



- 1.
2. There is limited functionality for this in our project. ROS transforms can be used to determine joint angles required. April tags can be faced on a person to track them, thought it is not a good idea as it can mask landmarks on face.
3. Yes. April tag libraries for Kinetic available were very poor, had to debug quiet a lot before installing 14.04 and Indigo and starting over. Also, the instruction manual isn't very helpful for kinetic users. The directory structure required isn't intuitive.