

Reducing a feasible solⁿ to a Basic Feasible solⁿ
 f.s. b.f.s.

Theorem - If there is a f.s. to a set of m simultaneous linear equation $Ax=b$ in n unknowns and $r(A)=m$, then there is a b.f.s.

$$A_{m \times n}$$

Example -

$x_1=2, x_2=3, x_3=1$ is a f.s. of the LPP.

$$\text{Max } Z = x_1 + 2x_2 + 4x_3$$

$$\text{s.t. } 2x_1 + x_2 + 4x_3 = 11$$

$$Ax=b \quad 3x_1 + x_2 + 5x_3 = 14$$

$$x_1, x_2, x_3 \geq 0$$

Find a b.f.s.

$$A = [a_1 \ a_2 \ a_3] = \begin{bmatrix} 2 & 1 & 4 \\ 3 & 1 & 5 \end{bmatrix} \quad b = \begin{bmatrix} 11 \\ 14 \end{bmatrix}$$

$$x_1 a_1 + x_2 a_2 + x_3 a_3 = b$$

$$2a_1 + 3a_2 + a_3 = b \quad \text{--- (1)}$$

a_1, a_2, a_3 are linearly dependent

$$\lambda_1 a_1 + \lambda_2 a_2 + \lambda_3 a_3 = 0$$

$$\lambda_1 \begin{pmatrix} 2 \\ 3 \end{pmatrix} + \lambda_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \lambda_3 \begin{pmatrix} 4 \\ 5 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$2\lambda_1 + \lambda_2 + 4\lambda_3 = 0$$

$$3\lambda_1 + \lambda_2 + 5\lambda_3 = 0$$

$$\frac{\lambda_1}{5-4} = \frac{\lambda_2}{12-10} = \frac{\lambda_3}{2-3} = k \text{ (say)}$$

$$\lambda_1 = k$$

$$\lambda_2 = 2k$$

$$\lambda_3 = -k$$

$$\left. \begin{array}{l} \lambda_1 = k \\ \lambda_2 = 2k \\ \lambda_3 = -k \end{array} \right\} \text{ Taking } k=1$$

$$\lambda_1 = 1 \quad \lambda_2 = 2 \quad \lambda_3 = -1$$

$$a_1 + 2a_2 - a_3 = 0 \quad \text{--- (2)}$$

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(2, 3, 1) is not a b.f.s as the b.f.s. of this problem cannot have more than 2 positive variable.

To determine the departing variable

$$\min_j \left\{ \frac{x_j}{\lambda_j} \mid \lambda_j > 0 \right\}$$

$$= \min \left\{ \frac{2}{1}, \frac{3}{2} \right\} = \frac{3}{2} \Rightarrow j=2$$

a_2 is the ^{departing}~~departing~~ vector and ~~the~~ ^{make} $x_2 = 0$.

$$\textcircled{1} x_2 - \textcircled{2} x_3 \leq$$

$$4a_1 + 6a_2 + 2a_3 = 2b$$

$$3a_1 + 6a_2 - 3a_3 = 0$$

$$\begin{array}{r} - \quad + \quad + \\ \hline a_1 \quad + 5a_3 = 2b \end{array}$$

$$\frac{1}{2}a_1 + 0 \cdot a_2 + \frac{5}{2}a_3 = b$$

$$\left(\frac{1}{2}, 0, \frac{5}{2} \right)$$

Instead we can calculate max ratio as

$$\max_j \left\{ \frac{x_j}{\lambda_j} \mid \lambda_j < 0 \right\} = \left\{ \frac{x_3}{\lambda_3} \right\} \Rightarrow j=3$$

a_3 departing vector

make $x_3 = 0$

$$\text{new } x_j = \text{old } x_j - \left(\frac{x_3}{\lambda_3} \right) \lambda_j$$

\downarrow
max ratio

$$\text{New } x_1 = 2 - (-1) \cdot 1 = 3$$

$$\text{New } x_2 = 3 - (-1) \cdot 2 = 5$$

$$\text{New } x_3 = 1 - (-1) \cdot (-1) = 0$$

b.f. Another b.f.s. (3, 5, 0)

Example -

$$\begin{aligned}x_1 + 2x_2 + 4x_3 + x_4 &= 7 \\ 2x_1 - x_2 + 3x_3 - 2x_4 &= 4\end{aligned}$$

f.s. $\rightarrow x_1=1, x_2=1, x_3=1, x_4=0$

Reduce it to a b.f.p.

$$x_1 a_1 + x_2 a_2 + x_3 a_3 + x_4 a_4 = b$$

$$a_1 + a_2 + a_3 = b$$

$$\lambda_1 a_1 + \lambda_2 a_2 + \lambda_3 a_3 = 0$$

Example -

Show that $x_1=5, x_2=0, x_3=-1$ is a b.f.s. of the system of eqn

$$x_1 + 2x_2 + x_3 = 4$$

$$2x_1 + x_2 + 5x_3 = 5$$

Find the basic soln if there is any.

$$A = (a_1, a_2, a_3) = \begin{pmatrix} 1 & 2 & 1 \\ 2 & 1 & 5 \end{pmatrix} \quad b = \begin{pmatrix} 4 \\ 5 \end{pmatrix}$$

$$x_2 = 0 \quad (a_1, a_3) = \begin{pmatrix} 1 & 1 \\ 2 & 5 \end{pmatrix}$$

$$\det \begin{pmatrix} 1 & 1 \\ 2 & 5 \end{pmatrix} = 5 - 2 = 3 \neq 0$$

a_1, a_3 linearly independent

So the given solution is basic

Other basic soln.

$$B = \begin{pmatrix} a_1 & a_3 \\ 1 & 1 \\ 2 & 5 \end{pmatrix} \quad B^{-1} = \frac{1}{3} \begin{pmatrix} 5 & -1 \\ -2 & 1 \end{pmatrix}$$

$$x_B = B^{-1}b = \frac{1}{3} \begin{pmatrix} 5 & -1 \\ -2 & 1 \end{pmatrix} \begin{pmatrix} 4 \\ 5 \end{pmatrix} = \frac{1}{3} \begin{pmatrix} 15 \\ -3 \end{pmatrix} = \begin{pmatrix} 5 \\ -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_3 \end{pmatrix}$$

checked.

For non-basic variable x_2 ,

$$y_2 = B^{-1}a_2 \\ = \frac{1}{3} \begin{pmatrix} 5 & -1 \\ -2 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \frac{1}{3} \begin{pmatrix} 9 \\ -3 \end{pmatrix} = \begin{pmatrix} 3 \\ -1 \end{pmatrix} \rightarrow \text{the}$$

atleast one component of y_2 is -ve
 a_2 can enter the basis replacing a_1 .

New Basis

$$\bar{B} = \begin{pmatrix} \overset{a_2}{2} & \overset{a_3}{1} \\ 1 & 5 \end{pmatrix}$$

$$(B)^{-1} = \frac{1}{9} \begin{pmatrix} 5 & -1 \\ -1 & 2 \end{pmatrix}$$

$$x_{\bar{B}} = (\bar{B})^{-1}b = \frac{1}{9} \begin{pmatrix} 5 & -1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} 4 \\ 5 \end{pmatrix} = \begin{pmatrix} 5/3 \\ 2/3 \end{pmatrix} = \begin{pmatrix} x_2 \\ x_3 \end{pmatrix}$$

$$x_1 = 0, \quad x_2 = 5/3, \quad x_3 = 2/3$$

Other basic solution -

for Non-basic variable x_1

$$y_1 = (\bar{B})^{-1}a_1 = \frac{1}{9} \begin{pmatrix} 5 & -1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 1/3 \\ 1/3 \end{pmatrix}$$

a_1 enters replacing a_3 in the basis

$$B' = (a_2, a_1) = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} \Rightarrow (B')^{-1} = \frac{1}{3} \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}$$

$$x_{B'} = (B')^{-1}b \\ = \frac{1}{3} \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} 4 \\ 5 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} x_2 \\ x_1 \end{pmatrix}$$

$$x_1 = 2 \quad x_2 = 1 \quad x_3 = 0$$

8- Apply the simplex process to solve the LPP (without using simplex table)

$$\text{Max } Z = 2x_1 - 3x_2$$

$$\text{s.t. } 2x_1 + 5x_2 \geq 10$$

$$3x_1 + 8x_2 \leq 24$$

$$x_1, x_2 \geq 0.$$

$$\text{Max } Z = 2x_1 - 3x_2$$

$$\text{s.t. } \begin{array}{l} 2x_1 + 5x_2 - x_3 = 10 \\ 3x_1 + 8x_2 + x_4 = 24 \end{array}$$

$$Ax = b$$

$$x_1, x_2, x_3, x_4 \geq 0$$

$$A = (a_1, a_2, a_3, a_4) = \begin{pmatrix} 2 & 5 & -1 & 0 \\ 3 & 8 & 0 & 1 \end{pmatrix}, b = \begin{pmatrix} 10 \\ 24 \end{pmatrix}$$

$$x = (x_1, x_2, x_3, x_4)^T$$

a_1, a_4 linearly independent

$$\text{Take basis } B = (a_1, a_4) = \begin{pmatrix} 2 & 0 \\ 3 & 1 \end{pmatrix}$$

$$B^{-1} = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ -3 & 2 \end{pmatrix}$$

Basic Feasible Solution (BFS)

$$x_B = B^{-1}b = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ -3 & 2 \end{pmatrix} \begin{pmatrix} 10 \\ 24 \end{pmatrix} = \begin{pmatrix} 5 \\ 9 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_4 \end{pmatrix}$$

$$x_1 = 5, x_2 = 0, x_3 = 0, x_4 = 9 \quad \text{--- (1)}$$

$$C_B = (2, 0) \quad Z_B = C_B x_B = (2, 0) \begin{pmatrix} 5 \\ 9 \end{pmatrix} = 10$$

for non-basic vector, compute

$$y_2 = B^{-1}a_2 = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ -3 & 2 \end{pmatrix} \begin{pmatrix} 5 \\ 8 \end{pmatrix} = \begin{pmatrix} 5/2 \\ 1/2 \end{pmatrix}$$

$$y_3 = B^{-1}a_3 = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ -3 & 2 \end{pmatrix} \begin{pmatrix} -1 \\ 0 \end{pmatrix} = \begin{pmatrix} -1/2 \\ 3/2 \end{pmatrix}$$

Compute $z_2 - c_2$, $z_3 - c_3$

$$z_2 - c_2 = C_B y_2 - c_2 = (2, 0) \begin{pmatrix} 5/2 \\ 1/2 \end{pmatrix} - (-3) \\ = 5 + 3 = 8$$

$$z_3 - c_3 = C_B y_3 - c_3 = (2, 0) \begin{pmatrix} -1/2 \\ 3/2 \end{pmatrix} - 0 \\ = -1 < 0$$

① is not an optimal solution

a_3 is the entering vector in the basis

Leaving variable determination

find the min ratio,

$$\min \left\{ \frac{x_{B_i}}{y_{ij}} \mid y_{ij} > 0 \right\} = \frac{8}{3} \times 2 = 16 \quad r=4$$

x_4 is leaving

New basis

$$B = (a_1, a_3) = \begin{pmatrix} 2 & -1 \\ 3 & 0 \end{pmatrix}$$

$$B^{-1} = \frac{1}{3} \begin{pmatrix} 0 & 1 \\ -3 & 2 \end{pmatrix}$$

$$x_B = B^{-1}b = \frac{1}{3} \begin{pmatrix} 0 & 1 \\ -3 & 2 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 2 & 4 \end{pmatrix} = \begin{pmatrix} 8 \\ 6 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_3 \end{pmatrix}$$

$$x_1 = 8, x_2 = 0, x_3 = 6, x_4 = 0 \quad \text{--- ②}$$

$$C_B = (2, 0)$$

$$Z = z_B = C_B x_B = (2, 0) \begin{pmatrix} 8 \\ 6 \end{pmatrix} = 16$$

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For non-basic variables x_2, x_4 we compute

$$\left. \begin{aligned} y_2 &= B^{-1} a_2 = \begin{pmatrix} 8/3 \\ 1/3 \end{pmatrix} \\ y_4 &= B^{-1} a_4 = \begin{pmatrix} 1/3 \\ 3/2 \end{pmatrix} \end{aligned} \right\} \text{check}$$

Compute -

$$z_2 - c_2 = c_B y_2 - (-3) = 25/3 > 0$$

$$z_4 - c_4 = c_B y_4 - 0 = 2/3 > 0$$

Optimality is reached

② is the optimal solution

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Q- Max $Z = 3x_1 + 4x_2$
 s.t. $x_1 - x_2 \geq 0$
 $-x_1 + 3x_2 \leq 3$
 $x_1, x_2 \geq 0$

attains unbounded soln.

Q- Max $Z = 6x_1 + 10x_2$
 s.t. $3x_1 + 5x_2 \leq 10$
 $5x_1 + 3x_2 \leq 15$
 $x_1, x_2 \geq 0$

attains an alternate optimal soln

$Z_j - C_j = 0$ for some non-basic variable.

Improving a BFS (Simplex Method)

Max $Z = Cx$

$Ax = b$

$A_{m \times n} \quad m < n$

$x \geq 0$

Rank of $A = m$

Basis $B = [\beta_1, \beta_2, \beta_3, \dots, \beta_m]$

$i, j \rightarrow$

	a_1	a_2	a_j	a_n
y_{11}	y_{12}	y_{1j}	y_{1n}	
y_{21}	y_{22}	y_{2j}	y_{2n}	
\vdots	\vdots	\vdots	\vdots	
y_{m1}	y_{m2}	y_{mj}	y_{mn}	

① - $A_j = \sum_{i=1}^m y_{ij} \beta_i = y_{1j} \beta_1 + y_{2j} \beta_2 + \dots + y_{mj} \beta_m$

$y_{rj} \neq 0 \Rightarrow \beta_r$ can be replaced by a_j

$\beta_r = \frac{a_j}{y_{rj}} - \sum_{\substack{i=1 \\ i \neq r}}^m \frac{y_{ij} \beta_i}{y_{rj}} \quad - (2)$

x_B is a BFS $\Rightarrow \beta x_B = b$

$\sum_{i=1}^m \beta_i x_{Bi} = b \quad - (3)$

$C = (C_B | C_R)$

$Z_B = C_B x_B = \sum_{i=1}^m C_{Bi} x_{Bi} \quad - (4)$

②, ③ \Rightarrow

$$\sum_{i=1}^m x_{\beta i} \beta_i + x_{\beta r} \left[\frac{a_j}{y_{rj}} - \sum_{\substack{i=1 \\ i \neq r}}^m \frac{y_{ij} \beta_i}{y_{rj}} \right] = b$$

$$\sum_{\substack{i=1 \\ i \neq r}}^m \left[x_{\beta i} - \frac{y_{ij} x_{\beta r}}{y_{rj}} \right] \beta_i + x_{\beta r} \frac{a_j}{y_{rj}} = b \quad \text{--- ⑤}$$

New Basic solution-

$$\left. \begin{aligned} \text{①} - 0 &\leq x_{\beta i} - \frac{y_{ij} x_{\beta r}}{y_{rj}} \quad i=1, 2, \dots, m, \quad i \neq r \\ \text{②} - &\leq 0 \quad \leftarrow \text{and } \frac{x_{\beta r}}{y_{rj}} \end{aligned} \right\} \quad \text{--- ⑥}$$

corresponds to the new basis -

$(\beta_1, \beta_2, \dots, \beta_{r-1}, a_j, \beta_{r+1}, \dots, \beta_m)$

$$y_{ij} > 0$$

$$x_{\beta r} = 0 \quad \rightarrow \text{⑥ f.s. as ①, ② satisfied.}$$

$$x_{\beta r} \neq 0 \quad \text{② satisfied and for ① to satisfy we need}$$

$$\text{③} - \frac{x_{\beta i}}{y_{ij}} - \frac{x_{\beta r}}{y_{rj}} \geq 0, \quad y_{ij} \geq 0$$

$$\frac{x_{Bs}}{y_{sj}} \leq \frac{x_{Bi}}{y_{ij}} \quad y_{ij} > 0$$

$$\frac{x_{Bs}}{y_{sj}} = \min \left\{ \frac{x_{Bi}}{y_{ij}} \mid y_{ij} > 0 \right\}$$

(min ratio)

a_j is the entering vector

$$Z' = \sum_{i=1}^m C_{Bi} \left(x_{Bi} - \frac{y_{ij}}{y_{sj}} x_{Bs} \right) + C_j \left(\frac{x_{Bs}}{y_{sj}} \right)$$

$$= \sum_{i=1}^m C_{Bi} x_{Bi} - \frac{x_{Bs}}{y_{sj}} \left(\sum_{i=1}^m C_{Bi} y_{ij} - C_j \right)$$

$\underbrace{\hspace{10em}}_{z_j - C_j}$

$$= Z_B - \frac{x_{Bs}}{y_{sj}} (z_j - C_j)$$

$$z_k - C_k = \min \{ z_j - C_j \mid z_j - C_j < 0 \}$$

↪ choice of EV {entering variable}

Alternative Optima-

Theorem- If there is an optimal BFS to a LPP and $z_j - c_j = 0$ for some non-basic vector a_j and $y_{ij} > 0$ for atleast one i then there exists an alternative Basic optimal solⁿ.

Theorem- If there is an optimal BFS to a LPP and $z_j - c_j = 0$ for some non-basic vector a_j and $y_{ij} < 0 \forall i=1, 2, \dots, m$ then there exists an alternative non-basic optimal solution.

Proof-

$$Ax = b$$

$$Bx_B = b$$

$$x_B = B^{-1}b$$

$$\sum_{i=1}^m x_{Bi} \beta_i + \theta a_j - \theta a_j = b$$

$$\sum_{i=1}^m (x_{Bi} - y_{ij} \theta) \beta_i + \theta a_j = b$$

Non basic f.p. $\left\{ \begin{array}{l} x_{Bi} - \theta y_{ij} \quad i=1, 2, \dots, m \\ \theta \rightarrow a_j \end{array} \right.$

\rightarrow a new f.p. with $(m+1)$ positive variables remaining zero

$$Z' = \sum_{i=1}^m C_{Bi} (x_{Bi} - \theta y_{ij}) + c_j \theta$$

$$= \sum_{i=1}^m C_{Bi} x_{Bi} - \theta \sum_{i=1}^m C_{Bi} y_{ij} + c_j \theta$$

$$= Z_B - \theta (z_j - c_j)$$

$$= Z_B$$

$z_j - c_j = 0$ for some non-basic variable for the existence of alternative option \rightarrow not a necessary condition

$z_j - c_j > 0$ for a non-basic vector a_j

$p_r \rightarrow$ leaving vector

$$x_{pr} = 0, y_{rj} > 0$$

→ degenerate case.

$$\frac{x_{pr}}{y_{rj}} = 0$$

$$z' = z_B - \frac{x_{pr}}{y_{rj}} (z_j - c_j)$$

$$= z_B$$

Two-Phase Method

Phase I-

$$\text{Max } z^* = 0 \cdot x_1 + 0 \cdot x_2 + \dots + 0 \cdot x_n$$

$$-1 \cdot x_{a1} - 1 \cdot x_{a2} - \dots - 1 \cdot x_{am}$$

→ no artificial variable

→ artificial variable at zero level.

Phase II-

Careful about artificial variable
should always remain at zero level

Case I-

a_k EV

a_r LV

$$\bar{x}_{bi} = x_{bi} - \frac{x_{br}}{y_{rk}} y_{ik}$$