

CS 178 HW 3

February 8, 2017

1 Kevin Phung, 47881547

```
In [1]: # Kevin Phung 47881547
```

```
import numpy as np
import matplotlib.pyplot as plt
import mltools as ml
import logisticClassify2 as lc

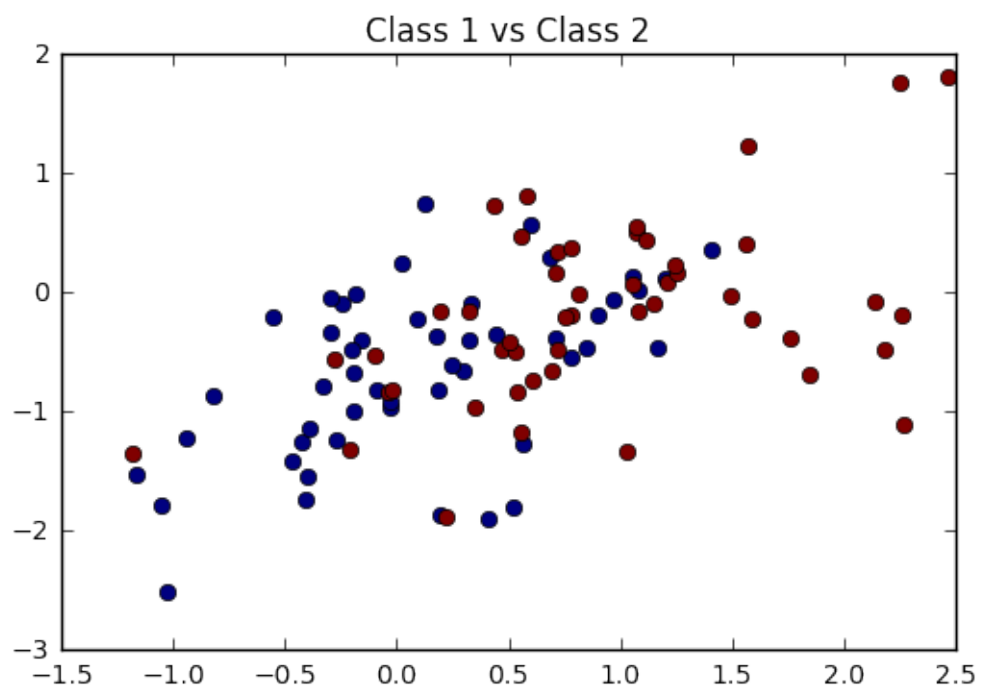
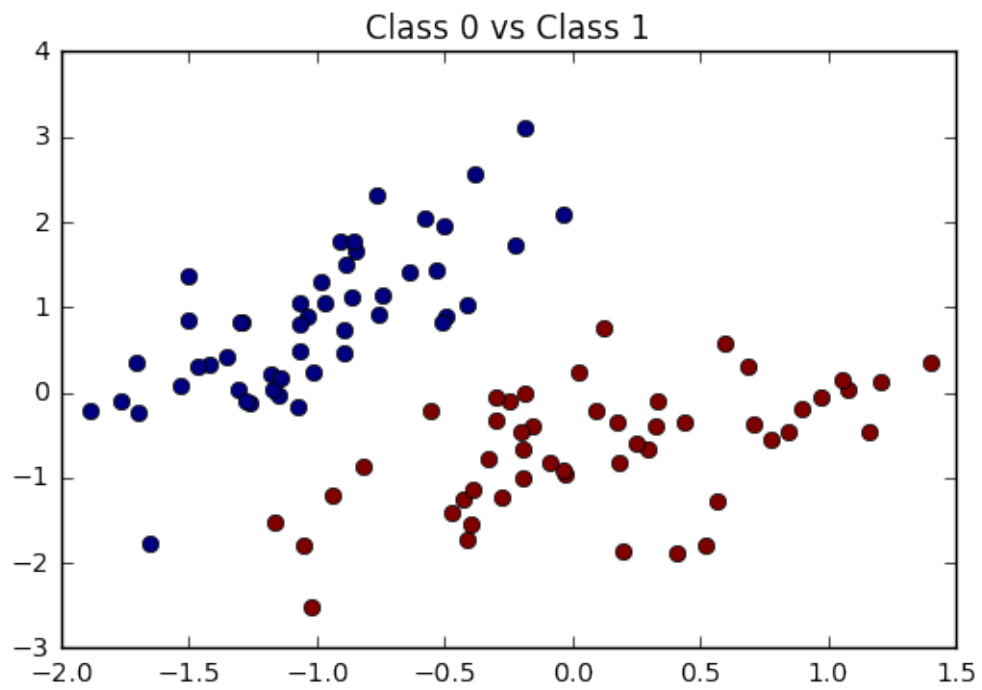
# Part A

iris = np.genfromtxt("data/iris.txt", delimiter=None)
X, Y = iris[:, 0:2], iris[:, -1] # get first two features & target
X, Y = ml.shuffleData(X, Y) # reorder randomly (important later)
X, _ = ml.rescale(X) # works much better on rescaled data

XA, YA = X[Y<2, :], Y[Y<2] # get class 0 vs 1
XB, YB = X[Y>0, :], Y[Y>0] # get class 1 vs 2

plt.title("Class 0 vs Class 1")
ml.plotClassify2D(None, XA, YA)
plt.show()

plt.title("Class 1 vs Class 2")
ml.plotClassify2D(None, XB, YB)
plt.show()
```



In [2]: # Part B

```

learnerA = lC.logisticClassify2();
learnerA.classes = np.unique(YA)
wts = np.array([.5,1,-.25])
learnerA.theta = wts

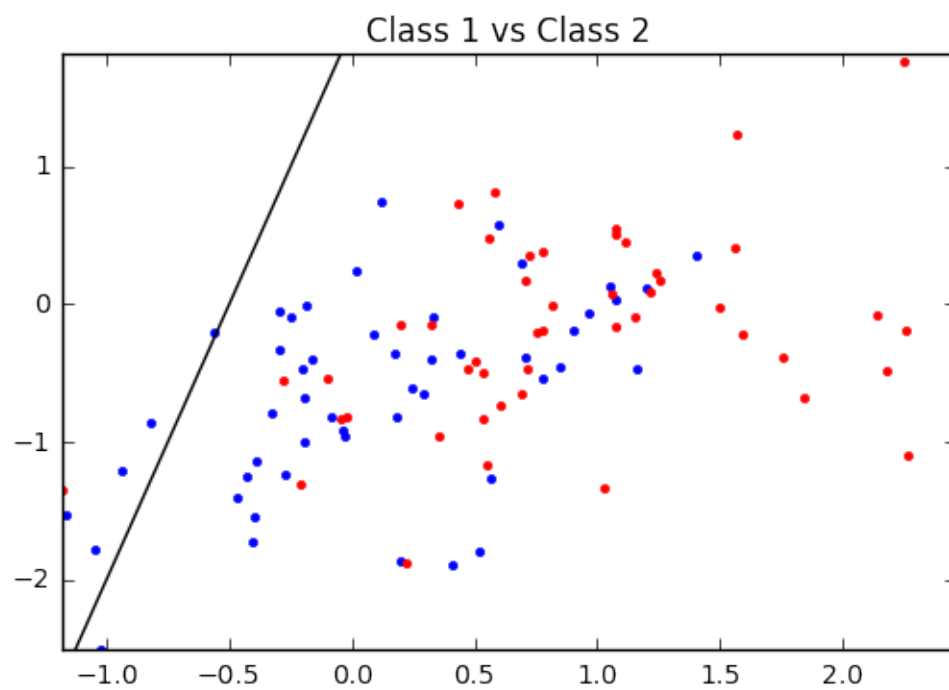
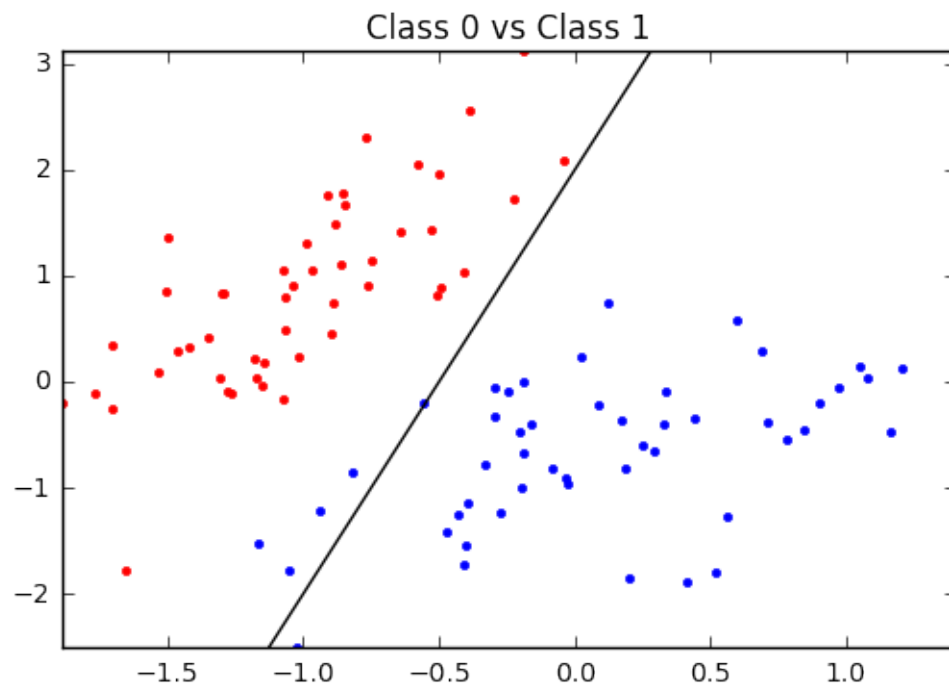
plt.title("Class 0 vs Class 1")
learnerA.plotBoundary(XA,YA)
plt.show()

learnerB = lC.logisticClassify2();
learnerB.classes = np.unique(YB)
wts = np.array([.5,1,-.25])
learnerB.theta = wts

plt.title("Class 1 vs Class 2")
learnerB.plotBoundary(XB,YB)
plt.show()

# def plotBoundary(self,X,Y):
#     """ Plot the (linear) decision boundary of
#     the classifier, along with data """
#
#     if len(self.theta) != 3: raise ValueError('Data & model must be 2D')
#     ax = X.min(0),X.max(0);
#     ax = (ax[0][0],ax[1][0],ax[0][1],ax[1][1]);
#     ## TODO: find points on decision boundary defined
#           by  $\theta_0 + \theta_1 X_1 + \theta_2 X_2 == 0$ 
#     x1b = np.array([ax[0],ax[1]]); # at  $X_1 =$  points in x1b
#     x2bx = (-self.theta[0] - self.theta[1]*x1b[0])/self.theta[2]
#     x2by = (-self.theta[0] - self.theta[1]*x1b[1])/self.theta[2]
#     x2b = np.array([x2bx,x2by])# TODO find x2
#           values as a function of x1's values
#     ## Now plot the data and the resulting boundary:
#     A = Y==1; # and plot it:
#     plt.plot(X[A,0],X[A,1], 'b.',X[-A,0],X[-A,1], 'r.',x1b,x2b, 'k-');
#     plt.axis(ax); plt.draw();
#

```



In [3]: # Part C

```

errTrainA = learnerA.err(XA, YA)
errTrainB = learnerB.err(XB, YB)
print("Set A Error Rate: "+str(errTrainA))
print("Set B Error Rate: "+str(errTrainB))

```

```

Set A Error Rate: 0.0505050505051
Set B Error Rate: 0.464646464646

```

```

In [4]: # Part D

```

```

plt.title("Set A Prediction")
ml.plotClassify2D(learnerA, XA, YA)
plt.show()

```

```

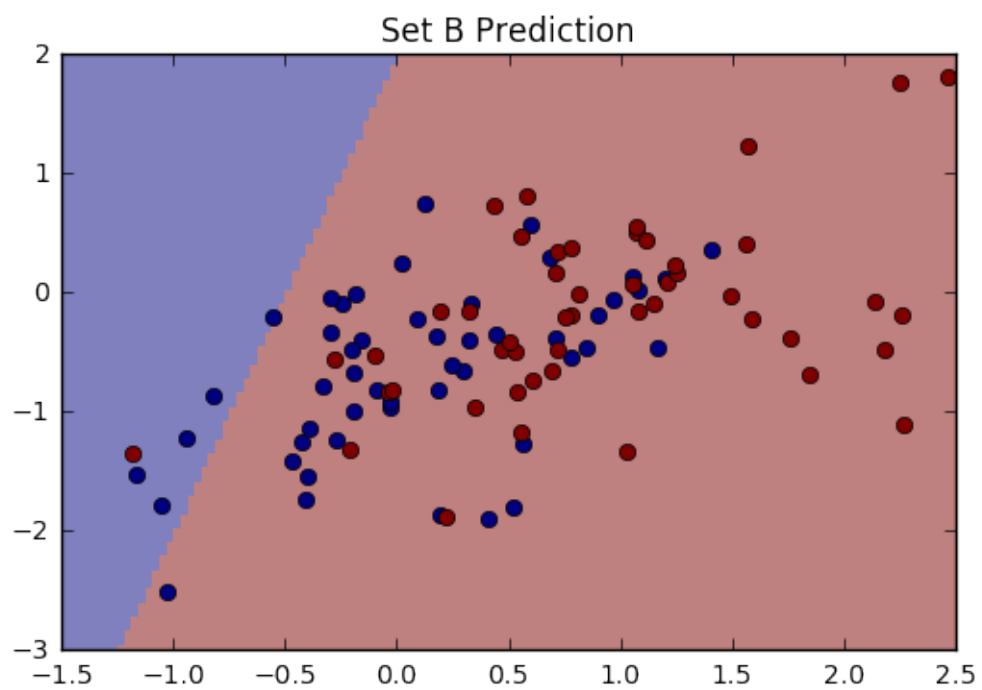
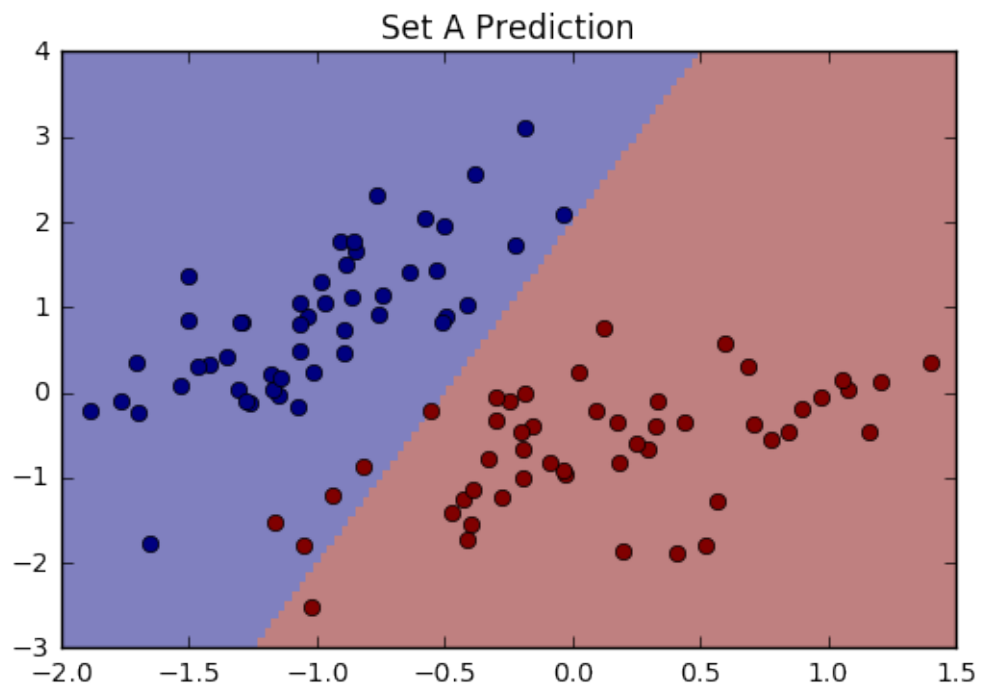
plt.title("Set B Prediction")
ml.plotClassify2D(learnerB, XB, YB)
plt.show()

```

```

#     def predict(self, X):
#         """ Return the predicted class of each data point in X"""
#
#         r = []
#         Yhat = []
#         for i,l in enumerate(X):
#             r.append(self.theta[0] + self.theta[1]*X[i,0]
#                               + self.theta[2]*X[i,1])
#             if r[i] > 0:
#                 Yhat.append(self.classes[1])
#             else:
#                 Yhat.append(self.classes[0])
#         Yhat = np.array(Yhat)
#
#         return Yhat

```



```
In [5]: # Part E
        #  $J/J(\theta) = -y^{(j)} \log(\text{sigmoid}(x^{(j)}\theta^T))$ 
```

```

#             - (1-y^(j))*log(1-sigmoid(x^(j)theta^T))
#         = -y^(j) * (1/sigmoid(x^J theta^T)) * sigmoid(x^J theta^T)
#             * (1-sigmoid(x^J theta^T))
#             - (1-y^J) * (1/ (1-sigmoid(x^J theta^T))
#             * -sigmoid(x^J theta^T) * (1-sigmoid(x^J theta^T))
#         = (-y^(j)) * (1-sigmoid(x^J theta^T)
#           + (1-y^j) * sigmoid(x^J theta^T)

```

In [6]: # Part F/G

```

learnerA2 = lC.logisticClassify2(XA,YA);
ml.plotClassify2D(learnerA2,XA,YA)
plt.show()

```

```

learnerB2 = lC.logisticClassify2(XB,YB)
ml.plotClassify2D(learnerB2,XB,YB)
plt.show()

```

```

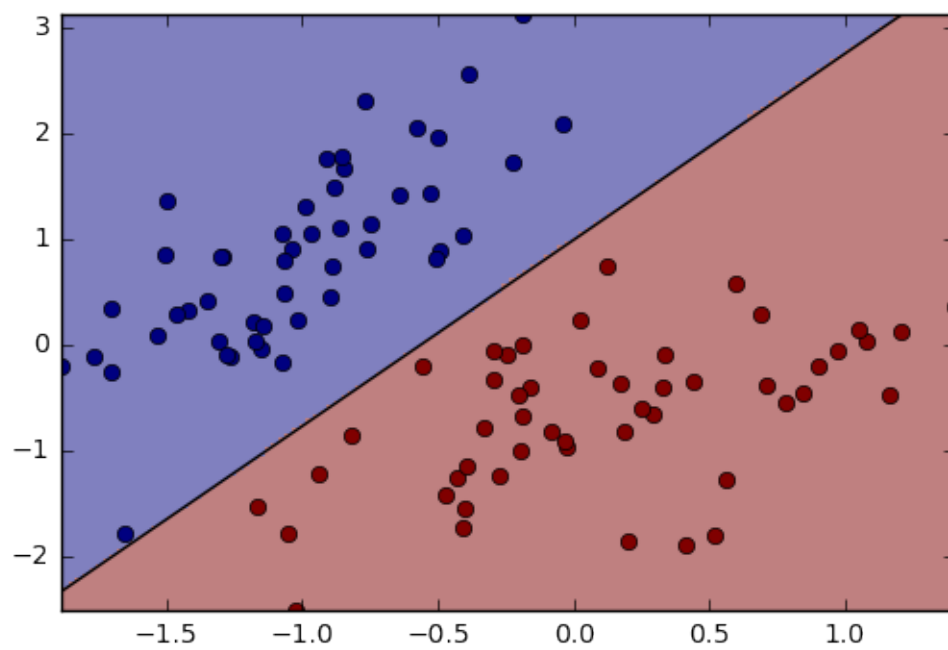
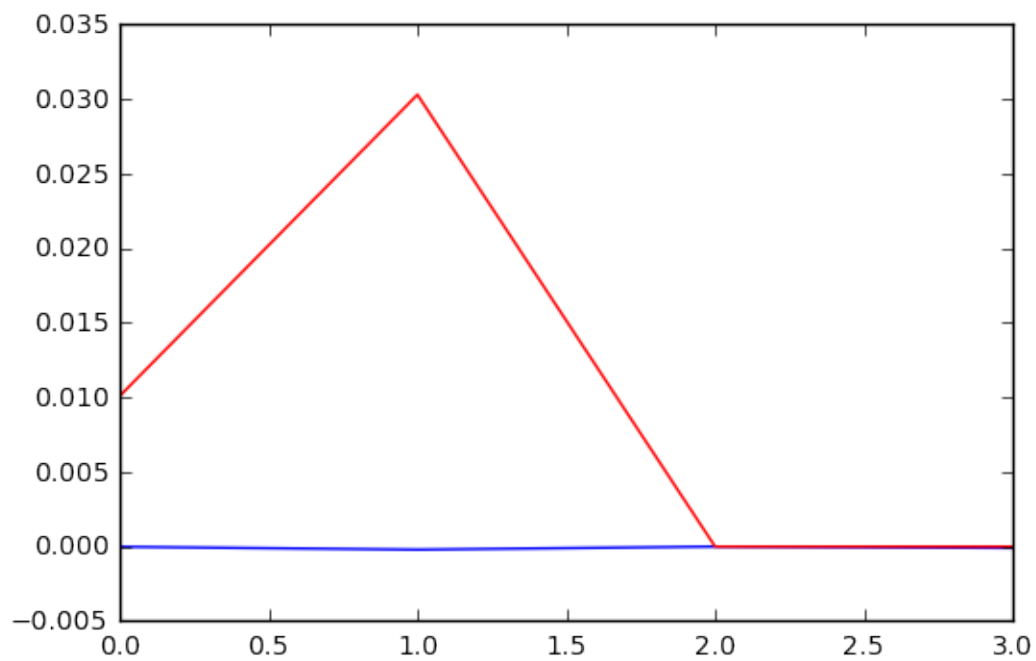
#     def sign(self,r):
#         return (1.0/(1.0/np.exp(-r)))
#
#     def train(self, X, Y, initStep=1.0, stopTol=1e-4, stopEpochs=5000, p
#         """ Train the logistic regression using stochastic gradient descen
#
#         M,N = X.shape;                # initialize the model if neces
#         self.classes = np.unique(Y);    # Y may have two classes, any v
#         XX = np.hstack((np.ones((M,1)),X)) # XX is X, but with an extra
#         YY = ml.toIndex(Y,self.classes); # YY is Y, but with canonical v
#         if len(self.theta)!=N+1: self.theta=np.random.rand(N+1);
#         # init loop variables:
#         epoch=0; done=False; Jnll=[]; J0l=[];
#         while not done:
#             stepsize = initStep*2.0/(2.0+epoch),
#             epoch +=1; # update stepsize
#
#             # Do an SGD pass through the entire data set:
#             for i in np.random.permutation(M):
#                 ri = self.theta[0] + self.theta[1] * X[i,0] + self.theta[2]
#
#                 si = self.sig(ri)
#                 theta1Grad = -YY[i] * (1 - si) + (1 - YY[i]) * si
#                 theta2Grad = -YY[i] * (1 - si) * X[i,0]
#                             + (1 - YY[i]) * si * X[i,0]
#                 theta3Grad = -YY[i] * (1 - si) * X[i,1]
#                             + (1 - YY[i]) * si * X[i,1]
#                 gradi = np.array([theta1Grad, theta2Grad, theta3Grad])
#
#                 self.theta -= stepsize * gradi; # take a gradient step
#

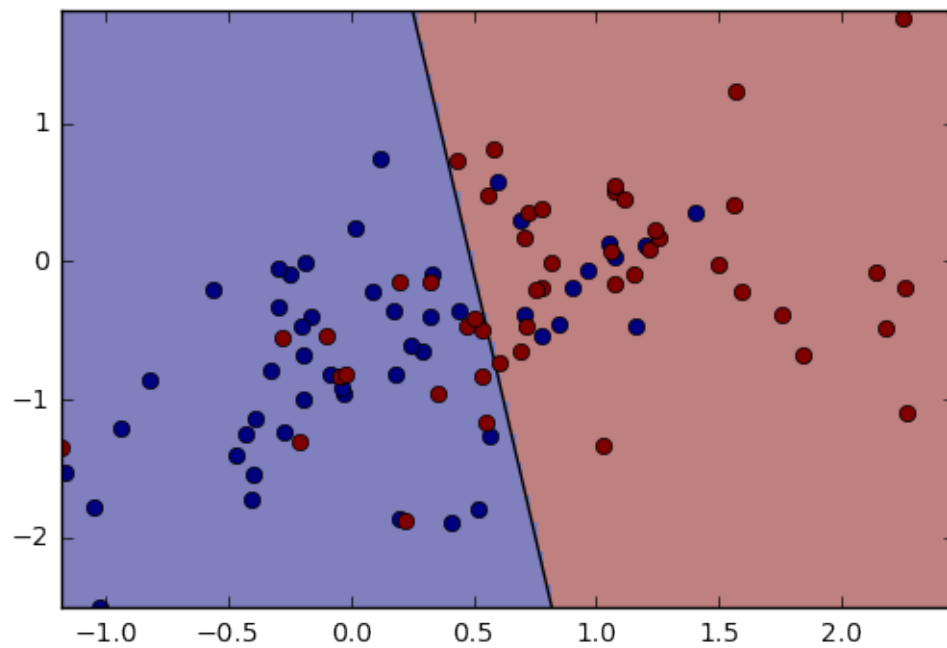
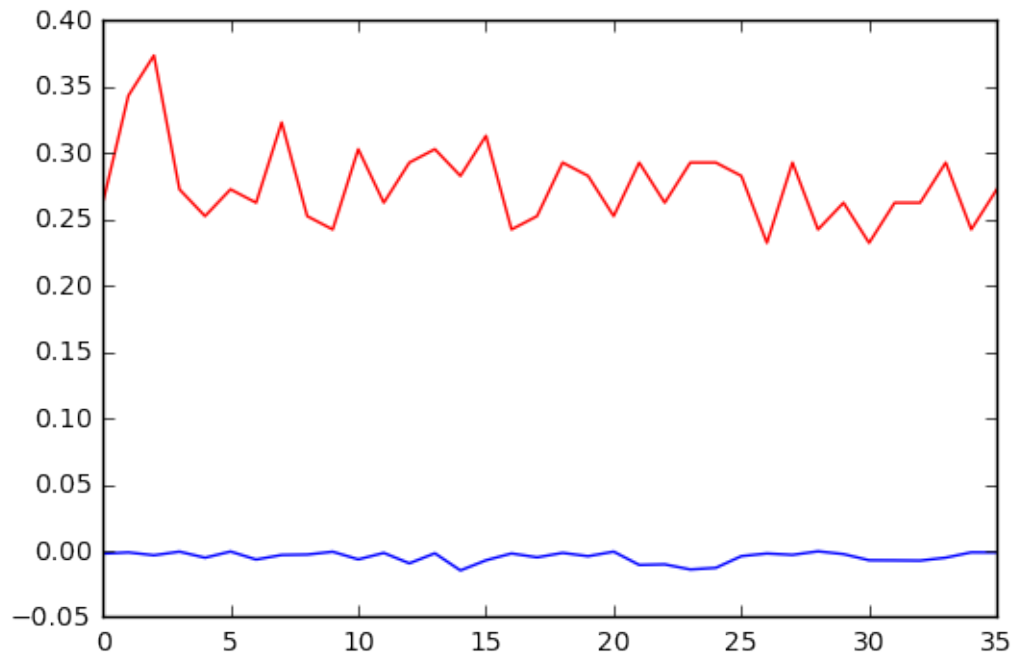
```

```

#         J01.append( self.err(X,Y) ) # evaluate the current error rate
#
#         ## TODO: compute surrogate loss (logistic negative log-likelihood)
#         ## Jsurr = sum_i [ (log si) if yi==1 else (log(1-si)) ]
#
#         Jsurr = np.sum([np.log(si) if YY[i] == 1 else np.log(1-si)])
#         Jnll.append(Jsurr/M)
#
#
#         #plt.figure(1); plt.plot(Jnll,'b-',J01,'r-'); plt.draw(); # plot
#         #if N==2: plt.figure(2); self.plotBoundary(X,Y); plt.draw(); # & plot
#         #plt.pause(.01); # let OS draw the plot
#
#         ## For debugging: you may want to print current parameters & loss
#         # print self.theta, ' => ', Jsurr[-1], ' / ', J01[-1]
#         # raw_input() # pause for keystroke
#
#         # TODO check stopping criteria: exit if exceeded # of epochs
#         if (epoch > stopEpochs):
#             done = True
#         if (epoch > 1 and abs(Jnll[-2]-Jnll[-1] < stopTol)):
#             done = True
#
#         plt.figure(1); plt.plot(Jnll,'b-',J01,'r-'); plt.draw(); # plot
#         if N==2: plt.figure(2); self.plotBoundary(X,Y); plt.draw(); # & plot
#         plt.pause(.01); # let OS draw the plot
#
"""
    For my parameters for Set A, I chose XA and YA. For set B,
    I chose XB and YB
"""

```



```
Out[6]: '\n      For my parameters for Set A, I chose XA and YA. For set B,\n      I ch\n\nIn [ ]: # Problem 2: Shattering and VC Dimension
```

```
# 2 Part A
```

```
"""
```

```
Learner A =  $T(a+bx_1)$  = line
```

```
For learner A, data points in a and b can be shattered because we can  
separate them into -1 and 1 and they will be divided by the  
function  $T(a+bx_1)$ . C and D cannot be shattered because for C, if  
the first and last points are the same while the middle point  
is different it cannot be shattered. For D if the first and last  
points are the same it cannot be shattered.
```

```
"""
```

```
# 2 Part B
```

```
"""
```

```
Learner B =  $T((x_1-a)^2 + (x_2-b)^2+c)$  = circle
```

```
For learner B, data points in a, b, and c can be shattered because  
we can separate them and they will be divided. D cannot be  
shattered because the points can be on the same side of the  
circle but have different values.
```

```
"""
```

```
# 2 Part C
```

```
"""
```

```
Learner C =  $T((a*b)x_1 + (c/a)x_2)$  = line
```

```
For learner C, data points in a and b can be shattered because we can  
separate them into -1 and 1 and they will also be divided. C and D  
cannot be shattered if the points on the same side of the line are  
different.
```

```
"""
```