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import cv2
import mediapipe as mp
class SignLanguageInterpreter:
  def __init__(self):
    self.signs = {
      'hi': 'Hi',
      'ok': 'OK'.
      'vanakkam': 'Vanakkam',
      'salute': 'Salutation',
    }
  def interpret_sign(self, sign):
    return self.signs.get(sign, 'Unknown sign')
def detect_gesture(hand_landmarks):
  if hand_landmarks is not None:
    # Check if all five fingers are open
    all_fingers_open = all(
      landmark.y <
hand landmarks.landmark[mp.solutions.hands.HandLandmark.INDEX FINGER MCP].y
      for landmark in
hand_landmarks.landmark[mp.solutions.hands.HandLandmark.INDEX_FINGER_TIP.value:mp.solutio
ns.hands.HandLandmark.PINKY_TIP.value + 1]
    # Check for thumbs-up gesture (thumb tip lower than thumb base)
    is_thumbs_up = hand_landmarks.landmark[mp.solutions.hands.HandLandmark.THUMB_TIP].y <
hand_landmarks.landmark[mp.solutions.hands.HandLandmark.THUMB_IP].y
    # Check if the wrist is positioned on or above the nose (representing a salute)
    is_salute = hand_landmarks.landmark[mp.solutions.hands.HandLandmark.WRIST].y <=
hand\_landmarks.landmark[mp.solutions.holistic.PoseLandmark.NOSE].y
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return 'hi'
    elif is_thumbs_up:
      return 'ok'
    elif is_salute:
      return 'salute'
  return None
def main():
  interpreter = SignLanguageInterpreter()
  # Initialize Mediapipe Hands module
  mp_hands = mp.solutions.hands
  hands = mp_hands.Hands()
  # Open the webcam
  cap = cv2.VideoCapture(0)
  while True:
    # Capture frame-by-frame
    ret, frame = cap.read()
    # Convert the BGR image to RGB
    rgb_frame = cv2.cvtColor(frame, cv2.COLOR_BGR2RGB)
    # Process the frame with Mediapipe Hands
    results = hands.process(rgb_frame)
    # Get hand landmarks if detected
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if all_fingers_open:

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hand_landmarks = results.multi_hand_landmarks[0] if results.multi_hand_landmarks else None
    # Display the resulting frame
    cv2.imshow('Webcam Feed', frame)
    # Perform gesture detection
    detected_gesture = detect_gesture(hand_landmarks)
    if detected_gesture:
      meaning = interpreter.interpret_sign(detected_gesture)
      print(f"Detected Gesture: {detected_gesture}, Meaning: {meaning}")
    # Break the loop if 'q' key is pressed
    if cv2.waitKey(1) \& 0xFF == ord('q'):
      break
  # Release the capture
  cap.release()
  cv2.destroyAllWindows()
if __name__ == "__main__":
  main()
```