### **Vulnerability Prevention**

**Holistic Software Security** 

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### Can we prevent vulnerabilities?

• Prevent => Making sure that a program does not have vulnerabilities.

• Why does a program has vulnerabilities?

### How do we write programs?

I want to write code to do X:

1. Think about "How to do X" -> Algorithm.

2. Code <-> Test.

Development mindset => Will the code **do "X"**?

Security mindset => I want the code **NOT to do Y**.

#### Possible Y's:

- Buffer overflow.
- Out-of-bounds access.
- etc.

# Bridging the gap!

- Train developers to have security mindset:
  - Secure coding training.

- Enable developers to write code that "cannot" have vulnerabilities:
  - o Provide Memory safe/Type safe languages:
    - Java, Python, C#, etc.

#### **Memory Safety**

- Spatial memory safety: Ensuring all memory dereferences are within the objects allocated space.
  - Out of bounds access, buffer overflow, underflow, etc.
  - o arr[i]

- Temporal memory safety: Ensuring that memory dereferences are valid at the time of access.
  - Use-after-free, double free, etc.
  - o free(p); \*p = 0;

# **Type Safety**

- Objects are well-typed and conversion between types is well-defined:
  - Ex: In Java, type conversion is allowed only with in subtypes.

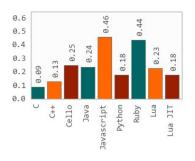
- Is Python type safe?
- Is Java type safe?
- Is C++ type safe?

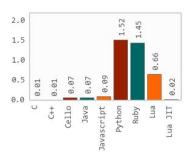
# How is safety implemented?

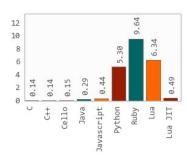
- Runtime checking:
  - Language runtime: Java JRE.
  - Memory accesses are checked for violations.
  - Castings are also checked at time.

#### Safety is not free!

Performance: Time and Space.







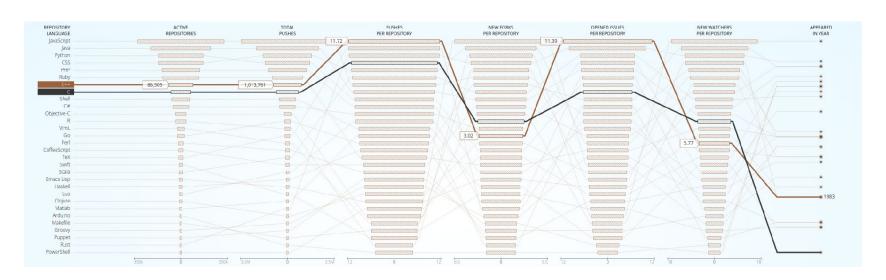
### High-performant safe languages

- Rust/Go:
  - Similar to C/C++, faster than Java, Python, etc.

Lets always use Rust/Go!

What is the catch?

# What about legacy code?



Can we ask all developers to convert their code to safe languages?

### **Retrofitting Techniques**

- Retrofit safety to unsafe languages:
  - o Modify language semantics so that certain safety properties can be achieved.

- Performance overhead?
  - Space and Time.

- Automated or manual?
  - Does developer has to make changes to the existing code?

#### Retrofitting Techniques: Principles

- Spatial memory safety (SMS):
  - An efficient way to track bounds (start and end) of the object being referenced.

- Temporal memory safety (TMS):
  - o An efficient way to track lifetime of objects.

#### SoftBound: SMS

For each pointer variable (p): Add two variables to track bounds (start: p\_base) and end: p\_bound).

Check each pointer dereference to be with in bounds.

```
value = *ptr;
SoftBound
```

```
check(ptr, ptr_base, ptr_bound, sizeof(*ptr));
value = *ptr;
```

```
void check(ptr, base, bound, size) {
  if ((ptr < base) || (ptr+size > bound)) {
    abort();
  }
}
```

#### **SoftBound: Tracking Pointers**

```
ptr = malloc(size);
```

```
newptr = ptr + index;
```

```
p = &(n->num);
```

```
ptr = malloc(size);
ptr_base = ptr;
ptr_bound = ptr + size;
```

```
newptr = ptr + index;
newptr_base = ptr_base;
newptr_bound = ptr_bound;
```

```
p = &(n->num);
p_base = max(&(n->num), n_base);
p_bound = min(p_base + sizeof(n->num), n_bound);
```

# **SoftBound: Tracking Pointers**

```
int** ptr;
int* new_ptr;
(*ptr) = new_ptr;
```

### **SoftBound: Tracking Pointers**

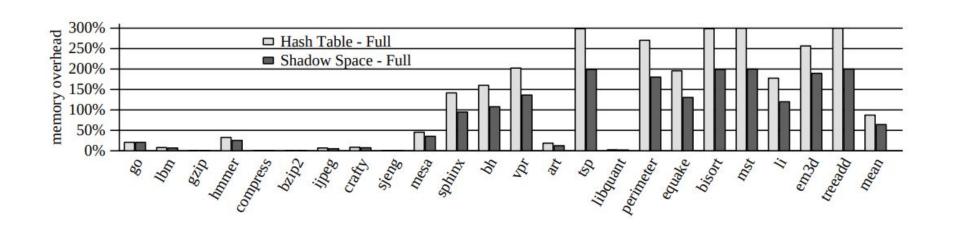
```
int** ptr;
int* new_ptr;
(*ptr) = new_ptr;
```

```
int** ptr;
int* new_ptr;
(*ptr) = new_ptr;
table_lookup(ptr)->base = newptr_base;
table_lookup(ptr)->bound = newptr_bound;
```

```
newptr = *ptr;
```

```
newptr = *ptr;
newptr_base = table_lookup(ptr)->base;
newptr_bound = table_lookup(ptr)->bound;
```

#### **SoftBound: Performance**



#### SafeCode: SMS

- Use splay trees to store the bounds information of pointers:
  - o **Temporal locality**: Recently accessed object will be accessed again.

- Splay trees favors temporal locality:
  - Stack behaving tree: Recently inserted object will be fast to access.

#### SafeCode: Novelty

• Use pool allocation: Objects size fall into one of the predefined sizes. E.g., 16, 32, 64, etc.

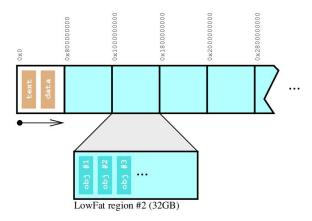
- Split the global splay tree into multiple small splay trees:
  - o One for each size.

• Given a pointer => Find its pool and check for the bounds in the splay tree of the corresponding pool.

#### **Low Fat Pointers: SMS**

We can smartly allocate and know the base and bounds from the pointer itself.

Each region will only store objects of specific size. E.g., 0x80000000-0xfffffffff for objects of size < 16 bytes



#### **Low Fat Pointers**

```
p = malloc(10); // p: 0x8997f2820
q = p + 5; // q = 0x8997f2825
char get(char *q, int i) {
```

return q[i];

```
\Longrightarrow
```

```
char get(char *q, int i) {
  char *q_base = base(q);
  size_t q_size = size(q);
  char *r = q + i;
  if (r < q_base || r >= q_base + q_size)
    report_oob_error();
  return *r;
}
```

# What is base(q) and size(q)?

base(q) =

size(q) =

#### What is base(q) and size(q)?

base(q) = 0x8997f2820

size(q) = 16

Since q is within the range (0x80000000..0xfffffffff), we know that the <u>allocation size of the object</u> pointed to by q is 16 bytes.

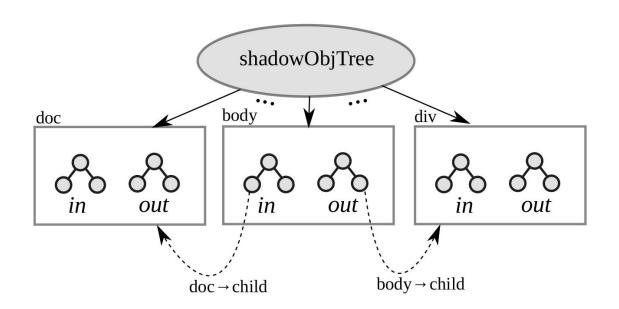
Base address should be:  $q - (q \mod 16) = 0x8997f2820$ .

#### **DANGNULL: TMS**

- Handles temporal memory safety:
  - Should keep track of object life times.

- Keep tracks of heap objects in a red-black tree (shadowObjTree).
  - Each object has in-bound and out-bound pointers.
  - o In-bound: Pointers that are pointing to the current object.
  - Out-bound: Objects to which the current object points to.

#### **DANGNULL**



#### **DANGNULL: Instrumentation**



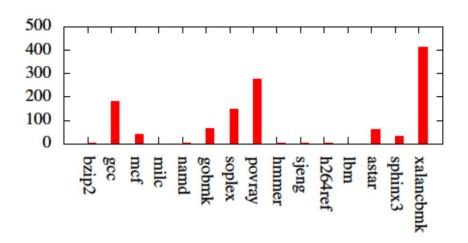
### **DANGNULL:** Helper functions

```
def allocObj(size):
   ptr = real_alloc(size)
   shadowObj = createShadowObj(ptr. size)
   shadowObjTree.insert(shadowObj)
   return ptr
```

```
# NOTE. lhs <- rhs
                                                          def freeObj(ptr):
                                                             shadowObi = shadowObiTree.find(ptr)
def trace(lhs. rhs):
   lhsShadowObj = shadowObjTree.find(lhs)
                                                            for ptr in shadowObj.getInboundPtrs():
   rhsShadowObj = shadowObjTree.find(rhs)
                                                               srcShadowObj = shadowObjTree.find(ptr)
                                                               srcShadowObj.removeOutboundPtr(ptr)
                                                               if shadowObj.base <= ptr < shadowObj.end:</pre>
   # Check if lhs and rhs are eligible targets.
   if lhsShadowObj and rhsShadowObj:
       removeOldShadowPtr(lhs, rhs)
                                                            for ptr in shadowObj.getOutboundPtrs():
                                                               dstShadowObj = shadowObjTree.find(ptr)
       ptr = createShadowPtr(lhs, rhs)
                                                               dstShadowObj.removeInboundPtr(ptr)
       lhsShadowObj.insertOutboundPtr(ptr)
                                                            shadowObiTree.remove(shadowObi)
       rhsShadowObj.insertInboundPtr(ptr)
   return
                                                            return real_free(ptr)
```

\*ptr = NULLIFY\_VALUE

#### **DANGNULL: Performance**



#### **Cost of automation**

• High performance penalty.

- Not backward compatible:
  - E.g., regular pointers cannot co-exist with low fat pointers.

• Maintenance overhead: Should have these features in the latest compilers.