



Vulnerability Prevention

Holistic Software Security

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Can we prevent vulnerabilities?

- Prevent => Making sure that a program does not have vulnerabilities.
- Why does a program has vulnerabilities?



How do we write programs?

I want to write code to do X:

1. Think about “How to do X” -> Algorithm.
2. Code <-> Test.

Development mindset => Will the code do “X”?

Security mindset => I want the code NOT to do Y.

Possible Y’s:

- Buffer overflow.
- Out-of-bounds access.
- etc.



Bridging the gap!

- Train developers to have security mindset:
 - Secure coding training.
- Enable developers to write code that “cannot” have vulnerabilities:
 - Provide Memory safe/Type safe languages:
 - Java, Python, C#, etc.



Memory Safety

- Spatial memory safety: Ensuring all memory dereferences are within the objects allocated space.
 - Out of bounds access, buffer overflow, underflow, etc.
 - **arr[i]**
- Temporal memory safety: Ensuring that memory dereferences are valid at the time of access.
 - Use-after-free, double free, etc.
 - **free(p); *p = 0;**



Type Safety

- Objects are well-typed and conversion between types is well-defined:
 - Ex: In Java, type conversion is allowed only within subtypes.
- Is Python type safe?
- Is Java type safe?
- Is C++ type safe?

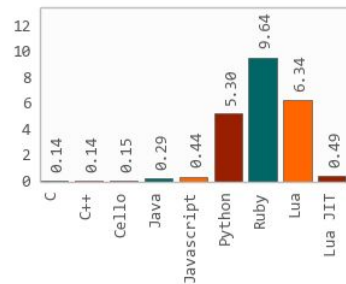
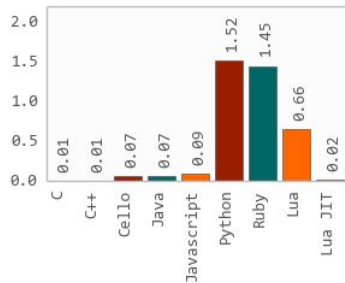
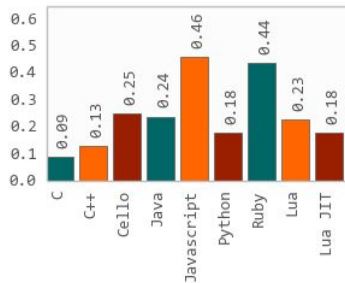


How is safety implemented?

- Runtime checking:
 - Language runtime: Java JRE.
 - Memory accesses are checked for violations.
 - Castings are also checked at time.

Safety is not free!

Performance: Time and Space.



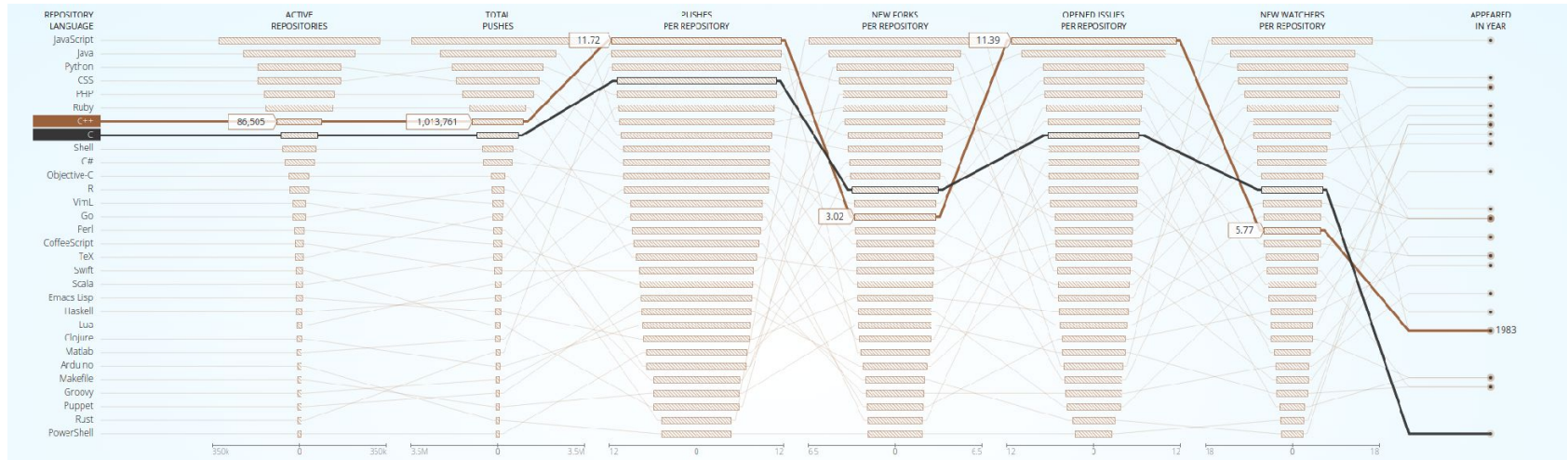


High-performant safe languages

- Rust/Go:
 - Similar to C/C++, faster than Java, Python, etc.
- Lets always use Rust/Go!

What is the catch?

What about legacy code?



Can we ask all developers to convert their code to safe languages?



Retrofitting Techniques

- Retrofit safety to unsafe languages:
 - Modify language semantics so that certain safety properties can be achieved.
 - Performance overhead?
 - Space and Time.
 - Automated or manual?
 - Does developer has to make changes to the existing code?



Retrofitting Techniques: Principles

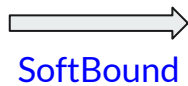
- Spatial memory safety (SMS):
 - An efficient way to track bounds (start and end) of the object being referenced.
- Temporal memory safety (TMS):
 - An efficient way to track lifetime of objects.

SoftBound: SMS

For each pointer variable (p) : Add two variables to track bounds (start : p_base) and end: p_bound).

Check each pointer dereference to be with in bounds.

```
value = *ptr;
```



```
check(ptr, ptr_base, ptr_bound, sizeof(*ptr));  
value = *ptr;
```

```
void check(ptr, base, bound, size) {  
    if ((ptr < base) || (ptr+size > bound)) {  
        abort();  
    }  
}
```

SoftBound: Tracking Pointers

```
ptr = malloc(size);
```



```
ptr = malloc(size);  
ptr_base = ptr;  
ptr_bound = ptr + size;
```

```
newptr = ptr + index;
```



```
newptr = ptr + index;  
newptr_base = ptr_base;  
newptr_bound = ptr_bound;
```

```
p = &(n->num);
```



```
p = &(n->num);  
p_base = max(&(n->num), n_base);  
p_bound = min(p_base + sizeof(n->num), n_bound);
```



SoftBound: Tracking Pointers

```
int** ptr;  
int* new_ptr;  
(*ptr) = new_ptr;
```





SoftBound: Tracking Pointers

```
int** ptr;  
int* new_ptr;  
(*ptr) = new_ptr;
```



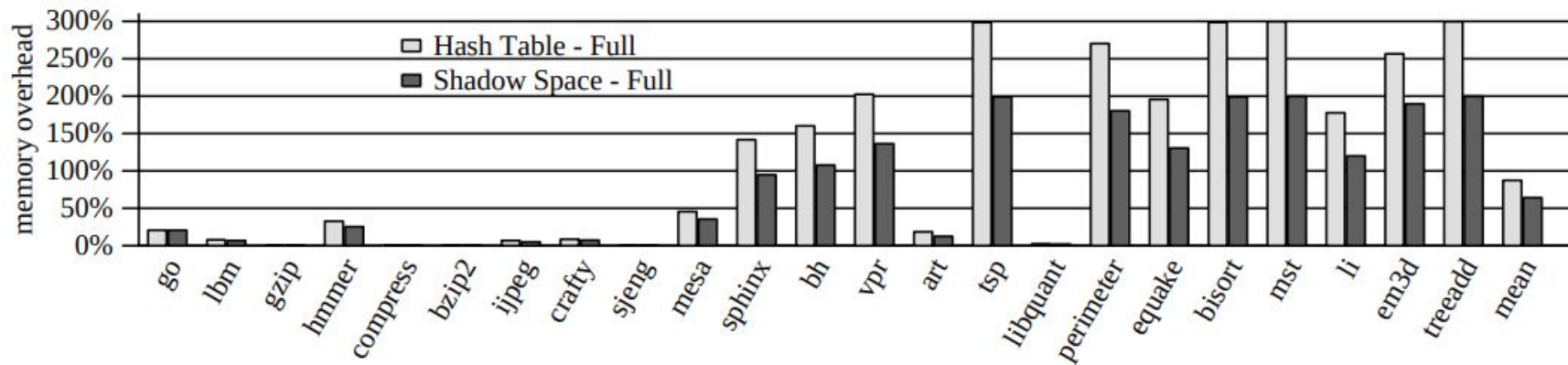
```
int** ptr;  
int* new_ptr;  
(*ptr) = new_ptr;  
table_lookup(ptr)->base = newptr_base;  
table_lookup(ptr)->bound = newptr_bound;
```

```
newptr = *ptr;
```



```
newptr = *ptr;  
newptr_base = table_lookup(ptr)->base;  
newptr_bound = table_lookup(ptr)->bound;
```


SoftBound: Performance





SafeCode: SMS

- Use splay trees to store the bounds information of pointers:
 - **Temporal locality:** Recently accessed object will be accessed again.
 - Splay trees favors temporal locality:
 - Stack behaving tree: Recently inserted object will be fast to access.



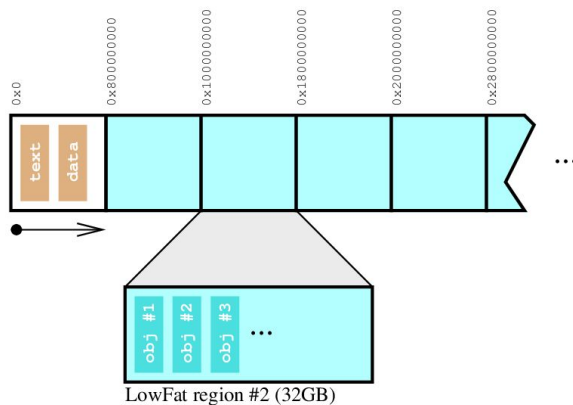
SafeCode: Novelty

- Use pool allocation: Objects size fall into one of the predefined sizes. E.g., 16, 32, 64, etc.
- Split the global splay tree into multiple small splay trees:
 - One for each size.
- Given a pointer => Find its pool and check for the bounds in the splay tree of the corresponding pool.

Low Fat Pointers: SMS

We can smartly allocate and know the base and bounds from the pointer itself.

Each region will only store objects of specific size. E.g., 0x800000000-0xffffffff for objects of size < 16 bytes





Low Fat Pointers

```
p = malloc(10); // p: 0x8997f2820
```

```
q = p + 5; // q = 0x8997f2825
```

```
char get(char *q, int i) {  
    return q[i];  
}
```



```
char get(char *q, int i) {  
    char *q_base = base(q);  
    size_t q_size = size(q);  
    char *r = q + i;  
    if (r < q_base || r >= q_base + q_size)  
        report_oob_error();  
    return *r;  
}
```



What is $\text{base}(q)$ and $\text{size}(q)$?

$\text{base}(q) =$

$\text{size}(q) =$



What is `base(q)` and `size(q)`?

`base(q) = 0x8997f2820`

`size(q) = 16`

Since `q` is within the range `(0x800000000..0xfffffffff)`, we know that the allocation size of the object pointed to by `q` is 16 bytes.

Base address should be: `q - (q mod 16) = 0x8997f2820`.



Handling pointer arithmetic

```
1  int list_length(Node *list)
2  {
3      int len = 0;
4      void *list_base = base(list);
5      size_t list_size = size(list);
6      while (list != NULL)
7      {
8          len++;
9          Node **next = &list->next;
10         void *next_base = list_base;
11         size_t next_size = list_size;
12         if (isOOB(next, next_base, next_size))
13             error();
14         list = *next;
15         list_base = base(list);
16         list_size = size(list);
17     }
18     return len;
19 }
```




Overhead

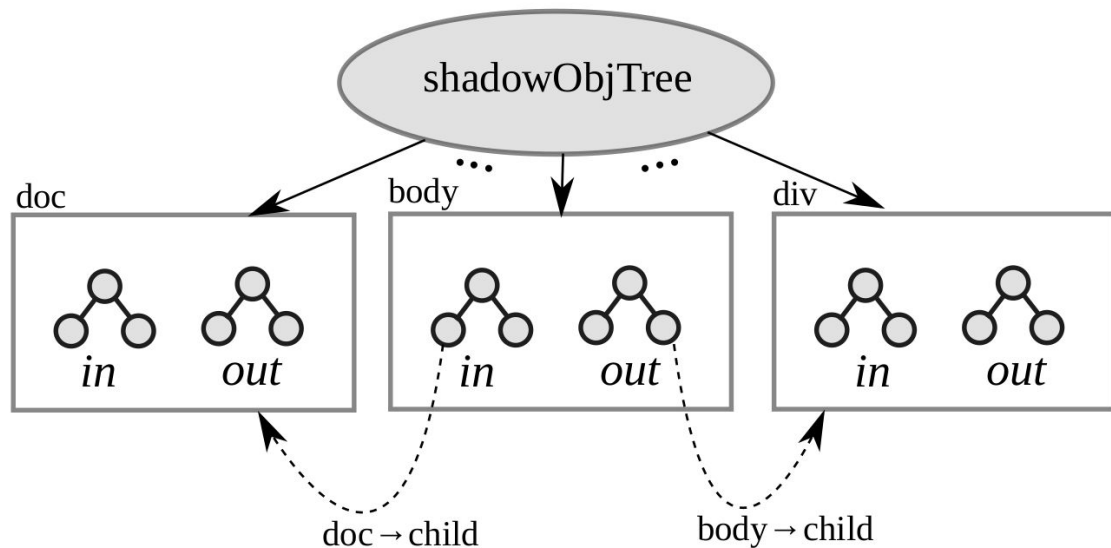
- 56% for reads+writes
- 13% for writes-only



DANGNULL: TMS

- Handles temporal memory safety:
 - Should keep track of object life times.
- Keep tracks of heap objects in a red-black tree (shadowObjTree).
 - Each object has in-bound and out-bound pointers.
 - In-bound: Pointers that are pointing to the current object.
 - Out-bound: Objects to which the current object points to.

DANGNULL



DANGNULL: Instrumentation

```
// (a) memory allocations
Document *doc = new Document();
Body *body = new Body();
Div *div = new Div();

// (b) using memory: propagating pointers
doc->child = body;
body->child = div;

// (c) memory free: doc->child is now dangled
delete body;

// (d) use-after-free: dereference the dangled pointer
if (doc->child)
    doc->child->getAlign();
```

→
DANGNULL

```
// (a) memory allocations
+ Document *doc = allocObj(Document);
+ Body *body = allocObj(Body);
+ Div *div = allocObj(Div);

// (b) using memory: propagating pointers
doc->child = body;
+ trace(&doc->child, body);

body->child = div;
+ trace(&body->child, div);

// (c) memory free: unsafe dangling pointer, doc->child,
// is automatically nullified
+ freeObj(body);

// (d) use-after-free is prevented, avoid dereferencing it
if (doc->child)
    doc->child->getAlign();
```



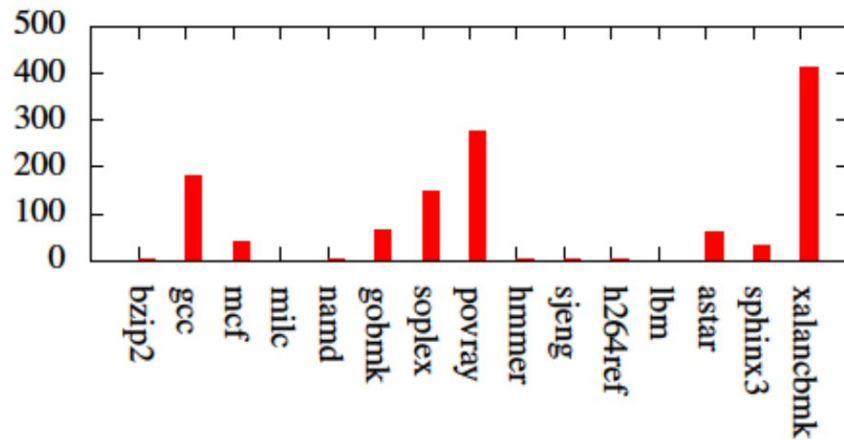
DANGNULL: Helper functions

```
def allocObj(size):  
    ptr = real_alloc(size)  
    shadowObj = createShadowObj(ptr, size)  
    shadowObjTree.insert(shadowObj)  
    return ptr
```

```
# NOTE. lhs <- rhs  
def trace(lhs, rhs):  
    lhsShadowObj = shadowObjTree.find(lhs)  
    rhsShadowObj = shadowObjTree.find(rhs)  
  
    # Check if lhs and rhs are eligible targets.  
    if lhsShadowObj and rhsShadowObj:  
        removeOldShadowPtr(lhs, rhs)  
        ptr = createShadowPtr(lhs, rhs)  
        lhsShadowObj.insertOutboundPtr(ptr)  
        rhsShadowObj.insertInboundPtr(ptr)  
    return
```

```
def freeObj(ptr):  
    shadowObj = shadowObjTree.find(ptr)  
  
    for ptr in shadowObj.getInboundPtrs():  
        srcShadowObj = shadowObjTree.find(ptr)  
        srcShadowObj.removeOutboundPtr(ptr)  
        if shadowObj.base <= ptr < shadowObj.end:  
            *ptr = NULLIFY_VALUE  
  
    for ptr in shadowObj.getOutboundPtrs():  
        dstShadowObj = shadowObjTree.find(ptr)  
        dstShadowObj.removeInboundPtr(ptr)  
  
    shadowObjTree.remove(shadowObj)  
  
    return real_free(ptr)
```

DANGNULL: Performance





Cost of automation

- High performance penalty.
- Not backward compatible:
 - E.g., regular pointers cannot co-exist with low fat pointers.
- Maintenance overhead: Should have these features in the latest compilers.