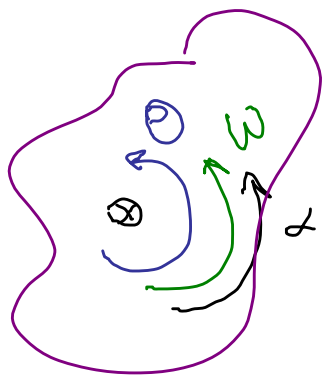


Phys 2110-4 3/19/12

Note Title

3/19/2012

Rotations Chap 10, Chap 11



Constant α :

$$\omega = \omega_0 + \alpha t$$

$$\theta = \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2$$

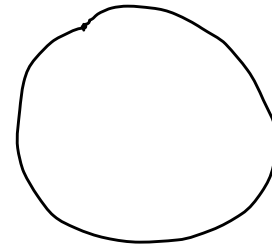
$$\omega^2 = \omega_0^2 + 2\alpha(\theta - \theta_0)$$

10.18 a) How long?

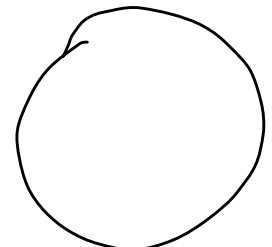
$$\alpha = \frac{\Delta \omega}{t}$$

$$t = \frac{\Delta \omega}{\alpha} = \frac{377 \frac{\text{rad}}{\text{s}}}{0.52 \frac{\text{rad}}{\text{s}^2}}$$

$$= 750 \text{ s} \approx 12 \text{ min}$$



$$\omega_0 = 0$$



$$\omega = 3600 \text{ rpm} \\ = 377 \frac{\text{rad}}{\text{s}}$$

$$\alpha = 0.52 \frac{\text{rad}}{\text{s}^2}$$

b) How many revolutions?

$$\theta = \frac{1}{2}(\omega + \omega_0) t$$

$$\theta = \frac{1}{2} \alpha t^2$$

Get same answer

$$\theta = \underline{1.37 \times 10^5 \text{ rev}} = \underline{2.17 \times 10^4 \text{ rad}}$$

10.19 Merry-go-round starts rest
accel's 0.010 rad/s^2 for 14 s.

a) How many rev's during that time?

b) Average angular speed?

$$\begin{aligned} \text{a) } \Theta &= \frac{1}{2} \alpha t^2 + \cancel{\omega_0 t} = 0.98 \text{ rad} \\ &= 0.156 \text{ rev} \end{aligned}$$

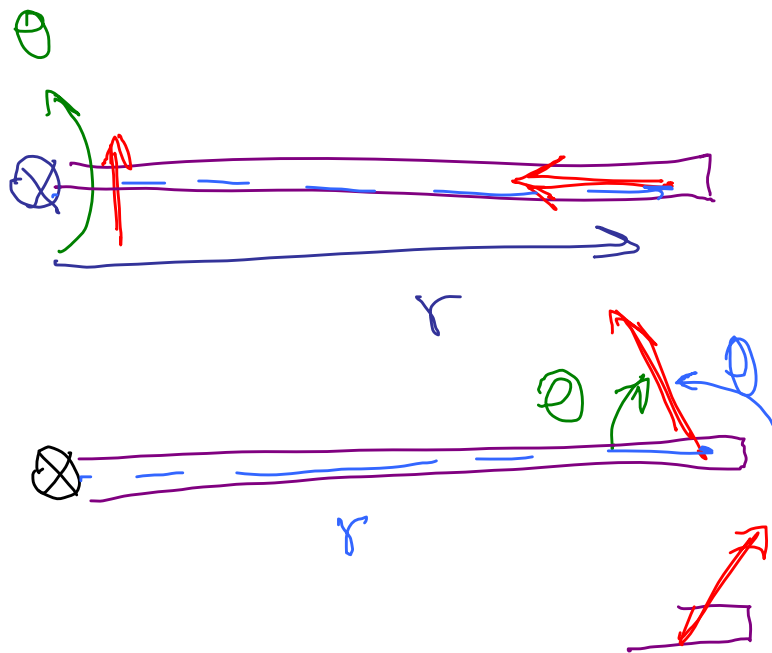
Kinematics



Dynamics

Why do things rotate

(Force) but ...



Push at large r .

$F, r, \sin \theta$

$$\tau = r F \sin \theta$$

torque

Torque

$$r F \sin \theta$$

Plus or minus

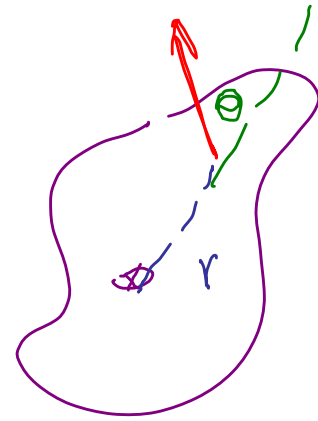
ccw : + cw : -

For now, it's scalar:

Units?

Units?

$$[\tau] = \text{m} \cdot \text{N} \\ = \text{N} \cdot \text{m}$$



$$1 \text{ J} = \text{N} \cdot \text{m}$$

Energy J

Torque N · m

Eq. ft · lb lb · ft

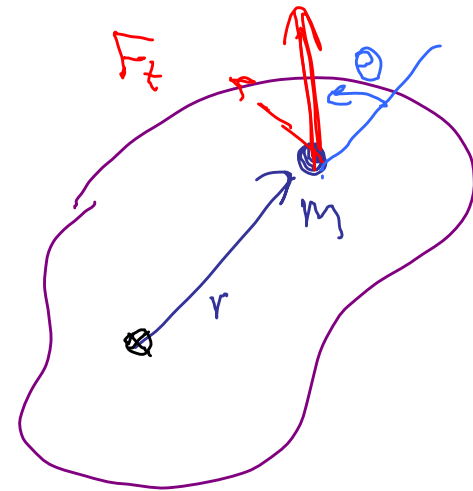
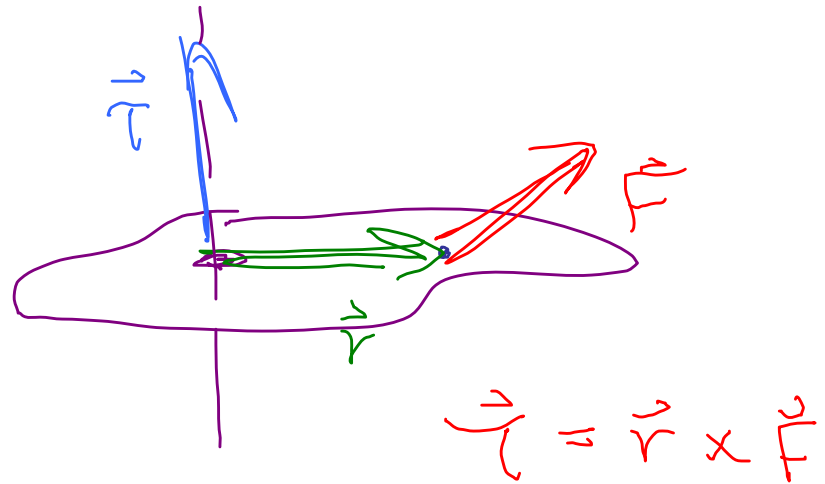
Later: Vector

Newton's 2nd Law
for Rotations

Heuristic derivation

$$m a_t = F_t = F \sin \theta$$

$$m r \alpha = F \sin \theta$$



Mult by r

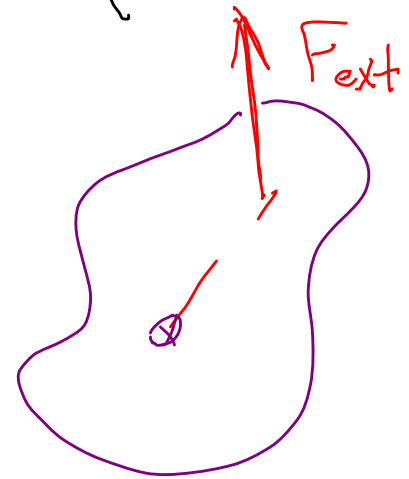
$$mr^2\alpha = rF\sin\theta = \tau$$

$$\tau = (mr^2)\alpha$$

Add up over all particles

$$\tau_{\text{net}} = \sum_i (m_i r_i^2 \alpha)$$

$$\tau_{\text{net}} = \left[\sum_i m_i r_i^2 \right] \alpha$$

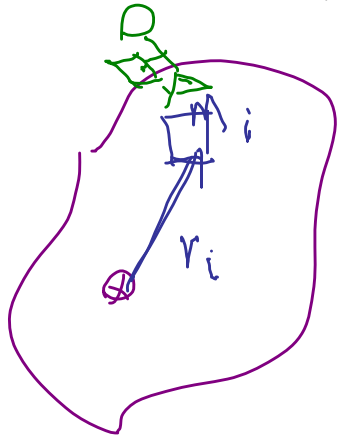


$$\begin{array}{ccccc} F & = & m & a \\ \downarrow & & \downarrow & \downarrow \\ \tau & & I & \alpha \end{array}$$

A green curved arrow points from the τ in the equation above to the τ in the equation below.

$$I = \sum_i m_i r_i^2$$

Moment of inertia
Rotational inertia

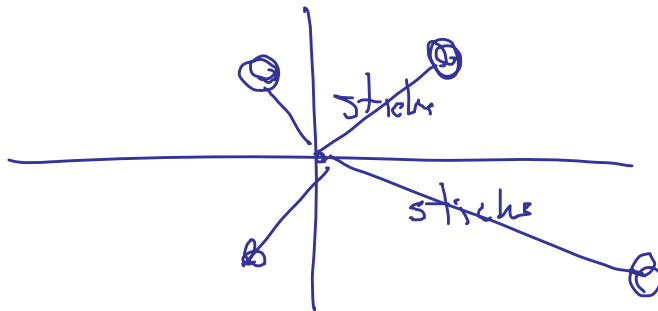


Scalar (Matrix!)

What is it?

Units:

$\text{kg} \cdot \text{m}^2$



$$\sum m r^2$$

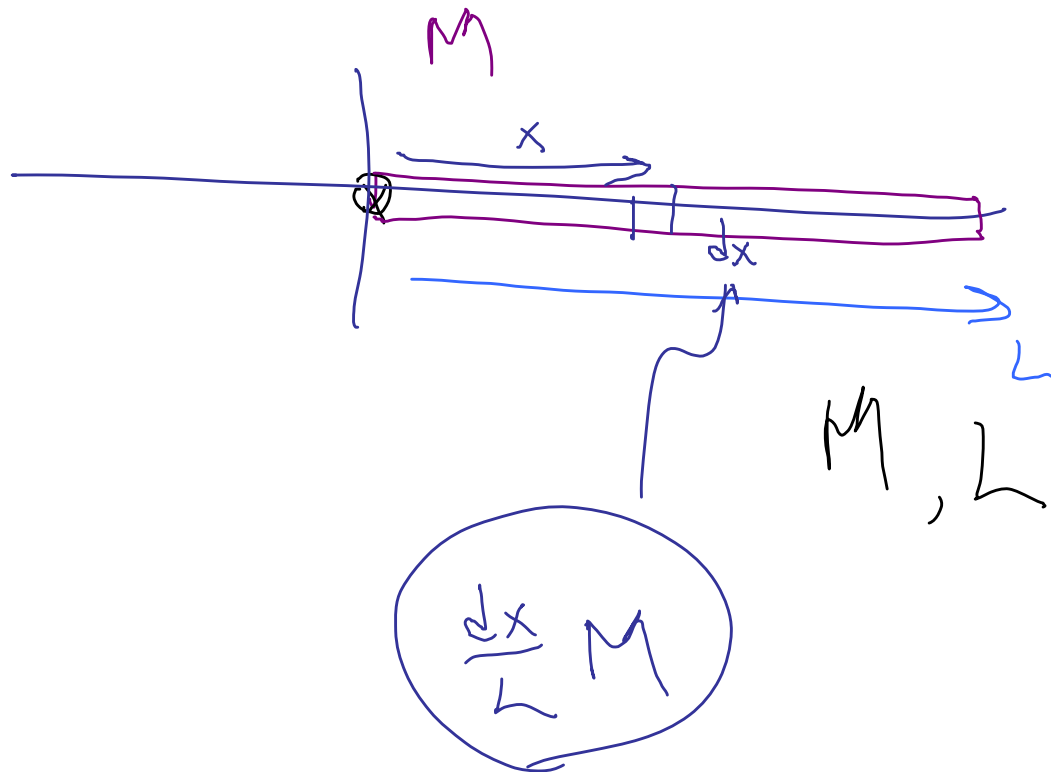
Example

$$I = \sum mr^2$$

$$\sum x^2 \cdot \frac{M dx}{L}$$

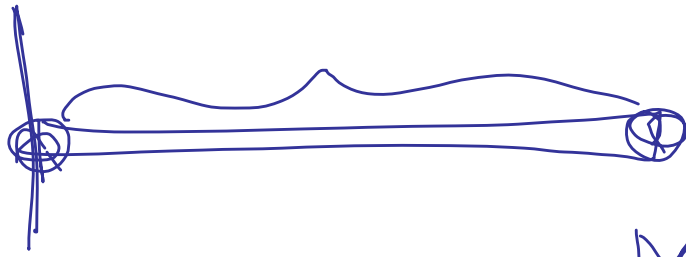
$$x: 0 \rightarrow L$$

$$I = \int_0^L \frac{M}{L} x^2 dx = \frac{M}{L} \int_0^L x^2 dx$$

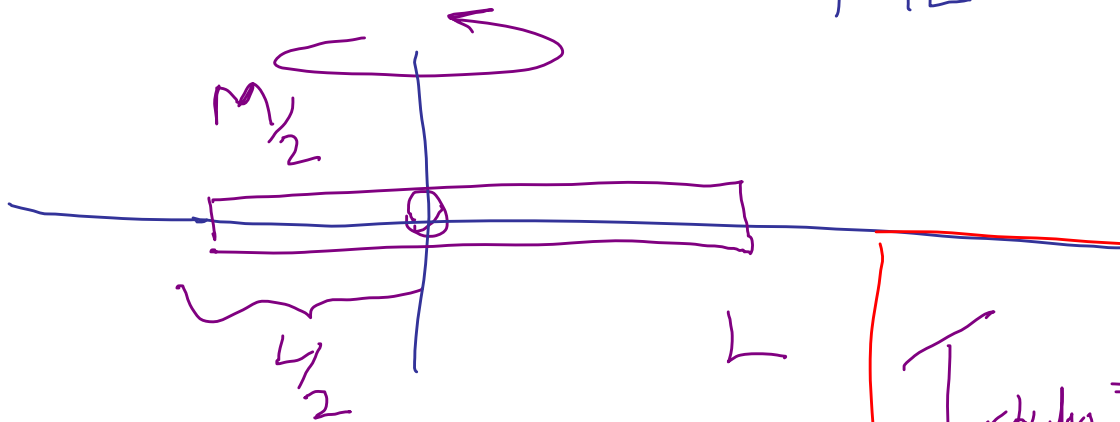


$$M \int \frac{x^3}{3} \Big|_0^L = \frac{1}{2} M L^3 + \frac{1}{3} M L^2$$

Stich
punkt

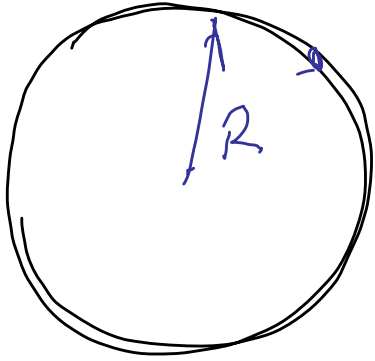


ML^2



$$I = \frac{1}{3} M \left(\frac{L}{2} \right)^2 + \frac{1}{3} M \left(\frac{L}{2} \right)^2$$

$$I_{\text{Stichpunkt}} = \frac{1}{12} M L^2$$



Loop

$$I_{\text{loop}} = MR^2$$