October 15th, 2024

To Whom it May Concern,

This document is to certify that the paper titled *"High Dynamic Range Modulo Imaging for Robust Object Detection in Autonomous Driving"* written by **Kebin Contreras, Brayan Monroy and Jorge Bacca** was accepted through a rigorous process of peer review of 8 independent reviewers at the ROAM (Robust, Out-of-Distribution and Multi-Modal models for Autonomous Driving) workshop at the ECCV (European Conference in Computer Vision) in Milan, Italy at the iteration of the year 2024.

In addition the previously mentioned paper won the ***Best Paper Award*** at the workshop scoring the highest score amongst all submitted and accepted papers at the workshop.

This paper was presented on *September 30th, 2024* and will be part of the **European Conference in Computer Vision (ECCV)** official workshop paper proceedings, which is one of the world's top leading venues in Computer Vision and Artificial Intelligence.

If you have any questions do not hesitate in contacting me,

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