#### Unit Conversion

$$1 \text{ ft} = 12 \text{ in}$$
  
 $1 \text{ mile} = 5280 \text{ ft}$ 

$$1 \text{ m} = 3.281 \text{ ft}$$
  
 $1 \text{ kip} = 1000 \text{ lb}$ 

$$1 \text{ slug} = 14.59 \text{ kg}$$
  
 $1 \text{ lb}_f = 4.448 \text{ N}$ 

$$g = 9.81 \text{ m/s}^2$$
  
= 32.2 ft/s<sup>2</sup>

$$1 \text{ yd} = 3 \text{ ft}$$

$$1 \text{ ton} = 2000 \text{ lb}$$

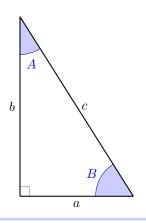
$$1 \text{ kg} = 2.205 \text{ lb}_m$$

# Right Triangles

$$\sin A = \frac{a}{c} \quad \cos A = \frac{b}{c} \quad \tan A = \frac{a}{b}$$

$$\sin B = \frac{b}{c} \quad \cos B = \frac{a}{c} \quad \tan B = \frac{b}{a}$$

$$a^2 + b^2 = c^2$$



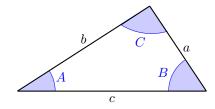
## **Oblique Triangles**

The law of cosines:

$$a^2 = b^2 + c^2 - 2bc(\cos A)$$

$$b^2 = a^2 + c^2 - 2ac(\cos B)$$

$$c^2 = a^2 + b^2 - 2ab(\cos C)$$



The law of sines:

$$\frac{a}{\sin A} = \frac{b}{\sin B} = \frac{c}{\sin C}$$

# Resultants and Equilibrium

Resultant of parallel force systems:

$$R = \sum F_y = F_1 + F_2 + \dots + F_n \qquad \overline{x} = \frac{\sum M}{R}$$

Three laws of equilibrium

$$\sum F_x = 0 \qquad \sum F_y = 0 \qquad \sum M = 0$$

#### **Friction**

Maximum available frictional force:

$$F = \mu_s N$$

For flat belts and ropes:

$$T_L = T_S e^{\mu\beta}$$
 or  $\ln T_L - \ln T_S = \mu\beta$ 

$$Torque = (T_L - T_s) r$$

For V-belts ( $\phi \equiv 1/2 \times$  groove angle):

$$T_L = T_S e^{\mu \beta / \sin \phi}$$
 or  $\ln T_L - \ln T_S = \frac{\mu \beta}{\sin \phi}$ 

Square-threaded screws:

Lead angle : 
$$\theta = \tan^{-1} \frac{L}{2\pi r} = \tan^{-1} \frac{p}{2\pi r}$$
 Jackscrew : Qa = Pr

### Centroids and Centers of Gravity

Location of center of gravity:

$$\overline{x} = \frac{\sum wx}{W}$$
 or  $\frac{\sum wx}{\sum w}$ 

$$\overline{x} = \frac{\sum ax}{A}$$
 or  $\frac{\sum ax}{\sum a}$ 

$$\overline{y} = \frac{\sum wy}{W}$$
 or  $\frac{\sum wy}{\sum w}$ 

$$\overline{y} = \frac{\sum ay}{A}$$
 or  $\frac{\sum ay}{\sum a}$ 

#### Area Moments of Inertia

Moment of inertia:

$$I_x = \sum ay^2 \qquad I_y = \sum ax^2$$

Parallel axis theorem or transfer formula:

$$I = I_o + ad^2$$

Moment of inertia of composite area:

$$I = \sum \left( I_o + ad^2 \right)$$

Radius of gyration:

$$r = \sqrt{\frac{I}{A}}$$

Polar moment of inertia:

$$J = I_x + I_y$$