

Sparse FGLM using the block Wiedemann algorithm

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Introduction

- Gröbner basis of an ideal is essential in solving systems of polynomials
- Orderings such as degree reverse lexicographical ordering (*degrevlex*) make computing the Gröbner basis faster
- Orderings such as lexicographical order (*lex*) make finding solution coordinates easier
- Compute first for degrevlex ordering and convert to lex ordering
- Sparse FGLM algorithm of [1] computes lex basis of a radical ideal I when I is in shape position (although they also provide an algorithm for non-radical ideals)
- $I \subset \mathbb{K}[x_1, \dots, x_n]$ is in *shape position* if its Gröbner basis has the form $(x_1 - R_1(x_n), \dots, x_{n-1} - R_{n-1}(x_n), R(x_n))$
- Difficult to parallelize

Main Problem

Input:

- Zero-dimensional ideal $I \subset \mathbb{K}[x_1, \dots, x_n]$ by means of a monomial basis $\mathbb{B} \subset Q$, $Q = \mathbb{K}[x_1, \dots, x_n]/I$
- Multiplication matrices $T_1, \dots, T_n \in \mathbb{K}^{D \times D}$ of x_1, \dots, x_n , with $D = \dim_{\mathbb{K}}(Q)$

Output:

- Lex Gröbner basis of \sqrt{I}

Block Sparse FGLM

- Inspired by Coppersmith's block Wiedemann Algorithm [3]
- Key idea:** Compute sequences of small matrices that require less terms than linear sequences

Algorithm

- Choose $U, V \in \mathbb{K}^{D \times m}$, where m is the number of threads supported
- Compute $s = (UT_n^i V)_{0 \leq i < \frac{2D}{M}}$, $S = \text{MatrixBerlekampMassey}(s)$, and $N = S \sum s^{(i)} / x^{i+1}$
- Find the Smith form of S , $D = ASB$ with invariant factors I_1, \dots, I_D . Set $\tilde{u} = \begin{bmatrix} I_D b_1 & I_D b_2 & \dots & I_D b_{D-1} & b_D \end{bmatrix} A$, where b_i is the i^{th} entry of the last row of B
- Set n^* to be the $(m, 1)$ -th entry of $\tilde{u}N$ and R_n as I_D written in x_n
- For $j = 1 \dots n - 1$:
 - Compute $s_j = (UT_n^i T_j V)_{0 \leq i < \frac{D}{M}}$ and $N_j = S \sum s_j^{(i)} / x^{i+1}$
 - Set $n_j = \tilde{u}N_j$ and R_j as $n_j / n^* \bmod R_n$ written in x_n
- Return $(x_1 - R_1, \dots, x_{n-1} - R_{n-1}, R_n)$

- Analysis for Coppersmith's algorithm has been provided by [Kaltofen '95], [Villard '97], [Kaltofen, Villard '04], [Kaltofen, Yuhász '06]

Example

We will demonstrate our new algorithm by running it on $I = \langle f_1, f_2, f_3 \rangle \subset \mathbb{K}[x_1, x_2, x_3]$,

$$\begin{aligned} f_1 &= 3426x_1^2 - 4443x_1x_2 + 2004x_2^2 + 2335x_1x_3 - 74x_2x_3 + 4215x_3^2 - 1405x_1 + 4108x_2 - 1838x_3 - 2741 \\ f_2 &= -4303x_1^2 - 1401x_1x_2 - 2604x_2^2 + 2745x_1x_3 + 3440x_2x_3 + 3331x_3^2 + 2112x_1 - 271x_2 - 2272x_3 - 3090 \\ f_3 &= -4160x_1^2 + 1056x_1x_2 - 252x_2^2 - 2842x_1x_3 - 3643x_2x_3 + 3024x_3^2 + 3353x_1 + 3908x_2 - 426x_3 + 4197 \end{aligned}$$

We choose $m = 2$ and two random matrices (with coefficients in $[0, \dots, 999]$ for this specific example)

$$U = \begin{bmatrix} 568 & 651 & 852 & 933 & 279 & 835 & 446 & 135 \\ 485 & 707 & 441 & 238 & 678 & 552 & 95 & 900 \end{bmatrix} \quad V = \begin{bmatrix} 338 & 147 & 24 & 526 & 549 & 806 & 741 & 966 \\ 243 & 637 & 563 & 545 & 580 & 432 & 544 & 165 \end{bmatrix}^t$$

Computing the minimal generating polynomial of $s = (UT_3^i V)_{0 \leq i < 8}$,

$$S = \begin{bmatrix} x^4 + 5848x^3 + 1193x^2 + 5800x + 4050 & 5414x^3 + 6409x^2 + 223x + 783 \\ 4469x^3 + 7812x^2 + 80x + 554 & x^4 + 3102x^3 + 4076x^2 + 1871x + 3985 \end{bmatrix}$$

After steps 4 and 5,

$$\begin{aligned} n &= 320x_3^7 + 3312x_3^6 + 38x_3^5 + 763x_3^4 + 5895x_3^3 + 6024x_3^2 + 8927x_3 + 1804 \\ R_3 &= x_3^8 + 8950x_3^7 + 8272x_3^6 + 2637x_3^5 + 3062x_3^4 + 7018x_3^3 + 6992x_3^2 + 8980x_3 + 7724 \end{aligned}$$

For $j = 1$,

$$\begin{aligned} n_1 &= 7981x_3^7 + 7201x_3^6 + 1005x_3^5 + 1044x_3^4 + 3205x_3^3 + 6671x_3^2 + 7423x_3 + 832 \\ R_1 &= 4200x_3^7 + 5082x_3^6 + 6769x_3^5 + 5671x_3^4 + 4288x_3^3 + 8885x_3^2 + 7423x_3 + 4930 \end{aligned}$$

For $j = 2$,

$$\begin{aligned} n_2 &= 4648x_3^7 + 377x_3^6 + 5551x_3^5 + 1738x_3^4 + 2653x_3^3 + 7064x_3^2 + 3229x_3 + 8719 \\ R_2 &= 1168x_3^7 + 5878x_3^6 + 2896x_3^5 + 4452x_3^4 + 3821x_3^3 + 7586x_3^2 + 7952x_3 + 28 \end{aligned}$$

Conclusion

References

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