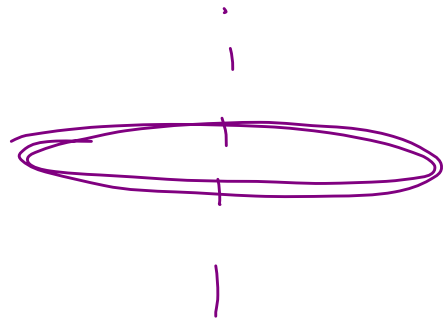


Internal torques
 No external torque
 $\sum I\omega = \text{constant}$



$=$

11.23 640-g hoop 90 cm in diameter
rotates at 170 rpm about central
What is ang mom?



$$I = MR^2$$

$$\omega = 170 \text{ rpm} \left(\frac{2\pi \text{ rad}}{1 \text{ rev}} \right) \left(\frac{1 \text{ min}}{60 \text{ s}} \right)$$

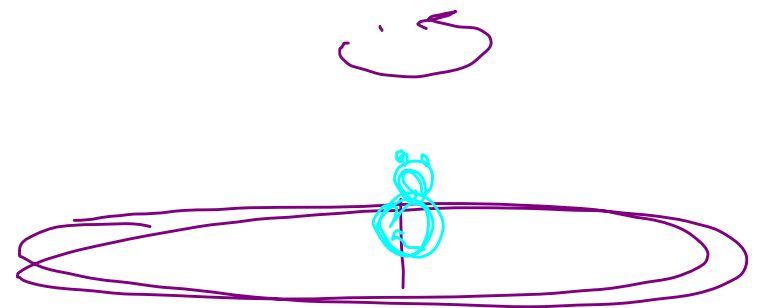
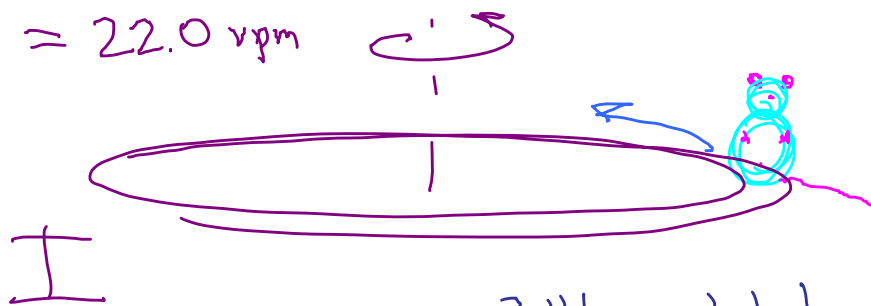
$$L = I\omega = 2.3 \text{ (J}\cdot\text{s)} \\ \left(\frac{\text{kg}\cdot\text{m}^2}{\text{s}} \right)$$

11.38 A turntable of radius 25 cm
 & rot. inertia 0.0154 kg m^2
 Spins freely at 22.0 rpm around axis,
 19.5 g mouse sits at edge. Walks edge
 to center. Find

- New rotation speed
- Work done by mouse.

[E not
 nec. conserved!!!

$\omega = 22.0 \text{ rpm}$

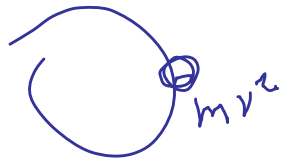


Rot'ly isolated. Total L is conserved.



$$L_{\text{init}} : I_{\text{Total}, 1} \omega_{\text{init}}$$

$$= (0.0154 \text{ kg m}^2 + (0.0195 \text{ kg})(0.25 \text{ m})^2) \omega_{\text{init}}$$



$$L_{\text{final}} : I_{\text{total}, 2} \omega_{\text{final}}$$

$$= (0.0154 \text{ kg m}^2) \omega_{\text{final}}$$

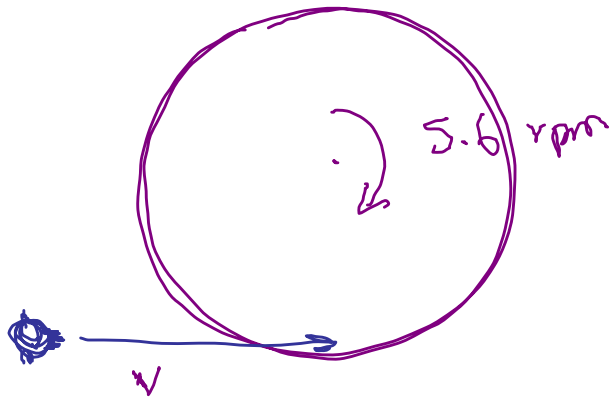
$$\omega_{\text{fin}} = \frac{I_1}{I_2} \omega_1 = 2.48 \frac{\text{rad}}{\text{s}} = 23.7 \text{ rpm}$$

$$b) \quad KE_{\text{int}} : \quad \frac{1}{2} I_1 \omega_1^2 = 0.04405 \text{ J}$$

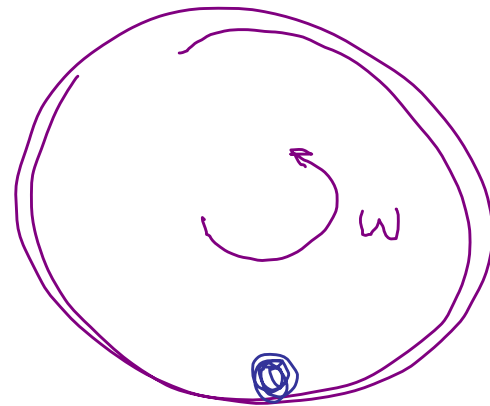
$$KE_{\text{final}} = \frac{1}{2} I_2 \omega_2^2 = 0.0473 \text{ J}$$

$$\Delta K = 3.3 \times 10^{-3} \text{ J} \quad \text{Gained energy.}$$

11.43 Circular bird feeder 19 cm in radius
rot'l inertia 0.12 kg m^2 , spins slowly at
5.6 rpm. 140 g bird lands on rim, comes
in tangent at 1.1 m/s in dir. opposite to
feeder's orig. motion. Final rot'n rate.



L_{Total} is conserved.



$$L_{\text{init}} = I_{\text{free}} (0.586 \frac{\text{rad}}{\text{s}}) \\ - (0.140 \text{ kg}) (1.1 \text{ m}) (0.19 \text{ m})$$

$$L_{\text{fin}} = (I_{\text{free}} + mR^2) \omega_f$$

$$I \text{ got } (?) \quad \omega_f = 0.329 \frac{\text{rad}}{\text{s}}$$

$$\omega = 0.586 \frac{\text{rad}}{\text{s}}$$

$$mvb$$

Gyroscopes

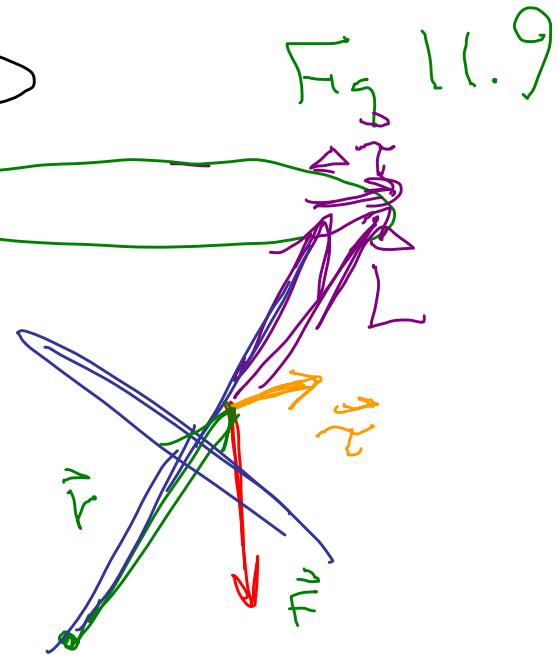
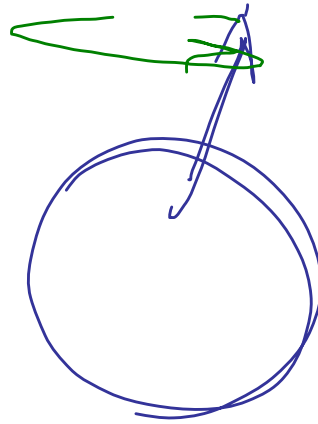
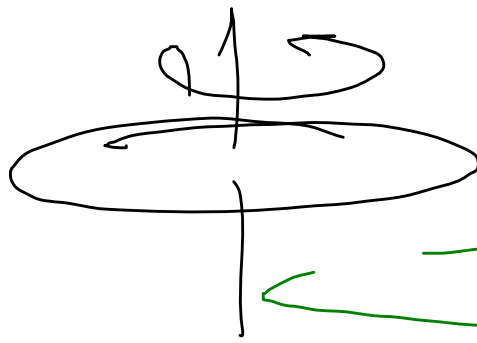
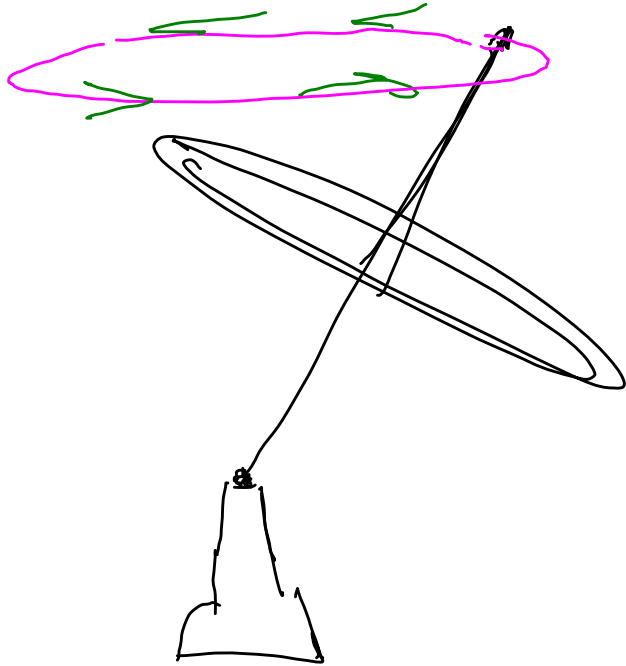


Fig 11.9

$$\tau = \frac{dL}{dt}$$

Same τ , as ΔL