

```
In [1]: import numpy as np
import scipy.linalg
```

1 Python Machine Learning Stack (Anaconda)

Task 1

In your terminal, run

```
In [2]: !conda info

active environment : dl
active env location : C:\Users\kdmen\miniconda3\envs\dl
shell level : 2
user config file : C:\Users\kdmen\.condarc
populated config files : C:\Users\kdmen\.condarc
conda version : 23.3.1
conda-build version : not installed
python version : 3.9.16.final.0
virtual packages : __archspec=1=x86_64
                  __win=0=0
base environment : C:\Users\kdmen\miniconda3 (writable)
conda av data dir : C:\Users\kdmen\miniconda3\etc\conda
conda av metadata url : None
channel URLs : https://conda.anaconda.org/conda-forge/win-64
               https://conda.anaconda.org/conda-forge/noarch
               https://repo.anaconda.com/pkgs/main/win-64
               https://repo.anaconda.com/pkgs/main/noarch
               https://repo.anaconda.com/pkgs/r/win-64
               https://repo.anaconda.com/pkgs/r/noarch
               https://repo.anaconda.com/pkgs/msys2/win-64
               https://repo.anaconda.com/pkgs/msys2/noarch
package cache : C:\Users\kdmen\miniconda3\pkgs
                 C:\Users\kdmen\.conda\pkgs
                 C:\Users\kdmen\AppData\Local\conda\conda\pkgs
envs directories : C:\Users\kdmen\miniconda3\envs
                   C:\Users\kdmen\.conda\envs
                   C:\Users\kdmen\AppData\Local\conda\conda\envs
platform : win-64
user-agent : conda/23.3.1 requests/2.29.0 CPython/3.9.16 Windows/10 Win
dows/10.0.22621
administrator : False
netrc file : None
offline mode : False
```

3 Transition from MATLAB to Python

Task 2

Run all of Python commands in the table “Linear Algebra Equivalents” in Numpy for MATLAB Users.

```
In [3]: a = np.array([[1., 2., 3.], [4., 5., 6.]])
b = np.array([[7., 8., 9.], [10., 11., 12.]])
c = np.array([[2., 2., 2.], [4., 4., 4.]])
d = np.array([[1., 1., 1.], [3., 3., 3.]])

n = 1

v = np.array([1, 1, 10])

x = np.array([[5, 5, 5], [11, 12, 13]])
```

```
In [4]: np.ndim(a)
```

```
Out[4]: 2
```

```
In [5]: np.size(a)
```

```
Out[5]: 6
```

```
In [6]: np.shape(a)
```

```
Out[6]: (2, 3)
```

```
In [7]: a.shape[n-1]
```

```
Out[7]: 2
```

```
In [8]: np.array([[1., 2., 3.], [4., 5., 6.]])
```

```
Out[8]: array([[1., 2., 3.],
               [4., 5., 6.]])
```

```
In [9]: np.block([[a, b], [c, d]])
```

```
Out[9]: array([[ 1.,  2.,  3.,  7.,  8.,  9.],
               [ 4.,  5.,  6., 10., 11., 12.],
               [ 2.,  2.,  2.,  1.,  1.,  1.],
               [ 4.,  4.,  4.,  3.,  3.,  3.]])
```

```
In [10]: a[-1]
```

```
Out[10]: array([4., 5., 6.])
```

```
In [11]: # a[1, 4]
a[1, 2]
```

Out[11]: 6.0

```
In [12]: # a[1] or a[1, :]  
a[1, :]
```

Out[12]: array([4., 5., 6.])

```
In [13]: # a[0:5] or a[:5] or a[0:5, :]  
a[0:5, :]
```

Out[13]: array([[1., 2., 3.],
 [4., 5., 6.]])

```
In [14]: a[-5:]
```

Out[14]: array([[1., 2., 3.],
 [4., 5., 6.]])

```
In [15]: a[0:3, 4:9]
```

Out[15]: array([], shape=(2, 0), dtype=float64)

```
In [16]: # a[np.ix_([1, 3, 4], [0, 2])]
a[np.ix_([0, 1], [0, 1, 2])]
```

Out[16]: array([[1., 2., 3.],
 [4., 5., 6.]])

```
In [17]: a[2:21:2, :]
```

Out[17]: array([], shape=(0, 3), dtype=float64)

```
In [18]: a[:, :2, :]
```

Out[18]: array([[1., 2., 3.]])

```
In [19]: a[:, :-1, :]
```

Out[19]: array([[4., 5., 6.],
 [1., 2., 3.]])

```
In [20]: a[np.r_[:len(a), 0]]
```

Out[20]: array([[1., 2., 3.],
 [4., 5., 6.],
 [1., 2., 3.]])

```
In [21]: a.T
```

Out[21]: array([[1., 4.],
 [2., 5.],
 [3., 6.]])

```
In [22]: a.conj().T
```

```
Out[22]: array([[1., 4.],
               [2., 5.],
               [3., 6.]])
```

```
In [23]: # a @ b
         a @ b.T
```

```
Out[23]: array([[ 50.,  68.],
               [122., 167.]])
```

```
In [24]: a * b
```

```
Out[24]: array([[ 7., 16., 27.],
               [40., 55., 72.]])
```

```
In [25]: a/b
```

```
Out[25]: array([[0.14285714, 0.25      , 0.33333333],
               [0.4      , 0.45454545, 0.5      ]])
```

```
In [26]: a**3
```

```
Out[26]: array([[ 1.,  8., 27.],
               [ 64., 125., 216.]])
```

```
In [27]: (a > 0.5)
```

```
Out[27]: array([[ True,  True,  True],
               [ True,  True,  True]])
```

```
In [28]: np.nonzero(a > 0.5)
```

```
Out[28]: (array([0, 0, 0, 1, 1, 1], dtype=int64),
         array([0, 1, 2, 0, 1, 2], dtype=int64))
```

```
In [29]: a[:, np.nonzero(v > 0.5)[0]]
```

```
Out[29]: array([[1., 2., 3.],
               [4., 5., 6.]])
```

```
In [30]: a[:, v.T > 0.5]
```

```
Out[30]: array([[1., 2., 3.],
               [4., 5., 6.]])
```

```
In [31]: a[a < 0.5]=0
```

```
In [32]: a * (a > 0.5)
```

```
Out[32]: array([[1., 2., 3.],
               [4., 5., 6.]])
```

```
In [33]: a[:] = 3
```

```
In [34]: y = x.copy()
```

```
In [35]: y = x[1, :].copy()
```

```
In [36]: y = x.flatten()
```

```
In [37]: # np.arange(1., 11.) or np.r_[1.:11.] or np.r_[1:10:10j]
np.arange(1., 11.)
```

```
Out[37]: array([ 1.,  2.,  3.,  4.,  5.,  6.,  7.,  8.,  9., 10.])
```

```
In [38]: # np.arange(10.) or np.r_[ :10.] or np.r_[ :9:10j]
np.arange(10.)
```

```
Out[38]: array([0., 1., 2., 3., 4., 5., 6., 7., 8., 9.])
```

```
In [39]: np.arange(1.,11.)[:, np.newaxis]
```

```
Out[39]: array([[ 1.],
               [ 2.],
               [ 3.],
               [ 4.],
               [ 5.],
               [ 6.],
               [ 7.],
               [ 8.],
               [ 9.],
               [10.]])
```

```
In [40]: np.zeros((3, 4))
```

```
Out[40]: array([[0., 0., 0., 0.],
               [0., 0., 0., 0.],
               [0., 0., 0., 0.]])
```

```
In [41]: np.zeros((3, 4, 5))
```

```
Out[41]: array([[[0., 0., 0., 0., 0.],
                 [0., 0., 0., 0., 0.],
                 [0., 0., 0., 0., 0.],
                 [0., 0., 0., 0., 0.]],
               [[0., 0., 0., 0., 0.],
                 [0., 0., 0., 0., 0.],
                 [0., 0., 0., 0., 0.],
                 [0., 0., 0., 0., 0.]],
               [[0., 0., 0., 0., 0.],
                 [0., 0., 0., 0., 0.],
                 [0., 0., 0., 0., 0.],
                 [0., 0., 0., 0., 0.]])
```

```
In [42]: np.ones((3, 4))
```

```
Out[42]: array([[1., 1., 1., 1.],
                [1., 1., 1., 1.],
                [1., 1., 1., 1.]])
```

```
In [43]: np.eye(3)
```

```
Out[43]: array([[1., 0., 0.],
                [0., 1., 0.],
                [0., 0., 1.]])
```

```
In [44]: np.diag(a)
```

```
Out[44]: array([3., 3.])
```

```
In [45]: np.diag(v, 0)
```

```
Out[45]: array([[ 1,  0,  0],
                 [ 0,  1,  0],
                 [ 0,  0, 10]])
```

```
In [46]: from numpy.random import default_rng
rng = default_rng(42)
rng.random((3, 4))
```

```
Out[46]: array([[0.77395605, 0.43887844, 0.85859792, 0.69736803],
                 [0.09417735, 0.97562235, 0.7611397 , 0.78606431],
                 [0.12811363, 0.45038594, 0.37079802, 0.92676499]])
```

```
In [47]: np.linspace(1,3,4)
```

```
Out[47]: array([1.          , 1.66666667, 2.33333333, 3.          ])
```

```
In [48]: # np.mgrid[0:9.,0:6.] or np.meshgrid(r_[0:9.],r_[0:6.])
         np.mgrid[0:9.,0:6.]
```

[illegible]

```
In [49]: # ogrid[0:9.,0:6.] or np.ix_(np.r_[0:9.],np.r_[0:6.]
np.ogrid[0:9.,0:6.]
```

```
Out[49]: [array([[0.],
                [1.],
                [2.],
                [3.],
                [4.],
                [5.],
                [6.],
                [7.],
                [8.])),
          array([[0., 1., 2., 3., 4., 5.]])]
```

```
In [50]: np.meshgrid([1,2,4],[2,4,5])
```

```
Out[50]: [array([[1, 2, 4],
                [1, 2, 4],
                [1, 2, 4]]),
          array([[2, 2, 2],
                [4, 4, 4],
                [5, 5, 5]])]
```

```
In [51]: np.ix_([1,2,4],[2,4,5])
```

```
Out[51]: (array([[1],
                [2],
                [4]]),
          array([[2, 4, 5]]))
```

```
In [52]: m = 3
np.tile(a, (m, n))
```

```
Out[52]: array([[3., 3., 3.],
                [3., 3., 3.],
                [3., 3., 3.],
                [3., 3., 3.],
                [3., 3., 3.],
                [3., 3., 3.]])
```

```
In [53]: # np.concatenate((a,b),1) or np.hstack((a,b)) or np.column_stack((a,b)) or np.c_[a,
np.concatenate((a,b),1)
```

```
Out[53]: array([[ 3.,  3.,  3.,  7.,  8.,  9.],
                [ 3.,  3.,  3., 10., 11., 12.]])
```

```
In [54]: # np.concatenate((a,b)) or np.vstack((a,b)) or np.r_[a,b]
np.concatenate((a,b))
```

```
Out[54]: array([[ 3.,  3.,  3.],
                [ 3.,  3.,  3.],
                [ 7.,  8.,  9.],
                [10., 11., 12.]])
```

```
In [55]: a.max()
```

Out[55]: 3.0

```
In [56]: a.max(0)
```

Out[56]: array([3., 3., 3.])

```
In [57]: a.max(1)
```

Out[57]: array([3., 3.])

```
In [58]: np.maximum(a, b)
```

Out[58]: array([[7., 8., 9.],
 [10., 11., 12.]])

```
In [59]: # np.sqrt(v @ v) or np.linalg.norm(v)
np.linalg.norm(v)
```

Out[59]: 10.099504938362077

```
In [60]: np.logical_and(a,b)
```

Out[60]: array([[True, True, True],
 [True, True, True]])

```
In [61]: np.logical_or(a,b)
```

Out[61]: array([[True, True, True],
 [True, True, True]])

```
In [62]: aa = np.array([5, 3, 7], dtype=np.uint8)
bb = np.array([3, 6, 7], dtype=np.uint8)
```

```
#a & b
np.bitwise_and(aa, bb)
```

Out[62]: array([1, 2, 7], dtype=uint8)

```
In [63]: #a | b
np.bitwise_or(aa, bb)
```

Out[63]: array([7, 7, 7], dtype=uint8)

```
In [64]: sq_mtx = np.array([[1,2,3], [4,5,6], [7,8,9]])
np.linalg.inv(sq_mtx)
```

Out[64]: array([[-4.50359963e+15, 9.00719925e+15, -4.50359963e+15],
 [9.00719925e+15, -1.80143985e+16, 9.00719925e+15],
 [-4.50359963e+15, 9.00719925e+15, -4.50359963e+15]])

```
In [65]: np.linalg.pinv(sq_mtx)
```



```
Out[65]: array([[ -6.38888889e-01, -1.66666667e-01,  3.05555556e-01],
               [-5.55555556e-02,  3.46944695e-17,  5.55555556e-02],
               [ 5.27777778e-01,  1.66666667e-01, -1.94444444e-01]])
```

```
In [66]: np.linalg.matrix_rank(sq_mtrx)
```

```
Out[66]: 2
```

```
In [67]: # linalg.solve(a, b) if a is square; linalg.lstsq(a, b) otherwise
np.linalg.solve(sq_mtrx, sq_mtrx)
```

```
Out[67]: array([[1. , 0.5, 0. ],
               [0. , 0. , 0. ],
               [0. , 0.5, 1. ]])
```

```
In [68]: # MATLAB: b/a --> NUMPY: Solve a.T x.T = b.T instead
```

```
In [69]: U, S, Vh = np.linalg.svd(a); V = Vh.T
```

```
In [70]: A = np.array([[4, -1, 2],
                      [-1, 5, 3],
                      [2, 3, 6]])

# Check if the matrix is positive definite
is_positive_definite = np.all(np.linalg.eigvals(A) > 0)

np.linalg.cholesky(A)
```

```
Out[70]: array([[ 2.         ,  0.         ,  0.         ],
               [-0.5        ,  2.17944947,  0.         ],
               [ 1.         ,  1.60591014,  1.55597321]])
```

```
In [71]: D,V = np.linalg.eig(sq_mtrx)
```

```
In [72]: D,V = np.linalg.eig((sq_mtrx, sq_mtrx))
```

```
In [73]: # Compute all eigenvalues and eigenvectors
D, V = np.linalg.eigh(A)

# Get the k (three) largest eigenvalues and their corresponding eigenvectors
k = 3
top_eigenvalues = D[-k:]
top_eigenvectors = V[:, -k:]
```

```
In [74]: Q,R = np.linalg.qr(A)
```

```
In [75]: # P,L,U = linalg.lu(a) where a == P@L@U
import scipy
P,L,U = scipy.linalg.lu(A)
```

```
In [76]: np.fft.fft(a)
```

```
Out[76]: array([[9.+0.j, 0.+0.j, 0.+0.j],
               [9.+0.j, 0.+0.j, 0.+0.j]])
```

```
In [77]: np.fft.ifft(a)
```

```
Out[77]: array([[3.+0.j, 0.+0.j, 0.+0.j],
               [3.+0.j, 0.+0.j, 0.+0.j]])
```

```
In [78]: # np.sort(a) or a.sort(axis=0)
         np.sort(a)
```

```
Out[78]: array([[3., 3., 3.],
               [3., 3., 3.]])
```

```
In [79]: # np.sort(a, axis=1) or a.sort(axis=1)
         np.sort(a, axis=1)
```

```
Out[79]: array([[3., 3., 3.],
               [3., 3., 3.]])
```

```
In [80]: I = np.argsort(a[:, 0]); b = a[I,:]
```

```
In [81]: Z = np.array([[1, 2], [3, 4], [5, 6]])
         y = np.array([7, 8, 9])
         np.linalg.lstsq(Z, y, rcond=None)[0]
```

```
Out[81]: array([-6. ,  6.5])
```

```
In [82]: from scipy.signal import resample
         x = np.array([1, 2, 3, 4, 5])
         resample(x, int(np.ceil(len(x) / 2)))
```

```
Out[82]: array([2.          , 2.30801829, 4.69198171])
```

```
In [83]: np.unique(a)
```

```
Out[83]: array([3.])
```

```
In [84]: a.squeeze()
```

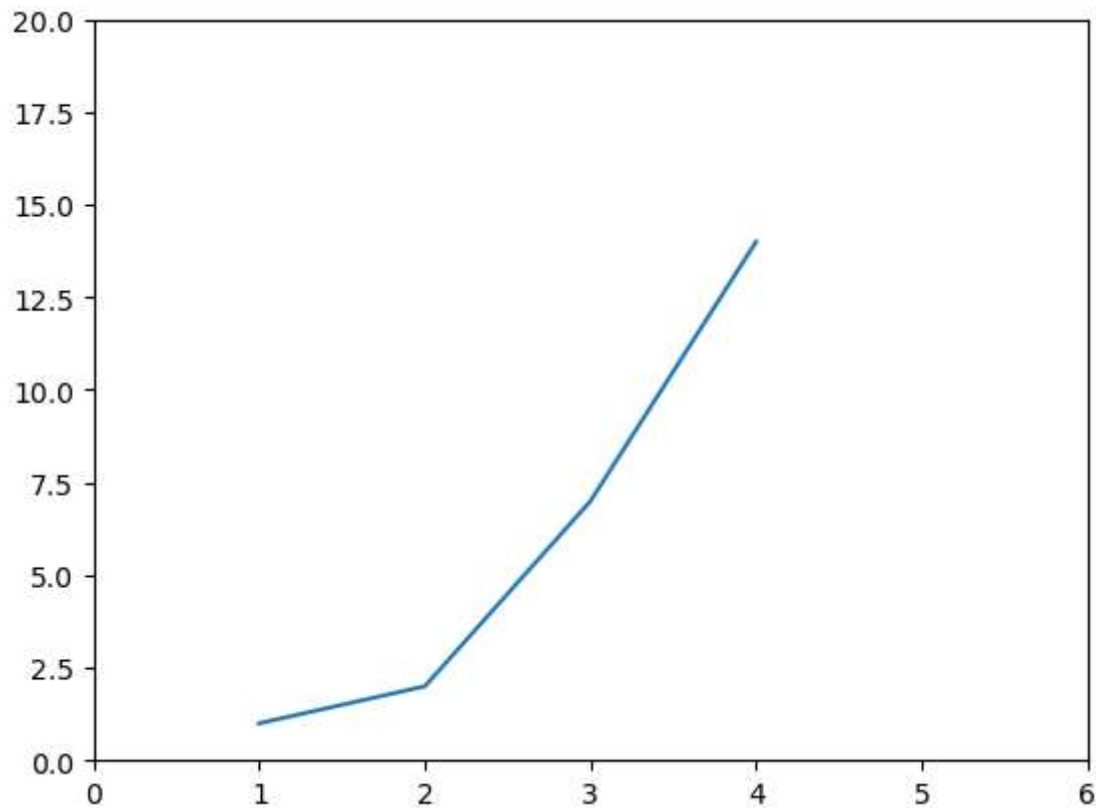
```
Out[84]: array([[3., 3., 3.],
               [3., 3., 3.]])
```

4 Plotting (Matplotlib / PyPlot)

Task 3

Run the following script in IPython and paste the figure created by the script into your report.

```
In [85]: import matplotlib.pyplot as plt
plt.plot([1,2,3,4], [1,2,7,14])
plt.axis([0, 6, 0, 20])
plt.show()
```

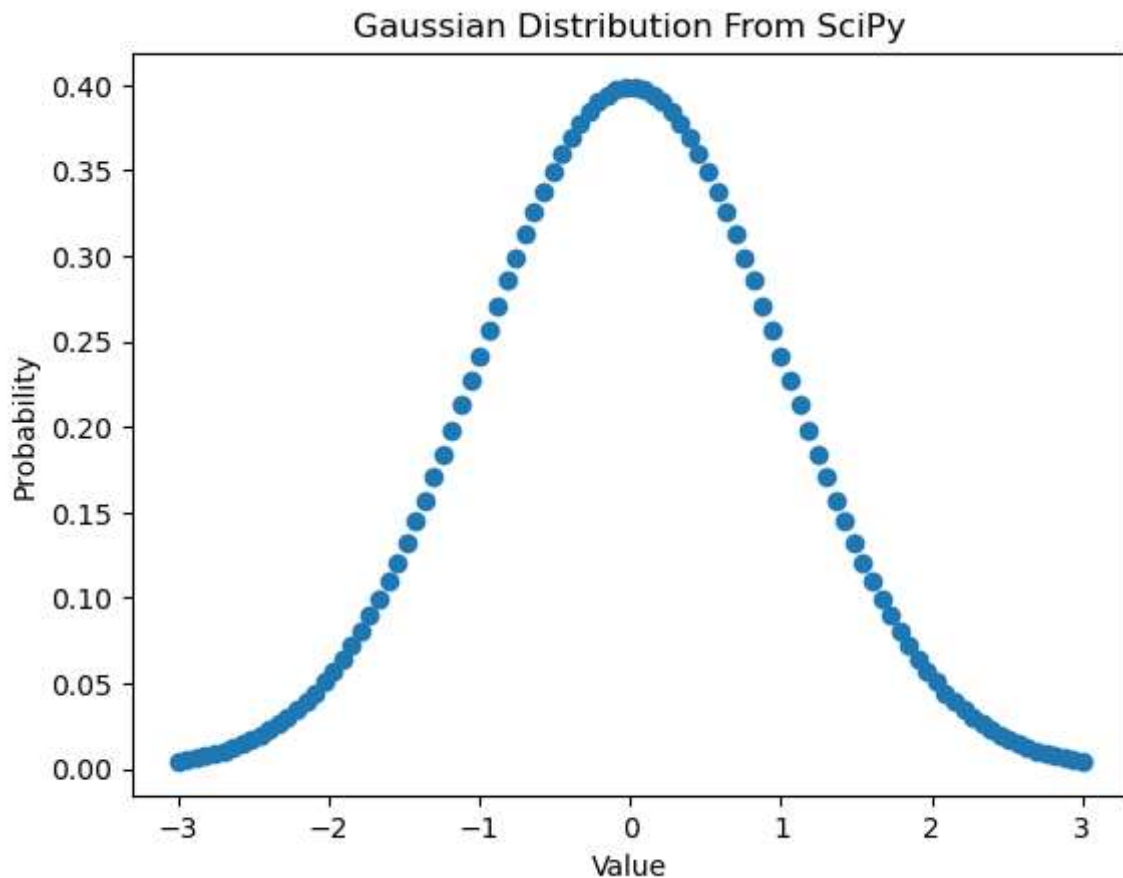


Task 4

Use Matplotlib to create a figure of your choice in IPython. Paste your code and figure into your report.

```
In [86]: import scipy.stats as stats

mean = 0
variance = 1
std = np.sqrt(variance)
x = np.linspace(mean-3*std, mean+3*std, 100)
plt.scatter(x, stats.norm.pdf(x, mean, std))
plt.title("Gaussian Distribution From SciPy")
plt.xlabel("Value")
plt.ylabel("Probability")
plt.show()
```



5 Version Control System (BitBucket/GitHub)

Task 5:

Paste your VCS account into your report.

- Platform: Github
- Username: kdmalc
- Link: <https://github.com/kdmalc>

6 Integrated Development Environment (PyCharm)

Task 6:

Start a new project in Pycharm. Commit and push your project to Bitbucket/GitHub as a public project. Paste the link of your project in your report.

- <https://github.com/kdmalc/deeplearning576>

In []: