

UNIT – II

EXTENDIBLE HASHING:

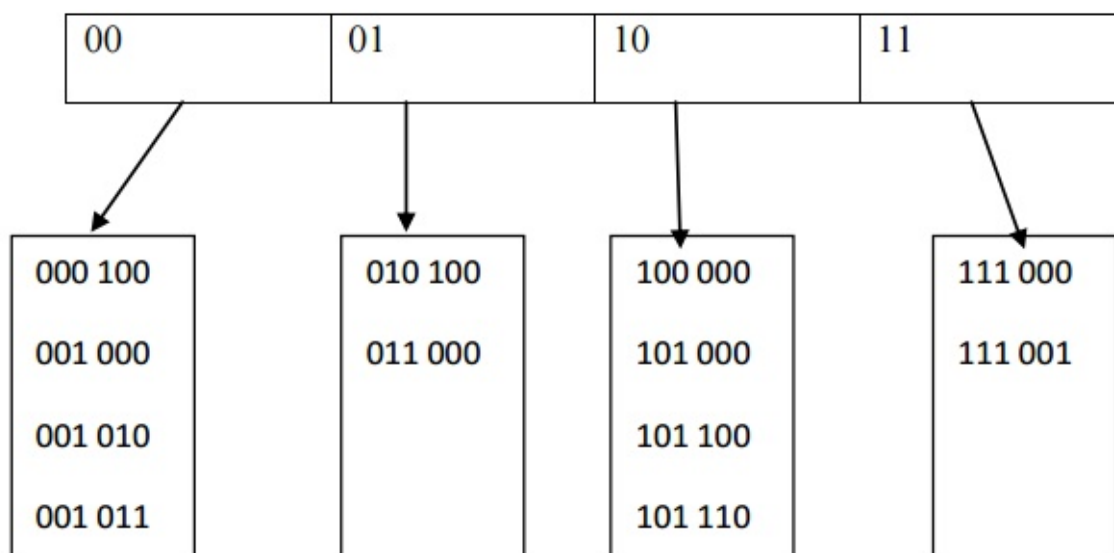
When open address hashing or separate chaining hashing is used, collisions could cause several blocks to be examined during a find even for a well distributed hashtable. Furthermore, when the table gets too full, an extremely expensive rehashing step must be performed, which requires $O(N)$ disk accesses.

This problem can be overcome by using extendible hashing.

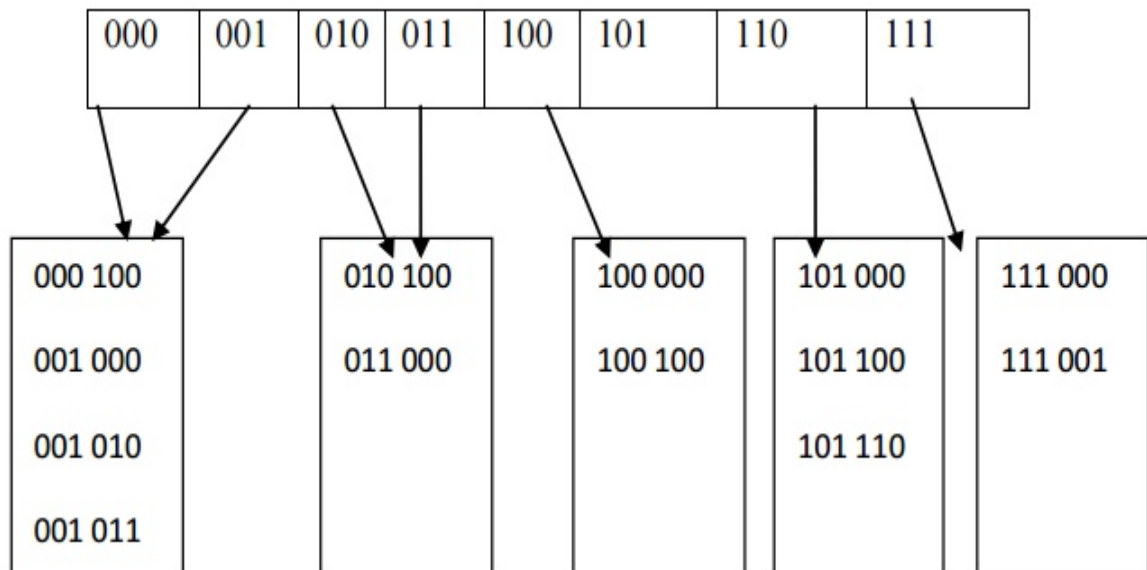
Extendible hashing, allows a find to be performed in two disk accesses. Insertion also requires a few disk accesses.

Let us suppose, consider our data consists of several six-bit integers. The root of the tree contains four pointers determined by the leading two bits of the data. Each leaf has up to $M=4$ elements. In each leaf, the first two bits are identified, this is indicated by the number in parenthesis.

D will represent the number of bits used by the root, also known as the directory. The number of entries in the directory is 2^D . d_L is the number of leading bits that all the elements of some leaf L have in common. $d_L < D$. The extendible hashing scheme for this data is given below.



Suppose that we want to insert the key 100100. This would go into the leaf, but as the third leaf is already full, there is no room. We thus split this leaf into two leaves, which are now determined by the first three bits. Now the directory size is increased to 3.



Similarly, if the key 000000 is inserted ,then the first leaf split generating two leaves with $d_L=3$. The 000 and 001 pointers are updated

Advantage:

- Provides quick access time for insert and find operation are large data bases.

Disadvantages:

- This algorithm does not work if there are more than M duplicates.
- If the elements in a leaf occurs in more than D+1 leading bits ,several directory split is possible the expected size of directory is $O(N^{1+1/M}/M)$.