

## Kevin Doherty

---

CONTACT INFORMATION	Stevens Institute of Technology 1 Castle Point Terrace Hoboken, NJ 07030	<i>Voice:</i> (732) 759-1012 <i>E-mail:</i> <a href="mailto:kdoherty@stevens.edu">kdoherty@stevens.edu</a> <i>WWW:</i> <a href="http://keevindoherty.github.io">http://keevindoherty.github.io</a>
RESEARCH INTERESTS	My interests lie broadly in autonomous robotics and machine learning, especially high-level autonomy, statistical inference, planning, and exploration.	
EDUCATION	<b>Stevens Institute of Technology</b> , Hoboken, New Jersey B.Eng. with Thesis, Electrical Engineering, expected May, 2017. GPA: 3.97 / 4.0 Minor in Computer Science GRE: 169 Q / 167 V	
REFEREED PUBLICATIONS	K. Doherty, J. Wang, and B. Englot, Probabilistic Map Fusion for Fast, Incremental Occupancy Mapping with 3D Hilbert Maps, <i>IEEE International Conference on Robotics and Automation (ICRA)</i> , 8 pp., May 16-21, 2016.  S. Bai, J. Wang, K. Doherty, and B. Englot. Inference-Enabled Information-Theoretic Exploration of Continuous Action Spaces, <i>The International Symposium on Robotics Research (ISRR)</i> , September 12-15, 2015.	
PROFESSIONAL EXPERIENCE	<b>MIT Lincoln Laboratory</b> , Lexington, Massachusetts USA <i>Summer Research Intern</i> <b>June, 2016 - August, 2016</b> Developed algorithms for semantic map filtering and object localization with application to search using lightweight UAVs and UUVs. Integrated algorithms into a SLAM system with the goal of enhancing situational awareness for a user via a heads-up display.  <b>Robust Field Autonomy Lab</b> , Stevens Institute of Technology, Hoboken, New Jersey USA <i>Undergraduate Research Assistant</i> <b>May, 2015 - Present</b> Studied autonomous robotics with specific interest in the problems of mapping and exploration. Investigated techniques to reduce the number of steps needed to completely explore an environment. Developed a method to enable fusion of several inferred local maps computed using different models. Current work is focused on the application of new machine learning algorithms to map inference.  <b>Cizr Tennis</b> <a href="http://www.cizr.com">www.cizr.com</a> , Austin, Texas USA <i>Part-time Software Engineering Intern</i> <b>December, 2014 - Present</b> Back- and front-end development for a tennis video annotation and editing platform. Built several features currently in production for uploading matches, saving match events, and generating and sharing highlight reels.  <b>Resolute Innovation</b> <a href="http://www.resoluteinnovation.com">www.resoluteinnovation.com</a> , New York City, New York USA <i>Part-time Software Engineering Intern</i> <b>December, 2014 - June, 2016</b> Prototyped web crawlers and parsers for the backend of a university tech-transfer search engine. Built support for user accounts and saved documents. Studied techniques for machine learning-assisted expert data curation.  <b>Sensorimotor Control Lab</b> , Stevens Institute of Technology, Hoboken, New Jersey USA <i>Undergraduate Research Assistant</i> <b>December, 2013 - August, 2014</b>	

Studied applications machine learning in Human-Machine Interfaces for control of upper-limb prostheses. Performed grasp classification and real-time control of a hand exoskeleton.

#### HONORS AND AWARDS

1st Place, Stevens Institute of Technology CS Club Github API CodeJam, 2016

ICFNIJ Research Symposium Grant, in support of undergraduate research on underwater robotics, 2015

1st Place, Stevens Institute of Technology ECE Department Big Data Competition, 2015

Anne P. Neupauer Scholarship, a four year, full-tuition merit scholarship granted by Stevens Institute of Technology, 2013-2017

#### COMPUTER SKILLS

- Languages: Professional experience: Python, Scala, C++, Java, Coffeescript/Javascript, HTML, CSS; Some experience: MATLAB, LabVIEW, R, C, Assembly, Bash scripting
- Tools: ROS, Gazebo, OpenCV, Git, Jenkins CI