

5	FAQ	105
6	Use Cases.....	108
6.1	Simple example of creating shared memory using metadata	108
6.2	Automotive Use Case.....	109
6.2.1	Characteristics.....	109
6.2.1.1	Sensors	109
6.2.1.2	Control Task	109
6.2.1.3	Lost Data	109
6.2.1.4	Types of Tasks	109
6.2.1.5	Load Balance	109
6.2.1.6	Message Size and Frequency	109
6.2.1.7	Synchronization.....	109
6.2.1.8	Shared Memory.....	109
6.2.2	Key functionality requirements.....	110
6.2.2.1	Control Task	110
6.2.2.2	Angle Task.....	110
6.2.2.3	Data Tasks	110
6.2.3	Context/Constraints	110
6.2.3.1	Operating System	110
6.2.3.2	Polling/Interrupts	110
6.2.3.3	Reliability	110
6.2.4	Metrics	110
6.2.4.1	Latency of the control task.....	110
6.2.4.2	# dropped sensor readings	110
6.2.4.3	Latencies of data tasks	110
6.2.4.4	Code size	110
6.2.5	Possible Factorings	110
6.2.6	MRAPI Requirements Implications.....	111
6.2.7	Mental Models	111
6.2.8	MRAPI pseudo-code	113
6.2.8.1	Initial Mapping.....	113
6.2.8.2	Changes required to port to new multicore device.....	117
6.3	Remote memory use cases	117
6.4	Synchronization Use Case	129
6.5	Networking use case	129
6.6	Metadata use cases.....	134
6.6.1	dynamic attribute example	134
6.6.2	mrapi_resource_get() examples	135