

#### Multi-Agent Actor-Critic for Mixed Cooperative-Competitive Environments

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#### Schema

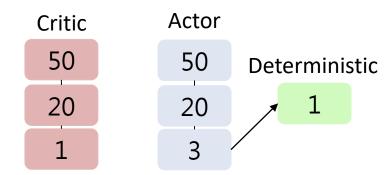
- > Introduction
- > DDPG
- > MADDPG
- > Summary
- > Reference

# 1 Introduction

Policy-gradient
Q-learning
+DQN
DDPG
MADDPG

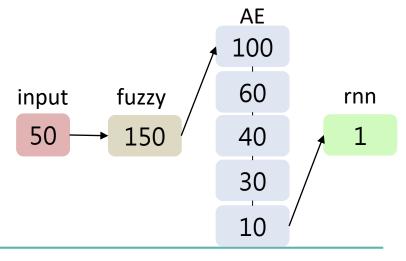
#### **DDPG**

- DDPG: Actor-critic + DQN
- ➤ Deep: memory pool + 雙網路
- ➤ Critic跟Actor要輪流train
- ➤ Deterministic: 概率→明確

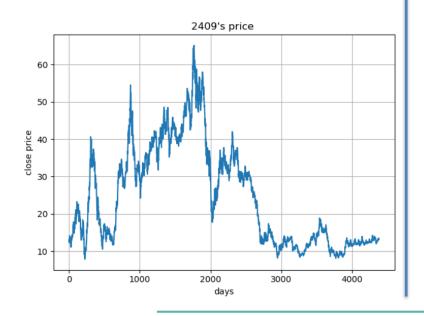


#### **FDRNN**

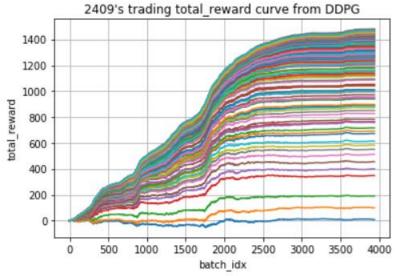
- ➤ Fuzzy部分讓資料分開一點
- ➤ AE部分加深網路
- ➤ RNN部分是模型主軸
- ➤ 以tanh方式壓輸出值



#### 友達

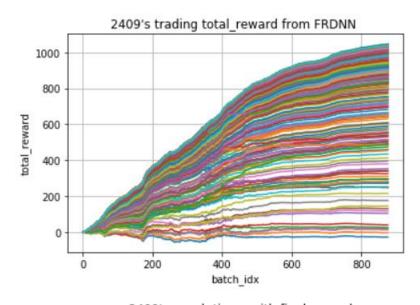


#### **DDPG**





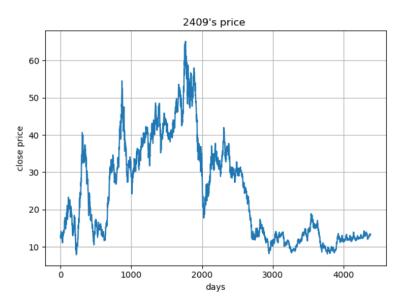
#### **FDRNN**

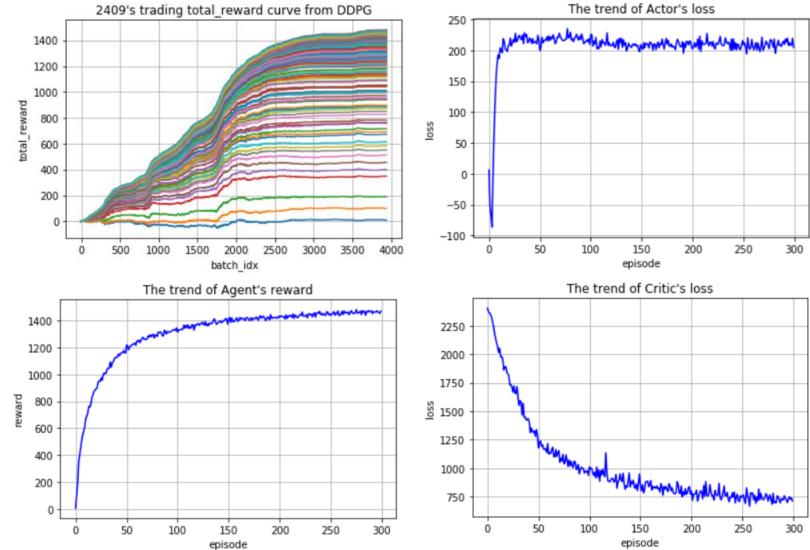




# DDPG友達

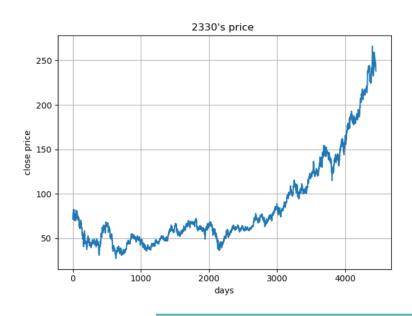


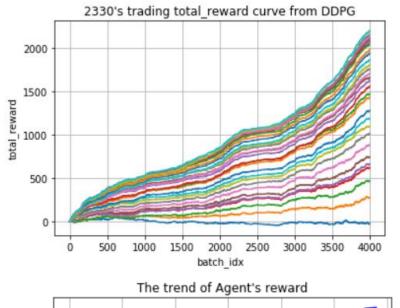


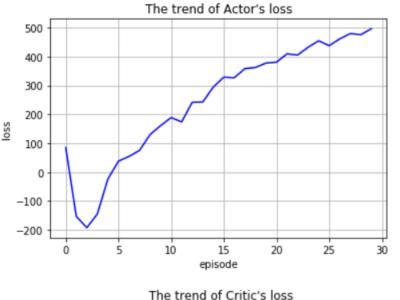


### DDPG台積電

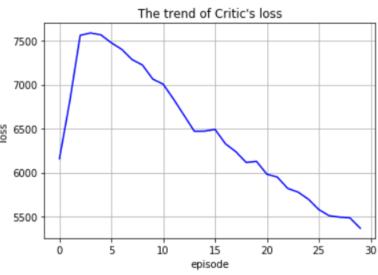






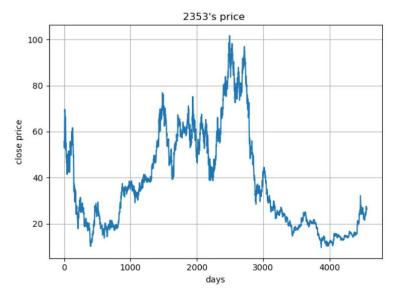


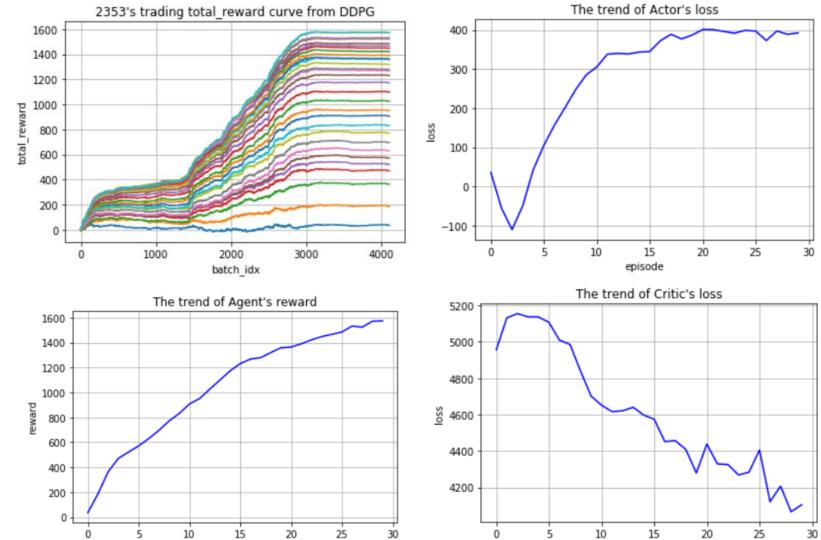




### DDPG宏碁







episode

episode

#### **MADDPG**

- ➤ 每個Agent的訓練和DDPG類似
- ➤ 不同點在於Critic的input, 增加了額外信息
  - ➤ 其他Agent的action
- ▶ 集中學習 + 分散執行

