

Relative Joint Locations from KR210 (from BL)

joint name	parent link	Child link	x(m)	y(m)	z(m)	r, r1
joint_1	base_link	link_1	0	0	0.33	0
joint_2	link_1	link_2	0.35	0	0.42	0
joint_3	link_2	link_3	0	0	1.25	0
joint_4	link_3	link_4	0.96	0	-0.054	0
joint_5	link_4	link_5	0.74	0	0	0
joint_6	link_5	link_6	0.193	0	0	0
gripper-joint	link_6	gripper-link	0.11	0	0	0