18.06 Problem Set 1 Solutions

Total: 100 points

Section 1.2. Problem 23: The figure shows that $\cos(\alpha) = v_1/\|v\|$ and $\sin(\alpha) = v_2/\|v\|$. Similarly $\cos(\beta)$ is _____ and $\sin(\beta)$ is ____. The angle θ is $\beta - \alpha$. Substitute into the trigonometry formula $\cos(\alpha)\cos(\beta) + \sin(\beta)\sin(\alpha)$ for $\cos(\beta - \alpha)$ to find $\cos(\theta) = v \cdot w/\|v\| \|w\|$.

Solution (4 points)

First blank: $w_1/\|w\|$. Second blank: $w_2/\|w\|$. Substituting into the trigonometry formula yields

$$\cos(\beta - \alpha) = (w_1/\|w\|)(v_1/\|v\|) + (w_2/\|w\|)(v_2/\|v\|) = v \cdot w/\|v\|\|w\|.$$

Section 1.2. Problem 28: Can three vectors in the xy plane have $u \cdot v < 0$ and $v \cdot w < 0$ and $u \cdot w < 0$?

Solution (12 points)

Yes. For instance take $u = (1,0), \ v = (-\frac{1}{2}, \frac{\sqrt{3}}{2}), \ w = (-\frac{1}{2}, -\frac{\sqrt{3}}{2}).$ Notice $u \cdot v = v \cdot w = u \cdot w = -\frac{1}{2}.$

Section 1.3. Problem 4: Find a combination $x_1w_1 + x_2w_2 + x_3w_3$ that gives the zero vector:

$$w_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}; \ w_2 = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}; \ w_3 = \begin{bmatrix} 7 \\ 8 \\ 9 \end{bmatrix}.$$

Those vectors are (independent)(dependent). The three vectors lie in a $_$ ____. The matrix W with those columns is not invertible.

Solution (4 points)

Observe $w_1 - 2w_2 + w_3 = 0$. The vectors are **dependent**. They lie in a **plane**.

Section 1.3. Problem 13: The very last words say that the 5 by 5 centered difference matrix is not invertible. Write down the 5 equations Cx = b. Find a

combination of left sides that gives zero. What combination of b_1, b_2, b_3, b_4, b_5 must be zero?

| Solution | (12 points)

The 5 by 5 centered difference matrix is

$$C = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 & 0 \\ 0 & -1 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 & 1 \\ 0 & 0 & 0 & -1 & 0 \end{pmatrix}.$$

The five equations Cx = b are

$$x_2 = b_1, -x_1 + x_3 = b_2, -x_2 + x_4 = b_3, -x_3 + x_5 = b_4, -x_4 = b_5.$$

Observe that the sum of the first, third, and fifth equations is zero. Similarly, $b_1 + b_3 + b_5 = 0$.

Section 2.1. Problem 29: Start with the vector $u_0 = (1,0)$. Multiply again and again by the same "Markov matrix" A = [.8 .3; .2 .7]. The next three vectors are u_1, u_2, u_3 :

$$u_1 = \begin{bmatrix} .8 & .3 \\ .2 & .7 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} .8 \\ .2 \end{bmatrix}$$
 $u_2 = Au_1 = \underline{\qquad}$ $u_3 = Au_2 = \underline{\qquad}$.

What property do you notice for all four vectors u_0 , u_1 , u_2 , u_3 .

Solution (4 points)

Computing, we get

$$u_2 = \begin{bmatrix} .7 \\ .3 \end{bmatrix}$$
 $u_3 = \begin{bmatrix} .65 \\ .35 \end{bmatrix}$.

All four vectors have components that sum to one.

Section 2.1. Problem 30: Continue Problem 29 from $u_0 = (1,0)$ to u_7 , and also from $v_0 = (0,1)$ to v_7 . What do you notice about u_7 and v_7 ? Here are two MATLAB codes, with while and for. They plot u_0 to u_7 and v_0 to v_7 .

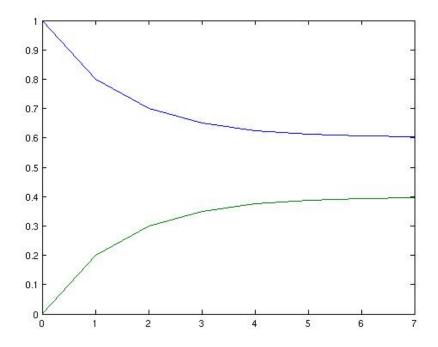
The u's and the v's are approaching a steady state vector s. Guess that vector and check that As = s. If you start with s, then you stay with s.

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Solution (12 points)
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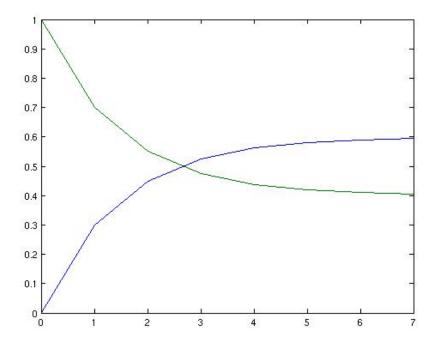
Here is the code entered into MATLAB.

```
u=[1; 0];
A = [.8.3; .2.7];
x= u;
k = [0:7];
while size (x, 2) \le 7
u = A^*u; x = [x, u];
end
plot (k,x)
v = [0;1];
A = [.8.3; .2.7];
x= v;
k = [0:7];
for j=1:7
v = A^*v; x = [x, v];
end
plot (k, x)
```

In this graph, we see that the sequence u_1, u_2, \ldots, u_7 is approaching (.6, .4).



In this graph, we see that the sequence v_1, v_2, \ldots, v_7 is approaching (.6, .4).



From the graphs, we guess that s = (.6, .4) is a steady state vector. We verify this with the computation

$$As = \begin{bmatrix} .8 & .3 \\ .2 & .7 \end{bmatrix} \begin{bmatrix} .6 \\ .4 \end{bmatrix} = \begin{bmatrix} .6 \\ .4 \end{bmatrix}.$$

Section 2.2. Problem 20: Three planes can fail to have an intersection point, even if no planes are parallel. The system is singular if row 3 of A is a _____ of the first two rows. Find a third equation that can't be solved together with x + y + z = 0 and x - 2y - z = 1.

Solution (4 points)

The system is singular if row 3 of A is a **linear combination** of the first two rows. There are many possible choices of a third equation that cannot be solved together with the ones given. An example is 2x + 5y + 4z = 1. Note that the left hand side of the third equation is the three times the left hand side of the first minus the left hand side of the second. However, the right hand side does not satisfy this relation.

Section 2.2. Problem 32: Start with 100 equations Ax = 0 for 100 unknowns $x = (x_1, \ldots, x_{100})$. Suppose elimination reduces the 100th equation to 0 = 0, so the system is "singular".

- (a) Elimination takes linear combinations of the rows. So this singular system has the singular property: Some linear combination of the 100 **rows** is _____.
- (b) Singular systems Ax = 0 have infinitely many solutions. This means that some linear combination of the 100 **columns** is
- (c) Invent a 100 by 100 singular matrix with no zero entries.
- (d) For your matrix, describe in words the row picture and the column picture of Ax = 0. Not necessary to draw 100-dimensional space.

Solution (12 points)

(a) Zero. (b) Zero. (c) There are many possible answers. For instance, the matrix for which every row is (1 2 3 ··· 100). (d) The row picture is 100 copies of the hyperplane in 100-space defined by the equation

$$x_1 + 2x_2 + 3x_3 + \dots + 100x_{100} = 0.$$

The column picture is the 100 vectors proportional to $(1\ 1\ 1\ \cdots\ 1)$ of lengths $10, 20, \ldots, 1000$.

Section 2.3. Problem 22: The entries of A and x are a_{ij} and x_j . So the first component of Ax is $\sum a_{1j}x_j=a_{11}x_1+\cdots+a_{1n}x_n$. If E_{21} subtracts row 1 from row 2, write a formula for

- (a) the third component of Ax
- (b) the (2,1) entry of $E_{21}A$
- (c) the (2,1) entry of $E_{21}(E_{21}A)$
- (d) the first component of $E_{21}Ax$.

Solution (4 points)

$$(a) \sum a_{3j} x_j$$
. (b) $a_{21} - a_{11}$. (c) $a_{21} - 2a_{11}$. (d) $\sum a_{1j} x_j$.

Section 2.3. Problem 29: Find the triangular matrix E that reduces "Pascal's matrix" to a smaller Pascal:

$$E\begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 2 & 1 & 0 \\ 1 & 3 & 3 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 2 & 1 \end{bmatrix}.$$

Which matrix M (multiplying several E's) reduces Pascal all the way to I?

Solution (12 points)

$$E = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix}.$$

One can eliminate the second column with the matrix

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix}$$

and the third column with the matrix

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix}.$$

Multiplying these together, we get

$$M = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 1 & -2 & 1 & 0 \\ -1 & 3 & -3 & 1 \end{bmatrix}.$$

Section 2.4. Problem 32: Suppose you solve Ax = b for three special right sides b:

$$Ax_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}; \quad Ax_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}; \quad Ax_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}.$$

If the three solutions x_1, x_2, x_3 are the columns of a matrix X, what is A times X?

Solution (4 points)

The matrix AX has columns Ax_1 , Ax_2 , and Ax_3 . Therefore, AX = I.

Section 2.4. Problem 36: Suppose A is m by n, B is n by p, and C is p by q. Then the multiplication count for (AB)C is mnp + mpq. The multiplication count from A times BC with mnq + npq separate multiplications.

- (a) If A is 2 by 4, B is 4 by 7, and C is 7 by 10, do you prefer (AB)C or A(BC)?
- (b) With N-component vectors, would you choose $(u^Tv)w^T$ or $u^T(vw^T)$?
- (c) Divide by mnpq to show that (AB)C is faster when $n^{-1} + q^{-1} < m^{-1} + p^{-1}$.

Solution (12 points)

- (a) Note that (AB)C has $2 \cdot 4 \cdot 7 + 2 \cdot 7 \cdot 10 = 196$ multiplications and A(BC) has $2 \cdot 4 \cdot 10 + 4 \cdot 7 \cdot 10 = 360$. Hence, we prefer (AB)C.
- (b) We prefer $(u^Tv)w^T$; it requires 2N multiplications. On the other hand, the multiplication count for $u^T(vw^T)$ is $2N^2$.
- (c) Note (AB)C is faster when mnp + mpq < mnq + npq. Dividing by mnpq, we get $q^{-1} + n^{-1} < p^{-1} + m^{-1}$.

Section 2.5. Problem 7: If A has row 1 + row 2 = row 3, show that A is not invertible:

- (a) Explain why Ax = (1, 0, 0) cannot have a solution.
- (b) Which right sides (b_1, b_2, b_3) might allow a solution to Ax = b?
- (c) What happens to row 3 in elimination?

Solution (4 points)

- (a) Suppose A has row vectors A_1 , A_2 , A_3 , and x is a solution to Ax = (1,0,0). Then $A_1 \cdot x = 1$, $A_2 \cdot x = 0$, and $A_3 \cdot x = 0$. But $A_1 + A_2 = A_3$ means that $A_1 \cdot x + A_2 \cdot x = A_3 \cdot x$ and 1 + 0 = 0, a contradiction.
- (b) If $Ax = (b_1, b_2, b_3)$, then $A_1 \cdot x = b_1$, $A_2 \cdot x = b_2$, $A_3 \cdot x = b_3$. Since $A_1 + A_2 = A_3$, we deduce $b_1 + b_2 = b_3$.
- (c) In the eliminated matrix, the third row will be zero.

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