

```

1  import StandardLibrary as STDLIB
2  import StandardMaterialsLibrary as STDMTLLIB
3  import postProcess as POSTPRO
4  import csv
5  import numpy as np
6  from numpy.linalg import inv
7
8  # INPUTS
9  #
10 -----
11 # The name of the input file
12 input_file = 'TrussProblem.sinp'
13
14 # Post processign info
15 deform_factor = 100000
16 #
17 -----
18 # INPUTS END
19
20 name_ip_file = input_file[:-5]
21
22 # Read entire input file
23 all_lines = STDLIB.readFile(input_file)
24
25 # Parse the input file for 'keywords'
26 [keyword_lines, all_keywords, comment_lines, all_asterix] =
STDLIB.parseKeywords(input_file)
27
28 # Read the Nodes
29 Nodes = STDLIB.readNodes(all_lines, all_keywords, keyword_lines, all_asterix)
30
31 # Read the elements
32 Elements = STDLIB.readElements(all_lines, all_keywords, keyword_lines, all_asterix)
33
34 # Read the linear elastic material
35 [E, nu] = STDLIB.read_elastic_material(all_lines, all_keywords, keyword_lines, all_asterix)
36
37
38 # Count the number of nodes
39 nnd = len(Nodes)
40 nel = len(Elements[0])
41
42 # Identify the element
43 name_of_Element = Elements[1]
44 currentElement = STDLIB.elementsLibrary(name_of_Element)
45
46 # Number of nodes per element
47 nne = currentElement.nne
48
49 # Number of degrees of freedom per node
50 nodof = currentElement.nodof
51
52 # Number of degrees of freedom per element
53 eldof = nne*nodof
54
55 '''
56 # Beam thickness in m
57 thick = 0.01
58
59 # Number of sampling points
60 num_gauss_points = 2;
61
62 # Form the elastic matrix for plane stress
63 dee = STDMTLLIB.formdsig(E, nu)
64

```

Make this section as
an automatic input
from the input file.

For the D-matrix
according to element
type.

```

65 # Create Node sets
66 # -----
67 NodeSets = STDLIB.createNodeSets(all_lines,all_keywords,keyword_lines,all_asterix)
68
69
70 # -----
71 # Boundary conditions
72 # -----
73
74 # Read the boundary conditions
75 BCS_NodeSet = STDLIB.read_BCS(all_lines,all_keywords,keyword_lines,all_asterix)
76
77 # Apply the Boundary Conditions
78 nf = STDLIB.apply_BCS(nnd,nodof,Nodes,NodeSets,BCS_NodeSet)
79
80 # Count the free degrees of freedom (Size of the stiffness matrix)
81 active_dof = 0
82
83 for i in range(0,nnd):
84     for j in range(0,nodof):
85         if nf[i,j] != 0:
86             active_dof=active_dof+1
87             nf[i,j]=active_dof
88
89 # -----
90 # Loading
91 # -----
92
93 # Read the node sets where the concentrated load sets are applied
94 [Cload_NodeSet_list, Cload_dof_mag]=
95 STDLIB.read_Cloads(all_lines,all_keywords,keyword_lines,all_asterix)
96
97 # Apply the actual loading
98 Nodal_loads =
99 STDLIB.apply_cloads(nnd,nodof,Nodes,NodeSets,Cload_NodeSet_list,Cload_dof_mag)
100
101 # -----
102 # Assemble the global force vector
103 # This force vector will have one column and active_dof-rows
104
105 force_global = np.zeros(shape=(active_dof,1))
106
107 for i in range(0,nnd):
108     if nf[i][0] != 0:
109         force_global[int(nf[i][0])-1] = Nodal_loads[i][0]
110
111     if nf[i][1] != 0:
112         force_global[int(nf[i][1])-1] = Nodal_loads[i][1]
113
114 # -----
115 # Assembly of the global stiffness matrix
116 # -----
117
118 # Collect the sampling points
119 samp = STDLIB.gaussPoints(num_gauss_points)
120
121 # Initialize the global stiffness matrix
122 KK = np.zeros(shape=(active_dof,active_dof))
123
124 # Form the element stiffness matrix and then assemble the global stiffness matrix
125 for i in range(0,nel):
126     # Extract the coordinates of the element and the steering vector
127     [coords,g] = STDLIB.elem_Q4(i,Nodes,Elements,nne,nodof,nf)
128
129     # Initialize the element stiffness matrix

```

```

130     ke = np.zeros(shape=(eldof,eldof))
131
132     # Calculate the element stiffness matrix at each Gauss point
133     for ig in range(0,num_gauss_points):
134         for jg in range(0,num_gauss_points):
135
136             [der_xi_eta, shapeFun] = STDLIB.fmQ4_lin(samp,ig,jg)
137
138             # For the jacobian matrix
139             jac = der_xi_eta.dot(coords)
140
141             # Compute the inverse of the Jacobian matrix
142             jac_inv = inv(jac)
143
144             # Compute the derivatives of the shape functions
145             der_x_y = jac_inv.dot(der_xi_eta)
146
147             # Form the B-matrix
148             bee = STDLIB.formbee_Q4_lin(der_x_y,nne,eldof)
149
150             # Integrate the stiffness matrix
151             wi = samp[ig][1]
152             wj = samp[jg][1]
153             d = np.linalg.det(jac)
154
155             ke = np.add(ke, reduce(np.dot, [d, thick, wi, wj, bee.transpose(), dee,bee]))
156
157     # Form the global stiffness matrix
158     KK = STDLIB.form_KK(KK,ke,g,eldof)
159
160     # Invert the global stiffness matrix and find the unknown displacements
161     delta = inv(KK).dot(force_global)
162
163     # Seperate the displacements into its componenets
164     # -----
165     node_disp = STDLIB.separate_disp(nodof,nnd,delta,nf)
166
167     nodesFinal = Nodes[...,:1:] + deform_factor*node_disp
168
169
170     # Name of the output database
171     name_output_db = name_ip_file + '.msh'
172     POSTPRO.write_gmsh_file(name_output_db,nnd,Nodes,nodesFinal,node_disp,nel,Elements)
173     '''

```

Change this for a Truss
Element

The output processor
currently only calculates
displacement. Add
Stress also as an
output.