

ALGORITMOS DE BUSCA INTERVALAR ORTOGONAIS

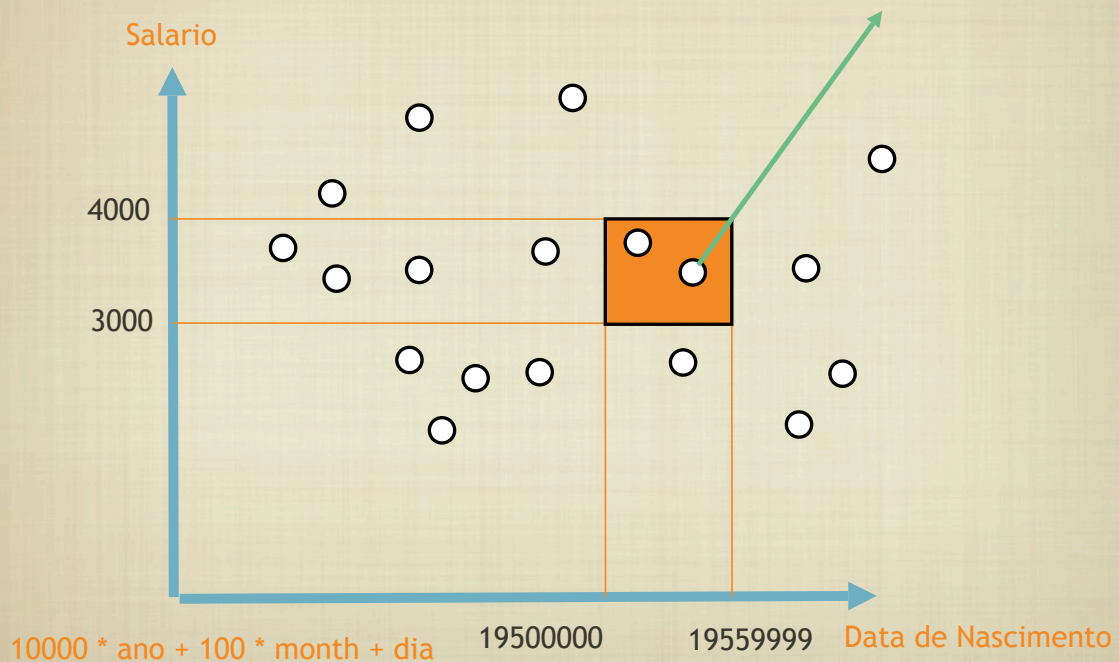
JOÃO COMBA

PROBLEMA

NOME	NASCIMENTO	SALARIO
JOSE DA SILVA	19/08/1954	3500
JOAO DA SILVA	21/03/1936	7000
LUIZ DA SILVA	22/10/1981	1000
...

Q: Reportar todos funcionarios nascidos entre 1950 e 1955 que recebem entre 3000 e 4000 por mes

INTERPRETACAO

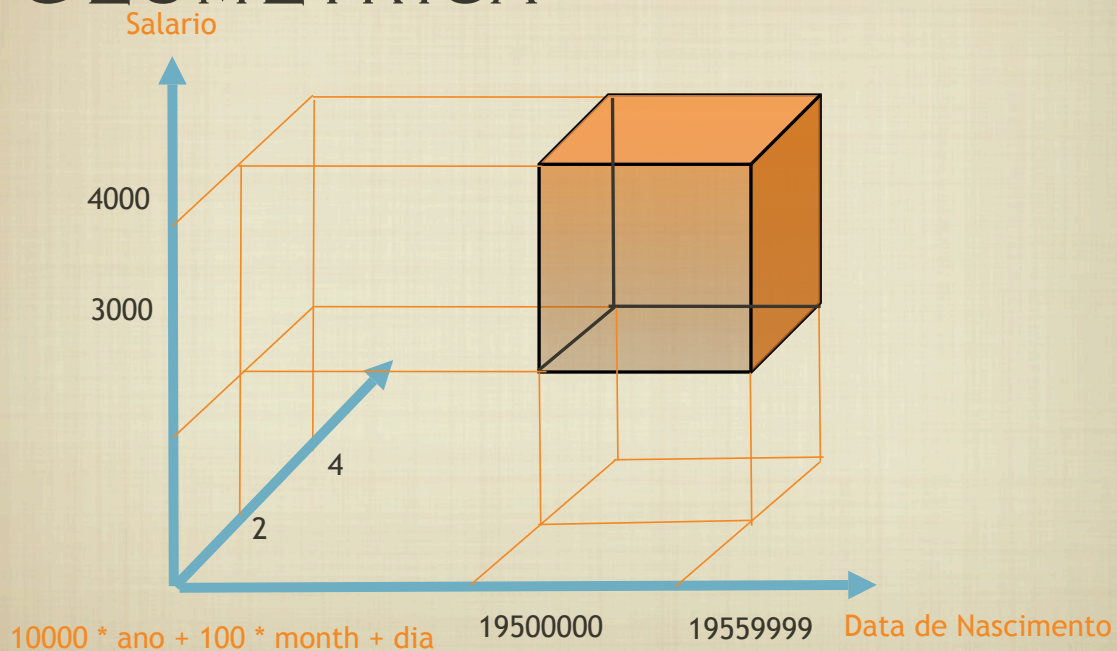


PROBLEMA

NOME	NASCIMENTO	SALARIO	FILHOS
JOSE DA SILVA	19/08/1954	3500	3
JOAO DA SILVA	21/03/1936	7000	0
LUIZ DA SILVA	22/10/1981	1000	2
...	

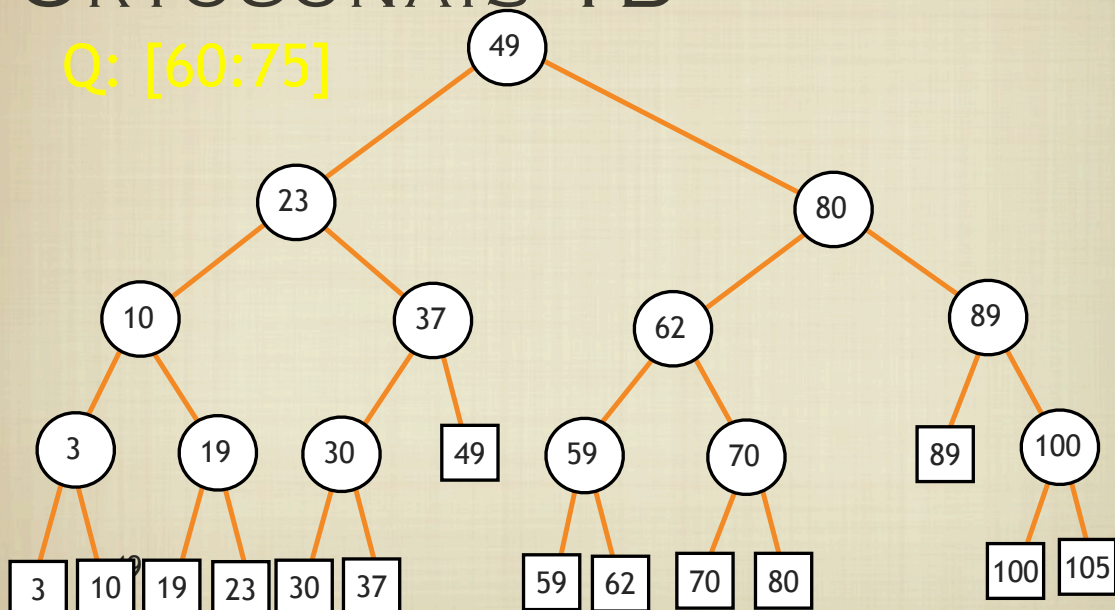
Q: Reportar todos funcionarios nascidos entre 1950 e 1955 que recebem entre 3000 e 4000 por mes e que tenham entre 2 e 4 filhos

INTERPRETACAO GEOMETRICA



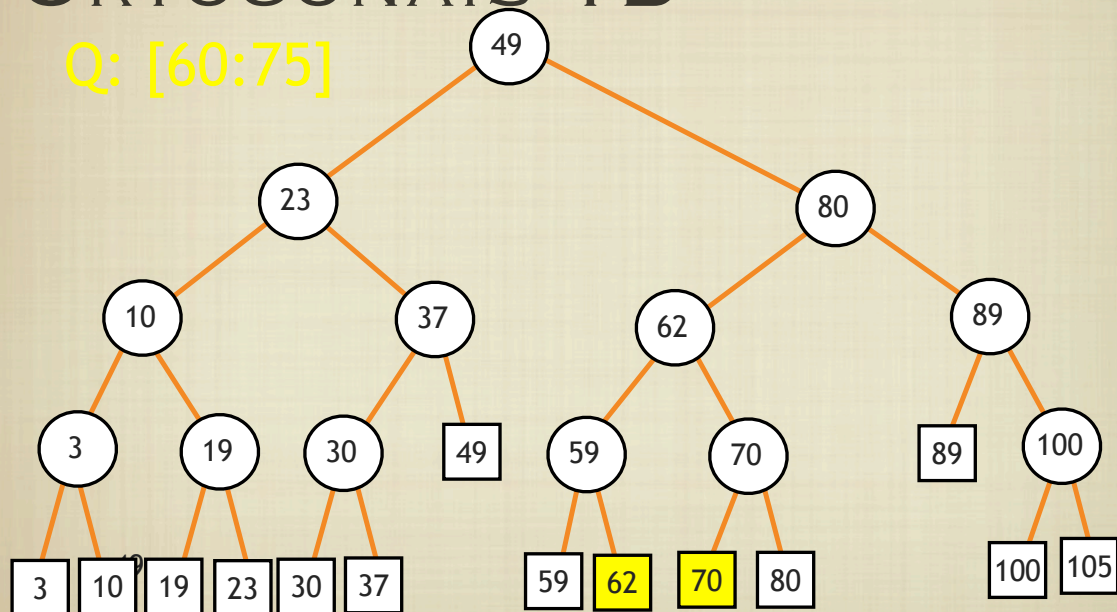
BUSCAS INTERVALARES ORTOGONAIS 1D

Q: [60:75]

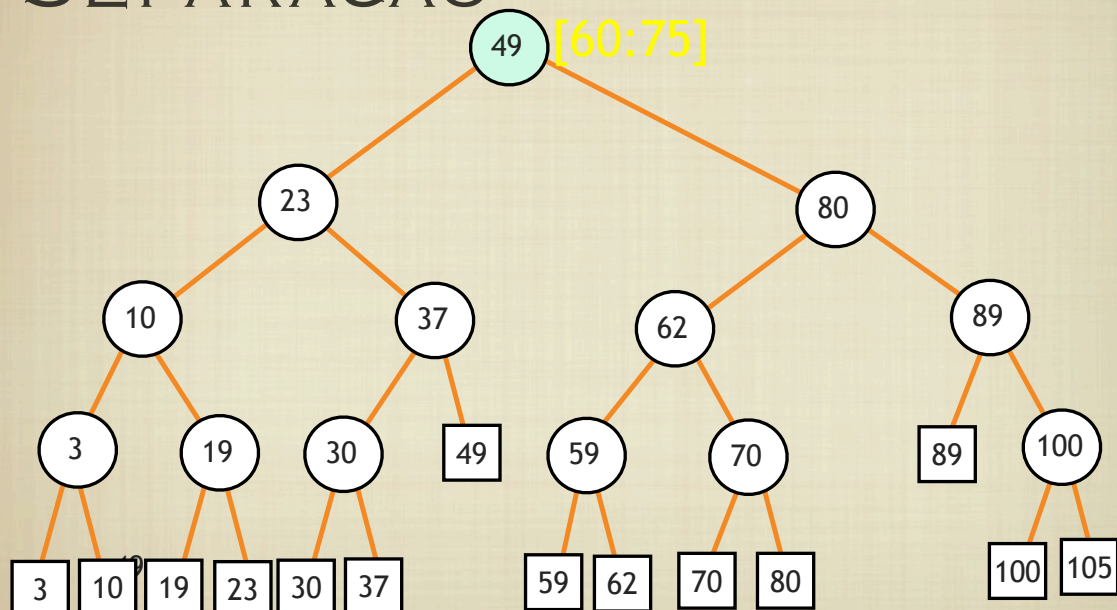


BUSCAS INTERVALARES ORTOGONAIS 1D

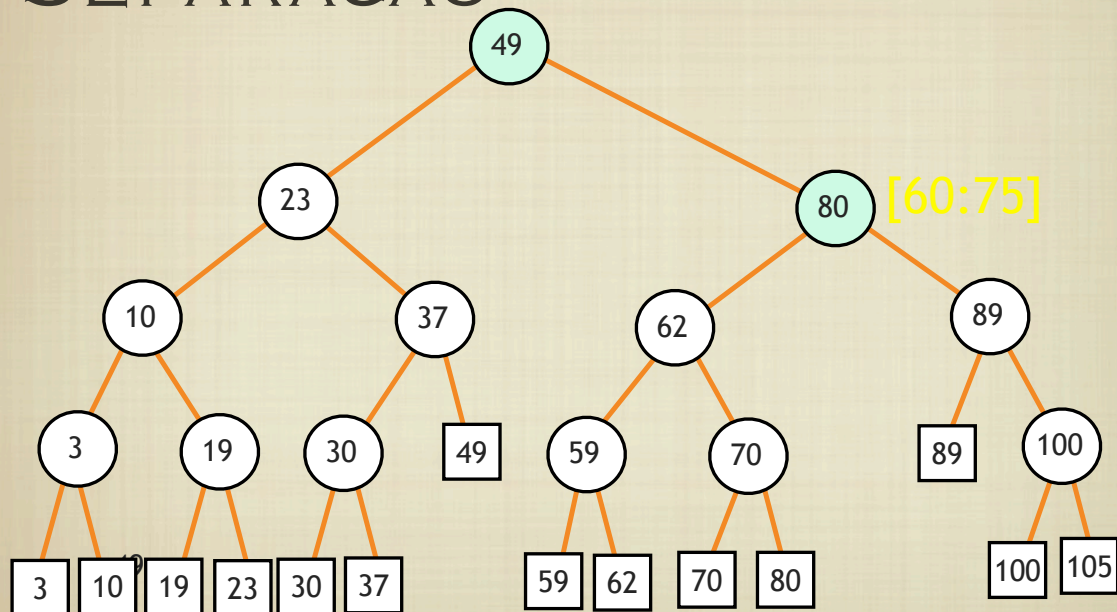
Q: [60:75]



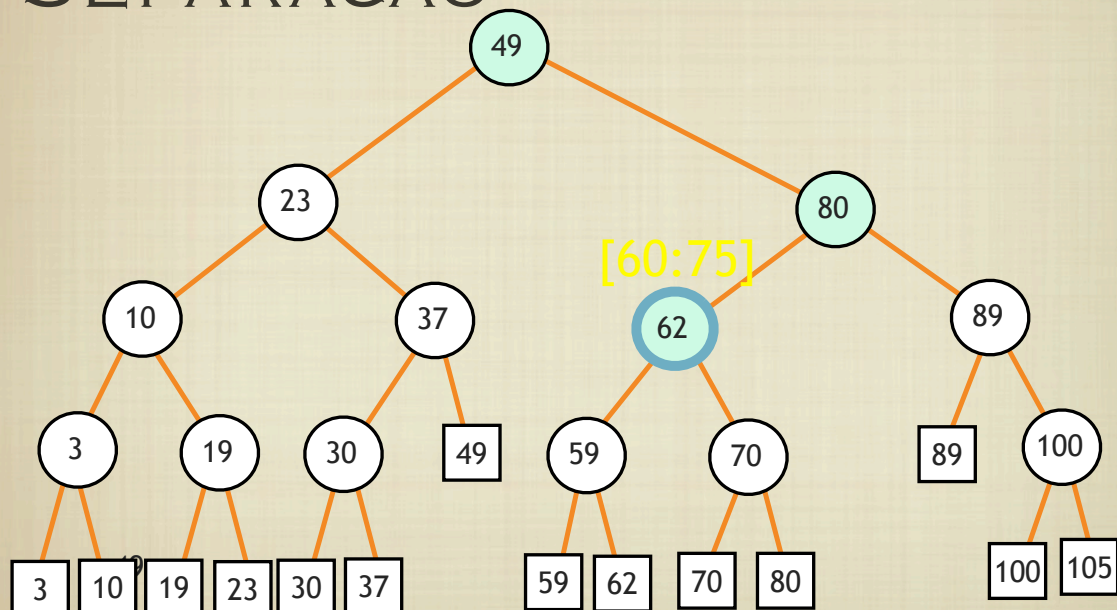
1. BUSCA NODO DE SEPARACAO



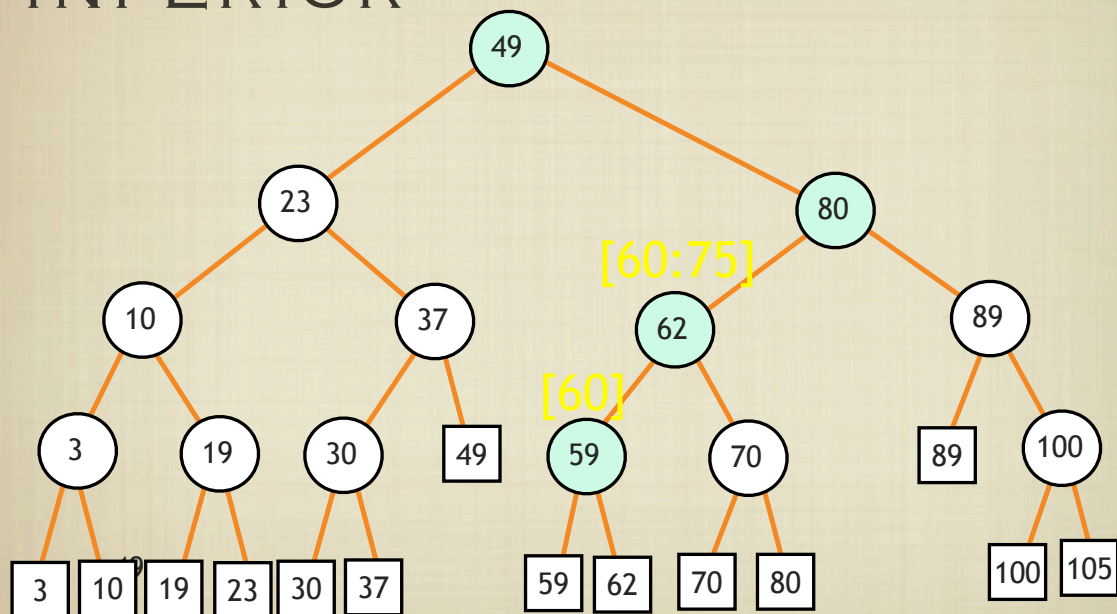
1. BUSCA NODO DE SEPARACAO



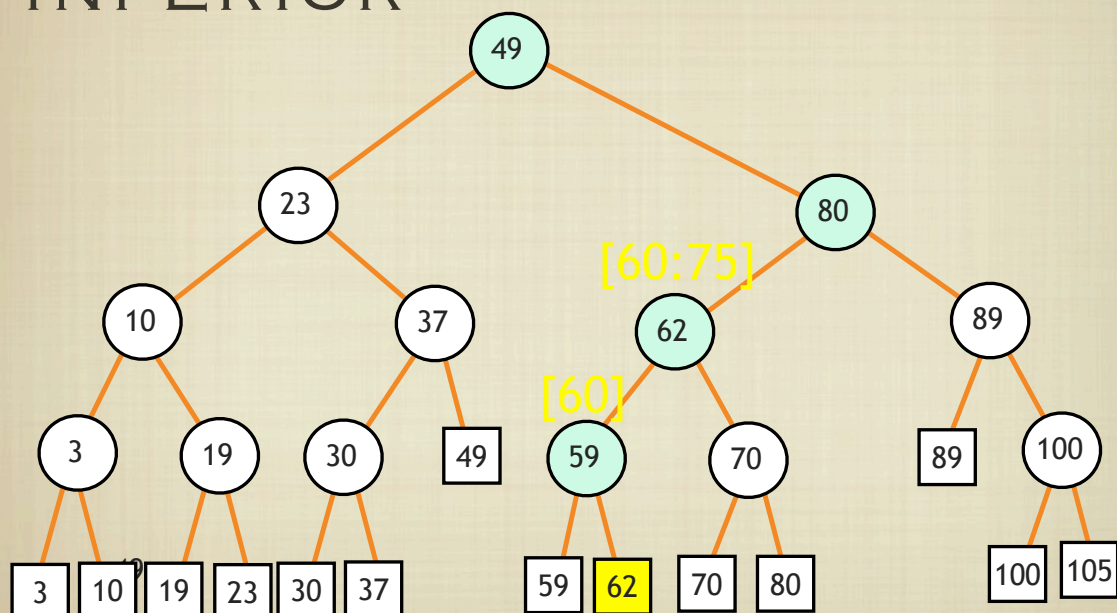
1. BUSCA NODO DE SEPARACAO



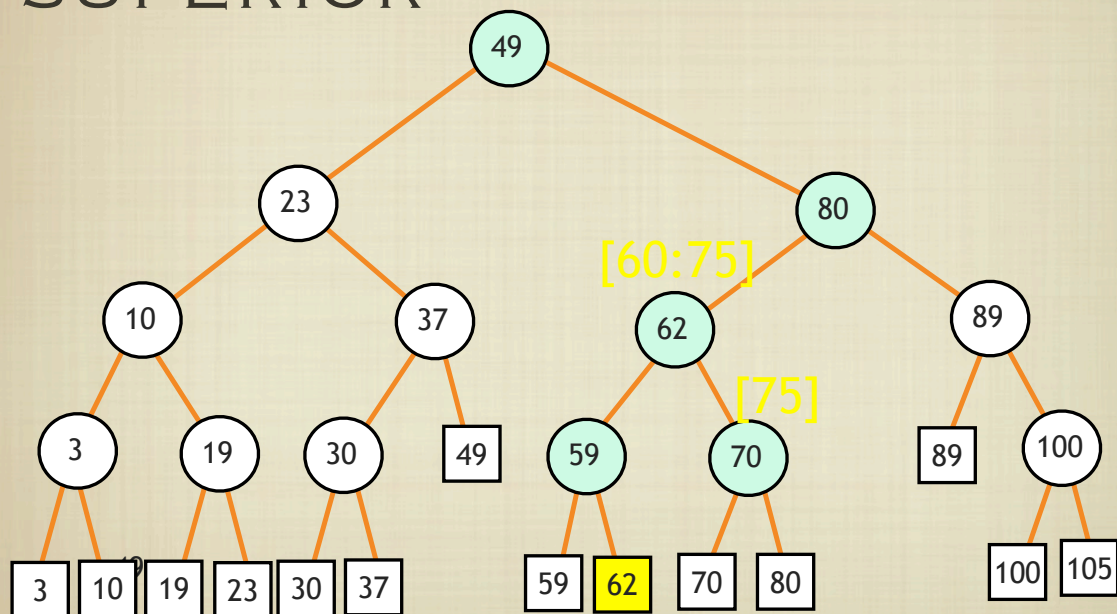
2. ENCONTRA LIMITE INFERIOR



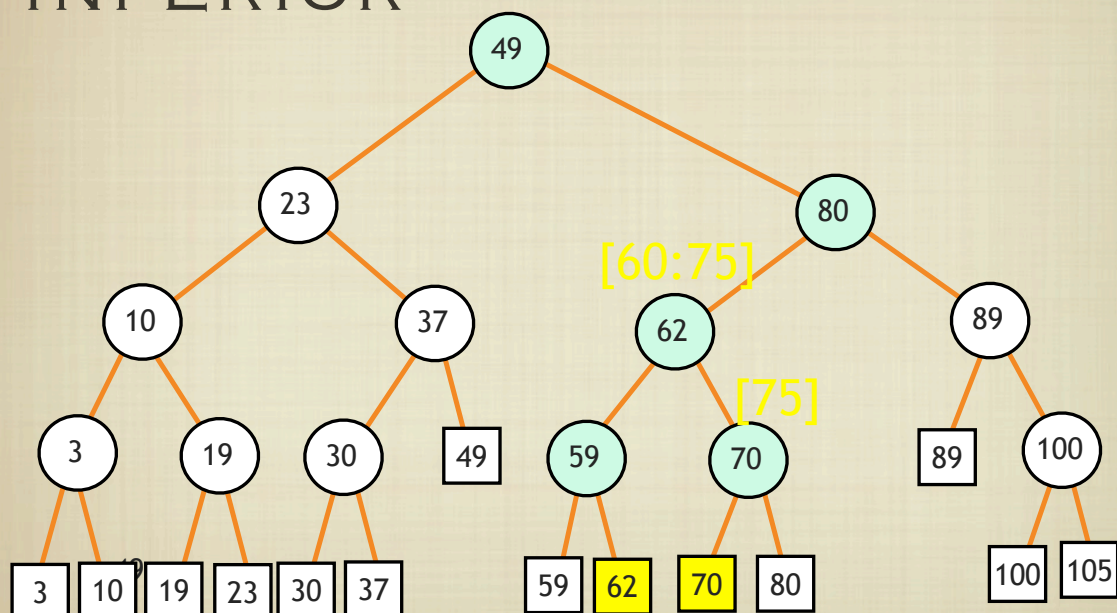
2. ENCONTRA LIMITE INFERIOR



3. ENCONTRA LIMITE SUPERIOR

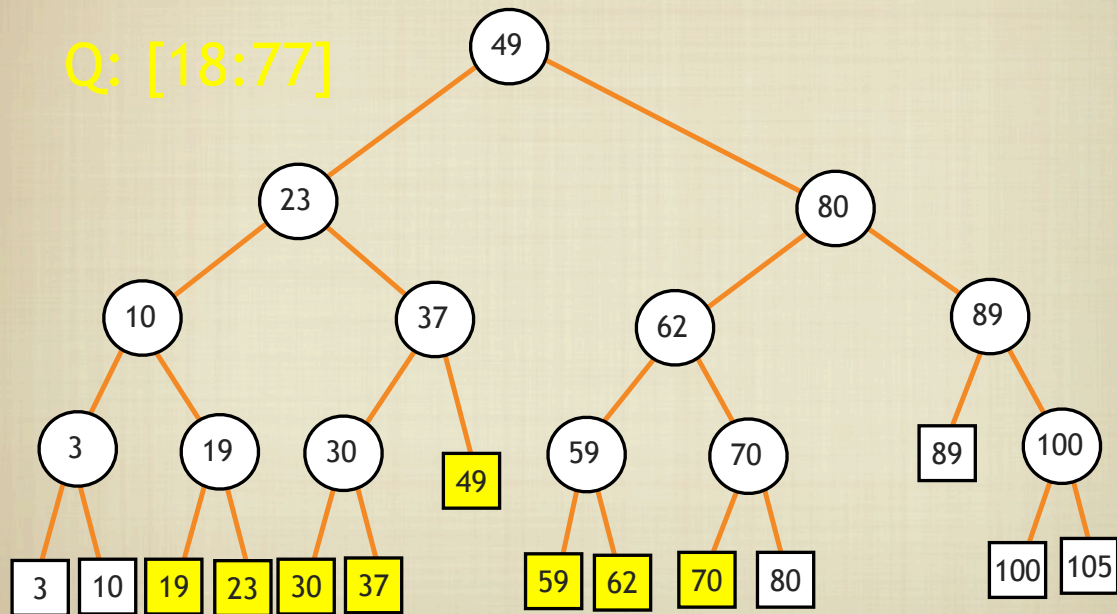


3. ENCONTRA LIMITE INFERIOR

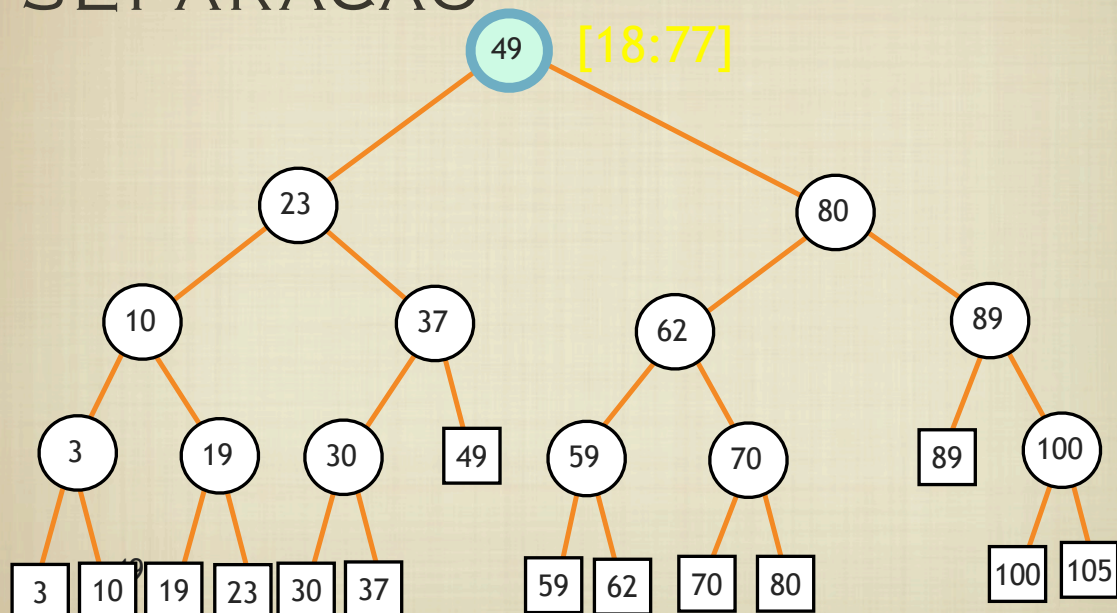


OUTRO EXEMPLO

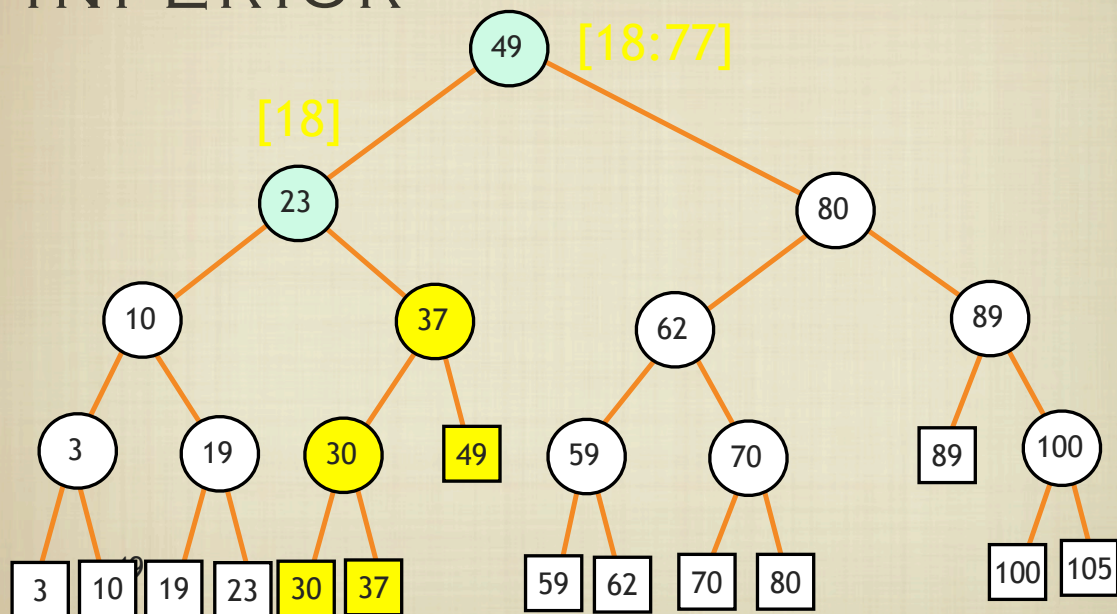
Q: [18:77]



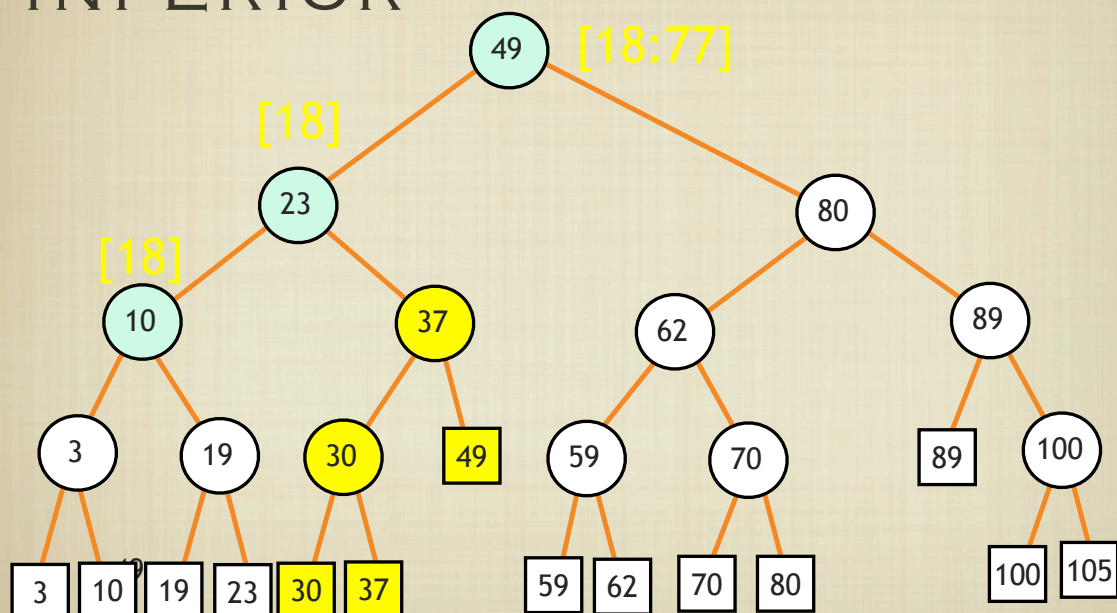
1. BUSCA NODO DE SEPARACAO



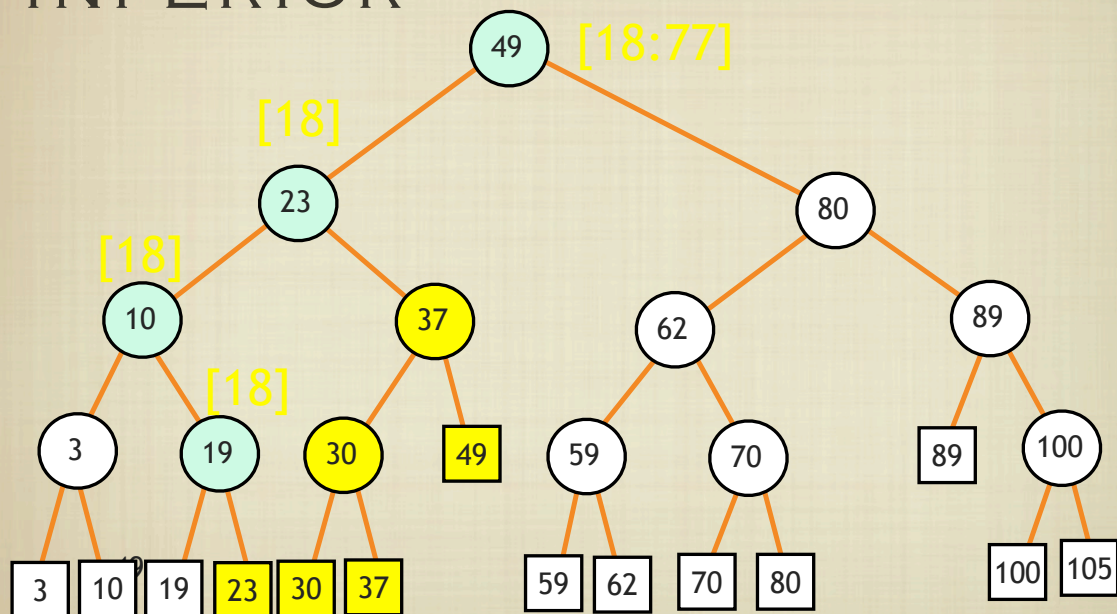
2. ENCONTRA LIMITE INFERIOR



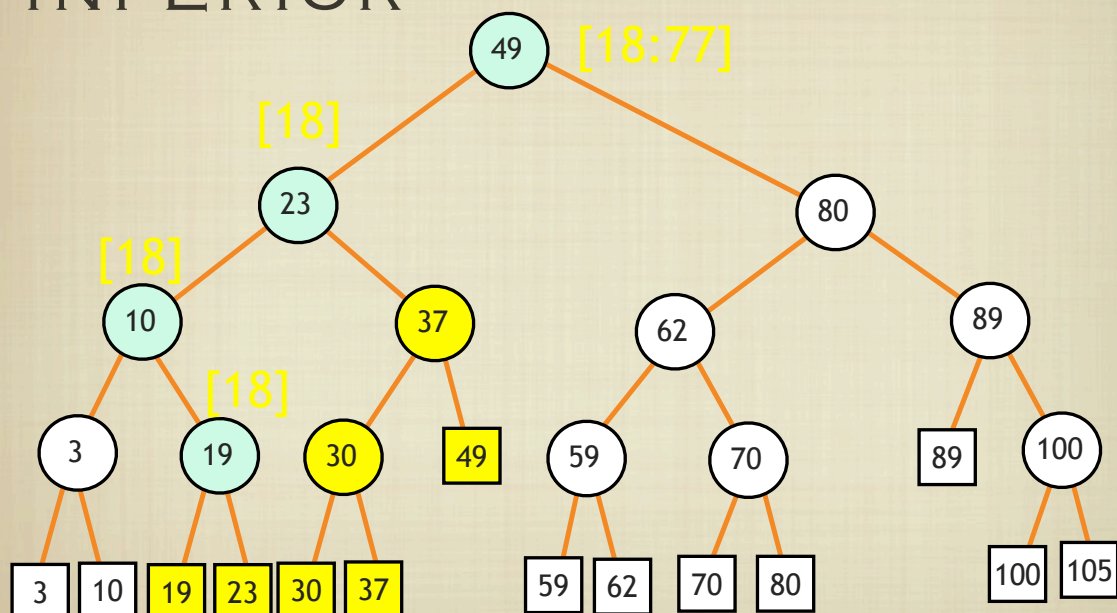
2. ENCONTRA LIMITE INFERIOR



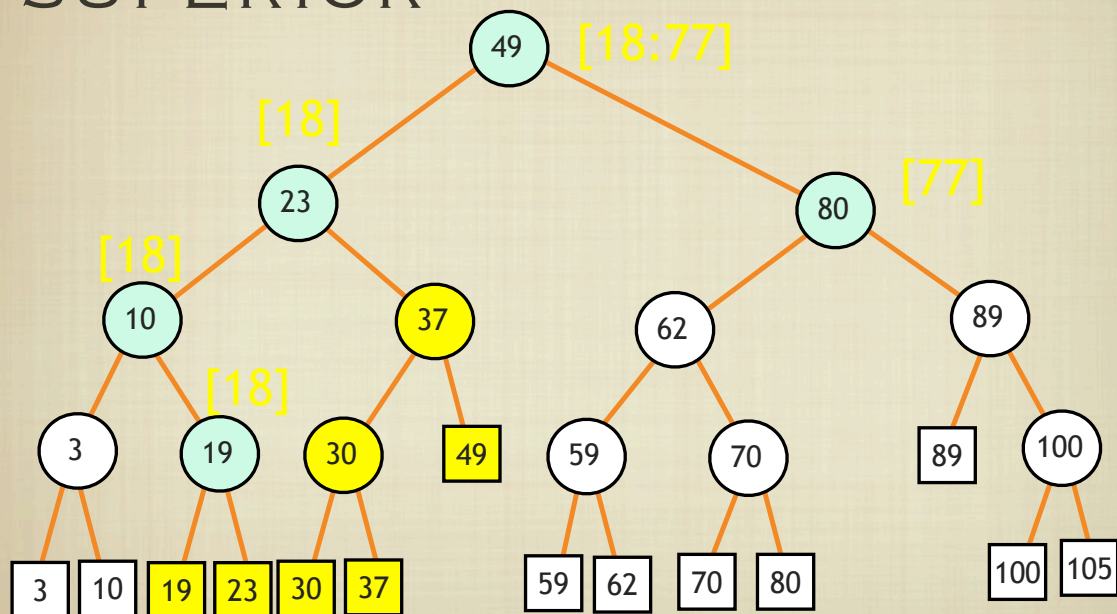
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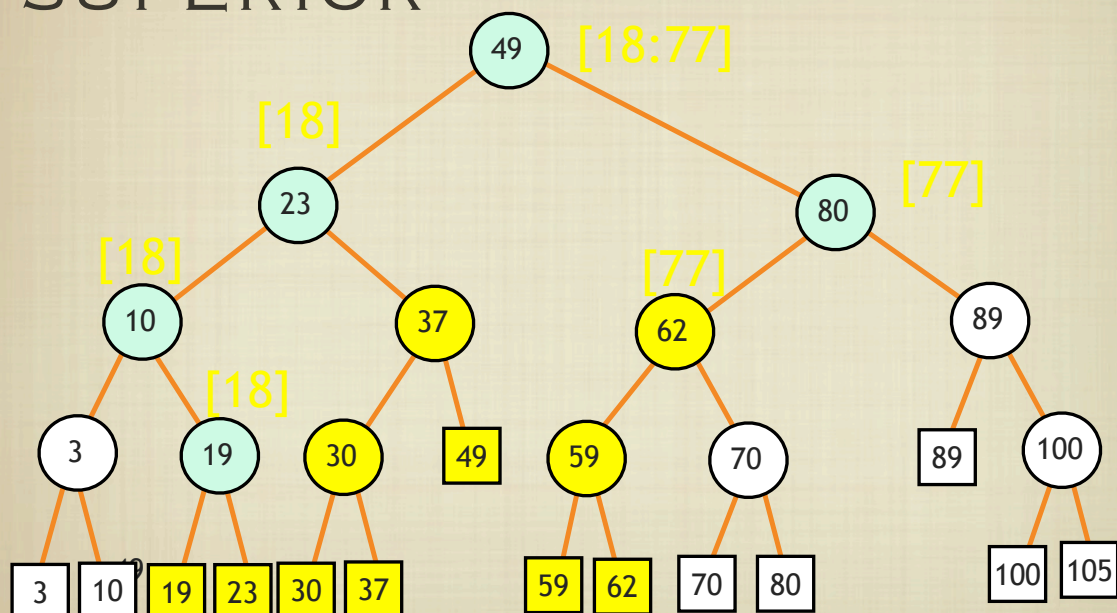
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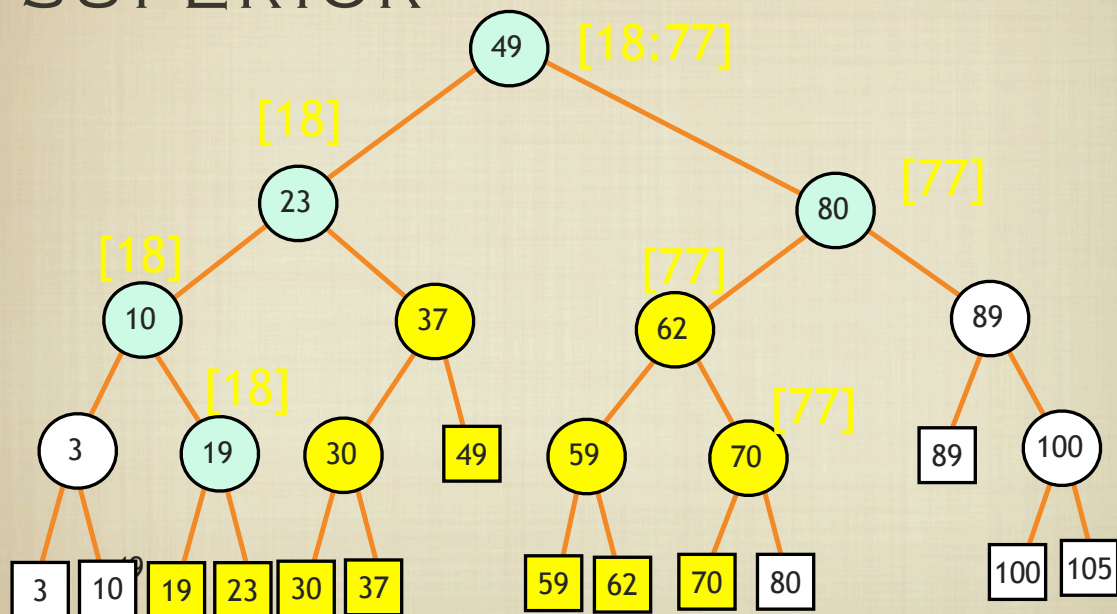
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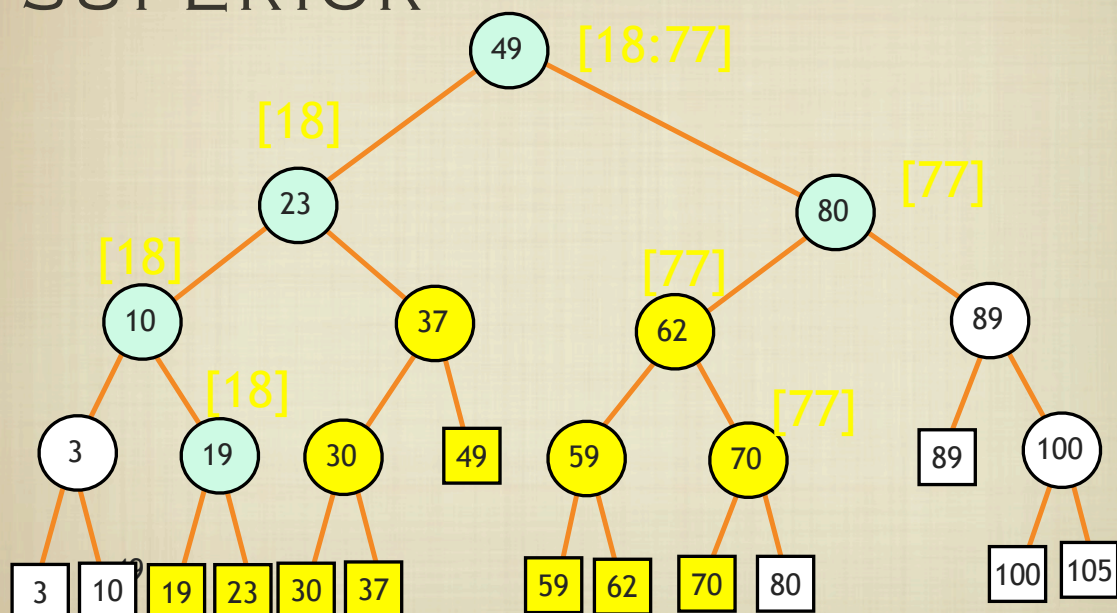
3. ENCONTRA LIMITE SUPERIOR



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ALGORITMO

ENCONTRANODOSEP

ENCONTRANODOSEP(T,xmin,xmax)

ENTRADA: T, valores min e max em x

SAIDA: nodo de separacao

1. $v = \text{root}(T)$
2. **WHILE** v nao e' folha e $(x_{\max} \leq xv \text{ OU } x_{\min} > xv)$
3. **DO IF** $(x_{\max} \leq xv)$
4. **THEN** $v = \text{left}(v)$
5. **ELSE** $v = \text{right}(v)$
6. **RETURN** v

ALGORITMO

BUSCARANGETREE1D(T,xmin,xmax)

ENTRADA: T, valores min e max em x

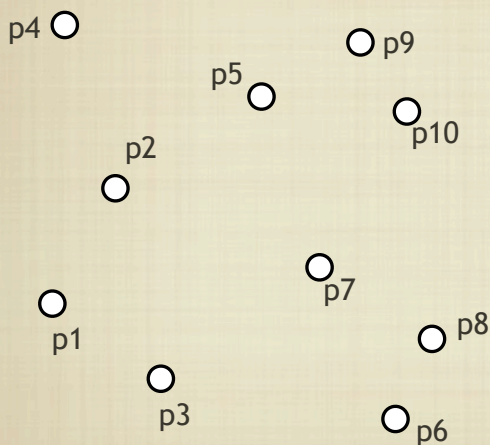
SAIDA: todos nodos no intervalo

1. $vsplit = \text{ENCONTRANODOSEP}(T, xmin, xmax)$
2. **IF** vsplit e' folha
3. **THEN** Verificar se ponto na folha deve ser reportado
4. **ELSE** //Percorrer arvore ate' xmin, reportar r-subtrees
5. $v = \text{left}(vsplit);$
6. **WHILE** v nao e' folha
7. **DO IF** $(x_{\min} \leq xv)$
8. **THEN** REPORTA_SUBARVORE(right(v))
9. $v = \text{left}(v)$
10. **ELSE** $v = \text{right}(v)$
11. // Verificar se ponto na folha deve ser reportado
12. // Da mesma maneira, percorrer arvore ate' xmax, reportar // subtrees a esquerda do caminho, e verificar se ponto na folha deve ser reportado

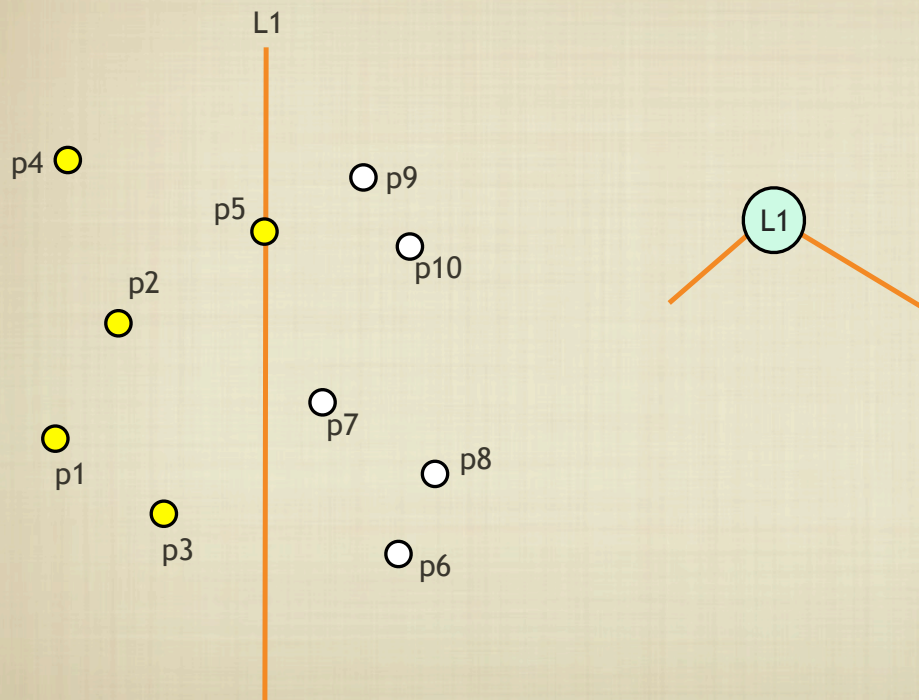
PERFORMANCE

- ARVORE BINARIA BALANCEADA: $O(N)$ MEMORIA
- CONSTRUCAO ARVORE: $O(N \log N)$
- CONSULTA ?
 - PIOR CASO: REPORTAR TODOS OS PONTOS
 - “OUTPUT-SENSITIVE”: PROPORCIONAL AO NUMERO DE VALORES REPORTADOS (K)
 - $O(\log N)$ CAMINHO MAXIMO, $O(1)$ EM CADA NODO
 - $O(K + \log N)$

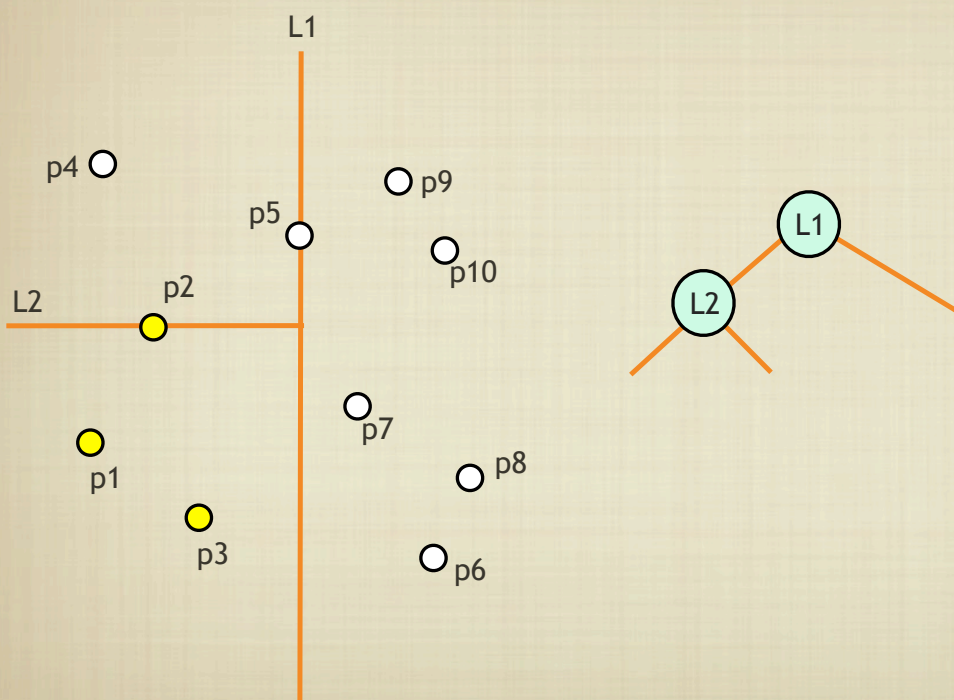
KD-TREES (2D PROBLEM)



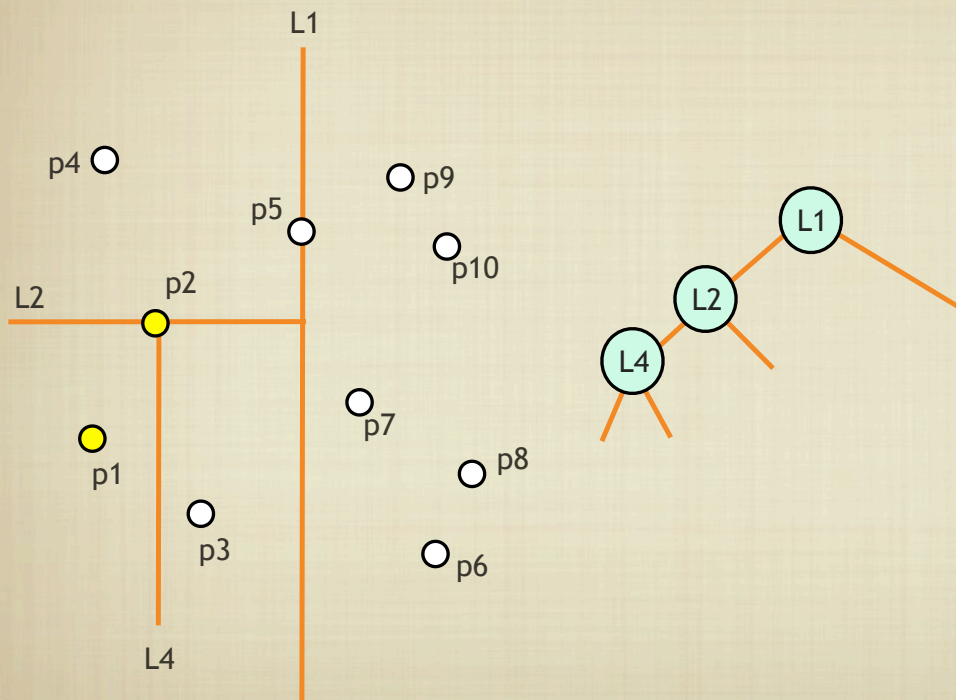
KD-TREES (2D PROBLEM)



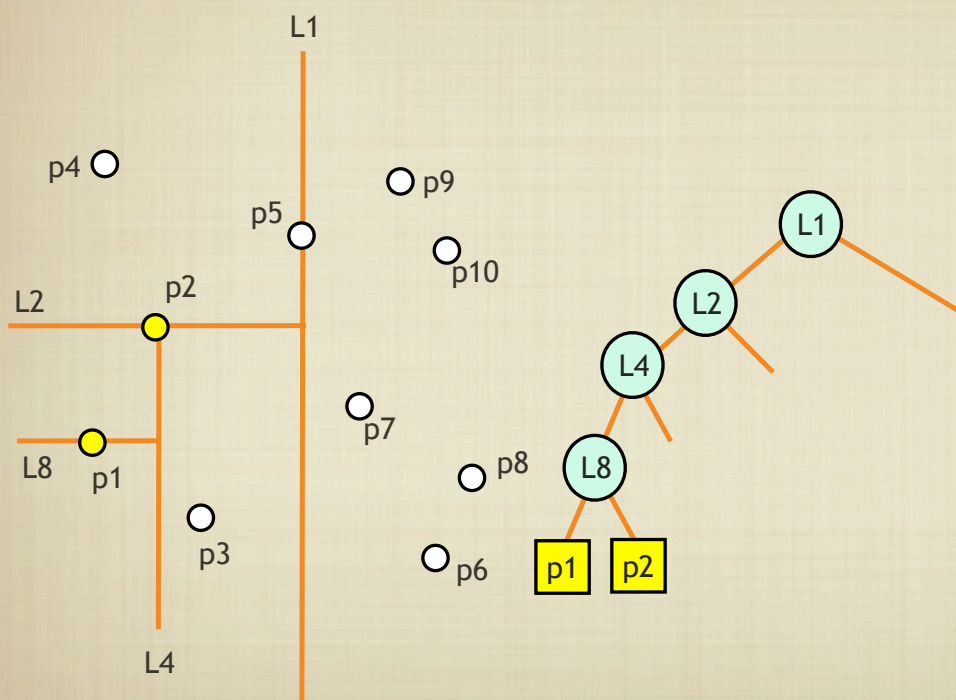
KD-TREES (2D PROBLEM)



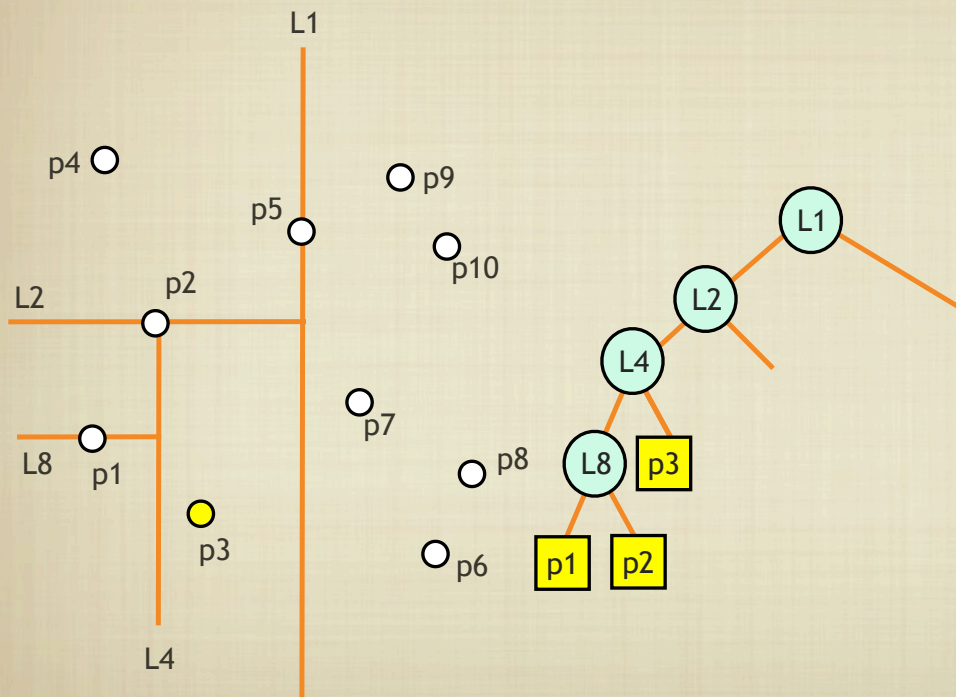
KD-TREES (2D PROBLEM)



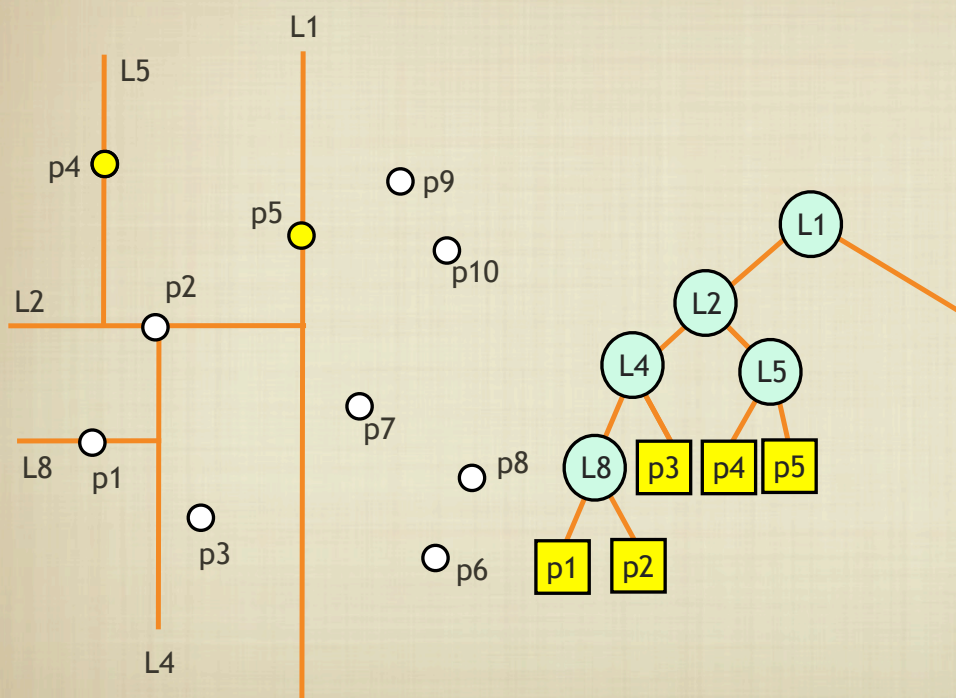
KD-TREES (2D PROBLEM)



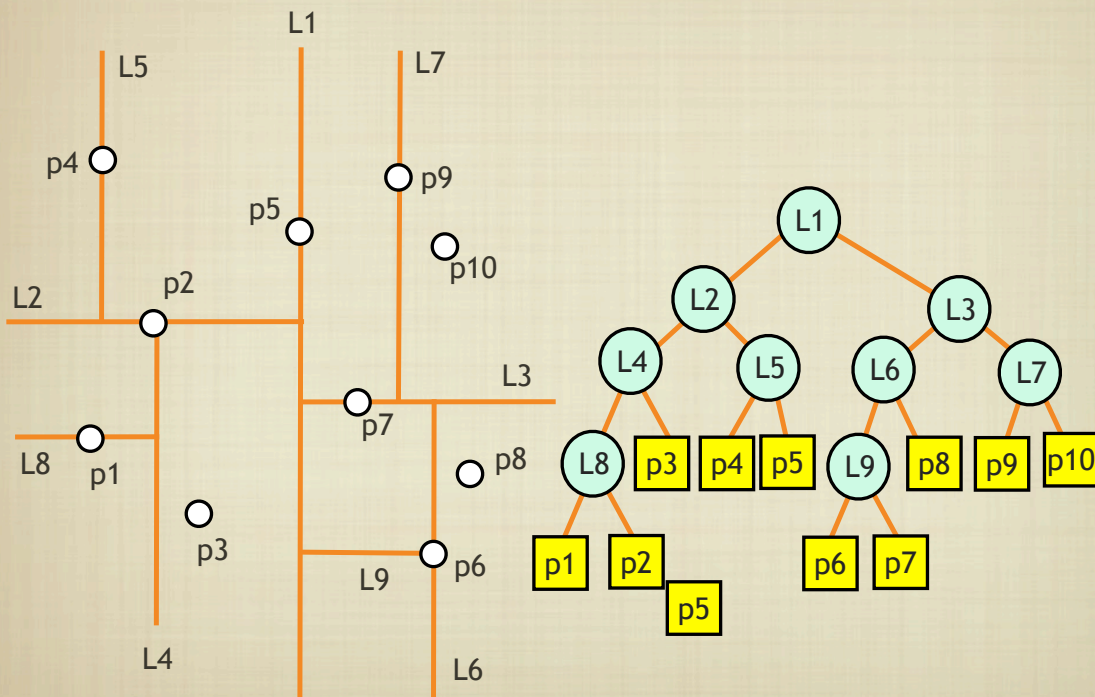
KD-TREES (2D PROBLEM)



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KD-TREES (2D PROBLEM)



ALGORITMO CONSTROI KDTREE

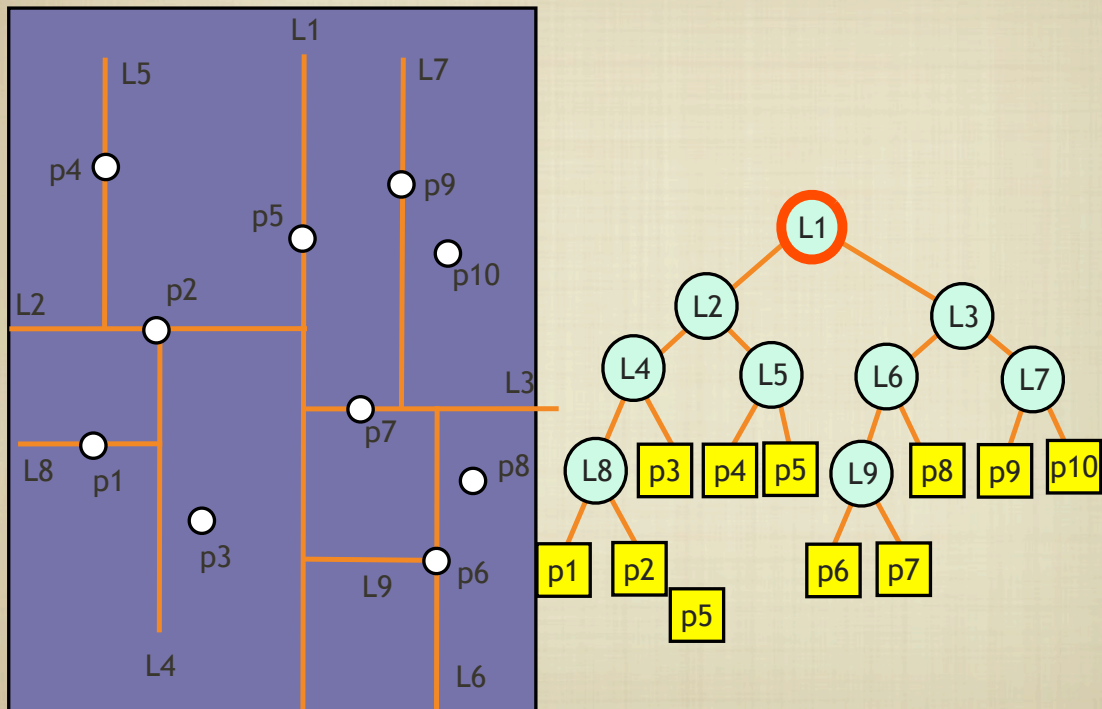
CONSTROI_KDTREE(P, profundidade)

ENTRADA: Conjunto de pontos P, profundidade corrente

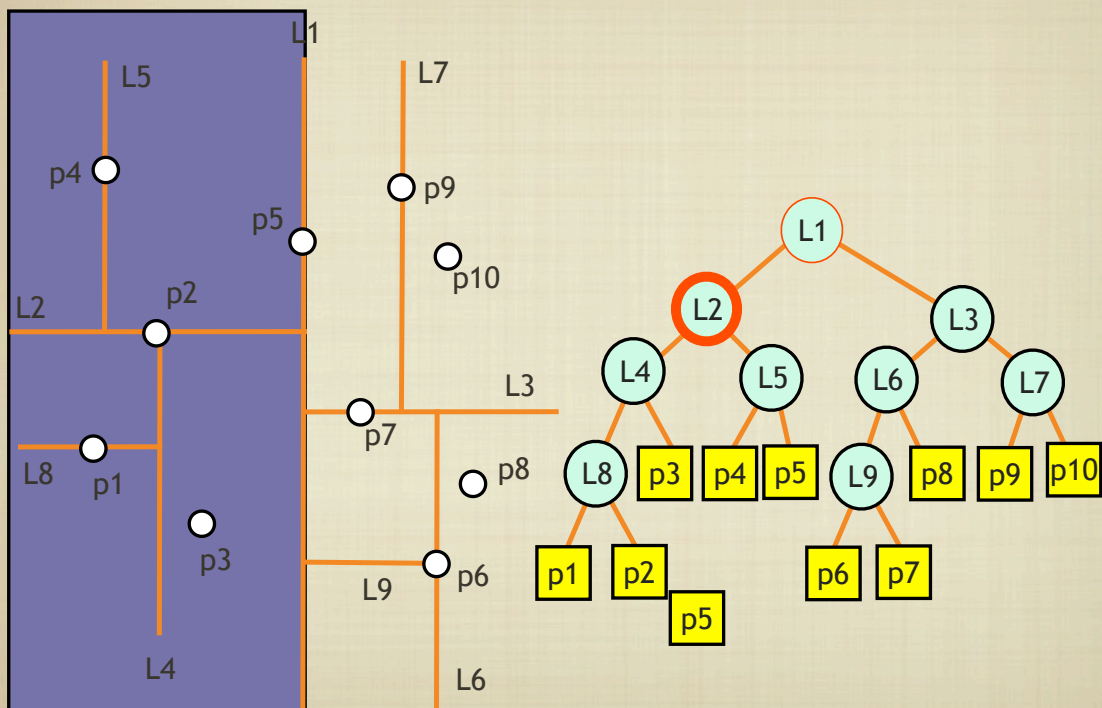
SAIDA: todos nodos no intervalo

1. IF P contem um ponto somente
2. THEN RETURN uma folha armazenando este ponto
3. ELSE IF profundidade e' par
4. THEN Particionar P em 2 conjuntos P1(e) e P2(d) com uma linha vertical L passando pela mediana dos pontos em P
5. ELSE Particionar P em 2 conjuntos P1(b) e P2(c) com uma linha vertical L passando pela mediana dos pontos em P
6. vleft = CONSTROI_KDTREE(P1, profundidade+1)
7. vright = CONSTROI_KDTREE(P2, profundidade+1)
8. Criar um nodo v armazenando L, atribuir vleft e vright como as subarvores deste nodo DO IF (xmin <= xv)
9. RETURN v

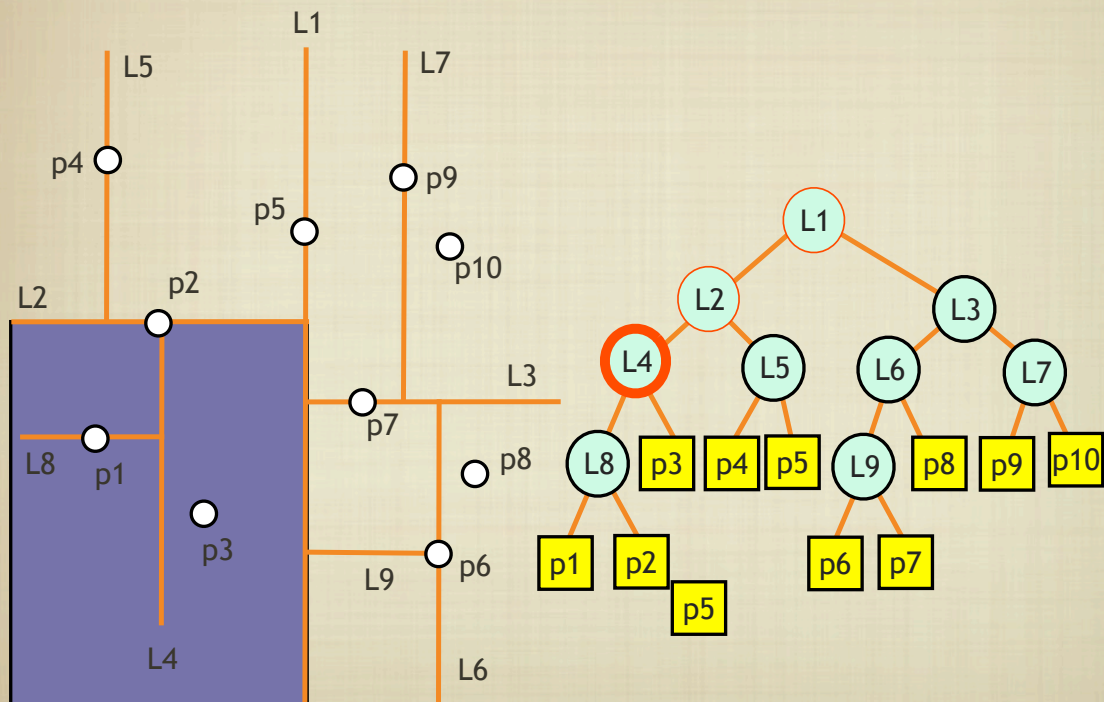
CORRESPONDENCIA NODOS X REGIONES



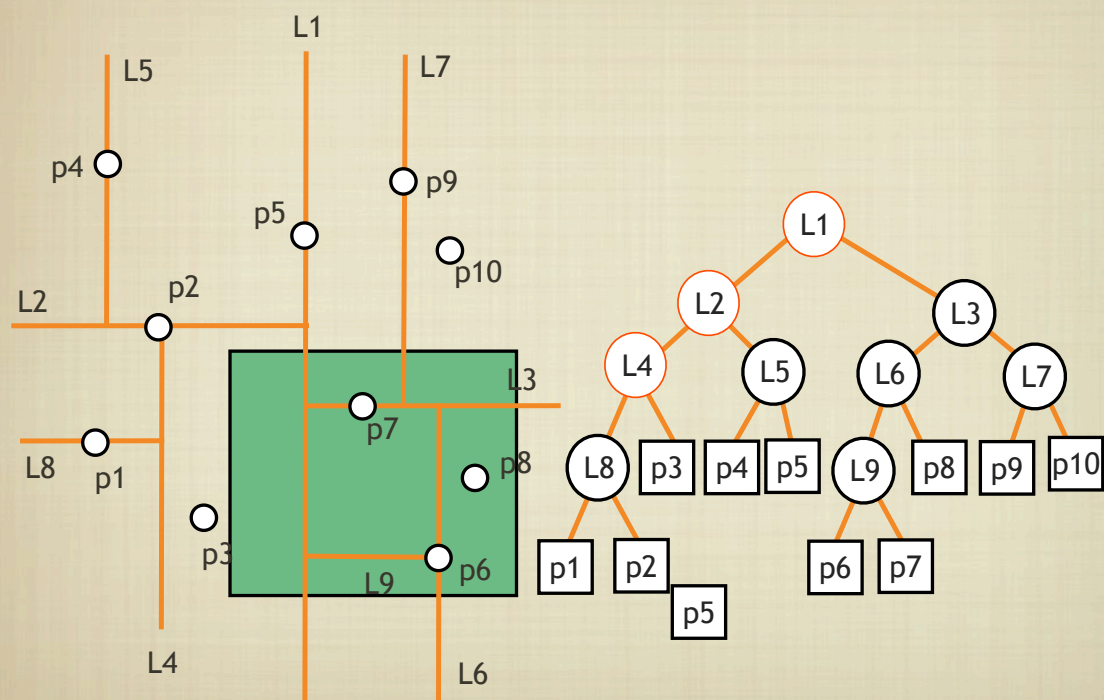
CORRESPONDENCIA NODOS X REGIONES



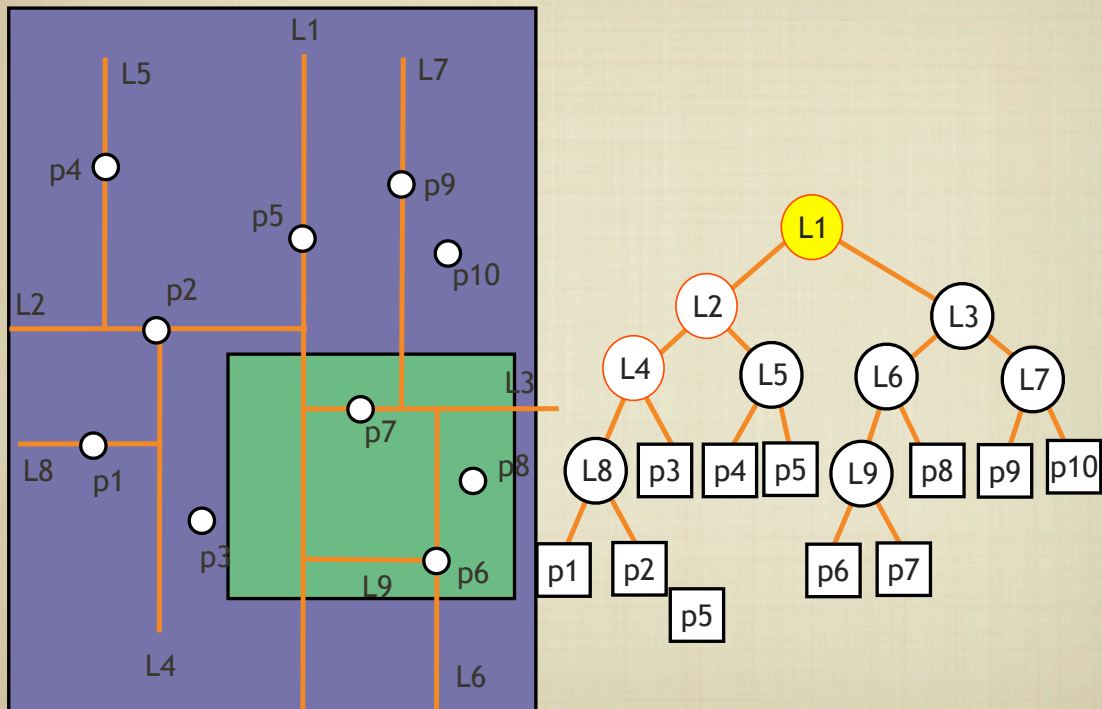
CORRESPONDENCIA NODOS X REGIOES



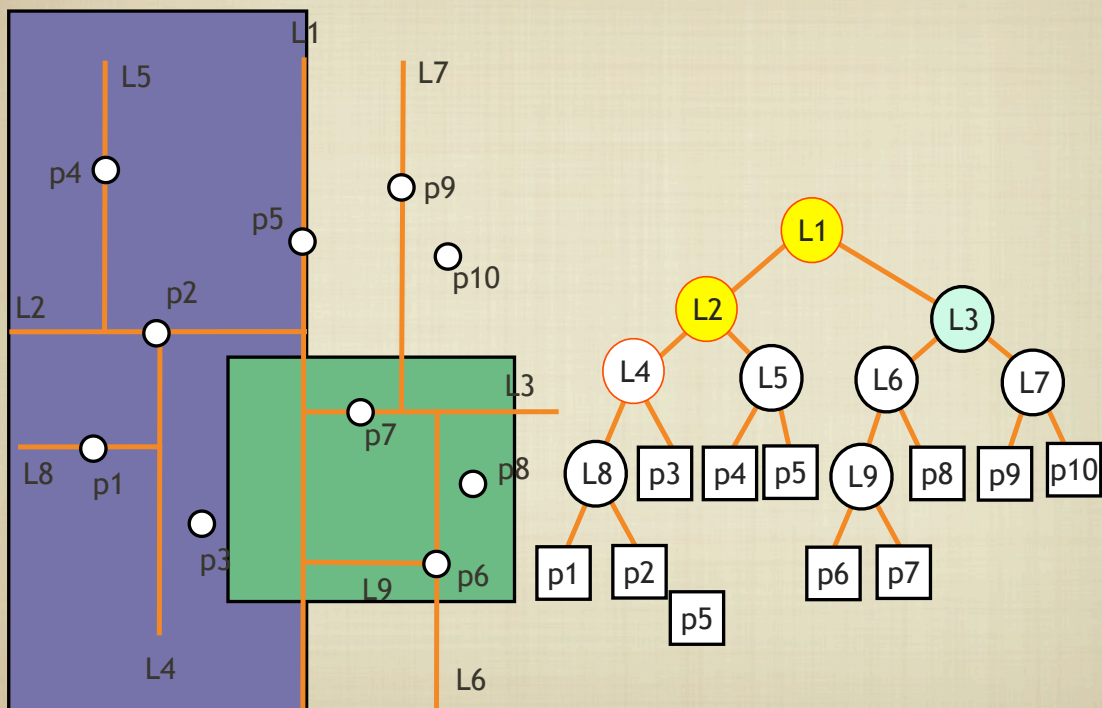
BUSCA EM KDTREES



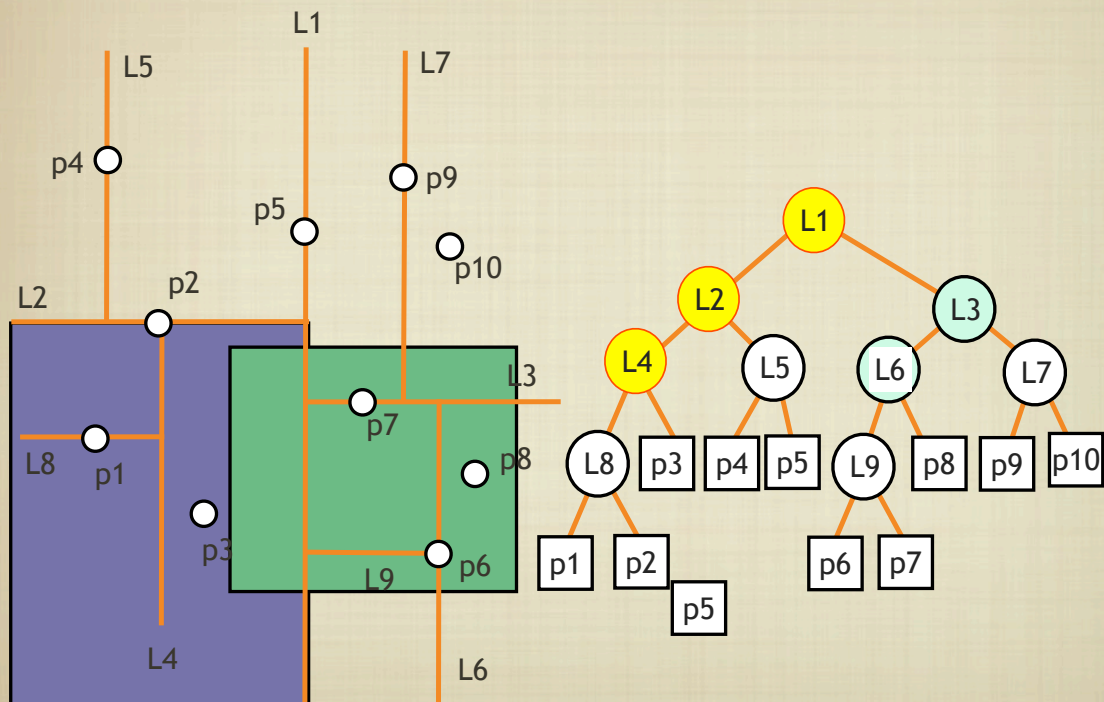
BUSCA EM KDTREES



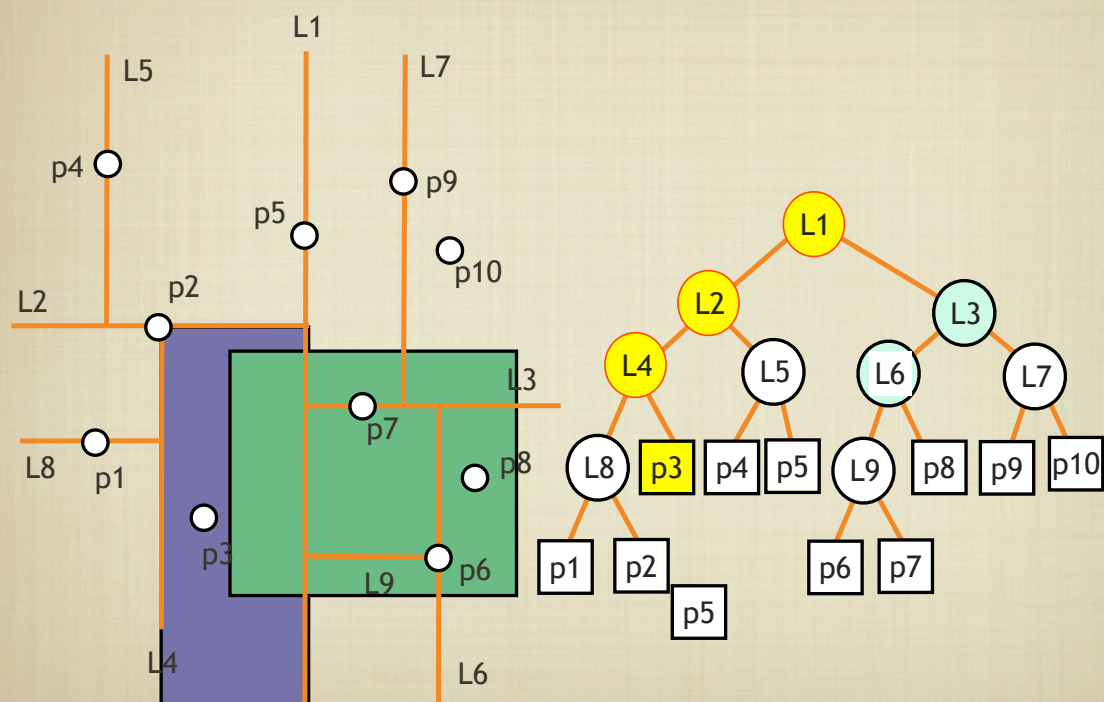
BUSCA EM KDTREES



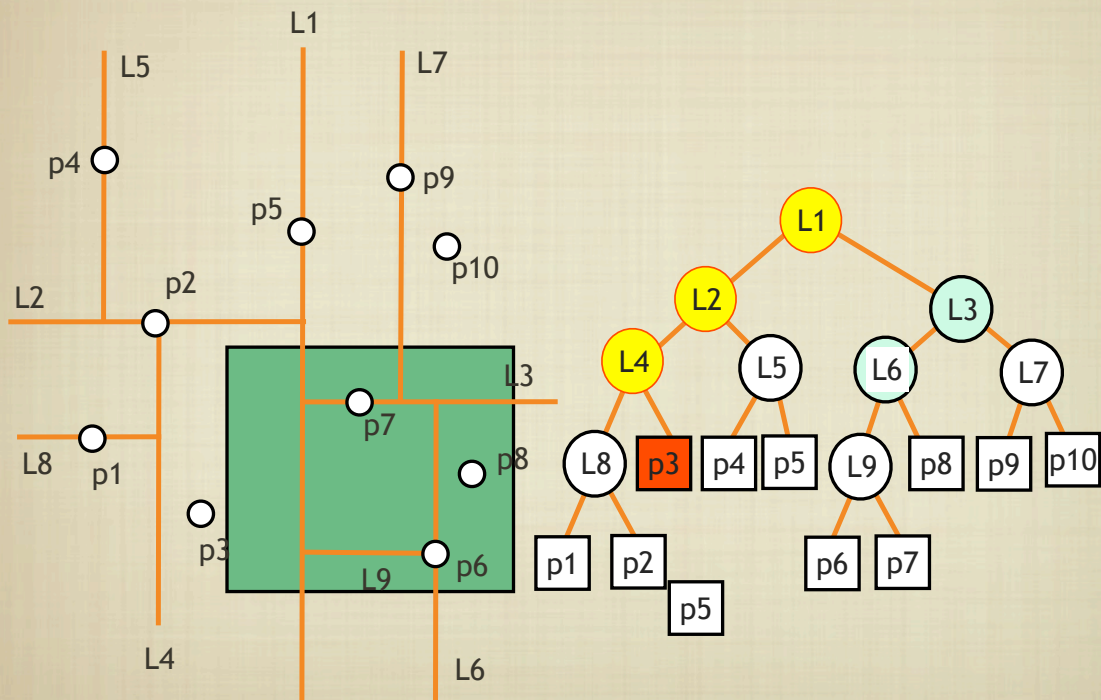
BUSCA EM KDTREES



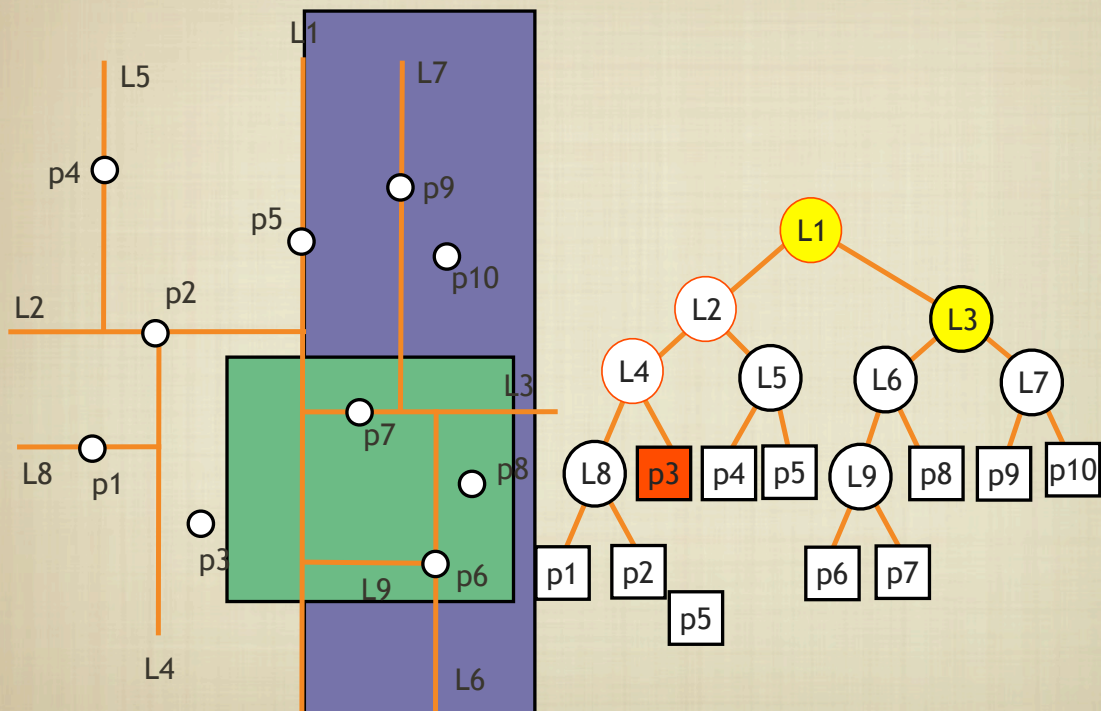
BUSCA EM KDTREES



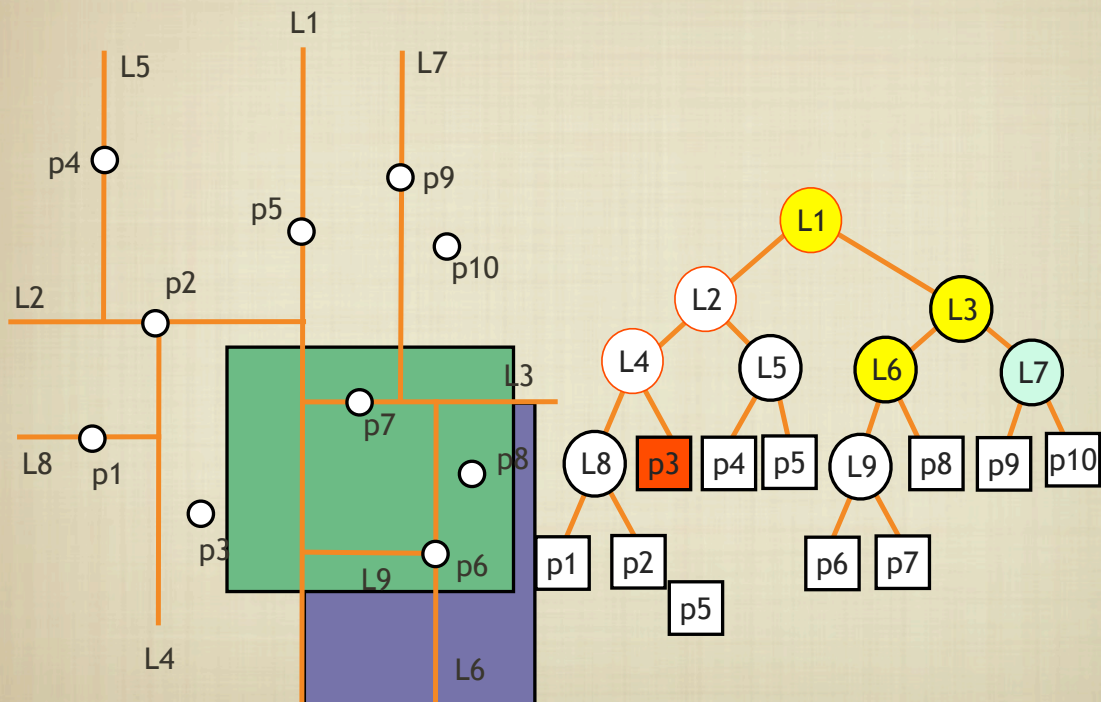
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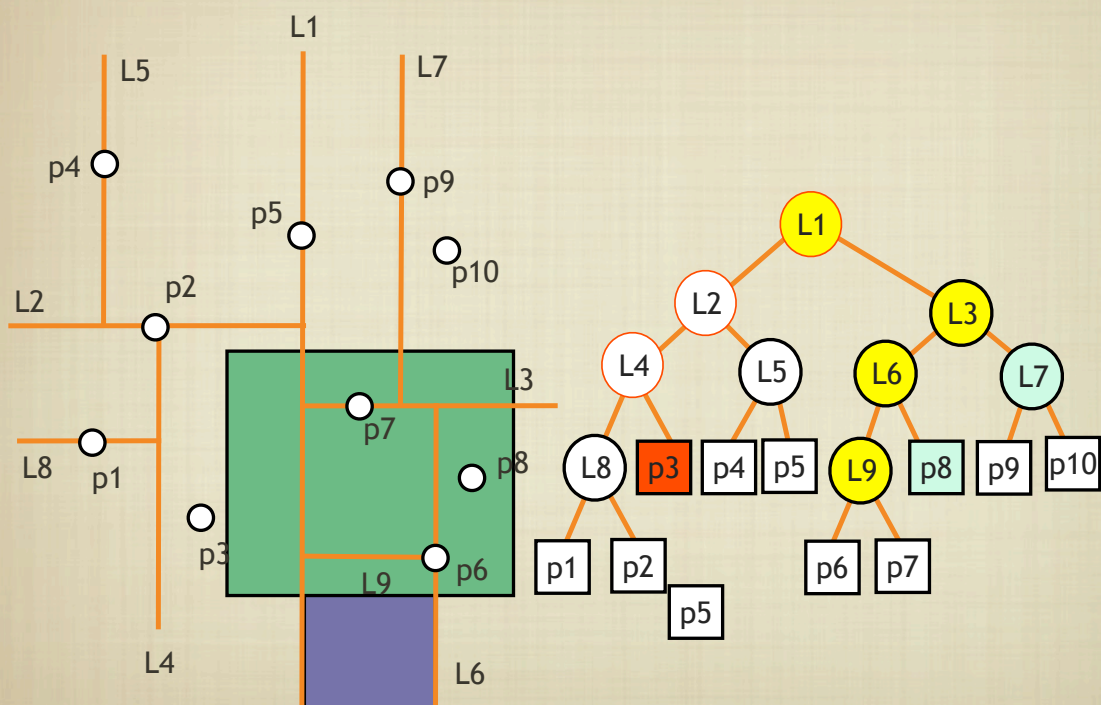
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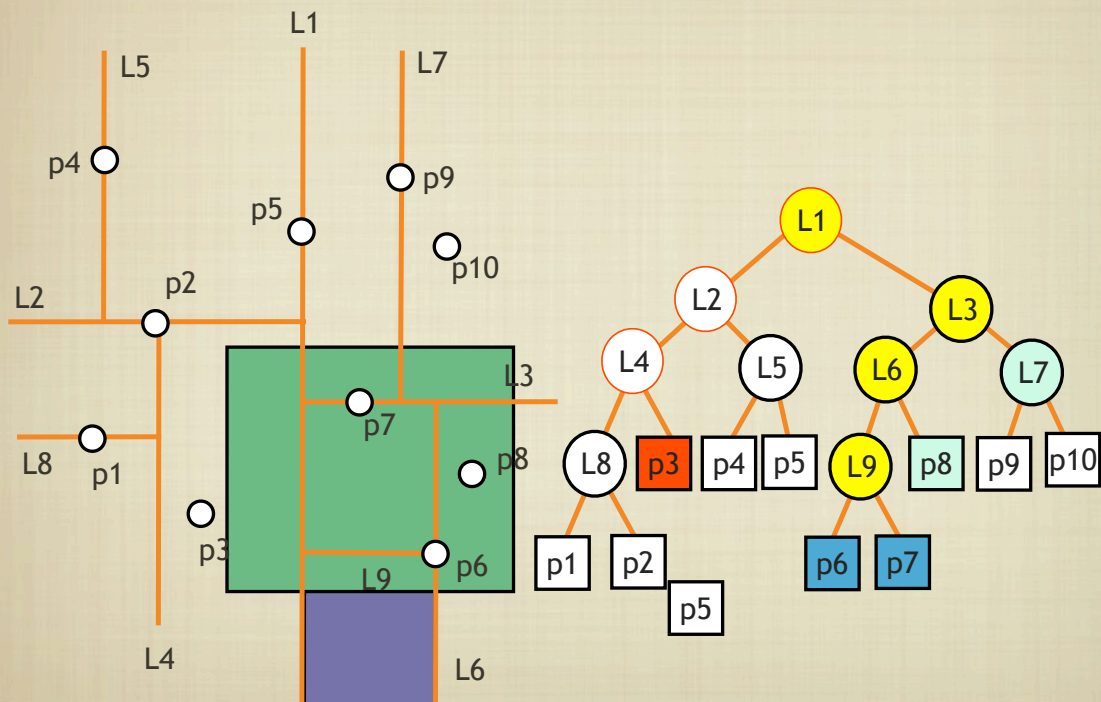
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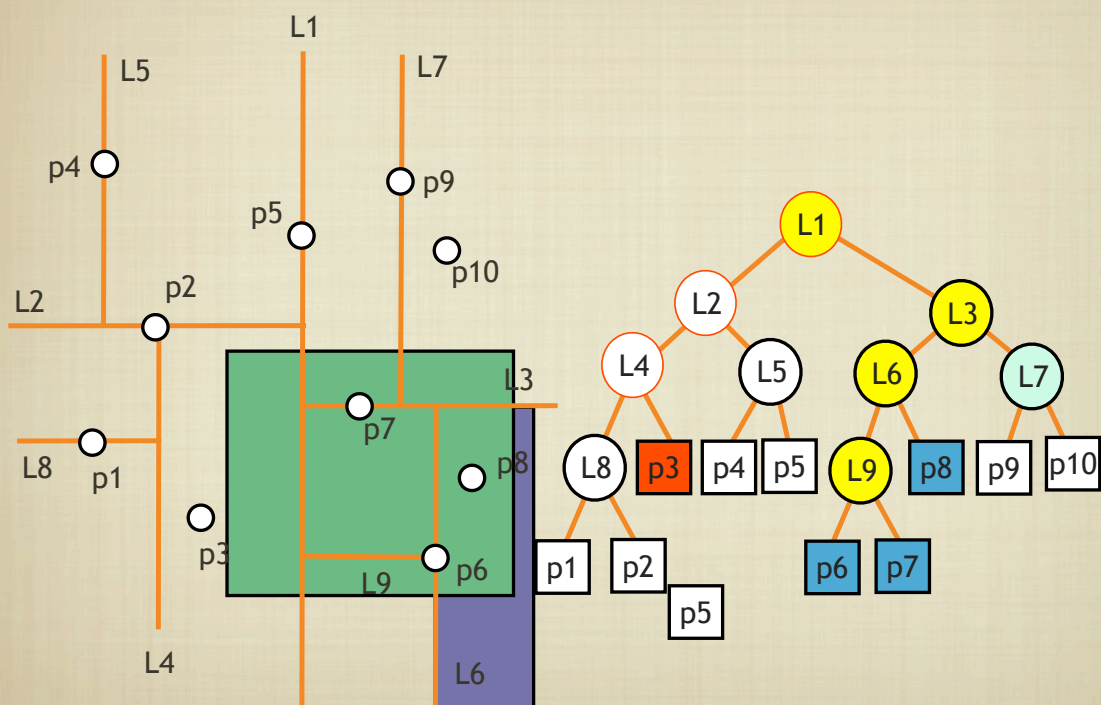
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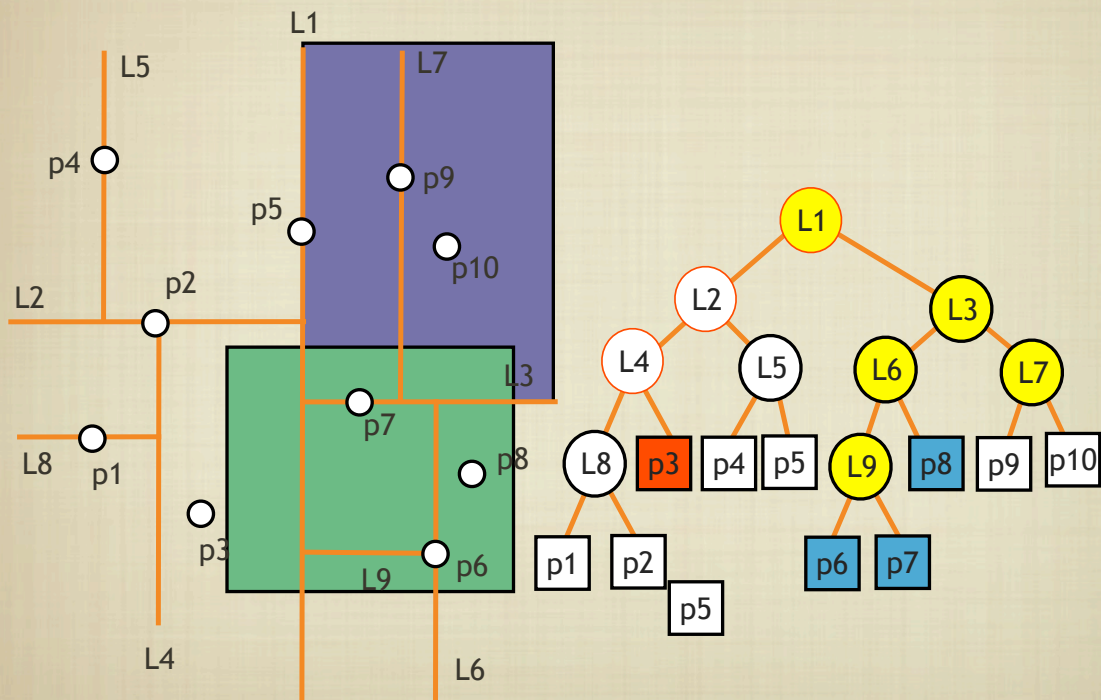
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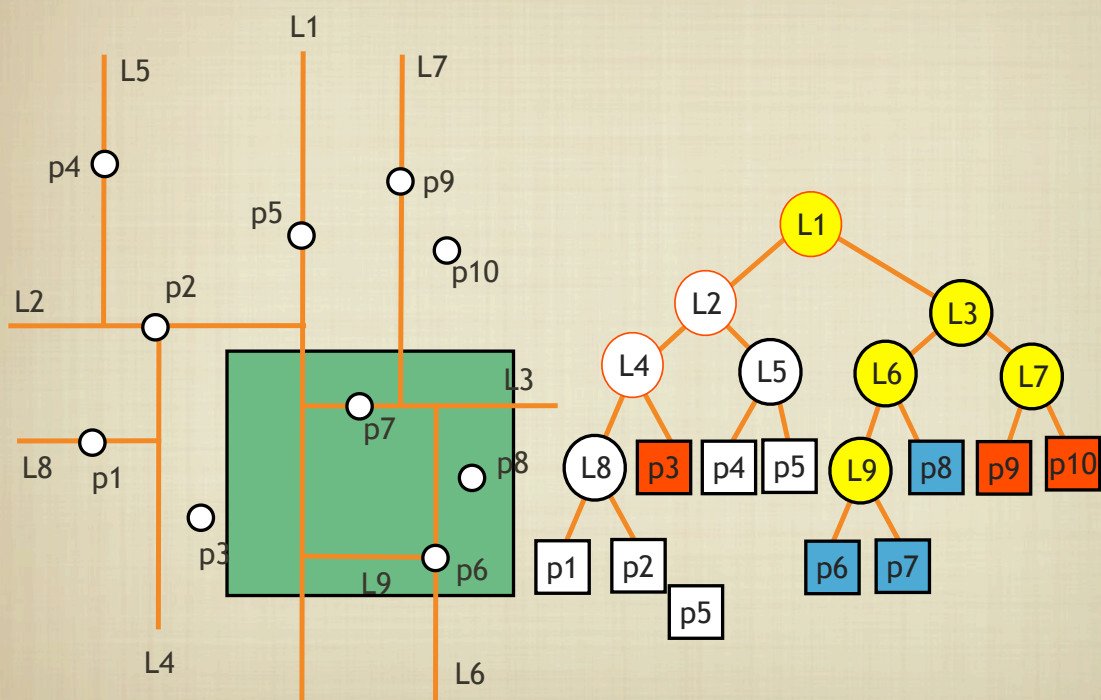
BUSCA EM KDTREES



BUSCA EM KDTREES



BUSCA EM KDTREES



ALGORITMO BUSCA_KDTREE

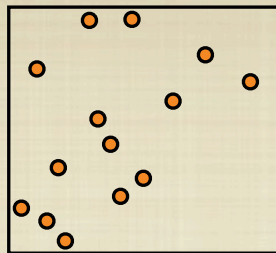
BUSCA_KDTREE(v , R)

ENTRADA: Raiz da kdtree e um intervalo 2D R

SAIDA: todas folhas contendo ponto no intervalo

1. IF v é uma folha
2. THEN reportar todos pontos em v que estão dentro de R
3. ELSE IF REGIAO(left(v)) está contida em R
4. THEN REPORTA_SUBARVORE(left(v))
5. ELSE IF REGIAO(left(v)) intersecta R
6. THEN BUSCA_KDTREE(left(v), R)
7. IF REGIAO(right(v)) está contida em R
8. THEN REPORTA_SUBARVORE(right(v))
9. ELSE IF REGIAO(right(v)) intersecta R
10. THEN BUSCA_KDTREE(right(v), R)

EXEMPLO



2 5 7 8 12 15 17 21 33 41 52 58 67 93
19 80 10 37 3 99 62 49 30 95 23 69 89 70

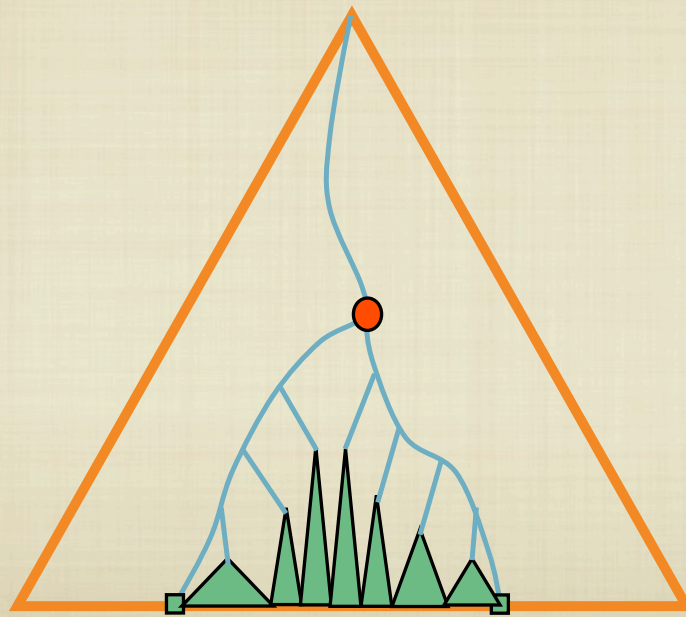
PERFORMANCE

- ARVORE BINARIA: $O(N)$ MEMORIA
- CONSTRUCAO ARVORE: $O(N \log N)$
- CONSULTA ?
 - $O(K + \text{SQROOT}(N))$
 - $Q(N) = [O(1) \text{ SE } N = 1, 2 + 2Q(N/4)]$

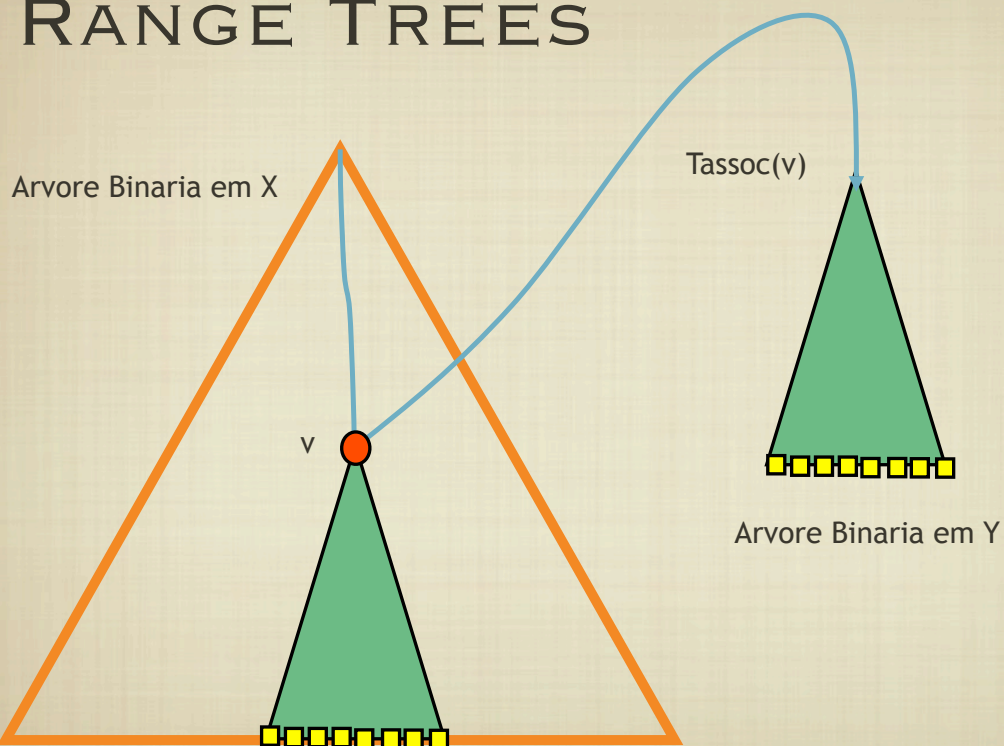
RANGE TREES

- **OBS: CONSULTA 2D CORRESPONDE A 2 CONSULTAS 1D (EM X, E DEPOIS EM Y)**
- **ESTRATEGIA $[X_{\min}:X_{\max}] \times [Y_{\min}:Y_{\max}]$**
 - CONSTRUIR UMA ARVORE BINARIA T_X EM X
 - ENCONTRAR OS PONTOS CUJAS COORDENADAS X ESTEJAM ENTRE X_{\min} E X_{\max} EM T_X
 - USAR ALGORITMO DESCRITO PRIMEIRO NA AULA
 - CONSTRUIR UMA ARVORE BINARIA T_Y COM OS PONTOS ENCONTRADOS EM Y
 - ENCONTRAR OS PONTOS CUJAS COORDENADAS Y ESTEJAM ENTRE Y_{\min} E Y_{\max}

RANGE TREES



RANGE TREES



ALGORITMO CONSTROI_RANGETREE_2D

CONSTROI_RANGETREE_2D(P)

ENTRADA: Conjunto de ponto P no plano

SAIDA: Raiz de uma range tree 2D

1. Constroi a arvore associada: Criar uma arvore binaria Tassoc no conjunto de coordenadas y dos pontos em P. Armazenar nas folhas nao a coordenada y, mas os pontos em si
2. **IF** P contem um ponto
3. **THEN** Criar uma folha v contendo a coord. x e a arvore associada
4. **ELSE** Particionar P em dois conjuntos P1(l) e P2(l) pela mediana da coordenada x.
 5. vleft = CONSTROI_RANGETREE_2D(P1)
 6. vright = CONSTROI_RANGETREE_2D(P2)
 7. Criar um nodo v contendo a coordenada x da mediana, as folhas esquerda e direita iguais a vleft e vright, e a arvore associada
8. **RETURN** v

ALGORITMO

BUSCARANGETREE2D(T,[xmin,xmax]x[ymin,ymax])

ENTRADA: Range tree 2D, intervalo 2D, **SAIDA:** Pontos na range tree dentro do intervalo

1. vsplit = ENCONTRANODOSEP(T, xmin, xmax)
2. **IF** vsplit e' folha
3. **THEN** Verificar se ponto na folha deve ser reportado
4. **ELSE** //Percorrer arvore ate' xmin, chamar BUSCARANGETREE1D
// com as r-subtrees
5. v = left(vsplit);
6. **WHILE** v nao e' folha
7. **DO IF** (xmin <= xv)
8. **THEN** BUSCARANGETREE1D(TASSOC(right(v)), [ymin,ymax])
9. v = left(v)
10. **ELSE** v = right(v)
11. // Verificar se ponto na folha deve ser reportado
12. // Percorrer arvore ate' xmax, chamar BUSCARANGETREE1D , e verificar se ponto na folha deve ser reportado

PERFORMANCE

- ARVORE BINARIA * LOGN: $O(N \log N)$ MEMORIA
- CONSTRUCAO RANGE TREE: $O(N \log N)$
 - REQUER ORDENACAO DOS PONTOS EM Y E EM X
- CONSULTA ?
 - $O(K + \log^2(N))$

CASCADEAMENTO FRACIONÁRIO

A1	3	10	19	23	30	37	59	62	70	80	100	105
----	---	----	----	----	----	----	----	----	----	----	-----	-----

A2	10	19	30	62	70	80	100
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- A2 e' um subconjunto de A1
- 2 buscas

CASCADEAMENTO FRACIONÁRIO

A1

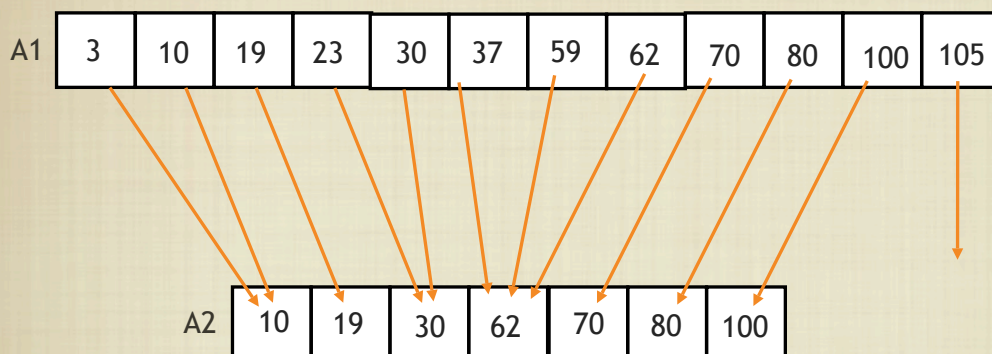
3	10	19	23	30	37	59	62	70	80	100	105
---	----	----	----	----	----	----	----	----	----	-----	-----

A2

10	19	30	62	70	80	100
----	----	----	----	----	----	-----

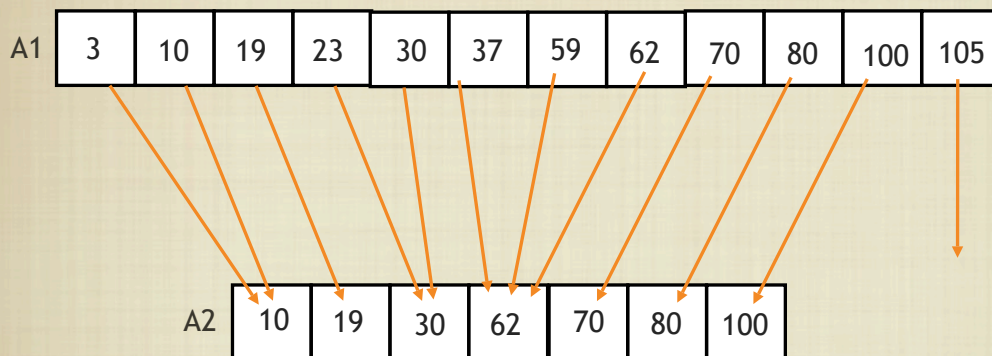
Colocar um pointer de cada entrada a1 em A1 para a entrada em A2 com a menor chave **maior ou igual** a a1, ponteiro nulo caso contrario

CASCADEAMENTO FRACIONÁRIO

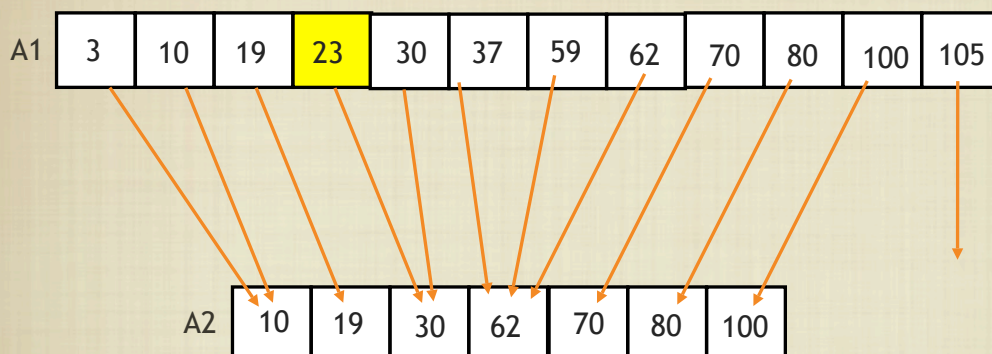


Colocar um pointer de cada entrada a1 em A1 para a entrada em A2 com a menor chave **maior ou igual** a a1, ponteiro nulo caso contrario

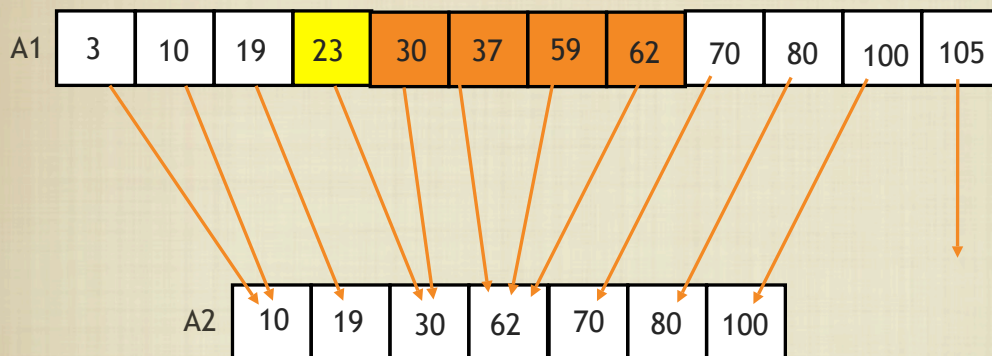
CASCADEAMENTO FRACIONÁRIO



CASCADEAMENTO FRACIONÁRIO

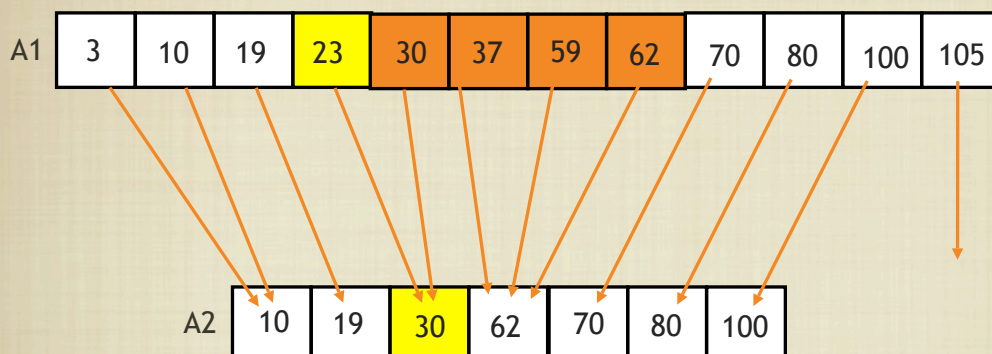


CASCADEAMENTO FRACIONÁRIO



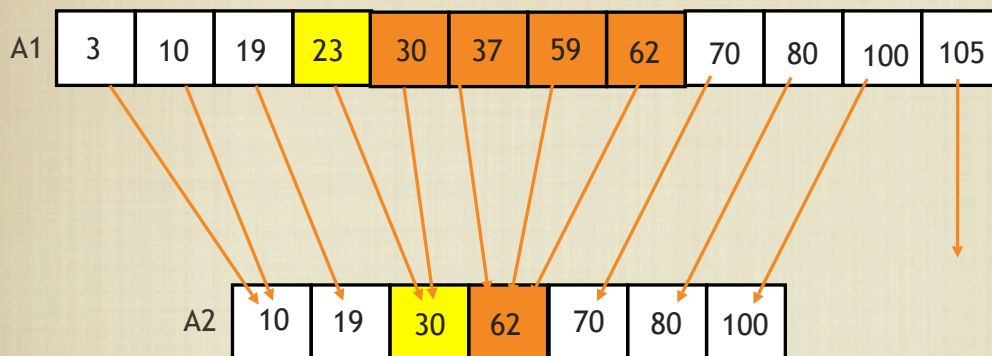
Exemplo: [20:65]

CASCADEAMENTO FRACIONÁRIO

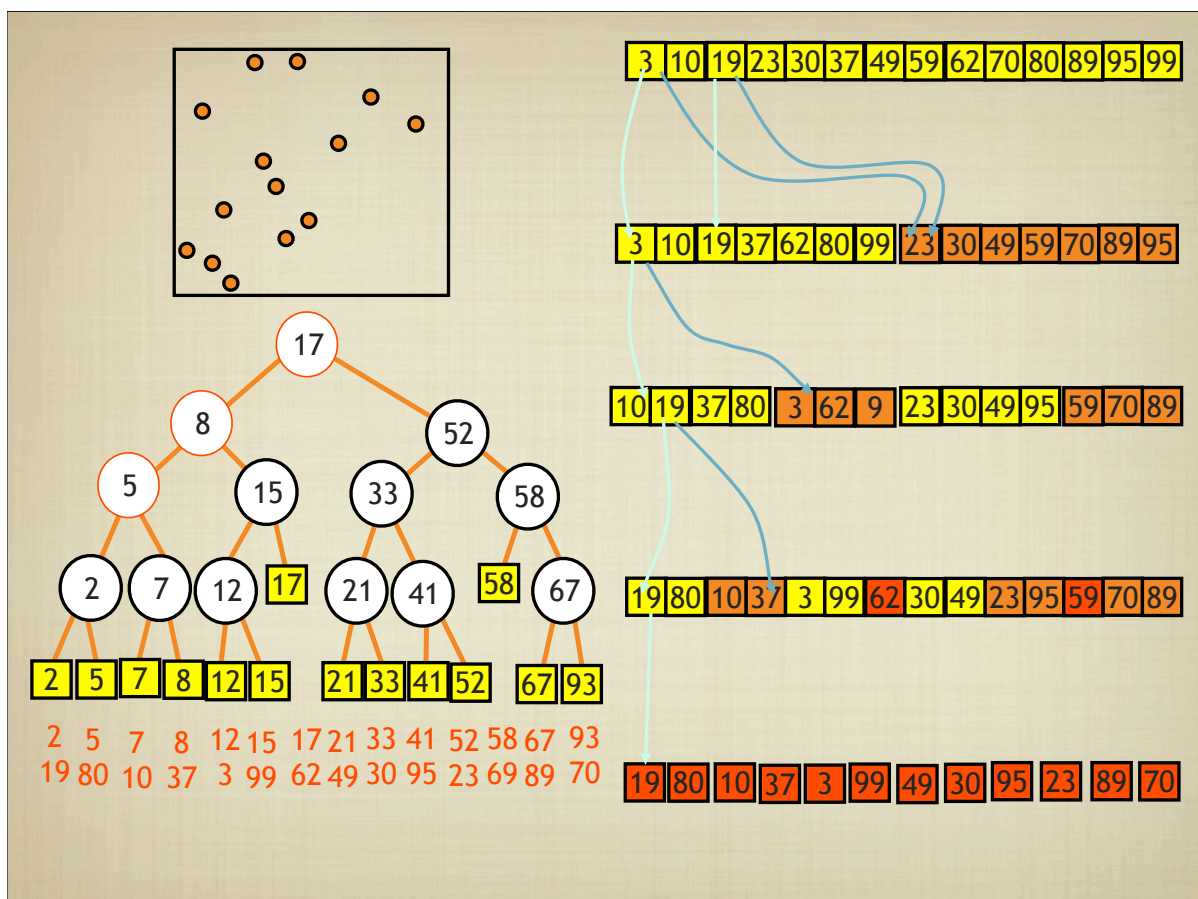


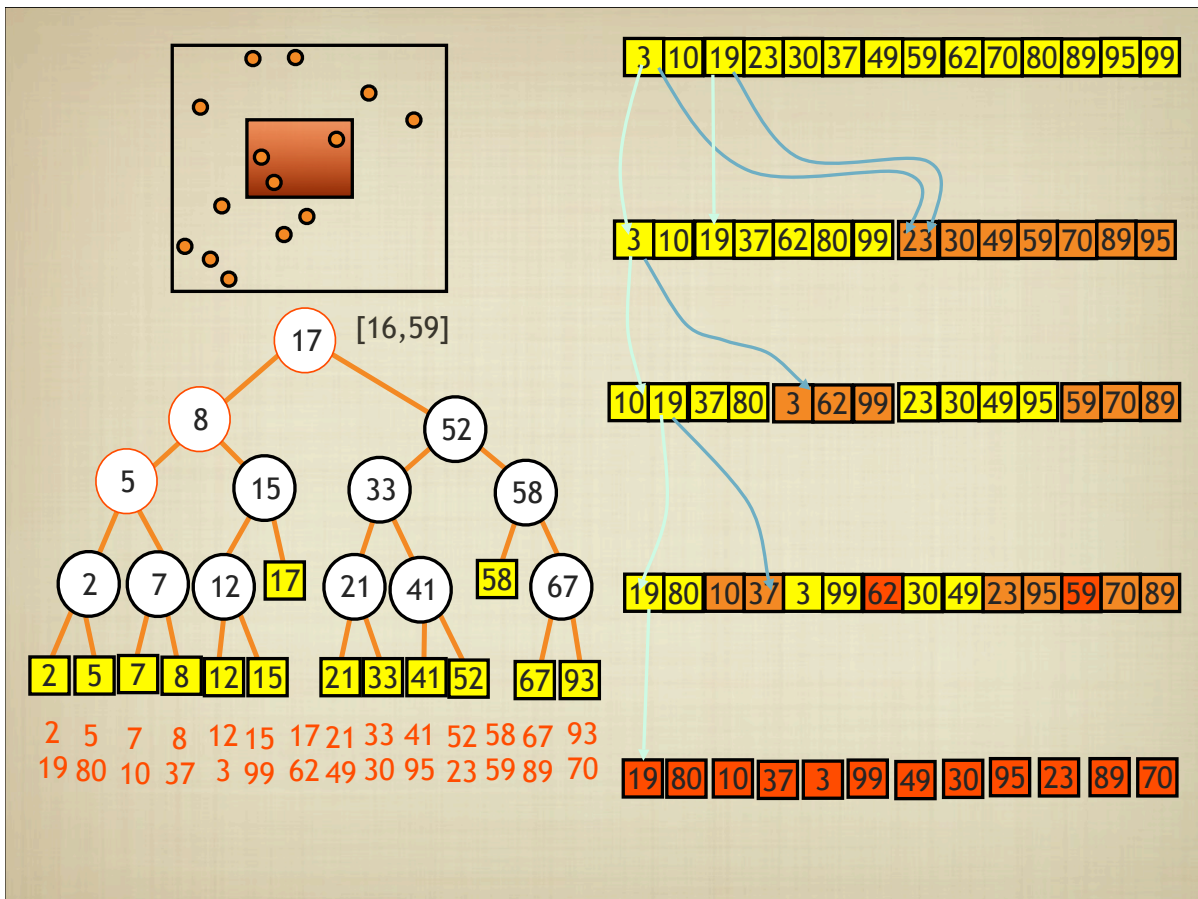
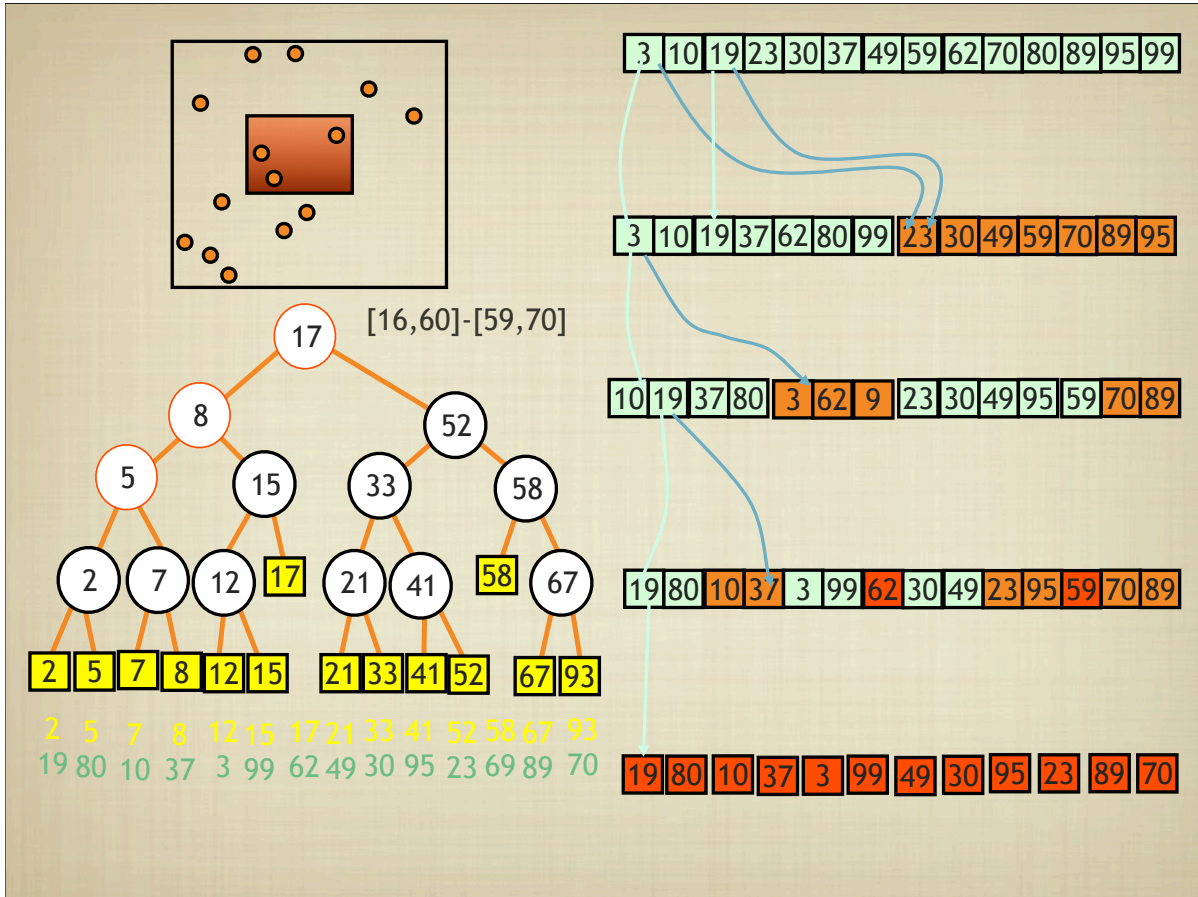
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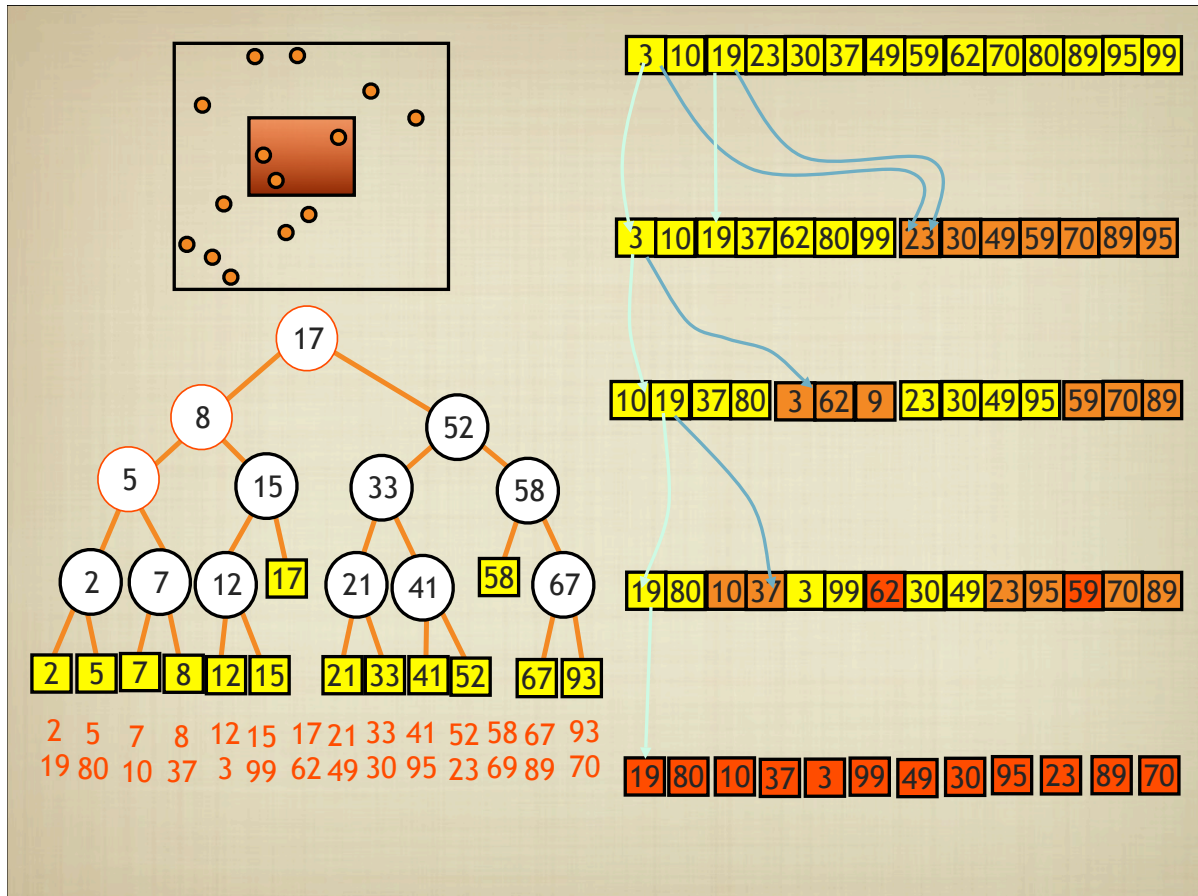
CASCADEAMENTO FRACIONÁRIO



Exemplo: [20:65]







CASCADEAMENTO FRACIONÁRIO

