Kefeng Huang

+86 13605180448 timkhuang@icloud.com London, UK

EDUCATION

University College London London, UK Master of Engineering in Computer Science 09/2019 - Present

Nanjing Dongshan Foreign Language School A-Level 4 A* (Mathematics, Further Mathematics, Chemistry, Physics) IELTS 7.5 Gold Award in UK Chemistry Olympiad

09/2017 - 06/201907/2018 03/2019

Nanjing, China

RESEARCH EXPERIENCE

Robotic System for Identifying and Watering House Plants

10/2021 — Present

Supervised by Prof. Simon Julier at University College London

- Technology: The robot is simulated over ROS and python is the main programming language.
- Team Work: We worked together as a team of 6 people, with different people working on different aspects including SLAM, Control, Path Planning and etc. Each person will implement the corresponding nodes in ROS and information is transferred using technics including Topics.
- Personal Contribution: I am responsible for the object detection and plant identification. A 3-month literature review is first conducted on detection and segmentation methods as well as the plant identification networks. Currently I am implementing the YOLOv3 nodes which takes the images as input and return detected objects and their bounding boxes.

Image Based Point Cloud Segmentation

08/2021 — Present

Guided by PhD student Henry at University of Oxford

- Technology: Experiments are run over KITTI-Odometry dataset as it contains both images and point cloud in each frame. SemanticKITTI is also used to provide the labels. Python is the main programming language as well as Pytorch to train the network. Nvidia Segmentation (DeepV3WPlus) is adapted to extract features from images.
- **Description**: Each 3D point is first projected to images within the same frame and the frames before. It is first implemented to choose the mode of the labels of the same point on different images. Then it is improved by making predictions using the features of the images instead. A network is trained on a new dataset that combines the actual point label and the corresponding images features.

TECHNICAL EXPERIENCE

ROLE / PROJECT A MMM YYYY - Present company A somewhere, state

- · Lorem ipsum dolor sit amet, consectetur adipiscing elit.
- Suspendisse pretium elit quis ullamcorper ultricies.
- Morbi a nisl sit amet massa ultricies fermentum.
- Sed a diam et turpis tempor venenatis eget eget ipsum.
- Vestibulum fermentum justo vitae aliquet accumsan.

ROLE / PROJECT B MMM YYYY — MMM YYYY company B somewhere, state

- Aenean semper felis et viverra eleifend. • Integer aliquam odio id tellus sollicitudin, ut pellentesque elit blandit.
- Vestibulum iaculis quam ac nibh tincidunt rutrum.

ROLE / PROJECT C MMM YYYY — MMM YYYY company C somewhere, state

- · Donec volutpat turpis et placerat pharetra.
- Sed sit amet sem facilisis, scelerisque lectus aliquam, accumsan purus.
- · Aliquam at urna congue dolor luctus sodales.
- Quisque vitae tortor at elit tincidunt molestie sed ac quam.

MMM YYYY — MMM YYYY **ROLE / PROJECT D** company D somewhere, state

- Vestibulum accumsan massa quis dignissim faucibus.
- Maecenas suscipit mi ut ullamcorper pharetra.
- In vitae ligula tristique, iaculis tortor in, egestas magna.
- In fringilla purus malesuada lectus imperdiet pulvinar.

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ACTIVITIES

Graduate Student Council Representative

Academic Student Association: Some Workshop, Creator/Facilitator

City Symposium Series, University of Motherland, Poster Presenter

College of Science and Engineering Student Project Showcase, Research Presenter

Graduate Research and Creative Works Showcase, State University, Research Presenter

Spring YYYY

Some Coding Sprint, University of Some Other State

YYYY — YYYY

Fall YYYY

Spring YYYY

Spring YYYY

Spring YYYY

SKILLS

Programming Languages Python, C, Java, Dart(Flutter), x86-Assembly

Communication Chinese, English