

Phys 2110-4 4/2/12

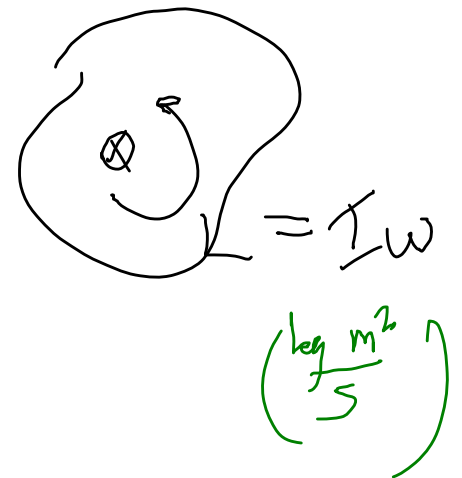
Note Title

4/2/2012

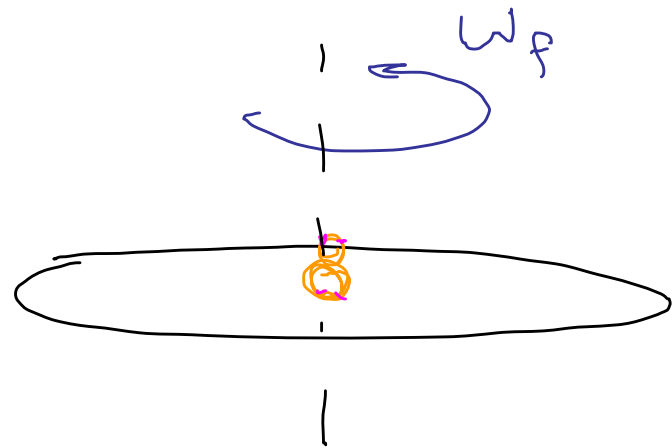
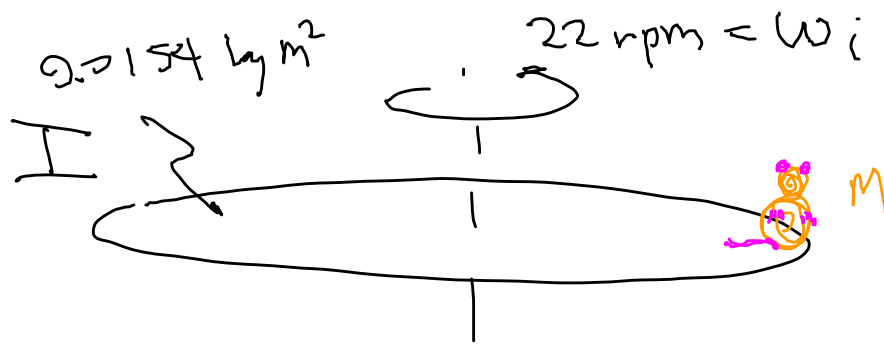
Angular Momentum

No (net) external torque

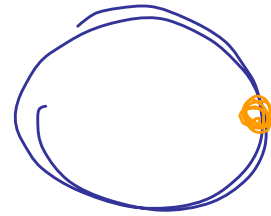
L_{total} is conserved.



11.38 A turntable of radius 25 cm
 & rot. inertia 0.0154 kg m^2 is spinning
 freely at 22 rpm about central axis
 with 19.5 g mouse at edge. Mouse walks
 from edge to center. Find new rotation rate
 & work done by mouse.



L_{total} is consd:



$$L_i = I_i \omega_i = (I_{\text{disk}} + mR^2) \omega_i$$

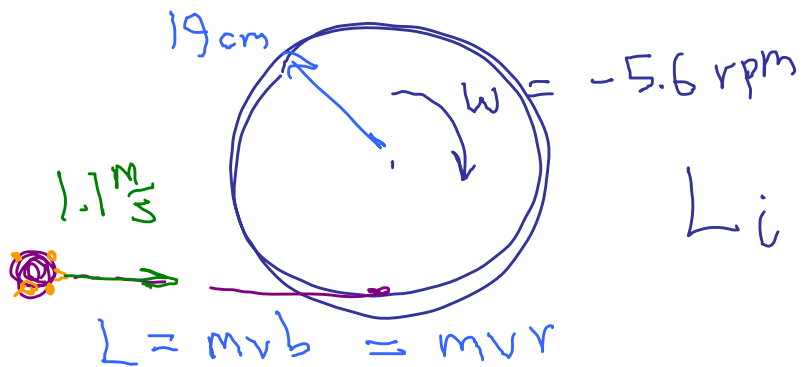
$$L_f = I_f \omega_f = (I_{\text{disk}}) \omega_f$$

Equal:

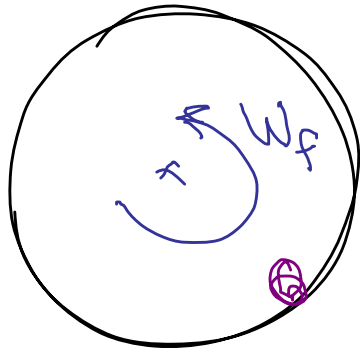
$$a) \quad \omega_f = \frac{(I_{\text{disk}} + mR^2)}{I_{\text{disk}}} \omega_i = 2.48 \frac{\text{rad}}{\text{s}} = 23.7 \frac{\text{rev}}{\text{min}}$$

$$b) \quad \Delta K_E = \frac{1}{2} I_f \omega_f^2 - \frac{1}{2} I_i \omega_i^2 = \boxed{3.3 \times 10^{-3} \text{ J}}$$

11.43 A circular bird feeder 19 cm in radius has rotational inertia 0.12 kg m^2 .
 Spinning slowly at 5.6 rpm.
 140 g bird lands on rim, comes in tangent at 1.1 m/s , opp feeder's rotation.
 What is rot'n rate after bird lands.



$$L_i = (I_{\text{feeder}})(-5.6 \text{ rpm}) + (140 \text{ g})(1.1 \frac{\text{m}}{\text{s}})(0.19 \text{ m})$$



$$\begin{aligned} L_f &= (I_{\text{system}}) \omega_f \\ &= (I_{\text{center}} + mr^2) \omega_f \end{aligned}$$

Equate them ω_f

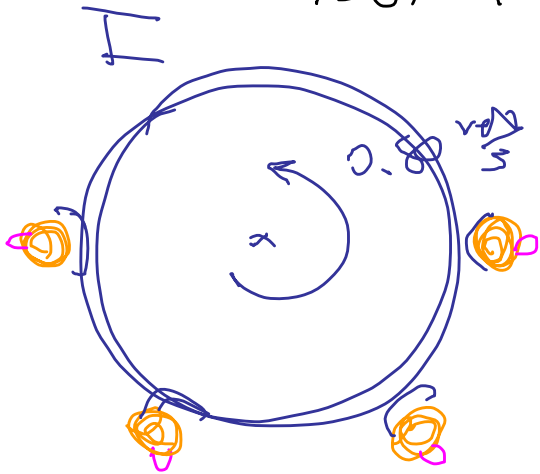
11.26

3m - diam. merry-go-round

$I = 120 \text{ kg m}^2$ spins 0.50 rev/s

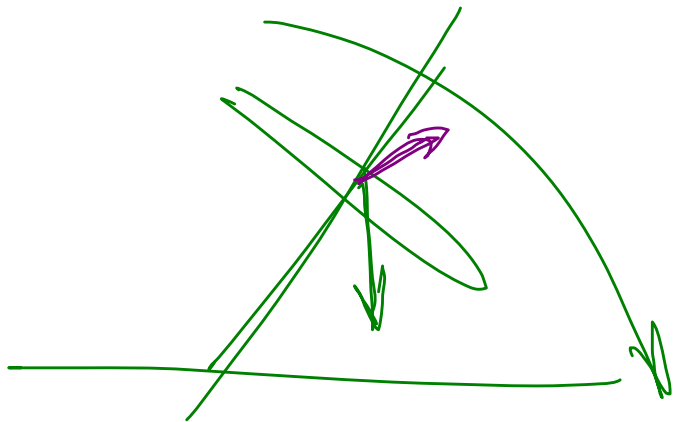
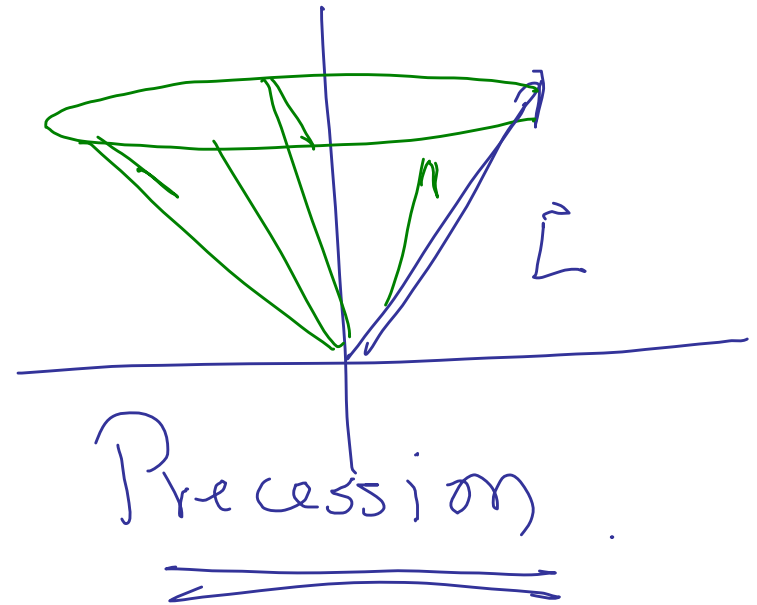
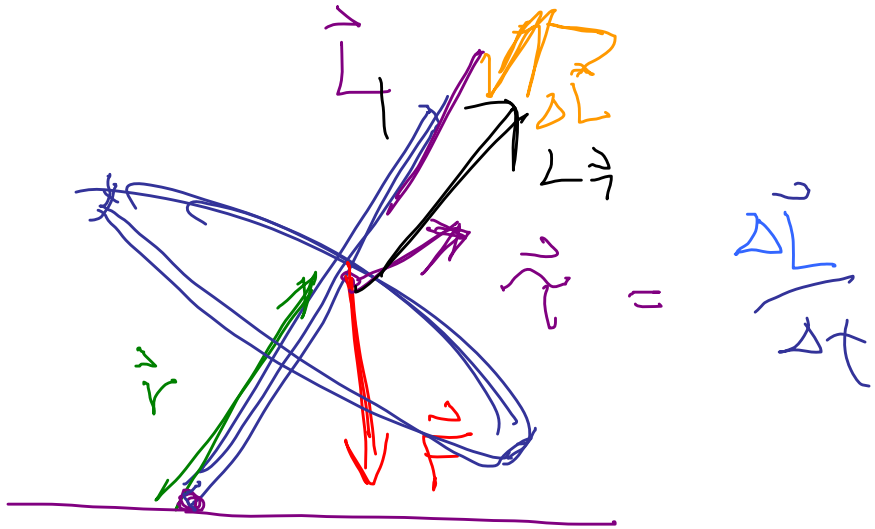
4 25 kg children sit suddenly on edge, find new angular speed, energy lost to friction

b) ΔK



$$I_{\text{disk}} \omega_i$$

$$= (I_{\text{disk}} + 4mr^2) \omega_f$$

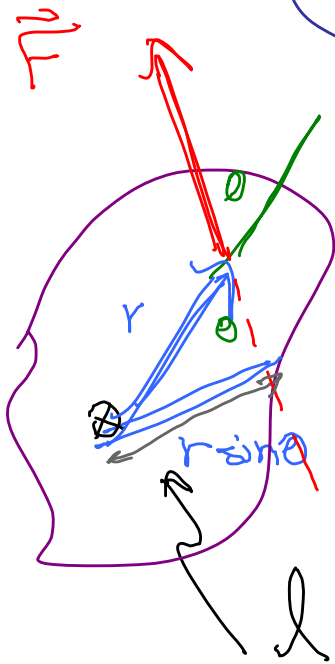
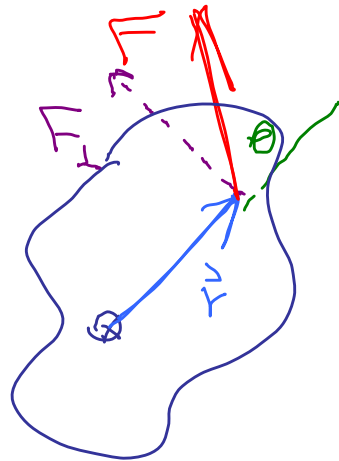


Chap: Vector nature.

$$\vec{\tau} = \vec{r} \times \vec{F} \quad \vec{L} = \vec{r} \times \vec{p}$$

$$L = I\omega \quad \underline{L \text{ is conserved.}}$$

Torque



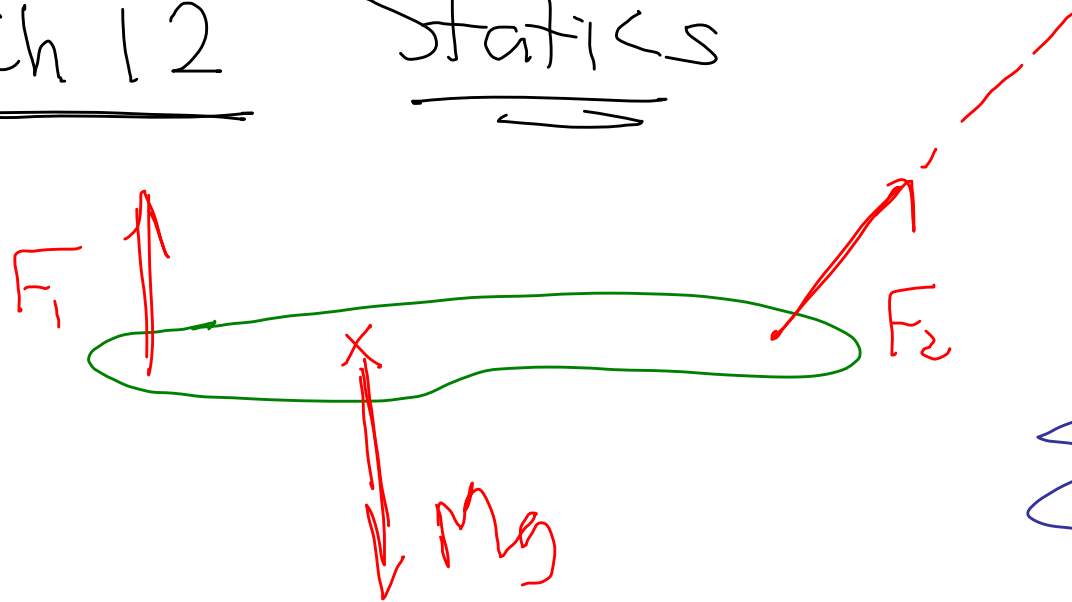
lever arm

$$\begin{aligned}\tau &= r F \sin \theta \\ &= r (F \sin \theta) \\ &= r F_{\perp}\end{aligned}$$

perp path $(\tau = r F)$

$$\begin{aligned}\tau &= (r \sin \theta) F \\ &= r_{\perp} F\end{aligned}$$

Ch 12 Statics



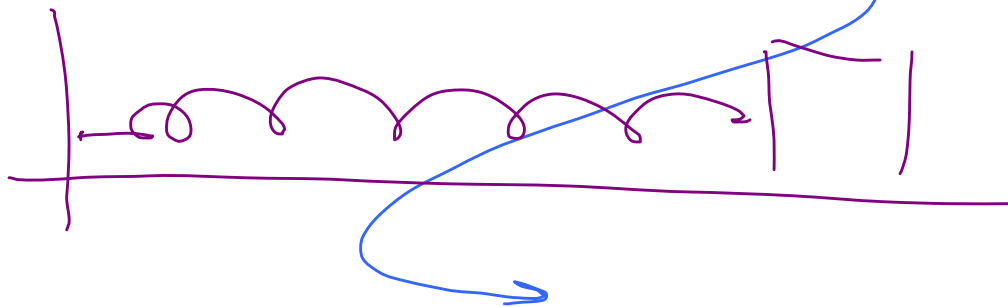
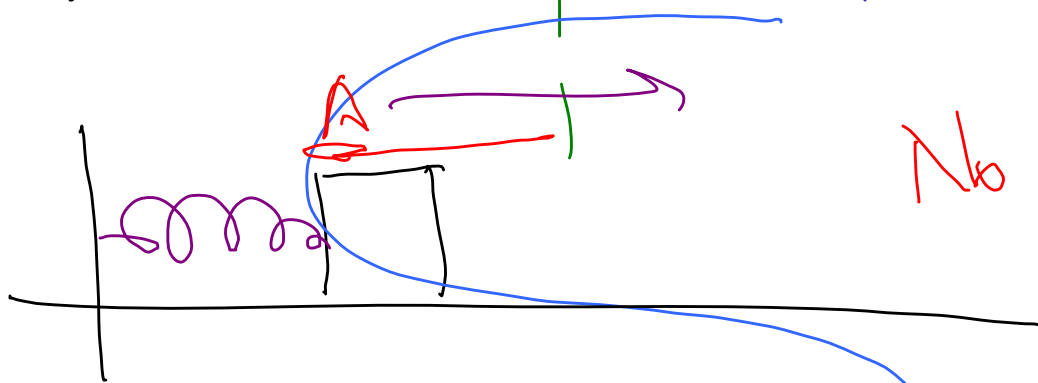
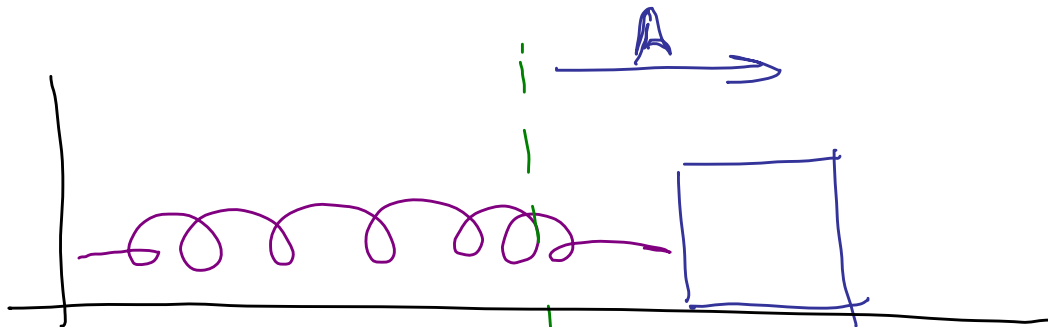
Not more.

$$\sum \vec{F} = 0$$

$$\sum \tau = 0$$

ME 2020 Statics

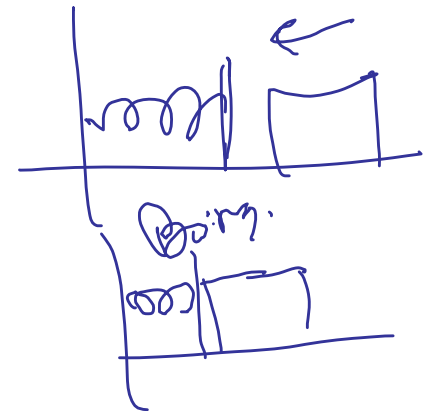


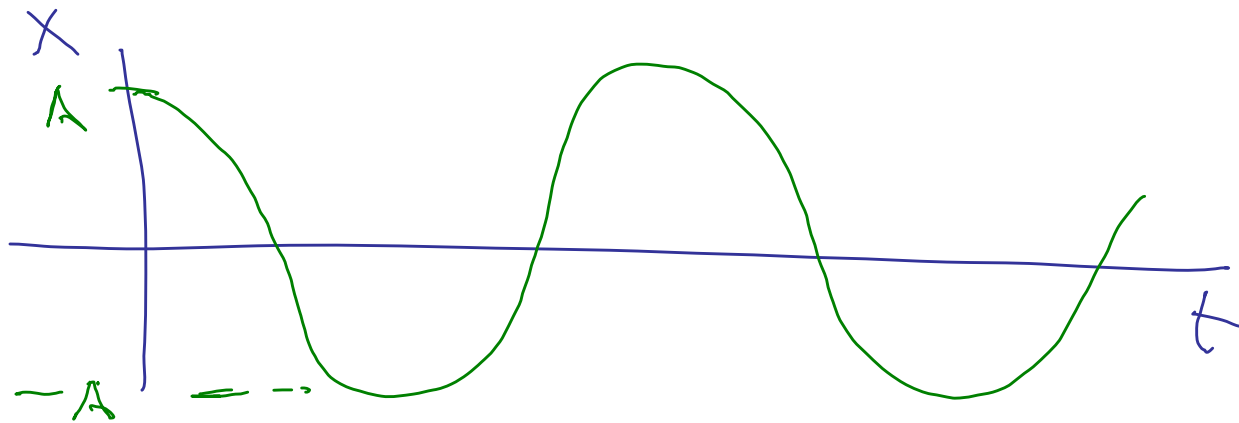


No fric.



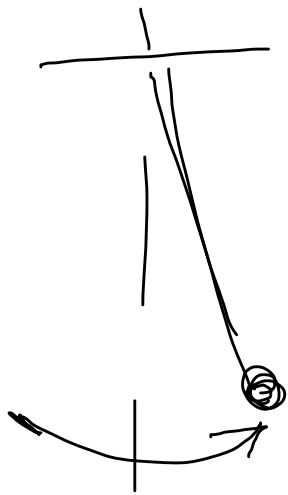
$$F_x = -kx$$





k, m

$A \cos(\omega t)$?



Oscillations
 (Linear Restoring Force)
 Simple Harmonic Motion
 SHM, SHO.