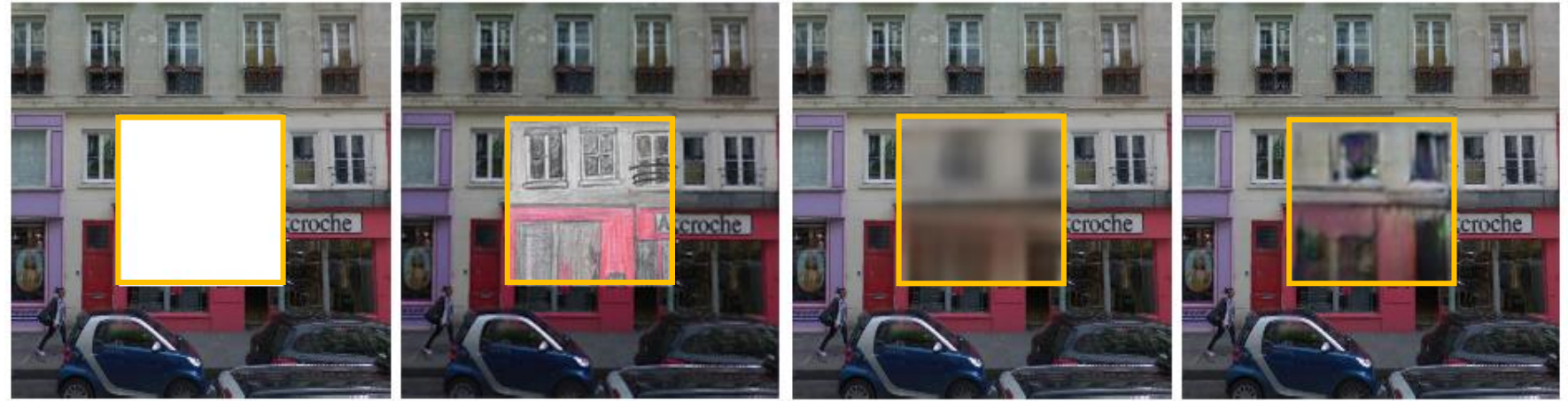


Context Encoders: Feature Learning by Inpainting

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Abstract



(a) Input context

(b) Human artist

(c) Context Encoder
($L2$ loss)

(d) Context Encoder
($L2 + \text{Adversarial loss}$)

- **Approach :**

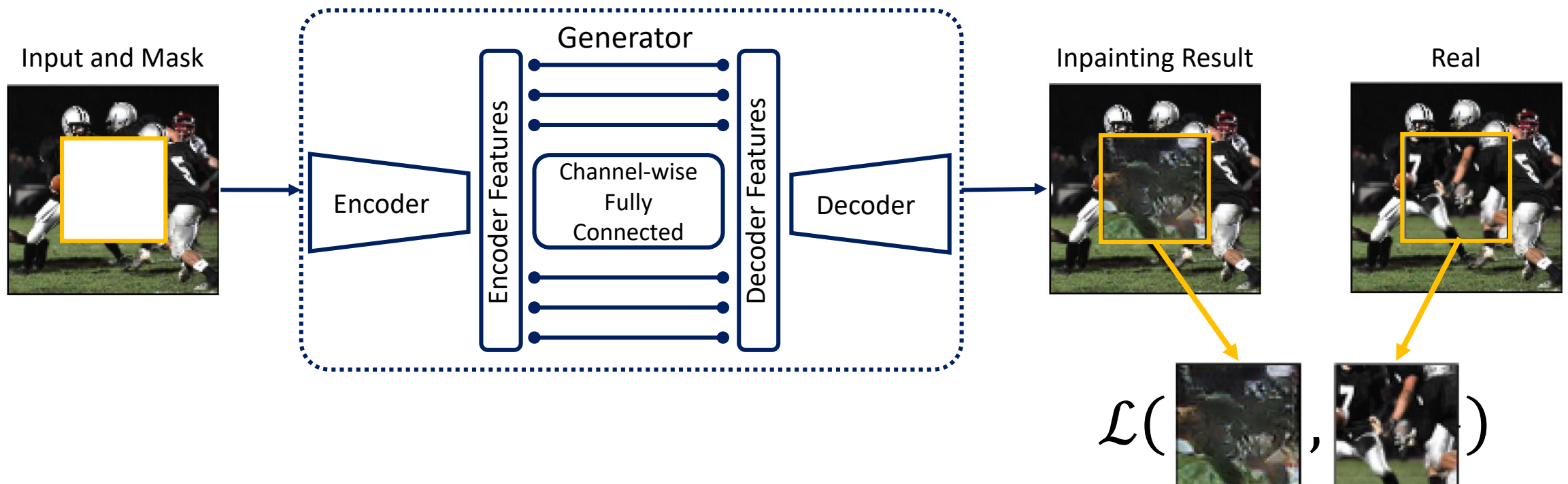
- An unsupervised visual feature learning algorithm driven by context-based pixel prediction.

- **Models :**

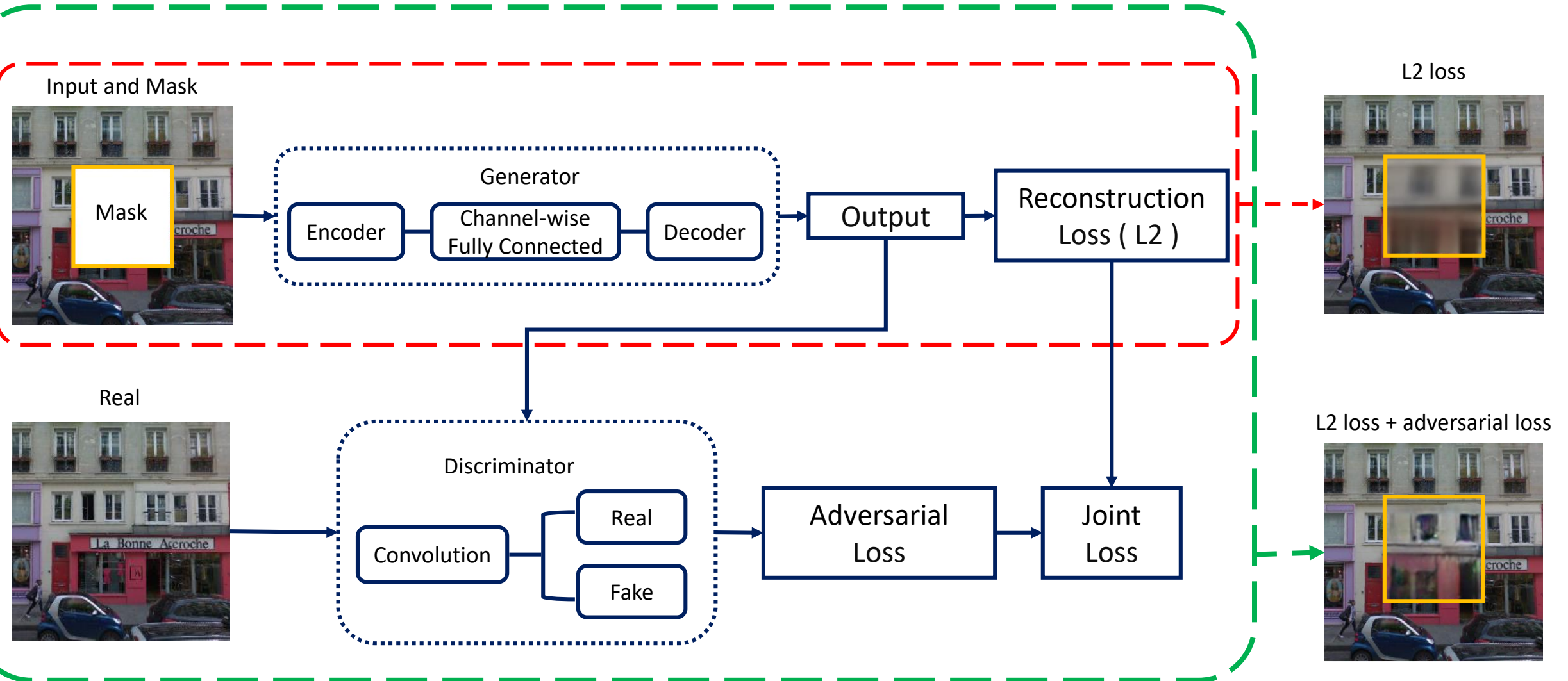
- Convolutional Neural Network
- Conditional Generative Adversarial Network

Context Encoder

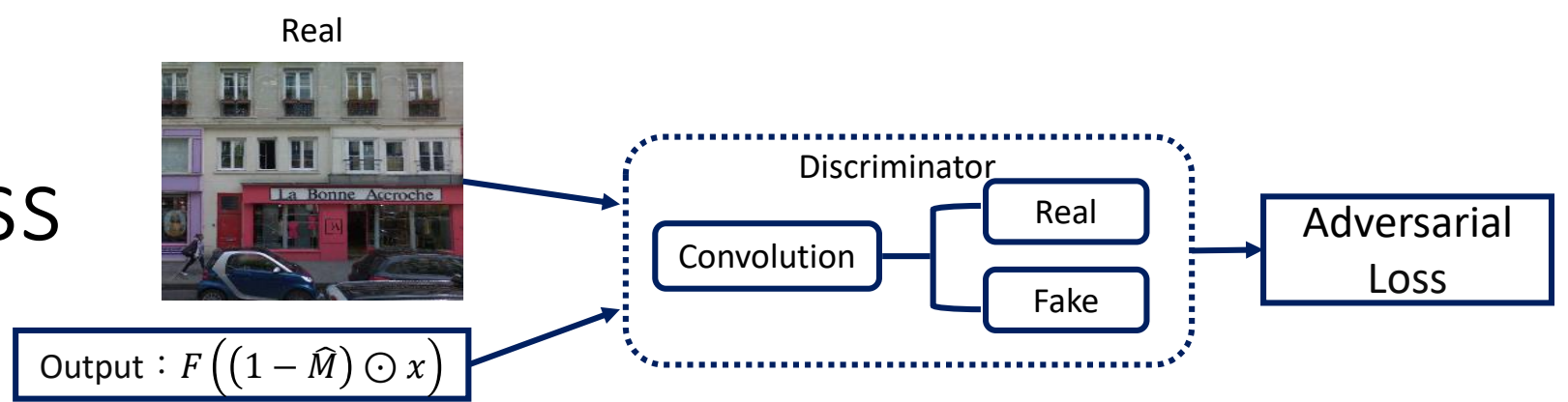
- CNNs that predict missing parts of a scene from their surroundings.



Framework



Adversarial Loss



- Original Adversarial Loss

- $$\min_G \max_D \mathbb{E}_{x \in \mathcal{X}} [\log(D(x))] + \mathbb{E}_{z \in \mathcal{Z}} [\log(1 - D(G(z)))]$$

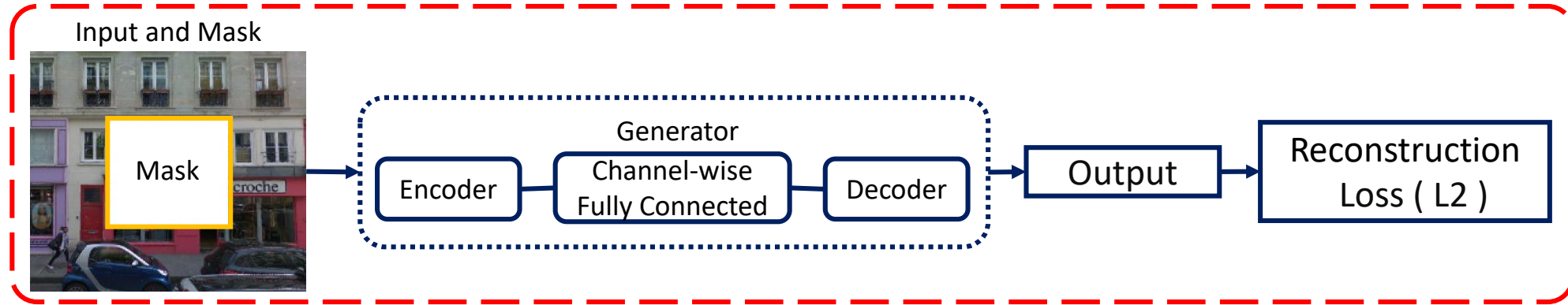
- G : Generator
- D : Discriminator
- x : real image
- z : noise
- \mathcal{X} : data distribution
- \mathcal{Z} : noise distribution

- Alternate Adversarial Loss

- $$\mathcal{L}_{adv} = \max_D \mathbb{E}_{x \in \mathcal{X}} \left[\log(D(x)) + \log \left(1 - D \left(F \left(\boxed{(1 - \hat{M}) \odot x} \right) \right) \right) \right]$$

- D : Discriminator
- $F : G \triangleq F$
- \hat{M} : input and mask , $\begin{cases} 0, & \text{for missing pixels} \\ 1, & \text{for elsewhere} \end{cases}$

Generator Loss



- Generator Loss
 - $\mathcal{L} = \lambda_{rec} \mathcal{L}_{rec} + \lambda_{adv} \mathcal{L}_{adv}$

- λ_{rec} 、 λ_{adv} : weights

- Reconstruction Loss (L2)

- $\mathcal{L}_{rec}(x) = \left\| \hat{M} \odot \left(x - F \left(\left((1 - \hat{M}) \odot x \right) \right) \right) \right\|_2^2$

- \hat{M} : input and mask , $\begin{cases} 0, & \text{for missing pixels} \\ 1, & \text{for elsewhere} \end{cases}$
 - x : real image
 - F : Generator

Expected Results

- Expected Results

